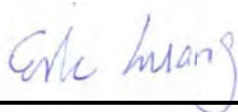


# FCC SAR Test Report

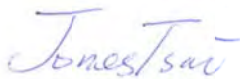
APPLICANT : Doro AB  
EQUIPMENT : Mobile Telephone  
BRAND NAME : doro  
MODEL NAME : Doro PhoneEasy 632  
MARKETING NAME : Doro PhoneEasy 632  
FCC ID : WS5DORO632  
STANDARD : FCC 47 CFR Part 2 (2.1093)  
ANSI/IEEE C95.1-1992  
IEEE 1528-2003

We, SPORTON INTERNATIONAL (SHENZHEN) INC., would like to declare that the tested sample has been evaluated in accordance with the procedures and shown the compliance with the applicable technical standards.

The test results in this report apply exclusively to the tested model / sample. Without written approval of SPORTON INTERNATIONAL (SHENZHEN) INC., the test report shall not be reproduced except in full.



Reviewed by: Eric Huang / Deputy Manager



Approved by: Jones Tsai / Manager



**SPORTON INTERNATIONAL (SHENZHEN) INC.**

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FCC ID : WS5DORO632

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Issued Date : Jul. 07, 2014

Form version : 140305



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## Revision History

REPORT NO.	VERSION	DESCRIPTION	ISSUED DATE
FA451707	Rev. 01	Initial issue of report	Jul. 07, 2014



## **1. Statement of Compliance**

The maximum results of Specific Absorption Rate (SAR) found during testing for **Doro AB, Mobile Telephone, Doro PhoneEasy 632**, are as follows.

Equipment Class	Frequency Band	Operating Mode	Highest SAR Summary		
			Head 1g SAR (W/kg)	Body-worn 1g SAR (W/kg) (Separation 1.5cm)	Simultaneous Transmission SAR (W/kg)
PCE	GSM1900	Voice/Data	0.17	0.28	0.55
DSS	Bluetooth	Data	-	-	0.55
Date of Testing:			06/04/2014 ~ 06/13/2014		

This device is in compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (1.6 W/kg) specified in FCC 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1-1992, and had been tested in accordance with the measurement methods and procedures specified in IEEE 1528-2003.

## 2. Administration Data

Testing Laboratory	
Test Site	SPORTON INTERNATIONAL (SHENZHEN) INC.
Test Site Location	No. 101, Complex Building C, Guanlong Village, Xili Town, Nanshan District, Shenzhen, Guangdong, P.R.C. TEL: +86-755-8637-9589 FAX: +86-755-8637-9595

Applicant	
Company Name	Doro AB
Address	Magistratsvägen 10 SE-226 43 Lund Sweden

Manufacturer	
Company Name	CK TELECOM LTD.
Address	Technology Road, High-Tech Development Zone, Heyuan, Guangdong, P. R. China.

## 3. Guidance Standard

The Specific Absorption Rate (SAR) testing specification, method, and procedure for this device is in accordance with the following standards:

- FCC 47 CFR Part 2 (2.1093)
- ANSI/IEEE C95.1-1992
- IEEE 1528-2003
- FCC KDB 865664 D01 SAR Measurement 100 MHz to 6 GHz v01r03
- FCC KDB 865664 D02 SAR Reporting v01r01
- FCC KDB 447498 D01 General RF Exposure Guidance v05r02
- FCC KDB 648474 D04 SAR Evaluation Considerations for Wireless Handsets v01r02
- FCC KDB 941225 D03 SAR Test Reduction GSM GPRS EDGE v01
-

## **4. Equipment Under Test (EUT)**

### **4.1 General Information**

Product Feature & Specification	
Equipment Name	Mobile Telephone
Brand Name	doro
Model Name	Doro PhoneEasy 632
Marketing Name	Doro PhoneEasy 632
FCC ID	WS5DORO632
IMEI Code	352427060006664
Wireless Technology and Frequency Range	GSM1900: 1850.2 MHz ~ 1909.8 MHz Bluetooth: 2402 MHz ~ 2480 MHz
Mode	<ul style="list-style-type: none"> <li>• GSM/GPRS</li> <li>• Bluetooth v2.1+EDR</li> </ul>
HW Version	SHUTTLE-V2.0
SW Version	SHUTTLE02A-S01A_DORO632_L17EN_118_140616
GSM / (E)GPRS Transfer mode	Class B – EUT cannot support Packet Switched and Circuit Switched Network simultaneously but can automatically switch between Packet and Circuit Switched Network.
EUT Stage	Production Unit
<b>Remark:</b> <ol style="list-style-type: none"> <li>1. This device supports GRPS mode up to multi-slot class12.</li> <li>2. This device does not support DTM operation.</li> <li>3. This device has no VOIP function.</li> </ol>	

**4.2 Maximum Tune-up Limit**

Mode	Burst average power(dBm)
	GSM 1900
GSM (GMSK, 1 Tx slot)	31
GPRS (GMSK, 1 Tx slot)	31
GPRS (GMSK, 2 Tx slots)	30
GPRS (GMSK, 3 Tx slots)	28
GPRS (GMSK, 4 Tx slots)	27

Mode	Maximum Average Power (dBm)
Bluetooth v2.1+EDR	9.5

## **5. RF Exposure Limits**

### **5.1 Uncontrolled Environment**

Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure. The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity.

### **5.2 Controlled Environment**

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation). In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. The exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means.

**Limits for Occupational/Controlled Exposure (W/kg)**

Whole-Body	Partial-Body	Hands, Wrists, Feet and Ankles
0.4	8.0	20.0

**Limits for General Population/Uncontrolled Exposure (W/kg)**

Whole-Body	Partial-Body	Hands, Wrists, Feet and Ankles
0.08	1.6	4.0

1. Whole-Body SAR is averaged over the entire body, partial-body SAR is averaged over any 1gram of tissue defined as a tissue volume in the shape of a cube. SAR for hands, wrists, feet and ankles is averaged over any 10 grams of tissue defined as a tissue volume in the shape of a cube.



## 6. Specific Absorption Rate (SAR)

### 6.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

### 6.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho dv} \right)$$

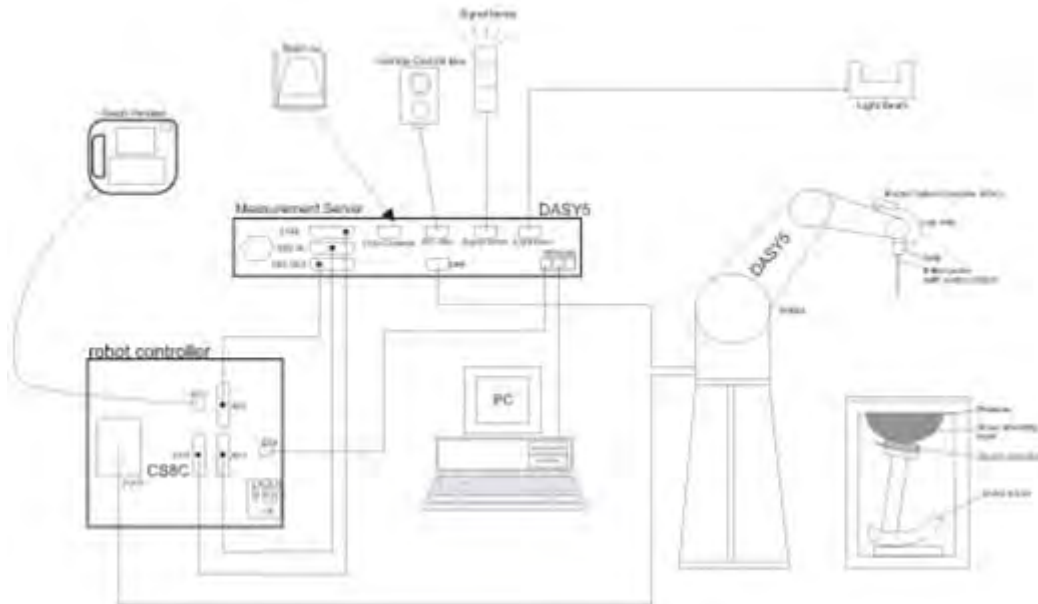
SAR is expressed in units of Watts per kilogram (W/kg)

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where: σ is the conductivity of the tissue, ρ is the mass density of the tissue and E is the RMS electrical field strength.

## **7. System Description and Setup**

The DASY system used for performing compliance tests consists of the following items:



- A standard high precision 6-axis robot with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic Field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP or Win7 and the DASY5 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.

## **8. Measurement Procedures**

The measurement procedures are as follows:

### <Conducted power measurement>

- (a) For WWAN power measurement, use base station simulator to configure EUT WWAN transmission in conducted connection with RF cable, at maximum power in each supported wireless interface and frequency band.
- (b) Read the WWAN RF power level from the base station simulator.
- (c) For BT power measurement, use engineering software to configure EUT BT continuously transmission, at maximum RF power in each supported wireless interface and frequency band
- (d) Connect EUT RF port through RF cable to the power meter, and measure BT output power

### <SAR measurement>

- (a) Use base station simulator to configure EUT WWAN transmission in radiated connection, and engineering software to configure EUT BT continuously transmission, at maximum RF power, in the highest power channel.
- (b) Place the EUT in the positions as Appendix D demonstrates.
- (c) Set scan area, grid size and other setting on the DASY software.
- (d) Measure SAR results for the highest power channel on each testing position.
- (e) Find out the largest SAR result on these testing positions of each band
- (f) Measure SAR results for other channels in worst SAR testing position if the reported SAR of highest power channel is larger than 0.8 W/kg

According to the test standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- (a) Power reference measurement
- (b) Area scan
- (c) Zoom scan
- (d) Power drift measurement

### **8.1 Spatial Peak SAR Evaluation**

The procedure for spatial peak SAR evaluation has been implemented according to the test standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

The entire evaluation of the spatial peak values is performed within the post-processing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- (a) Extraction of the measured data (grid and values) from the Zoom Scan
- (b) Calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- (c) Generation of a high-resolution mesh within the measured volume
- (d) Interpolation of all measured values from the measurement grid to the high-resolution grid
- (e) Extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- (f) Calculation of the averaged SAR within masses of 1g and 10g

## 8.2 Power Reference Measurement

The Power Reference Measurement and Power Drift Measurements are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface determines the closest measurement point to phantom surface. This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties.

## 8.3 Area Scan

The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in DASY software can find the maximum found in the scanned area, within a range of the global maximum. The range (in dB0) is specified in the standards for compliance testing. For example, a 2 dB range is required in IEEE standard 1528 and IEC 62209 standards, whereby 3 dB is a requirement when compliance is assessed in accordance with the ARIB standard (Japan), if only one zoom scan follows the area scan, then only the absolute maximum will be taken as reference. For cases where multiple maximums are detected, the number of zoom scans has to be increased accordingly.

Area scan parameters extracted from FCC KDB 865664 D01v01r03 SAR measurement 100 MHz to 6 GHz.

	$\leq 3$ GHz	$> 3$ GHz
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	$5 \pm 1$ mm	$\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5$ mm
Maximum probe angle from probe axis to phantom surface normal at the measurement location	$30^\circ \pm 1^\circ$	$20^\circ \pm 1^\circ$
Maximum area scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$	$\leq 2$ GHz: $\leq 15$ mm $2 - 3$ GHz: $\leq 12$ mm	$3 - 4$ GHz: $\leq 12$ mm $4 - 6$ GHz: $\leq 10$ mm
	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be $\leq$ the corresponding x or y dimension of the test device with at least one measurement point on the test device.	

## 8.4 Zoom Scan

Zoom scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 gram and 10 gram of simulated tissue. The zoom scan measures points (refer to table below) within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the zoom scan evaluates the averaged SAR for 1 gram and 10 gram and displays these values next to the job's label.

Zoom scan parameters extracted from FCC KDB 865664 D01v01r03 SAR measurement 100 MHz to 6 GHz.

			$\leq 3$ GHz	$> 3$ GHz
Maximum zoom scan spatial resolution: $\Delta x_{\text{Zoom}}, \Delta y_{\text{Zoom}}$			$\leq 2$ GHz: $\leq 8$ mm 2 – 3 GHz: $\leq 5$ mm*	3 – 4 GHz: $\leq 5$ mm* 4 – 6 GHz: $\leq 4$ mm*
Maximum zoom scan spatial resolution, normal to phantom surface	uniform grid: $\Delta z_{\text{Zoom}}(n)$		$\leq 5$ mm	3 – 4 GHz: $\leq 4$ mm 4 – 5 GHz: $\leq 3$ mm 5 – 6 GHz: $\leq 2$ mm
	graded grid	$\Delta z_{\text{Zoom}}(1)$ : between 1 <sup>st</sup> two points closest to phantom surface	$\leq 4$ mm	3 – 4 GHz: $\leq 3$ mm 4 – 5 GHz: $\leq 2.5$ mm 5 – 6 GHz: $\leq 2$ mm
		$\Delta z_{\text{Zoom}}(n>1)$ : between subsequent points	$\leq 1.5 \cdot \Delta z_{\text{Zoom}}(n-1)$	
Minimum zoom scan volume	x, y, z		$\geq 30$ mm	3 – 4 GHz: $\geq 28$ mm 4 – 5 GHz: $\geq 25$ mm 5 – 6 GHz: $\geq 22$ mm
Note: $\delta$ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.				
* When zoom scan is required and the <i>reported</i> SAR from the <i>area scan based 1-g SAR estimation</i> procedures of KDB 447498 is $\leq 1.4$ W/kg, $\leq 8$ mm, $\leq 7$ mm and $\leq 5$ mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.				

## 8.5 Volume Scan Procedures

The volume scan is used to assess overlapping SAR distributions for antennas transmitting in different frequency bands. It is equivalent to an oversized zoom scan used in standalone measurements. The measurement volume will be used to enclose all the simultaneous transmitting antennas. For antennas transmitting simultaneously in different frequency bands, the volume scan is measured separately in each frequency band. In order to sum correctly to compute the 1g aggregate SAR, the EUT remain in the same test position for all measurements and all volume scan use the same spatial resolution and grid spacing. When all volume scan were completed, the software, SEMCAD postprocessor can combine and subsequently superpose these measurement data to calculating the multiband SAR.

## 8.6 Power Drift Monitoring

All SAR testing is under the EUT install full charged battery and transmit maximum output power. In DASY measurement software, the power reference measurement and power drift measurement procedures are used for monitoring the power drift of EUT during SAR test. Both these procedures measure the field at a specified reference position before and after the SAR testing. The software will calculate the field difference in dB. If the power drifts more than 5%, the SAR will be retested.

## 9. Test Equipment List

Manufacturer	Name of Equipment	Type/Model	Serial Number	Calibration	
				Last Cal.	Due Date
SPEAG	1900MHz System Validation Kit	D1900V2	5d118	Nov. 21, 2011	Nov. 14, 2014
SPEAG	Data Acquisition Electronics	DAE4	910	Dec.17, 2013	Dec.16, 2014
SPEAG	Data Acquisition Electronics	DAE3	569	Nov. 22, 2013	Nov. 21, 2014
SPEAG	Dosimetric E-Field Probe	EX3DV4	3819	Nov. 27, 2013	Nov. 26, 2014
SPEAG	SAM Twin Phantom	QD 000 P40 CD	TP-1670	NCR	NCR
SPEAG	SAM Twin Phantom	QD 000 P40 CD	TP-1671	NCR	NCR
SPEAG	Phone Positioner	N/A	N/A	NCR	NCR
Agilent	Wireless Communication Test Set	E5515C	MY50267224	Oct. 10, 2013	Oct. 09, 2014
R&S	Network Analyzer	ZVB8	100106	Nov.07, 2013	Nov. 06, 2014
SPEAG	Dielectric Assessment KIT	DAK-3.5	1032	NCR	NCR
Anritsu	Power Meter	ML2495A	1218010	Mar. 03, 2014	Mar. 02, 2015
Anritsu	Power Sensor	MA2411B	1207253	Mar. 03, 2014	Mar. 02, 2015
Agilent	Dual Directional Coupler	778D	50422	Note 2	
Woken	Attenuator	WK0602-XX	N/A	Note 2	
PE	Attenuator	PE7005-10	N/A	Note 2	
PE	Attenuator	PE7005- 3	N/A	Note 2	
AR	Power Amplifier	5S1G4M2	0328767	Note 2	
Mini-Circuits	Power Amplifier	ZVE-3W	162601250	Note 2	
Mini-Circuits	Power Amplifier	ZHL-42W+	13440021344	Note 2	

**General Note:**

1. Prior to system verification and validation, the path loss from the signal generator to the system check source and the power meter, which includes the amplifier, cable, attenuator and directional coupler, was measured by the network analyzer. The reading of the power meter was offset by the path loss difference between the path to the power meter and the path to the system check source to monitor the actual power level fed to the system check source.
2. Referring to KDB 865664 D01v01r03, the dipole calibration interval can be extended to 3 years with justification. The dipoles are also not physically damaged, or repaired during the interval.
3. The justification data of dipole D1900V2, SN: 5d118 can be found in appendix C. The return loss is < -20dB, within 20% of prior calibration, the impedance is within 5 ohm of prior calibration.

## 10. System Verification

### 10.1 Tissue Verification

The following tissue formulations are provided for reference only as some of the parameters have not been thoroughly verified. The composition of ingredients may be modified accordingly to achieve the desired target tissue parameters required for routine SAR evaluation.

Frequency (MHz)	Water (%)	Sugar (%)	Cellulose (%)	Salt (%)	Preventol (%)	DGBE (%)	Conductivity ( $\sigma$ )	Permittivity ( $\epsilon_r$ )
For Head								
1800, 1900, 2000	55.2	0	0	0.3	0	44.5	1.40	40.0
For Body								
1800, 1900, 2000	70.2	0	0	0.4	0	29.4	1.52	53.3

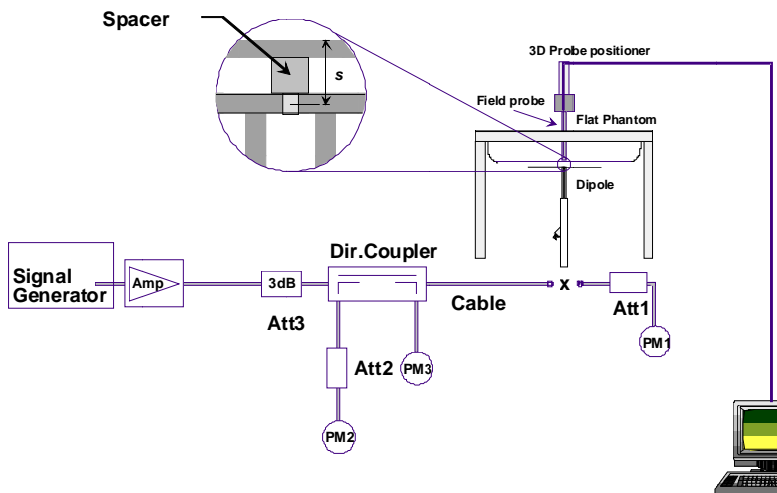
### <Tissue Dielectric Parameter Check Results>

Frequency (MHz)	Tissue Type	Liquid Temp. (°C)	Conductivity ( $\sigma$ )	Permittivity ( $\epsilon_r$ )	Conductivity Target ( $\sigma$ )	Permittivity Target ( $\epsilon_r$ )	Delta ( $\sigma$ ) (%)	Delta ( $\epsilon_r$ ) (%)	Limit (%)	Date
1900	Head	22.6	1.422	38.942	1.40	40.00	1.57	-2.65	±5	2014/6/4
1900	Body	22.8	1.545	53.535	1.52	53.30	1.64	0.44	±5	2014/6/13

## 10.2 System Performance Check Results

Comparing to the original SAR value provided by SPEAG, the verification data should be within its specification of 10 %. Below table shows the target SAR and measured SAR after normalized to 1W input power. The table below indicates the system performance check can meet the variation criterion and the plots can be referred to Appendix A of this report.

Date	Frequency (MHz)	Tissue Type	Input Power (mW)	Dipole S/N	Probe S/N	DAE S/N	Measured SAR (W/kg)	Targeted SAR (W/kg)	Normalized SAR (W/kg)	Deviation (%)
2014/6/4	1900	Head	250	5d118	3819	910	9.92	40.30	39.68	-1.54
2014/6/13	1900	Body	250	5d118	3819	569	10.40	41.80	41.6	-0.48



**Fig 8.3.1 System Performance Check Setup**



**Fig 8.3.2 Setup Photo**



## 11. RF Exposure Positions

### 11.1 Ear and handset reference point

Figure 9.1.1 shows the front, back, and side views of the SAM phantom. The center-of-mouth reference point is labeled "M," the left ear reference point (ERP) is marked "LE," and the right ERP is marked "RE." Each ERP is 15 mm along the B-M (back-mouth) line behind the entrance-to-ear-canal (EEC) point, as shown in Figure 9.1.2. The Reference Plane is defined as passing through the two ear reference points and point M. The line N-F (neck-front), also called the reference pivoting line, is normal to the Reference Plane and perpendicular to both a line passing through RE and LE and the B-M line (see Figure 9.1.3). Both N-F and B-M lines should be marked on the exterior of the phantom shell to facilitate handset positioning. Posterior to the N-F line the ear shape is a flat surface with 6 mm thickness at each ERP, and forward of the N-F line the ear is truncated, as illustrated in Figure 9.1.2. The ear truncation is introduced to preclude the ear lobe from interfering with handset tilt, which could lead to unstable positioning at the cheek.

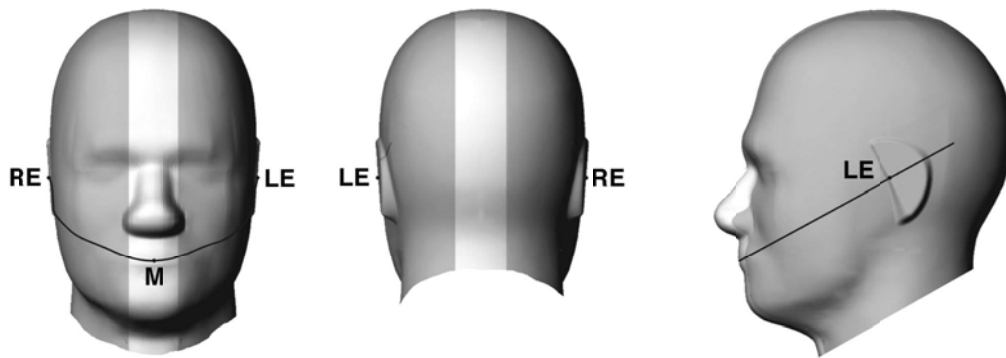


Fig 9.1.1 Front, back, and side views of SAM twin phantom

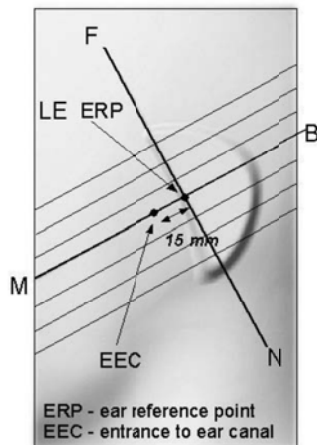


Fig 9.1.2 Close-up side view of phantom showing the ear region.

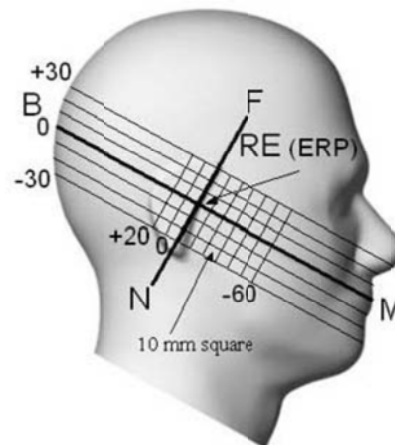
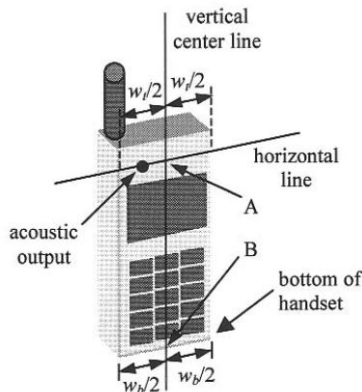


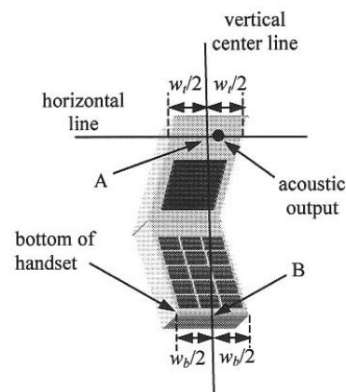
Fig 9.1.3 Side view of the phantom showing relevant markings and seven cross-sectional plane locations

## **11.2 Definition of the cheek position**

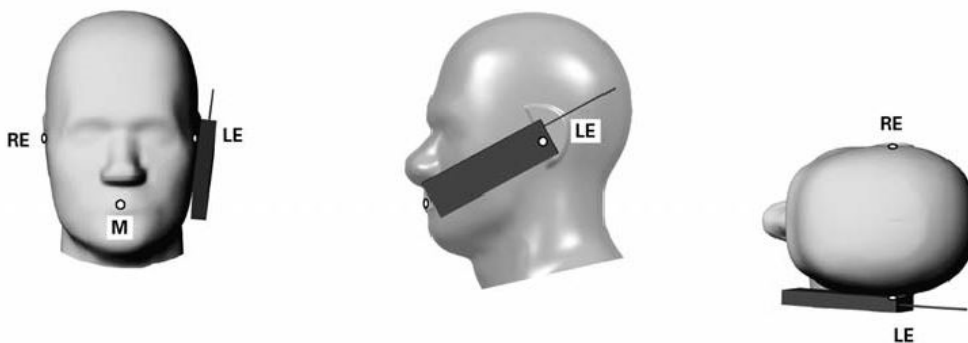
1. Ready the handset for talk operation, if necessary. For example, for handsets with a cover piece (flip cover), open the cover. If the handset can transmit with the cover closed, both configurations must be tested.
2. Define two imaginary lines on the handset—the vertical centerline and the horizontal line. The vertical centerline passes through two points on the front side of the handset—the midpoint of the width  $w_t$  of the handset at the level of the acoustic output (point A in Figure 9.2.1 and Figure 9.2.2), and the midpoint of the width  $w_b$  of the bottom of the handset (point B). The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output (see Figure 9.2.1). The two lines intersect at point A. Note that for many handsets, point A coincides with the center of the acoustic output; however, the acoustic output may be located elsewhere on the horizontal line. Also note that the vertical centerline is not necessarily parallel to the front face of the handset (see Figure 9.2.2), especially for clamshell handsets, handsets with flip covers, and other irregularly-shaped handsets.
3. Position the handset close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure 9.2.3), such that the plane defined by the vertical centerline and the horizontal line of the handset is approximately parallel to the sagittal plane of the phantom.
4. Translate the handset towards the phantom along the line passing through RE and LE until handset point A touches the pinna at the ERP.
5. While maintaining the handset in this plane, rotate it around the LE-RE line until the vertical centerline is in the plane normal to the plane containing B-M and N-F lines, i.e., the Reference Plane.
6. Rotate the handset around the vertical centerline until the handset (horizontal line) is parallel to the N-F line.
7. While maintaining the vertical centerline in the Reference Plane, keeping point A on the line passing through RE and LE, and maintaining the handset contact with the pinna, rotate the handset about the N-F line until any point on the handset is in contact with a phantom point below the pinna on the cheek. See Figure 9.2.3. The actual rotation angles should be documented in the test report.



**Fig 9.2.1 Handset vertical and horizontal reference lines—"fixed case"**



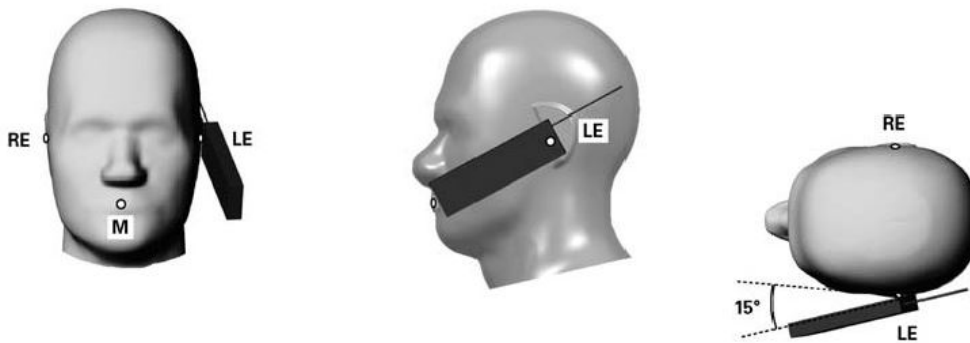
**Fig 9.2.2 Handset vertical and horizontal reference lines—"clam-shell case"**



**Fig 9.2.3 cheek or touch position. The reference points for the right ear (RE), left ear (LE), and mouth (M), which establish the Reference Plane for handset positioning, are indicated.**

### **11.3 Definition of the tilt position**

1. Ready the handset for talk operation, if necessary. For example, for handsets with a cover piece (flip cover), open the cover. If the handset can transmit with the cover closed, both configurations must be tested.
2. While maintaining the orientation of the handset, move the handset away from the pinna along the line passing through RE and LE far enough to allow a rotation of the handset away from the cheek by 15°.
3. Rotate the handset around the horizontal line by 15°.
4. While maintaining the orientation of the handset, move the handset towards the phantom on the line passing through RE and LE until any part of the handset touches the ear. The tilt position is obtained when the contact point is on the pinna. See Figure 9.3.1. If contact occurs at any location other than the pinna, e.g., the antenna at the back of the phantom head, the angle of the handset should be reduced. In this case, the tilt position is obtained if any point on the handset is in contact with the pinna and a second point

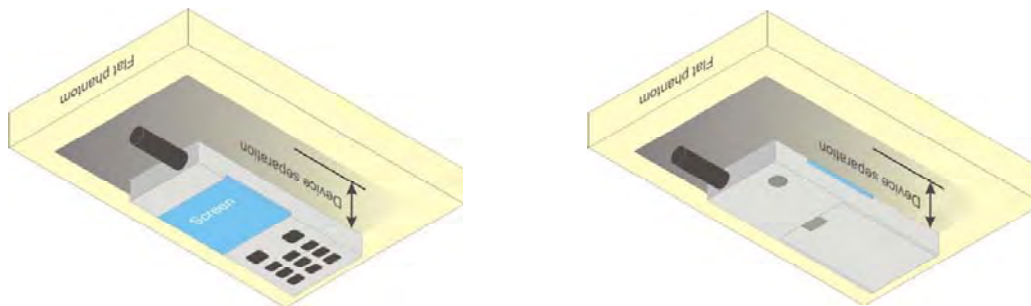


**Fig 9.3.1 Tilt position. The reference points for the right ear (RE), left ear (LE), and mouth (M), which define the Reference Plane for handset positioning, are indicated.**

### 11.4 Body Worn Accessory

Body-worn operating configurations are tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in a normal use configuration (see Figure 9.4). Per KDB 648474 D04v01r02, body-worn accessory exposure is typically related to voice mode operations when handsets are carried in body-worn accessories. The body-worn accessory procedures in FCC KDB 447498 D01v05r02 should be used to test for body-worn accessory SAR compliance, without a headset connected to it. This enables the test results for such configuration to be compatible with that required for hotspot mode when the body-worn accessory test separation distance is greater than or equal to that required for hotspot mode, when applicable. When the reported SAR for body-worn accessory, measured without a headset connected to the handset is  $< 1.2 \text{ W/kg}$ , the highest reported SAR configuration for that wireless mode and frequency band should be repeated for that body-worn accessory with a handset attached to the handset.

Accessories for body-worn operation configurations are divided into two categories: those that do not contain metallic components and those that do contain metallic components. When multiple accessories that do not contain metallic components are supplied with the device, the device is tested with only the accessory that dictates the closest spacing to the body. Then multiple accessories that contain metallic components are test with the device with each accessory. If multiple accessories share an identical metallic component (i.e. the same metallic belt-clip used with different holsters with no other metallic components) only the accessory that dictates the closest spacing to the body is tested.



**Fig 9.4 Body Worn Position**

## 12. Conducted RF Output Power (Unit: dBm)

### <GSM Conducted Power>

1. Per KDB 447498 D01v05r02, the maximum output power channel is used for SAR testing and for further SAR test reduction.
2. For head SAR testing, the EUT was set in GSM Voice for GSM1900.
3. For body-worn SAR testing, the EUT was set in GSM voice for GSM1900.

Band GSM1900	Burst Average Power (dBm)			Tune-up	Frame-Average Power (dBm)			Tune-up
TX Channel	512	661	810	Limit	512	661	810	Limit
Frequency (MHz)	1850.2	1880	1909.8	(dBm)	1850.2	1880	1909.8	(dBm)
GSM (GMSK, 1 Tx slot)	30.23	30.26	30.10	31	21.23	21.26	21.10	22
GPRS (GMSK, 1 Tx slot) – CS1	30.22	30.23	30.08	31	21.22	21.23	21.08	22
GPRS (GMSK, 2 Tx slots) – CS1	29.38	29.41	29.24	30	23.38	23.41	23.24	24
GPRS (GMSK, 3 Tx slots) – CS1	27.45	27.52	27.27	28	23.19	23.26	23.01	23.74
GPRS (GMSK, 4 Tx slots) – CS1	26.45	26.56	26.18	27	23.45	23.56	23.18	24

Remark: The frame-averaged power is linearly scaled the maximum burst averaged power over 8 time slots.

The calculated method are shown as below:

Frame-averaged power = Maximum burst averaged power (1 Tx Slot) - 9 dB

Frame-averaged power = Maximum burst averaged power (2 Tx Slots) - 6 dB

Frame-averaged power = Maximum burst averaged power (3 Tx Slots) - 4.26 dB

Frame-averaged power = Maximum burst averaged power (4 Tx Slots) - 3 dB

## 13. Bluetooth Exclusions Applied

Mode Band	Average power(dBm)
	Bluetooth v2.1+EDR
2.4GHz Bluetooth	9.5

### Note:

1. Per KDB 447498 D01v05r02, the 1-g and 10-g SAR test exclusion thresholds for 100 MHz to 6 GHz at *test separation distances* ≤ 50 mm are determined by:

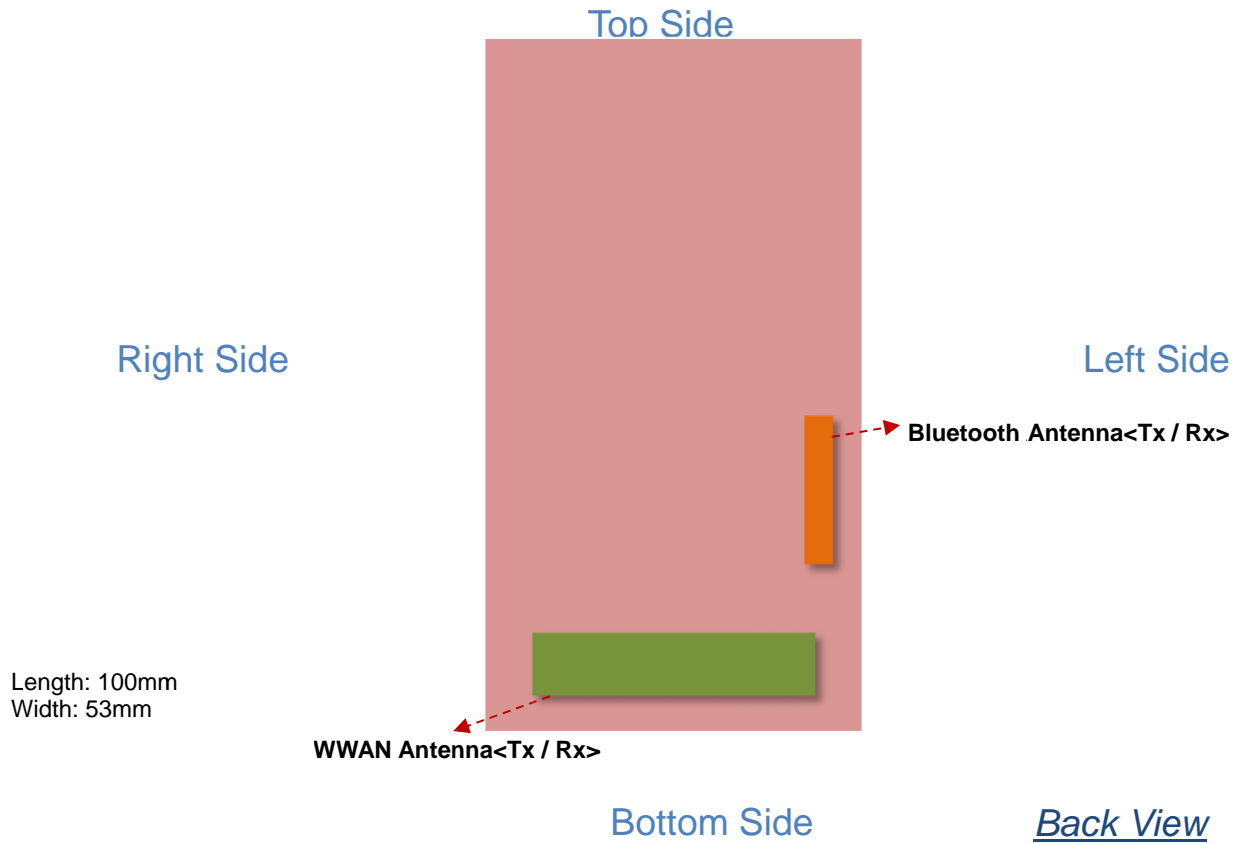
$[(\text{max. power of channel, including tune-up tolerance, mW}) / (\text{min. test separation distance, mm})] \cdot [\sqrt{f(\text{GHz})}] \leq 3.0$  for 1-g SAR and ≤ 7.5 for 10-g extremity SAR

- f(GHz) is the RF channel transmit frequency in GHz
- Power and distance are rounded to the nearest mW and mm before calculation
- The result is rounded to one decimal place for comparison

Bluetooth Max Power (dBm)	mW	Separation Distance (mm)	Frequency (GHz)	exclusion thresholds
9.5	9.00	0	2.48	2.83

**Note:** Per KDB 447498 D01v05r02, when the minimum test separation distance is < 5 mm, a distance of 5 mm is applied to determine SAR test exclusion. The test exclusion threshold is 2.83 which is ≤ 3, SAR testing is not required.

## 14. Antenna Location



## 15. SAR Test Results

### General Note:

- Per KDB 447498 D01v05r02, the reported SAR is the measured SAR value adjusted for maximum tune-up tolerance.
  - Tune-up scaling Factor = tune-up limit power (mW) / EUT RF power (mW), where tune-up limit is the maximum rated power among all production units.
  - Reported SAR(W/kg)= Measured SAR(W/kg)\*Tune-up Scaling Factor
- Per KDB 447498 D01v05r02, for each exposure position, testing of other required channels within the operating mode of a frequency band is not required when the *reported* 1-g or 10-g SAR for the mid-band or highest output power channel is:
  - ≤ 0.8 W/kg or 2.0 W/kg, for 1-g or 10-g respectively, when the transmission band is ≤ 100 MHz
  - ≤ 0.6 W/kg or 1.5 W/kg, for 1-g or 10-g respectively, when the transmission band is between 100 MHz and 200 MHz
  - ≤ 0.4 W/kg or 1.0 W/kg, for 1-g or 10-g respectively, when the transmission band is ≥ 200 MHz
- Per KDB 447498 D01v05r02, for each exposure position, if the highest output channel reported SAR ≤ 0.8W/kg, other channels SAR testing is not necessary.
- Per KDB 648474 D04v01r02, when the reported SAR for a body-worn accessory measured without a headset connected to the handset is ≤ 1.2 W/kg, SAR testing with a headset connected to the handset is not required.

### 15.1 Head SAR

#### <GSM SAR>

Plot No.	Band	Mode	Test Position	EUT Status	Battery	Ch.	Freq. (MHz)	Average Power (dBm)	Tune-Up Limit (dBm)	Tune-up Scaling Factor	Power Drift (dB)	Measured 1g SAR (W/kg)	Reported 1g SAR (W/kg)
	GSM 1900	GSM Voice	Right Cheek	Flip Open	Battery 1	661	1880	30.26	31	1.186	-0.09	0.068	0.081
	GSM 1900	GSM Voice	Right Tilted	Flip Open	Battery 1	661	1880	30.26	31	1.186	-0.07	0.032	0.038
01	GSM 1900	GSM Voice	Left Cheek	Flip Open	Battery 1	661	1880	30.26	31	1.186	-0.06	0.104	0.123
	GSM 1900	GSM Voice	Left Tilted	Flip Open	Battery 1	661	1880	30.26	31	1.186	-0.15	0.031	0.037
02	GSM 1900	GSM Voice	Left Cheek SAR in mouth area	Flip Open	Battery 1	661	1880	30.26	31	1.186	-0.03	0.141	0.167
	GSM 1900	GSM Voice	Left Cheek SAR in mouth area	Flip Open	Battery 2	661	1880	30.26	31	1.186	-0.1	0.116	0.138

**Note:** The device antenna is located near the bottom and the measured head SAR distribution was clipped. According to KDB 648474 D04 v01r02 section 8, EUT was positioned under the flat phantom with a separation distance of 4 mm between the ear reference point (ERP) and the outer surface of the flat phantom shell, the low bottom of the phone was lowered from the phantom to establish the same separation distance at the peak SAR location identified by the truncated partial SAR distribution measured with the SAM phantom. The distance from the peak SAR location to the phone was determined by the straight line passing perpendicularly through the phantom surface. The procedure to determine the separation for EUT positioning under the flat phantom is illustrated in the SAR test setup photo exhibit.

### 15.2 Body Worn Accessory SAR

#### <GSM SAR>

Plot No.	Band	Mode	Test Position	EUT Status	Battery	Gap (cm)	Ch.	Freq. (MHz)	Average Power (dBm)	Tune-Up Limit (dBm)	Tune-up Scaling Factor	Power Drift (dB)	Measured 1g SAR (W/kg)	Reported 1g SAR (W/kg)
03	GSM1900	GSM Voice	Front	Flip Close	Battery 1	1.5	661	1880	30.26	31	1.186	0.08	0.232	0.275
	GSM1900	GSM Voice	Back	Flip Close	Battery 1	1.5	661	1880	30.26	31	1.186	0.03	0.156	0.185
	GSM1900	GSM Voice	Front	Flip Close	Battery 2	1.5	661	1880	30.26	31	1.186	0.17	0.203	0.241



## 16. Simultaneous Transmission Analysis

NO.	Simultaneous Transmission Configurations	Portable Handset		Note
		Head	Body-worn	
1.	GSM(Voice) + Bluetooth(data)	Yes	Yes	-
2.	GPRS (Data) + Bluetooth(data)	Yes	Yes	Bluetooth Tethering

**General Note:**

1. The Reported SAR summation is calculated based on the same configuration and test position.
2. Per KDB 447498 D01v05r02, simultaneous transmission SAR is compliant if,
  - i) Scalar SAR summation < 1.6W/kg.
  - ii)  $SPLSR = (SAR_1 + SAR_2)^{1.5} / (min. separation distance, mm)$ , and the peak separation distance is determined from the square root of  $[(x_1-x_2)^2 + (y_1-y_2)^2 + (z_1-z_2)^2]$ , where  $(x_1, y_1, z_1)$  and  $(x_2, y_2, z_2)$  are the coordinates of the extrapolated peak SAR locations in the zoom scan
  - iii) If  $SPLSR \leq 0.04$ , simultaneously transmission SAR measurement is not necessary.
  - iv) Simultaneously transmission SAR measurement, and the reported multi-band SAR < 1.6W/kg.
3. For simultaneous transmission analysis, Bluetooth SAR is estimated per KDB 447498 D01v05r02 based on the formula below.
  - i)  $(max. power of channel, including tune-up tolerance, mW) / (min. test separation distance, mm) \cdot [\sqrt{f(GHz)/x}] W/kg$  for test separation distances  $\leq 50$  mm; where  $x = 7.5$  for 1-g SAR, and  $x = 18.75$  for 10-g SAR.
  - ii) When the minimum separation distance is < 5mm, the distance is used 5mm to determine SAR test exclusion.
  - iii) 0.4 W/kg for 1-g SAR and 1.0 W/kg for 10-g SAR, when the test separation distances is > 50 mm.
  - iv) Bluetooth estimated SAR is conservatively determined by 5mm separation, for all applicable exposure positions.

Bluetooth Max Power	Exposure Position	Head	Body worn
	Test separation	0 mm	15 mm
9.5 dBm	Estimated SAR (W/kg)	0.378 W/kg	0.126 W/kg



**16.1 Head Exposure Conditions**

WWAN Band		Exposure Position	WWAN	Bluetooth DSS	Summed SAR (W/kg)
			SAR (W/kg)	Estimated SAR (W/kg)	
GSM	GSM1900	Right Cheek	0.081	0.378	0.46
		Right Tilted	0.038	0.378	0.42
		Left Cheek	0.167	0.378	<b>0.55</b>
		Left Tilted	0.037	0.378	0.42

**16.2 Body-Worn Accessory Exposure Conditions**

WWAN Band		Exposure Position	WWAN	Bluetooth DSS	Summed SAR (W/kg)
			SAR (W/kg)	Estimated SAR (W/kg)	
GSM	GSM1900	Front	0.275	0.126	0.40
		Back	0.185	0.126	0.31

**Test Engineer :** Luke Lu

## 17. Uncertainty Assessment

The component of uncertainty may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainty by the statistical analysis of a series of observations is termed a Type A evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience, and knowledge of the behavior and properties of relevant materials and instruments, manufacture's specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in table below.

Uncertainty Distributions	Normal	Rectangular	Triangular	U-Shape
Multi-plying Factor <sup>(a)</sup>	1/ $\kappa$ <sup>(b)</sup>	1/ $\sqrt{3}$	1/ $\sqrt{6}$	1/ $\sqrt{2}$

(a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity

(b)  $\kappa$  is the coverage factor

**Table 17.1. Standard Uncertainty for Assumed Distribution**

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual "root-sum-squares" (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %. The DASY uncertainty Budget is shown in the following tables.

Error Description	Uncertainty Value (±%)	Probability Distribution	Divisor	Ci (1g)	Ci (10g)	Standard Uncertainty (1g)	Standard Uncertainty (10g)
<b>Measurement System</b>							
Probe Calibration	6.0	Normal	1	1	1	± 6.0 %	± 6.0 %
Axial Isotropy	4.7	Rectangular	√3	0.7	0.7	± 1.9 %	± 1.9 %
Hemispherical Isotropy	9.6	Rectangular	√3	0.7	0.7	± 3.9 %	± 3.9 %
Boundary Effects	1.0	Rectangular	√3	1	1	± 0.6 %	± 0.6 %
Linearity	4.7	Rectangular	√3	1	1	± 2.7 %	± 2.7 %
System Detection Limits	1.0	Rectangular	√3	1	1	± 0.6 %	± 0.6 %
Readout Electronics	0.3	Normal	1	1	1	± 0.3 %	± 0.3 %
Response Time	0.8	Rectangular	√3	1	1	± 0.5 %	± 0.5 %
Integration Time	2.6	Rectangular	√3	1	1	± 1.5 %	± 1.5 %
RF Ambient Noise	3.0	Rectangular	√3	1	1	± 1.7 %	± 1.7 %
RF Ambient Reflections	3.0	Rectangular	√3	1	1	± 1.7 %	± 1.7 %
Probe Positioner	0.4	Rectangular	√3	1	1	± 0.2 %	± 0.2 %
Probe Positioning	2.9	Rectangular	√3	1	1	± 1.7 %	± 1.7 %
Max. SAR Eval.	1.0	Rectangular	√3	1	1	± 0.6 %	± 0.6 %
<b>Test Sample Related</b>							
Device Positioning	2.9	Normal	1	1	1	± 2.9 %	± 2.9 %
Device Holder	3.6	Normal	1	1	1	± 3.6 %	± 3.6 %
Power Drift	5.0	Rectangular	√3	1	1	± 2.9 %	± 2.9 %
<b>Phantom and Setup</b>							
Phantom Uncertainty	4.0	Rectangular	√3	1	1	± 2.3 %	± 2.3 %
Liquid Conductivity (Target)	5.0	Rectangular	√3	0.64	0.43	± 1.8 %	± 1.2 %
Liquid Conductivity (Meas.)	2.5	Normal	1	0.64	0.43	± 1.6 %	± 1.1 %
Liquid Permittivity (Target)	5.0	Rectangular	√3	0.6	0.49	± 1.7 %	± 1.4 %
Liquid Permittivity (Meas.)	2.5	Normal	1	0.6	0.49	± 1.5 %	± 1.2 %
<b>Combined Standard Uncertainty</b>						± 11.0 %	± 10.8 %
<b>Coverage Factor for 95 %</b>						K=2	
<b>Expanded Uncertainty</b>						± 22.0 %	± 21.5 %

**Table 17.2. Uncertainty Budget for frequency range 300 MHz to 3 GHz**

## **18. References**

- [1] FCC 47 CFR Part 2 "Frequency Allocations and Radio Treaty Matters; General Rules and Regulations"
- [2] ANSI/IEEE Std. C95.1-1992, "IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz", September 1992
- [3] IEEE Std. 1528-2003, "Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- [4] SPEAG DASY System Handbook
- [5] FCC KDB 447498 D01 v05r02, "Mobile and Portable Device RF Exposure Procedures and Equipment Authorization Policies", Feb 2014
- [6] FCC KDB 648474 D04 v01r02, "SAR Evaluation Considerations for Wireless Handsets", Dec 2013.
- [7] FCC KDB 941225 D03 v01, "Recommended SAR Test Reduction Procedures for GSM / GPRS / EDGE", December 2008
- [8] FCC KDB 865664 D01 v01r03, "SAR Measurement Requirements for 100 MHz to 6 GHz", Feb 2014.
- [9] FCC KDB 865664 D02 v01r01, "RF Exposure Compliance Reporting and Documentation Considerations" May 2013.



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**Appendix A. Plots of System Performance Check**

The plots are shown as follows.

**System Check\_Head\_1900MHz\_140604****DUT: D1900V2-SN: 5d118**

Communication System: UID 0, CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium: HSL\_1900\_140604 Medium parameters used:  $f = 1900$  MHz;  $\sigma = 1.422$  S/m;  $\epsilon_r = 38.942$ ;

$\rho = 1000$  kg/m<sup>3</sup>

Ambient Temperature : 23.5 °C; Liquid Temperature : 22.6 °C

**DASY5 Configuration:**

- Probe: EX3DV4 - SN3819; ConvF(8, 8, 8); Calibrated: 2013.11.27;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn910; Calibrated: 2013.12.17
- Phantom: SAM1; Type: QD000P40CD; Serial: TP:1670
- Measurement SW: DASY52, Version 52.8 (7); SEMCAD X Version 14.6.10 (7164)

**Pin=250mW/Area Scan (61x61x1):** Interpolated grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 14.4 W/kg

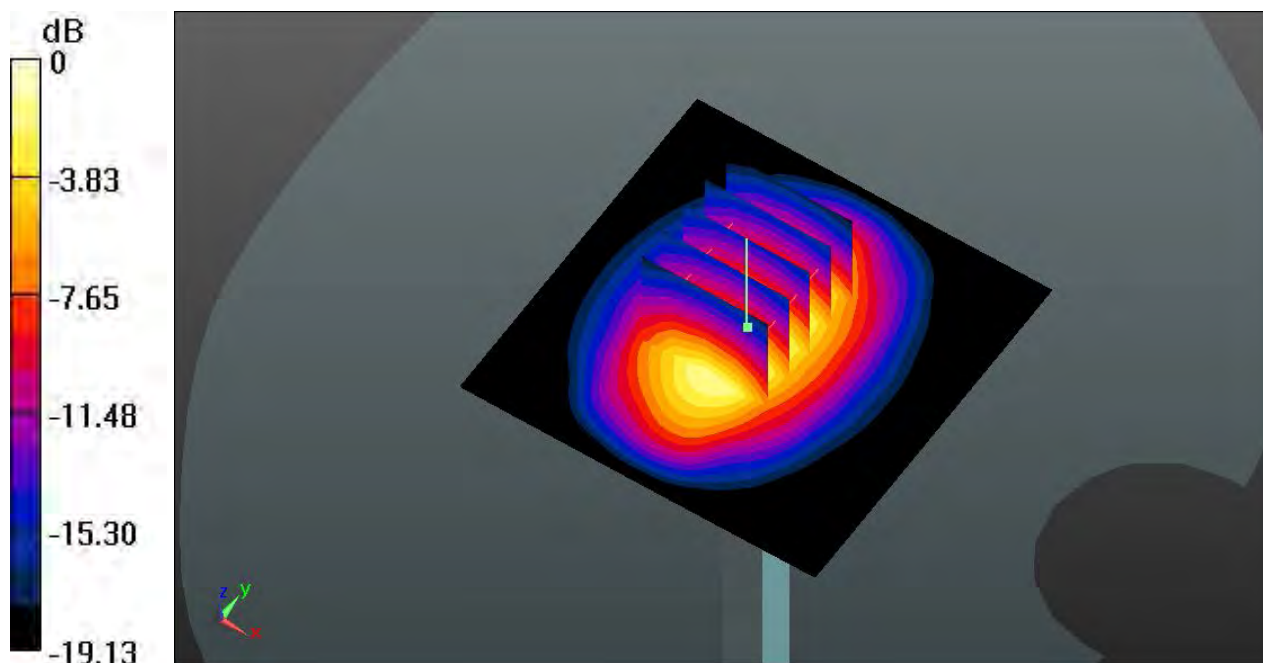
**Pin=250mW/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 100.6 V/m; Power Drift = 0.01 dB

Peak SAR (extrapolated) = 18.6 W/kg

**SAR(1 g) = 9.92 W/kg; SAR(10 g) = 5.1 W/kg**

Maximum value of SAR (measured) = 13.9 W/kg



0 dB = 13.9 W/kg

**System Check\_Body\_1900MHz\_140613****DUT: D1900V2-SN: 5d118**

Communication System: UID 0, CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium: MSL\_1900\_140613 Medium parameters used:  $f = 1900$  MHz;  $\sigma = 1.545$  S/m;  $\epsilon_r = 53.535$ ;  
 $\rho = 1000$  kg/m<sup>3</sup>

Ambient Temperature : 23.6 °C; Liquid Temperature : 22.8 °C

**DASY5 Configuration:**

- Probe: EX3DV4 - SN3819; ConvF(7.55, 7.55, 7.55); Calibrated: 2013.11.27;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn569; Calibrated: 2013.11.22
- Phantom: SAM2; Type: QD000P40CD; Serial: TP:1671
- Measurement SW: DASY52, Version 52.8 (7); SEMCAD X Version 14.6.10 (7164)

**Pin=250mW/Area Scan (61x61x1):** Interpolated grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 14.8 W/kg

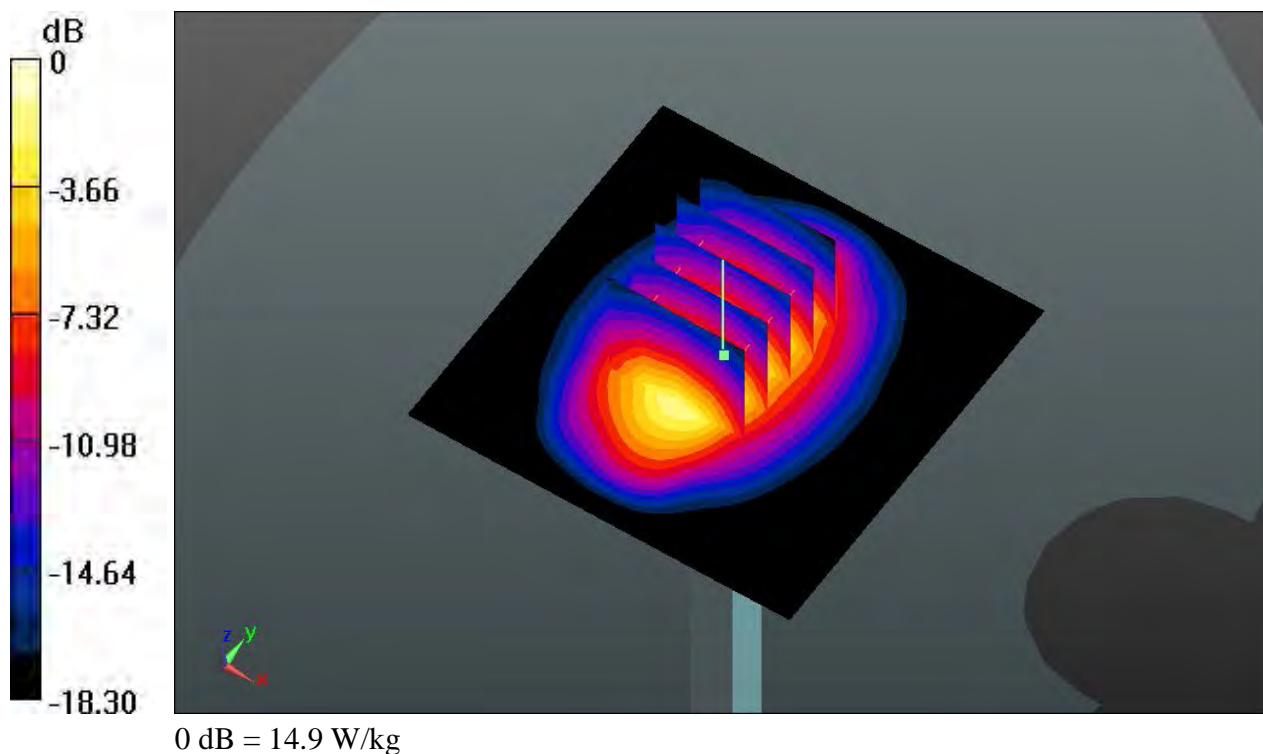
**Pin=250mW/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 86.373 V/m; Power Drift = 0.04 dB

Peak SAR (extrapolated) = 18.8 W/kg

**SAR(1 g) = 10.4 W/kg; SAR(10 g) = 5.39 W/kg**

Maximum value of SAR (measured) = 14.9 W/kg





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**Appendix B. Plots of High SAR Measurement**

The plots are shown as follows.



**01 GSM1900\_GSM Voice\_Left Cheek\_Ch661\_Battery 1**

Communication System: UID 0, Generic GSM (0); Frequency: 1880 MHz; Duty Cycle: 1:8.3  
Medium: HSL\_1900\_140604 Medium parameters used:  $f = 1880$  MHz;  $\sigma = 1.403$  S/m;  $\epsilon_r = 39.034$ ;  
 $\rho = 1000$  kg/m<sup>3</sup>  
Ambient Temperature : 23.5 °C; Liquid Temperature : 22.6 °C

**DASY5 Configuration:**

- Probe: EX3DV4 - SN3819; ConvF(8, 8, 8); Calibrated: 2013.11.27;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn910; Calibrated: 2013.12.17
- Phantom: SAM1; Type: QD000P40CD; Serial: TP:1670
- Measurement SW: DASY52, Version 52.8 (7); SEMCAD X Version 14.6.10 (7164)

**Ch661/Area Scan (51x151x1):** Interpolated grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.138 W/kg

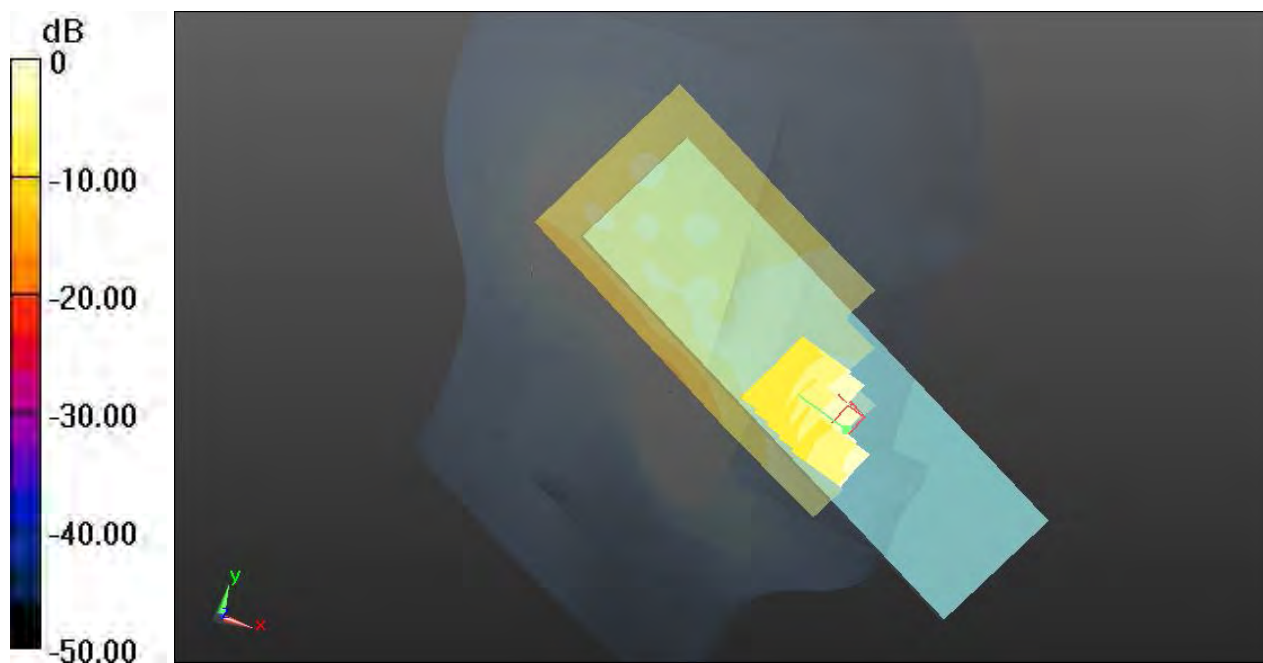
**Ch661/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 3.785 V/m; Power Drift = -0.06 dB

Peak SAR (extrapolated) = 0.121 W/kg

**SAR(1 g) = 0.104 W/kg; SAR(10 g) = n.a.**

Maximum value of SAR (measured) = 0.120 W/kg



0 dB = 0.120 W/kg

**02 GSM1900\_GSM Voice\_Left Cheek\_Ch661\_SAR in mouth\_Battery 1**

Communication System: UID 0, Generic GSM (0); Frequency: 1880 MHz; Duty Cycle: 1:8.3  
Medium: HSL\_1900\_140604 Medium parameters used:  $f = 1880$  MHz;  $\sigma = 1.403$  S/m;  $\epsilon_r = 39.034$ ;  
 $\rho = 1000$  kg/m<sup>3</sup>  
Ambient Temperature : 23.5 °C; Liquid Temperature : 22.6 °C

**DASY5 Configuration:**

- Probe: EX3DV4 - SN3819; ConvF(8, 8, 8); Calibrated: 2013.11.27;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn910; Calibrated: 2013.12.17
- Phantom: SAM1; Type: QD000P40CD; Serial: TP:1670
- Measurement SW: DASY52, Version 52.8 (7); SEMCAD X Version 14.6.10 (7164)

**Ch661/Area Scan (61x81x1):** Interpolated grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.181 W/kg

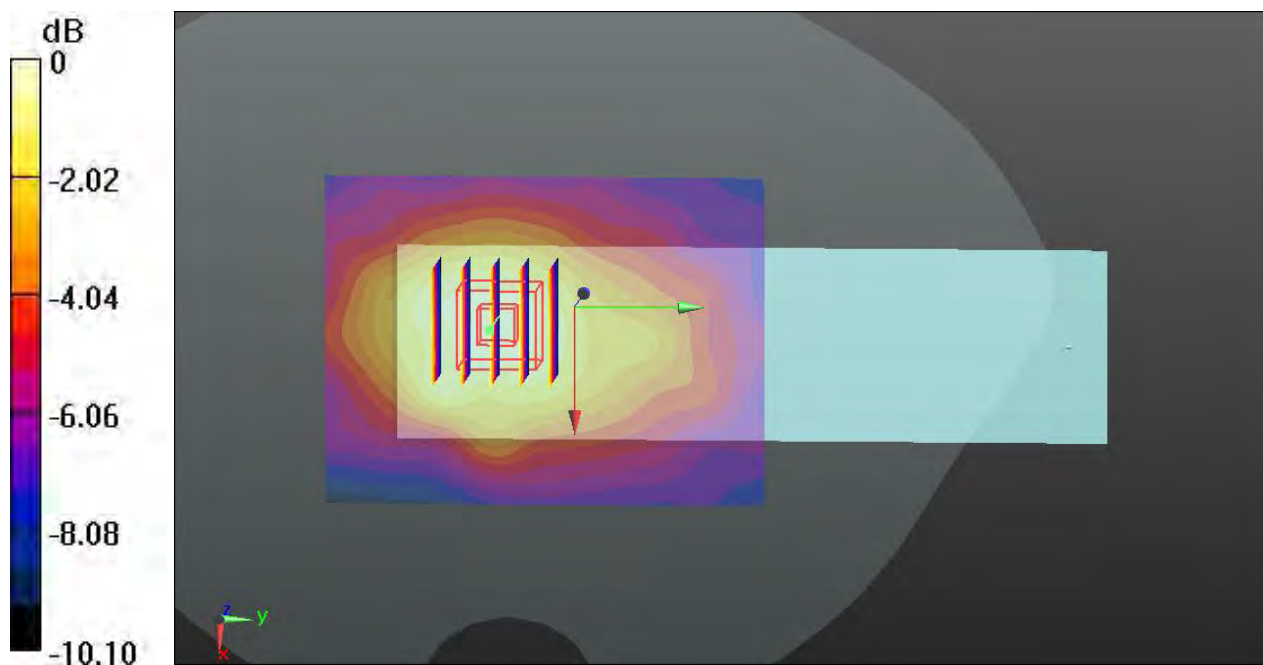
**Ch661/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 4.340 V/m; Power Drift = -0.03 dB

Peak SAR (extrapolated) = 0.200 W/kg

**SAR(1 g) = 0.141 W/kg; SAR(10 g) = 0.096 W/kg**

Maximum value of SAR (measured) = 0.180 W/kg



0 dB = 0.180 W/kg

**03 GSM1900\_GSM Voice\_Front\_1.5cm\_Ch661\_Battery 1**

Communication System: UID 0, Generic GSM (0); Frequency: 1880 MHz; Duty Cycle: 1:8.3  
Medium: MSL\_1900\_140613 Medium parameters used:  $f = 1880$  MHz;  $\sigma = 1.521$  S/m;  $\epsilon_r = 53.575$ ;  
 $\rho = 1000$  kg/m<sup>3</sup>  
Ambient Temperature : 23.6 °C; Liquid Temperature : 22.8 °C

**DASY5 Configuration:**

- Probe: EX3DV4 - SN3819; ConvF(7.55, 7.55, 7.55); Calibrated: 2013.11.27;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn569; Calibrated: 2013.11.22
- Phantom: SAM2; Type: QD000P40CD; Serial: TP:1671
- Measurement SW: DASY52, Version 52.8 (7); SEMCAD X Version 14.6.10 (7164)

**Ch661/Area Scan (51x91x1):** Interpolated grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.309 W/kg

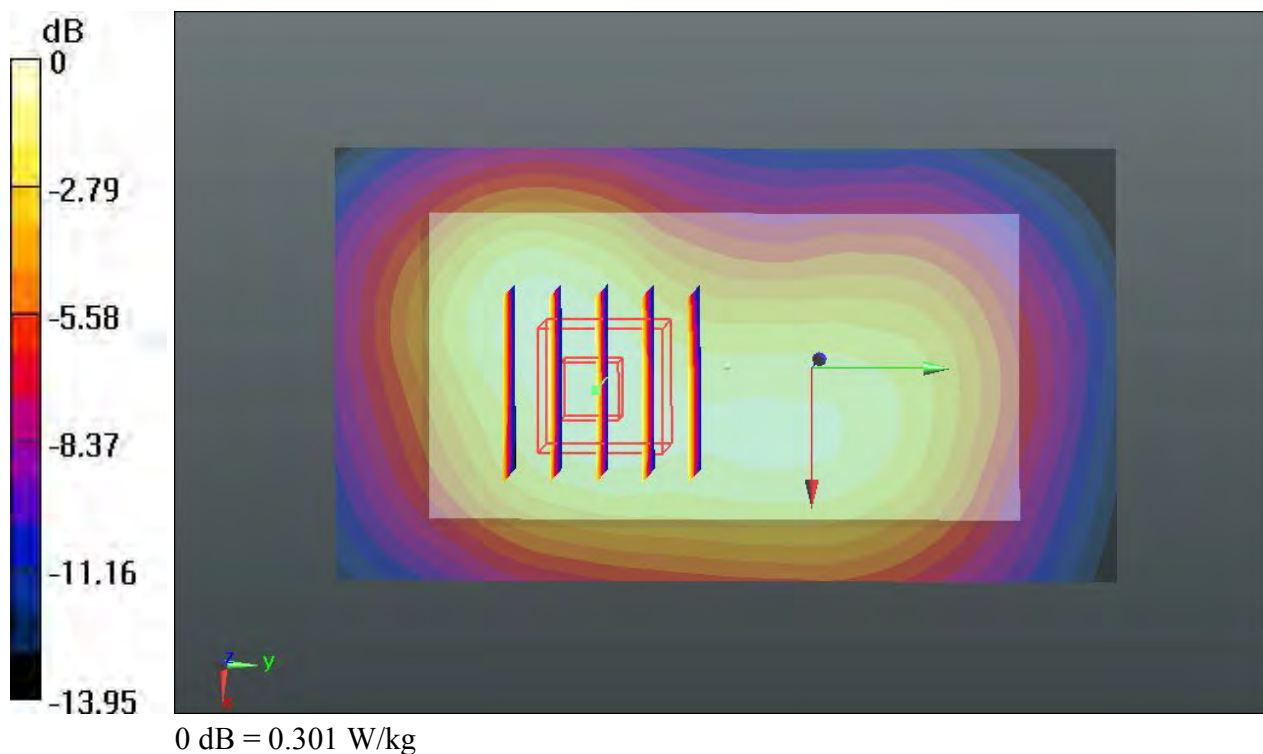
**Ch661/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 3.166 V/m; Power Drift = 0.08 dB

Peak SAR (extrapolated) = 0.364 W/kg

**SAR(1 g) = 0.232 W/kg; SAR(10 g) = 0.147 W/kg**

Maximum value of SAR (measured) = 0.301 W/kg





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**Appendix C.      DASYS Calibration Certificate**

The DASYS calibration certificates are shown as follows.



Accredited by the Swiss Accreditation Service (SAS)

Accreditation No.: **SCS 108**

The Swiss Accreditation Service is one of the signatories to the EA  
Multilateral Agreement for the recognition of calibration certificates

Client **Spartan-CH (Auden)**

Certificate No: **D1900V2-5d118\_Nov11**

## CALIBRATION CERTIFICATE

Object: **D1900V2 - SN: 5d118**

Calibration procedure(s): **QA CAL-05.v8**  
**Calibration procedure for dipole validation kits above 700 MHz**

Calibration date: **November 21, 2011**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).  
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature ( $22 \pm 3$ )°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter EPM-442A	GB37480704	05-Oct-11 (No. 217-01451)	Oct-12
Power sensor HP 8481A	US37292783	05-Oct-11 (No. 217-01451)	Oct-12
Reference 20 dB Attenuator	SN: 5086 (20g)	29-Mai-11 (No. 217-01368)	Apr-12
Type-N mismatch combination	SN: 5047.2 / 06327	29-Mar-11 (No. 217-01371)	Apr-12
Reference Probe ES3DV3	SN: 3205	29-Apr-11 (No. ES3-3205_Apr11)	Apr-12
DAE4	SN: 601	04-Jul-11 (No. DAE4-601_Jul11)	Jul-12
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Power sensor HP 8481A	MY41092317	18-Oct-02 (in house check Oct-11)	In house check: Oct-13
RF generator R&S SMT-06	100005	04-Aug-99 (in house check Oct-11)	In house check: Oct-13
Network Analyzer HP 8753E	US37390585 S4206	18-Oct-01 (in house check Oct-11)	In house check: Oct-12

Calibrated by:	Name <b>Dimos Iliev</b>	Function <b>Laboratory Technician</b>	Signature 
Approved by:	Name <b>Katja Pokovic</b>	Function <b>Technical Manager</b>	Signature 

Issued: November 21, 2011

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.



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Accreditation No.: **SCS 108**

The Swiss Accreditation Service is one of the signatories to the EA  
Multilateral Agreement for the recognition of calibration certificates

**Glossary:**

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

**Calibration is Performed According to the Following Standards:**

- IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005
- Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

**Additional Documentation:**

- DASY4/5 System Handbook

**Methods Applied and Interpretation of Parameters:**

- Measurement Conditions:** Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL:** The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss:** These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- Electrical Delay:** One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured:** SAR measured at the stated antenna input power.
- SAR normalized:** SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters:** The measured TSL parameters are used to calculate the nominal SAR result.



## Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY5	V52.6.2
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom	
Distance Dipole Center - TSL	10 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	1900 MHz $\pm$ 1 MHz	

## Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	40.0	1.40 mho/m
Measured Head TSL parameters	(22.0 $\pm$ 0.2) °C	39.5 $\pm$ 6 %	1.42 mho/m $\pm$ 6 %
Head TSL temperature change during test	< 0.5 °C	----	----

## SAR result with Head TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	10.2 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	40.3 mW / g $\pm$ 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Head TSL	condition	
SAR measured	250 mW input power	5.29 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	21.0 mW / g $\pm$ 16.5 % (k=2)

## Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	53.3	1.52 mho/m
Measured Body TSL parameters	(22.0 $\pm$ 0.2) °C	54.2 $\pm$ 6 %	1.59 mho/m $\pm$ 6 %
Body TSL temperature change during test	< 0.5 °C	----	----

## SAR result with Body TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	10.7 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	41.8 mW / g $\pm$ 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Body TSL	condition	
SAR measured	250 mW input power	5.59 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	22.0 mW / g $\pm$ 16.5 % (k=2)

## Appendix

### Antenna Parameters with Head TSL

Impedance, transformed to feed point	$53.4 \Omega + 6.9 j\Omega$
Return Loss	- 22.5 dB

### Antenna Parameters with Body TSL

Impedance, transformed to feed point	$47.8 \Omega + 7.1 j\Omega$
Return Loss	- 22.4 dB

### General Antenna Parameters and Design

Electrical Delay (one direction)	1.200 ns
----------------------------------	----------

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.

No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

### Additional EUT Data

Manufactured by	SPEAG
Manufactured on	August 21, 2009



## DASY5 Validation Report for Head TSL

Date: 21.11.2011

Test Laboratory: SPEAG, Zurich, Switzerland

**DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN: 5d118**

Communication System: CW; Frequency: 1900 MHz

Medium parameters used:  $f = 1900$  MHz;  $\sigma = 1.42$  mho/m;  $\epsilon_r = 39.5$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY52 Configuration:

- Probe: ES3DV3 - SN3205; ConvF(5.01, 5.01, 5.01); Calibrated: 29.04.2011
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 04.07.2011
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; Serial: 1001
- DASY52 52.6.2(482); SEMCAD X 14.4.5(3634)

### Dipole Calibration for Head Tissue/Pin=250 mW, d=10mm/Zoom Scan (7x7x7)/Cube 0:

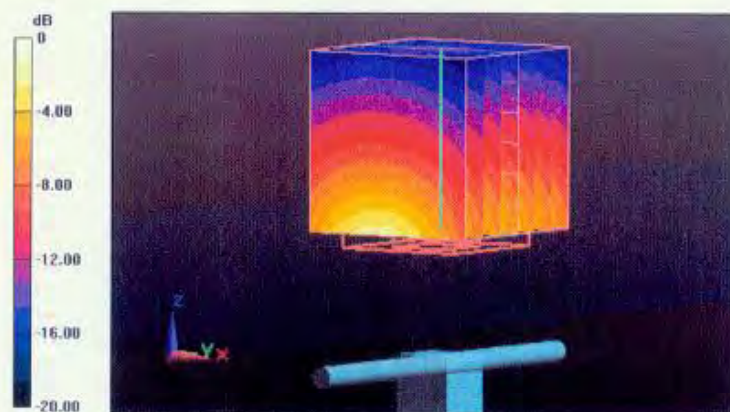
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 98.061 V/m; Power Drift = 0.04 dB

Peak SAR (extrapolated) = 18.620 W/kg

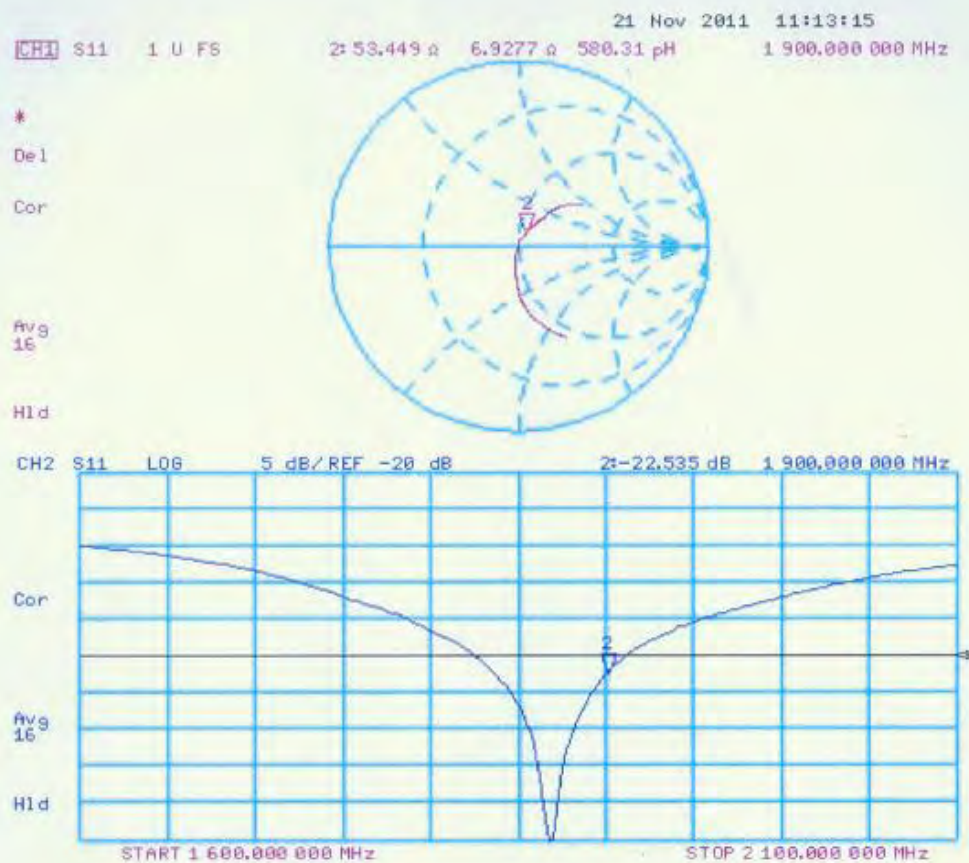
**SAR(1 g) = 10.2 mW/g; SAR(10 g) = 5.29 mW/g**

Maximum value of SAR (measured) = 12.702 mW/g



0 dB = 12.700mW/g

# Impedance Measurement Plot for Head TSL





## DASY5 Validation Report for Body TSL

Date: 21.11.2011

Test Laboratory: SPEAG, Zurich, Switzerland

**DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN: 5d118**

Communication System: CW; Frequency: 1900 MHz

Medium parameters used:  $f = 1900$  MHz;  $\sigma = 1.59$  mho/m;  $\epsilon_r = 54.2$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY52 Configuration:

- Probe: ES3DV3 - SN3205; ConvF(4.62, 4.62, 4.62); Calibrated: 29.04.2011
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 04.07.2011
- Phantom: Flat Phantom 5.0 (back); Type: QD000P50AA; Serial: 1002
- DASY52 52.6.2(482); SEMCAD X 14.4.5(3634)

### Dipole Calibration for Body Tissue/Pin=250 mW, d=10mm/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 96.110 V/m; Power Drift = -0.01 dB

Peak SAR (extrapolated) = 18.910 W/kg

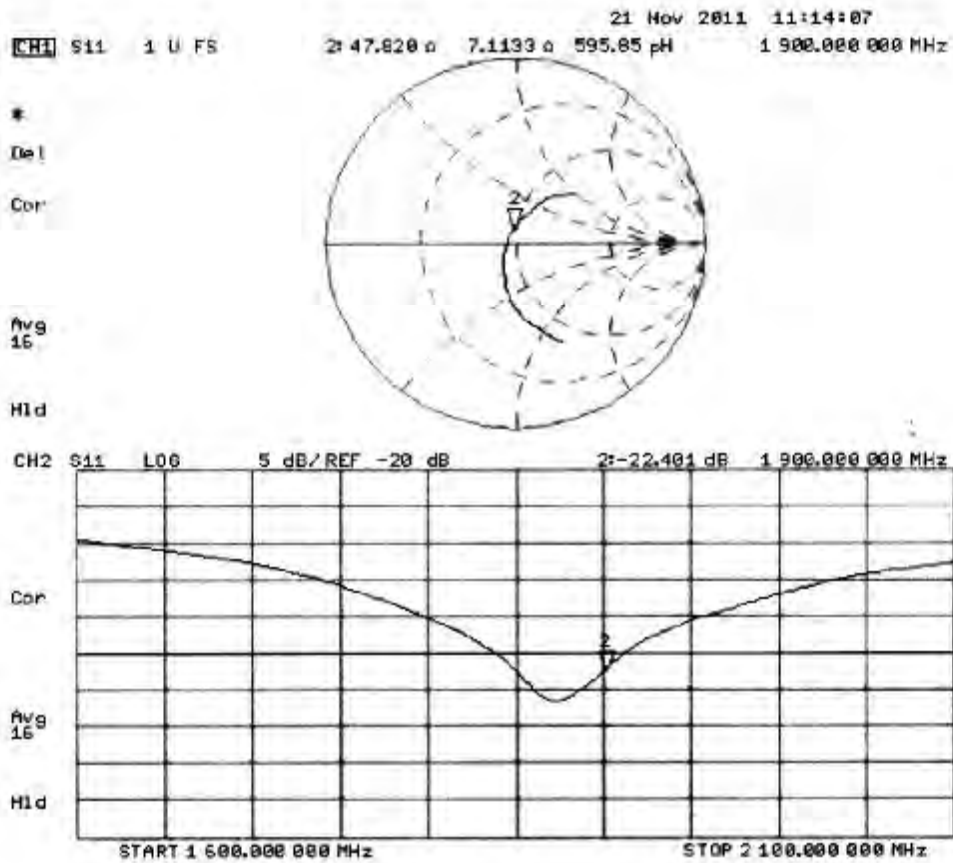
**SAR(1 g) = 10.7 mW/g; SAR(10 g) = 5.59 mW/g**

Maximum value of SAR (measured) = 13.549 mW/g



0 dB = 13.550mW/g

# Impedance Measurement Plot for Body TSL



## D1900V2, serial no. 5d118 Extended Dipole Calibrations

Referring to KDB 865664D01V01r01, if dipoles are verified in return loss ( $< -20\text{dB}$ , within 20% of prior calibration), and in impedance (within 5 ohm of prior calibration), the annual calibration is not necessary and the calibration interval can be extended.

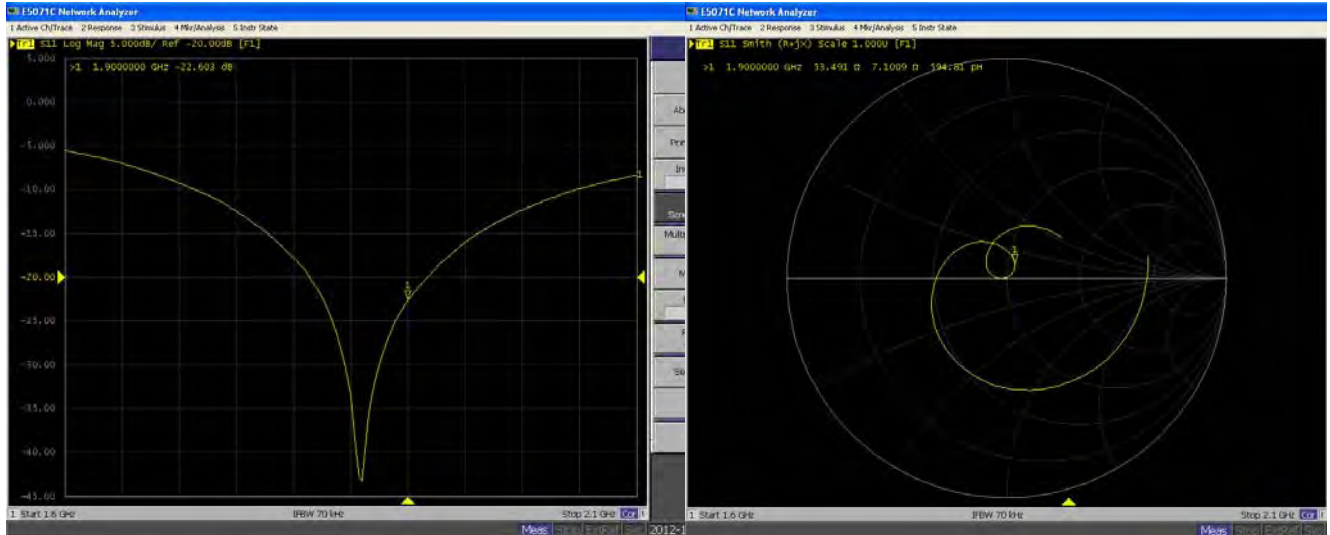
### <Justification of the extended calibration>

D1900V2 – serial no. 5d118												
	1900 Head						1900 Body					
Date of Measurement	Return-Loss (dB)	Delta (%)	Real Impedance (ohm)	Delta (ohm)	Imaginary Impedance (ohm)	Delta (ohm)	Return-Loss (dB)	Delta (%)	Real Impedance (ohm)	Delta (ohm)	Imaginary Impedance (ohm)	Delta (ohm)
11.21.2011	-22.535		53.449		6.9277		-22.401		47.82		7.1133	
11.17.2012	-22.603	0.30	53.491	-0.04	7.1009	0.17	-22.45	0.22	46.14	-1.68	6.7234	-0.39

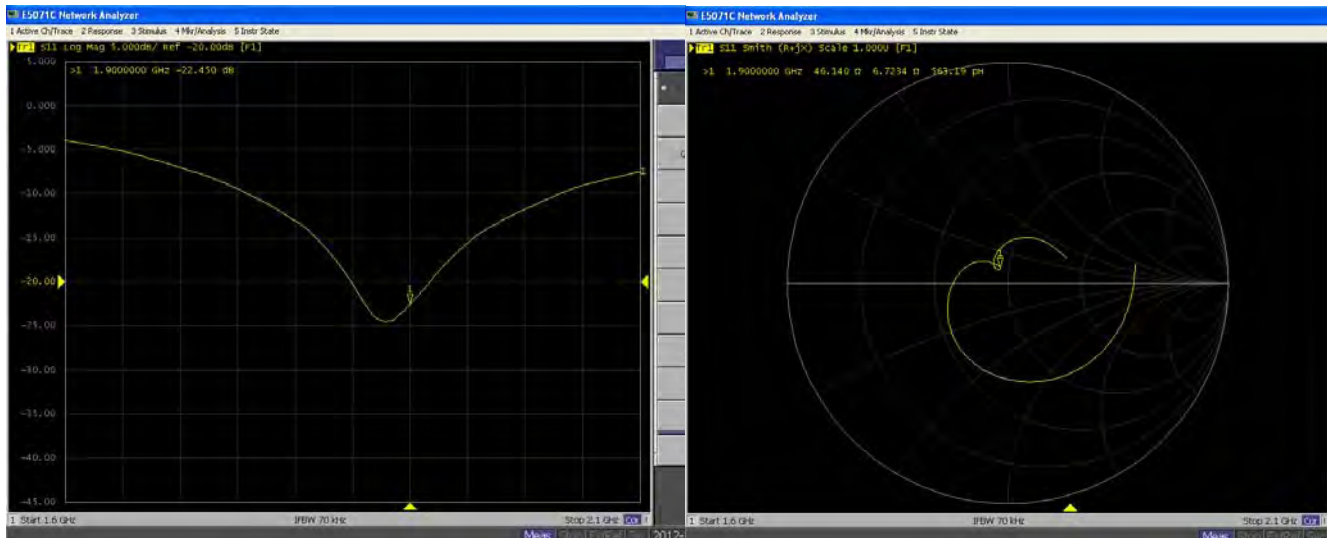
The return loss is  $< -20\text{dB}$ , within 20% of prior calibration; the impedance is within 5 ohm of prior calibration. Therefore the verification result should support extended calibration.

## <Dipole Verification Data>- D1900V2, serial no. 5d118

### 1900MHz – Head



### 1900MHz - Body



## D1900V2, Serial No. 5d118 Extended Dipole Calibrations

Referring to KDB 865664 D01 v01r02, if dipoles are verified in return loss ( $< -20\text{dB}$ , within 20% of prior calibration), and in impedance (within 5 ohm of prior calibration), the annual calibration is not necessary and the calibration interval can be extended.

### <Justification of the extended calibration>

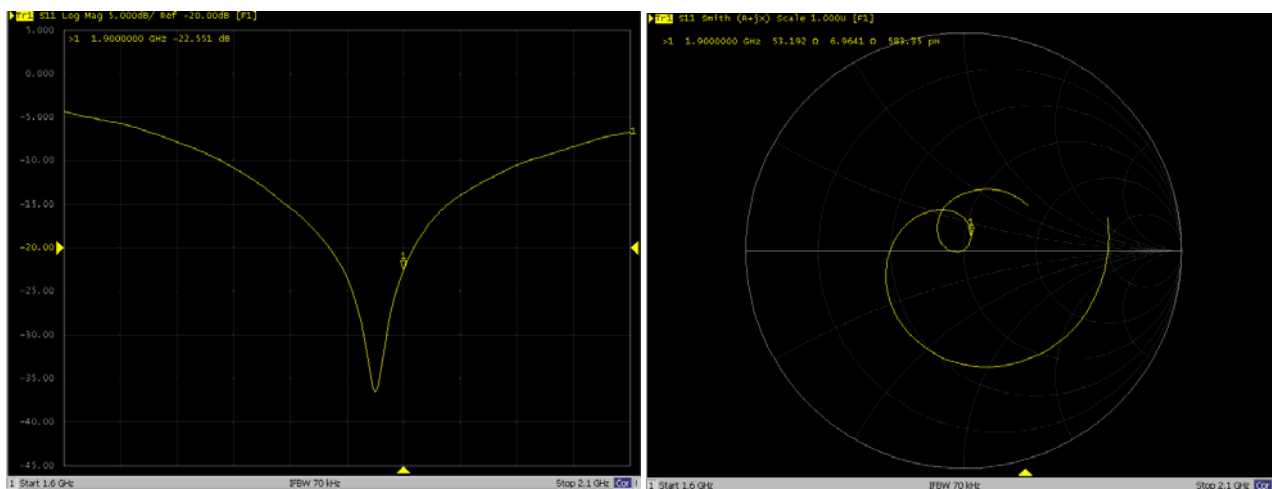
D1900V2 – serial no. 5d118												
	1900 Head						1900 Body					
Date of Measurement	Return-Loss (dB)	Delta (%)	Real Impedance (ohm)	Delta (ohm)	Imaginary Impedance (ohm)	Delta (ohm)	Return-Loss (dB)	Delta (%)	Real Impedance (ohm)	Delta (ohm)	Imaginary Impedance (ohm)	Delta (ohm)
11.21.2011	-22.535		53.449		6.9277		-22.401		47.82		7.1133	
11.17.2012	-22.603	0.30	53.491	-0.04	7.1009	-0.17	-22.450	0.22	46.14	-1.68	6.7234	-0.39
11.15.2013	-22.551	0.23	53.192	0.30	6.9641	0.14	-22.412	0.17	47.419	-1.28	7.1127	-0.39

The return loss is  $< -20\text{dB}$ , within 20% of prior calibration; the impedance is within 5 ohm of prior calibration.

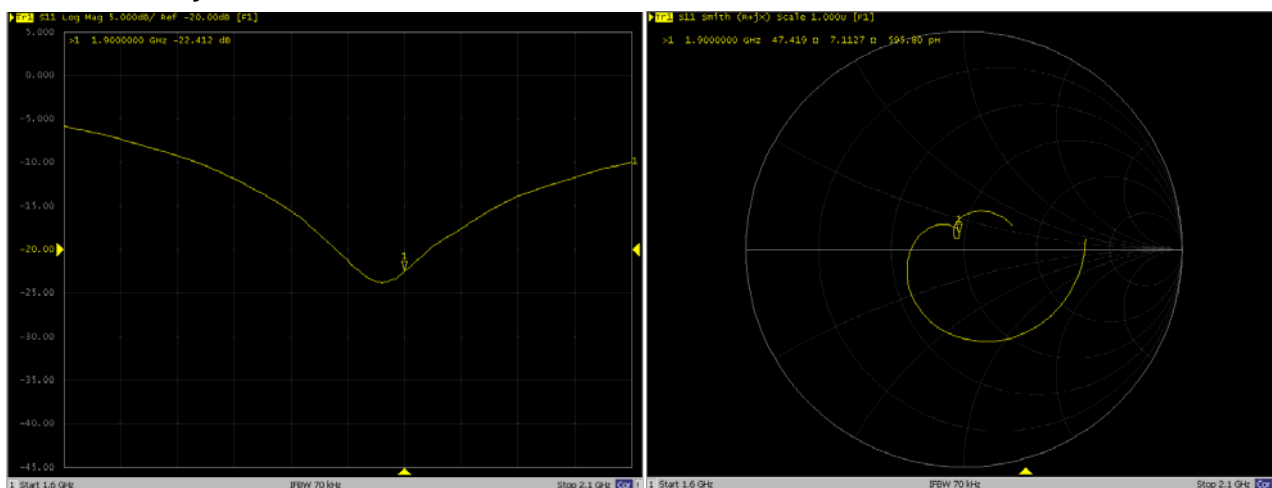
Therefore the verification result should support extended calibration.

## <Dipole Verification Data>- D1900V2, serial no. 5d118

### 1900MHz – Head



### 1900MHz - Body





## IMPORTANT NOTICE

### USAGE OF THE DAE 4

The DAE unit is a delicate, high precision instrument and requires careful treatment by the user. There are no serviceable parts inside the DAE. Special attention shall be given to the following points:

**Battery Exchange:** The battery cover of the DAE4 unit is closed using a screw, over tightening the screw may cause the threads inside the DAE to wear out.

**Shipping of the DAE:** Before shipping the DAE to SPEAG for calibration, remove the batteries and pack the DAE in an antistatic bag. This antistatic bag shall then be packed into a larger box or container which protects the DAE from impacts during transportation. The package shall be marked to indicate that a fragile instrument is inside.

**E-Stop Failures:** Touch detection may be malfunctioning due to broken magnets in the E-stop. Rough handling of the E-stop may lead to damage of these magnets. Touch and collision errors are often caused by dust and dirt accumulated in the E-stop. To prevent E-stop failure, the customer shall always mount the probe to the DAE carefully and keep the DAE unit in a non-dusty environment if not used for measurements.

**Repair:** Minor repairs are performed at no extra cost during the annual calibration. However, SPEAG reserves the right to charge for any repair especially if rough unprofessional handling caused the defect.

**DASY Configuration Files:** Since the exact values of the DAE input resistances, as measured during the calibration procedure of a DAE unit, are not used by the DASY software, a nominal value of 200 MOhm is given in the corresponding configuration file.

**Important Note:**

**Warranty and calibration is void if the DAE unit is disassembled partly or fully by the Customer.**

**Important Note:**

**Never attempt to grease or oil the E-stop assembly. Cleaning and readjusting of the E-stop assembly is allowed by certified SPEAG personnel only and is part of the annual calibration procedure.**

**Important Note:**

**To prevent damage of the DAE probe connector pins, use great care when installing the probe to the DAE. Carefully connect the probe with the connector notch oriented in the mating position. Avoid any rotational movement of the probe body versus the DAE while turning the locking nut of the connector. The same care shall be used when disconnecting the probe from the DAE.**



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Client **Auden**

Certificate No: **DAE4-910\_Dec13**

## CALIBRATION CERTIFICATE

Object **DAE4 - SD 000 D04 BK - SN: 910**

Calibration procedure(s) **QA CAL-06.v26**  
**Calibration procedure for the data acquisition electronics (DAE)**

Calibration date: **December 17, 2013**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).  
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature  $(22 \pm 3)^{\circ}\text{C}$  and humidity  $< 70\%$ .

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Keithley Multimeter Type 2001	SN: 0810278	01-Oct-13 (No:13976)	Oct-14
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Auto DAE Calibration Unit	SE UWS 053 AA 1001	07-Jan-13 (in house check)	In house check: Jan-14
Calibrator Box V2.1	SE UMS 006 AA 1002	07-Jan-13 (in house check)	In house check: Jan-14

Calibrated by:	Name <b>R.Mayoraz</b>	Function <b>Technician</b>	Signature 
Approved by:	<b>Fin Bomholt</b>	<b>Deputy Technical Manager</b>	

Issued: December 17, 2013

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Accreditation No.: **SCS 108**

## Glossary

DAE data acquisition electronics  
Connector angle information used in DASY system to align probe sensor X to the robot coordinate system.

## Methods Applied and Interpretation of Parameters

- *DC Voltage Measurement:* Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle:* The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
  - *DC Voltage Measurement Linearity:* Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
  - *Common mode sensitivity:* Influence of a positive or negative common mode voltage on the differential measurement.
  - *Channel separation:* Influence of a voltage on the neighbor channels not subject to an input voltage.
  - *AD Converter Values with inputs shorted:* Values on the internal AD converter corresponding to zero input voltage
  - *Input Offset Measurement:* Output voltage and statistical results over a large number of zero voltage measurements.
  - *Input Offset Current:* Typical value for information; Maximum channel input offset current, not considering the input resistance.
  - *Input resistance:* Typical value for information; DAE input resistance at the connector, during internal auto-zeroing and during measurement.
  - *Low Battery Alarm Voltage:* Typical value for information. Below this voltage, a battery alarm signal is generated.
  - *Power consumption:* Typical value for information. Supply currents in various operating modes.

## DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1  $\mu$ V , full range = -100...+300 mV

Low Range: 1LSB = 61 nV , full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	403.322 $\pm$ 0.02% (k=2)	402.723 $\pm$ 0.02% (k=2)	403.207 $\pm$ 0.02% (k=2)
Low Range	3.98182 $\pm$ 1.50% (k=2)	3.94224 $\pm$ 1.50% (k=2)	3.94936 $\pm$ 1.50% (k=2)

## Connector Angle

Connector Angle to be used in DASY system	233.0 ° $\pm$ 1 °
---	-------------------

## Appendix

### 1. DC Voltage Linearity

High Range		Reading ( $\mu\text{V}$ )	Difference ( $\mu\text{V}$ )	Error (%)
Channel X	+ Input	200032.32	-0.83	-0.00
Channel X	+ Input	20004.60	1.54	0.01
Channel X	- Input	-20002.78	3.07	-0.02
Channel Y	+ Input	200035.16	1.90	0.00
Channel Y	+ Input	20001.98	-1.07	-0.01
Channel Y	- Input	-20006.13	-0.17	0.00
Channel Z	+ Input	200035.21	2.05	0.00
Channel Z	+ Input	20002.94	-0.06	-0.00
Channel Z	- Input	-20006.08	-0.02	0.00

Low Range		Reading ( $\mu\text{V}$ )	Difference ( $\mu\text{V}$ )	Error (%)
Channel X	+ Input	2000.35	0.48	0.02
Channel X	+ Input	200.15	0.15	0.08
Channel X	- Input	-200.04	0.14	-0.07
Channel Y	+ Input	2000.33	0.65	0.03
Channel Y	+ Input	199.54	-0.32	-0.16
Channel Y	- Input	-201.29	-1.11	0.55
Channel Z	+ Input	2001.04	1.27	0.06
Channel Z	+ Input	198.05	-1.62	-0.81
Channel Z	- Input	-201.41	-1.23	0.61

### 2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading ( $\mu\text{V}$ )	Low Range Average Reading ( $\mu\text{V}$ )
Channel X	200	-14.07	-15.91
	- 200	17.64	15.36
Channel Y	200	5.92	6.01
	- 200	-6.42	-6.96
Channel Z	200	-11.90	-12.13
	- 200	9.23	9.49

### 3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X ( $\mu\text{V}$ )	Channel Y ( $\mu\text{V}$ )	Channel Z ( $\mu\text{V}$ )
Channel X	200	-	5.20	-3.06
Channel Y	200	10.28	-	5.40
Channel Z	200	11.13	8.33	-

#### 4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	16187	15921
Channel Y	15383	16628
Channel Z	16716	16362

#### 5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10M $\Omega$

	Average ( $\mu$ V)	min. Offset ( $\mu$ V)	max. Offset ( $\mu$ V)	Std. Deviation ( $\mu$ V)
Channel X	-0.00	-1.68	1.68	0.70
Channel Y	0.62	-0.76	1.86	0.60
Channel Z	-1.19	-2.62	0.29	0.69

#### 6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

#### 7. Input Resistance (Typical values for information)

	Zeroing (kOhm)	Measuring (MOhm)
Channel X	200	200
Channel Y	200	200
Channel Z	200	200

#### 8. Low Battery Alarm Voltage (Typical values for information)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

#### 9. Power Consumption (Typical values for information)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.01	+6	+14
Supply (- Vcc)	-0.01	-8	-9



## IMPORTANT NOTICE

### USAGE OF THE DAE 3

The DAE unit is a delicate, high precision instrument and requires careful treatment by the user. There are no serviceable parts inside the DAE. Special attention shall be given to the following points:

**Battery Exchange:** The battery cover of the DAE3 unit is connected to a fragile 3-pin battery connector. Customer is responsible to apply utmost caution not to bend or damage the connector when changing batteries.

**Shipping of the DAE:** Before shipping the DAE to SPEAG for calibration the customer shall remove the batteries and pack the DAE in an antistatic bag. This antistatic bag shall then be packed into a larger box or container which protects the DAE from impacts transportation. The package shall be marked to indicate that a fragile instrument is inside.

**E-Stop Failures:** Touch detection may be malfunctioning due to broken magnets in the E-stop. Rough handling of the E-stop may lead to damage of these magnets. Touch and collision errors are often caused by dust and dirt accumulated in the E-stop. To prevent E-stop failure, Customer shall always mount the probe to the DAE carefully and keep the DAE unit in a non-dusty environment if not used for measurements.

**Repair:** Minor repairs are performed at no extra cost during the annual calibration. However, SPEAG reserves the right to charge for any repair especially if rough unprofessional handling caused the defect.

**DASY Configuration Files:** Since the exact values of the DAE input resistances, as measured during the calibration procedure of a DAE unit, are not used by the DASY software, a nominal value of 200 MOhm is given in the corresponding configuration file.

**Important Note:**

**Warranty and calibration is void if the DAE unit is disassembled partly or fully by the Customer.**

**Important Note:**

**Never attempt to grease or oil the E-stop assembly. Cleaning and readjusting of the E-stop assembly is allowed by certified SPEAG personnel only and is part of the annual calibration procedure.**

**Important Note:**

**To prevent damage of the DAE probe connector pins, use great care when installing the probe to the DAE. Carefully connect the probe with the connector notch oriented in the mating position. Avoid any rotational movement of the probe body versus the DAE while turning the locking nut of the connector. The same care shall be used when disconnecting the probe from the DAE.**





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Client **SGS - ZH (Auden)**

Certificate No: **DAE3-569\_Nov13**

## CALIBRATION CERTIFICATE

Object **DAE3 - SD 000 D03 AA - SN: 569**

Calibration procedure(s) **QA CAL-06.v26**  
**Calibration procedure for the data acquisition electronics (DAE)**

Calibration date: **November 22, 2013**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).  
 The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature  $(22 \pm 3)^\circ\text{C}$  and humidity  $< 70\%$ .

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Keithley Multimeter Type 2001	SN: 0810278	01-Oct-13 (No:13976)	Oct-14
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Auto DAE Calibration Unit	SE UWS 053 AA 1001	07-Jan-13 (in house check)	In house check: Jan-14
Calibrator Box V2.1	SE UMS 006 AA 1002	07-Jan-13 (in house check)	In house check: Jan-14

	Name	Function	Signature
Calibrated by:	Eric Hainfeld	Technician	
Approved by:	Fin Bomholt	Deputy Technical Manager	

Issued: November 22, 2013

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Accreditation No.: **SCS 108**

## Glossary

DAE	data acquisition electronics
Connector angle	information used in DASY system to align probe sensor X to the robot coordinate system.

## Methods Applied and Interpretation of Parameters

- *DC Voltage Measurement:* Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle:* The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
  - *DC Voltage Measurement Linearity:* Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
  - *Common mode sensitivity:* Influence of a positive or negative common mode voltage on the differential measurement.
  - *Channel separation:* Influence of a voltage on the neighbor channels not subject to an input voltage.
  - *AD Converter Values with inputs shorted:* Values on the internal AD converter corresponding to zero input voltage
  - *Input Offset Measurement:* Output voltage and statistical results over a large number of zero voltage measurements.
  - *Input Offset Current:* Typical value for information; Maximum channel input offset current, not considering the input resistance.
  - *Input resistance:* Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
  - *Low Battery Alarm Voltage:* Typical value for information. Below this voltage, a battery alarm signal is generated.
  - *Power consumption:* Typical value for information. Supply currents in various operating modes.

## DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1 $\mu$ V , full range = -100...+300 mV

Low Range: 1LSB = 61nV , full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	403.044 $\pm$ 0.02% (k=2)	403.443 $\pm$ 0.02% (k=2)	403.617 $\pm$ 0.02% (k=2)
Low Range	3.94201 $\pm$ 1.50% (k=2)	3.95604 $\pm$ 1.50% (k=2)	3.94389 $\pm$ 1.50% (k=2)

## Connector Angle

Connector Angle to be used in DASY system	262.5 ° $\pm$ 1 °
---	-------------------



## Appendix

### 1. DC Voltage Linearity

High Range	Reading ( $\mu\text{V}$ )	Difference ( $\mu\text{V}$ )	Error (%)
Channel X + Input	199993.93	-2.78	-0.00
Channel X + Input	19998.22	-2.12	-0.01
Channel X - Input	-20001.42	-0.25	0.00
Channel Y + Input	199997.32	0.36	0.00
Channel Y + Input	20002.20	1.55	0.01
Channel Y - Input	-20000.21	0.87	-0.00
Channel Z + Input	199997.05	-0.02	-0.00
Channel Z + Input	19996.57	-3.95	-0.02
Channel Z - Input	-20001.04	0.17	-0.00

Low Range	Reading ( $\mu\text{V}$ )	Difference ( $\mu\text{V}$ )	Error (%)
Channel X + Input	2001.02	0.39	0.02
Channel X + Input	201.44	0.42	0.21
Channel X - Input	-197.34	1.32	-0.67
Channel Y + Input	2000.80	0.19	0.01
Channel Y + Input	201.17	0.07	0.03
Channel Y - Input	-199.58	-0.75	0.38
Channel Z + Input	2000.93	0.26	0.01
Channel Z + Input	200.10	-0.84	-0.42
Channel Z - Input	-199.73	-0.91	0.46

### 2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading ( $\mu\text{V}$ )	Low Range Average Reading ( $\mu\text{V}$ )
Channel X	200	-0.24	-2.04
	- 200	2.76	1.27
Channel Y	200	4.80	4.90
	- 200	-6.14	-6.55
Channel Z	200	-13.76	-13.77
	- 200	11.04	11.29

### 3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X ( $\mu\text{V}$ )	Channel Y ( $\mu\text{V}$ )	Channel Z ( $\mu\text{V}$ )
Channel X	200	-	2.83	-2.47
Channel Y	200	9.46	-	3.54
Channel Z	200	7.51	7.74	-

#### 4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	16190	16754
Channel Y	16540	16468
Channel Z	15791	17162

#### 5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10M $\Omega$

	Average ( $\mu$ V)	min. Offset ( $\mu$ V)	max. Offset ( $\mu$ V)	Std. Deviation ( $\mu$ V)
Channel X	0.60	-1.47	2.64	0.79
Channel Y	-0.27	-1.99	2.05	0.72
Channel Z	-1.01	-3.56	0.67	0.63

#### 6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

#### 7. Input Resistance (Typical values for information)

	Zeroing (kOhm)	Measuring (MOhm)
Channel X	200	200
Channel Y	200	200
Channel Z	200	200

#### 8. Low Battery Alarm Voltage (Typical values for information)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

#### 9. Power Consumption (Typical values for information)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.01	+6	+14
Supply (- Vcc)	-0.01	-8	-9





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Client **Sporton-KS (Auden)**

Certificate No: **EX3-3819\_Nov13**

## CALIBRATION CERTIFICATE

Object **EX3DV4 - SN:3819**

Calibration procedure(s) **QA CAL-01.v9, QA CAL-14.v4, QA CAL-23.v5, QA CAL-25.v6  
Calibration procedure for dosimetric E-field probes**

Calibration date: **November 27, 2013**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).  
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature  $(22 \pm 3)^{\circ}\text{C}$  and humidity  $< 70\%$ .

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	04-Apr-13 (No. 217-01733)	Apr-14
Power sensor E4412A	MY41498087	04-Apr-13 (No. 217-01733)	Apr-14
Reference 3 dB Attenuator	SN: S5054 (3c)	04-Apr-13 (No. 217-01737)	Apr-14
Reference 20 dB Attenuator	SN: S5277 (20x)	04-Apr-13 (No. 217-01735)	Apr-14
Reference 30 dB Attenuator	SN: S5129 (30b)	04-Apr-13 (No. 217-01738)	Apr-14
Reference Probe ES3DV2	SN: 3013	28-Dec-12 (No. ES3-3013_Dec12)	Dec-13
DAE4	SN: 660	4-Sep-13 (No. DAE4-660_Sep13)	Sep-14
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Apr-13)	In house check: Apr-15
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-13)	In house check: Oct-14

Calibrated by:	Name <b>Israe El-Naouq</b>	Function <b>Laboratory Technician</b>	Signature 
Approved by:	<b>Katja Pokovic</b>	<b>Technical Manager</b>	

Issued: November 30, 2013

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### Glossary:

TSL	tissue simulating liquid
NORM <sub>x,y,z</sub>	sensitivity in free space
ConvF	sensitivity in TSL / NORM <sub>x,y,z</sub>
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C, D	modulation dependent linearization parameters
Polarization $\phi$	$\phi$ rotation around probe axis
Polarization $\vartheta$	$\vartheta$ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

### Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

### Methods Applied and Interpretation of Parameters:

- NORM<sub>x,y,z</sub>:** Assessed for E-field polarization  $\vartheta = 0$  ( $f \leq 900$  MHz in TEM-cell;  $f > 1800$  MHz: R22 waveguide). NORM<sub>x,y,z</sub> are only intermediate values, i.e., the uncertainties of NORM<sub>x,y,z</sub> does not affect the  $E^2$ -field uncertainty inside TSL (see below ConvF).
- NORM(f)<sub>x,y,z</sub> = NORM<sub>x,y,z</sub> \* frequency\_response** (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCP<sub>x,y,z</sub>:** DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR:** PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- A<sub>x,y,z</sub>; B<sub>x,y,z</sub>; C<sub>x,y,z</sub>; D<sub>x,y,z</sub>; VR<sub>x,y,z</sub>:** A, B, C, D are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters:** Assessed in flat phantom using E-field (or Temperature Transfer Standard for  $f \leq 800$  MHz) and inside waveguide using analytical field distributions based on power measurements for  $f > 800$  MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORM<sub>x,y,z</sub> \* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from  $\pm 50$  MHz to  $\pm 100$  MHz.
- Spherical isotropy (3D deviation from isotropy):** in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset:** The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle:** The angle is assessed using the information gained by determining the NORM<sub>x</sub> (no uncertainty required).

# Probe EX3DV4

## SN:3819

Manufactured: September 2, 2011  
Calibrated: November 27, 2013

Calibrated for DASY/EASY Systems  
(Note: non-compatible with DASY2 system!)

## DASY/EASY - Parameters of Probe: EX3DV4 - SN:3819

### Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ( $\mu\text{V}/(\text{V}/\text{m})^2$ ) <sup>A</sup>	0.48	0.38	0.53	$\pm 10.1 \%$
DCP (mV) <sup>B</sup>	95.5	103.0	99.3	

### Modulation Calibration Parameters

UID	Communication System Name		A dB	B dB $\sqrt{\mu\text{V}}$	C	D dB	VR mV	Unc <sup>E</sup> (k=2)
0	CW	X	0.0	0.0	1.0	0.00	159.1	$\pm 3.3 \%$
		Y	0.0	0.0	1.0		177.5	
		Z	0.0	0.0	1.0		159.5	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

<sup>A</sup> The uncertainties of NormX,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Pages 5 and 6).

<sup>B</sup> Numerical linearization parameter: uncertainty not required.

<sup>E</sup> Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.



## DASY/EASY - Parameters of Probe: EX3DV4 - SN:3819

### Calibration Parameter Determined in Head Tissue Simulating Media

f (MHz) <sup>C</sup>	Relative Permittivity <sup>F</sup>	Conductivity (S/m) <sup>F</sup>	ConvF X	ConvF Y	ConvF Z	Alpha <sup>G</sup>	Depth <sup>G</sup> (mm)	Unct. (k=2)
750	41.9	0.89	10.13	10.13	10.13	0.22	1.24	± 12.0 %
835	41.5	0.90	9.68	9.68	9.68	0.16	1.83	± 12.0 %
900	41.5	0.97	9.64	9.64	9.64	0.19	1.45	± 12.0 %
1750	40.1	1.37	8.26	8.26	8.26	0.67	0.63	± 12.0 %
1900	40.0	1.40	8.00	8.00	8.00	0.57	0.66	± 12.0 %
2000	40.0	1.40	8.02	8.02	8.02	0.35	0.83	± 12.0 %
2450	39.2	1.80	7.22	7.22	7.22	0.32	0.90	± 12.0 %
2600	39.0	1.96	7.06	7.06	7.06	0.36	0.90	± 12.0 %
5200	36.0	4.66	5.27	5.27	5.27	0.35	1.80	± 13.1 %
5300	35.9	4.76	4.92	4.92	4.92	0.40	1.80	± 13.1 %
5500	35.6	4.96	4.63	4.63	4.63	0.45	1.80	± 13.1 %
5600	35.5	5.07	4.33	4.33	4.33	0.55	1.80	± 13.1 %
5800	35.3	5.27	4.49	4.49	4.49	0.50	1.80	± 13.1 %

<sup>C</sup> Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

<sup>F</sup> At frequencies below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

<sup>G</sup> Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

## DASY/EASY - Parameters of Probe: EX3DV4 - SN:3819

### Calibration Parameter Determined in Body Tissue Simulating Media

f (MHz) <sup>C</sup>	Relative Permittivity <sup>F</sup>	Conductivity (S/m) <sup>F</sup>	ConvF X	ConvF Y	ConvF Z	Alpha <sup>G</sup>	Depth <sup>G</sup> (mm)	Unct. (k=2)
750	55.5	0.96	9.71	9.71	9.71	0.29	1.09	± 12.0 %
835	55.2	0.97	9.54	9.54	9.54	0.20	1.61	± 12.0 %
900	55.0	1.05	9.38	9.38	9.38	0.26	1.22	± 12.0 %
1750	53.4	1.49	8.01	8.01	8.01	0.80	0.61	± 12.0 %
1900	53.3	1.52	7.55	7.55	7.55	0.45	0.80	± 12.0 %
2000	53.3	1.52	7.64	7.64	7.64	0.42	0.86	± 12.0 %
2450	52.7	1.95	7.07	7.07	7.07	0.71	0.67	± 12.0 %
2600	52.5	2.16	6.79	6.79	6.79	0.80	0.62	± 12.0 %
5200	49.0	5.30	4.61	4.61	4.61	0.45	1.90	± 13.1 %
5300	48.9	5.42	4.34	4.34	4.34	0.50	1.90	± 13.1 %
5500	48.6	5.65	4.06	4.06	4.06	0.50	1.90	± 13.1 %
5600	48.5	5.77	3.89	3.89	3.89	0.50	1.90	± 13.1 %
5800	48.2	6.00	4.02	4.02	4.02	0.60	1.90	± 13.1 %

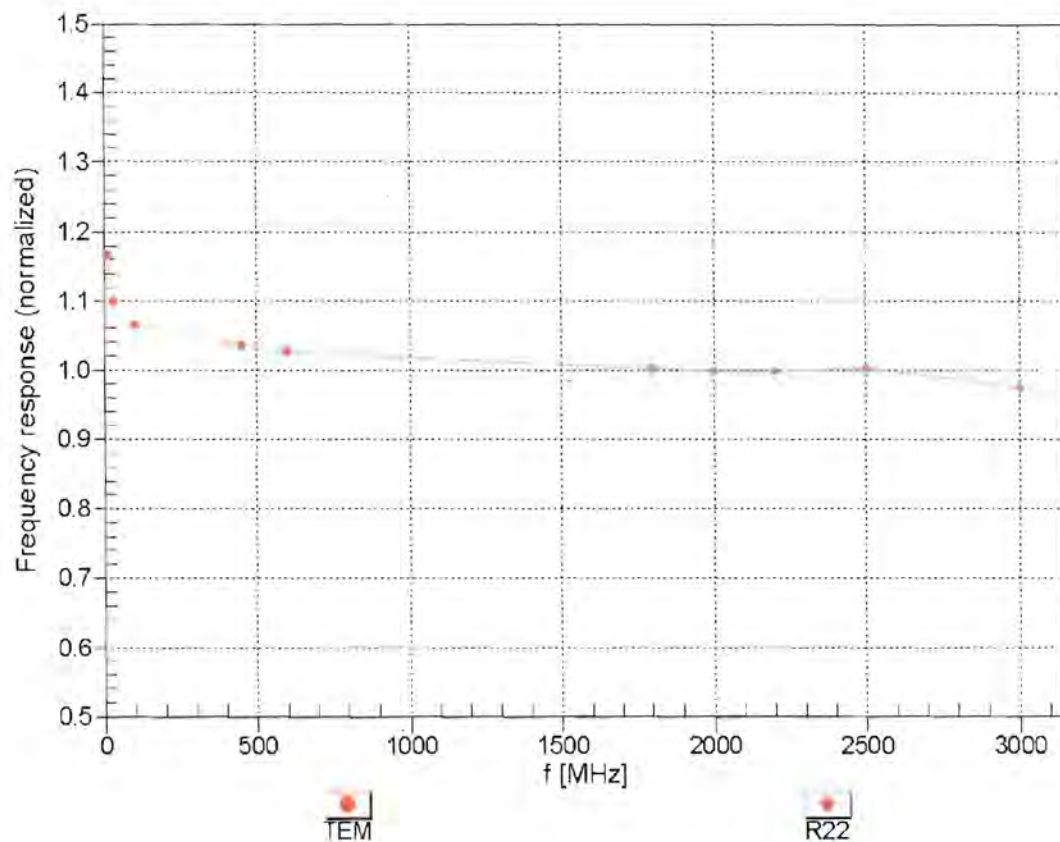
<sup>C</sup> Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

<sup>F</sup> At frequencies below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

<sup>G</sup> Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

## Frequency Response of E-Field

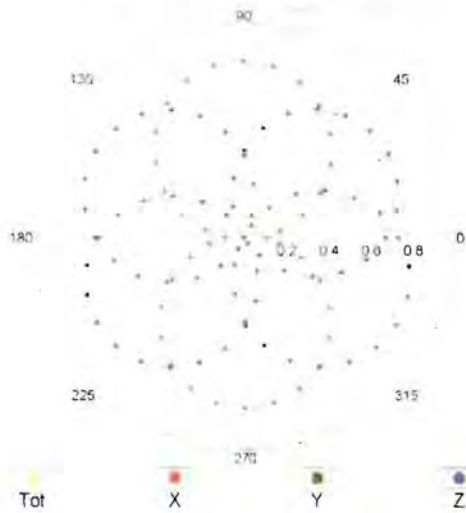
(TEM-Cell:ifi110 EXX, Waveguide: R22)



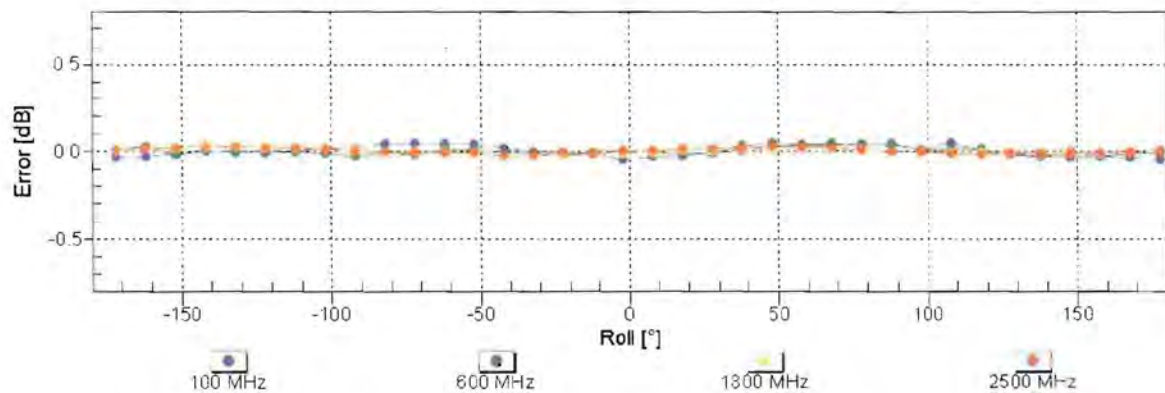
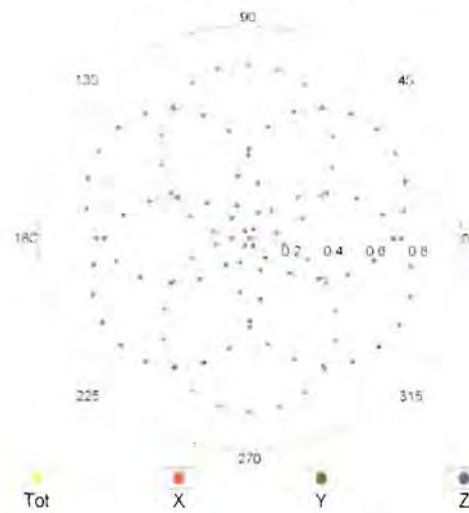
Uncertainty of Frequency Response of E-field:  $\pm 6.3\%$  ( $k=2$ )

## Receiving Pattern ( $\phi$ ), $\theta = 0^\circ$

f=600 MHz,TEM

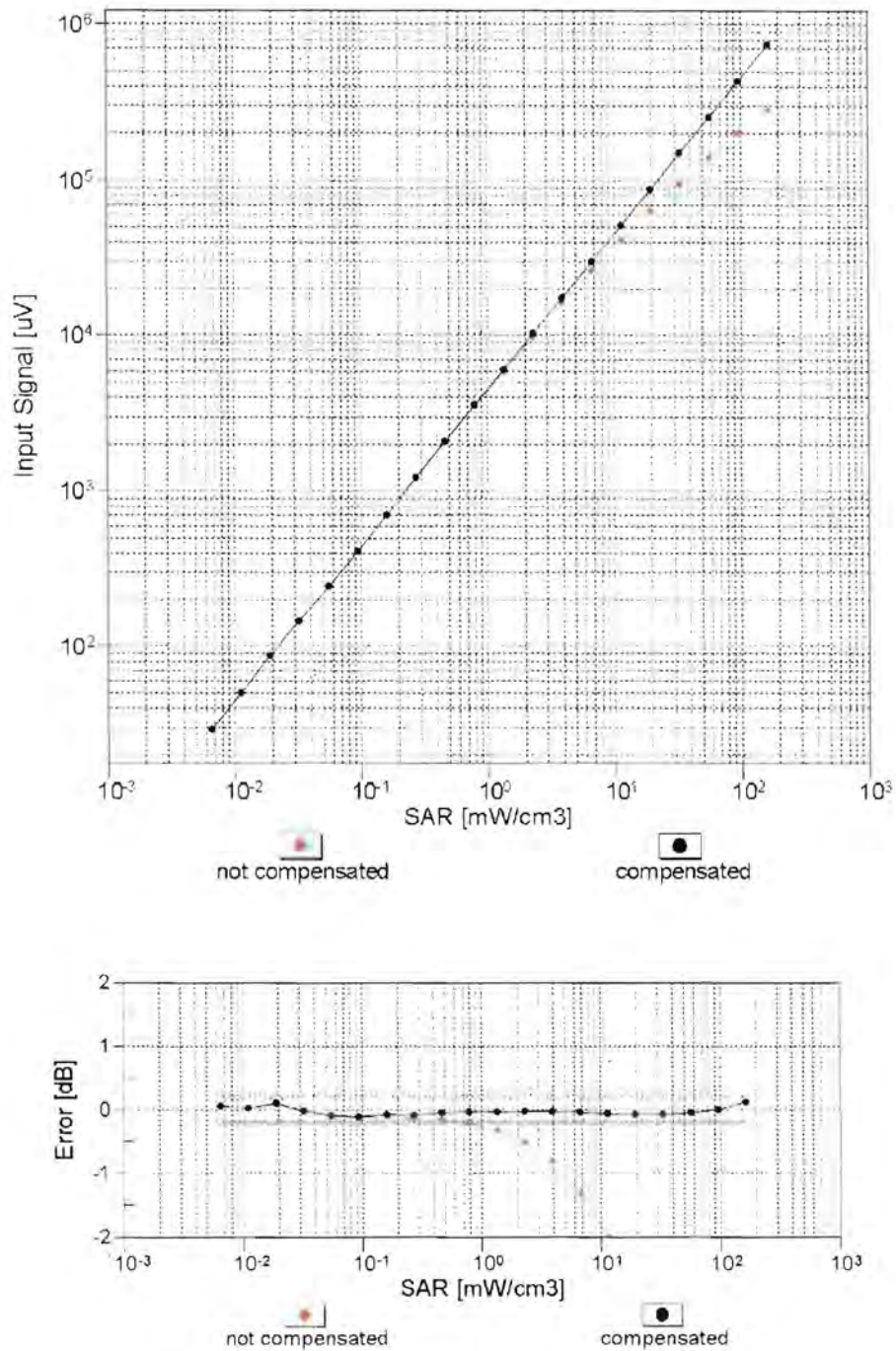


f=1800 MHz,R22



Uncertainty of Axial Isotropy Assessment:  $\pm 0.5\%$  ( $k=2$ )

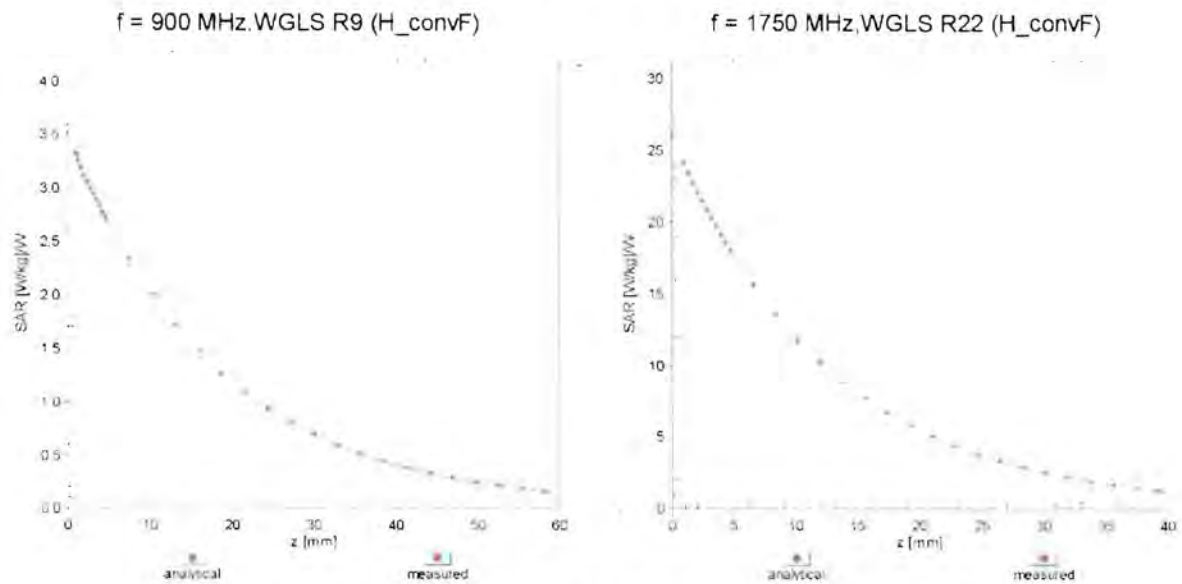
## Dynamic Range $f(\text{SAR}_{\text{head}})$ (TEM cell, $f = 900 \text{ MHz}$ )



Uncertainty of Linearity Assessment:  $\pm 0.6\%$  ( $k=2$ )

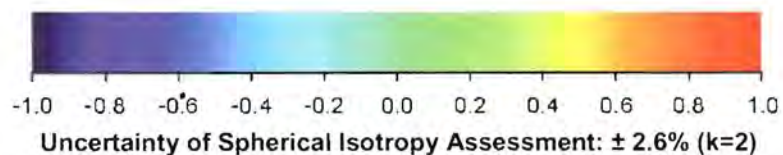
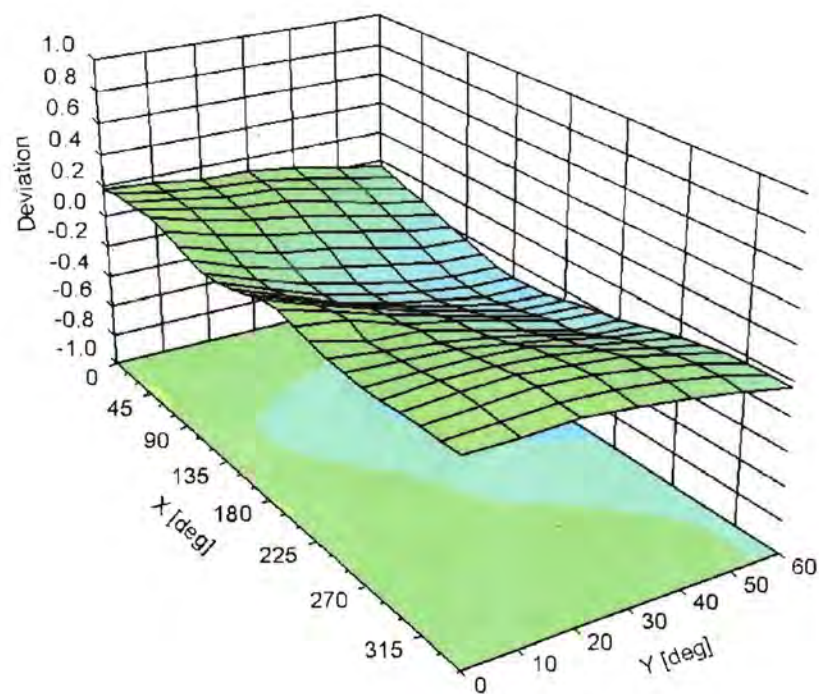


## Conversion Factor Assessment



## Deviation from Isotropy in Liquid

Error ( $\phi, \theta$ ),  $f = 900 \text{ MHz}$



Uncertainty of Spherical Isotropy Assessment:  $\pm 2.6\%$  ( $k=2$ )

## DASY/EASY - Parameters of Probe: EX3DV4 - SN:3819

### Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle (°)	-42.1
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	9 mm
Tip Diameter	2.5 mm
Probe Tip to Sensor X Calibration Point	1 mm
Probe Tip to Sensor Y Calibration Point	1 mm
Probe Tip to Sensor Z Calibration Point	1 mm
Recommended Measurement Distance from Surface	2 mm



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***Appendix D. Photographs of EUT***

Please refer to Sporton report number EP451707 which is issued separately.