



# Variant FCC SAR Test Report

**APPLICANT** : ZTE CORPORATION  
**EQUIPMENT** : CDMA2000 Digital Mobile Phone  
**BRAND NAME** : ZTE  
**MODEL NAME** : X501  
**FCC ID** : Q78-X501  
**STANDARD** : FCC 47 CFR Part 2 (2.1093)  
ANSI/IEEE C95.1-1992  
IEEE 1528-2003  
FCC OET Bulletin 65 Supplement C (Edition 01-01)

This is a variant report which is only valid together with the original test report. The product was received on Jun. 25, 2012 and completely tested on Jul. 18, 2012. We, SPORTON INTERNATIONAL (KUNSHAN) INC., would like to declare that the tested sample has been evaluated in accordance with the procedures and shown the compliance with the applicable technical standards.

The test results in this report apply exclusively to the tested model / sample. Without written approval of SPORTON INTERNATIONAL (KUNSHAN) INC., the test report shall not be reproduced except in full.

Reviewed by:

Jones Tsai / Manager



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## Table of Contents

<b>1. Statement of Compliance</b>	<b>4</b>
<b>2. Administration Data</b>	<b>5</b>
2.1 Testing Laboratory	5
2.2 Applicant	5
2.3 Manufacturer	5
2.4 Application Details	5
<b>3. General Information</b>	<b>6</b>
3.1 Description of Equipment Under Test (EUT)	6
3.2 Product Photos	7
3.3 Applied Standard	7
3.4 Device Category and SAR Limits	7
3.5 Test Conditions	7
<b>4. Specific Absorption Rate (SAR)</b>	<b>8</b>
4.1 Introduction	8
4.2 SAR Definition	8
<b>5. SAR Measurement System</b>	<b>9</b>
5.1 E-Field Probe	10
5.2 Data Acquisition Electronics (DAE)	11
5.3 Robot	11
5.4 Measurement Server	11
5.5 Phantom	12
5.6 Device Holder	12
5.7 Data Storage and Evaluation	13
5.8 Test Equipment List	15
<b>6. Tissue Simulating Liquids</b>	<b>16</b>
<b>7. SAR Measurement Evaluation</b>	<b>18</b>
7.1 Purpose of System Performance check	18
7.2 System Setup	18
7.3 Validation Results	19
<b>8. EUT Testing Position</b>	<b>20</b>
8.1 Define two imaginary lines on the handset	20
8.2 Cheek Position	21
8.3 Body Worn Position	21
<b>9. Measurement Procedures</b>	<b>22</b>
9.1 Spatial Peak SAR Evaluation	22
9.2 Area & Zoom Scan Procedures	22
9.3 Volume Scan Procedures	23
9.4 SAR Averaged Methods	23
9.5 Power Drift Monitoring	23
<b>10. SAR Test Configurations</b>	<b>24</b>
10.1 Exposure Positions Consideration	24
10.2 Conducted RF Output Power (Unit: dBm)	26
<b>11. SAR Test Results</b>	<b>27</b>
11.1 Test Records for Head SAR Test	27
11.2 Test Records for Hotspot SAR Test	27
11.3 Test Records for Body-worn SAR Test	28
11.4 Simultaneous Multi-band Transmission Analysis	29
<b>12. Uncertainty Assessment</b>	<b>30</b>
<b>13. References</b>	<b>32</b>
<b>Appendix A. Plots of System Performance Check</b>	
<b>Appendix B. Plots of SAR Measurement</b>	
<b>Appendix C. DASYS Calibration Certificate</b>	
<b>Appendix D. Product Photos</b>	
<b>Appendix E. Test Setup Photos</b>	
<b>Appendix F. Product Equality Declaration</b>	





### 1. Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) found during testing for **ZTE CORPORATION**;  
DUT: **CDMA2000 Digital Mobile Phone**; Brand Name: **ZTE**; Model Name: **X501** are as follows.

<Standalone SAR>

Band	Position	SAR <sub>1g</sub> (W/kg)
CDMA2000 BC0	Head	0.757
CDMA2000 BC15	Head	1.070
CDMA2000 BC1	Head	0.814
WLAN 2.4G	Head	0.388
CDMA2000 BC0	Hotspot (1 cm)	1.050
CDMA2000 BC15	Hotspot (1 cm)	1.190
CDMA2000 BC1	Hotspot (1 cm)	0.968
CDMA2000 BC0	Body-worn (1 cm)	1.050
CDMA2000 BC15	Body-worn (1 cm)	1.210
CDMA2000 BC1	Body-worn (1 cm)	1.010
WLAN 2.4G	Body-worn (1 cm)	0.370

This device is in compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (1.6 W/kg) specified in FCC 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1-1992, and had been tested in accordance with the measurement methods and procedures specified in IEEE 1528-2003 and FCC OET Bulletin 65 Supplement C (Edition 01-01).



## 2. Administration Data

### 2.1 Testing Laboratory

Test Site	SPORTON INTERNATIONAL (KUNSHAN) INC.
Test Site Location	No. 3-2, PingXiang Road, Kunshan, Jiangsu Province, P.R.C. TEL: +86-0512-5790-0158 FAX: +86-0512-5790-0958

### 2.2 Applicant

Company Name	ZTE CORPORATION
Address	ZTE Plaza, Keji Road South, Hi-Tech, Industrial Park, Nanshan District, Shenzhen, Guangdong, P.R.China

### 2.3 Manufacturer

Company Name	ZTE CORPORATION
Address	ZTE Plaza, Keji Road South, Hi-Tech, Industrial Park, Nanshan District, Shenzhen, Guangdong, P.R.China

### 2.4 Application Details

Date of Receipt of Application	Jun. 25, 2012
Date of Start during the Test	Jul. 06, 2012
Date of End during the Test	Jul. 18, 2012



### 3. General Information

#### 3.1 Description of Equipment Under Test (EUT)

Product Feature & Specification	
<b>EUT</b>	CDMA2000 Digital Mobile Phone
<b>Brand Name</b>	ZTE
<b>Model Name</b>	X501
<b>FCC ID</b>	Q78-X501
<b>IMEI Code</b>	A0000032BFC281
<b>Tx Frequency</b>	CDMA2000 BC0 : 824.70 MHz ~ 848.31 MHz CDMA2000 BC15 : 1711.25 ~ 1753.75 MHz CDMA2000 BC1 : 1851.25 MHz ~ 1908.75 MHz WLAN2.4G: 2412 MHz ~ 2462 MHz Bluetooth : 2402 MHz ~ 2480 MHz
<b>Rx Frequency</b>	CDMA2000 BC0 : 869.70 MHz ~ 893.31 MHz CDMA2000 BC15 : 2111.25 ~ 2153.75 MHz CDMA2000 BC1 : 1931.25 MHz ~ 1988.75 MHz WLAN2.4G: 2412 MHz ~ 2462 MHz Bluetooth : 2402 MHz ~ 2480 MHz
<b>Maximum Average Output Power to Antenna</b>	CDMA2000 BC0 : 23.71 dBm CDMA2000 BC15 : 23.21 dBm CDMA2000 BC1 : 24.18 dBm 802.11b : 13.96 dBm 802.11g : 14.11 dBm Bluetooth: 8.72 dBm
<b>Antenna Type</b>	WWAN: Fixed Internal Antenna WLAN: PIFA Antenna Bluetooth: PIFA Antenna
<b>HW Version</b>	QB7627-05AMB_E
<b>SW Version</b>	X501_CKT_4.03
<b>Type of Modulation</b>	CDMA2000 : QPSK 802.11b : DSSS (BPSK / QPSK / CCK) 802.11g : OFDM (BPSK / QPSK / 16QAM / 64QAM) Bluetooth (1Mbps) : GFSK Bluetooth EDR (2Mbps) : $\pi/4$ -DQPSK Bluetooth EDR (3Mbps) : 8-DPSK
<b>EUT Stage</b>	Identical Prototype
<b>Remark:</b> The above EUT's information was declared by manufacturer. Please refer to the specifications or user's manual for more detailed description.	



**3.2 Product Photos**

Please refer to Appendix D.

**3.3 Applied Standard**

The Specific Absorption Rate (SAR) testing specification, method and procedure for this device is in accordance with the following standards:

- FCC 47 CFR Part 2 (2.1093)
- ANSI/IEEE C95.1-1992
- IEEE 1528-2003
- FCC OET Bulletin 65 Supplement C (Edition 01-01)
- FCC KDB 447498 D01 v04
- FCC KDB 648474 D01 v01r05
- FCC KDB 941225 D01 v02
- FCC KDB 941225 D06 v01
- FCC KDB 248227 D01 v01r02

**3.4 Device Category and SAR Limits**

This device belongs to portable device category because its radiating structure is allowed to be used within 20 centimeters of the body of the user. Limit for General Population/Uncontrolled exposure should be applied for this device, it is 1.6 W/kg as averaged over any 1 gram of tissue.

**3.5 Test Conditions**

**3.5.1 Ambient Condition**

<b>Ambient Temperature</b>	20 to 24 °C
<b>Humidity</b>	< 60 %

**3.5.2 Test Configuration**

The device was controlled by using a base station emulator. Communication between the device and the emulator was established by air link. The distance between the EUT and the antenna of the emulator is larger than 50 cm and the output power radiated from the emulator antenna is at least 30 dB smaller than the output power of EUT. The EUT was set from the emulator to radiate maximum output power during all tests.

For WLAN SAR testing, WLAN engineering testing software installed on the EUT can provide continuous transmitting RF signal.

## **4. Specific Absorption Rate (SAR)**

### **4.1 Introduction**

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

### **4.2 SAR Definition**

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density ( $\rho$ ). The equation description is as below:

$$\text{SAR} = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho dv} \right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$\text{SAR} = c \left( \frac{\delta T}{\delta t} \right)$$

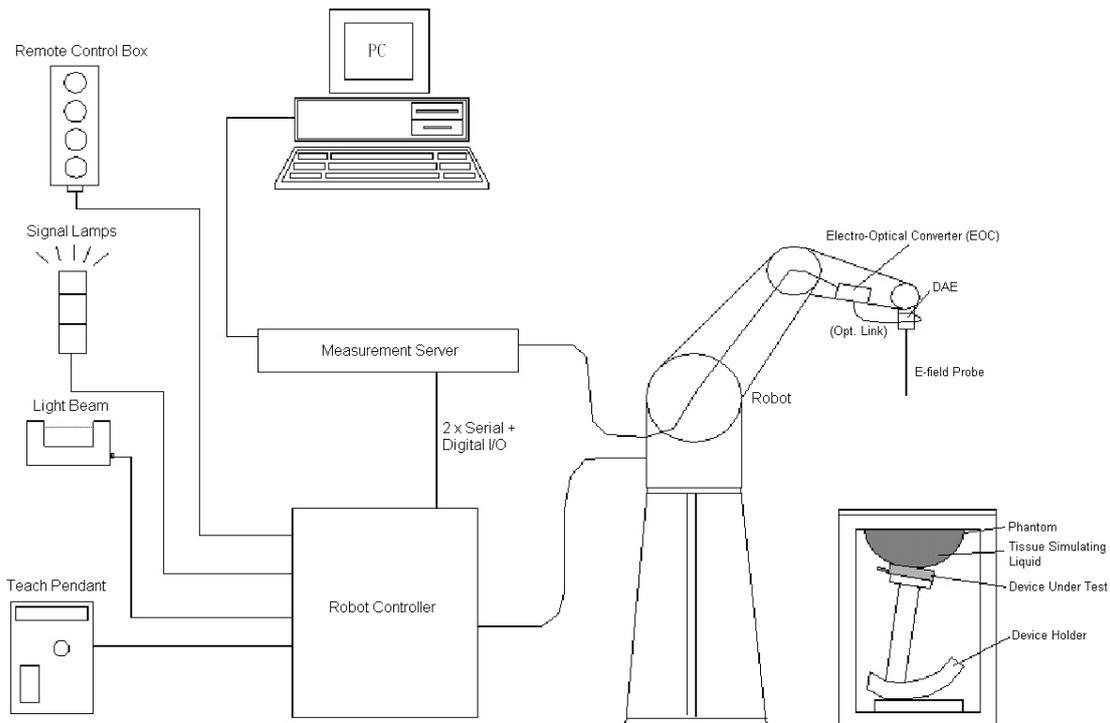
Where: C is the specific heat capacity,  $\delta T$  is the temperature rise and  $\delta t$  is the exposure duration, or related to the electrical field in the tissue by

$$\text{SAR} = \frac{\sigma |E|^2}{\rho}$$

Where:  $\sigma$  is the conductivity of the tissue,  $\rho$  is the mass density of the tissue and E is the RMS electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

## 5. SAR Measurement System



**Fig 5.1 SPEAG DASY System Configurations**

The DASY system for performance compliance tests is illustrated above graphically. This system consists of the following items:

- A standard high precision 6-axis robot with controller, a teach pendant and software
- A data acquisition electronic (DAE) attached to the robot arm extension
- A dosimetric probe equipped with an optical surface detector system
- The electro-optical converter (EOC) performs the conversion between optical and electrical signals
- A measurement server performs the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the accuracy of the probe positioning
- A computer operating Windows XP
- DASY software
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom
- A device holder
- Tissue simulating liquid
- Dipole for evaluating the proper functioning of the system

Component details are described in in the following sub-sections.

**5.1 E-Field Probe**

The SAR measurement is conducted with the dosimetric probe (manufactured by SPEAG). The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. This probe has a built in optical surface detection system to prevent from collision with phantom.

**5.1.1 E-Field Probe Specification**

**<ES3DV3>**

<b>Construction</b>	Symmetrical design with triangular core Interleaved sensors Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)	 <p><b>Fig 5.2 Photo of ES3DV3</b></p>
<b>Frequency</b>	10 MHz to 4 GHz; Linearity: $\pm 0.2$ dB	
<b>Directivity</b>	$\pm 0.2$ dB in HSL (rotation around probe axis) $\pm 0.3$ dB in tissue material (rotation normal to probe axis)	
<b>Dynamic Range</b>	5 $\mu$ W/g to 100 mW/g; Linearity: $\pm 0.2$ dB	
<b>Dimensions</b>	Overall length: 337 mm (Tip: 20 mm) Tip diameter: 3.9 mm (Body: 12 mm) Distance from probe tip to dipole centers: 2.0 mm	

**<EX3DV4>**

<b>Construction</b>	Symmetrical design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)	 <p><b>Fig 5.3 Photo of EX3DV4</b></p>
<b>Frequency</b>	10 MHz to 6 GHz; Linearity: $\pm 0.2$ dB	
<b>Directivity</b>	$\pm 0.3$ dB in HSL (rotation around probe axis) $\pm 0.5$ dB in tissue material (rotation normal to probe axis)	
<b>Dynamic Range</b>	10 $\mu$ W/g to 100 mW/g; Linearity: $\pm 0.2$ dB (noise: typically $< 1 \mu$ W/g)	
<b>Dimensions</b>	Overall length: 330 mm (Tip: 20 mm) Tip diameter: 2.5 mm (Body: 12 mm) Typical distance from probe tip to dipole centers: 1 mm	

**5.1.2 E-Field Probe Calibration**

Each probe needs to be calibrated according to a dosimetric assessment procedure with accuracy better than  $\pm 10\%$ . The spherical isotropy shall be evaluated and within  $\pm 0.25$  dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested. The calibration data can be referred to appendix C of this report.

### 5.2 Data Acquisition Electronics (DAE)

The data acquisition electronics (DAE) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The input impedance of the DAE is 200 MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



Fig 5.4 Photo of DAE

### 5.3 Robot

The SPEAG DASY system uses the high precision robots (DASY5: TX90XL) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version (DASY5: CS8c) from Stäubli is used. The Stäubli robot series have many features that are important for our application:

- High precision (repeatability  $\pm 0.035$  mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)



Fig 5.5 Photo of DASY5

### 5.4 Measurement Server

The measurement server is based on a PC/104 CPU board with CPU (DASY5: 400 MHz, Intel Celeron), chipdisk (DASY5: 128 MB), RAM (DASY5: 128 MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all the real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operations.



Fig 5.6 Photo of Server for DASY5

### 5.5 Phantom

<SAM Twin Phantom>

<b>Shell Thickness</b>	2 ± 0.2 mm; Center ear point: 6 ± 0.2 mm	
<b>Filling Volume</b>	Approx. 25 liters	
<b>Dimensions</b>	Length: 1000 mm; Width: 500 mm; Height: adjustable feet	
<b>Measurement Areas</b>	Left Hand, Right Hand, Flat Phantom	

Fig 5.7 Photo of SAM Phantom

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

### 5.6 Device Holder

<Device Holder for SAM Twin Phantom>

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5 mm distance, a positioning uncertainty of ± 0.5 mm would produce a SAR uncertainty of ± 20 %. Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR). Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss POM material having the following dielectric parameters: relative permittivity  $\epsilon = 3$  and loss tangent  $\delta = 0.02$ . The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



Fig 5.8 Device Holder

## **5.7 Data Storage and Evaluation**

### **5.7.1 Data Storage**

The DASY software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files. The post-processing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type (e.g., [V/m], [A/m], [mW/g]). Some of these units are not available in certain situations or give meaningless results, e.g., a SAR-output in a non-lose media, will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

### **5.7.2 Data Evaluation**

The DASY post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software :

<b>Probe parameters :</b>	- Sensitivity	Norm <sub>i</sub> , a <sub>i0</sub> , a <sub>i1</sub> , a <sub>i2</sub>
	- Conversion factor	ConvF <sub>i</sub>
	- Diode compression point	dcp <sub>i</sub>
<b>Device parameters :</b>	- Frequency	f
	- Crest factor	cf
<b>Media parameters :</b>	- Conductivity	$\sigma$
	- Density	$\rho$

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power.

The formula for each channel can be given as :

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with  $V_i$  = compensated signal of channel  $i$ , ( $i = x, y, z$ )  
 $U_i$  = input signal of channel  $i$ , ( $i = x, y, z$ )  
 $cf$  = crest factor of exciting field (DASY parameter)  
 $dcp_i$  = diode compression point (DASY parameter)

From the compensated input signals, the primary field data for each channel can be evaluated :

$$\text{E-field Probes : } E_i = \sqrt{\frac{V_i}{\text{Norm}_i \cdot \text{ConvF}}}$$

$$\text{H-field Probes : } H_i = \sqrt{V_i \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}}$$

with  $V_i$  = compensated signal of channel  $i$ , ( $i = x, y, z$ )  
 $\text{Norm}_i$  = sensor sensitivity of channel  $i$ , ( $i = x, y, z$ ),  $\mu\text{V}/(\text{V/m})^2$  for E-field Probes  
 $\text{ConvF}$  = sensitivity enhancement in solution  
 $a_{ij}$  = sensor sensitivity factors for H-field probes  
 $f$  = carrier frequency [GHz]  
 $E_i$  = electric field strength of channel  $i$  in V/m  
 $H_i$  = magnetic field strength of channel  $i$  in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude) :

$$E_{\text{tot}} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$\text{SAR} = E_{\text{tot}}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with SAR = local specific absorption rate in mW/g  
 $E_{\text{tot}}$  = total field strength in V/m  
 $\sigma$  = conductivity in [mho/m] or [Siemens/m]  
 $\rho$  = equivalent tissue density in  $\text{g}/\text{cm}^3$

Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.



**5.8 Test Equipment List**

Manufacturer	Name of Equipment	Type/Model	Serial Number	Calibration	
				Last Cal.	Due Date
SPEAG	Dosimetric E-Field Probe	ES3DV3	3270	Sep. 12, 2011	Sep. 11, 2012
SPEAG	Dosimetric E-Field Probe	EX3DV4	3697	Sep. 02, 2011	Sep. 01, 2012
SPEAG	Data Acquisition Electronics	DAE4	1303	Nov. 10, 2011	Nov. 09, 2012
SPEAG	Data Acquisition Electronics	DAE4	1210	Nov. 18, 2011	Nov. 17, 2012
SPEAG	835MHz System Validation Kit	D835V2	4d091	Nov. 18, 2011	Nov. 17, 2012
SPEAG	1750MHz System Validation Kit	D1750V2	1023	Jun. 20, 2012	Jun. 19, 2013
SPEAG	1900MHz System Validation Kit	D1900V2	5d118	Nov. 21, 2011	Nov. 20, 2012
SPEAG	2450MHz System Validation Kit	D2450V2	736	Jul. 25, 2011	Jul. 24, 2012
SPEAG	SAM Twin Phantom	QD 000 P40 CD	TP-1670	NCR	NCR
SPEAG	SAM Twin Phantom	QD 000 P40 CD	TP-1671	NCR	NCR
SPEAG	SAM Twin Phantom	QD 000 P40 CB	TP-1477	NCR	NCR
SPEAG	SAM Twin Phantom	QD 000 P40 CB	TP-1479	NCR	NCR
SPEAG	Test Arch Phantom	Par phantom	1105	NCR	NCR
SPEAG	Phone Positioner	N/A	N/A	NCR	NCR
Anritsu	Radio Communication Analyzer	MT8820C	6201091028	Jun. 10, 2012	Jun. 09, 2013
Agilent	Base Station	E5515C	MY50267224	Dec. 29, 2011	Dec. 28, 2012
Agilent	ENA Series Network Analyzer	E5071C	MY46111157	Apr. 13, 2012	Apr. 12, 2013
R&S	Signal Generator	SMR40	100455	Dec. 30, 2011	Dec. 29, 2012
Agilent	Power Meter	E4416A	MY45101555	Aug. 23, 2012	Aug. 22, 2012
Agilent	Power Sensor	E9327A	MY44421198	Aug. 23, 2012	Aug. 22, 2012
R&S	Spectrum Analyzer	FSP30	101400	Jun. 01, 2012	May. 31, 2013

**Table 5.1 Test Equipment List**

**Note:** The calibration certificate of DASY can be referred to appendix C of this report.

## 6. Tissue Simulating Liquids

For the measurement of the field distribution inside the SAM phantom with DASY, the phantom must be filled with around 25 liters of homogeneous body tissue simulating liquid. For head SAR testing, the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15 cm, which is shown in Fig. 6.1. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15 cm, which is shown in Fig. 6.2.



Fig 6.1 Photo of Liquid Height for Head SAR



Fig 6.2 Photo of Liquid Height for Body SAR

The following table gives the recipes for tissue simulating liquid.

Frequency (MHz)	Water (%)	Sugar (%)	Cellulose (%)	Salt (%)	Preventol (%)	DGBE (%)	Conductivity ( $\sigma$ )	Permittivity ( $\epsilon_r$ )
<b>For Head</b>								
835	40.3	57.9	0.2	1.4	0.2	0	0.90	41.5
1800, 1900, 2000	55.2	0	0	0.3	0	44.5	1.40	40.0
2450	55.0	0	0	0	0	45.0	1.80	39.2
<b>For Body</b>								
835	50.8	48.2	0	0.9	0.1	0	0.97	55.2
1800, 1900, 2000	70.2	0	0	0.4	0	29.4	1.52	53.3
2450	68.6	0	0	0	0	31.4	1.95	52.7

Table 6.1 Recipes of Tissue Simulating Liquid



The dielectric parameters of the liquids were verified prior to the SAR evaluation using an Agilent 85070D Dielectric Probe Kit and an Agilent Network Analyzer.

The following table shows the measuring results for simulating liquid.

Freq. (MHz)	Liquid Type	Temp. (°C)	Conductivity ( $\sigma$ )	Permittivity ( $\epsilon_r$ )	Conductivity Target ( $\sigma$ )	Permittivity Target ( $\epsilon_r$ )	Delta ( $\sigma$ ) (%)	Delta ( $\epsilon_r$ ) (%)	Limit (%)	Date
835	Head	21.5	0.914	41.826	0.90	41.5	1.56	0.79	±5	Jul. 06, 2012
835	Body	21.4	0.97	56.499	0.97	55.2	0.00	2.35	±5	Jul. 09, 2012
1750	Head	21.3	1.378	40.204	1.40	40.0	-1.57	0.51	±5	Jul. 09, 2012
1750	Body	21.5	1.512	55.273	1.52	53.3	-0.53	3.70	±5	Jul. 06, 2012
1900	Head	21.6	1.427	41.191	1.40	40.0	1.93	2.98	±5	Jul. 09, 2012
1900	Body	21.7	1.519	53.569	1.52	53.3	-0.07	0.50	±5	Jul. 06, 2012
2450	Head	21.7	1.861	39.575	1.8	39.2	3.39	0.96	±5	Jul. 18, 2012
2450	Body	21.3	1.949	53.894	1.95	52.7	-0.05	2.27	±5	Jul. 18, 2012

**Table 6.2 Measuring Results for Simulating Liquid**

## 7. SAR Measurement Evaluation

Each DASY system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system performance check and system validation. System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder.

### 7.1 Purpose of System Performance check

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

### 7.2 System Setup

In the simplified setup for system evaluation, the EUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:

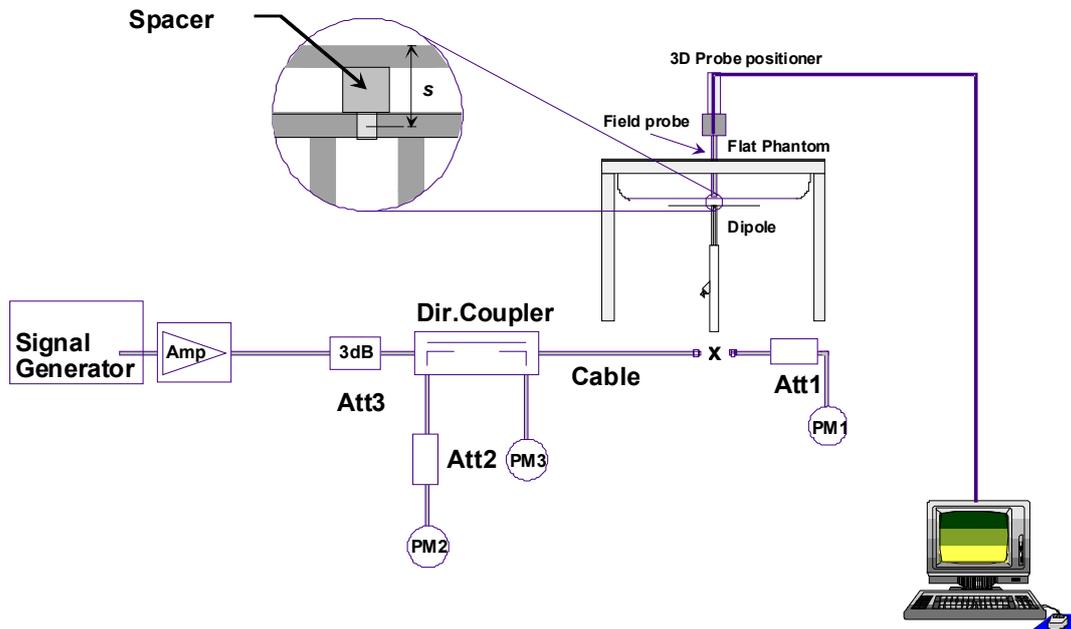


Fig 7.1 System Setup for System Evaluation

1. Signal Generator
2. Amplifier
3. Directional Coupler
4. Power Meter
5. Calibrated Dipole

The output power on dipole port must be calibrated to 24 dBm (250 mW) before dipole is connected.



**Fig 7.2 Photo of Dipole Setup**

**7.3 Validation Results**

Comparing to the original SAR value provided by SPEAG, the validation data should be within its specification of 10 %. Table 7.1 shows the target SAR and measured SAR after normalized to 1W input power. The table below indicates the system performance check can meet the variation criterion and the plots can be referred to Appendix A of this report.

Measurement Date	Frequency (MHz)	Liquid Type	Targeted SAR <sub>1g</sub> (W/kg)	Measured SAR <sub>1g</sub> (W/kg)	Normalized SAR <sub>1g</sub> (W/kg)	Deviation (%)
Jul. 06, 2012	835	Head	9.40	2.47	9.88	5.11
Jul. 09, 2012	835	Body	9.42	2.35	9.40	-0.21
Jul. 09, 2012	1750	Head	36.2	9.5	38.00	4.97
Jul. 06, 2012	1750	Body	36.8	9.61	38.44	4.46
Jul. 09, 2012	1900	Head	40.30	9.62	38.48	-4.52
Jul. 06, 2012	1900	Body	41.8	10.6	42.40	1.44
Jul. 18, 2012	2450	Head	54.8	13.2	52.80	-3.65
Jul. 18, 2012	2450	Body	52.3	13.3	53.20	1.72

**Table 7.1 Target and Measurement SAR after Normalized**

## 8. EUT Testing Position

This EUT was tested in three different positions. They are left cheek, Back of the EUT with phantom 1 cm gap, and Bottom Side of the EUT with phantom 1 cm gap, as illustrated below:

### 8.1 Define two imaginary lines on the handset

- The vertical centerline passes through two points on the front side of the handset - the midpoint of the width  $w_t$  of the handset at the level of the acoustic output, and the midpoint of the width  $w_b$  of the bottom of the handset.
- The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output. The horizontal line is also tangential to the face of the handset at point A.
- The two lines intersect at point A. Note that for many handsets, point A coincides with the center of the acoustic output; however, the acoustic output may be located elsewhere on the horizontal line. Also note that the vertical centerline is not necessarily parallel to the front face of the handset, especially for clamshell handsets, handsets with flip covers, and other irregularly shaped handsets.

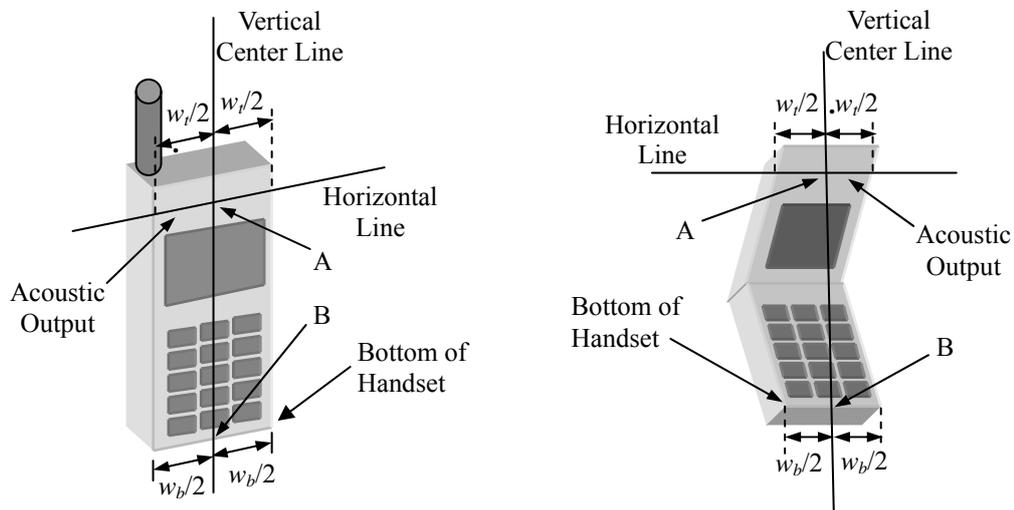


Fig 9.1 Illustration for Handset Vertical and Horizontal Reference Lines

### 8.2 Cheek Position

- (a) To position the device with the vertical center line of the body of the device and the horizontal line crossing the center piece in a plane parallel to the sagittal plane of the phantom. While maintaining the device in this plane, align the vertical center line with the reference plane containing the three ear and mouth reference point (M: Mouth, RE: Right Ear, and LE: Left Ear) and align the center of the ear piece with the line RE-LE.
- (b) To move the device towards the phantom with the ear piece aligned with the line LE-RE until the phone touched the ear. While maintaining the device in the reference plane and maintaining the phone contact with the ear, move the bottom of the phone until any point on the front side is in contact with the cheek of the phantom or until contact with the ear is lost (see Fig. 9.2).

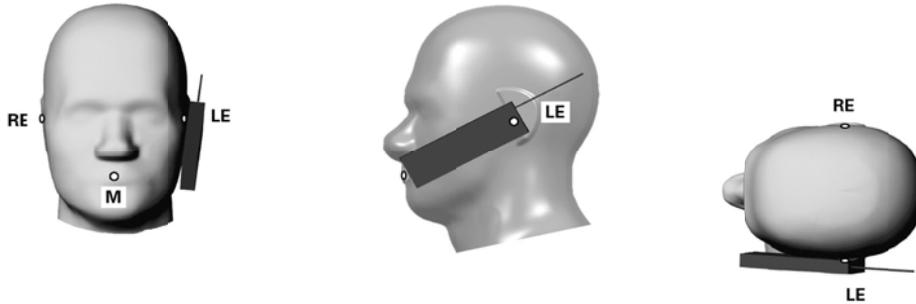


Fig 9.2 Illustration for Cheek Position

### 8.3 Body Worn Position

- (a) To position the device parallel to the phantom surface with keypad down.
- (b) To adjust the device parallel to the flat phantom.
- (c) To adjust the distance between the device surface and the flat phantom to 1 cm.

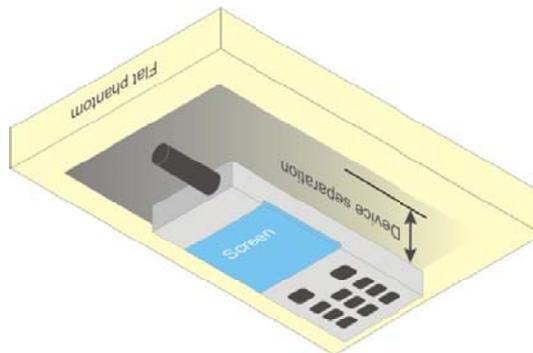


Fig 9.3 Illustration for Body Worn Position

#### <EUT Setup Photos>

Please refer to Appendix E for the test setup photos.

## **9. Measurement Procedures**

The measurement procedures are as follows:

- (a) Use base station simulator (if applicable) or engineering software to transmit RF power continuously (continuous Tx) in the highest power channel.
- (b) Keep EUT to radiate maximum output power or 100% duty factor (if applicable)
- (c) Measure output power through RF cable and power meter.
- (d) Place the EUT in the positions as Appendix E demonstrates.
- (e) Set scan area, grid size and other setting on the DASY software.
- (f) Measure SAR results for the highest power channel on each testing position.
- (g) Find out the largest SAR result on these testing positions of each band
- (h) Measure SAR results for other channels in worst SAR testing position if the SAR of highest power channel is larger than 0.8 W/kg

According to the test standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- (a) Power reference measurement
- (b) Area scan
- (c) Zoom scan
- (d) Power drift measurement

### **9.1 Spatial Peak SAR Evaluation**

The procedure for spatial peak SAR evaluation has been implemented according to the test standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

The entire evaluation of the spatial peak values is performed within the post-processing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- (a) Extraction of the measured data (grid and values) from the Zoom Scan
- (b) Calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- (c) Generation of a high-resolution mesh within the measured volume
- (d) Interpolation of all measured values from the measurement grid to the high-resolution grid
- (e) Extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- (f) Calculation of the averaged SAR within masses of 1g and 10g

### **9.2 Area & Zoom Scan Procedures**

First Area Scan is used to locate the approximate location(s) of the local peak SAR value(s). The measurement grid within an Area Scan is defined by the grid extent, grid step size and grid offset. Next, in order to determine the EM field distribution in a three-dimensional spatial extension, Zoom Scan is required. The Zoom Scan measures 5x5x7 points with step size 8, 8 and 5 mm for 300 MHz to 3 GHz, and 8x8x8 points with step size 4, 4 and 2.5 mm for 3 GHz to 6 GHz. The Zoom Scan is performed around the highest E-field value to determine the averaged SAR-distribution over 10 g.



### **9.3 Volume Scan Procedures**

The volume scan is used to assess overlapping SAR distributions for antennas transmitting in different frequency bands. It is equivalent to an oversized zoom scan used in standalone measurements. The measurement volume will be used to enclose all the simultaneous transmitting antennas. For antennas transmitting simultaneously in different frequency bands, the volume scan is measured separately in each frequency band. In order to sum correctly to compute the 1g aggregate SAR, the EUT remains in the same test position for all measurements and all volume scans use the same spatial resolution and grid spacing (step-size is 4, 4 and 2.5 mm). When all volume scans are completed, the software, SEMCAD postprocessor can combine and subsequently superpose these measurement data to calculate the multiband SAR.

### **9.4 SAR Averaged Methods**

In DASy, the interpolation and extrapolation are both based on the modified Quadratic Shepard's method. The interpolation scheme combines a least-square fitted function method and a weighted average method which are the two basic types of computational interpolation and approximation.

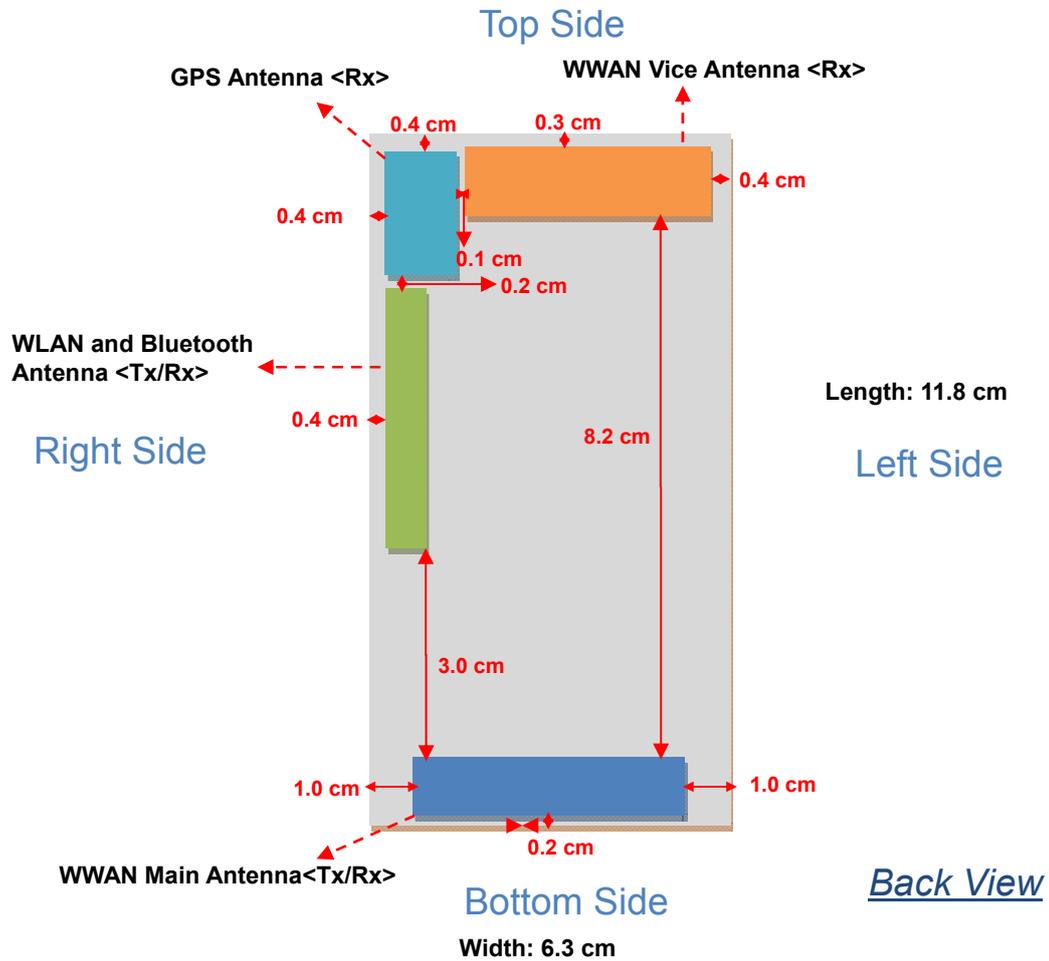
Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. The uncertainty increases with the extrapolation distance. To keep the uncertainty within 1% for the 1 g and 10 g cubes, the extrapolation distance should not be larger than 5 mm.

### **9.5 Power Drift Monitoring**

All SAR testing is under the EUT installed full charged battery and transmit maximum output power. In DASy measurement software, the power reference measurement and power drift measurement procedures are used for monitoring the power drift of EUT during SAR test. Both these procedures measure the field at a specified reference position before and after the SAR testing. The software will calculate the field difference in dB. If the power drift is more than 5%, the SAR will be retested.

## 10. SAR Test Configurations

### 10.1 Exposure Positions Consideration



Antennas	Wireless Interface
WWAN Main Antenna (Tx / Rx)	CDMA2000 EVDO: BC 0/1/15
WWAN Vice Antenna (Rx only)	CDMA2000 EVDO: BC 0/1/15
WLAN & Bluetooth Antenna (Tx / Rx)	WLAN 2.4GHz Bluetooth
GPS Antenna (Rx only)	GPS receiving only



<b>Sides for SAR tests; Hotspot mode</b>						
<b>Test distance: 10 mm</b>						
<b>Antennas</b>	<b>Back</b>	<b>Front</b>	<b>Top Side</b>	<b>Bottom Side</b>	<b>Right Side</b>	<b>Left Side</b>
<b>WWAN Main</b>	YES	NO	NO	YES	NO	NO
<b>WLAN 2.4G</b>	NO	NO	NO	NO	NO	NO

**Note:** Referring to KDB 941225 D06, when the overall device length and width are  $\geq 9\text{cm} \times 5\text{cm}$ , the test distance is 10 mm. SAR must be measured for all sides and surfaces with a transmitting antenna located within 25mm from that surface or edge.

**10.2 Conducted RF Output Power (Unit: dBm)**

**<CDMA2000>**

Band	CDMA2000 BC0			CDMA2000 BC1			CDMA2000 BC15		
Channel	1013	384	777	25	600	1175	25	425	875
Frequency (MHz)	824.70	836.52	848.31	1851.25	1880.00	1908.75	1711.25	1731.25	1753.75
1xRTT RC1+SO55	23.71	23.65	23.62	24.18	23.83	24.00	22.99	22.93	23.21
1xRTT RC3+SO55	23.66	23.67	23.60	24.10	23.82	24.04	22.95	22.92	23.18
1xRTT RC3+SO32 (FCH)	23.68	23.66	23.50	24.16	23.84	23.99	22.88	22.85	23.09
1xRTT RC3+SO32 (FCH+SCH)	23.68	23.68	23.51	24.12	23.81	23.97	22.88	22.86	23.10
1xEVDO RTAP 153.6	23.65	23.69	23.56	24.16	23.78	23.95	22.94	22.85	23.11
1xEVDO RETAP 4096	23.62	23.66	23.58	24.17	23.81	23.96	22.89	22.85	23.09

**Note:**

1. According to KDB 941225 D01, Head SAR for RC1+SO55 is not required because the maximum average output power of RC1 is less than 1/4 dB higher than RC3+SO55.
2. Referring to KDB 941225 D01, the CDMA Handset Body-worn SAR tests based on RC3+SO32. RC1, RTAP (REV 0), and RETAP (Rev A) power are all less than 1/4 dB higher than RC3, thus SAR tests in these mode are not necessary.
3. Referring to KDB 941225 D01, in Hotspot mode EUT is treated as data device and SAR is tested with RTAP 153.6kbps (Ev-Do). If RC3+SO32 power is less than 1/4dB higher than Ev-Do, SAR tests with RC3+SO32 setting are not necessary.

**<WLAN 2.4GHz>**

Mode	Channel	Frequency (MHz)	Average power (dBm)			
			Data Rate (bps)			
			1M	2M	5.5M	11M
802.11b	CH 01	2412	13.96	13.78	13.86	13.82
	CH 06	2437	13.78	13.79	13.87	13.84
	CH 11	2462	13.56	13.52	13.56	13.51

Mode	Channel	Frequency (MHz)	Average power (dBm)							
			Data Rate (bps)							
			6M	9M	12M	18M	24M	36M	48M	54M
802.11g	CH 01	2412	14.11	14.04	14.07	14.04	13.30	13.32	13.46	13.30
	CH 06	2437	13.76	13.74	13.75	13.82	12.97	12.95	13.47	13.43
	CH 11	2462	14.00	13.99	13.96	13.97	12.77	12.74	13.27	13.24

**Note:**

1. Per KDB 248227, 11g output power is less than 1/4 dB higher than 11b mode, thus the SAR can be excluded.
2. For each frequency band, testing at higher data rates and higher order modulations is not requirement when the maximum average output power for each of these configurations is less than 1/4 dB higher than those measured at the lowest data rate.

**<Bluetooth>**

Band	Bluetooth		
Channel	0	39	78
Frequency (MHz)	2402	2441	2480
Average Power (dBm)	7.73	8.72	8.27

## 11. SAR Test Results

### 11.1 Test Records for Head SAR Test

<CDMA2000>

Plot No.	Band	Mode	Test Position	Ch.	Freq. (MHz)	Output Power (dBm)	Power Drift (dB)	SAR <sub>1g</sub> (W/kg)
7	CDMA2000 BC0	RC3 SO55	Left Cheek	777	848.31	23.6	-0.03	0.757
26	CDMA2000 BC0	RC3 SO55	Left Cheek	1013	824.7	23.66	-0.13	0.674
27	CDMA2000 BC0	RC3 SO55	Left Cheek	384	836.52	23.67	0.06	0.735
20	CDMA2000 BC15	RC3 SO55	Left Cheek	425	1731.25	22.92	0.03	1.070
21	CDMA2000 BC15	RC3 SO55	Left Cheek	25	1711.25	22.95	-0.04	0.928
22	CDMA2000 BC15	RC3 SO55	Left Cheek	875	1753.75	23.18	0.06	0.787
23	CDMA2000 BC1	RC3 SO55	Left Cheek	25	1851.25	24.1	-0.07	0.814
24	CDMA2000 BC1	RC3 SO55	Left Cheek	600	1880	23.82	0.08	0.756
25	CDMA2000 BC1	RC3 SO55	Left Cheek	1175	1908.75	24.04	-0.16	0.809

Note:

- Per KDB 447498, if the highest output channel SAR for each exposure position  $\leq 0.8$  W/kg other channels SAR tests are not necessary.

<WLAN>

Plot No.	Band	Mode	Test Position	Ch.	Freq. (MHz)	Output Power (dBm)	Power Drift (dB)	SAR <sub>1g</sub> (W/kg)
28	WLAN 2.4G	802.11b	Left Cheek	6	2437	13.78	0.05	0.322
29	WLAN 2.4G	802.11b	Left Cheek	1	2412	13.96	0.07	0.366
30	WLAN 2.4G	802.11b	Left Cheek	11	2462	13.56	0.09	0.388

Note:

- Per KDB 248227, if the highest output channel SAR for each exposure position  $\leq 0.8$  W/kg other channels SAR tests are not necessary.

### 11.2 Test Records for Hotspot SAR Test

<CDMA2000>

Plot No.	Band	Mode	Test Position	Gap (cm)	Ch.	Freq. (MHz)	Output Power (dBm)	Power Drift (dB)	SAR <sub>1g</sub> (W/kg)
11	CDMA2000 BC0	RTAP 153.6	Back	1	1013	824.7	23.65	0.06	1.050
12	CDMA2000 BC0	RTAP 153.6	Back	1	384	836.52	23.69	-0.03	1.030
13	CDMA2000 BC0	RTAP 153.6	Back	1	777	848.31	23.56	0.06	0.987
1	CDMA2000 BC15	RTAP 153.6	Back	1	425	1731.25	22.85	-0.07	1.190
2	CDMA2000 BC15	RTAP 153.6	Back	1	25	1711.25	22.94	-0.05	1.010
3	CDMA2000 BC15	RTAP 153.6	Back	1	875	1753.75	23.11	0.04	0.886
4	CDMA2000 BC1	RTAP 153.6	Bottom Side	1	25	1851.25	24.16	-0.08	0.968
5	CDMA2000 BC1	RTAP 153.6	Bottom Side	1	600	1880	23.78	-0.04	0.895
6	CDMA2000 BC1	RTAP 153.6	Bottom Side	1	1175	1908.75	23.95	-0.03	0.940

Note:

- Per KDB 941225 D06, for EUT dimension  $\geq 9\text{cm} \times 5\text{cm}$ , the test distance is 1cm. SAR must be measured for all surfaces and sides with a transmitting antenna located within 2.5cm from that surface or edge.
- Per KDB 447498, if the highest output channel SAR for each exposure position  $\leq 0.8$  W/kg other channels SAR tests are not necessary.

**11.3 Test Records for Body-worn SAR Test**

**<CDMA2000>**

Plot No.	Band	Mode	Test Position	Gap (cm)	Ch.	Freq. (MHz)	Output Power (dBm)	Headset	Power Drift (dB)	SAR <sub>1g</sub> (W/kg)
11	CDMA2000 BC0	RTAP 153.6	Back	1	1013	824.7	23.65	-	0.06	1.050
12	CDMA2000 BC0	RTAP 153.6	Back	1	384	836.52	23.69	-	-0.03	1.030
13	CDMA2000 BC0	RTAP 153.6	Back	1	777	848.31	23.56	-	0.06	0.987
14	CDMA2000 BC0	RC3 SO32	Back	1	777	848.31	23.5	v	0.01	0.659
15	CDMA2000 BC0	RC3 SO32	Back	1	1013	824.7	23.68	v	-0.01	0.847
16	CDMA2000 BC0	RC3 SO32	Back	1	384	836.52	23.66	v	-0.01	0.785
1	CDMA2000 BC15	RTAP 153.6	Back	1	425	1731.25	22.85	-	-0.07	1.190
2	CDMA2000 BC15	RTAP 153.6	Back	1	25	1711.25	22.94	-	-0.05	1.010
3	CDMA2000 BC15	RTAP 153.6	Back	1	875	1753.75	23.11	-	0.04	0.886
17	CDMA2000 BC15	RC3 SO32	Back	1	425	1731.25	22.85	v	-0.09	1.210
18	CDMA2000 BC15	RC3 SO32	Back	1	25	1711.25	22.88	v	-0.07	1.020
19	CDMA2000 BC15	RC3 SO32	Back	1	875	1753.75	23.09	v	-0.04	0.964
8	CDMA2000 BC1	RC3 SO32	Back	1	25	1851.25	24.16	V	-0.07	0.992
9	CDMA2000 BC1	RC3 SO32	Back	1	600	1880	23.84	V	0.01	0.839
10	CDMA2000 BC1	RC3 SO32	Back	1	1175	1908.75	23.99	V	-0.04	1.010

**Note:**

1. Per KDB 447498, if the highest output channel SAR for each exposure position ≤ 0.8 W/kg other channels SAR tests are not necessary.
2. "V" in the earphone column means the earphone is plugged during SAR testing.

**<WLAN>**

Plot No.	Band	Mode	Test Position	Gap (cm)	Ch.	Freq. (MHz)	Output Power (dBm)	Headset	Power Drift (dB)	SAR <sub>1g</sub> (W/kg)
31	WLAN 2.4G	802.11b	Back	1	6	2437	13.78	V	0.1	0.350
32	WLAN 2.4G	802.11b	Back	1	1	2412	13.96	V	0.03	0.343
33	WLAN 2.4G	802.11b	Back	1	11	2462	13.56	V	-0.03	0.370

**Note:**

1. Per KDB 248227, if the highest output channel SAR for each exposure position ≤ 0.8 W/kg other channels SAR tests are not necessary.
2. "V" in the earphone column means the earphone is plugged during SAR testing.

**11.4 Simultaneous Multi-band Transmission Analysis**

No.	Applicable Simultaneous Transmission Combination
1.	CDMA2000 + Bluetooth
2.	CDMA2000 + WLAN 2.4G

**Note:**

1. WLAN and BT share the same antenna, and cannot transmit simultaneously.
2. Per KDB 648474 D01, Bluetooth (8.72 dBm) output power  $\leq P_{Ref}$  (10.8 dBm) and the distance to WWAN transmitting antenna  $\geq 2.5\text{cm}$ , therefore, Bluetooth stand-alone SAR is not required; the simultaneous transmission SAR for Bluetooth and WWAN is not required, because Bluetooth stand-alone SAR is not required and the maximum WWAN SAR is 1.21 W/kg, thus the SAR summation is less than 1.6 W/kg.
3. Per KDB 648474 D01, the simultaneous transmission SAR for WWAN and WLAN was not required, because the SAR summation (Head: 1.458 W/kg; Body: 1.580 W/kg) is less than 1.6 W/kg.

**<Maximum SAR list for each band and position>**

Position	WWAN			WLAN		Max. SAR Summation
	WWAN Band	Plot No	Max. WWAN SAR (W/kg)	Plot No	Max. WLAN SAR (W/kg)	
Left Cheek	CDMA2000 BC0	7	0.757	30	0.388	1.145
	CDMA2000 BC15	20	1.070	30	0.388	1.458
	CDMA2000 BC1	23	0.814	30	0.388	1.202
Back	CDMA2000 BC0	11	1.050	33	0.370	1.42
	CDMA2000 BC15	1	1.190	33	0.370	1.56
	CDMA2000 BC1	-	-	33	0.370	0.370
Bottom Side	CDMA2000 BC0	-	-	33	0.370	0.370
	CDMA2000 BC15	-	-	33	0.370	0.370
	CDMA2000 BC1	4	0.968	33	0.370	1.338
Back (with Headset)	CDMA2000 BC0	15	0.847	33	0.370	1.217
	CDMA2000 BC15	17	1.210	33	0.370	1.580
	CDMA2000 BC1	10	1.010	33	0.370	1.380

**Note:**

1. The maximum SAR summation is calculated based on the same configuration and test position.
2. When stand-alone 1-g SAR is not required for a transmitter or antenna, its SAR is considered zero in the 1-g SAR summing process to determine simultaneous transmission SAR evaluation requirements
3. If 1g-SAR scalar summation  $< 1.6\text{W/kg}$ , simultaneous SAR measurement is not necessary.
4. If 1g-SAR summation  $> 1.6\text{W/kg}$ , SPLSR calculation is necessary.

## **12. Uncertainty Assessment**

The component of uncertainty may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainty by the statistical analysis of a series of observations is termed a Type A evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observations is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience and knowledge of the behavior and properties of relevant materials and instruments, manufacture's specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table 12.1

<b>Uncertainty Distributions</b>	<b>Normal</b>	<b>Rectangular</b>	<b>Triangular</b>	<b>U-Shape</b>
Multi-plying Factor <sup>(a)</sup>	1/ $\kappa$ <sup>(b)</sup>	1/ $\sqrt{3}$	1/ $\sqrt{6}$	1/ $\sqrt{2}$

(a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity

(b)  $\kappa$  is the coverage factor

**Table 12.1 Standard Uncertainty for Assumed Distribution**

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual "root-sum-squares" (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %. The DASY uncertainty Budget is shown in the following tables.



Error Description	Uncertainty	Probability	Divisor	Ci	Ci	Standard	Standard
	Value (±%)	Distribution		(1g)	(10g)	Uncertainty (1g)	Uncertainty (10g)
<b>Measurement System</b>							
Probe Calibration	6.0	Normal	1	1	1	± 6.0 %	± 6.0 %
Axial Isotropy	4.7	Rectangular	√3	0.7	0.7	± 1.9 %	± 1.9 %
Hemispherical Isotropy	9.6	Rectangular	√3	0.7	0.7	± 3.9 %	± 3.9 %
Boundary Effects	1.0	Rectangular	√3	1	1	± 0.6 %	± 0.6 %
Linearity	4.7	Rectangular	√3	1	1	± 2.7 %	± 2.7 %
System Detection Limits	1.0	Rectangular	√3	1	1	± 0.6 %	± 0.6 %
Readout Electronics	0.3	Normal	1	1	1	± 0.3 %	± 0.3 %
Response Time	0.8	Rectangular	√3	1	1	± 0.5 %	± 0.5 %
Integration Time	2.6	Rectangular	√3	1	1	± 1.5 %	± 1.5 %
RF Ambient Noise	3.0	Rectangular	√3	1	1	± 1.7 %	± 1.7 %
RF Ambient Reflections	3.0	Rectangular	√3	1	1	± 1.7 %	± 1.7 %
Probe Positioner	0.4	Rectangular	√3	1	1	± 0.2 %	± 0.2 %
Probe Positioning	2.9	Rectangular	√3	1	1	± 1.7 %	± 1.7 %
Max. SAR Eval.	1.0	Rectangular	√3	1	1	± 0.6 %	± 0.6 %
<b>Test Sample Related</b>							
Device Positioning	2.9	Normal	1	1	1	± 2.9 %	± 2.9 %
Device Holder	3.6	Normal	1	1	1	± 3.6 %	± 3.6 %
Power Drift	5.0	Rectangular	√3	1	1	± 2.9 %	± 2.9 %
<b>Phantom and Setup</b>							
Phantom Uncertainty	4.0	Rectangular	√3	1	1	± 2.3 %	± 2.3 %
Liquid Conductivity (Target)	5.0	Rectangular	√3	0.64	0.43	± 1.8 %	± 1.2 %
Liquid Conductivity (Meas.)	2.5	Normal	1	0.64	0.43	± 1.6 %	± 1.1 %
Liquid Permittivity (Target)	5.0	Rectangular	√3	0.6	0.49	± 1.7 %	± 1.4 %
Liquid Permittivity (Meas.)	2.5	Normal	1	0.6	0.49	± 1.5 %	± 1.2 %
<b>Combined Standard Uncertainty</b>						± 11.0 %	± 10.8 %
<b>Coverage Factor for 95 %</b>						K=2	
<b>Expanded Uncertainty</b>						± 22.0 %	± 21.5 %

Table 12.2 Uncertainty Budget of DASY for frequency range 300 MHz to 3 GHz



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