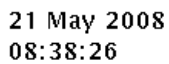
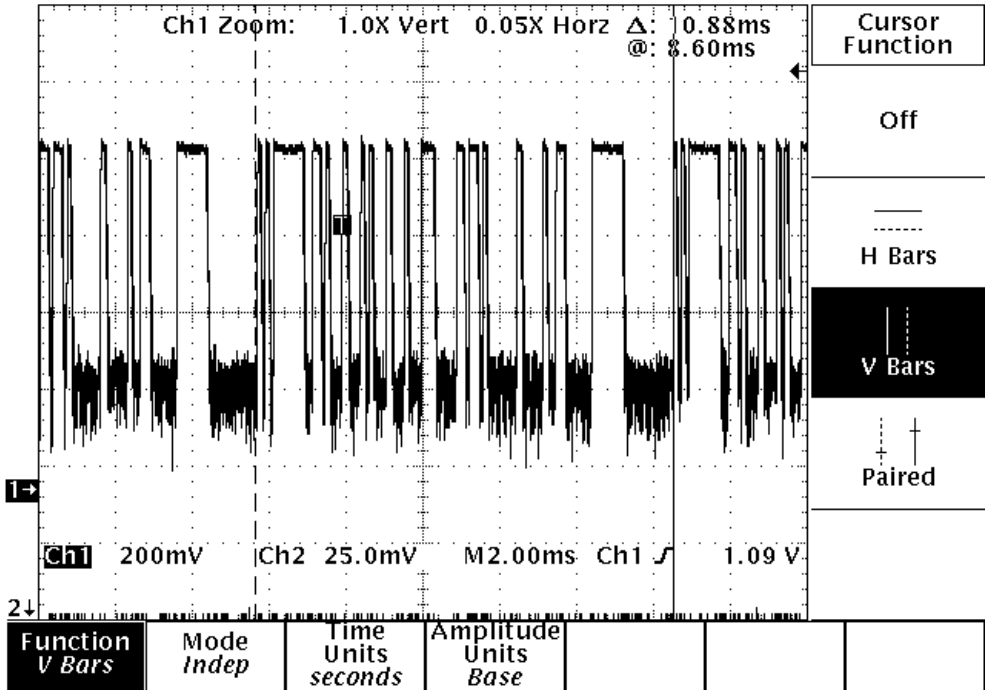
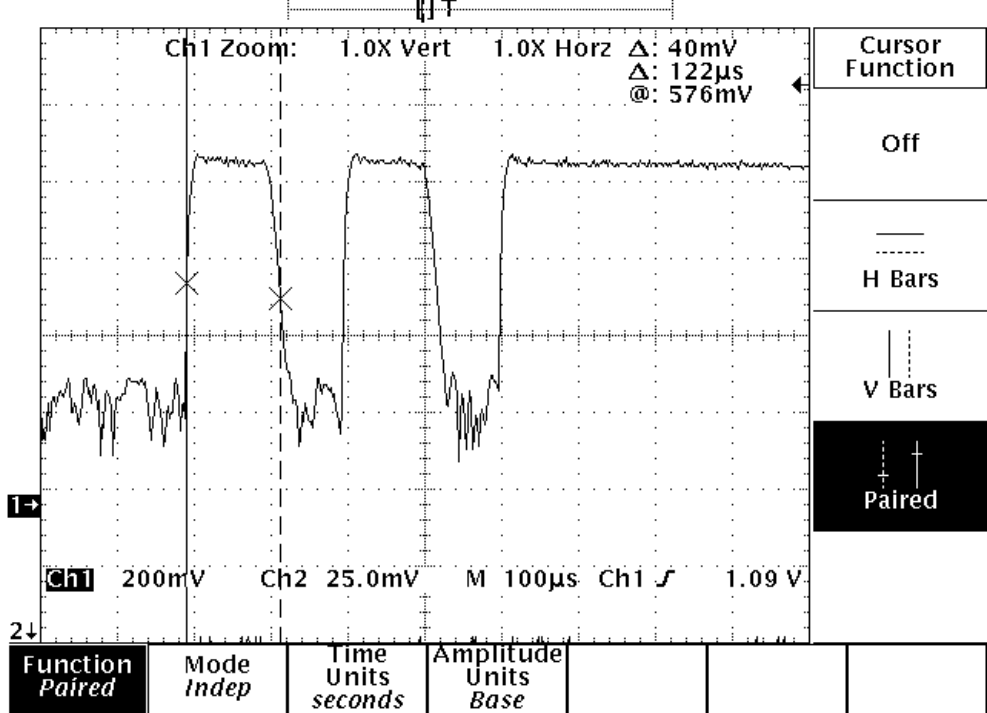
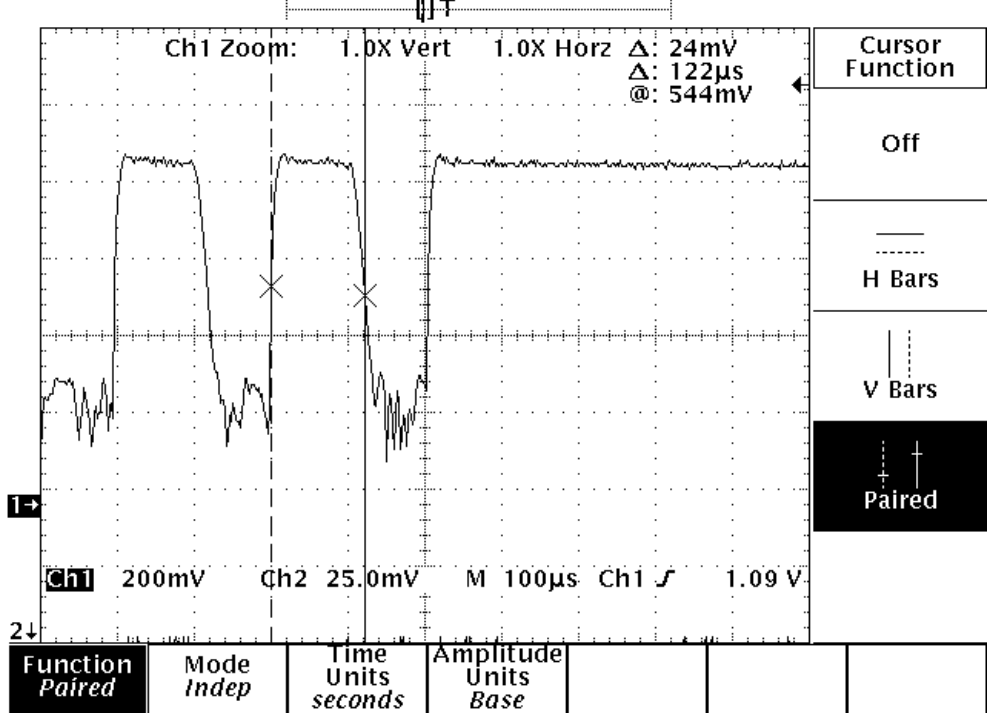


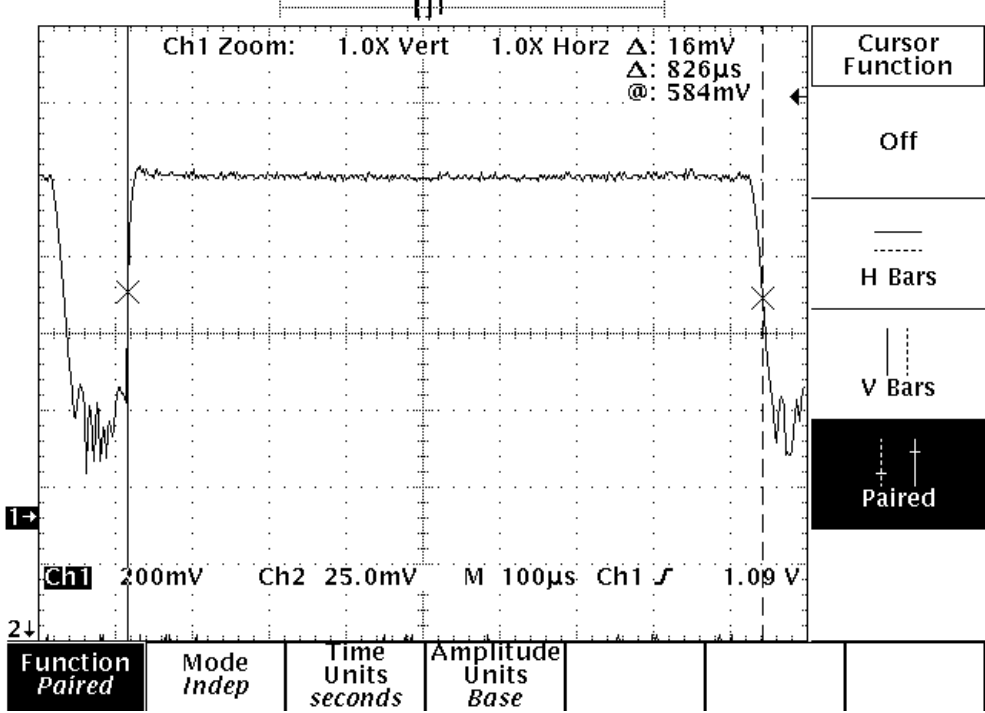
## Trig?

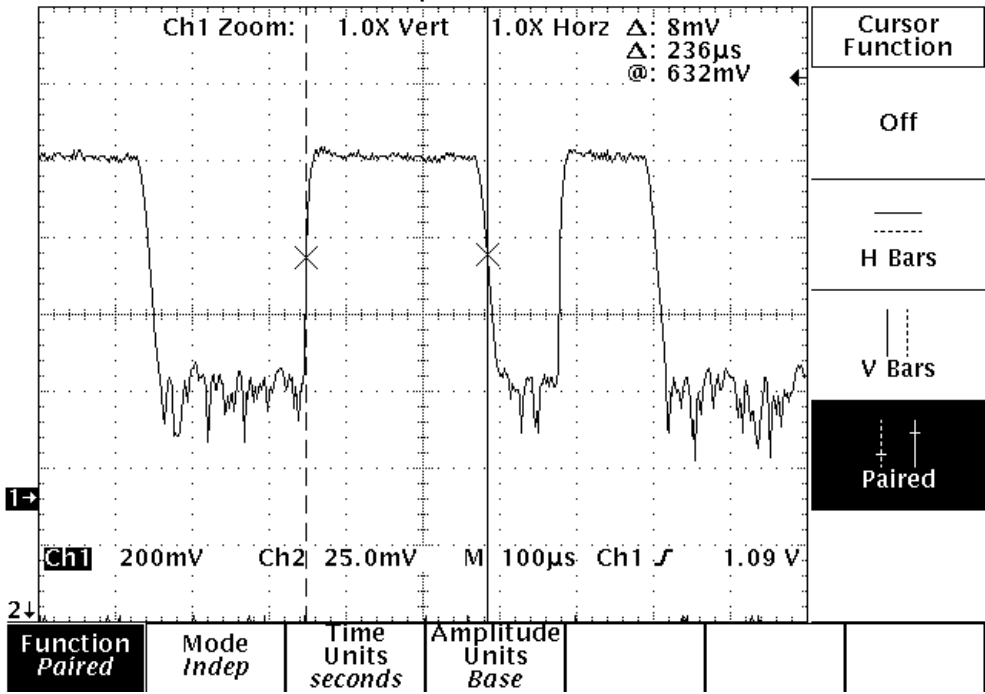


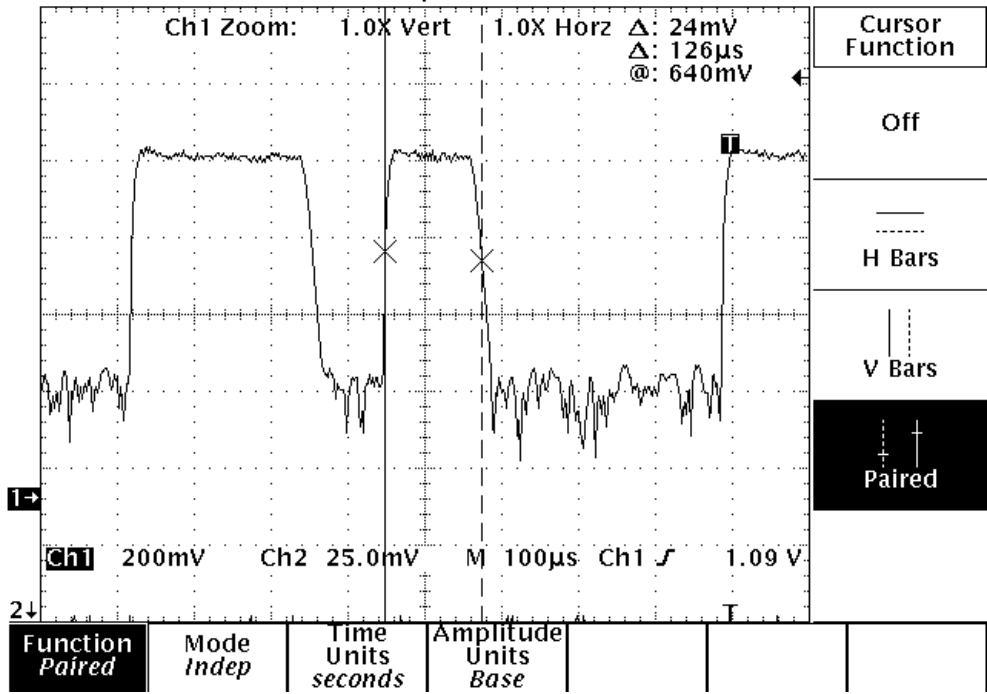


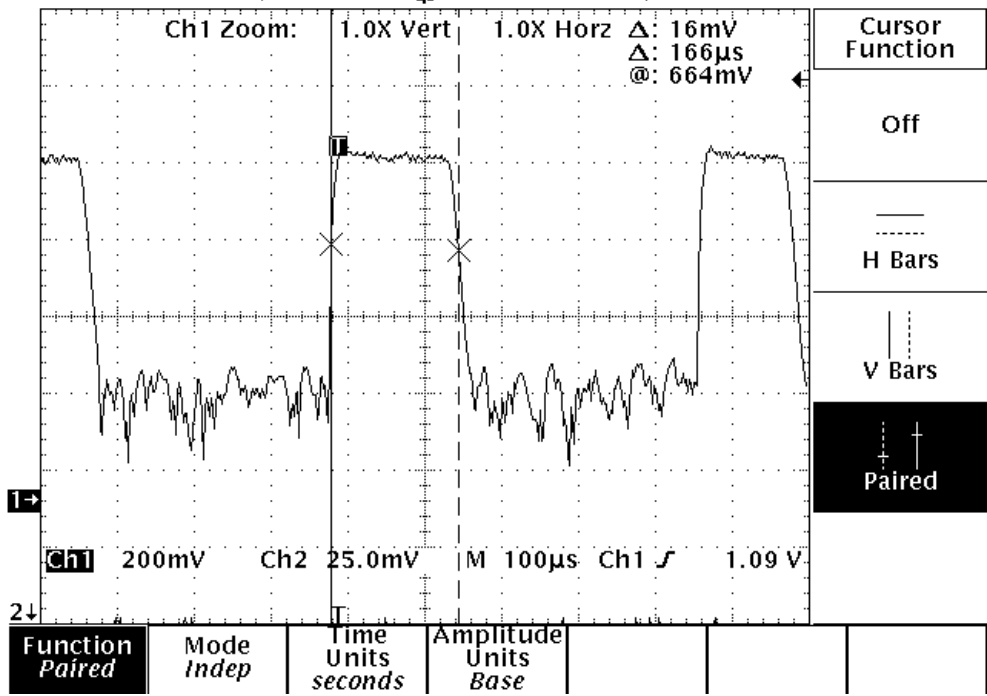


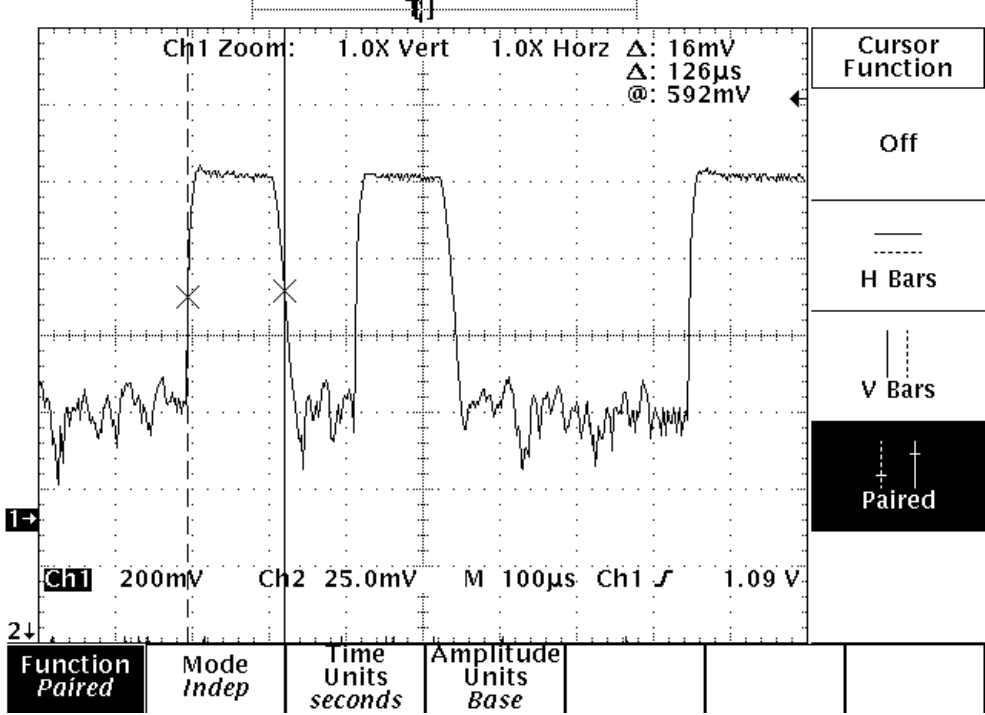


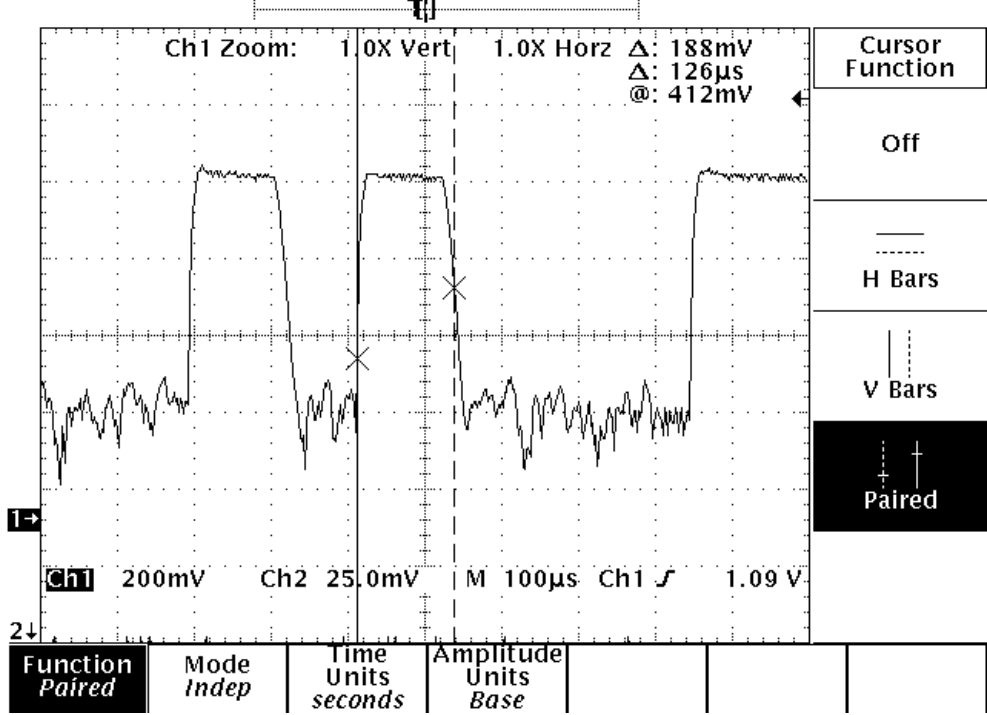


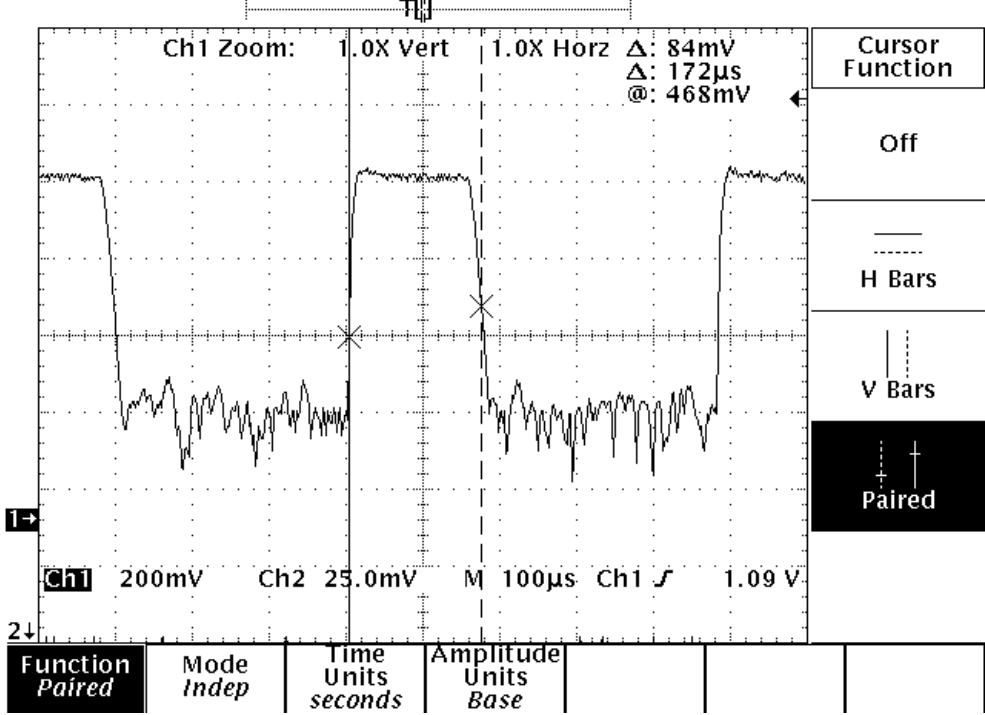


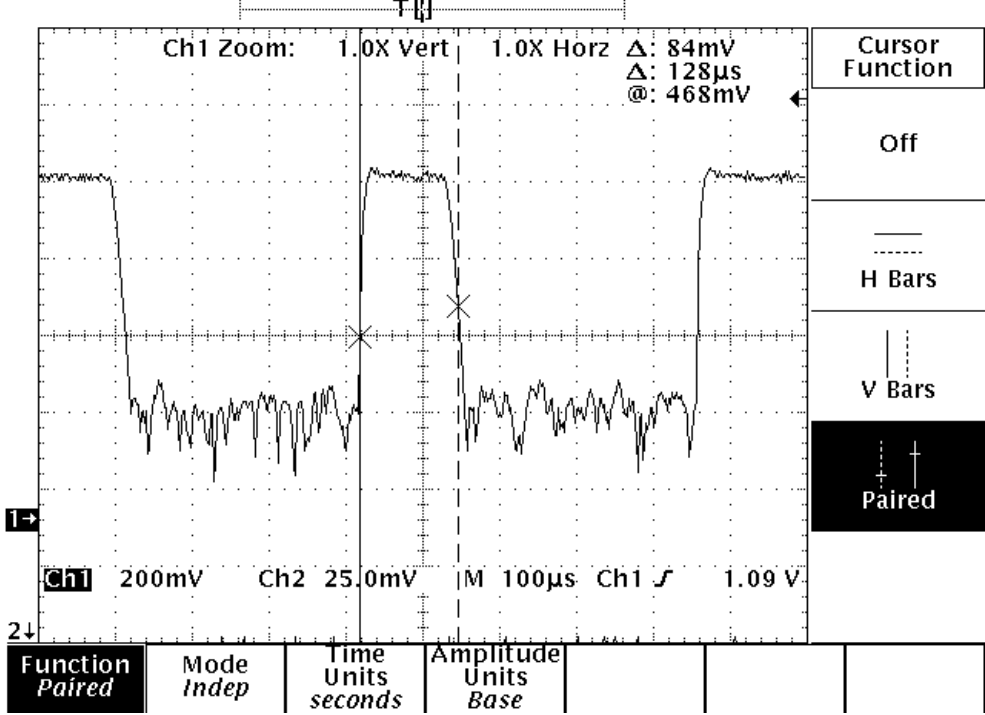


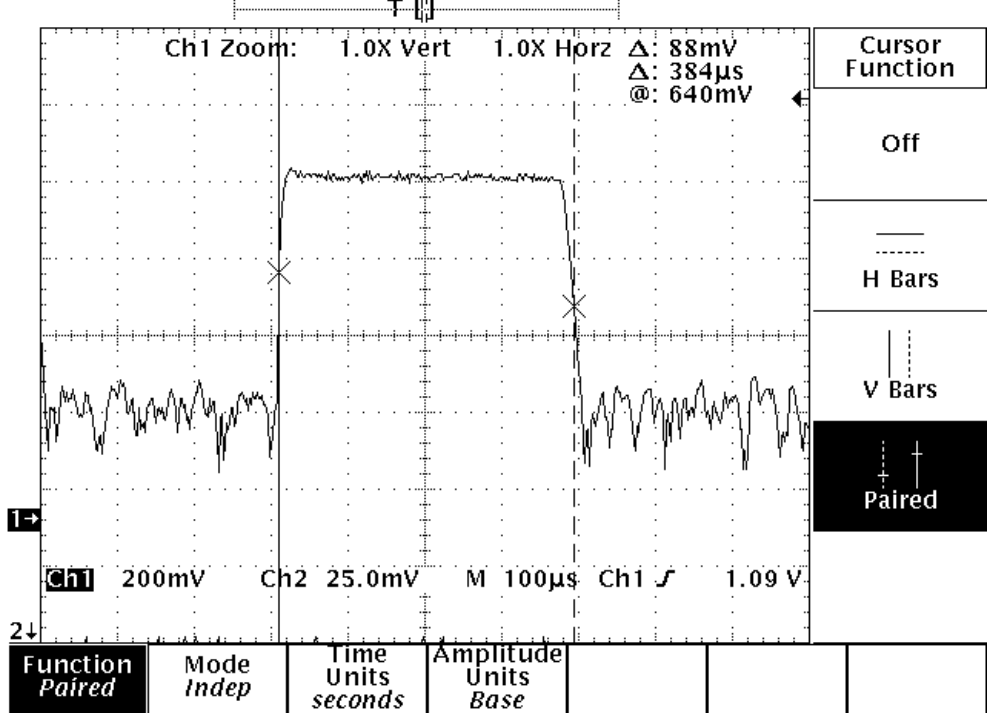


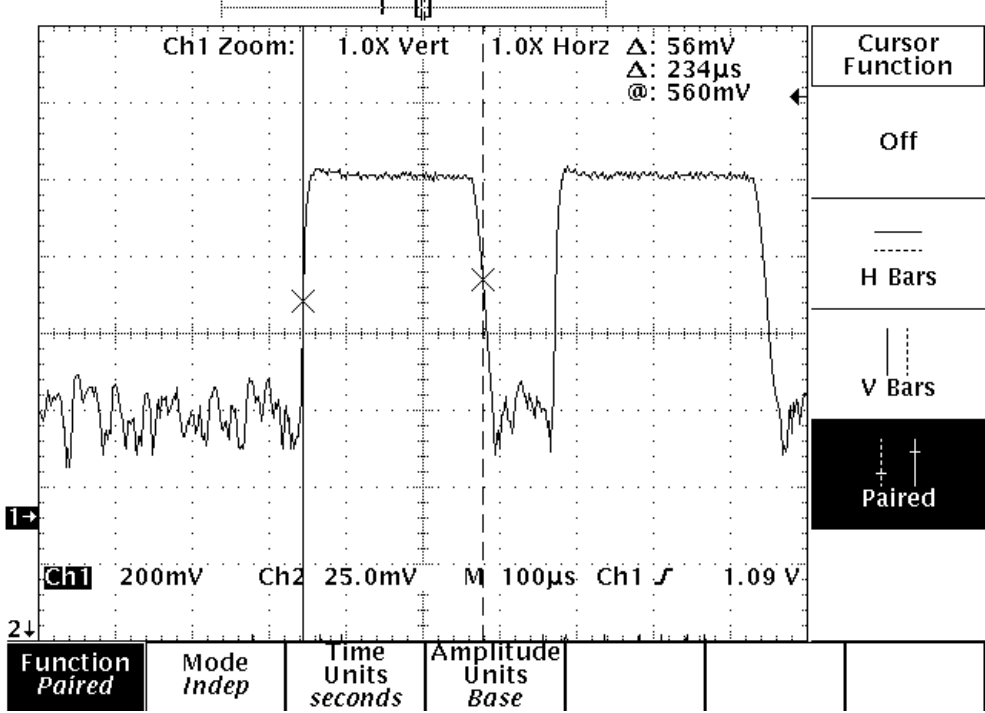


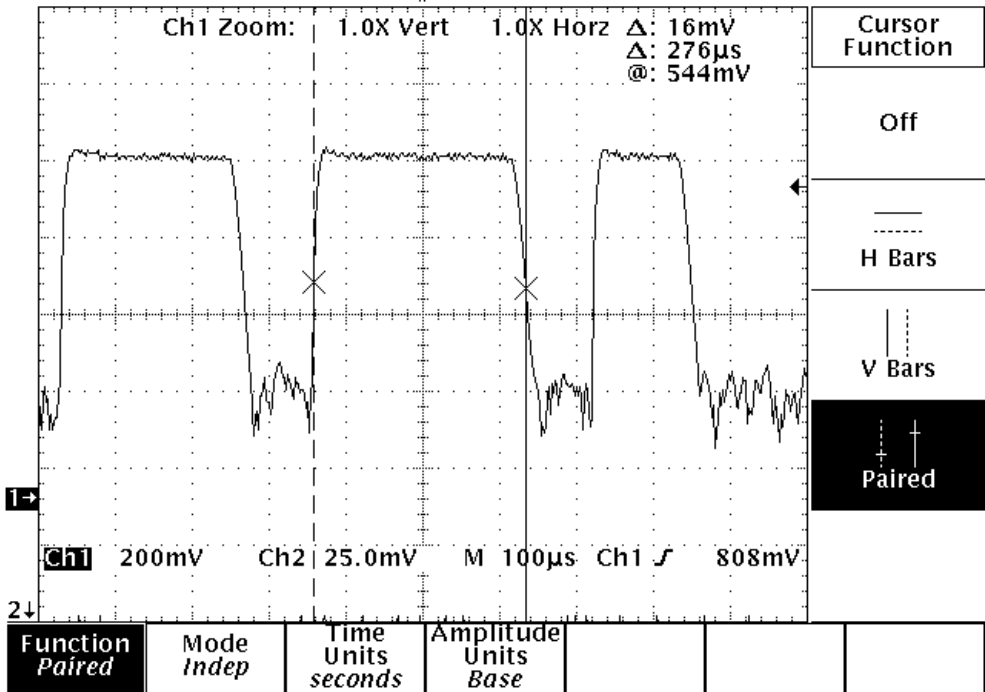


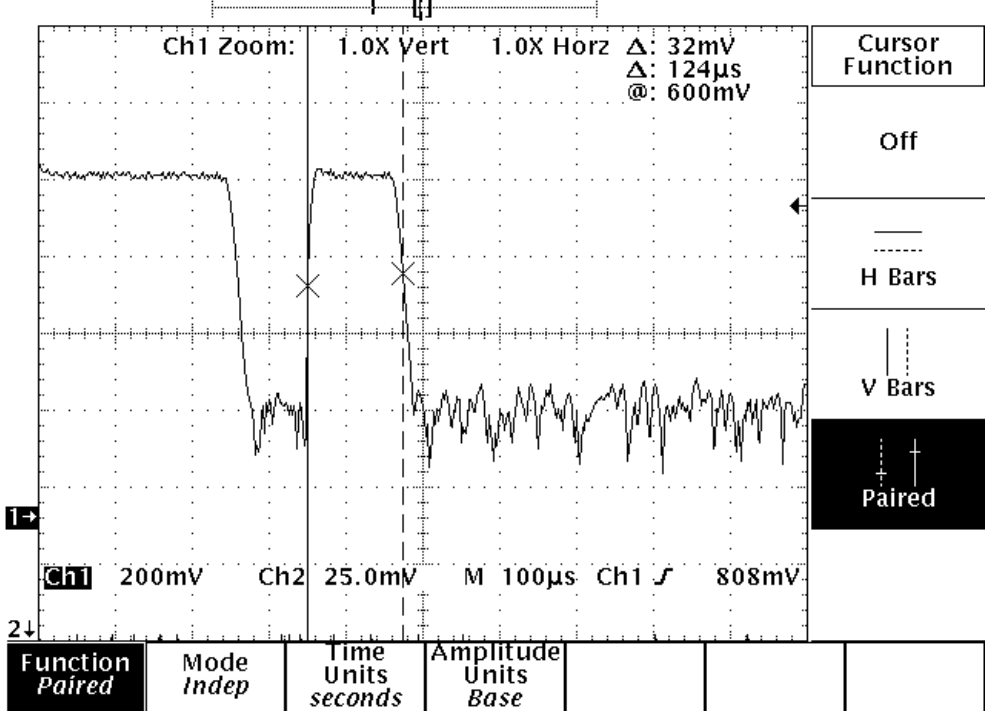


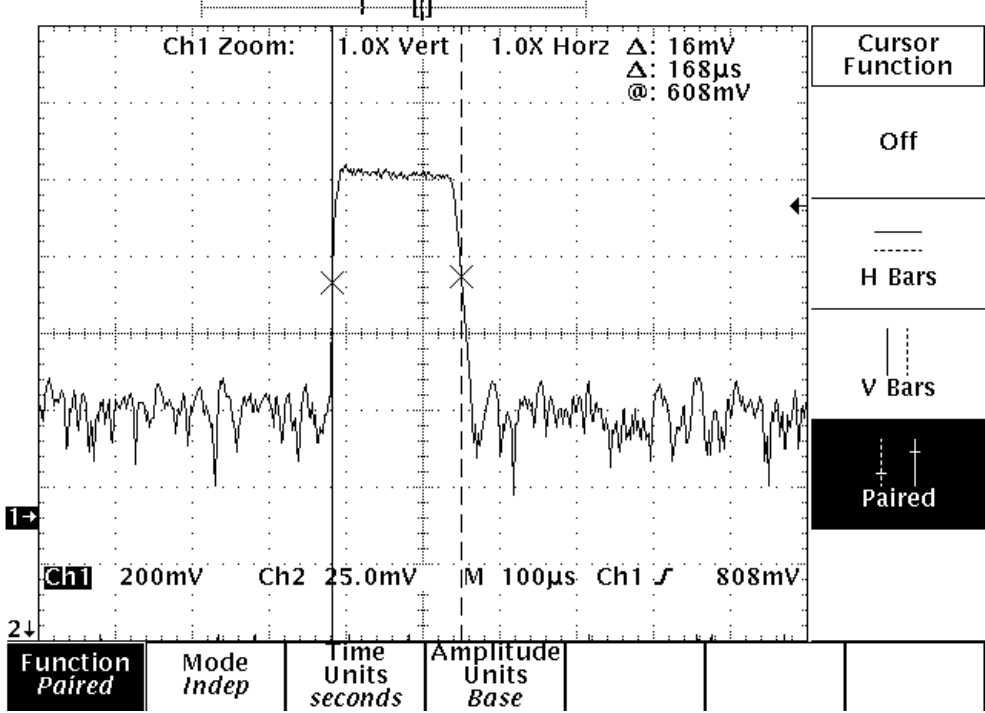




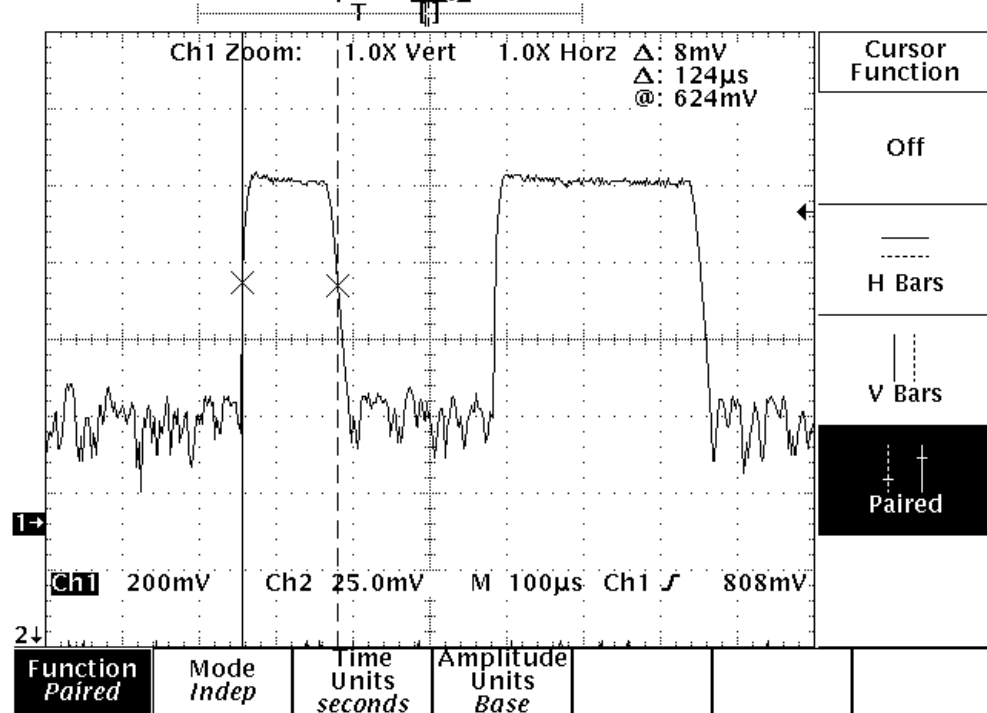


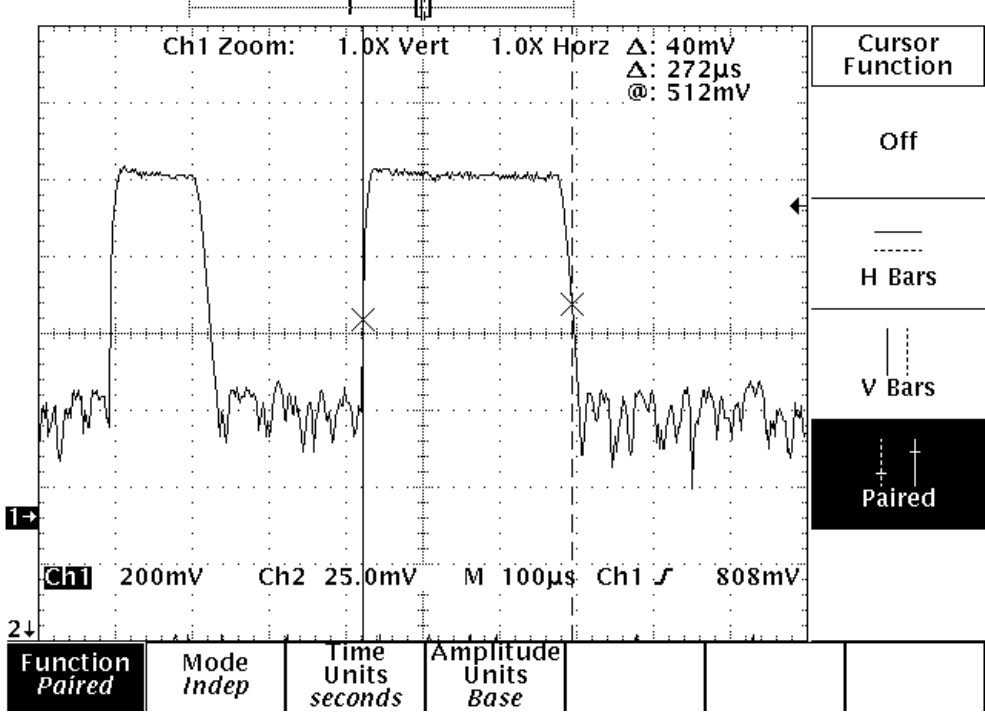


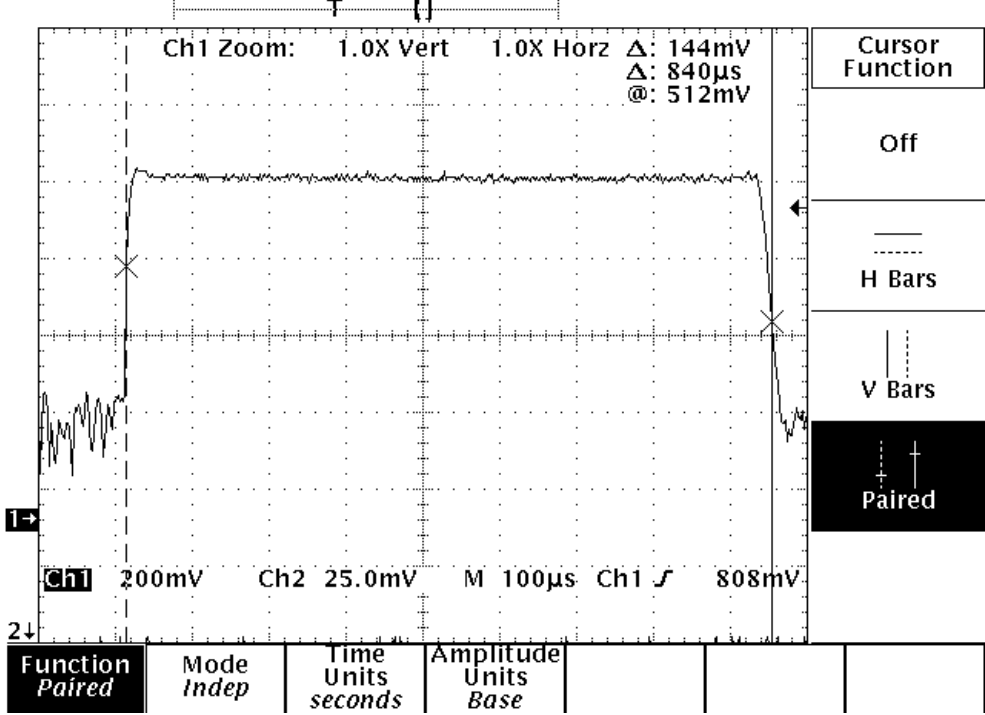




Tek Run: 500kS/s      Sample      Trig?







Pulse Number	Length of pulse (uS)
1	122
2	122
3	826
4	236
5	126
6	166
7	126
8	126
9	172
10	128
11	384
12	234
13	276
14	124
15	168
16	124
17	272
18	840
	4572

$4.572 \text{ mS} / 10.88 \text{ mS} = 42.02\% = \text{Measured Duty Cycle}$

# MS Series Encoder Data Structure

The MS Series encoder is designed to securely register button presses or switch closures over a wireless link for remote control applications. It will turn eight parallel input lines into a secure, encoded serial bit stream output.

The MS Series algorithm is designed to create a data stream with 5 High Data Bits at 9600bps.

## Logic State Description:

1 = HIGH  
0 = LOW



Total bits, including start and stop bits = 80

Total 1's = 40

Total 0's = 40

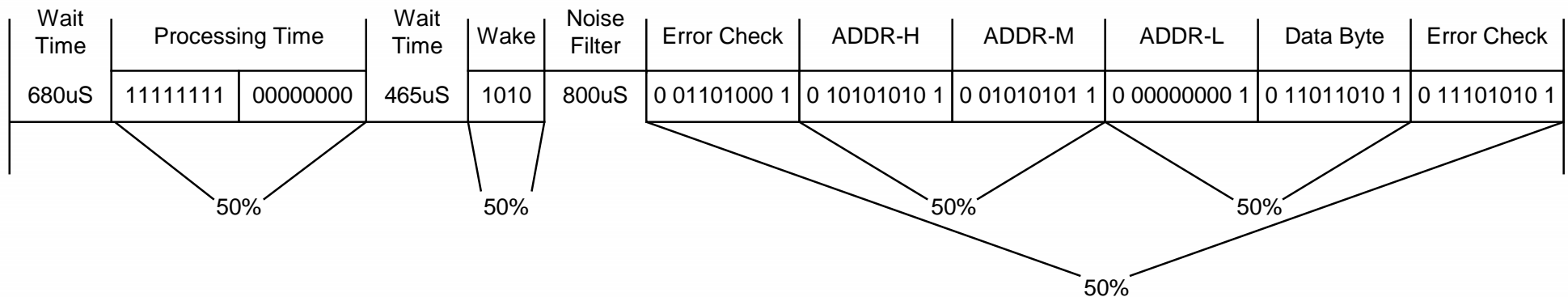
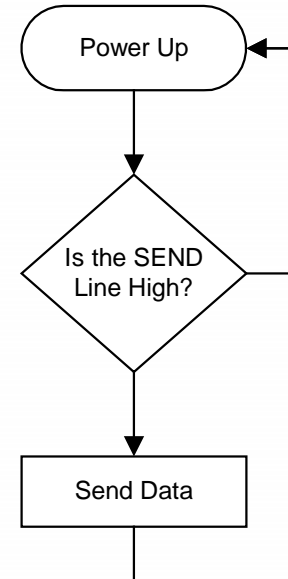
## Value for each bit per baud rate:

2400bps = 417uS or 1.18% of duty cycle

9600bps = 104uS or 1.01% of duty cycle

19200bps = 52uS or 0.85% of duty cycle

28800bps = 35uS or 0.74% of duty cycle



$$\text{Duty Cycle} = \frac{\text{Time High}}{\text{Total Time}} \rightarrow \frac{37 \text{ bits} + 800\text{uS}}{80 \text{ bits} + 680\text{uS} + 465\text{uS} + 800\text{uS}} \rightarrow \frac{(37 \times 104\text{uS}) + 800\text{uS}}{(80 \times 104\text{uS}) + 1,945\text{uS}} = \frac{4,648\text{uS}}{10,265\text{uS}} = 45.28\%$$