

1:16 RC Car Rx

The car will receive this RF signal by a super-regenerate circuit. Then the decoder IC (RX2C) will decode the signal to control the motor driver circuit.

Power is supplied by 4x1.5V AA size batteries for CAR.

The detail Function as below:

1. Turn the power switch of controller and car to “ON” position.
2. When the Tx output one forward signal, the car unit RX2C Pin11 output High level to control the move forward.
3. When the Tx output one back signal, RX2C Pin10 output high level to control car move back.
4. When the Tx output turn right or left signal, RX2C Pin6 or Pin7 output high level to control the steering motor run to right or left.