

### 1.9 Supported use cases

Use case	Distance to human body	corresponding test configuration
EUT placed at human body	5 mm (from Antenna to Flat-Phantom)	generic device

### 1.10 Radio Test Modes

Mode	Settings
IEEE 802.15.4	Modulation = OQPSK2000 Duty cycle = 90% Data rate = 2 Mbps Power level = Ch.: 11 "D"; Ch.: 18 "E"; Ch.: 25 "F" Antenna = integrated

### 1.11 Test Positions

Position	Description
BACK-5MM	EUT rear side with 5mm distance from antenna to the phantom.
TOP-5MM	EUT top side with 5mm distance from antenna to the phantom.
RIGHT-5MM	EUT right side with 5mm distance from antenna to the phantom.
BOTTOM-5MM	EUT bottom side with 5mm distance from antenna to the phantom.

## 1.12 Test Equipment Used During Testing

SAR Measurement					
Description	Manufacturer	Model	Identifier	Cal. Date	Cal. Due
Stäubli Robot	Stäubli	RX90B L	EF00271	functional test	functional test
Stäubli Robot Controller	Stäubli	CS7MB	EF00272	functional test	functional test
DASY 5 Measurement Server	Schmid & Partner		EF00273	functional test	functional test
Control Pendant	Stäubli		EF00274	functional test	functional test
Dell Computer	Schmid & Partner	Intel	EF00275	functional test	functional test
Data Acquisition Electronics	Schmid & Partner	DAE3V1	EF00276	2015-09	2016-09
Dosimetric E-Field Probe	Schmid & Partner	ET3DV6	EF00279	2015-09	2016-09
Dosimetric E-Field Probe	Schmid & Partner	EX3DV4	EF00826	2015-10	2016-10
System Validation Kit	Schmid & Partner	D300V3	EF00299	2015-09	2018-09
System Validation Kit	Schmid & Partner	D450V3	EF00300	2015-09	2018-09
System Validation Kit	Schmid & Partner	D900V2	EF00281	2015-09	2018-09
System Validation Kit	Schmid & Partner	D1800V2	EF00282	2015-09	2018-09
System Validation Kit	Schmid & Partner	D1900V2	EF00283	2015-09	2018-09
System Validation Kit	Schmid & Partner	D2450V2	EF00284	2015-09	2018-09
System Validation Kit	Schmid & Partner	D5GHZV2	EF00827	2015-10	2018-10
Flat phantom	Schmid & Partner	V 4.4	EF00328	no calibration required	no calibration required
Oval flat phantom	Schmid & Partner	ELI 4	EF00289	functional test	functional test
Mounting Device	Schmid & Partner	V 3.1	EF00287	functional test	functional test
Millivoltmeter	Rohde & Schwarz	URV 5	EF00126	2013-08	2016-08
Power sensor	Rohde & Schwarz	NRV-Z2	EF00125	2015-09	2017-09
RF signal generator	Rohde & Schwarz	SMP 02	EF00165	2015-05	2017-05
Insertion unit	Rohde & Schwarz	URV5-Z4	EF00322	2015-10	2016-10
Directional Coupler	HP	HP 87300B	EF00288	functional test	functional test
Radio Communication Tester	Rohde & Schwarz	CMD65	EF00625	ICO (initial calibration only)	ICO (initial calibration only)
Universal Radio Communication Tester	Rohde & Schwarz	CMU 200	EF00304	2015-05	2016-05
Network Analyzer 300 kHz to 3 GHz	Agilent	8752C	EF00140	2015-06	2016-06
Dielectric Probe Kit	Agilent	85070C	EF00291	functional test	functional test
Dielectric Probe Kit	SPEAG	DAK-3.5	EF00945	2015-09	2016-09
DAK Measurement Software	SPEAG	DAKS	EF00965	-	-
Thermometer	LKM electronic GmbH	DTM3000	EF00967	2015-10	2016-10

## 2 Result Summary

447498 D01 General RF Exposure Guidance					
Product Specific Standard Section	Requirement – Test	Reference Method	Maximum SAR [W/kg]	Result	Remarks
447498 D01 General RF Exposure Guidance	Single-band conformity	KDB Publication 447498 KDB Publication 865664	1.006	PASS	
447498 D01 General RF Exposure Guidance	Multi-band conformity	KDB Publication 447498 KDB Publication 865664	N/A	N/R	No concurrent transmission modes
<b>Remarks:</b>					

### 3 Definitions

The specific absorption rate (SAR) is defined as the time derivative of the incremental energy ( $dW$ ) absorbed by (dissipated in) an incremental mass ( $dm$ ) contained in a volume element ( $dV$ ) of a given density ( $\rho_t$ ), expressed in watts per kilogram (W/kg)

$$\text{SAR} = \frac{dW}{dt} \frac{dm}{dV} = \frac{dW}{dt} \frac{dW}{\rho_t dV} = \sigma / \rho_t |E_t|^2$$

where

$$\frac{dW}{dt} = \int_V E J dV = \int_V \sigma E^2 dV$$

#### 3.1 Controlled Exposure

The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity. Warning labels placed on low-power consumer devices such as cellular telephones are not considered sufficient to allow the device to be considered under the occupational/controlled category and the general population/uncontrolled exposure limits apply to these devices.

#### 3.2 Uncontrolled Exposure

In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means. Awareness of the potential for RF exposure in a workplace or similar environment can be provided through specific training as part of a RF safety program. If appropriate, warning signs and labels can also be used to establish such awareness by providing prominent information on the risk of potential exposure and instructions on the risk of potential exposure and instructions on methods to minimize such exposure risks.

#### 3.3 Localized SAR

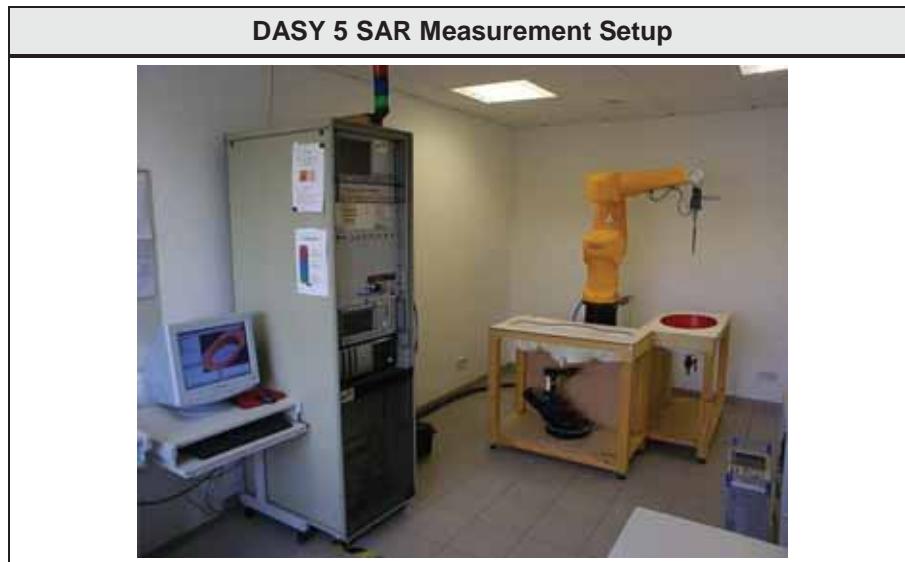
Compliance with the localized SAR limits is demonstrated using the head and trunk limit because this SAR limit is only half the limbs limit value. The values are obtained by SAR measurements according to EN 62209-2.

## 4 Localized SAR Measurement Equipment

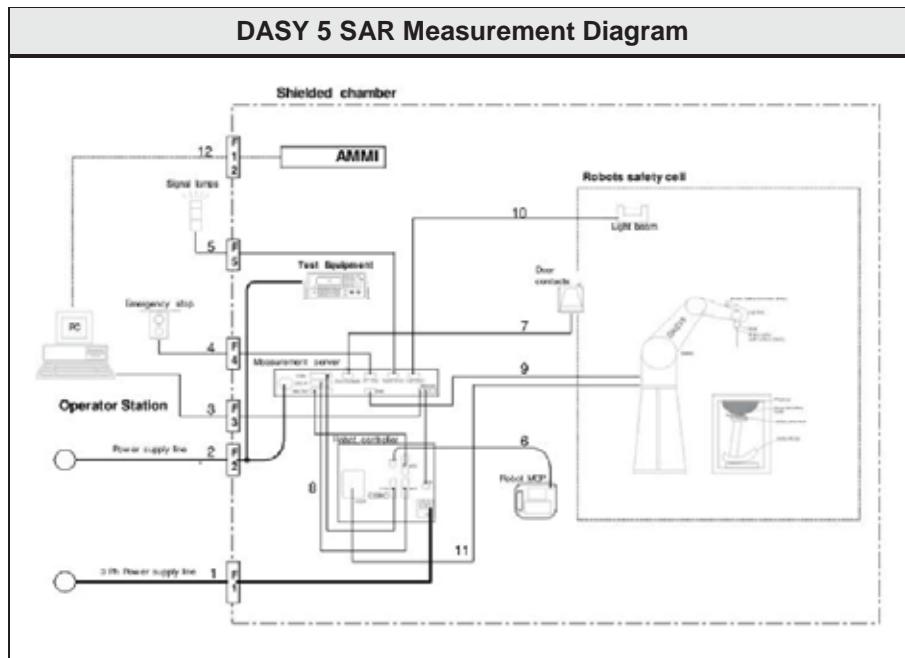
The measurements were performed with Dasy5 automated near-field scanning system comprised of high precision robot, robot controller, computer, e-field probe, probe alignment unit, phantoms, non-conductive phone positioned and software extension.

### 4.1 Complete SAR DASY5 Measurement System

Measurements are performed using the DASY5 automated assessment system made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland.



The following Diagram show the elements involved in the measurement setup.



The DASY5 system for performing compliance tests consists of the following items:

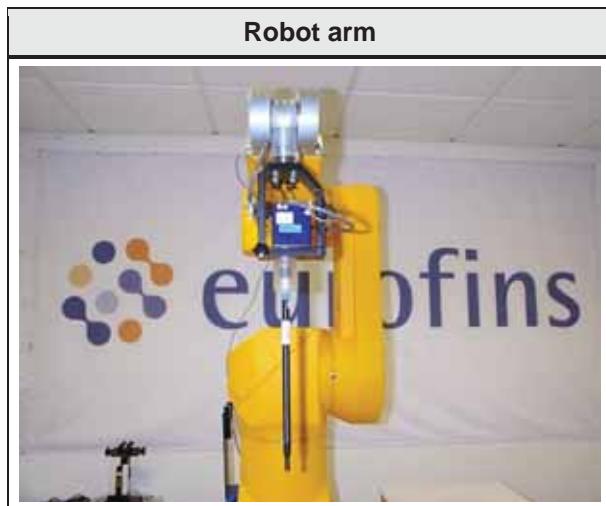
<b>DASY5 SAR Measurement System</b>	
Device	Description:
RX90BL	A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software.
Probe Alignment Unit	A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
Teach Pendant	The Manual Control Pendant (MCP), also called the manual teach pendant, is the user interface to the robot. In DASY, it is used for certain installation and teach procedures
Signal Lamps	External warning lamp which indicates when the robot arm is powered-on and if the robot is under software control or in manual mode (controlled with the teach pendant).
DAE	The data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
E-Field Probes	Isotropic E-Field probe optimized and calibrated for E-field measurements in free space.
EOC	The electro-optical converter (EOC) performs the conversion between optical and electrical signals
Measurement Server	The functions of the measurement server is to perform the time critical task such as signal filtering, surveillance of the robot operation, fast movement interrupts.
Control Computer	A computer operating Windows 2000 or Windows NT with DASY 4 Software.
Control Software	DASY4 and SEMCAD post processing Software
SAM Twin Phantom	The SAM twin phantom enabling testing left-hand and right-hand usage.
Flat Phantom	Flat Phantom (only for body-mounted transceivers operating below 800 MHz).
Tissue simulating liquid	Tissue simulating liquid mixed according to the given recipes.
Device Holder	The device holder for handheld mobile phones.
System Validation Dipoles	System validation dipoles allowing to validate the proper functioning of the system.

#### 4.2 Robot Arm

The DASY5 system uses the high precision robots RX90BL type out of the newer series from Stäubli SA (France).

The RX robot series have many features that are important for our application:

- High precision (repeatability 0.02 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)
- 6-axis controller



#### 4.3 Data Acquisition Electronics

The data acquisition electronics (DAE3) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection. The input impedance of the DAE3 is 200M Ohm; the inputs are symmetrical and floating. Common mode rejection is above 80dB.



#### 4.4 Isotropic E-Field Probe $\leq 2$ GHz

##### Probe Specifications

###### **Construction:**

One dipole parallel, two dipoles normal to probe axis built-in shielding against static charges.

###### **Calibration:**

In air from 10 MHz to 2.5 GHz,  
In brain and muscle simulating tissue at  
Frequencies of 835MHz, 900MHz, 1800MHz,  
1900 MHz

###### **Frequency:**

10MHz to  $> 3$ GHz,  
Linearity  $\pm 0.2$ dB (30MHz to 3GHz)

###### **Directivity:**

$\pm 0.2$ dB in HSL (rotation around probe axis)  
 $\pm 0.4$ dB in HSL (rotation normal to probe axis)

###### **Dynamic Range:**

5 $\mu$ W/g to  $> 100$ mW/g

###### **Linearity:**

$\pm 0.2$ dB

###### **Dimensions:**

Overall Length: 330mm (Tip: 16mm),  
Tip Diameter: 6.8mm (Body: 12mm),  
Distance from probe tip to dipole centers: 2.7mm

###### **Application:**

General dosimetry up to 3 GHz  
Compliance tests of mobile phones  
Fast automatic scanning in arbitrary phantoms



#### 4.5 Isotropic E-Field Probe ≤ 6 GHz

##### Probe Specifications

###### **Construction:**

One dipole parallel, two dipoles normal to probe axis built-in shielding against static charges.

###### **Calibration:**

In air from 10 MHz to 6 GHz,  
In brain and muscle simulating tissue at  
Frequencies of 2450, 5200, 5500, 5800

###### **Frequency:**

10MHz to 6GHz,  
Linearity  $\pm 0.2$ dB (30MHz to 6GHz)

###### **Directivity:**

$\pm 0.3$ dB in HSL (rotation around probe axis)  
 $\pm 0.5$ dB in tissue material (rotation normal to probe axis)

###### **Dynamic Range:**

10 $\mu$ W/g to > 100mW/g

###### **Linearity:**

$\pm 0.2$ dB

###### **Dimensions:**

Overall Length: 337mm (Tip: 20mm),  
Tip Diameter: 2.5mm (Body: 12mm),  
Distance from probe tip to dipole centers: 1mm

###### **Application:**

General dosimetry up to 6 GHz  
Compliance tests of mobile phones  
Fast automatic scanning in arbitrary phantoms

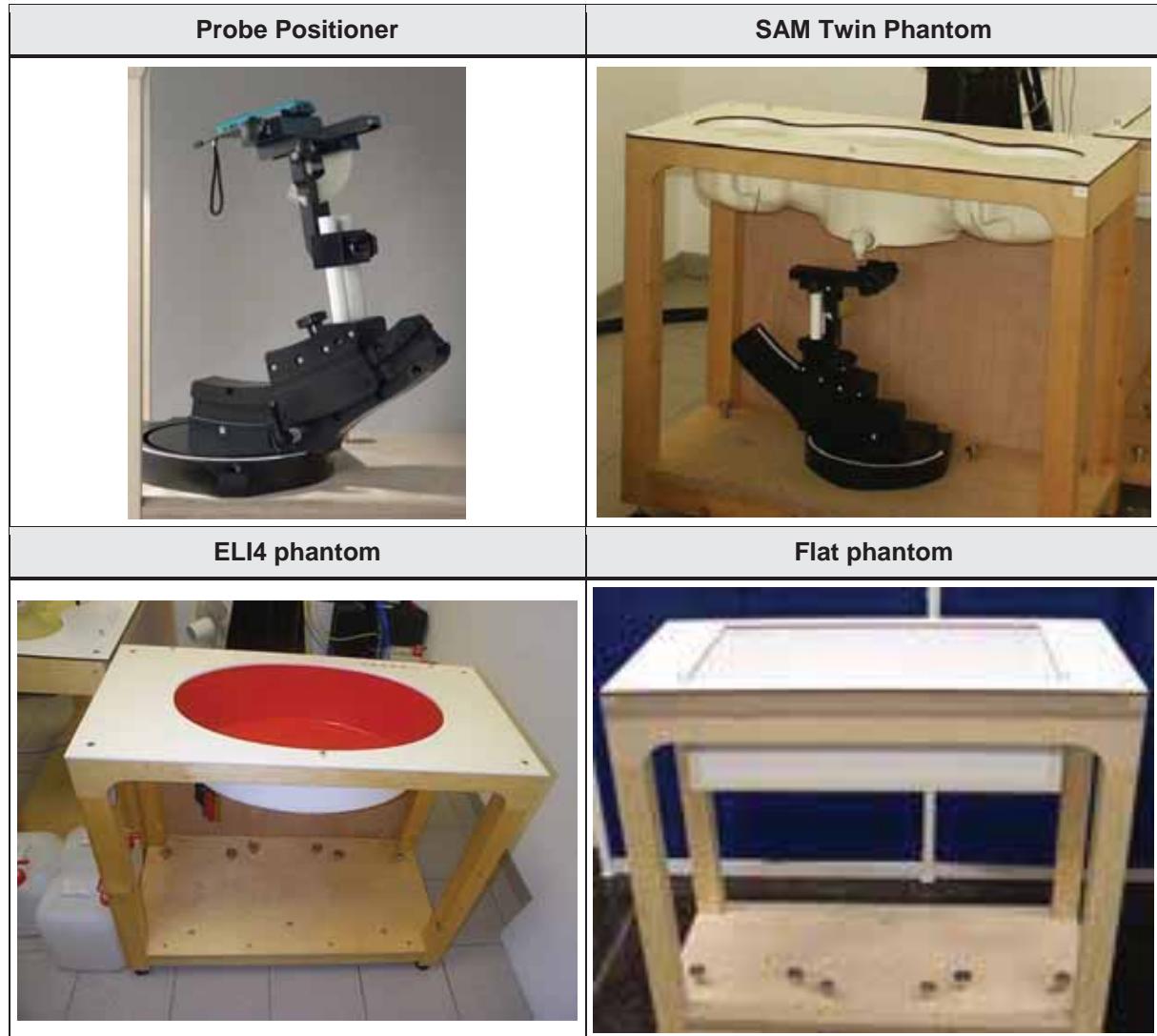
**Isotropic E-Field Probe EX3DV4**



#### 4.6 Test phantom and positioner

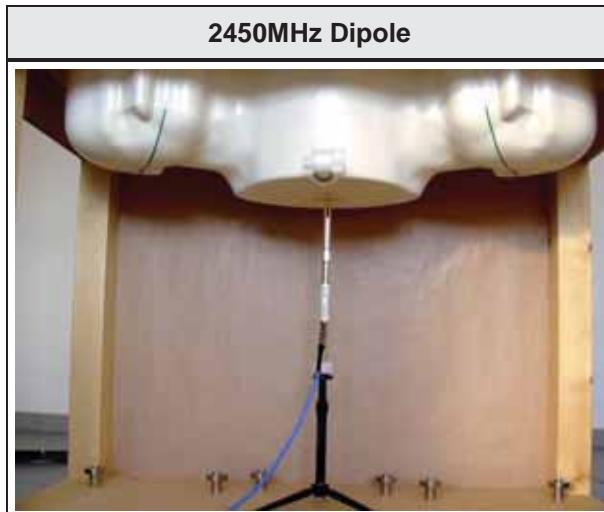
The positioner and test phantoms are manufactured by SPEAG. The test phantoms are used for all tests i.e. for both validation testing and device testing. The positioner and test phantom conforms to the requirements of EN 62209 and IEEE 1528.

The SPEAG device holder was used to position the test device in all tests whilst a tripod was used to position the validation dipoles in the test arch.



#### 4.7 System Validation Dipoles

A set of calibration dipoles (D2450V) is included as a part of the SAR measurement setup. These are used for the validation of the test setup after its installation and prior to the EUT measurements. The calibration dipole is placed in the position normally occupied by the EUT. All calibration dipoles have the same height which allows an exact fitting below the center point of the test phantom. The dipole center is 10mm below the surface of the test phantom.



## 5 Single-band SAR Measurement

After successful completion of the tissue and system verification the SAR values of the EUT are measured according to the following description.

### 5.1 General measurement description

The measurement is performed for each frequency band of the device. If the width of the transmit frequency band exceeds 1% of its center frequency, than the channels at the lowest and highest frequencies should also be tested. Furthermore, if the width of the transmit band exceeds 10% of its center frequency the following formula is used to determine the number of channels:

$$N_C = 2 \cdot \text{roundup}[10 \cdot (f_{\text{high}} - f_{\text{low}})/f_c] + 1$$

First the device is tested on the center channel of each frequency band used by the device. An operation mode and configuration with maximum transmit power is established. If battery operated equipment is used, the batteries are fully charged.

SAR measurements are performed using the steps outlined in the next section for all relevant operational modes, EUT configurations and measurement positions.

For the condition (position, configuration, operational mode) that provides the highest spatial-average SAR value on the center channel, the other channels are also tested.

Additionally all other conditions where the spatial-average SAR value is within 3dB of the SAR limit are also tested on all determined test frequencies.

### 5.2 SAR measurement description

First the local SAR value at a test point within 10mm or less in normal direction from the inner surface of the phantom is measured. This SAR value is used to determine the measurement drift during SAR measurement.

Next an area scan is performed over an area larger than the projection of the EUT with antenna on the surface of the phantom with a spatial grid step of 10mm.

From the scanned SAR distribution the position of maximum SAR value is identified as well as any local SAR maxima within 2dB of the maximum value that are not within the zoom scan volume. (The additional peaks are only measured when the primary peak is within 2dB of the SAR limit.)

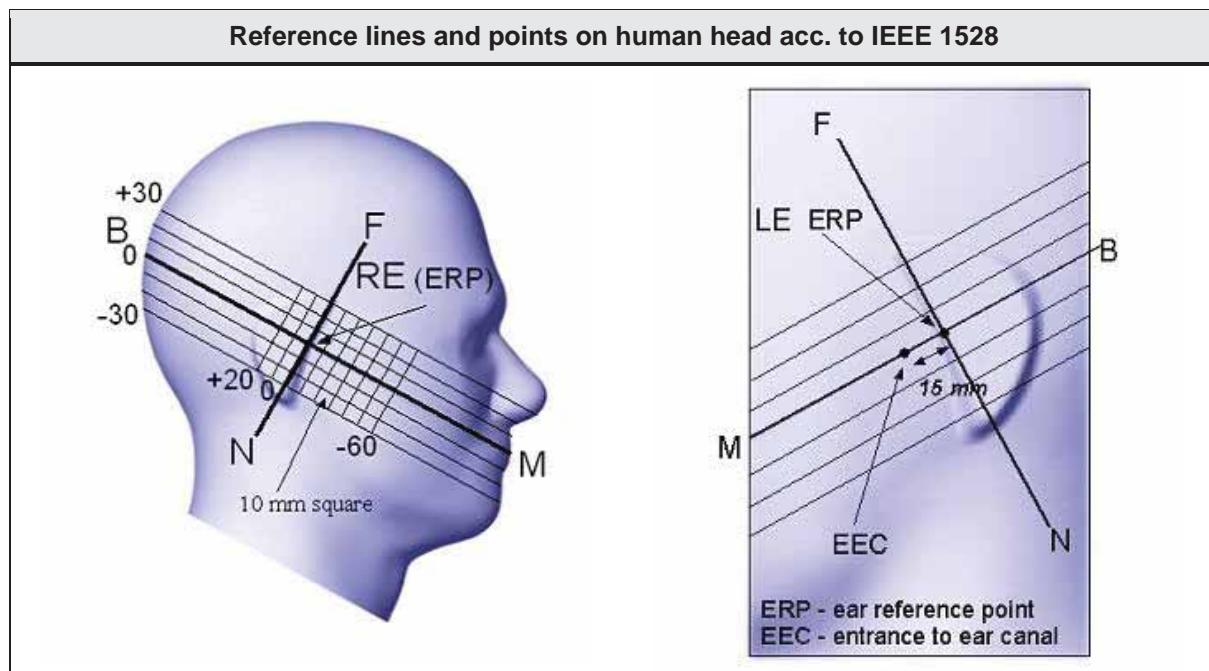
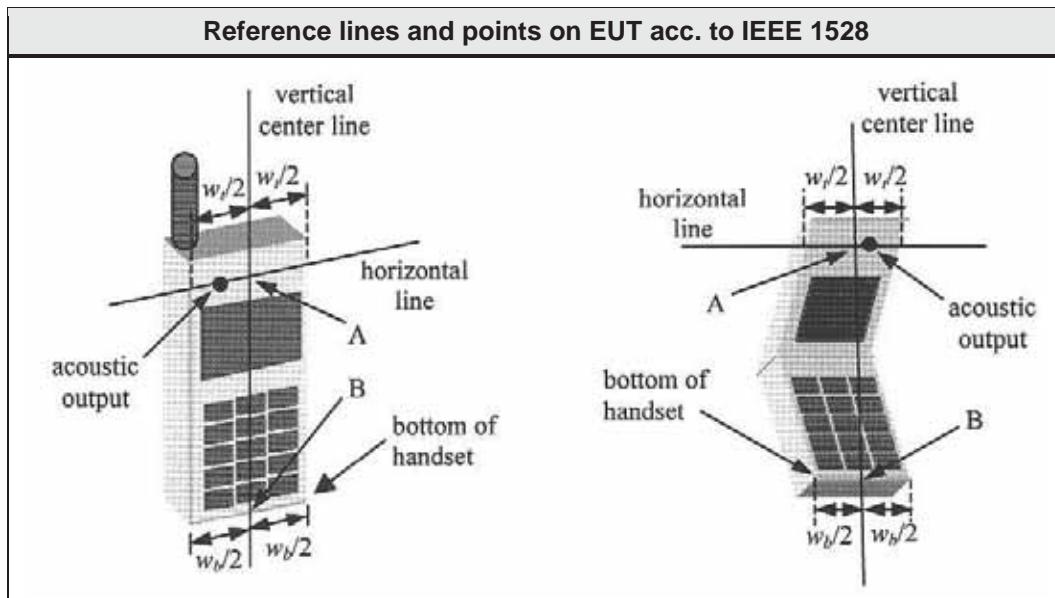
The zoom-scan volume constructed on the peak SAR position is scanned with a grid step of 5mm. The measured data are extracted and the local SAR value for each measurement point is calculated. The measured values are interpolated over a fine-mesh within the scan volume and the average SAR value over 10g mass is calculated.

At the end of the measurement the reference point measured at the beginning of the measurement is measured again and from the difference the drift is calculated.

### 5.3 Reference lines and points for Handsets

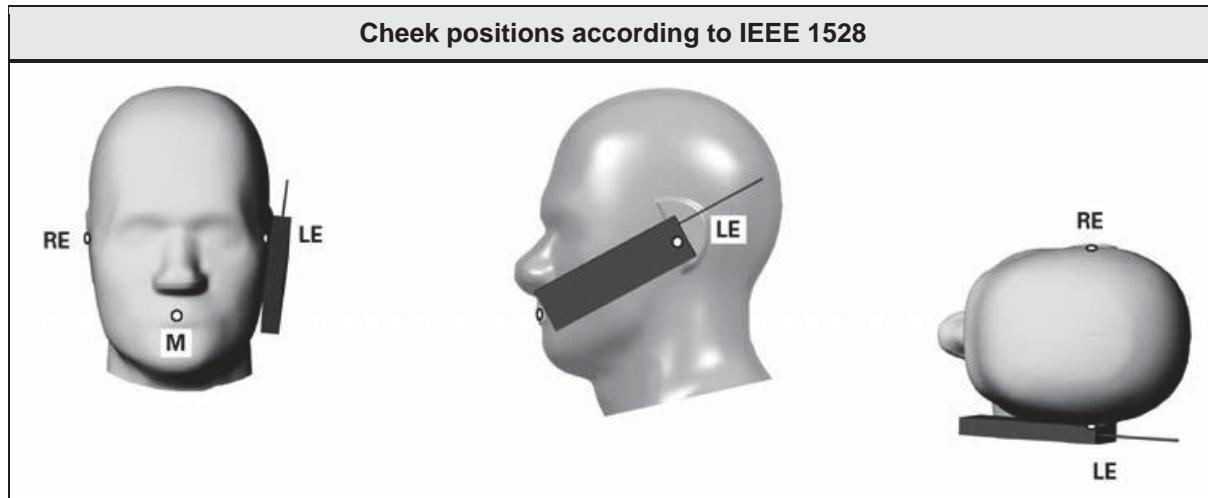
For all measurement positions of the EUT, the EUT has to be placed in a specific orientation with respect to the phantom. The orientation of the EUT relative to the phantom is defined by reference lines and points.

According to IEEE 1528, the reference lines and points shall be positioned at the EUT as shown in the following figure.



## 5.4 Test positions relative to the Head

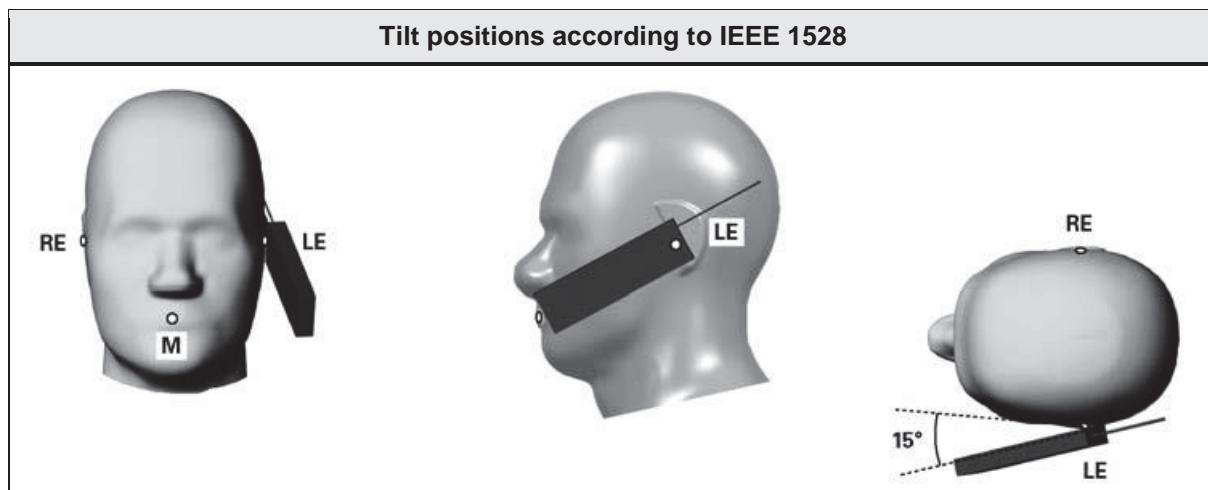
### Cheek position



The handset is positioned close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure), such that the plane defined by the vertical centerline and the horizontal line of the handset is approximately parallel to the sagittal plane of the phantom. Next the handset is translated towards the phantom along the line passing through RE and LE until handset point A touches the pinna at the ERP.

While the handset is maintained in this plane, it is rotated around the LE-RE line until the vertical centerline is in the plane normal to the plane containing B-M and N-F lines, i.e., the Reference Plane. Then it is rotated around the vertical centerline until the handset (horizontal line) is parallel to the N-F line. While the vertical centerline is maintained in the Reference Plane, point A is kept on the line passing through RE and LE, and the handset is maintained in contact with the pinna, the handset is rotated about the N-F line until any point on the handset is in contact with a phantom point below the pinna on the cheek.

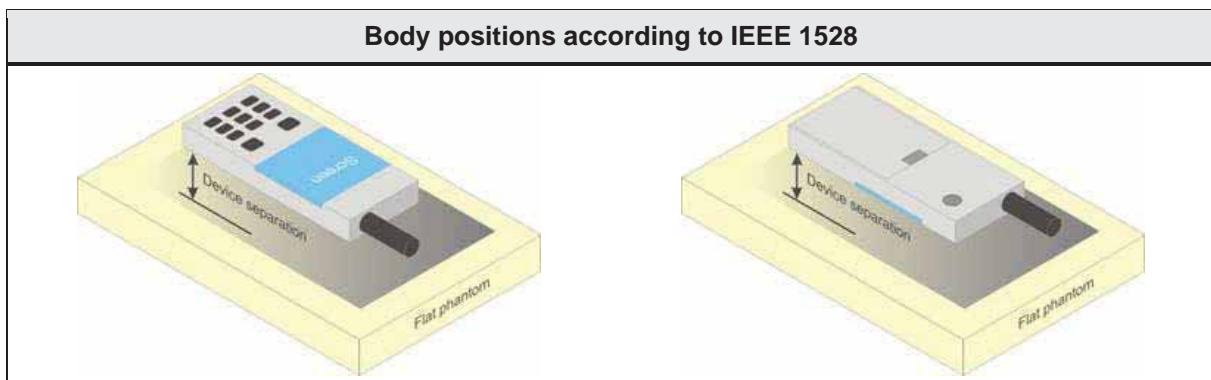
### Tilt position



First the EUT is placed in the cheek position. Next the handset is moved away from the pinna along the line passing through RE and LE far enough to allow a rotation of the handset away from the cheek by 15°. Then the handset is rotated around the horizontal line by 15°.

The handset is moved towards the phantom on the line passing through RE and LE until any part of the handset touches the ear. The tilt position is obtained when the contact point is on the pinna. See Figure. If contact occurs at any location other than the pinna, e.g., the antenna at the back of the phantom head, the angle of the handset should be reduced. In this case, the tilt position is obtained if any point on the handset is in contact with the pinna and a second point on the handset is in contact with the phantom, e.g., the antenna with the back of the head

### 5.5 Test positions relative to the human body



In body worn configuration the device is positioned parallel to the phantom surface with either top or bottom side of the EUT facing against the phantom.

The separation distance of the EUT is selected according to the use case of the EUT (e.g. with belt clip or holster).

## 5.6 Measurement Uncertainty

Measurement Uncertainty according to IEEE 1528							
Error Description	Uncertainty Value	Probability Distribution	Div.	$c_i(1g)$	$c_i(10g)$	Std. Unc. 1g	Std. Unc. 10g
<b>Measurement System</b>							
Probe Calibration	±6.55%	N	1	1	1	±6.55%	±6.55%
Axial Isotropy	±4.7%	R	$\sqrt{3}$	0.7	0.7	±1.9%	±1.9%
Hemispherical Isotropy	±9.6%	R	$\sqrt{3}$	0.7	0.7	±3.9%	±3.9%
Linearity	±4.7%	R	$\sqrt{3}$	1	1	±2.7%	±2.7%
Modulation Response	±2.4%	R	$\sqrt{3}$	1	1	±1.4%	±1.4%
System Detection Limits	±1.0%	R	$\sqrt{3}$	1	1	±0.6%	±0.6%
Boundary effects	±2.0%	R	$\sqrt{3}$	1	1	±1.2%	±1.2%
Readout Electronics	±0.3%	N	1	1	1	±0.3%	±0.3%
Response Time	±0.8%	R	$\sqrt{3}$	1	1	±0.5%	±0.5%
Integration Time	±2.6%	R	$\sqrt{3}$	1	1	±1.5%	±1.5%
RF Ambient Noise	±3.0%	R	$\sqrt{3}$	1	1	±1.7%	±1.7%
RF Ambient Reflections	±3.0%	R	$\sqrt{3}$	1	1	±1.7%	±1.7%
Probe Positioner	±0.8%	R	$\sqrt{3}$	1	1	±0.5%	±0.5%
Probe Positioning	±6.7%	R	$\sqrt{3}$	1	1	±3.9%	±3.9%
Post processing	±4.0%	R	$\sqrt{3}$	1	1	±2.3%	±2.3%
<b>Test Sample Related</b>							
Device Holder	±3.6%	N	1	1	1	±3.6%	±3.6%
Test Sample Positioning	±2.9%	N	1	1	1	±2.9%	±2.9%
Power Scaling	±0%	R	$\sqrt{3}$	1	1	±0%	±0%
Power Drift	±5.0%	R	$\sqrt{3}$	1	1	±2.9%	±2.9%
<b>Phantom and Setup Related</b>							
Phantom Uncertainty	±7.9%	R	$\sqrt{3}$	1	1	±4.6%	±4.6%
SAR correction	±1.9%	R	$\sqrt{3}$	1	0.84	±1.1%	±0.9%
Liquid conductivity (measured)	±2.5%	N	1	0.78	0.71	±2.0%	±1.8%
Liquid permittivity (measured)	±2.5%	N	1	0.26	0.26	±0.1%	±0.1%
Temperature uncertainty - Conductivity	±5.2%	R	$\sqrt{3}$	0.78	0.71	±2.3%	±2.1%
Temperature uncertainty - Permittivity	±0.8%	R	$\sqrt{3}$	0.23	0.26	±0.1%	±0.1%
Combined Standard Uncertainty						±12.8%	±12.7%
Expanded Standard Uncertainty						±25.6%	±25.4%

Measurement Uncertainty according to EN 62209-1							
Error Description	Uncertainty Value	Probability Distribution	Div.	$c_i$ (1g)	$c_i$ (10g)	Std. Unc. 1g	Std. Unc. 10g
<b>Measurement System</b>							
Probe Calibration	±6.0%	N	1	1	1	±6.0%	±6.0%
Axial Isotropy	±4.7%	R	$\sqrt{3}$	0.7	0.7	±1.9%	±1.9%
Hemispherical Isotropy	±9.6%	R	$\sqrt{3}$	0.7	0.7	±3.9%	±3.9%
Boundary effects	±1.0%	R	$\sqrt{3}$	1	1	±0.6%	±0.6%
Linearity	±4.7%	R	$\sqrt{3}$	1	1	±2.7%	±2.7%
System Detection Limits	±1.0%	R	$\sqrt{3}$	1	1	±0.6%	±0.6%
Readout Electronics	±0.3%	N	1	1	1	±0.3%	±0.3%
Response Time	±0.8%	R	$\sqrt{3}$	1	1	±0.5%	±0.5%
Integration Time	±2.6%	R	$\sqrt{3}$	1	1	±1.5%	±1.5%
RF Ambient Noise	±3.0%	R	$\sqrt{3}$	1	1	±1.7%	±1.7%
RF Ambient Reflections	±3.0%	R	$\sqrt{3}$	1	1	±1.7%	±1.7%
Probe Positioner	±0.4%	R	$\sqrt{3}$	1	1	±0.2%	±0.2%
Probe Positioning	±2.9%	R	$\sqrt{3}$	1	1	±1.7%	±1.7%
Max. SAR Evaluation	±2.0%	R	$\sqrt{3}$	1	1	±1.2%	±1.2%
<b>Test Sample Related</b>							
Device Positioning	±2.9%	N	1	1	1	±2.9%	±2.9%
Device Holder	±3.6%	N	1	1	1	±3.6%	±3.6%
Power Drift	±5.0%	R	$\sqrt{3}$	1	1	±2.9%	±2.9%
Power Scaling	±0%	R	$\sqrt{3}$	1	1	±0.0%	±0.0%
<b>Phantom and Setup Related</b>							
Phantom Uncertainty	±6.1%	R	$\sqrt{3}$	1	1	±3.5%	±3.5%
SAR correction	±1.9%	R	$\sqrt{3}$	1	0.84	±1.1%	±0.9%
Liquid conductivity (measured)	±2.5%	N	1	0.78	0.71	±2.0%	±1.8%
Liquid permittivity (measured)	±2.5%	N	1	0.26	0.26	±0.6%	±0.7%
Temperature uncertainty - Conductivity	±5.2%	R	$\sqrt{3}$	0.78	0.71	±2.3%	±2.1%
Temperature uncertainty - Permittivity	±0.8%	R	$\sqrt{3}$	0.23	0.26	±0.1%	±0.1%
Combined Standard Uncertainty						±11.4%	±11.3%
Expanded Standard Uncertainty						±22.9%	±22.7%

Measurement Uncertainty according to EN 62209-2							
Error Description	Uncertainty Value	Probability Distribution	Div.	$c_i$ (1g)	$c_i$ (10g)	Std. Unc. 1g	Std. Unc. 10g
<b>Measurement System</b>							
Probe Calibration	±6.55%	N	1	1	1	±6.55%	±6.55%
Axial Isotropy	±4.7%	R	$\sqrt{3}$	0.7	0.7	±1.9%	±1.9%
Hemispherical Isotropy	±9.6%	R	$\sqrt{3}$	0.7	0.7	±3.9%	±3.9%
Linearity	±4.7%	R	$\sqrt{3}$	1	1	±2.7%	±2.7%
Modulation Response	±2.4%	R	$\sqrt{3}$	1	1	±1.4%	±1.4%
System Detection Limits	±1.0%	R	$\sqrt{3}$	1	1	±0.6%	±0.6%
Boundary effects	±2.0%	R	$\sqrt{3}$	1	1	±1.2%	±1.2%
Readout Electronics	±0.3%	N	1	1	1	±0.3%	±0.3%
Response Time	±0.8%	R	$\sqrt{3}$	1	1	±0.5%	±0.5%
Integration Time	±2.6%	R	$\sqrt{3}$	1	1	±1.5%	±1.5%
RF Ambient Noise	±3.0%	R	$\sqrt{3}$	1	1	±1.7%	±1.7%
RF Ambient Reflections	±3.0%	R	$\sqrt{3}$	1	1	±1.7%	±1.7%
Probe Positioner	±0.8%	R	$\sqrt{3}$	1	1	±0.5%	±0.5%
Probe Positioning	±6.7%	R	$\sqrt{3}$	1	1	±3.9%	±3.9%
Post processing	±4.0%	R	$\sqrt{3}$	1	1	±2.3%	±2.3%
<b>Test Sample Related</b>							
Device Holder	±3.6%	N	1	1	1	±3.6%	±3.6%
Test Sample Positioning	±2.9%	N	1	1	1	±2.9%	±2.9%
Power Scaling	±0%	R	$\sqrt{3}$	1	1	±0%	±0%
Power Drift	±5.0%	R	$\sqrt{3}$	1	1	±2.9%	±2.9%
<b>Phantom and Setup Related</b>							
Phantom Uncertainty	±7.9%	R	$\sqrt{3}$	1	1	±4.6%	±4.6%
SAR correction	±1.9%	R	$\sqrt{3}$	1	0.84	±1.1%	±0.9%
Liquid conductivity (measured)	±2.5%	N	1	0.78	0.71	±2.0%	±1.8%
Liquid permittivity (measured)	±2.5%	N	1	0.26	0.26	±0.1%	±0.1%
Temperature uncertainty - Conductivity	±5.2%	R	$\sqrt{3}$	0.78	0.71	±2.3%	±2.1%
Temperature uncertainty - Permittivity	±0.8%	R	$\sqrt{3}$	0.23	0.26	±0.1%	±0.1%
Combined Standard Uncertainty						±12.8%	±12.7%
<b>Expanded Standard Uncertainty</b>						<b>±25.6%</b>	<b>±25.4%</b>

## 6 Test Conditions and Results

### 6.1 Recipes for Tissue Simulating Liquids

Body Tissue Simulating Liquids					
Ingredient	M 450-B weight (%)	M 900-B weight (%)	M 1800-B weight (%)	M 1950-A weight (%)	M 2450-B weight (%)
Water	46.21	50.75	70.17	69.79	68.64
Sugar	51.17	48.21			
Cellulose	0.18				
Salt	2.34		0.39	0.2	
Preventol	0.08	0.1			
DGBE			29.44	30	31.37
Head Tissue Simulating Liquids					
Ingredient	HSL 450-A weight (%)	HSL 900-B weight (%)	HSL 1800-F weight (%)	HSL 1950-B weight (%)	HSL 2450-B weight (%)
Water	38.91	40.29	55.24	55.41	55
Sugar	56.93	57.9			
Cellulose	0.25	0.24			
Salt	3.79	1.38	0.31	0.08	
Preventol	0.12	0.18			
DGBE			44.45	44.51	45

Water: deionized water, resistivity  $\geq 16 \text{ M}\Omega$

Sugar: refined white sugar

Salt: pure NaCl

Cellulose: Hydroxyethyl-cellulose

Preservative: Preventol D-7

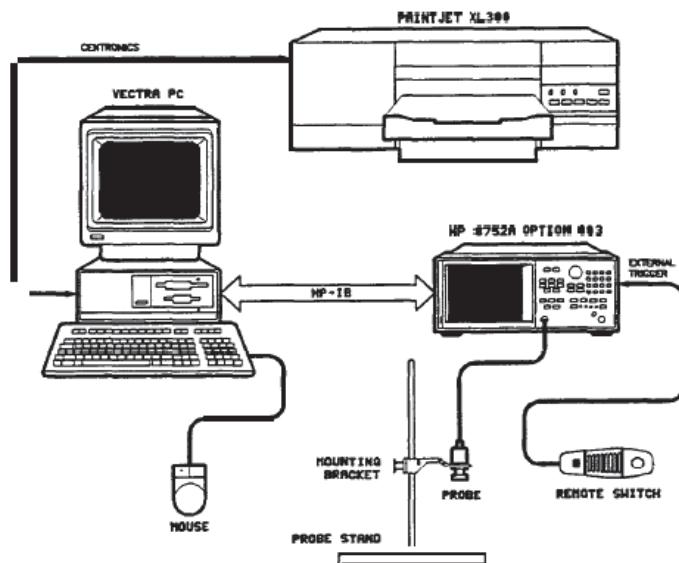
DGBE: Diethylenglycol-monobutyl ether

The parameters for the different frequencies are defined in the corresponding compliance standards (e.g., IEEE 1528-2003, IEC 62209-1)

The HBBL3-6GHz and MBBL 3-6 GHz liquids are direct from Speag.

## 6.2 Test Conditions and Results – Tissue Validation

Tissue Validation acc. to 865664 D01 SAR Measurement 100 MHz to 6 GHz / IC RSS-102					Verdict: PASS
Test according to measurement reference	Reference Method				
	865664 D01 SAR Measurement 100 MHz to 6 GHz				
Target Values					
Frequency [MHz]	Head		Body		Permitted tolerance [%]
	Relative dielectric constant $\epsilon_r$	Conductivity $\sigma$ [S/m]	Relative dielectric constant $\epsilon_r$	Conductivity $\sigma$ [S/m]	
150	52.3	0.76	61.9	0.80	$\leq \pm 5$
300	45.3	0.87	58.2	0.92	$\leq \pm 5$
450	43.5	0.87	56.7	0.94	$\leq \pm 5$
835	41.5	0.90	55.2	0.97	$\leq \pm 5$
900	41.5	0.97	55.0	1.05	$\leq \pm 5$
915	41.5	0.98	55.0	1.06	$\leq \pm 5$
1450	40.5	1.20	54.0	1.30	$\leq \pm 5$
1610	40.3	1.29	53.8	1.40	$\leq \pm 5$
1800 – 2000	40.0	1.40	53.3	1.52	$\leq \pm 5$
2450	39.2	1.80	52.7	1.95	$\leq \pm 5$
3000	38.5	2.40	52.0	2.73	$\leq \pm 5$
5200	36.0	4.66	49.0	5.30	$\leq \pm 5$
5500	35.6	4.96	48.6	5.65	$\leq \pm 5$
5800	35.3	5.27	48.2	6.00	$\leq \pm 5$

**Test setup****Test procedure**

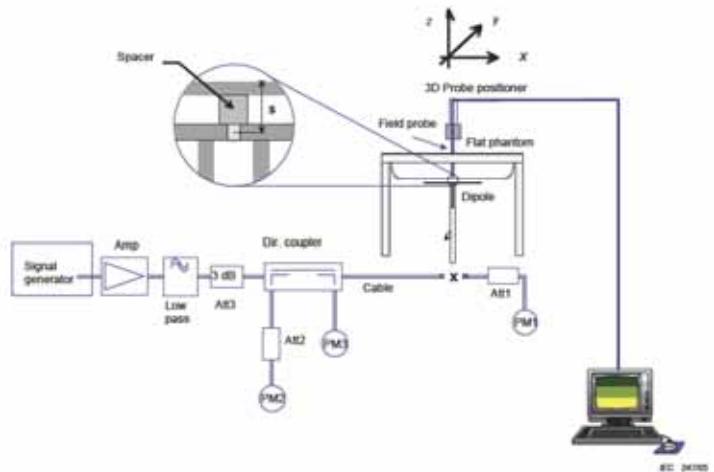
1. The dielectric probe kit is calibrated using the standards air, short circuit and deionized water
2. The tissue simulating liquid is measured using the dielectric probe
3. Target values are compared to the measurement values and deviations are determined

TISSUE VALIDATION									
Room Temperature [°C]					23				
Tissue	Freq. [MHz]	Measured $\epsilon_r$	Target $\epsilon_r$ *	$\Delta \epsilon_r$ [%] **	Measured $\sigma$ [S/m]	Target $\sigma$ [S/m] *	$\Delta \sigma$ [%] **	Operator	Date
MSL-2450	2450	2.01	1.95	03.18	50.55	52.70	-04.08	M. Handrik	18.05.2016
MSL-2450	2405	1.95	1.91	02.09	50.69	52.76	-03.92	M. Handrik	18.05.2016
MSL-2450	2440	2.00	1.94	03.09	50.6	52.71	-04.00	M. Handrik	18.05.2016
MSL-2450	2475	2.06	1.99	03.52	50.44	52.67	-04.23	M. Handrik	18.05.2016

\* The target tissue dielectric properties of the corresponding basic SAR measurement standard apply

\*\* The deviation has to be 5% or lower

### 6.3 Test Conditions and Results – System Validation

System Validation acc. to 865664 D01 SAR Measurement 100 MHz to 6 GHz / IC RSS-102		Verdict: PASS
Test according to measurement reference	Reference Method	865664 D01 SAR Measurement 100 MHz to 6 GHz / IEEE 1528
Test frequency range	Tested frequencies	2450 MHz
Test mode	unmodulated CW	
Target Values		
Frequency [MHz]	Target SAR value [W/kg (1g)]	Permitted tolerance [%]
2450	12.5 @ 250mW	$\leq \pm 10$
The target reference values are taken from the calibration sheets (see annex)		
Test setup		
		
Test procedure		
<ol style="list-style-type: none"> <li>1. The dipole antenna input power is set to 250mW</li> <li>2. The reference dipole is positioned under the phantom</li> <li>3. With the dipole antenna powered the SAR value is measured</li> <li>4. The measured SAR values are compared to the target SAR values</li> </ol>		

SYSTEM VALIDATION – 1g									
Room Temperature [°C]					23				
TSL	Validation Dipole	Measurement Phantom	Validation Frequency [MHz]	Input Power [mW]	Measured SAR (1g) [W/kg]	Target SAR (1g) [W/kg] *	Δ SAR (1g) [%] **	Operator	Date
MSL-2450	D2450V2	ELI 4	2450	250 mW	13.7	12.5	09.60	M. Handrik	18.05.2016

\* See calibration documents of system validation dipole  
\*\* The deviation has to be 10% or lower

#### 6.4 Test Conditions and Results – Standalone SAR Measurement

<b>Standalone SAR acc. to 865664 D01 SAR Measurement 100 MHz to 6 GHz / IC RSS-102</b>		<b>Verdict: PASS</b>
Test according to measurement reference	Reference Method	865664 D01 SAR Measurement 100 MHz to 6 GHz / IC RSS-102 Issue 5
Room temperature	22.0 – 22.6 °C	
Liquid depth	15.5 cm	
Environment	general public	
<b>Limits</b>		
Region	Occupational SAR values [W/kg]	General public SAR values [W/kg]
Whole body average SAR	0.4	0.08
Localized SAR (Head and trunk) SAR averaging mass = 1g	8	1.6
Localized SAR (Limbs) SAR averaging mass = 10g	20	4

SINGLE TRANSMITTER SAR EVALUATION – 1g											
Room Temperature [°C]						23					
Mode	Position	TSL	Phant.	Ch.	Freq. [MHz]	Power Drift [dB]	Measured SAR (1g) [W/kg]	Power Scaling Factor*	Reported SAR (1g) [W/kg] **	Operator	Date
IEEE 802.15.4	TOP	MSL-2450	ELI 4	11	2405	-0.06	0.455	1.413	0.643	M. Handrik	18.05.2016
IEEE 802.15.4	BOTTOM	MSL-2450	ELI 4	11	2405	-0.05	0.712	1.413	<b>1.006</b>	M. Handrik	18.05.2016
IEEE 802.15.4	BOTTOM	MSL-2450	ELI 4	18	2440	0.02	0.000	1.413	0.000	M. Handrik	18.05.2016
IEEE 802.15.4	BOTTOM	MSL-2450	ELI 4	25	2475	-	0.000	1.413	0.000	M. Handrik	18.05.2016
IEEE 802.15.4	RIGHT	MSL-2450	ELI 4	11	2405	0.06	0.127	1.413	0.179	M. Handrik	18.05.2016
IEEE 802.15.4	FRONT	MSL-2450	ELI 4	11	2405	-0.06	0.022	1.413	0.031	M. Handrik	18.05.2016

\* Scaling factor = Max. conducted power (including tune up tolerance) / measured conducted power + duty cycle correction  
 \*\* Reported SAR = Measured SAR \* Scaling Factor

According to KDB 865664 D02 v01r02 only the SAR plots for the highest SAR results for each EUT configuration and operating condition are given in the “SAR Results” part of the report.

## ANNEX A Calibration Documents

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Test Report No.: G0M-1605-5589-TFC093SR-V01

Eurofins Product Service GmbH  
Storkower Str. 38c, D-15526 Reichenwalde, Germany

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Accreditation No.: SCS 0108

Client Eurofins

Certificate No: DAE3-522\_Sep15

## CALIBRATION CERTIFICATE

Object DAE3 - SD 000 D03 AA - SN: 522

Calibration procedure(s) QA CAL-06.v29  
Calibration procedure for the data acquisition electronics (DAE)

Calibration date: September 24, 2015

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).  
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Keithley Multimeter Type 2001	SN: 0810278	09-Sep-15 (No:17153)	Sep-16
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Auto DAE Calibration Unit	SE UWS 053 AA 1001	06-Jan-15 (in house check)	In house check: Jan-16
Calibrator Box V2.1	SE UMS 006 AA 1002	06-Jan-15 (in house check)	In house check: Jan-16

Calibrated by:	Name Eric Hainfeld	Function Technician	Signature 
Approved by:	Fin Bomholt	Deputy Technical Manager	

Issued: September 24, 2015

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## Glossary

DAE	data acquisition electronics
Connector angle	information used in DASY system to align probe sensor X to the robot coordinate system.

## Methods Applied and Interpretation of Parameters

- *DC Voltage Measurement*: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle*: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
  - *DC Voltage Measurement Linearity*: Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
  - *Common mode sensitivity*: Influence of a positive or negative common mode voltage on the differential measurement.
  - *Channel separation*: Influence of a voltage on the neighbor channels not subject to an input voltage.
  - *AD Converter Values with inputs shorted*: Values on the internal AD converter corresponding to zero input voltage
  - *Input Offset Measurement*: Output voltage and statistical results over a large number of zero voltage measurements.
  - *Input Offset Current*: Typical value for information; Maximum channel input offset current, not considering the input resistance.
  - *Input resistance*: Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
  - *Low Battery Alarm Voltage*: Typical value for information. Below this voltage, a battery alarm signal is generated.
  - *Power consumption*: Typical value for information. Supply currents in various operating modes.

## DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB =  $6.1\mu\text{V}$ , full range = -100...+300 mV

Low Range: 1LSB =  $61\text{nV}$ , full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	$404.198 \pm 0.02\% \text{ (k=2)}$	$403.863 \pm 0.02\% \text{ (k=2)}$	$404.698 \pm 0.02\% \text{ (k=2)}$
Low Range	$3.96451 \pm 1.50\% \text{ (k=2)}$	$3.95745 \pm 1.50\% \text{ (k=2)}$	$3.97398 \pm 1.50\% \text{ (k=2)}$

## Connector Angle

Connector Angle to be used in DASY system	$56.0^\circ \pm 1^\circ$
---	--------------------------

## Appendix (Additional assessments outside the scope of SCS0108)

### 1. DC Voltage Linearity

High Range		Reading (µV)	Difference (µV)	Error (%)
Channel X	+ Input	200037.86	0.08	0.00
Channel X	+ Input	20006.75	2.17	0.01
Channel X	- Input	-20001.15	4.82	-0.02
Channel Y	+ Input	200036.95	-0.67	-0.00
Channel Y	+ Input	20005.40	0.94	0.00
Channel Y	- Input	-20001.70	4.35	-0.02
Channel Z	+ Input	200038.78	0.88	0.00
Channel Z	+ Input	20003.12	-1.20	-0.01
Channel Z	- Input	-20004.89	1.37	-0.01

Low Range		Reading (µV)	Difference (µV)	Error (%)
Channel X	+ Input	2000.75	0.01	0.00
Channel X	+ Input	200.67	-0.11	-0.05
Channel X	- Input	-198.63	0.60	-0.30
Channel Y	+ Input	2000.71	0.04	0.00
Channel Y	+ Input	199.25	-1.30	-0.65
Channel Y	- Input	-200.06	-0.69	0.35
Channel Z	+ Input	2000.53	-0.08	-0.00
Channel Z	+ Input	199.47	-1.09	-0.54
Channel Z	- Input	-200.51	-1.14	0.57

### 2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (µV)	Low Range Average Reading (µV)
Channel X	200	-3.92	-5.37
	-200	6.71	5.09
Channel Y	200	-0.54	-0.66
	-200	-0.21	-0.52
Channel Z	200	15.77	15.63
	-200	-17.68	-18.50

### 3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (µV)	Channel Y (µV)	Channel Z (µV)
Channel X	200	-	-2.21	-2.23
Channel Y	200	8.59	-	-0.90
Channel Z	200	5.35	5.42	-

#### 4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15743	17021
Channel Y	15716	14963
Channel Z	16065	17384

#### 5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input  $10M\Omega$

	Average ( $\mu V$ )	min. Offset ( $\mu V$ )	max. Offset ( $\mu V$ )	Std. Deviation ( $\mu V$ )
Channel X	0.97	-0.75	2.41	0.58
Channel Y	0.24	-1.21	1.47	0.58
Channel Z	0.16	-1.04	1.85	0.56

#### 6. Input Offset Current

Nominal Input circuitry offset current on all channels:  $<25fA$

#### 7. Input Resistance (Typical values for information)

	Zeroing (kOhm)	Measuring (MOhm)
Channel X	200	200
Channel Y	200	200
Channel Z	200	200

#### 8. Low Battery Alarm Voltage (Typical values for information)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

#### 9. Power Consumption (Typical values for information)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.01	+6	+14
Supply (- Vcc)	-0.01	-8	-9



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Client **Eurofins**

Certificate No: **EX3-3893\_Oct15**

## CALIBRATION CERTIFICATE

Object **EX3DV4 - SN:3893**

Calibration procedure(s) **QA CAL-01.v9, QA CAL-23.v5, QA CAL-25.v6**  
Calibration procedure for dosimetric E-field probes

Calibration date: **October 22, 2015 (Additional Conversion Factors)**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).  
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature  $(22 \pm 3)^\circ\text{C}$  and humidity  $< 70\%$ .

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	01-Apr-15 (No. 217-02128)	Mar-16
Power sensor E4412A	MY41498087	01-Apr-15 (No. 217-02128)	Mar-16
Reference 3 dB Attenuator	SN: S5054 (3c)	01-Apr-15 (No. 217-02129)	Mar-16
Reference 20 dB Attenuator	SN: S5277 (20x)	01-Apr-15 (No. 217-02132)	Mar-16
Reference 30 dB Attenuator	SN: S5129 (30b)	01-Apr-15 (No. 217-02133)	Mar-16
Reference Probe ES3DV2	SN: 3013	30-Dec-14 (No. ES3-3013_Dec14)	Dec-15
DAE4	SN: 660	14-Jan-15 (No. DAE4-660_Jan15)	Jan-16
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Apr-13)	In house check: Apr-16
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-15)	In house check: Oct-16

Calibrated by:	Name Claudio Leubler	Function Laboratory Technician	Signature 
Approved by:	Katja Pokovic	Technical Manager	

Issued: October 23, 2015

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Accreditation No.: **SCS 0108**

### Glossary:

TSL	tissue simulating liquid
NORM $x,y,z$	sensitivity in free space
ConvF	sensitivity in TSL / NORM $x,y,z$
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C, D	modulation dependent linearization parameters
Polarization $\varphi$	$\varphi$ rotation around probe axis
Polarization $\vartheta$	$\vartheta$ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

### Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005
- IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010
- KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

### Methods Applied and Interpretation of Parameters:

- $NORMx,y,z$ : Assessed for E-field polarization  $\vartheta = 0$  ( $f \leq 900$  MHz in TEM-cell;  $f > 1800$  MHz: R22 waveguide).  $NORMx,y,z$  are only intermediate values, i.e., the uncertainties of  $NORMx,y,z$  does not affect the  $E^2$ -field uncertainty inside TSL (see below ConvF).
- $NORM(f)x,y,z = NORMx,y,z * frequency\_response$  (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- $DCPx,y,z$ : DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- $PAR$ : PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- $Ax,y,z; Bx,y,z; Cx,y,z; Dx,y,z; VRx,y,z; A, B, C, D$  are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters*: Assessed in flat phantom using E-field (or Temperature Transfer Standard for  $f \leq 800$  MHz) and inside waveguide using analytical field distributions based on power measurements for  $f > 800$  MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to  $NORMx,y,z * ConvF$  whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from  $\pm 50$  MHz to  $\pm 100$  MHz.
- Spherical isotropy (3D deviation from isotropy)*: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle*: The angle is assessed using the information gained by determining the  $NORMx$  (no uncertainty required).

# Probe EX3DV4

**SN:3893**

## **Additional Conversion Factors**

Manufactured: October 9, 2012  
Calibrated: October 22, 2015

Calibrated for DASY/EASY Systems  
(Note: non-compatible with DASY2 system!)

## DASY/EASY - Parameters of Probe: EX3DV4 - SN:3893

### Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm $(\mu\text{V}/(\text{V}/\text{m})^2)^{\text{A}}$	0.56	0.42	0.33	$\pm 10.1 \%$
DCP (mV) <sup>B</sup>	99.4	100.6	97.2	

### Modulation Calibration Parameters

UID	Communication System Name		A dB	B dB $\sqrt{\mu\text{V}}$	C	D dB	VR mV	Unc <sup>E</sup> (k=2)
0	CW	X	0.0	0.0	1.0	0.00	153.8	$\pm 3.0 \%$
		Y	0.0	0.0	1.0		144.5	
		Z	0.0	0.0	1.0		142.5	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

<sup>A</sup> The uncertainties of NormX,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Pages 5 and 6).

<sup>B</sup> Numerical linearization parameter: uncertainty not required.

<sup>E</sup> Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

## DASY/EASY - Parameters of Probe: EX3DV4 - SN:3893

### Calibration Parameter Determined in Head Tissue Simulating Media

f (MHz) <sup>C</sup>	Relative Permittivity <sup>F</sup>	Conductivity (S/m) <sup>F</sup>	ConvF X	ConvF Y	ConvF Z	Alpha <sup>G</sup>	Depth <sup>G</sup> (mm)	Unc (k=2)
2450	39.2	1.80	7.47	7.47	7.47	0.24	0.96	± 12.0 %

<sup>C</sup> Frequency validity above 300 MHz of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

<sup>F</sup> At frequencies below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

<sup>G</sup> Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

## DASY/EASY - Parameters of Probe: EX3DV4- SN:3893

### Calibration Parameter Determined in Body Tissue Simulating Media

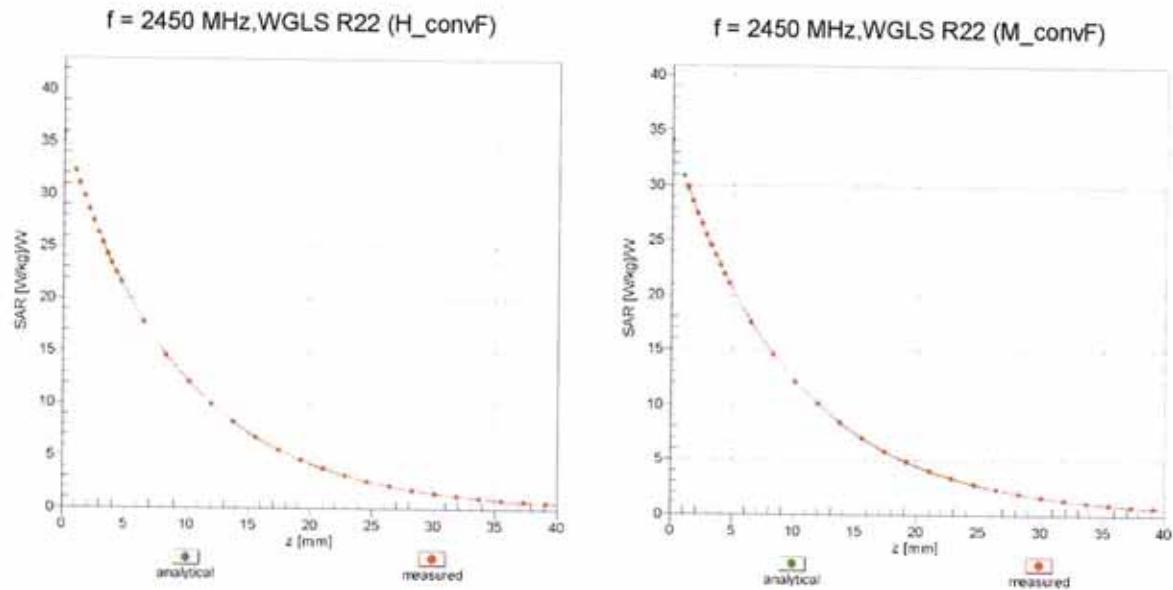
f (MHz) <sup>C</sup>	Relative Permittivity <sup>F</sup>	Conductivity (S/m) <sup>F</sup>	ConvF X	ConvF Y	ConvF Z	Alpha <sup>G</sup>	Depth <sup>G</sup> (mm)	Unc (k=2)
2450	52.7	1.95	7.60	7.60	7.60	0.27	0.80	± 12.0 %

<sup>C</sup> Frequency validity above 300 MHz of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

<sup>F</sup> At frequencies below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

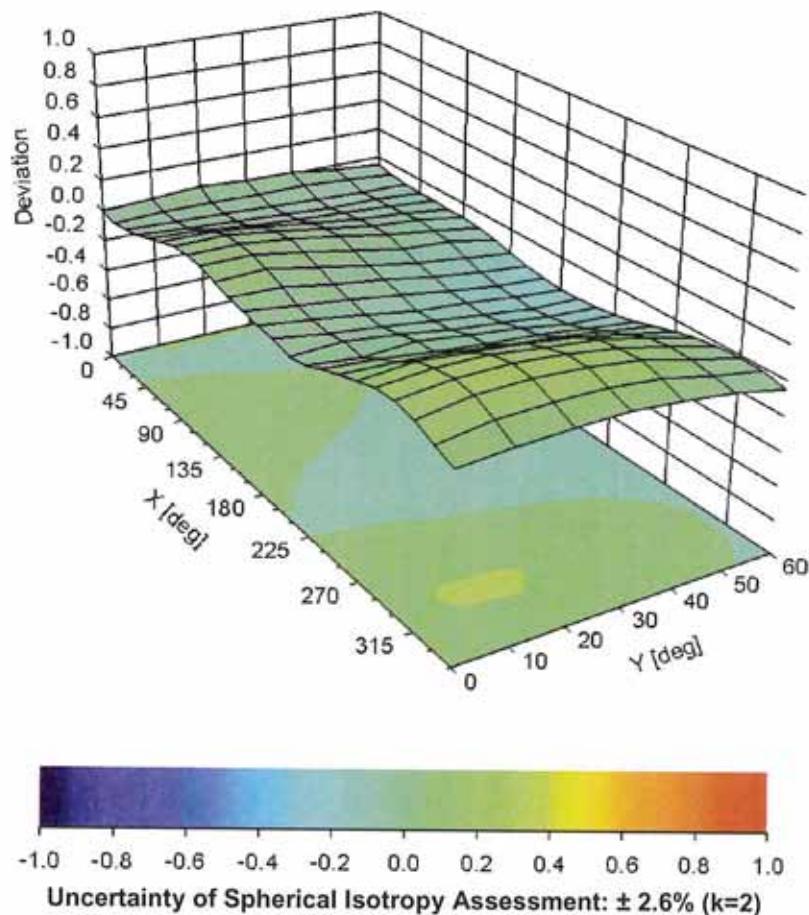
<sup>G</sup> Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

## Conversion Factor Assessment



## Deviation from Isotropy in Liquid

Error ( $\phi, \theta$ ),  $f = 900 \text{ MHz}$



## DASY/EASY - Parameters of Probe: EX3DV4 - SN:3893

### Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle (°)	-22.1
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	9 mm
Tip Diameter	2.5 mm
Probe Tip to Sensor X Calibration Point	1 mm
Probe Tip to Sensor Y Calibration Point	1 mm
Probe Tip to Sensor Z Calibration Point	1 mm
Recommended Measurement Distance from Surface	1.4 mm



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The Swiss Accreditation Service is one of the signatories to the EA  
 Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 0108**

Client **Eurofins**

Certificate No: **D2450V2-722\_Sep15**

## CALIBRATION CERTIFICATE

Object **D2450V2 - SN: 722**

Calibration procedure(s) **QA CAL-05.v9**  
 Calibration procedure for dipole validation kits above 700 MHz

Calibration date: **September 28, 2015**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).  
 The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature  $(22 \pm 3)^\circ\text{C}$  and humidity  $< 70\%$ .

### Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter EPM-442A	GB37480704	07-Oct-14 (No. 217-02020)	Oct-15
Power sensor HP 8481A	US37292783	07-Oct-14 (No. 217-02020)	Oct-15
Power sensor HP 8481A	MY41092317	07-Oct-14 (No. 217-02021)	Oct-15
Reference 20 dB Attenuator	SN: 5058 (20k)	01-Apr-15 (No. 217-02131)	Mar-16
Type-N mismatch combination	SN: 5047.2 / 06327	01-Apr-15 (No. 217-02134)	Mar-16
Reference Probe EX3DV4	SN: 7349	30-Dec-14 (No. EX3-7349_Dec14)	Dec-15
DAE4	SN: 601	17-Aug-15 (No. DAE4-601_Aug15)	Aug-16
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator R&S SMT-06	100972	15-Jun-15 (in house check Jun-15)	In house check: Jun-18
Network Analyzer HP 8753E	US37390585 S4206	18-Oct-01 (in house check Oct-14)	In house check: Oct-15

Calibrated by: Name **Jeton Kastrati** Function **Laboratory Technician**  
 Approved by: Name **Katja Pokovic** Function **Technical Manager**

Issued: September 28, 2015

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.



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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: SCS 0108

#### **Glossary:**

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

#### **Calibration is Performed According to the Following Standards:**

- a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005
- c) IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010
- d) KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

#### **Additional Documentation:**

- e) DASY4/5 System Handbook

#### **Methods Applied and Interpretation of Parameters:**

- *Measurement Conditions:* Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- *Antenna Parameters with TSL:* The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- *Feed Point Impedance and Return Loss:* These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- *Electrical Delay:* One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- *SAR measured:* SAR measured at the stated antenna input power.
- *SAR normalized:* SAR as measured, normalized to an input power of 1 W at the antenna connector.
- *SAR for nominal TSL parameters:* The measured TSL parameters are used to calculate the nominal SAR result.

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor  $k=2$ , which for a normal distribution corresponds to a coverage probability of approximately 95%.

## Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY5	V52.8.8
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom	
Distance Dipole Center - TSL	10 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	2450 MHz $\pm$ 1 MHz	

## Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	39.2	1.80 mho/m
Measured Head TSL parameters	(22.0 $\pm$ 0.2) °C	39.2 $\pm$ 6 %	1.86 mho/m $\pm$ 6 %
Head TSL temperature change during test	< 0.5 °C	----	----

## SAR result with Head TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	12.7 W/kg
SAR for nominal Head TSL parameters	normalized to 1W	50.0 W/kg $\pm$ 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Head TSL	condition	
SAR measured	250 mW input power	5.90 W/kg
SAR for nominal Head TSL parameters	normalized to 1W	23.4 W/kg $\pm$ 16.5 % (k=2)

## Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	52.7	1.95 mho/m
Measured Body TSL parameters	(22.0 $\pm$ 0.2) °C	53.2 $\pm$ 6 %	2.00 mho/m $\pm$ 6 %
Body TSL temperature change during test	< 0.5 °C	----	----

## SAR result with Body TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	12.5 W/kg
SAR for nominal Body TSL parameters	normalized to 1W	49.5 W/kg $\pm$ 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Body TSL	condition	
SAR measured	250 mW input power	5.88 W/kg
SAR for nominal Body TSL parameters	normalized to 1W	23.4 W/kg $\pm$ 16.5 % (k=2)

## Appendix (Additional assessments outside the scope of SCS 0108)

### Antenna Parameters with Head TSL

Impedance, transformed to feed point	$51.7 \Omega + 9.2 j\Omega$
Return Loss	- 20.8 dB

### Antenna Parameters with Body TSL

Impedance, transformed to feed point	$46.3 \Omega + 8.6 j\Omega$
Return Loss	- 20.2 dB

### General Antenna Parameters and Design

Electrical Delay (one direction)	1.152 ns
----------------------------------	----------

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. On some of the dipoles, small end caps are added to the dipole arms in order to improve matching when loaded according to the position as explained in the "Measurement Conditions" paragraph. The SAR data are not affected by this change. The overall dipole length is still according to the Standard.

No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

### Additional EUT Data

Manufactured by	SPEAG
Manufactured on	October 16, 2002

# DASY5 Validation Report for Head TSL

Date: 28.09.2015

Test Laboratory: SPEAG, Zurich, Switzerland

**DUT: Dipole 2450 MHz ; Type: D2450V2; Serial: D2450V2 - SN: 722**

Communication System: UID 0 - CW; Frequency: 2450 MHz

Medium parameters used:  $f = 2450$  MHz;  $\sigma = 1.86$  S/m;  $\epsilon_r = 39.2$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY52 Configuration:

- Probe: EX3DV4 - SN7349; ConvF(7.67, 7.67, 7.67); Calibrated: 30.12.2014;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 17.08.2015
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; Serial: 1001
- DASY52 52.8.8(1222); SEMCAD X 14.6.10(7331)

## Dipole Calibration for Head Tissue/Pin=250 mW, d=10mm/Zoom Scan (7x7x7)/Cube 0:

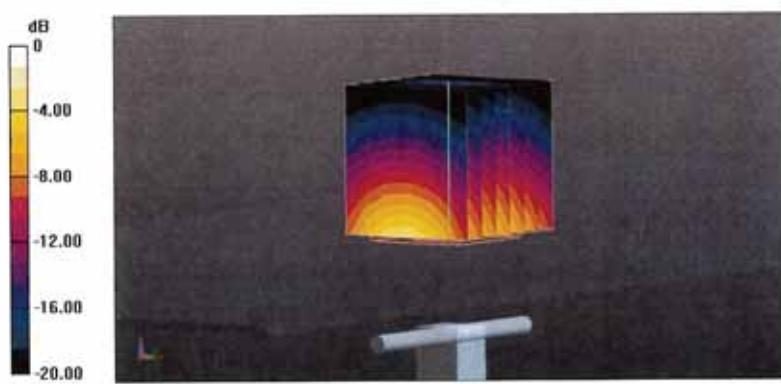
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 111.4 V/m; Power Drift = 0.00 dB

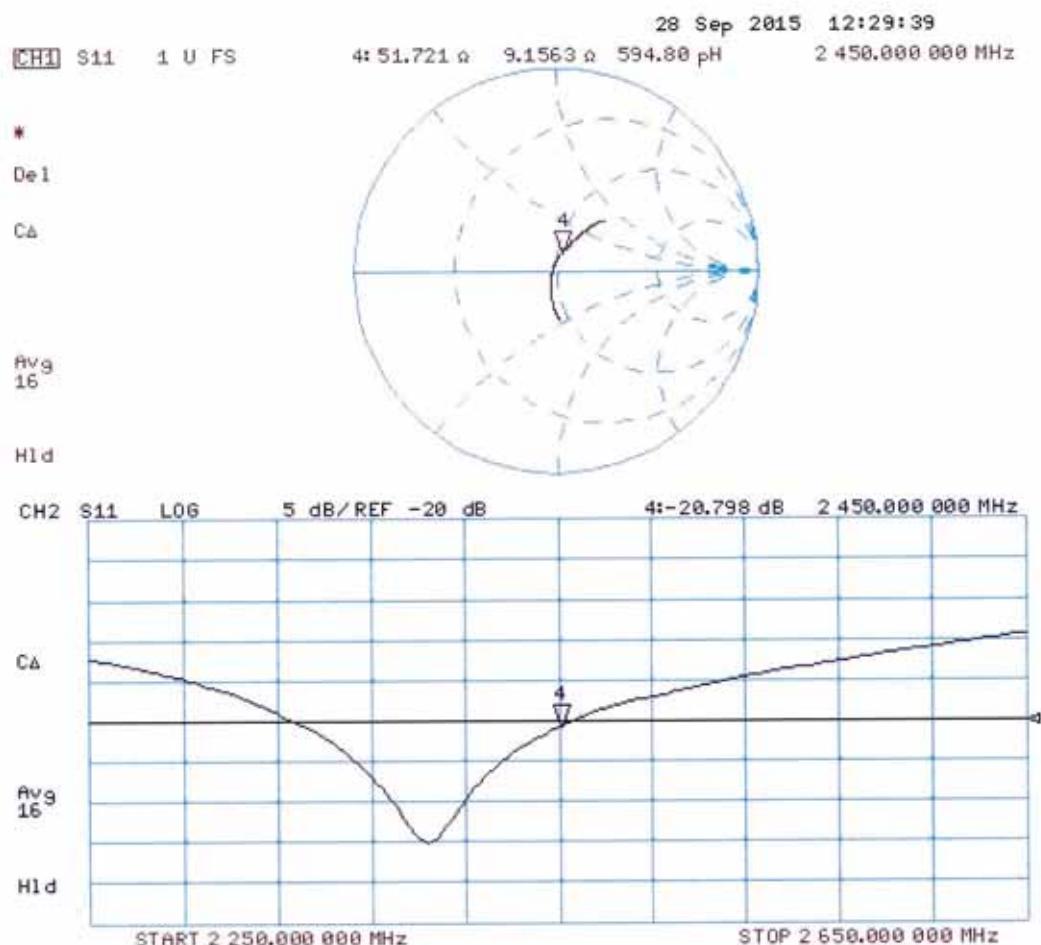
Peak SAR (extrapolated) = 26.1 W/kg

**SAR(1 g) = 12.7 W/kg; SAR(10 g) = 5.9 W/kg**

Maximum value of SAR (measured) = 21.1 W/kg



## Impedance Measurement Plot for Head TSL



# DASY5 Validation Report for Body TSL

Date: 28.09.2015

Test Laboratory: SPEAG, Zurich, Switzerland

**DUT: Dipole 2450 MHz ; Type: D2450V2; Serial: D2450V2 - SN: 722**

Communication System: UID 0 - CW; Frequency: 2450 MHz

Medium parameters used:  $f = 2450$  MHz;  $\sigma = 2$  S/m;  $\epsilon_r = 53.2$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY52 Configuration:

- Probe: EX3DV4 - SN7349; ConvF(7.53, 7.53, 7.53); Calibrated: 30.12.2014;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 17.08.2015
- Phantom: Flat Phantom 5.0 (back); Type: QD000P50AA; Serial: 1002
- DASY52 52.8.8(1222); SEMCAD X 14.6.10(7331)

## Dipole Calibration for Body Tissue/Pin=250 mW, d=10mm/Zoom Scan (7x7x7)/Cube 0:

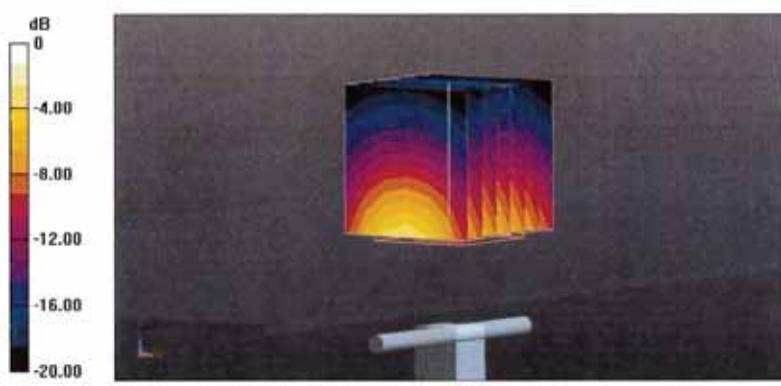
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 105.8 V/m; Power Drift = -0.01 dB

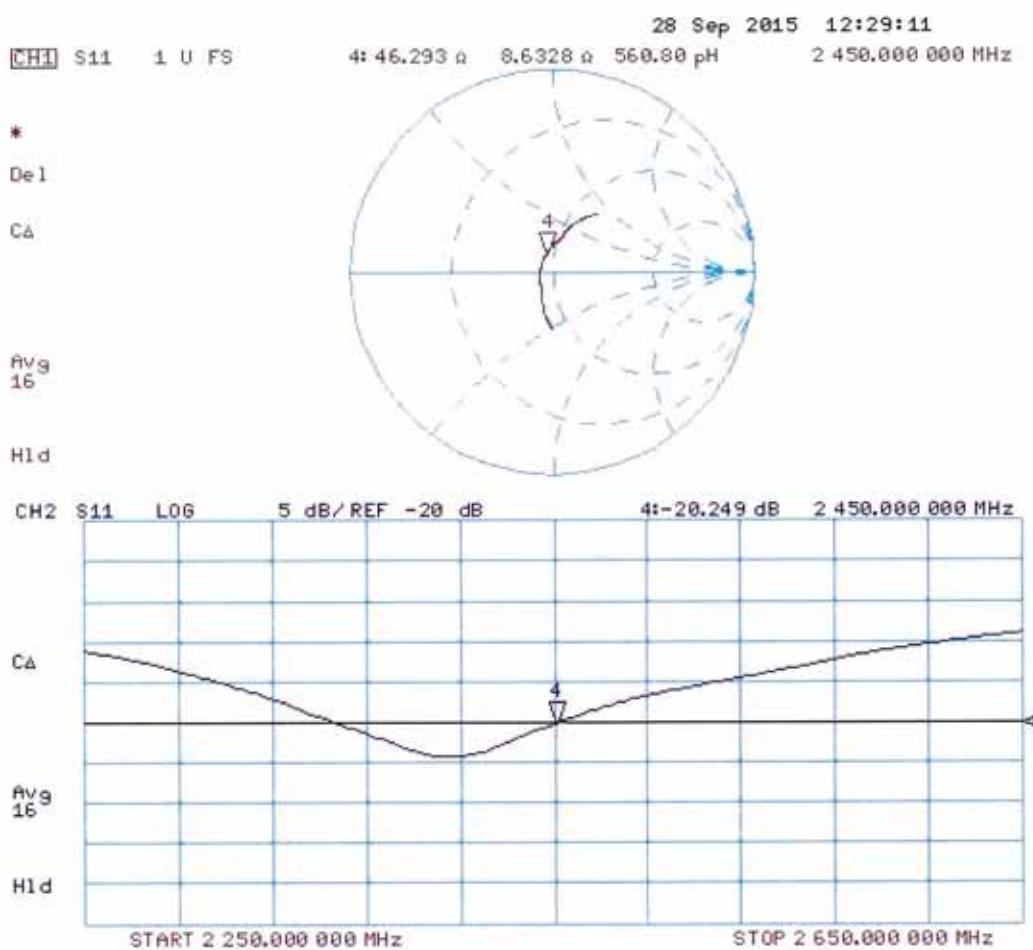
Peak SAR (extrapolated) = 24.7 W/kg

**SAR(1 g) = 12.5 W/kg; SAR(10 g) = 5.88 W/kg**

Maximum value of SAR (measured) = 20.5 W/kg



## Impedance Measurement Plot for Body TSL



## ANNEX B System Validation Reports

Test Laboratory: Eurofins Product Service GmbH

**System Performance Check - ELI Phantom - EX3DV6 - MSL - 2450 MHz\_18\_05\_2016**

**DUT: Dipole 2450 MHz; Type: D2450V2; Serial: 722**

Communication System: UID 0 - n/a, CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: Muscle 2450 MHz Medium parameters used (interpolated):  $f = 2450$  MHz;  $\sigma = 2.012$  S/m;  $\epsilon_r = 50.554$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

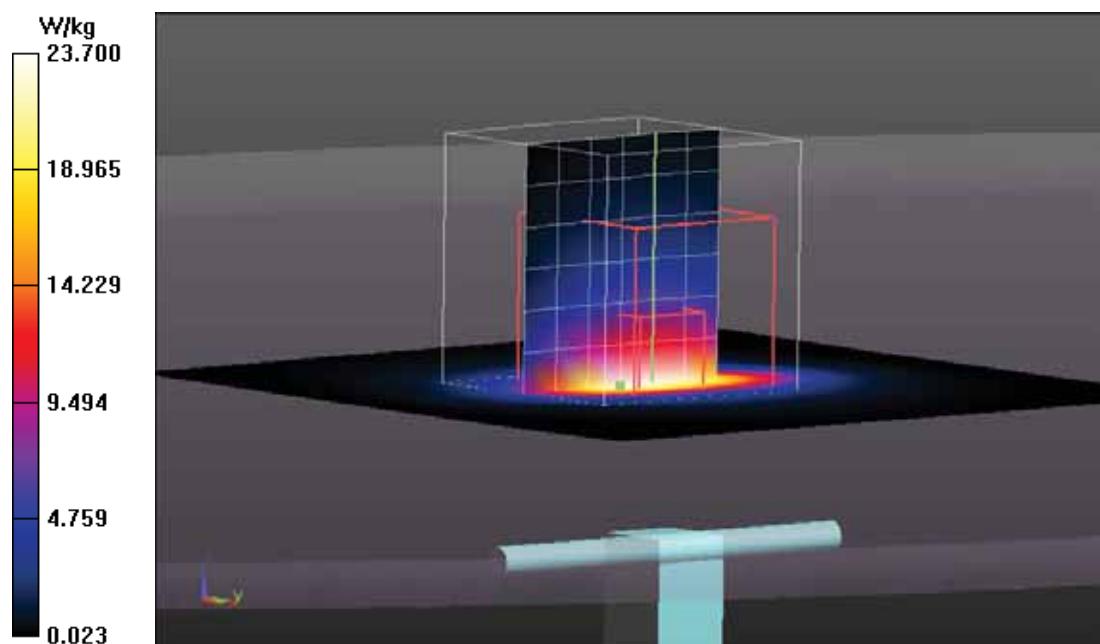
Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

**DASY5.2 Configuration:**

- Probe: EX3DV4 - SN3893 (add ConvF); ConvF(7.6, 7.6, 7.6); Calibrated: 10/22/2015;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/24/2015
- Phantom: Flat Phantom ELI4.0; Type: QDOVA001BB; Serial: SN:1013
- Measurement SW: DASY52, Version 52.8 (6); SEMCAD X Version 14.6.9 (7117)

**System Performance Check at Frequencies above 1 GHz/d=10mm, Pin=250 mW, dist=1.4mm (EX-Probe)/Area Scan (61x61x1):** Interpolated grid: dx=1.500 mm, dy=1.500 mm  
Maximum value of SAR (interpolated) = 23.7 W/kg

**System Performance Check at Frequencies above 1 GHz/d=10mm, Pin=250 mW, dist=1.4mm (EX-Probe)/Zoom Scan (7x7x7) (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm  
Reference Value = 108.3 V/m; Power Drift = -0.07 dB  
Peak SAR (extrapolated) = 28.5 W/kg  
**SAR(1 g) = 13.7 W/kg; SAR(10 g) = 6.36 W/kg**  
Maximum value of SAR (measured) = 22.6 W/kg



## ANNEX C SAR Measurement Reports

**Test Laboratory: Eurofins Product Service GmbH****IEEE 802\_15\_4 Ch 11 - flat bottom 5mm****DUT: ZigBee USB Stick; Type: -; Serial: -**

Communication System: UID 0 - n/a, IEEE 802.15.4; Frequency: 2405 MHz; Duty Cycle: 1:1  
 Medium: Muscle 2450 MHz Medium parameters used (interpolated):  $f = 2405$  MHz;  $\sigma = 1.95$  S/m;  $\epsilon_r = 50.686$ ;  
 $\rho = 1000$  kg/m<sup>3</sup>  
 Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

**DASY5.2 Configuration:**

- Probe: EX3DV4 - SN3893 (add ConvF); ConvF(7.6, 7.6, 7.6); Calibrated: 10/22/2015;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/24/2015
- Phantom: Flat Phantom ELI4.0; Type: QDOVA001BB; Serial: SN:1013
- Measurement SW: DASY52, Version 52.8 (6); SEMCAD X Version 14.6.9 (7117)

**System Performance Check at Frequencies above 1 GHz/Flat bottom 5mm (EX-Probe)/Area****Scan (71x121x1):** Interpolated grid: dx=1.000 mm, dy=1.000 mm

Maximum value of SAR (interpolated) = 1.12 W/kg

**System Performance Check at Frequencies above 1 GHz/Flat bottom 5mm (EX-Probe)/Zoom****Scan (7x7x7) (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 19.847 V/m; Power Drift = -0.05 dB

Peak SAR (extrapolated) = 1.31 W/kg

**SAR(1 g) = 0.712 W/kg; SAR(10 g) = 0.351 W/kg**

Maximum value of SAR (measured) = 1.08 W/kg

