SAR TEST REPORT

Reference No.	:	WTS16S0551685-2E V6
FCC ID	:	UC7H60
Applicant	:	AUDIX CORPORATION
Address	:	9400 SW Barber Street, Wilsonville, Oregon 97070, United States
Manufacturer	:	Relacart Electronics Co.,Ltd.
Address	:	No. 10 Fuxing Road, Pingshi Industrial District, Enping City, Guangdong, China-529400
Product Name	:	Wireless microphone Handheld Transmitter
Model No	:	H60
Brand		AUDIX
Standards	:	FCC 47 CFR Part2(2.1093) ANSI/IEEE C95.1-2006 IEEE 1528-2013 & KDB 447498 D01 v06
Date of Receipt sample	:	Jun. 25, 2016
Date of Test	:	Jul. 01-Aug.16, 2016
Date of Issue	:	Aug. 25, 2016
Test Result	:	Pass

Remarks:
The results shown in this test report refer only to the sample(s) tested, this test report cannot be reproduced, except in full, without prior written permission of the company. The report would be invalid without specific stamp of test institute and the signatures of compiler and approver.

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1 Laboratory Introduction

Waltek Service Co., Ltd. is a professional third-party testing and certification organization with multi-year product testing and certification experience， Established strictly in accordance with ISO/IEC Guide 65 and ISO/IEC 17025，our company has got recognition from CNAS (China National Accreditation Service for Conformity Assessment) and International Laboratory Accreditation Cooperation (ILAC)。 At the same time, our company has been approved by some authoritative organizations， such as EMSD of Hongkong、UL、Intertek-ETL SEMKO、CSA、MET、TÜV Rheinland、TÜV SÜD、SGS、Nemko、FCC 、IC of Canada、CPSC、TMICO and California Energy Commission (CEC)。Since the set-up of our company, we sincerely help our customers to improve their products to achieve relative international standards. We are accepted by various clients in international market and well-known in the same industry.

There are several laboratories in our company which are equipped with advanced equipments for fully testing. It can provide testing and certification services for products exported around the world, also it can ensure that the products reach international standards in aspects of safety, electromagnetic compatibility, virulence, energy efficiency, reliability and so on. To enable our customers can get local services more directly and conveniently, and to realize our promise to provide more high quality services. Our company has set up product testing labs in South China and East China (Shenzhen, Dongguan, Foshan, Suzhou and Ningbo). We can provide our clients with accurate test and technical support services in good faith, and actively follow customer demand. These can fully demonstrate Waltek Services concept -- “One-stop Services”.

Our company has many experienced engineers and customer service representatives to meet our customer’s demand for a number of tests and provide superb technical guidance and modification service; At the same time we can provide global certification services by our global partners to help our customer’s products to successfully extend to the global market.

2 Contents

1 LABORATORY INTRODUCTION........2

2 CONTENTS........3

3 GENERAL INFORMATION........4

4 INTRODUCTION........5

5 SAR MEASUREMENT SETUP........6

6 EXPOSURE LIMIT........15

7 SYSTEM AND LIQUID VALIDATION........16

8 TYPE A MEASUREMENT UNCERTAINTY........22

9 TEST INSTRUMENT........25

10 OUTPUT POWER VERIFICATION........26

11 EXPOSURE CONDITIONS CONSIDERATION........27

12 SAR TEST RESULTS........29

13 SAR MEASUREMENT REFERENCES........31

14 CALIBRATION REPORTS-PROBE........39

15 SAR SYSTEM PHOTOS........60

16 SETUP PHOTOS........61

17 EUT PHOTOS........62

3 General Information

3.1 General Description of E.U.T.

Product Name:	Wireless microphone Handheld Transmitter
Model No.:	H60
Differences describe	N/A
Operation Frequency	522.100MHz-585.575MHz,207channels
The Lowest Oscillator	16MHz
Antenna installation	Internal permanently attached antenna

3.2 Details of E.U.T.

Operation Frequency	522.100MHz-585.575MHz
Max. RF output power	16.13dBm
Max.SAR:	0.05 W/Kg 1g Body SAR
	0.02 W/Kg 10g Extremity SAR
Technical Data:	DC 3V by 2*1.5V(size “AA”) batteries

4 INTRODUCTION

Introduction

This measurement report shows compliance of the EUT with ANSI/IEEE C95.1-2006 and FCC 47 CFR Part2 (2.1093)

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The test procedures, as described in IEEE 1528-2013 Standard for IEEE Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques(300MHz~6GHz) and Published RF Exposure KDB Procedures

SAR Definition

- SAR : Specific Absorption Rate
- The SAR characterize the absorption of energy by a quantity of tissue
- This is related to a increase of the temperature of these tissues during a time period.

$$\mathrm{DAS} = \frac{\sigma E^2}{\rho}$$

$$\mathrm{DAS} = \frac{\mathrm{d}}{\mathrm{d}t}\left(\frac{\mathrm{d}W}{\mathrm{d}m}\right) = \frac{\mathrm{d}}{\mathrm{d}t}\left(\frac{\mathrm{d}W}{\rho\,\mathrm{d}V}\right)$$

$$\mathrm{DAS} = c_{\mathrm{h}} \left.\frac{\mathrm{d}T}{\mathrm{d}t}\right|_{t=0}$$

SAR definition

$$SAR = \frac{\sigma E^2}{\rho}$$

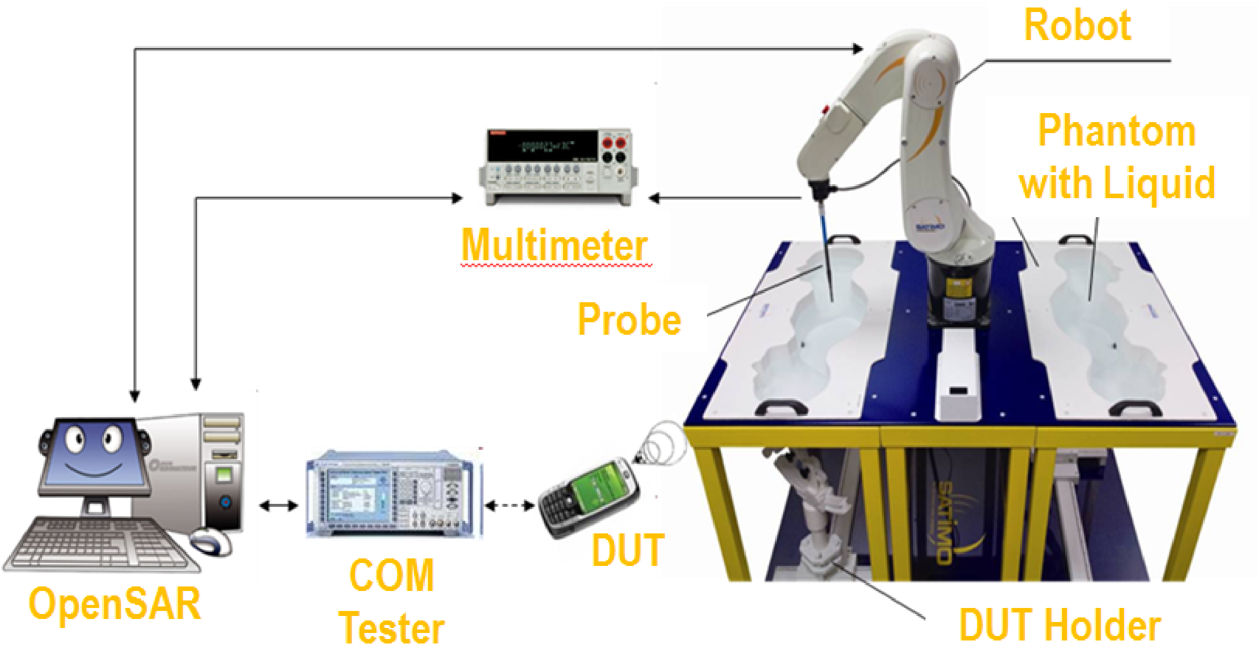
- SAR : Specific Absorption Rate
  - σ : Liquid conductivity
    - $\varepsilon_r = \varepsilon' - j\varepsilon''$ (complex permittivity of liquid)
    - $\sigma = \frac{\varepsilon'' \omega}{\varepsilon_0}$
  - ρ: Liquid density
    - ρ = 1000 g/L = 1000Kg/m³

where:

σ = conductivity of the tissue (S/m)
ρ = mass density of the tissue (kg/m3)
E = rms electric field strength (V/m)

5 SAR MEASUREMENT SETUP

SAR bench sub-systems



Scanning System (robot)

- It must be able to scan all the volume of the phantom to evaluate the tridimensional distribution of SAR.
- Must be able to set the probe orthogonal of the surface of the phantom (±30°).
- Detects stresses on the probe and stop itself if necessary to keep the integrity of the probe.

SAM Phantom (Specific Anthropomorphic Mannequin)

- The probe scanning of the E-Field is done in the 2 half of the normalized head.
- The normalized shape of the phantom corresponds to the dimensions of 90% of an adult head size.
- The materials for the phantom should not affect the radiation of the device under test (DUT)
  - Permittivity < 5
- The head is filled with tissue simulating liquid.
- The hand holding the DUT does not have to be modeled.

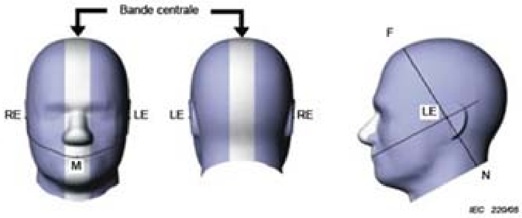
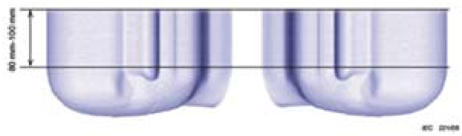
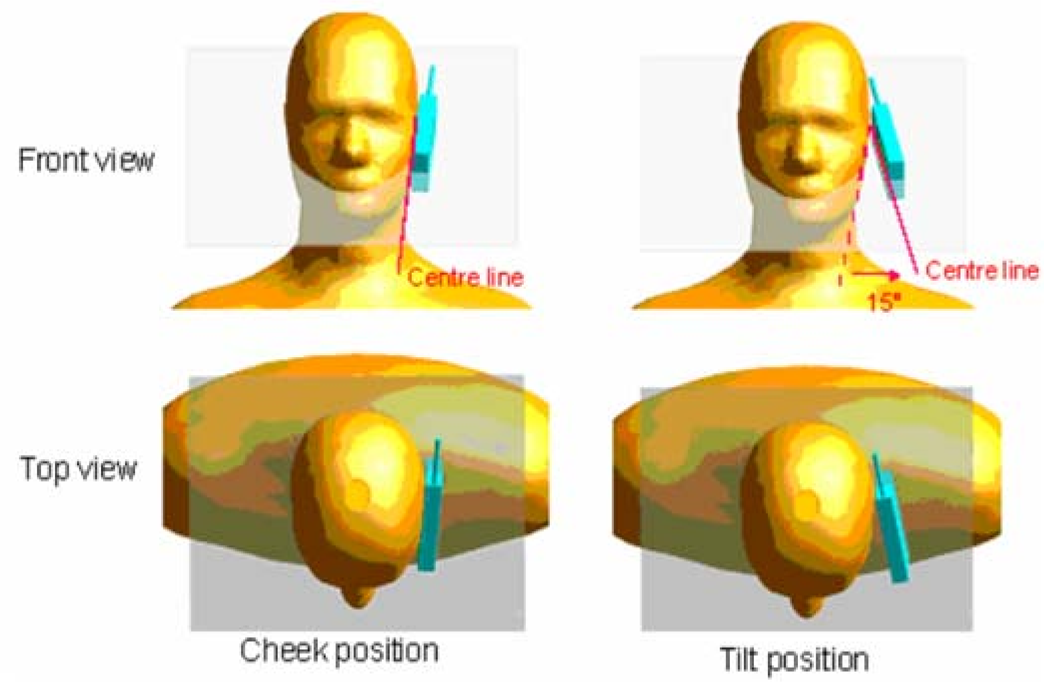


Illustration du fantôme donnant les points de référence des oreilles, RE et LE, le point de référence de la bouche, M, la ligne de référence N-F et la bande centrale



Bi-section sagittale du fantôme avec périmètre étendu (montrée sur le côté comme lors des essais de DAS de l'appareil)



The OPENSAR system for performing compliance tests consist of the following items:

1. A standard high precision 6-axis robot (KUKA) with controller and software.
2. KUKA Control Panel (KCP).
3. A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
4. The functions of the PC plug-in card are to perform the time critical task such as signal filtering, surveillance of the robot operation fast movement interrupts.
5. A computer operating Windows 7.
6. OPENSAR software.
7. Remote control with teaches pendant and additional circuitry for robot safety such as warning lamps, etc.
8. The SAM phantom enabling testing left-hand right-hand and body usage.
9. The Position device for handheld EUT.
10. Tissue simulating liquid mixed according to the given recipes (see Application Note).
11. System validation dipoles to validate the proper functioning of the system.

Data Evaluation

The OPENSAR software automatically executes the following procedure to calculate the field units from the microvolt readings at the probe connector. The parameters used in the valuation are stored in the configuration modules of the software:

Probe Parameters	· Sensitivity	$Norm_i$
	· Conversion factor	ConvFi
	· Diode compression point Dcpi	
Device Parameter	· Frequency	f
	· Crest factor	cf
Media Parametrs	· Conductivity	σ
	· Density	ρ

These parameters must be set correctly in the software. They can either be found in the component documents or be imported into the software from the configuration files issued for the OPENSAR components.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

Where V_i = *Compensated signal of channel i (i = x, y, z)*

U_i = *Input signal of channel i (i = x, y, z)*

cf = *Crest factor of exciting field (DASY parameter)*

dcp_i = *Diode compression point (DASY parameter)*

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes: $E_i = \sqrt{\dfrac{V_i}{Norm_i \cdot ConvF}}$

H-field probes: $H_i = \sqrt{Vi} \cdot \dfrac{a_{i10} + a_{i11} f + a_{i12} f^2}{f}$

Where V_i = *Compensated signal of channel i (i = x, y, z)*
$Norm_i$ = *Sensor sensitivity of channel i (i = x, y, z)*
μV/(V/m)2 for E0field Probes
ConvF = *Sensitivity enhancement in solution*
a_{ij} = *Sensor sensitivity factors for H-field probes*

f = *Carrier frequency (GHz)*
E_i = *Electric field strength of channel i in V/m*
H_i = *Magnetic field strength of channel i in A/m*

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

where *SAR* = *local specific absorption rate in mW/g*
E_{tot} = *total field strength in V/m*
σ = *conductivity in [mho/m] or [siemens/m]*
ρ = *equivalent tissue density in g/cm3*

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid.

The power flow density is calculated assuming the excitation field as a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770} \quad or \quad P_{pwe} = H_{tot}^2 \cdot 37.7$$

where P_{pwe} = *Equivalent power density of a plane wave in mW/cm2*
E_{tot} = *total electric field strength in V/m*
H_{tot} = *total magnetic field strength in A/m*

SAR Evaluation – Peak Spatial - Average

The procedure for assessing the peak spatial-average SAR value consists of the following steps

- **Power Reference Measurement**

  The reference and drift jobs are useful jobs for monitoring the power drift of the device under test in the batch process. Both jobs measure the field at a specified reference position, at a selectable distance from the phantom surface. The reference position can be either the selected section's grid reference point or a user point in this section. The reference job projects the selected point onto the phantom surface, orients the probe perpendicularly to the surface, and approaches the surface using the selected detection method.

- **Area Scan**

  The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a finer measurement around the hot spot. The sophisticated interpolation routines implemented in OPENSAR software can find the maximum locations even in relatively coarse grids. The scan area is defined by an editable grid. This grid is anchored at the grid reference point of the selected section in the phantom. When the area scan's property sheet is brought-up, grid was at to 15 mm by 15 mm and can be edited by a user.

- **Zoom Scan**

  Zoom scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The default zoom scan measures 5 x 5 x 7 points within a cube whose base faces are centered around the maximum found in a preceding area scan job within the same procedure. If the preceding Area Scan job indicates more then one maximum, the number of Zoom Scans has to be enlarged accordingly (The default number inserted is 1).

- **Power Drift measurement**

  The drift job measures the field at the same location as the most recent reference job within the same procedure, and with the same settings. The drift measurement gives the field difference in dB from the reading conducted within the last reference measurement. Several drift measurements are possible for one reference measurement. This allows a user to monitor the power drift of the device under test within a batch process. In the properties of the Drift job, the user can specify a limit for the drift and have OPENSAR software stop the measurements if this limit is exceeded.

SAR Evaluation – Peak SAR

The procedure for spatial peak SAR evaluation has been implemented according to the IEEE1529 standard. It can be conducted for 1 g and 10 g. The OPENSAR system allows evaluations that combine measured data and robot positions, such as:

- maximum search
- extrapolation
- boundary correction
- peak search for averaged SAR

During a maximum search, global and local maximum searches are automatically performed in 2-D after each Area Scan measurement with at least 6 measurement points. It is based on the evaluation of the local SAR gradient calculated by the Quadratic Shepard's method. The algorithm will find the global maximum and all local maxima within -2 dB of the global maxima for all SAR distributions.

Extrapolation

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. Several measurements at different distances are necessary for the extrapolation.
They are used in the Cube Scan to obtain SAR values between the lowest measurement points and the inner phantom surface. The routine uses the fourth order least square polynomial method for extrapolation. For a grid using 5x5x7 measurement points with 5mm resolution amounting to 343 measurement points, the uncertainty of the extrapolation routines is less than 1% for 1 g and 10 g cubes.

Definition of Reference Points

Ear Reference Point

Figure 6.2 shows the front, back and side views of the SAM Phantom. The point “M” is the reference point for the center of the mouth, “LE” is the left ear reference point (ERP), and “RE” is the right ERP. The ERPs are 15mm posterior to the entrance to the ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 6.1. The plane passing through the two ear canals and M is defined as the Reference Plane. The line N-F (Neck-Front) is perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting Line (see Figure 6.1). Line B-M is perpendicular to the N-F line. Both N-F and B-M lines are marked on the external phantom shell to facilitate handset positioning [5].

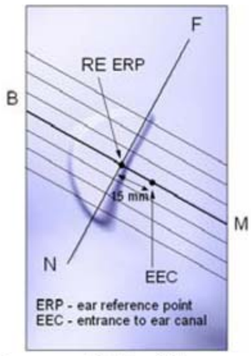


Figure 6.1 Close-up side view of ERP’s

Figure 6.2 Front, back and side view of SAM

Device Reference Points

Two imaginary lines on the device need to be established: the vertical centerline and the horizontal line. The test device is placed in a normal operating position with the “test device reference point” located along the “vertical centerline” on the front of the device aligned to the “ear reference point” (See Fig. 6.3). The “test device reference point” is than located at the same level as the center of the ear reference point. The test device is positioned so that the “vertical centerline” is bisecting the front surface of the device at it’s top and bottom edges, positioning the “ear reference point” on the outer surface of both the left and right head phantoms on the ear reference point [5].

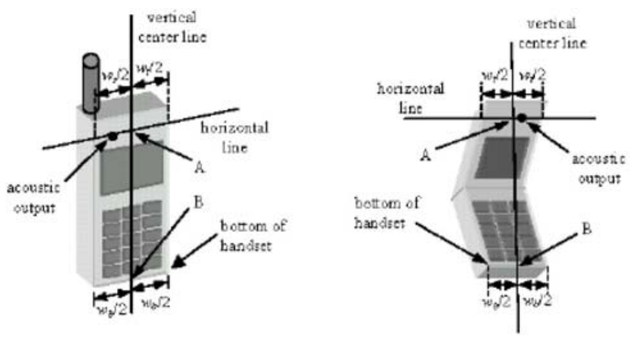


Figure 6.3 Handset Vertical Center & Horizontal Line Reference Points

Test Configuration – Positioning for Cheek / Touch

1. Position the device close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure below), such that the plane defined by the vertical center line and the horizontal line of the device is approximately parallel to the sagittal plane of the phantom

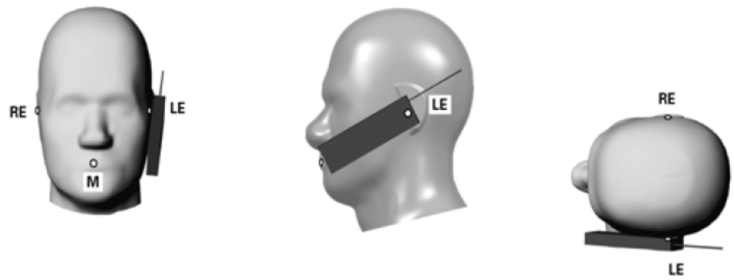


Figure 7.1 Front, Side and Top View of Cheek/Touch Position

2. Translate the device towards the phantom along the line passing through RE and LE until the device touches the ear.

3. While maintaining the device in this plane, rotate it around the LE-RE line until the vertical centerline is in the plane normal to MB-NF including the line MB (called the reference plane).
4. Rotate the device around the vertical centerline until the device (horizontal line) is symmetrical with respect to the line NF.

5. While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE and maintaining the device contact with the ear, rotate the device about the line NF until any point on the device is in contact with a phantom point below the ear (cheek). See Figure below.

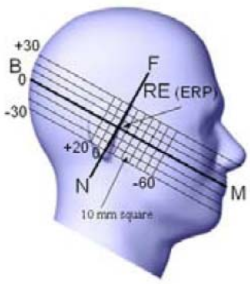


Figure 7.2 Side view w/ relevant markings

Test Configuration – Positioning for Ear / 15° Tilt

With the test device aligned in the Cheek/Touch Position":

1. While maintaining the orientation of the device, retracted the device parallel to the reference plane far enough to enable a rotation of the device by 15 degrees.

2. Rotate the device around the horizontal line by 15 degrees.

3. While maintaining the orientation of the device, move the device parallel to the reference plane until any part of the device touches the head. (In this position, point A is located on the line RE-LE). The tilted position is obtained when the contact is on the pinna. If the contact is at any location other than the pinna, the angle of the device shall be reduced. The tilted position is obtained when any part of the device is in contact with the ear as well as a second part of the device is in contact with the head (see Figure below).

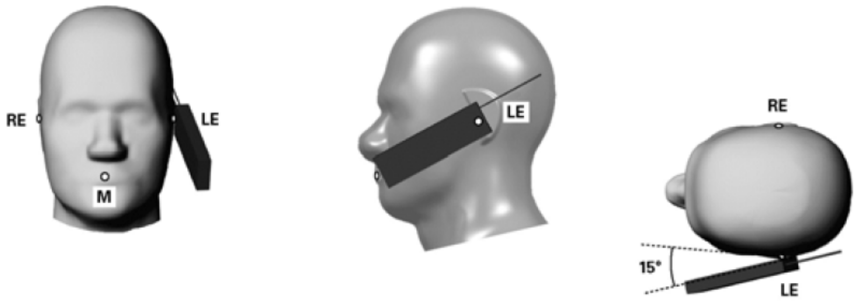
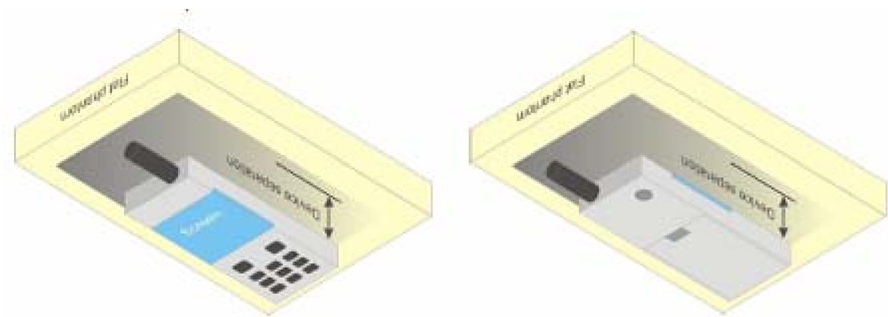


Figure 7.3 Front, Side and Top View of Ear/15˚ Tilt Position

Test Position – Body Configurations

Body Worn Position
(a) To position the device parallel to the phantom surface with either keypad up or down.
(b) To adjust the device parallel to the flat phantom.
(c) To adjust the distance between the device surface and the flat phantom to 0 cm.



6 EXPOSURE LIMIT

In order for users to be aware of the body-worn operating requirements for meeting RF exposure compliance, operating instructions and cautions statements are included in the user's manual.

Uncontrolled Environment

Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure. The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity.

Controlled Environment

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation). In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means.

Table 8.1 Human Exposure Limits

	UNCONTROLLED ENVIRONMENT General Population (W/kg) or (mW/g)	CONTROLLED ENVIROMENT Professional Population (W/kg) or (mW/g)
SPATIAL PEAK SAR[1] Brain	1.60	8.00
SPATIAL AVERAGE SAR[2] Whole Body	0.08	0.40
SPATIAL PEAK SAR[3] Hands, Feet, Ankles, Wrists	4.00	20.00

[1] The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.
[2] The Spatial Average value of the SAR averaged over the whole body.
[3] The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

7 SYSTEM AND LIQUID VALIDATION

System Validation

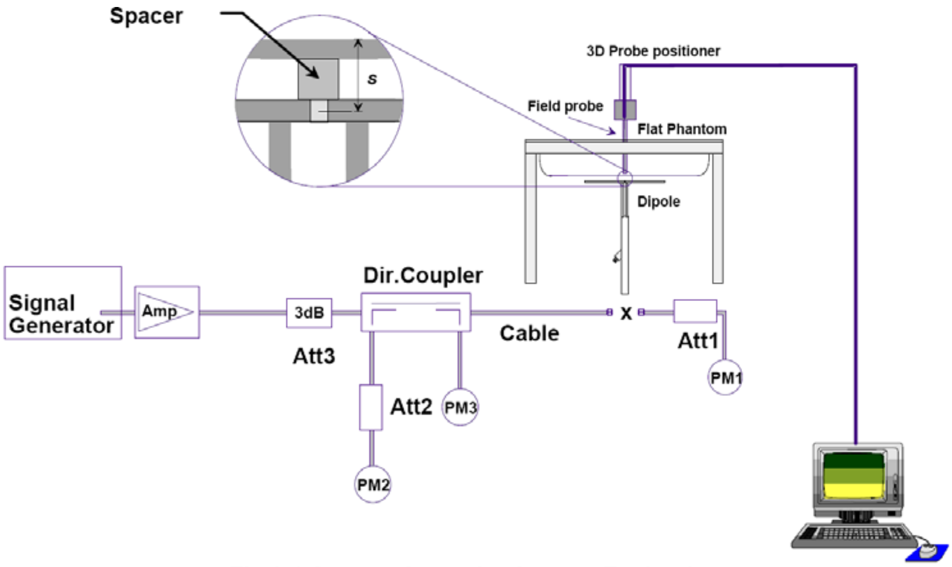


Fig 8.1 System Setup for System Evaluation

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:

1. Signal Generator
2. Amplifier
3. Directional Coupler
4. Power Meter
5. Calibrated Dipole

The output power on dipole port must be calibrated to 30 dBm (1000 mW) before dipole is connected.

Numerical reference SAR values (W/kg) for reference dipole and flat phantom

Frequency (MHz)	1 g SAR	10 g SAR	Local SAR at surface (above feed-point)	Local SAR at surface (y = 2 cm offset from feed-point)[a]
300	3.0	2.0	4.4	2.1
450	4.9	3.3	7.2	3.2
835	9.5	6.2	4.1	4.9
900	10.8	6.9	16.4	5.4
1450	29.0	16.0	50.2	6.5
1800	38.1	19.8	69.5	6.8
1900	39.7	20.5	72.1	6.6
2000	41.1	21.1	74.6	6.5
2450	52.4	24.0	104.2	7.7
3000	63.8	25.7	140.2	9.5

Table 1: system validation (1g)

Measurement Date	Frequency (MHz)	Liquid Type (head/body)	Target SAR1g (W/kg)	Measured SAR1g (W/kg)	Normalized SAR1g (W/kg)	Deviation (%)
Jul 1, 2016	450	body	5.00	0.515	5.15	1.03
Aug 16, 2016	450	body	5.00	0.514	5.14	1.03

Note: system check input power: 100mW

Table 2: system validation (10g)

Measurement Date	Frequency (MHz)	Liquid Type (head/body)	Target SAR10g (W/kg)	Measured SAR10g (W/kg)	Normalized SAR10g (W/kg)	Deviation (%)
Jul 1, 2016	450	body	3.22	0.313	3.13	-2.8
Aug 16, 2016	450	body	3.22	0.313	3.13	-2.8

Note: system check input power: 100mW

Liquid Validation

The dielectric parameters were checked prior to assessment using the HP85070C dielectric probe kit. The dielectric parameters measured are reported in each correspondent section.

KDB 865664 recommended Tissue Dielectric Parameters

The head and body tissue parameters given in this below table should be used to measure the SAR of transmitters operating in 100 MHz to 6 GHz frequency range. The tissue dielectric parameters of the tissue medium at the test frequency should be within the tolerance required in this document. The dielectric parameters should be linearly interpolated between the closest pair of target frequencies to determine the applicable dielectric parameters corresponding to the device test frequency.

The head tissue dielectric parameters recommended by IEEE Std 1528-2013 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in 1528 are derived from tissue dielectric parameters computed from the 4-Cole-Cole equations described above and extrapolated according to the head parameters specified in 1528.

Target Frequency	Head Tissue		Body Tissue	
MHz	εr	σ (S/m)	εr	σ (S/m)
150	52.3	0.76	61.9	0.80
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	0.98	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800-2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73
5800	35.3	5.27	48.2	6.00

Tissue Dielectric Parameters for Head and Body Phantoms

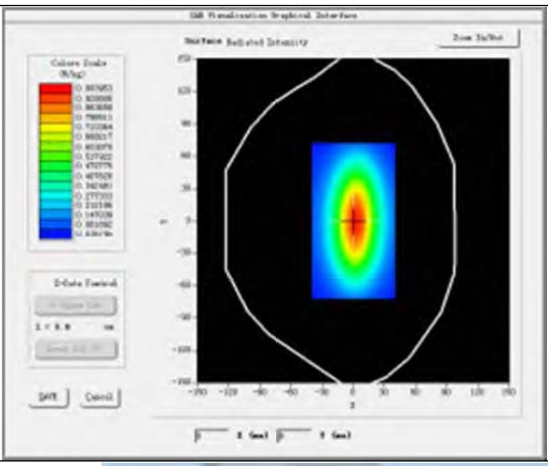
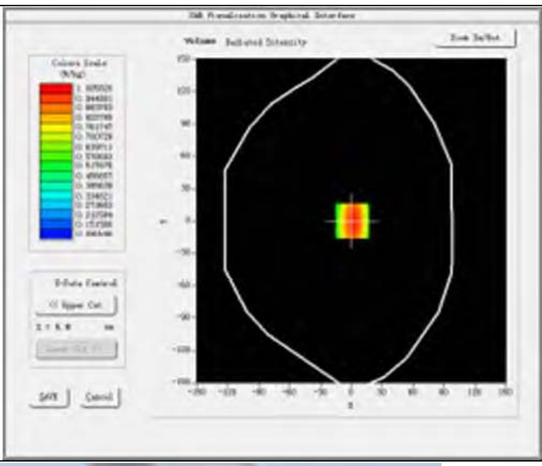
The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in P1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness Power drifts in a human head. Other head and body tissue parameters that have not been specified in P1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations described in Reference [12] and extrapolated according to the head parameters specified in P1528.

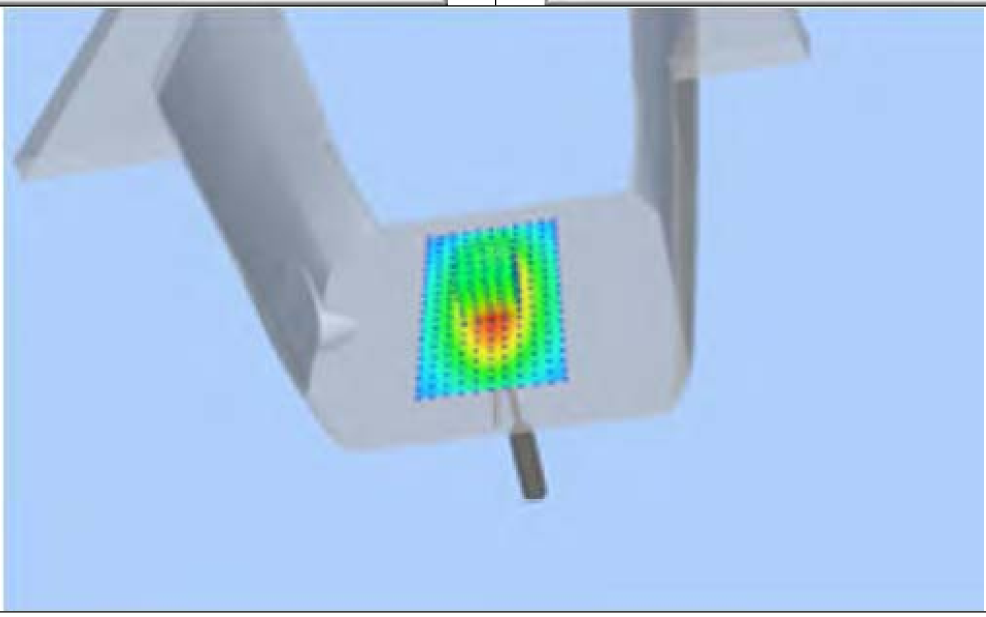
Table 3: Dielectric Performance of Body Tissue Simulating Liquid

Temperature: 21°C , Relative humidity: 57% , Measured Date: Jun 1, 2016				
Frequency(MHz)	**Measured Date**	**Description**	**Dielectric Parameters**	
			εr	**σ(s/m)**
450	Jul 1, 2016	Target Value ±5% window	56.7 53.87 — 59.53	0.94 0.89 — 0.99
		Measurement Value	54.7	0.98
450	Aug 16, 2016	Target Value ±5% window	56.7 53.87 — 59.53	0.94 0.89 — 0.99
		Measurement Value	55.3	0.98

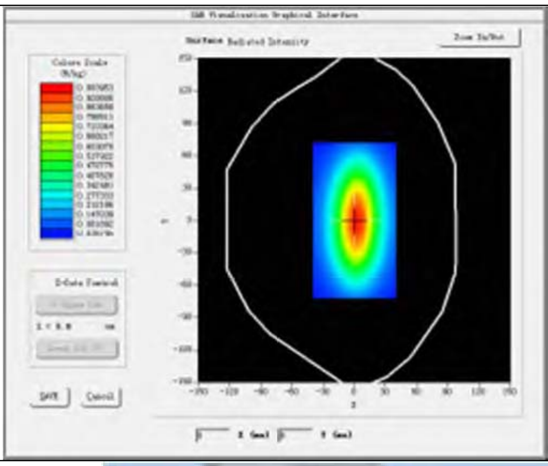
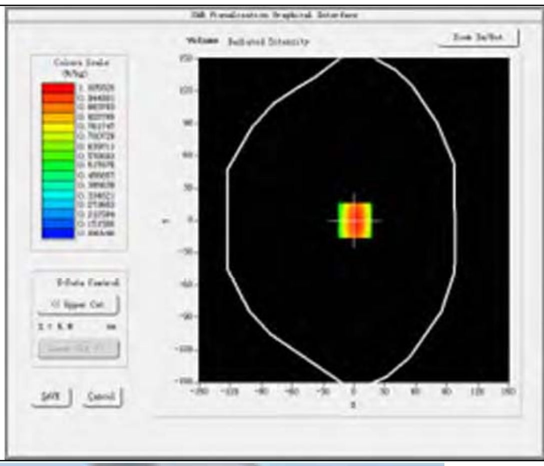
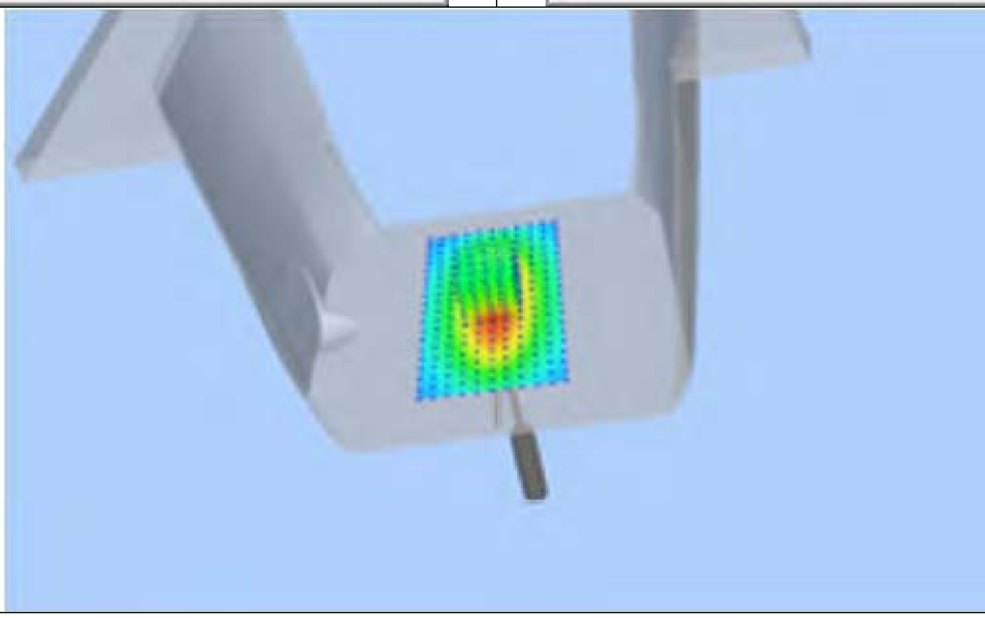
System Verification Plots

Product Description: Dipole
Model: SID450
Test Date: Jul 1, 2016

Medium(liquid type)	MSL_450
Frequency (MHz)	450.000000
Relative permittivity (real part)	54.7
Conductivity (S/m)	0.98
Input power	100mW
E-Field Probe	SN 45/15 EPGO281
Duty cycle	1:1
Conversion Factor	1.81
Sensor-surface	4mm
Area Scan	dx=8mm dy=8mm
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm
Variation (%)	-0.63
SAR 10g (W/Kg)	0.312573
SAR 1g (W/Kg)	0.514742
SURFACE SAR	**VOLUME SAR**
	



Product Description: Dipole
Model: SID450
Test Date: Aug 16, 2016

Medium(liquid type)	MSL_450
Frequency (MHz)	450.000000
Relative permittivity (real part)	55.3
Conductivity (S/m)	0.98
Input power	100mW
E-Field Probe	SN 45/15 EPGO281
Duty cycle	1:1
Conversion Factor	1.81
Sensor-surface	4mm
Area Scan	dx=8mm dy=8mm
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm
Variation (%)	-0.47
SAR 10g (W/Kg)	0.312701
SAR 1g (W/Kg)	0.514326
SURFACE SAR	**VOLUME SAR**
	
	

8 TYPE A MEASUREMENT UNCERTAINTY

The component of uncertainly may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainly by the statistical analysis of a series of observations is termed a Type An evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience and specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table below :

Uncertainty Distribution	Normal	Rectangle	Triangular	U Shape
Multi-plying Factor[(a)]	$1/k^{(b)}$	$1 / \sqrt{3}$	$1 / \sqrt{6}$	$1 / \sqrt{2}$

(a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity
(b) κ is the coverage factor

Standard Uncertainty for Assumed Distribution

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type -sum-by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %.

The COMOSAR Uncertainty Budget is show in below table:

UNCERTAINTY FOR SYSTEM PERFORMANCE CHECK

Uncertainty Component	Tol. (± %)	Prob. Dist.	Div.	ci (1 g)	ci (10 g)	1 g ui (± %)	10 g ui (± %)	vi
Measurement System								
Probe Calibration	5,8	N	1	1	1	5,8	5,8	∞
Axial Isotropy	3,5	R	√3	(1-cp)1/2	(1-cp)1/2	1,42887	1,42887	∞
Hemispherical Isotropy	5,9	R	√3	√Cp	√Cp	2,40866	2,40866	∞
Boundary Effect	1	R	√3	1	1	0,57735	0,57735	∞
Linearity	4,7	R	√3	1	1	2,71355	2,71355	∞
System Detection Limits	1	R	√3	1	1	0,57735	0,57735	∞
Readout Electronics	0,5	N	1	1	1	0,5	0,5	∞
Response Time	0	R	√3	1	1	0	0	∞
Integration Time	1,4	R	√3	1	1	0,80829	0,80829	∞
RF Ambient Conditions	3	R	√3	1	1	1,73205	1,73205	∞
Probe Positioner Mechanical Tolerance	1,4	R	√3	1	1	0,80829	0,80829	∞
Probe Positioning with respect to Phantom Shell	1,4	R	√3	1	1	0,80829	0,80829	∞
Extrapolation, interpolation and Integration Algorithms for Max. SAR Evaluation	2,3	R	√3	1	1	1,32791	1,32791	∞
Dipole								
Dipole Axis to Liquid Distance	2	N	√3	1	1	1,1547	1,1547	N-1
Input Power and SAR drift measurement	5	R	√3	1	1	2,88675	2,88675	∞
Phantom and Tissue Parameters								
Phantom Uncertainty (shape and thickness tolerances)	4	R	√3	1	1	2,3094	2,3094	∞
Liquid Conductivity - deviation from target values	5	R	√3	0,64	0,43	1,84752	1,2413	∞
Liquid Conductivity - measurement uncertainty	4	N	1	0,64	0,43	2,56	1,72	M
Liquid Permittivity - deviation from target values	5	R	√3	0,6	0,49	1,73205	1,41451	∞
Liquid Permittivity - measurement uncertainty	5	N	1	0,6	0,49	3	2,45	M
Combined Standard Uncertainty		RSS				9.6671	9.1646	
Expanded Uncertainty (95% CONFIDENCE INTERVAL)		k				19.3342	18.3292	

UNCERTAINTY EVALUATION FOR HANDSET SAR TEST

Uncertainty Component	Tol. (± %)	Prob. Dist.	Div.	c_i (1 g)	c_i (10 g)	1 g u_i (± %)	10 g u_i (± %)	v_i
Measurement System								
Probe Calibration	5,8	N	1	1	1	5,8	5,8	∞
Axial Isotropy	3,5	R	√3	$(1-c_p)^{1/2}$	$(1-c_p)^{1/2}$	1,43	1,43	∞
Hemispherical Isotropy	5,9	R	√3	$\sqrt{C_p}$	$\sqrt{C_p}$	2,41	2,41	∞
Boundary Effect	1	R	√3	1	1	0,58	0,58	∞
Linearity	4,7	R	√3	1	1	2,71	2,71	∞
System Detection Limits	1	R	√3	1	1	0,58	0,58	∞
Readout Electronics	0,5	N	1	1	1	0,50	0,50	∞
Response Time	0	R	√3	1	1	0,00	0,00	∞
Integration Time	1,4	R	√3	1	1	0,81	0,81	∞
RF Ambient Conditions	3	R	√3	1	1	1,73	1,73	∞
Probe Positioner Mechanical Tolerance	1,4	R	√3	1	1	0,81	0,81	∞
Probe Positioning with respect to Phantom Shell	1,4	R	√3	1	1	0,81	0,81	∞
Extrapolation, interpolation and Integration Algorithms for Max. SAR Evaluation	2,3	R	√3	1	1	1,33	1,33	∞
Test sample Related								
Test Sample Positioning	2,6	N	1	1	1	2,60	2,60	N-1
Device Holder Uncertainty	3	N	1	1	1	3,00	3,00	N-1
Output Power Variation - SAR drift measurement	5	R	√3	1	1	2,89	2,89	∞
Phantom and Tissue Parameters								
Phantom Uncertainty (shape and thickness tolerances)	4	R	√3	1	1	2,31	2,31	∞
Liquid Conductivity - deviation from target values	5	R	√3	0,64	0,43	1,85	1,24	∞
Liquid Conductivity - measurement uncertainty	4	N	1	0,64	0,43	2,56	1,72	M
Liquid Permittivity - deviation from target values	5	R	√3	0,6	0,49	1,73	1,41	∞
Liquid Permittivity - measurement uncertainty	5	N	1	0,6	0,49	3,00	2,45	M
Combined Standard Uncertainty		RSS				10.39	9.92	
Expanded Uncertainty (95% CONFIDENCE INTERVAL)		k				20.78	19.84	

9 TEST INSTRUMENT

Name of Equipment	Manufacturer	Type/Model	Serial Number	Calibration Date	Calibration Due
6 AXIS ROBOT	KUKA	KR6 R900 SIXX	502635	N/A	N/A
SATIMO Test Software	MVG	OPENSAR	OPENSAR V_4_02_27	N/A	N/A
PHANTOM TABLE	MVG	N/A	SAR_1215_01	N/A	N/A
SAM PHANTOM	MVG	SAM118	SN 11/15 SAM118	N/A	N/A
MultiMeter	Keithley	MiltiMeter 2000	4073942	2016-03-16	2017-03-15
Data Acquisition Electronics	MVG	DAE4	915	2016-03-16	2017-03-15
S-Parameter Network Analyzer	Agilent	8753E	JP38160684	2016-04-02	2017-04-01
Universal Radio Communication Tester	ROHDE&SCHW ARZ	CMU200	112461	2016-03-23	2017-03-22
E-Field Probe	MVG	SSE5	SN 45/15 EPGO281	2015-12-10	2016-12-09
DIPOLE 450	MVG	SID450	SN 30/14 DIP 0G450-330	2015-09-01	2016-08-30
Limesar Dielectric Probe	MVG	SCLMP	SN 11/15 OCPG 69	2016-03-16	2017-03-15
Power Amplifier	BONN	BLWA 0830 -160/100/40D	128740	2015-09-14	2016-09-14
Signal Generator	R&S	SMB100A	105942	2015-09-14	2016-09-14
Power Meter	R&S	NRP2	102031	2015-09-14	2016-09-14

10 OUTPUT POWER VERIFICATION

Test Condition:

1. Conducted Measurement
   EUT was set for low, mid, high channel with modulated mode and highest RF output power.
   The base station simulator was connected to the antenna terminal.
2. Conducted Emissions Measurement Uncertainty
   All test measurements carried out are traceable to national standards. The uncertainty of the measurement at a confidence level of approximately 95% (in the case where distributions are normal), with a coverage factor of 2, in the range 30MHz – 40GHz is ±1.5dB.
3. Environmental Conditions
   Temperature 23°C
   Relative Humidity 53%
   Atmospheric Pressure 1019mbar
4. Test Date : Jul 1, 2016
   Tested By : Damon Wang

Test Procedures:

According to KDB 447498 D01v06， when the frequency channels required for SAR testing are not specified in the published RF exposure KDB procedures, the following should be applied to determine the number of required test channel. The test channel should be evenly spread across the transmission frequency band of each wireless mode.

$$N_c = Round\left\{\left[100\left(f_{high} - f_{low}\right)/f_c\right]^{0.5} \times \left(f_c/100\right)^{0.2}\right\},$$

where

- N_c is the number of test channels, rounded to the nearest integer,
- f_{high} and f_{low} are the highest and lowest channel frequencies within the transmission band,
- f_c is the mid-band channel frequency,
- all frequencies are in MHz.

Test Result:

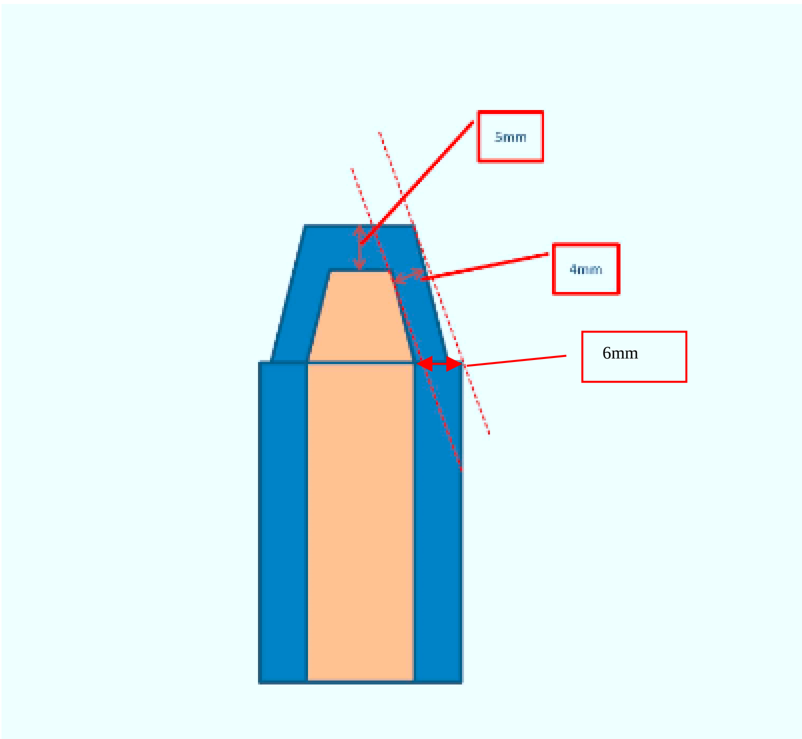
Mode	Frequency (MHz)	Output Power(dBm)	Tune up limited(dBm)
FM	522.100	15.81	16±1
	554.125	16.13	16±1
	585.575	15.71	16±1

Note: When the measured SAR for middle channel is less than 0.6W/Kg, and the transmission band is between 100MHz and 200MHz, other channels are not required.

11 EXPOSURE CONDITIONS CONSIDERATION

EUT antenna location:

A(antenna location and the distances from antenna to head edge)



B(the distances from antenna to edge)

1. Test positions & distance of Antenna-User

Antenna	Mode/Antenna/Position	Distance(mm)
FM	Body Mode(Inclined)	4
	Body Mode(Bottom)	5
FM	Head Mode(N/A)	255
FM	Extremity Mode(Inclined)	4
	Extremity Mode(Bottom)	5

2. SAR Test Exclusion Calculations for FM

2.1 Antennas < 50mm to surface

The 1-g and 10-g SAR test exclusion thresholds for 100 MHz to 6 GHz at *test separation distances* ≤ 50 mm are determined by:

[(*max. power of channel, including tune-up tolerance, mW*)/(*min. test separation distance, mm*)] · [$\sqrt{f_{(GHz)}}$] ≤ 3.0 for 1-g SAR and ≤ 7.5 for 10-g extremity SAR,[16] where

- $f_{(GHz)}$ is the RF channel transmit frequency in GHz
- Power and distance are rounded to the nearest mW and mm before calculation[17]
- The result is rounded to one decimal place for comparison

The test exclusions are applicable only when the minimum *test separation distance* is ≤ 50 mm and for transmission frequencies between 100 MHz and 6 GHz. When the minimum *test separation distance* is < 5 mm, a distance of 5 mm is applied to determine SAR test exclusion.

Antenna	Frequency (MHz)	Output power		Separation Distance(mm)		
		dBm	mW(Average)	Body Mode	Head Mode	Extremity Mode
FM	554.125	17	50.12	Inclined (4 mm)	NA	Inclined (4 mm)
FM	554.125	17	50.12	Bottom (5 mm)	NA	Bottom (5 mm)

Calculated Threshold Value (continued)

Antenna	Frequency (MHz)	Calculated Threshold Value		
		Body Mode	Head Mode	Extremity Mode
FM	554.125	7.46	NA	7.46

2.2 Antennas > 50mm to surface

Antenna	Frequency (MHz)	Output power		Separation Distance(mm)	Calculated Threshold Value(mw) /exempt power
		dBm	mW(Average)	Head Mode	Head Mode
FM	554.125	17	50.12	255	811

Note: 1>. According to section4.3.1.b with KDB 447498 D01 v06, if the calculated Power threshold is less than the output power then SAR testing is required.

2>. Per FCC KDB616217, the surface of the microphone should be tested for SAR compliance with the microphone touching the phantom

12 SAR TEST RESULTS

Test Condition:

1. SAR Measurement
   The distance between the EUT and the antenna of the emulator is more than 50 cm and the output power radiated from the emulator antenna is at least 30 dB less than the output power of EUT.

2	Environmental Conditions	Temperature	23°C
		Relative Humidity	57%
		Atmospheric Pressure	1019mbar

3 Test Date : Jul 1, 2016 – Aug 16,2016
Tested By : Damon Wang

Test Procedures:

1. Establish communication link between EUT and base station emulation by air link.
2. Consider the SAR test reduction per FCC KDB guide line. For FM, set EUT into highest output power channel with test mode which has the maximum source-based time-averaged burst power listed in power table.
3. Place the EUT in the selected test position.
4. Perform SAR testing at highest output power channel under the selected test mode. If the measured 1-g SAR is ≤ 0.8 W/kg, then testing for the other channel will not be performed.
5. When SAR is<0.8W/kg, no repeated SAR measurement is required

SAR measurement system will proceed the following basic steps:

1. Initial power reference measurement
2. Area Scan
3. Zoom Scan
4. Power drift measurement

SAR Summary Test Result:

Table 4: Body SAR Values of FM

Test Date: Jul. 01- Aug. 16, 2016 Test separation distance: 0mm

Test Positions	Channel		Power(dBm)		SAR 1g(W/Kg), Limit(1.6W/kg)		Plot No.
	CH.	MHz	Maximum Turn-up Power(dBm)	Measured output power(dBm)	Measured SAR 1g(W/kg)	Scaled SAR 1g(W/kg)	
inclined	Low	522.100	17	15.81	0.032	0.04	**1**
	Mid	554.125	17	16.13	0.038	0.05	**2**
	High	585.575	17	15.71	0.037	0.05	**3**
bottom	Low	522.100	17	15.81	0.037	0.05	**4**
	Mid	554.125	17	16.13	0.033	0.04	**5**
	High	585.575	17	15.71	0.015	0.02	**6**

Table 5: Extremity SAR Values of FM

Test Date: Jul. 01 -Aug. 16, 2016 Test separation distance: 0mm

Test Positions	Channel		Power(dBm)		SAR 10g(W/Kg), Limit(4.0W/kg)		Plot No.
	CH.	MHz	Maximum Turn-up Power(dBm)	Measured output power(dBm)	Measured SAR 10g(W/kg)	Scaled SAR 10g(W/kg)	
inclined	Low	522.100	17	15.81	0.015	0.02	**1**
	Mid	554.125	17	16.13	0.018	0.02	**2**
	High	585.575	17	15.71	0.018	0.02	**3**
bottom	Low	522.100	17	15.81	0.019	0.02	**4**
	Mid	554.125	17	16.13	0.015	0.02	**5**
	High	585.575	17	15.71	0.006	0.01	**6**

Note: Because this is a handheld microphone, the extremity SAR for hands is required.

Measurement variability consideration

According to KDB 865664 D01v01r04 section 2.8.1, repeated measurements are required following the procedures as below:

1. Repeated measurement is not required when the original highest measured SAR is < 0.80W/kg; steps 2) through 4) do not apply.
2. When the original highest measured SAR is ≥ 0.80 W/kg, repeat that measurement once.
3. Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 1.45 W/kg (~ 10% from the 1-g SAR limit).
4. Perform a third repeated measurement only if the original, first or second repeated measurement is ≥ 1.5 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20.

No repeated SAR.

13 SAR MEASUREMENT REFERENCES

References

1. FCC 47 CFR Part 2 “Frequency Allocations and Radio Treaty Matters; General Rules and Regulations”
2. IEEE Std. C95.1-2005, “IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3kHz to 300GHz”, 2005
3. IEEE Std. 1528-2013, “IEEE Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques”, June 2013
4. IEC 62209-2, “Human exposure to radio frequency fields from hand-held and body-mounted wireless communication devices—Human models, instrumentation, and procedures – Part 2: Procedure to determine the specific absorption rate(SAR) for wireless communication devices used in close proximity to the human body(frequency range of 30MHz to 6GHz)”, April 2010
5. FCC KDB 447498 D01 v06, “Mobile and Portable Device RF Exposure Procedures and Equipment Authorization Policies”, Oct 23th, 2015
6. FCC KDB865664 D01 v01r04, “SAR Measurement Requirements 100MHz to 6GHz”, Aug 7th, 2015
7. FCC KDB865664 D02 v01r02, “RF Exposure Compliance Reporting and Documentation Considerations ”, Oct 23$^{th"}$, 2015
8. FCC KDB648474 D04 v01r03, “SAR Evaluation Considerations for Wireless Handsets”, Oct 23$^{th"}$, 2015