

## Description for operating function

1. Power supply : 12VDC
2. Operation frequency: 27.145MHz;
3. Rated Sending Power: **80dB  $\mu$  V**
4. Turn on the power switch
5. Press JZ1、JZ2、JZ3; controlling forward ,left turn 、 right turn
6. Tx-2 send out remote control coding signal, through magnifying circuit and carrier wave, with sending circuit and antenna.
7. Push stick channel 2 up to control the airplane to fly up and forward; push stick channel 1 right or left to control the airplane to fly right or left
8. Turn off power switch
9. This car is a high-speed model, any may turn over when running on uneven ground or turning at high speed.
10. This car requires a comparatively large turning diameter when turning
11. Advance: push the left lever forward. The two motors will start spinning at full speed, pushing the car forward.
8. The controlling distance of the boat is about 50m; do not allow the boat to go beyond this distance to avoid losing its control
12. If you find the boat slows down, please immediately control it go to go back, otherwise, you may lose its control due to insufficient.
- 13 this controller uses 8 AA batteries (NI- cd or other types) or 9.6 V power pack
- 14 if the battery power has been used up, it needs 2 hours to fully charge the battery .if there is still power in the battery , charging time can be shortened accordingly.(when the battery surface becomes a little hot, it means it's already fully charged.