



# **SAR Evaluation Report**

in accordance with the requirements of  
FCC Report and Order: ET Docket 93-62, and OET Bulletin 65 Supplement C

for

**2.4 GHz DIGITAL FREQUENCY HOPPING SPREAD SPECTRUM**

**CORDLESS PHONE**

**MODEL: EP-236**

**FCC ID: NI3-EP-236**

**OCTOBER 17, 2002**

**REPORT NO: 02T1525-1**

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**CERTIFICATE OF COMPLIANCE (SAR EVALUATION)****DATES OF TEST: OCTOBER 16 - 17, 2002****REPORT NO: 02T1525-1**

<b>APPLICANT:</b>	SENAO INTERNATIONAL CO., LTD. 2F, NO. 531 CHUNG CHENG ROAD TAIPEI, TAIWAN, R.O.C. 231
<b>TRADE NAME:</b>	SENAO INTERNATIONAL CO., LTD.
<b>MODEL:</b>	EP-236
<b>FCC ID:</b>	NI3-EP-236
<b>DEVICE CATEGORY:</b>	PORTABLE DEVICES
<b>EXPOSURE CATEGORY:</b>	GENERAL POPULATION / UNCONTROLLED EXPOSURE

**Test Sample is a:** Production Unit**Operating Mode:** Maximum Continuous Output**Tx Frequency:** 2401.06 – 2479.68 MHz**Rx Frequency:** 2401.06 – 2479.68 MHz**Max. RF Output Power (Conducted):** 17.49 dBm (2479.68MHz)**Max. SAR (1g):** 0.317 mW/g  
(at 2479.68MHz, Left Touch Configuration)**Application Type:** Stub type**FCC Rule Part(s):** § 15.247

This wireless portable device has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment/general population exposure limits specified in ANSI/IEEE Std. C95.1-1992 and had been tested in accordance with the measurement procedures specified in FCC OET 65 Supplement C (released on 6/29/2001 see Test Report).

I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualifications of all persons taking them.

**Steve Cheng**  
**EMC Engineering**  
**Manager**

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**1. EUT DESCRIPTION**

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(at 2479.68MHz, Left Touch Configuration)**Application Type:** Stub type**FCC Rule Part(s):** § 15.247**Antenna Dimensions:** Length = 59 mm; Width = 17 mm (bottom) – 7.5mm (tip)**Battery option:** Only one model with EUT

<sup>1</sup> Specific Absorption Rate (SAR) is a measure of the rate of energy absorption due to exposure to an RF transmitting source (wireless portable device).

<sup>2</sup> IEEE/ANSI Std. C95.1-1992 limits are used to determine compliance with FCC ET Docket 93-62.

## 2. REQUIREMENTS FOR COMPLIANCE TESTING DEFINED BY THE FCC

The US Federal Communications Commission has released the report and order "Guidelines for Evaluating the Environmental Effects of RF Radiation", ET Docket No. 93-62 in August 1996. The order requires routine SAR evaluation prior to equipment authorization of portable transmitter devices, including portable telephones. For consumer products, the applicable limit is 1.6 mW/g for an uncontrolled environment and 8.0 mW/g for an occupational/controlled environment as recommended by the ANSI/IEEE standard C95.1-1992. According to the Supplement C of OET Bulletin 65 "Evaluating Compliance with FCC Guide-lines for Human Exposure to Radio frequency Electromagnetic Fields", released on Jun 29, 2001 by the FCC, the device should be evaluated at maximum output power (radiated from the antenna) under "worst-case" conditions for normal or intended use, incorporating normal antenna operating positions, device peak performance frequencies and positions for maximum RF energy coupling.

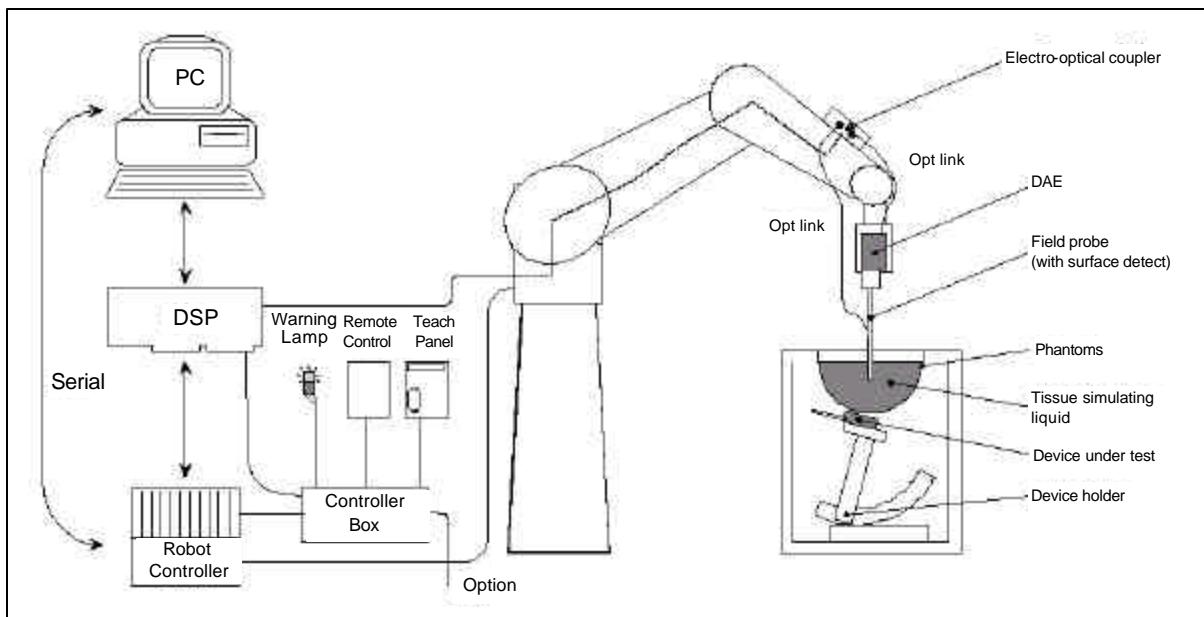
## 3. DOSIMETRIC ASSESSMENT SETUP

These measurements were performed with the automated near-field scanning system DASY3 from Schmid & Partner Engineering AG (SPEAG). The system is based on a high precision robot (working range greater than 0.9 m), which positions the probes with a positional repeatability of better than  $\pm$  0.02 mm. Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines to the data acquisition unit. The SAR measurements were conducted with the dosimetric probe ET3DV6, SN: 1577 (manufactured by SPEAG), designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe has been calibrated according to the procedure described in [7] with accuracy of better than  $\pm$ 10%. The spherical isotropy was evaluated with the procedure described in [8] and found to be better than  $\pm$ 0.25 dB. The phantom used was the SAM Twin Phantom as described in FCC supplement C, IEE P1528 and CENELEC EN50361.

The Tissue simulation liquid used for each test is in according with the FCC OET65 supplement C as listed below.

Ingredients (% by weight)	Frequency (MHz)									
	450		835		915		1900		2450	
Tissue Type	Head	Body	Head	Body	Head	Body	Head	Body	Head	Body
Water	38.56	51.16	41.45	52.4	41.05	56.0	54.9	40.4	62.7	73.2
Salt (NaCl)	3.95	1.49	1.45	1.4	1.35	0.76	0.18	0.5	0.5	0.04
Sugar	56.32	46.78	56.0	45.0	56.5	41.76	0.0	58.0	0.0	0.0
HEC	0.98	0.52	1.0	1.0	1.0	1.21	0.0	1.0	0.0	0.0
Bactericide	0.19	0.05	0.1	0.1	0.1	0.27	0.0	0.1	0.0	0.0
Triton X-100	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	36.8	0.0
DGBE	0.0	0.0	0.0	0.0	0.0	0.0	44.92	0.0	0.0	26.7
Dielectric Constant	43.42	58.0	42.54	56.1	42.0	56.8	39.9	54.0	39.8	52.5
Conductivity (S/m)	0.85	0.83	0.91	0.95	1.0	1.07	1.42	1.45	1.88	1.78

### 3.1. MEASUREMENT SYSTEM DIAGRAM



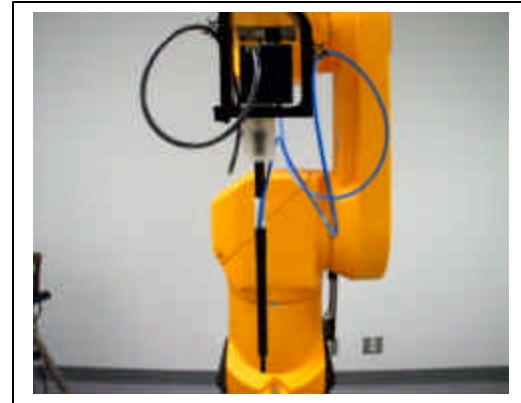
**The DASY3 system for performing compliance tests consist of the following items:**

1. A standard high precision 6-axis robot (Stäubli RX family) with controller and software.
2. An arm extension for accommodating the data acquisition electronics (DAE).
3. A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
4. A data acquisition electronic (DAE), which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
5. A unit to operate the optical surface detector, which is connected to the EOC.
6. The Electro-optical coupler (EOC) performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the PC plug-in card.
7. The functions of the PC plug-in card based on a DSP is to perform the time critical task such as signal filtering, surveillance of the robot operation fast movement interrupts.
8. A computer operating Windows 95 or larger
9. DASY3 software
10. Remote control with teaches pendant and additional circuitry for robot safety such as warning lamps, etc.
11. The SAM phantom enabling testing left-hand and right-hand usage.
12. The device holder for handheld EUT.
13. Tissue simulating liquid mixed according to the given recipes (see Application Note).
14. System validation dipoles to validate the proper functioning of the system.

### 3.2. SYSTEM COMPONENTS

#### ET3DV5 Probe Specification

Construction Symmetrical design with triangular core  
 Built-in optical fiber for surface detection System  
 Built-in shielding against static charges  
 Calibration In air from 10 MHz to 2.5 GHz  
 In brain and muscle simulating tissue at  
 Frequencies of 450 MHz, 900 MHz and  
 1.8 GHz (accuracy  $\pm$  8%)  
 Frequency 10 MHz to > 6 GHz; Linearity:  $\pm$  0.2 dB  
 (30 MHz to 3 GHz)  
 Directivity  $\pm$  0.2 dB in brain tissue (rotation around probe axis)  
 $\pm$  0.4 dB in brain tissue (rotation normal probe axis)  
 Dynamic 5 mW/g to > 100 mW/g;  
 Range Linearity:  $\pm$  0.2 dB  
 Surface  $\pm$  0.2 mm repeatability in air and clear liquids  
 Detection over diffuse reflecting surfaces.  
 Dimensions Overall length: 330 mm  
 Tip length: 16 mm  
 Body diameter: 12 mm  
 Tip diameter: 6.8 mm  
 Distance from probe tip to dipole centers: 2.7 mm  
 Application General dosimetric up to 3 GHz  
 Compliance tests of mobile phones  
 Fast automatic scanning in arbitrary phantoms



Photograph of the probe

The SAR measurements were conducted with the dosimetric probe ET3DV6 designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multi-fiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY3 software reads the reflection during a software approach and looks for the maximum using a 2 nd order fitting. The approach is stopped when reaching the maximum.



Inside view of  
ET3DV6 E-field Probe

## E-Field Probe Calibration Process

Each probe is calibrated according to a dosimetric assessment procedure described in [6] with accuracy better than +/- 10%. The spherical isotropy was evaluated with the procedure described in [7] and found to be better than +/-0.25dB. The sensitivity parameters (NormX, NormY, NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested.

The free space E-field from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies bellow 1 GHz, and in a waveguide above 1 GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium correlates to temperature rise in dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

### Data Evaluation

The DASY3 software automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	Norm <sub>i</sub> , a <sub>i10</sub> , a <sub>i11</sub> , a <sub>i12</sub>
	- Conversion factor	ConvF <sub>i</sub>
	- Diode compression point	Dcp <sub>i</sub>
Device parameters:	- Frequency	f
	- Crest factor	cf
Media parameters:	- Conductivity	$\sigma$
	- Density	$\rho$

These parameters must be set correctly in the software. They can either be found in the component documents or be imported into the software from the configuration files issued for the DASY3 components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with	$V_i$	= Compensated signal of channel i (i = x, y, z)
	$U_i$	= Input signal of channel i (i = x, y, z)
	$cf$	= Crest factor of exciting field (DASY parameter)
	$dcp_i$	= Diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes: 
$$E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

H-field probes: 
$$H_i = \sqrt{Vi} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

with  $V_i$  = Compensated signal of channel i (i = x, y, z)

$Norm_i$  = Sensor sensitivity of channel i (i = x, y, z)

$\mu\text{V}/(\text{V}/\text{m})^2$  for E0field Probes

$ConvF$  = Sensitivity enhancement in solution

$a_{ij}$  = Sensor sensitivity factors for H-field probes

$f$  = Carrier frequency (GHz)

$E_i$  = Electric field strength of channel i in V/m

$H_i$  = Magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with  $SAR$  = local specific absorption rate in mW/g

$E_{tot}$  = total field strength in V/m

$\sigma$  = conductivity in [mho/m] or [siemens/m]

$\rho$  = equivalent tissue density in g/cm<sup>3</sup>

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid.

The power flow density is calculated assuming the excitation field as a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770} \quad \text{or} \quad P_{pwe} = H_{tot}^2 \cdot 37.7$$

with  $P_{pwe}$  = Equivalent power density of a plane wave in mW/cm<sup>2</sup>

$E_{tot}$  = total electric field strength in V/m

$H_{tot}$  = total magnetic field strength in A/m

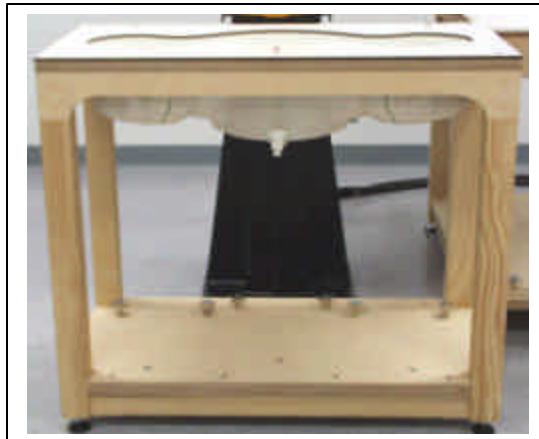
### SAM Phantom

The SAM Phantom V4.0 is constructed of a fiberglass shell integrated in a wooden table. The shape of the shell is in compliance with the specification set in IEE P1528 and CENELEC EN50361. The phantom enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents the evaporation of the liquid. Reference markings on the Phantom allows the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot.

Shell Thickness: 2  $\pm$  0.2 mm

Filling Volume: Approx. 25 liters

Dimensions (H x L x W): 810 x 1000 x 500 mm



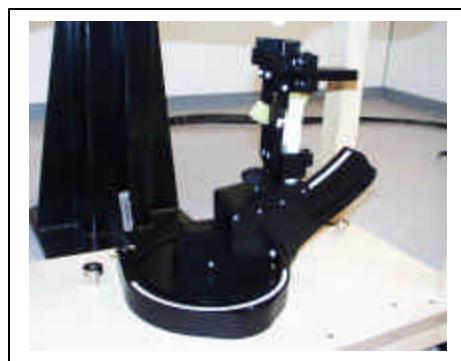
**SAM Phantom**

### Device Holder for Transmitters

In combination with the SAM Twin Phantom V4.0, the Mounting Device enables the rotation of the mounted transmitter in spherical coordinates whereby the rotation points is the ear opening. The devices can be easily, accurately, and repeatedly positioned according to the FCC and CENELEC specifications. The device holder can be locked at different phantom locations (left head, right head, flat phantom).

\* Note: A simulating human hand is not used due to the complex anatomical and geometrical structure of the hand that may produced infinite number of configurations [10].

To produce the worst-case condition (the hand absorbs antenna output power), the hand is omitted during the tests.



**Device Holder**

### 3.3. EUT ARRANGEMENT

#### Handset test position – Head position

The device was placed in a normal operating position with the Point A on the device, as illustrated in following drawing, aligned with the location of the RE(ERP) on the phantom. With the ear-piece pressed against the head, the vertical center line of the body of the handset was aligned with an imaginary plane consisting of the RE, LE and M. While maintaining these alignments, the body of the handset was gradually moved towards the cheek until any point on the mouth-piece or keypad contacted the cheek. This is a cheek/touch position. For ear/tilt position, while maintain the device aligned with the BM and FN lines, the device was pivot against ERP back for 15° or until the device antenna touch the phantom. Please refer to IEEE SC-2 P1528 illustration below.

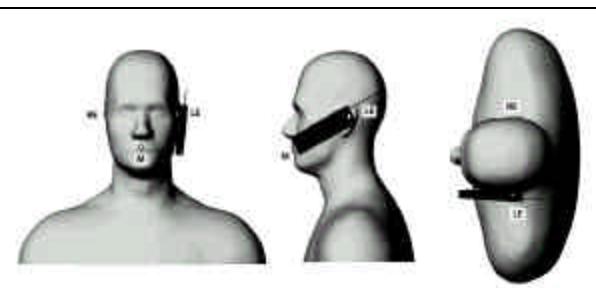
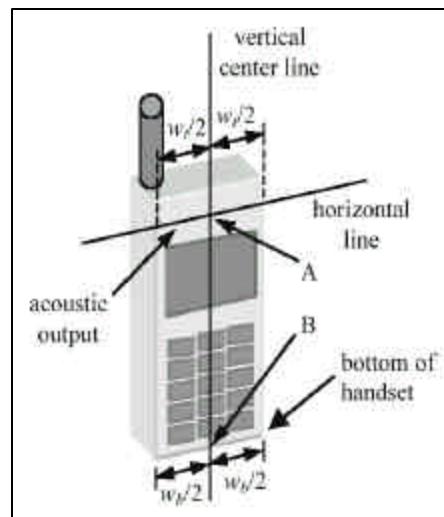
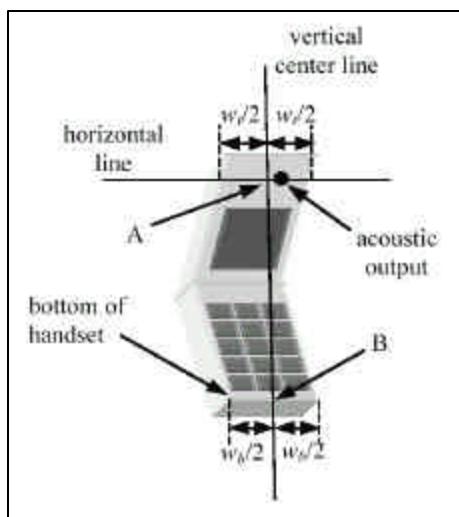
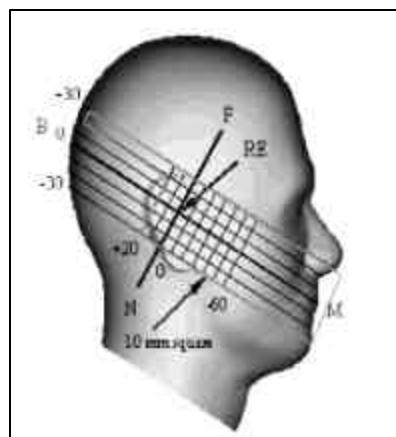


Figure – Phone position 1, "cheek" or "touch" position. The reference points for the right ear (RE), left ear (LE) and mouth (M), which define the reference plane for phone positioning, are indicated. The shoulders are shown for illustration purposes only.

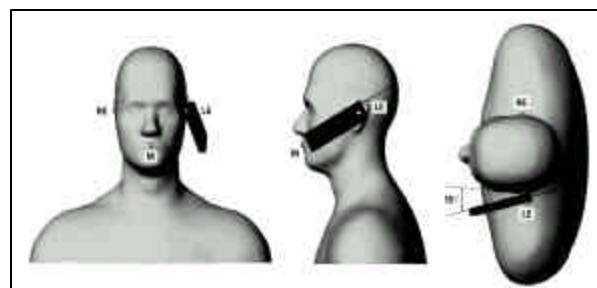
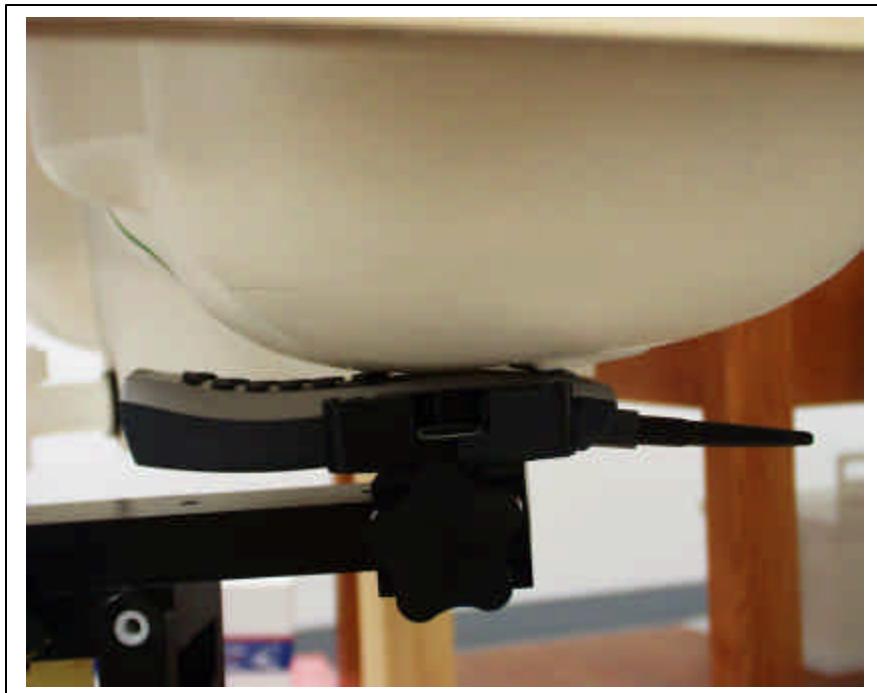


Figure – Phone position 2, "tilted position." The reference points for the right ear (RE), left ear (LE) and mouth (M), which define the reference plane for phone positioning, are indicated. The shoulders are shown for illustration purposes only.

**EUT SET-UP PHOTOS**

LEFT HEAD – TOUCH POSITION



LEFT HEAD – TILT POSITION



**SET-UP PHOTOS (Continued)**

RIGHT HEAD – TOUCH POSITION

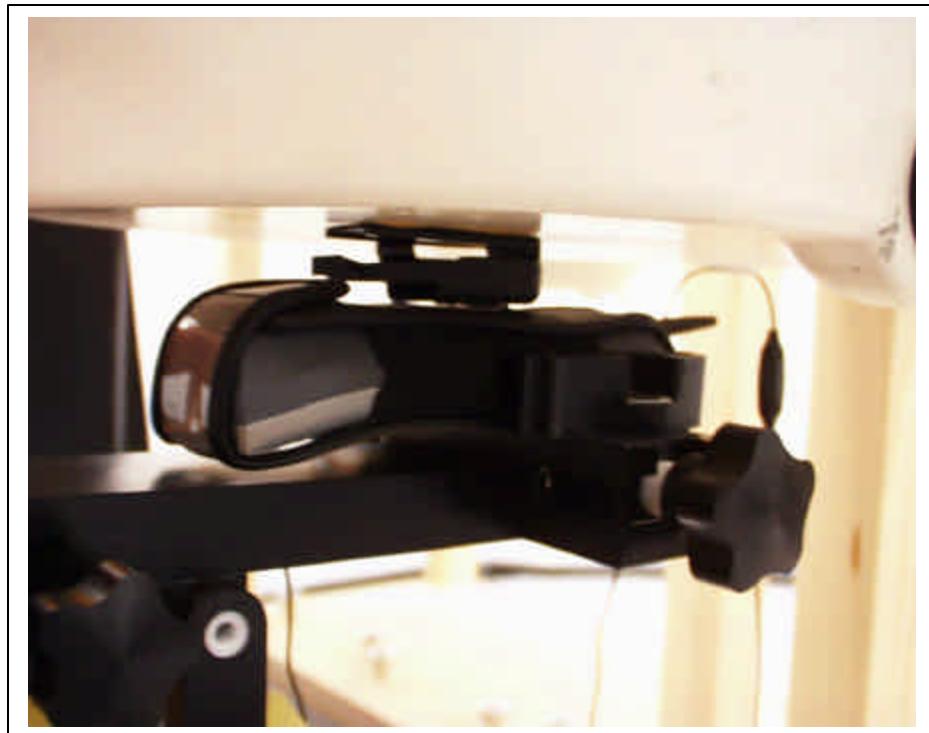


RIGHT HEAD – TILT POSITION



**SET-UP PHOTOS (Continued)**

FLAT POSITION



**Note:** The belt clip was attached to EUT, and the clip is positioned against the phantom surface as show above.

The Ear-Microphone was connected to the EUT to simulate the operation in a body-worn configuration

### 3.4. MEASUREMENT UNCERTAINTY

#### Uncertainty Budget per IEEE P1528

Error Description	Uncertainty value ±%	Probability distribution	divisor	$e_i$ 1g	Standard unc. (1g) ±%	$v_i$ or $v_{eff}$
<b>Measurement System</b>						
Probe calibration	± 4.8	normal	1	1	± 4.8	∞
Axial isotropy of the probe	± 4.7	rectangular	$\sqrt{3}$	$(1-c_p)^{1/2}$	± 1.9	∞
Sph. isotropy of the probe	± 9.6	rectangular	$\sqrt{3}$	$(e_p)^{1/2}$	± 3.9	∞
Probe linearity	± 4.7	rectangular	$\sqrt{3}$	1	± 2.7	∞
Detection limit	± 1.0	rectangular	$\sqrt{3}$	1	± 0.6	∞
Boundary effects	± 8.3	rectangular	$\sqrt{3}$	1	± 4.8	∞
Readout electronics	± 1.0	normal	1	1	± 1.0	∞
Response time	± 0.8	rectangular	$\sqrt{3}$	1	± 0.5	∞
Integration time	± 1.4	rectangular	$\sqrt{3}$	1	± 0.8	∞
Mech. constrains of robot	± 0.4	rectangular	$\sqrt{3}$	1	± 0.2	∞
Probe positioning	± 2.9	rectangular	$\sqrt{3}$	1	± 1.7	∞
Extrap. and integration	± 3.9	rectangular	$\sqrt{3}$	1	± 2.3	∞
RF ambient conditions	± 0.75	rectangular	$\sqrt{3}$	1	± 0.43	∞
<b>Test Sample Related</b>						
Device positioning	± 2.23	normal	1	1	± 2.23	11
Device holder uncertainty	± 5.0	normal	1	1	± 5.0	7
Power drift	± 5.0	rectangular	$\sqrt{3}$	1	± 2.9	∞
<b>Phantom and Setup</b>						
Phantom uncertainty	± 4.0	rectangular	$\sqrt{3}$	1	± 2.3	∞
Liquid conductivity (target)	± 5.0	rectangular	$\sqrt{3}$	0.6	± 1.7	∞
Liquid conductivity (meas.)	± 10.0/5.0	rectangular	$\sqrt{3}$	0.6	± 3.5/1.73	∞
Liquid permittivity (target)	± 5.0	rectangular	$\sqrt{3}$	0.6	± 1.7	∞
Liquid permittivity (meas.)	± 5.0	rectangular	$\sqrt{3}$	0.6	± 1.7	∞
Combined Standard Uncertainty					± 12.14/11.76	
Coverage Factor for 95%	$k_p = 2$					
Expanded Standard Uncertainty					± 24.29/23.51	

Note: Due to the different spec for liquid above 2G (+/- 10%) and below the 2G (+/- 5%), the uncertainty budget is different accordingly.

### 4. EUT TUNE-UP PROCEDURE

The following procedures had been used to prepare the EUT for the SAR test.

- The client supplied a special driving program to program the EUT to continually transmit the specified maximum power, and also changed the channel frequency.
- The conducted power was measured at high, middle and low channel before and after the SAR measurement.

## 5. EVALUATION PROCEDURE

### Simulated Tissue Liquid Parameter confirmation

The dielectric parameters were checked prior to assessment using the HP85070A dielectric probe kit. The dielectric parameters measured are reported in each correspondent section.

### IEEE SCC-34/SC-2 P1528 recommended Tissue Dielectric Parameters

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in P1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in P1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations and extrapolated according to the head parameters specified in P1528.

Target Frequency	Head		Body	
	(MHz)	$\epsilon_r$	$\sigma$ (S/m)	$\epsilon_r$
150	52.3	0.76	61.9	0.80
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	0.98	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800-2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73
5800	45.3	5.27	48.2	6.00

( $\epsilon_r$  = relative permittivity,  $\sigma$  = conductivity and  $\rho = 1000 \text{ kg/m}^3$ )

### System Accuracy Verification

Prior to the assessment, the system validation kit was used to test whether the system was operating within its specifications of  $\pm 10\%$ . The validation results are tabulated below. And also the corresponding SAR plot is attached as well in the SAR plots files.

### IEEE P1528 Recommended Reference Value

Frequency (MHz)	1 g SAR	10 g SAR	Local SAR at surface (Above feed point)	Local SAR at surface (y=2cm offset from feed point)
300	3.0	2.0	4.4	2.1
450	4.9	3.3	7.2	3.2
835	9.5	6.2	14.1	4.9
900	10.8	6.9	16.4	5.4
1450	29.0	16.0	50.2	6.5
1800	38.1	19.8	69.5	6.8
1900	39.7	20.5	72.1	6.6
2000	41.1	21.1	74.6	6.5
2450	52.4	24.0	104.2	7.7
3000	63.8	25.7	140.2	9.5

## 5.1. SYSTEM VALIDATION RESULTS

Measured Date: October 16, 2002

Ambient conditions - Ambient temperature: 23°C; Relative humidity: 58 %						
System Validation Dipole: D2450V2 S/N: 706				Depth of liquid: 15.1 cm		
Liquid	Liquid Temp [°C]	Parameters	Target Value	Measured Value	Deviation [%]	Limit [%]
Head 2450MHz	21.3	$\epsilon_r$	39.2	38.4	-2.04	$\pm 5$
		$\sigma$	1.80	1.93	7.22	$\pm 10$
	21.3	1 g SAR	52.4	56.8	8.40	$\pm 10$

Note: Please refer to Attachment for the result presentation in plot format.

## 5.2. SAR EVALUATION PROCEDURE

The evaluation was performed with the following procedure:

**Step 1:** Measurement of the SAR value at a fixed location above the ear point or central position was used as a reference value for assessing the power drop.

**Step 2:** The SAR distribution at the exposed side of the head was measured at a distance of 3.9 mm from the inner surface of the shell. The area covered the entire dimension of the head or EUT and the horizontal grid spacing was 20 mm x 20 mm. Based on these data, the area of the maximum absorption was determined by spline interpolation.

**Step 3:** Around this point, a volume of 32 mm x 32 mm x 34 mm was assessed by measuring 5 x 5 x 7 points. On the basis of this data set, the spatial peak SAR value was evaluated under the following procedure:

1. The data at the surface were extrapolated, since the center of the dipoles is 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.2 mm. The extrapolation was based on a least square algorithm [11]. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.
2. The maximum interpolated value was searched with a straightforward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1 g or 10 g) were computed by the 3D-Spline interpolation algorithm. The 3D-Spline is composed of three one-dimensional splines with the "Not a knot"-condition (in x, y and z-directions) [11], [12]. The volume was integrated with the trapezoidal-algorithm. One thousand points (10 x 10 x 10) were interpolated to calculate the average.
3. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.

**Step 4:** Re-measurement of the SAR value at the same location as in Step 1. If the value changed by more than 5%, the evaluation was repeated.

### 5.3. EXPOSURE LIMIT

(A). Limits for Occupational/Controlled Exposure (W/kg)

Whole-Body	Partial-Body	Hands, Wrists, Feet and Ankles
0.4	8.0	20.0

(B). Limits for General Population/Uncontrolled Exposure (W/kg)

Whole-Body	Partial-Body	Hands, Wrists, Feet and Ankles
0.08	1.6	4.0

NOTE: **Whole-Body SAR** is averaged over the entire body, **partial-body SAR** is averaged over any 1 gram of tissue defined as a tissue volume in the shape of a cube. **SAR for hands, wrists, feet and ankles** is averaged over any 10 grams of tissue defined as a tissue volume in the shape of a cube.

**Population/Uncontrolled Environments:** are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

**Occupational/Controlled Environments:** are defined as locations where there is exposure that may be incurred by people who are aware of the potential for exposure, (i.e. as a result of employment or occupation).

**NOTE**  
**GENERAL POPULATION/UNCONTROLLED EXPOSURE**  
**PARTIAL BODY LIMIT**  
**1.6 mW/g**

## 6. MEASUREMENT RESULTS

LIQUID VERIFY				Measured date: <u>October 16, 2002</u>				
<b>Ambient Conditions</b> - Ambient temperature: <u>23°C</u> ; Relative humidity: <u>56 %</u>								
Liquid	Temp [°C]	Parameters	Target Value	Measured	Deviation [%]	Limit [%]		
<b>Head 2450 MHz</b>	21.3	$\epsilon_r$	39.2	38.4	-2.04	$\pm 10$		
		$\sigma$	1.80	1.93	7.22	$\pm 10$		
<b>SAR MEASUREMENT</b>								
Model Name: <u>EP-236</u> , Duty cycle: <u>8 %</u> , Crest factor: <u>13</u>								
Phantom Section: <u>Left Head - Touch position</u>				Depth of liquid: <u>15.1 cm</u>				
Frequency		EUT Set-up conditions		Conducted power [dBm]		Liquid Temp [°C]	<b>SAR</b> (W/kg)	Limit (W/kg)
Channel	MHz	Antenna	EUT Position	Before	After			
Low	2401.06	Fixed	Touch	16.97	16.75	21.3	0.158	1.6
Mid	2441.66	Fixed	Touch	17.48	17.34	21.3	0.292	1.6
High	2479.68	Fixed	Touch	17.49	17.35	21.3	<b>0.317</b>	1.6
Phantom Section: <u>Left Head - Tilt position</u>								
Low	2401.06	Fixed	Tilt	16.97	16.75	21.3	0.151	1.6
Mid	2441.66	Fixed	Tilt	17.48	17.34	21.3	0.246	1.6
High	2479.68	Fixed	Tilt	17.49	17.35	21.3	<b>0.272</b>	1.6
Phantom Section: <u>Right head - Touch position</u>								
Low	2401.06	Fixed	Touch	16.97	16.75	21.3	0.109	1.6
Mid	2441.66	Fixed	Touch	17.48	17.34	21.3	0.176	1.6
High	2479.68	Fixed	Touch	17.49	17.35	21.3	<b>0.183</b>	1.6
Phantom Section: <u>Right head - Tilt position</u>								
Low	2401.06	Fixed	Tilt	16.97	16.75	21.3	0.170	1.6
Mid	2441.66	Fixed	Tilt	17.48	17.34	21.3	0.273	1.6
High	2479.68	Fixed	Tilt	17.49	17.35	21.3	<b>0.307</b>	1.6
Note (s): Please refer to attachment for the result presentation in plot format.								

**MEASUREMENT RESULTS (COUNTINUED)**

<b>LIQUID VERIFY</b>						Measured date: <u>October 17, 2002</u>				
<b>Ambient Conditions</b> - Ambient temperature: <u>23.1°C</u> ; Relative Humidity: <u>56%</u>										
Liquid	Temp. [°C]	Parameters	Target Value	Measured	Deviation [%]	Limit [%]				
<b>Muscle</b> <b>2450 MHz</b>	21.3	$\epsilon_r$	52.7	50.82	3.57	$\pm 10$				
		$\sigma$	1.95	2.019	-3.54	$\pm 10$				
<b>SAR MEASUREMENT</b>										
Model: <u>EP-236</u> , Duty cycle: <u>8 %</u> , Crest factor: <u>13</u>										
Phantom Section: Flat (Body) position				Depth of liquid: <u>15.1 cm</u>						
Frequency		EUT Set-up conditions		Conducted power [dBm]		Liquid Temp [°C]	SAR (W/kg)			
Channel	MHz	Antenna	Sep. [mm]	Before	After		Limit (W/kg)			
Low	2401.06	Fixed	With clip	16.97	16.75	21.1	0.0697			
Mid	2441.66	Fixed	With clip	17.48	17.34	21.1	0.0961			
High	2479.68	Fixed	With clip	17.49	17.35	21.1	<b>0.113</b>			
Note (s): Please refer to attachment for the result presentation in plot format.										

**7. EUT PHOTOS****EXTERNAL PHOTOS**

## 8. EQUIPMENTS LIST & CALIBRATION INFORMATION

Name of Equipment	Manufacturer	Type/Model	Serial Number	Calibration	
				last cal.	due date
S-Parameter Network Analyzer	Agilent	8753ES	MY40001647	8/6/02	8/6/03
Electronic Probe kit	Hewlett Packard	85070A	N/A	N/A	N/A
3.5 mm Calibration Kit	Agilent	85033D	3423A07200	8/6/02	8/6/03
Power Meter	Rohde & Schwarz	NRVD	842093/017	1/21/02	1/21/03
Power Sensor	Rohde & Schwarz	NRV-Z51	841275/013	1/21/02	1/21/03
Universal Radio Communication Tester	Rohde & Schwarz	CMU 200	838114/032	11/20/01	11/20/02
Amplifier	Mini-Circuit	ZHL-42W	D072701-5	N/A	N/A
DC Power Generator	Kenwood	PA36-3A	7060074	N/A	N/A
Data Acquisition Electronics (DAE)	SPEAG	DAE3 V1	500	2/26/02	2/26/03
Dosimetric E-Field Probe	SPEAG	ET3DV6	1578	2/22/01	2/22/03
450 MHz System Validation Dipole	SPEAG	D450V2	1003	4/5/02	4/19/04
900 MHz System Validation Dipole	SPEAG	D900V2	108	4/17/01	4/17/03
1800 MHz System Validation Dipole	SPEAG	D1800V2	294	4/19/01	4/19/03
Probe Alignment Unit	SPEAG	LB (V2)	261	N/A	N/A
Robot	Staubli	RX90BL	F00/5H31A1/A/01	N/A	N/A
Generic Twin Phantom	SPEAG	N/A	N/A	N/A	N/A
SAM Phantom	SPEAG	N/A	N/A	N/A	N/A
Devices Holder	SPEAG	N/A	N/A	N/A	N/A
Head 450 MHz	CCS	H450A	N/A	Daily	N/A
Muscle 450 MHz	CCS	M450A	N/A	Daily	N/A
Head 835 MHz	CCS	H835A	N/A	Daily	N/A
Muscle 835 MHz	CCS	M835A	N/A	Daily	N/A
Head 900 MHz	CCS	H900A	N/A	Daily	N/A
Muscle 900 MHz	CCS	M900A	N/A	Daily	N/A
Head 1800 MHz	CCS	H1800A	N/A	Daily	N/A
Muscle 1800 MHz	CCS	M1800A	N/A	Daily	N/A
Head 1900 MHz	CCS	H1900A	N/A	Daily	N/A
Muscle 1900 MHz	CCS	M1900A	N/A	Daily	N/A
Head 2450 MHz	CCS	H2450A	N/A	Daily	N/A
Muscle 2450 MHz	CCS	M2450A	N/A	Daily	N/A

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**10. ATTACHMANTS**

Exhibit	Content	No. of page (s)
1	System Validation Plots	2
2	SAR Test Plots	20
3	Dosimetric E-Field Probe (ET3DV6, S/N: 1578)	14
4	System Validation Dipole (D2450V2 S/N: 706)	7

**End of Report**