

SAR Test Report

of

Product Name

Super Speed N Wireless USB Adapter

Model

WL-160N

Applied by:

ASUSTek Computer Inc.
4Fl., No. 150, Li-Te Rd., Peitou,
Taipei,
Taiwan

Test Performed by:

International Standards Laboratory
No. 120, Lane 180, San Ho Tsuen, Hsin Ho Rd.
Lung-Tan Hsiang, Tao Yuan County 325
Taiwan, R.O.C.
Tel:(03)407-1718 Fax:(03)407-1738

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ISL-T10-R4-14

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1. General

1.1 Certification of Accuracy of Test Data

Standards: FCC Oet65 Supplement C June 2001
IEEE Std. 1528-2003
47CFR § 2.1093

Equipment Tested: Super Speed N Wireless USB Adapter

Model: WL-160N

Applied by ASUSTek Computer Inc.

Sample received Date: 2007/03/09

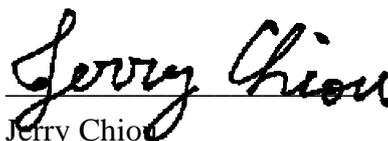
Final test Date : refer to the date of test data

Report Engineer: Ivy Yang

Test Site: SAR test site

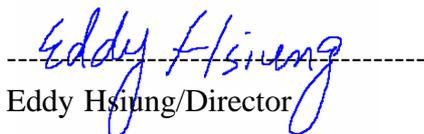
Test Summary **Body Maximum SAR Measurement (1g)**
802.11b (2450 MHz): 1.343 W/g
802.11g (2450 MHz): 1.39 W/g
802.11n (2450 MHz . Data Rate 20M): 1.233 W/g
802.11n (2450 MHz . Data Rate 40M): 1.317 W/g

Test Engineer:


Jerry Chio

All the tests in this report have been performed and recorded in accordance with the standards described above and performed by an independent test lab, International Standards Laboratory. The test results contained in this report accurately represent the measurements of the characteristics and the energy generated by sample equipment under test at the time of the test. The sample equipment tested as described in this report is in compliance with the limits of above standards.

Approve & Signature


Eddy Hsiung/Director

Test results given in this report apply only to the specific sample(s) tested under stated test conditions. This report shall not be reproduced other than in full without the explicit written consent of ISL. This report totally contains 24 pages, including 1 cover page, 1 contents page, and 22 pages for the test description. This report must not be use to claim product endorsement by NVLAP, NIST, any agency of the federal government.

2. Description of Equipment Under Test (EUT)

| | |
|-------------------------------|--|
| Product Name | Super Speed N Wireless USB Adapter |
| Model No. | WL-160N |
| Brand | ASUS |
| FCC ID: | MSQWL160N |
| TX Frequency | 2412 MHz ~ 2462 MHz |
| Type of Modulation | 802.11b: DSSS 802.11g: OFDM 802.11n: OFDM |
| Max. Output Power (Conducted) | 802.11b: 18.82 dBm 802.11g: 21.36 dBm 802.11n(20M): 24.33 dBm 802.11n(40M): 24.74 dBm |
| Antenna Peak Gain | 3.43dBi |
| Transfer Rate | 802.11b: 1~11Mbps 802.11g: 6~54Mbps 802.11n: 20,40Mbps |
| Power Type | From Notebook PC |
| Antenna Type | Internal |
| Device Category | Portable |
| RF Exposure Environment | Uncontrolled |

2.1 Test Environment

Ambient conditions of test site:

| Item | Required | Actual |
|------------------|----------|--------|
| Temperature (°C) | 18-25 | 21.5 |
| Humidity (%RH) | 30-70 | 48 |

3. SAR Measurement System

3.1 ALSAS-10U System Description

ALSAS-10-U is fully compliant with the technical and scientific requirements of IEEE 1528, IEC 62209, CENELEC, ARIB, ACA, and the Federal Communications Commission. The system comprises of a six axes articulated robot which utilizes a dedicated controller.

ALSAS-10U uses the latest methodologies and FDTD modeling to provide a platform which is repeatable with minimum uncertainty.

3.1.1 Applications

Predefined measurement procedures compliant with the guidelines of CENELEC, IEEE, IEC, FCC, etc are utilized during the assessment for the device. Automatic detection for all SAR maxima are embedded within the core architecture for the system, ensuring that peak locations used for centering the zoom scan are within a 1mm resolution and a 0.05mm repeatable position. System operation range currently available up-to 6 GHz in simulated tissue.



3.1.2 Area Scans

Area scans are defined prior to the measurement process being executed with a user defined variable spacing between each measurement point (integral) allowing low uncertainty measurements to be conducted. Scans defined for FCC applications utilize a 10mm² step integral, with 1mm interpolation used to locate the peak SAR area used for zoom scan assessments.

Where the system identifies multiple SAR peaks (which are within 25% of peak value) the system will provide the user with the option of assessing each peak location individually for zoom scan averaging.

3.1.3 Zoom Scan (Cube Scan Averaging)

The averaging zoom scan volume utilized in the ALSAS-10U software is in the shape of a cube and the side dimension of a 1 g or 10 g mass is dependent on the density of the liquid representing the simulated tissue. A density of 1000 kg/m³ is used to represent the head and body tissue density and not the phantom liquid density, in order to be consistent with the definition of the liquid dielectric properties, i.e. the side length of the 1 g cube is 10mm, with the side length of the 10 g cube 21,5mm.

When the cube intersects with the surface of the phantom, it is oriented so that 3 vertices touch the surface of the shell or the center of a face is tangent to the surface. The face of the cube closest to the surface is modified in order to conform to the tangent surface.

The zoom scan integer steps can be user defined so as to reduce uncertainty, but normal practice for typical test applications (including FCC) utilize a physical step of 5x5x8 (8mmx8mmx5mm) providing a volume of 32mm in the X & Y axis, and 35mm in the Z axis.

3.1.4 ALSAS-10U Interpolation and Extrapolation Uncertainty

The overall uncertainty for the methodology and algorithms the used during the SAR calculation was evaluated using the data from IEEE 1528 based on the example f3 algorithm:

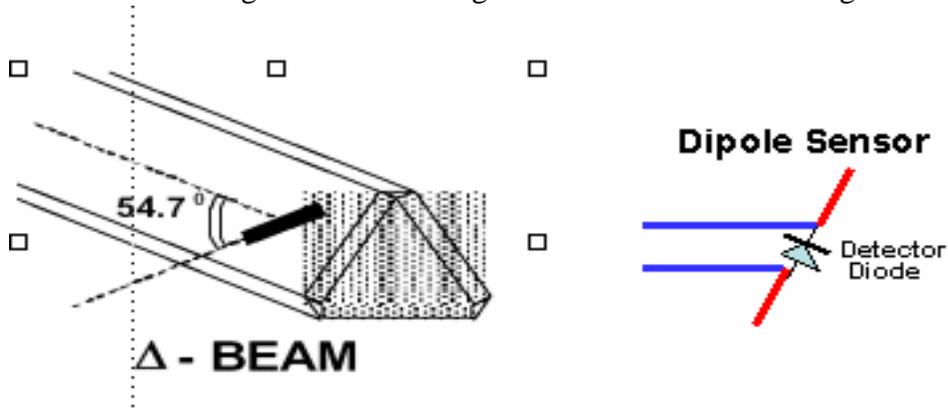
$$f_3(x, y, z) = A \frac{a^2}{\frac{a^2}{4} + x'^2 + y'^2} \cdot \left(e^{-\frac{2z}{a}} + \frac{a^2}{2(a + 2z)^2} \right)$$

3.2 Isotropic E-Field Probe

The isotropic E-Field probe has been fully calibrated and assessed for isotropicity, and boundary effect within a controlled environment. Depending on the frequency for which the probe is calibrated the method utilized for calibration will change. A number of methods is used for calibrating probes, and these are outlined in the table below:

| Calibration Frequency | Air Calibration | Tissue Calibration |
|-----------------------|-----------------|--------------------|
| 835MHz | TEM Cell | Temperature |
| 900MHz | TEM Cell | Temperature |
| 1800MHz | TEM Cell | Temperature |
| 1900MHz | TEM Cell | Temperature |
| 2450MHz | Waveguide | Temperature |
| 5200MHz | Waveguide | Temperature |
| 5800MHz | Waveguide | Temperature |

The E-Field probe utilizes a triangular sensor arrangement as detailed in the diagram below:



SAR is assessed with a calibrated probe which moves at a default height of 5mm from the center of the diode, which is mounted to the sensor, to the phantom surface (in the Z Axis). The 5mm offset height has been selected so as to minimize any resultant boundary effect due to the probe being in close proximity to the phantom surface.

The following algorithm is an example of the function used by the system for linearization of the output from the probe when measuring complex modulation schemes.

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

3.2.1 Isotropic E-Field Probe Specification

| | |
|-------------------------------|--|
| Calibration in Air | Frequency Dependent Below 2GHz Calibration in air performed in a TEM Cell Above 2GHz Calibration in air performed in waveguide |
| Sensitivity | 0.70 $\mu\text{V}/(\text{V}/\text{m})^2$ to 0.85 $\mu\text{V}/(\text{V}/\text{m})^2$ |
| Dynamic Range | 0.0005 W/kg to 100W/kg |
| Isotropic Response | Better than 0.2dB |
| Diode Compression point (DCP) | Calibration for Specific Frequency |
| Probe Tip Radius | < 5mm |
| Sensor Offset | 1.56 (+/- 0.02mm) |
| Probe Length | 290mm |
| Video Bandwidth | @ 500 Hz: 1dB @ 1.02 KHz: 3dB |
| Boundary Effect | Less than 2% for distance greater than 2.4mm |
| Spatial Resolution | Diameter less than 5mm Compliant with Standards |

3.3 Boundary Detection Unit and Probe Mounting Device

ALSAS-10U incorporates a boundary detection unit with a sensitivity of 0.05mm for detecting all types of surfaces. The robust design allows for detection during probe tilt (probe normalize) exercises, and utilizes a second stage emergency stop. The signal electronics are fed directly into the robot controller for high accuracy surface detection in lateral and axial detection modes (X, Y, & Z).

The probe is mounted directly onto the Boundary Detection unit for accurate tooling and displacement calculations controlled by the robot kinematics. The probe is connect to an isolated probe interconnect where the output stage of the probe is fed directly into the amplifier stage of the Daq-Paq.

3.4 Daq-Paq (Analog to Digital Electronics)

ALSAS-10U incorporates a fully calibrated Daq-Paq (analog to digital conversion system) which has a 4 channel input stage, sent via a 2 stage auto-set amplifier module. The input signal is amplified accordingly so as to offer a dynamic range from 5µV to 800mV. Integration of the fields measured is carried out at board level utilizing a Co-Processor which then sends the measured fields down into the main computational module in digitized form via an RS232 communications port. Probe linearity and duty cycle compensation is carried out within the main Daq-Paq module.

| | |
|--------------------------|---|
| ADC | 12 Bit |
| Amplifier Range | 20mV to 200mV and 150mV to 800mV |
| Field Integration | Local Co-Processor utilizing proprietary integration algorithms |
| Number of Input Channels | 4 in total 3 dedicated and 1 spare |
| Communication | Packet data via RS232 |

3.5 Axis Articulated Robot



ALSAS-10U utilizes a six axis articulated robot, which is controlled using a Pentium based real-time movement controller. The movement kinematics engine utilizes proprietary (Thermo CRS) interpolation and extrapolation algorithms, which allow full freedom of movement for each of the six joints within the working envelope. Utilization of joint 6 allows for full probe rotation with a tolerance better than 0.05mm around the central axis.

| | |
|-------------------------------|-----------------------------------|
| Robot/Controller Manufacturer | Thermo CRS |
| Number of Axis | Six independently controlled axis |
| Positioning Repeatability | 0.05mm |
| Controller Type | Single phase Pentium based C500C |
| Robot Reach | 710mm |
| Communication | RS232 and LAN compatible |

3.6 ALSAS Universal Workstation

ALSAS Universal workstation allows for repeatability and fast adaptability. It allows users to do calibration, testing and measurements using different types of phantoms with one set up, which significantly speeds up the measurement process.

3.7 Universal Device Positioner

The universal device positioner allows complete freedom of movement of the EUT. Developed to hold a EUT in a free-space scenario any additional loading attributable to the material used in the construction of the positioner has been eliminated. Repeatability has been enhanced through the linear scales which form the design used to indicate positioning for any given test scenario in all major axes. A 15° tilt indicator is included for the of aid cheek to tilt movements for head SAR analysis. Overall uncertainty for measurements have been reduced due to the design of the Universal device positioner, which allows positioning of a device in as near to a free-space scenario as possible, and by providing the means for complete repeatability.

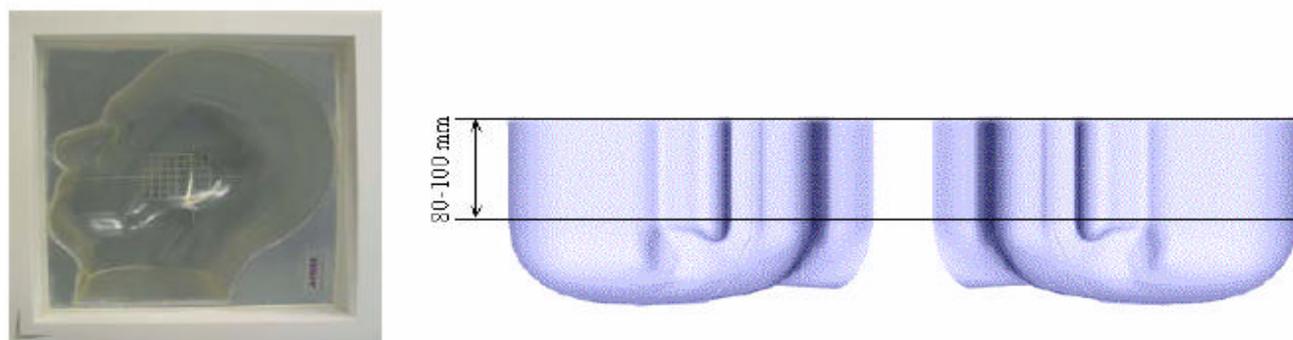


3.8 Phantom Types

The ALSAS-10U allows the integration of multiple phantom types. SAM Phantoms fully compliant with IEEE 1528, Universal Phantom, and Universal Flat.

APREL SAM Phantoms

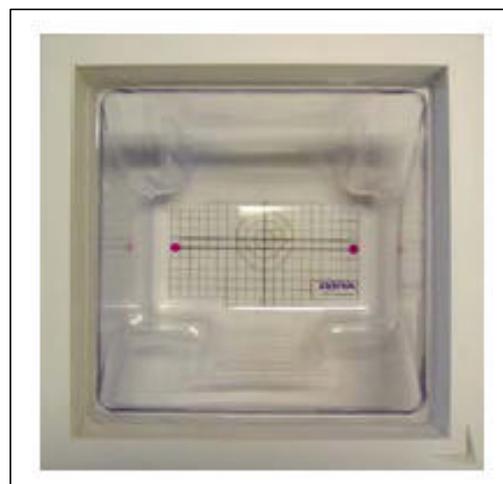
The SAM phantoms developed using the IEEE SAM CAD file. They are fully compliant with the requirements for both IEEE 1528 and FCC Supplement C. Both the left and right SAM phantoms are interchangeable, transparent and include the IEEE 1528 grid with visible NF and MB lines.



3.8.1 APREL Laboratories Universal Phantom

The Universal Phantom is used on the ALSAS-10U as a system validation phantom. The Universal Phantom has been fully validated both experimentally from 800MHz to 6GHz and numerically using XFDTD numerical software. The shell thickness is 2mm overall, with a 4mm spacer located at the NF/MB intersection providing an overall thickness of 6mm in line with the requirements of IEEE-1528.

The design allows for fast and accurate measurements, of handsets, by allowing the conservative SAR to be evaluated at on frequency for both left and right head experiments in one measurement.



4. Tissue Simulating Liquid

4.1 The composition of the tissue simulating liquid

| INGREDIENT (% Weight) | 2450MHz Head | 2450MHz Body |
|--------------------------|-----------------|-----------------|
| Water | 46.7 | 73.2 |
| Salt | 0.00 | 0.40 |
| Sugar | 0.00 | 0.00 |
| HEC | 0.00 | 0.00 |
| Preventol | 0.00 | 0.00 |
| DGBE | 53.3 | 26.76 |

4.2 Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using Agilent Dielectric Probe Kit and Agilent E5071B Vector Network Analyzer

| Head Tissue Simulant Measurement | | | | |
|----------------------------------|---------------------------------|------------------------|---------------------|----------------------|
| Frequency [MHz] | Description | Dielectric Parameters | | Tissue Temp. [°C] |
| | | ϵ_r | σ [s/m] | |
| 2450MHz | Reference result ± 5% window | 39.2 37.24 to 41.16 | 1.8 1.71 to 1.89 | N/A |
| | 19-Mar-2007 | 39.81 | 1.77 | 21.4 |

| Body Tissue Simulant Measurement | | | | |
|----------------------------------|----------------------------------|--------------------------|--------------------------|----------------------|
| Frequency [MHz] | Description/ Calibration date | Dielectric Parameters | | Tissue Temp. [°C] |
| | | ϵ_r | σ [s/m] | |
| 2450MHz | Reference result ± 5% window | 52.7 50.065 to 55.335 | 1.95 1.8525 to 2.0475 | N/A |
| | 19-Mar-2007 | 53.66 | 18.9 | 21.4 |

4.3 Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in P1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in P1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations described in Reference [12] and extrapolated according to the head parameters specified in P1528.

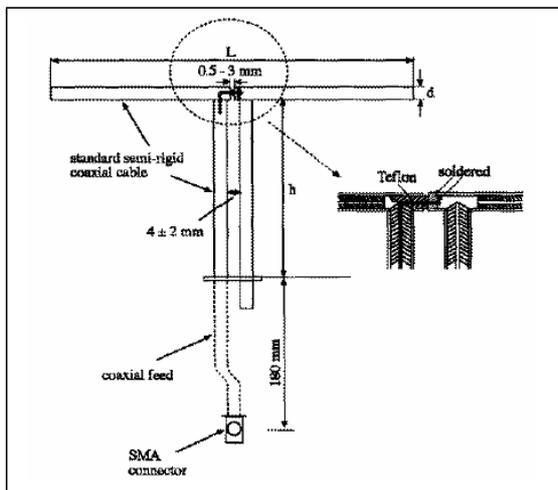
| Target Frequency (MHz) | Head | | Body | |
|---------------------------|--------------|----------------|--------------|----------------|
| | ϵ_r | σ (S/m) | ϵ_r | σ (S/m) |
| 150 | 52.3 | 0.76 | 61.9 | 0.80 |
| 300 | 45.3 | 0.87 | 58.2 | 0.92 |
| 450 | 43.5 | 0.87 | 56.7 | 0.94 |
| 835 | 41.5 | 0.90 | 55.2 | 0.97 |
| 900 | 41.5 | 0.97 | 55.0 | 1.05 |
| 915 | 41.5 | 0.98 | 55.0 | 1.06 |
| 1450 | 40.5 | 1.20 | 54.0 | 1.30 |
| 1610 | 40.3 | 1.29 | 53.8 | 1.40 |
| 1800 – 2000 | 40.0 | 1.40 | 53.3 | 1.52 |
| 2450 | 39.2 | 1.80 | 52.7 | 1.95 |
| 3000 | 38.5 | 2.40 | 52.0 | 2.73 |
| 5800 | 35.3 | 5.27 | 48.2 | 6.00 |

(ϵ_r = relative permittivity, σ = conductivity and $\rho = 1000 \text{ kg/m}^3$)

5. SAR Measurement Procedure

5.1 SAR System Validation

5.1.1 Validation Dipoles



The dipoles used is based on the IEEE-1528 standard, and is complied with mechanical and electrical specifications in line with the requirements of both IEEE and FCC Supplement C. the table below provides details for the mechanical and electrical specifications for the dipoles.

| * | Frequency | L (mm) | h (mm) | d (mm) |
|---|-----------|--------|--------|--------|
| | 835MHz | 161.0 | 89.8 | 3.6 |
| | 900MHz | 149.0 | 83.3 | 3.6 |
| | 1800MHz | 72.0 | 41.7 | 3.6 |
| | 1900MHz | 68.0 | 39.5 | 3.6 |
| v | 2450MHz | 51.5 | 30.4 | 3.6 |
| | 5200MHz | 23.6 | 14.0 | 3.6 |
| | 5800MHz | 21.6 | 12.6 | 3.6 |

*Note: "V" indicates Frequency used of EUT

5.1.2 Validation Result

System Performance Check at 2450MHz

Validation Kit: ASL-D-2450-S-2

| Frequency [MHz] | Description | SAR [w/kg] 1g | SAR [w/kg] 10g | Tissue Temp. [°C] |
|-----------------|---------------------------------|------------------------|--------------------|-------------------|
| 2450 MHz | Reference result ± 5% window | 52.4 49.78 to 55.02 | 24 22.8 to 25.2 | N/A |
| | 03/19/2007 | 52.024 | 24.981 | 21.4 |

Note: All SAR values are 1W forward power.

5.2 Arrangement Assessment Setup

5.2.1 Test Positions of Device Relative to Head

This specifies exactly two test positions for the handset against the head phantom, the “cheek” position and the “tilted” position. The handset should be tested in both positions on the left and right sides of the SAM phantom. If the handset construction is such that it cannot be positioned using the handset positioning procedures described in 4.2.2.1 and 4.2.2.2 to represent normal use conditions (e.g., asymmetric handset), alternative alignment procedures should be considered with details provided in the test report.

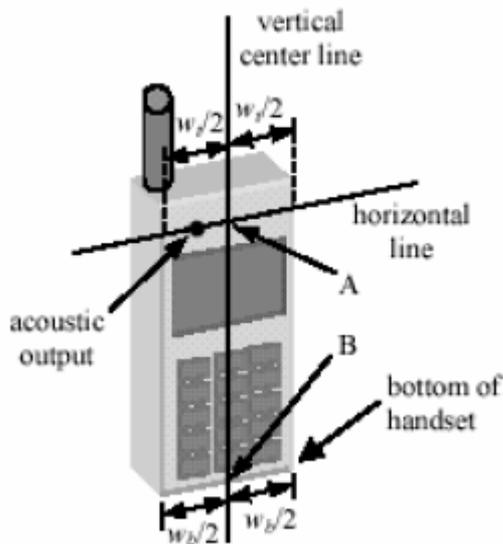


Figure 4.1a Fixed Case

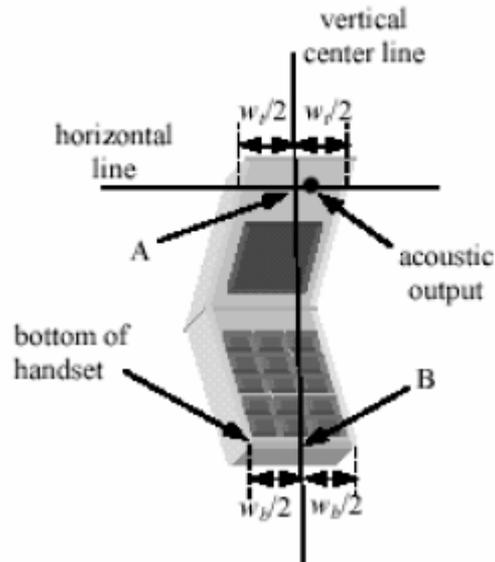


Figure 4.1b Clam Shell

5.2.2 Definition of the “Cheek” Position

The “cheek” position is defined as follows:

- Ready the handset for talk operation, if necessary. For example, for handsets with a cover piece, open the cover. (If the handset can also be used with the cover closed both configurations must be tested.)
- Define two imaginary lines on the handset: the vertical centerline and the horizontal line. The vertical centerline passes through two points on the front side of the handset: the midpoint of the width w_t of the handset at the level of the acoustic output (point A on Figures 4.1a and 4.1b), and the midpoint of the width w_b of the bottom of the handset (point B). The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output (see Figure 4.1a). The two lines intersect at point A. Note that for many handsets, point A coincides with the center of the acoustic output. However, the acoustic output may be located elsewhere on the horizontal line. Also note that the vertical centerline is not necessarily parallel to the front face of the handset (see Figure 4.1b), especially for clamshell handsets, handsets with flip pieces, and other irregularly-shaped handsets.

- c. Position the handset close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure 4.2), such that the plane defined by the vertical center line and the horizontal line of the handset is approximately parallel to the sagittal plane of the phantom.
- d. Translate the handset towards the phantom along the line passing through RE and LE until the handset touches the pinna.
- e. While maintaining the handset in this plane, rotate it around the LE-RE line until the vertical centerline is in the plane normal to MB-NF including the line MB (called the reference plane).
- f. Rotate the handset around the vertical centerline until the handset (horizontal line) is symmetrical with respect to the line NF.
- g. While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE and maintaining the handset contact with the pinna, rotate the handset about the line NF until any point on the handset is in contact with a phantom point below the pinna (cheek). See Figure 4.2 the physical angles of rotation should be noted.

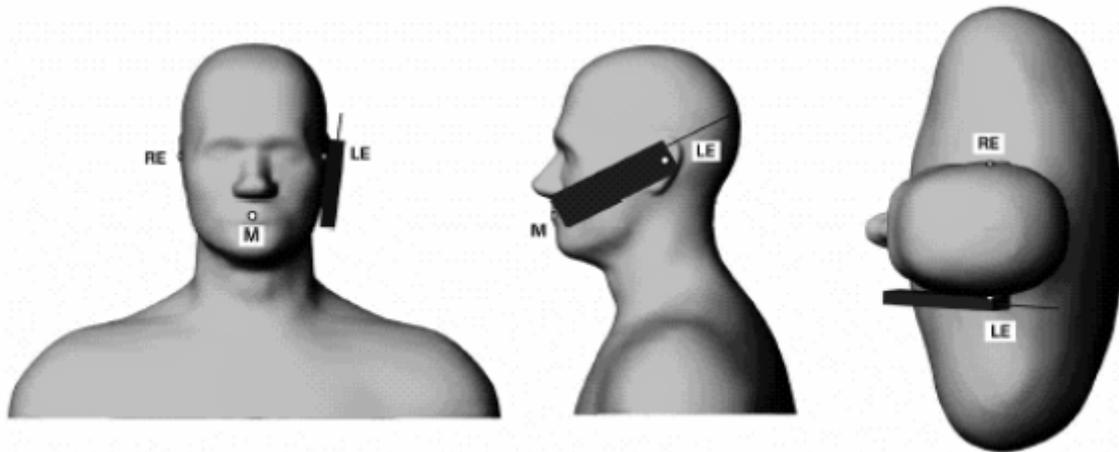


Figure 4.2 – Phone position 1, “cheek” or “touch” position.

5.2.3 Definition of the “Tilted” Position

The “tilted” position is defined as follows:

- a. Repeat steps (a) – (g) of 4.2.1.1 to place the device in the “cheek position.”
- b. While maintaining the orientation of the handset move the handset away from the pinna along the line passing through RE and LE in order to enable a rotation of the handset by 15 degrees.
- c. Rotate the handset around the horizontal line by 15 degrees.
- d. While maintaining the orientation of the handset, move the handset towards the phantom on a line passing through RE and LE until any part of the handset touches the ear. The tilted position is obtained when the contact is on the pinna. If the contact is at any location other than the pinna (e.g., the antenna with the back of the phantom head), the angle of the handset should be reduced. In this case, the tilted position is obtained if any part of the handset is in contact with the pinna as well as a second part of the handset is contact with the phantom (e.g., the antenna with the back of the head).

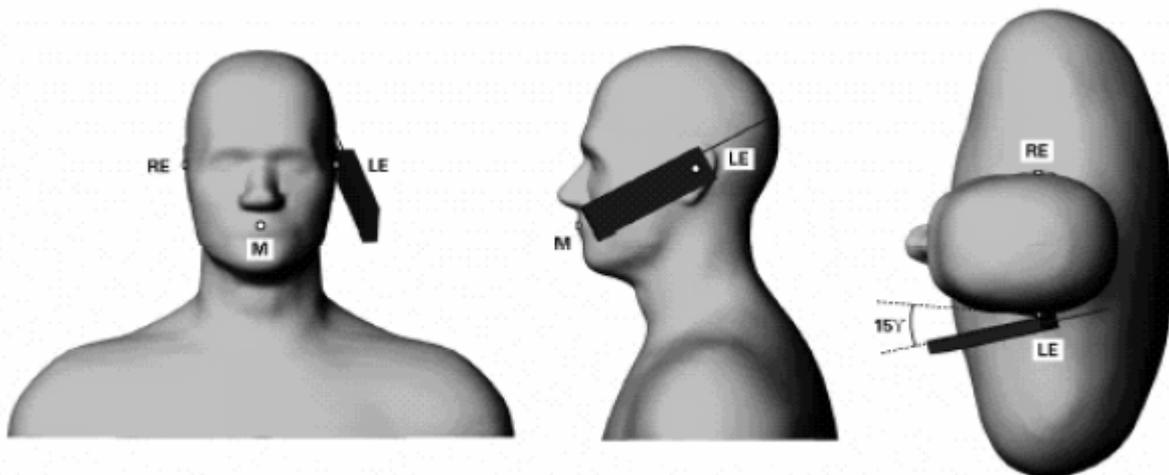


Figure 4.3 – Phone position 2, “tilted” position.

5.2.4 Test Positions for body-worn

Body-worn operating configurations should be tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in normal use configurations. A separation distance of 1.5 cm between the back of the device and a flat phantom is recommended for testing body-worn SAR compliance under such circumstances. Other separation distance may be use, but not exceed 2.5 cm.

5.3 SAR Measurement Procedure

The ALSAS-10U calculates SAR using the following equation,

$$SAR = \frac{\sigma |E|^2}{\rho}$$

σ : represents the simulated tissue conductivity

ρ : represents the tissue density

The EUT is set to transmit at the required power in line with product specification, at each frequency relating to the LOW, MID, and HIGH channel settings.

Pre-scans are made on the device to establish the location for the transmitting antenna, using a large area scan in either air or tissue simulation fluid.

The EUT is placed against the Universal Phantom where the maximum area scan dimensions are larger than the physical size of the resonating antenna. When the scan size is not large enough to cover the peak SAR distribution, it is modified by either extending the area scan size in both the X and Y directions, or the device is shifted within the predefined area.

The area scan is then run to establish the peak SAR location (interpolated resolution set at 1mm²) which is then used to orient the center of the zoom scan. The zoom scan is then executed and the 1g and 10g averages are derived from the zoom scan volume (interpolated resolution set at 1mm³).

6. SAR Exposure Limits

SAR assessments have been made in line with the requirements of IEEE-1528, FCC Supplement C, and comply with ANSI/IEEE C95.1-1992 “Uncontrolled Environments” limits. These limits apply to a location which is deemed as “Uncontrolled Environment” which can be described as a situation where the general public may be exposed to an RF source with no prior knowledge or control over their exposure.

Limits for General Population/Uncontrolled Exposure (W/kg)

| Type Exposure | Uncontrolled Environment Limit |
|--|--------------------------------|
| Spatial Peak SAR (1g cube tissue for brain or body) | 1.60 W/kg |
| Spatial Average SAR (whole body) | 0.08 W/kg |
| Spatial Peak SAR (10g for hands, feet, ankles and wrist) | 4.00 W/kg |

7. Test Equipment List

| Instrument | Manufacturer | Model No. | Serial No. | Last Calibration |
|------------------------------------|--------------|------------------------|-------------|------------------|
| Vector Network Analyzer | Agilent | E5071B | MY42402726 | Jul. 2006 |
| Dielectric Probe Kit | Agilent | 85070E | MY44300124 | N/A |
| Signal Generator | Anritsu | MG3692A | 020311 | Feb. 2007 |
| Power Meter | Agilent | 438A | 3513U06187 | Feb. 2007 |
| Power Sensor | Agilent | 84815A | 3318A01828 | Feb. 2007 |
| Data Acquisition Package | Aprel | ALS-DAQ-PAQ-2 | 110-00203 | N/A |
| Aprel Laboratories Probe | Aprel | ALS-E020 | 266 | Jun. 2006 |
| Aprel Reference Dipole 835MHz | Aprel | ALS-D-835-S-2 | 180-00553 | Feb. 2007 |
| Aprel Reference Dipole 1900MHz | Aprel | ALS-D-1900-S-2 | 210-00703 | Feb. 2007 |
| Aprel Reference Dipole 2450MHz | Aprel | ALS-D-2450-S-2 | 220-00753 | Feb. 2007 |
| Aprel Reference Dipole 5200MHz | Aprel | ALS-D-5200-S-2 | 230-00802 | Feb. 2007 |
| Aprel Reference Dipole 5800MHz | Aprel | ALS-D-5800-S-2 | 240-00852 | Feb. 2007 |
| Boundary Detection SensorSystem | Aprel | ALS-PMDPS-2 | 120-00253 | N/A |
| Universal Work Station | Aprel | ALS-UWS | 100-00153 | N/A |
| Device Holder 2.0 | Aprel | ALS-H-E-SET-2 | 170-00503 | N/A |
| Left Ear SAM Phantom | Aprel | ALS-P-SAM-L | 130-00305 | N/A |
| Right Ear SAM Phantom | Aprel | ALS-P-SAM-R | 140-00355 | N/A |
| Universal Phantom | Aprel | ALS-P-UP-1 | 150-00405 | N/A |
| Aprel Dipole Spacer | Aprel | ALS-DS-U | 250-00903 | N/A |
| SAR Software | Aprel | ALSAS-10U Ver.2.2.0 | B0D5F-112FE | N/A |
| CRS C500C Controller | Thermo | ALS-C500 | RCF0440278 | N/A |
| CRF F3 Robot | Thermo | ALS-F3 | RAF0440252 | N/A |
| Power Amplifier | Mini-Circuit | ZVE-8G | D030305 | N/A |
| Vector Network Analyzer | Agilent | E5071B | MY42402726 | Jul. 2007 |
| Dielectric Probe Kit | Agilent | 85070E | MY44300124 | N/A |
| Signal Generator | Anritsu | MG3692A | 020311 | Feb. 2007 |
| Power Meter | Agilent | 438A | 3513U06187 | Feb. 2007 |
| Power Sensor | Agilent | 84815A | 3318A01828 | Feb. 2007 |

Note: All equipment upon which need to be calibrated are with calibration period of 1 year except Reference Dipole is to be calibrated every two years. .

8. Measurement Uncertainty

Exposure Assessment Measurement Uncertainty

| Source of Uncertainty | Tolerance Value | Probability Distribution | Divisor | c_i^1 (1g) | c_i^1 (10g) | Standard Uncertainty (1-g) % | Standard Uncertainty (10g) % |
|---|-----------------|--------------------------|------------|----------------|----------------|------------------------------|------------------------------|
| Measurement System | | | | | | | |
| Probe Calibration | 3.5 | normal | 1 | 1 | 1 | 3.5 | 3.5 |
| Axial Isotropy | 3.7 | rectangular | $\sqrt{3}$ | $(1-cp)^{1/2}$ | $(1-cp)^{1/2}$ | 1.5 | 1.5 |
| Hemispherical Isotropy | 10.9 | rectangular | $\sqrt{3}$ | vcp | vcp | 4.4 | 4.4 |
| Boundary Effect | 1.0 | rectangular | $\sqrt{3}$ | 1 | 1 | 0.6 | 0.6 |
| Linearity | 4.7 | rectangular | $\sqrt{3}$ | 1 | 1 | 2.7 | 2.7 |
| Detection Limit | 1.0 | rectangular | $\sqrt{3}$ | 1 | 1 | 0.6 | 0.6 |
| Readout Electronics | 1.0 | normal | 1 | 1 | 1 | 1.0 | 1.0 |
| Response Time | 0.8 | rectangular | $\sqrt{3}$ | 1 | 1 | 0.5 | 0.5 |
| Integration Time | 1.7 | rectangular | $\sqrt{3}$ | 1 | 1 | 1.0 | 1.0 |
| RF Ambient Condition | 3.0 | rectangular | $\sqrt{3}$ | 1 | 1 | 1.7 | 1.7 |
| Probe Positioner Mech. | 0.4 | rectangular | $\sqrt{3}$ | 1 | 1 | 0.2 | 0.2 |
| Restriction | | | | | | | |
| Probe Positioning with respect to Phantom Shell | 2.9 | rectangular | $\sqrt{3}$ | 1 | 1 | 1.7 | 1.7 |
| Extrapolation and Integration | 3.7 | rectangular | $\sqrt{3}$ | 1 | 1 | 2.1 | 2.1 |
| Test Sample Positioning | 4.0 | normal | 1 | 1 | 1 | 4.0 | 4.0 |
| Device Holder Uncertainty | 2.0 | normal | 1 | 1 | 1 | 2.0 | 2.0 |
| Drift of Output Power | 1.6 | rectangular | $\sqrt{3}$ | 1 | 1 | 0.9 | 0.9 |
| Phantom and Setup | | | | | | | |
| Phantom Uncertainty (shape & thickness tolerance) | 3.4 | rectangular | $\sqrt{3}$ | 1 | 1 | 2.0 | 2.0 |
| Liquid Conductivity (target) | 5.0 | rectangular | $\sqrt{3}$ | 0.7 | 0.5 | 2.0 | 1.4 |
| Liquid Conductivity(meas.) | 4.6 | normal | 1 | 0.7 | 0.5 | 3.2 | 2.3 |
| Liquid Permittivity(target) | 5.0 | rectangular | $\sqrt{3}$ | 0.6 | 0.5 | 1.7 | 1.4 |
| Liquid Permittivity(meas.) | 2.3 | normal | 1 | 0.6 | 0.5 | 1.4 | 1.1 |
| Combined Uncertainty | | RSS | | | | 9.9 | 9.5 |
| Combined Uncertainty (coverage factor=2) | | Normal(k=2) | | | | 19.8 | 18.9 |

9. Test Result Summary

9.1 802.11b Test Result

| SAR Measurement | | | | | | |
|---------------------------------|--------------|-----------|------|----------------------------|---------------|--------------|
| Ambient Temperature (°C) : 21.5 | | | | Relative Humidity (%) : 48 | | |
| Liquid Temperature (°C) : 21.4 | | | | Depth of Liquid (cm) : >15 | | |
| Test Mode : 802.11b | | | | | | |
| Test Position of EUT | Antenna Type | Frequency | | Conducted power (dBm) | SAR 1g (W/Kg) | Limit (W/Kg) |
| | | Channel | MHz | | | |
| Front | Internal | Low | 2412 | 18.38 | -- | 1.6 |
| Front | Internal | Mid | 2437 | 18.45 | 0.083 | 1.6 |
| Front | Internal | High | 2462 | 18.82 | -- | 1.6 |
| Top | Internal | Low | 2412 | 18.38 | -- | 1.6 |
| Top | Internal | Mid | 2437 | 18.45 | 0.339 | 1.6 |
| Top | Internal | High | 2462 | 18.82 | -- | 1.6 |
| Bottom | Internal | Low | 2412 | 18.38 | 0.880 | 1.6 |
| Bottom | Internal | Mid | 2437 | 18.45 | 1.008 | 1.6 |
| Bottom | Internal | High | 2462 | 18.82 | 1.343 | 1.6 |

Note: The SAR measured at the middle channel for this configuration is at least 3 dB lower than SAR limit, testing at the high and low channels is option.

9.2 802.11g Test Result

| SAR Measurement | | | | | | |
|---------------------------------|--------------|-----------|------|----------------------------|---------------|--------------|
| Ambient Temperature (°C) : 21.5 | | | | Relative Humidity (%) : 48 | | |
| Liquid Temperature (°C) : 21.4 | | | | Depth of Liquid (cm) : >15 | | |
| Test Mode : 802.11g | | | | | | |
| Test Position of EUT | Antenna Type | Frequency | | Conducted power (dBm) | SAR 1g (W/Kg) | Limit (W/Kg) |
| | | Channel | MHz | | | |
| Front | Internal | Low | 2412 | 20.63 | -- | 1.6 |
| Front | Internal | Mid | 2437 | 21.36 | 0.113 | 1.6 |
| Front | Internal | High | 2462 | 20.38 | -- | 1.6 |
| Top | Internal | Low | 2412 | 20.63 | -- | 1.6 |
| Top | Internal | Mid | 2437 | 21.36 | 0.571 | 1.6 |
| Top | Internal | High | 2462 | 20.38 | -- | 1.6 |
| Bottom | Internal | Low | 2412 | 20.63 | 1.390 | 1.6 |
| Bottom | Internal | Mid | 2437 | 21.36 | 1.028 | 1.6 |
| Bottom | Internal | High | 2462 | 20.38 | 1.041 | 1.6 |

Note: The SAR measured at the middle channel for this configuration is at least 3 dB lower than SAR limit, testing at the high and low channels is option.

9.3 802.11n_20M(2412MHz ~ 2462MHz) Test Result

| SAR Measurement | | | | | | |
|--|--------------|-----------|------|----------------------------|---------------|--------------|
| Ambient Temperature (°C) : 21.5 | | | | Relative Humidity (%) : 48 | | |
| Liquid Temperature (°C) : 21.4 | | | | Depth of Liquid (cm) : >15 | | |
| Test Mode : 802.11n_20M(2412MHz ~ 2462MHz) | | | | | | |
| Test Position of EUT | Antenna Type | Frequency | | Conducted power (dBm) | SAR 1g (W/Kg) | Limit (W/Kg) |
| | | Channel | MHz | | | |
| Front | Internal | Low | 2412 | 23.86 | -- | 1.6 |
| Front | Internal | Mid | 2437 | 23.99 | 0.102 | 1.6 |
| Front | Internal | High | 2462 | 24.33 | -- | 1.6 |
| Top | Internal | Low | 2412 | 23.86 | -- | 1.6 |
| Top | Internal | Mid | 2437 | 23.99 | 0.409 | 1.6 |
| Top | Internal | High | 2462 | 24.33 | -- | 1.6 |
| Bottom | Internal | Low | 2412 | 23.86 | 0.865 | 1.6 |
| Bottom | Internal | Mid | 2437 | 23.99 | 1.214 | 1.6 |
| Bottom | Internal | High | 2462 | 24.33 | 1.233 | 1.6 |

Note: The SAR measured at the middle channel for this configuration is at least 3 dB lower than SAR limit, testing at the high and low channels is option.

9.4 802.11n_40M(2422MHz ~2452MHz) Test Result

| SAR Measurement | | | | | | |
|---|--------------|-----------|------|----------------------------|---------------|--------------|
| Ambient Temperature (°C) : 21.5 | | | | Relative Humidity (%) : 48 | | |
| Liquid Temperature (°C) : 21.4 | | | | Depth of Liquid (cm) : >15 | | |
| Test Mode : 802.11n_40M(2422MHz ~2452MHz) | | | | | | |
| Test Position of EUT | Antenna Type | Frequency | | Conducted power (dBm) | SAR 1g (W/Kg) | Limit (W/Kg) |
| | | Channel | MHz | | | |
| Front | Internal | Low | 2422 | 24.46 | -- | 1.6 |
| Front | Internal | Mid | 2437 | 24.74 | 0.106 | 1.6 |
| Front | Internal | High | 2452 | 24.58 | -- | 1.6 |
| Top | Internal | Low | 2422 | 24.46 | -- | 1.6 |
| Top | Internal | Mid | 2437 | 24.74 | 0.381 | 1.6 |
| Top | Internal | High | 2452 | 24.58 | -- | 1.6 |
| Bottom | Internal | Low | 2422 | 24.46 | 1.187 | 1.6 |
| Bottom | Internal | Mid | 2437 | 24.74 | 0.986 | 1.6 |
| Bottom | Internal | High | 2452 | 24.58 | 1.317 | 1.6 |

Note: The SAR measured at the middle channel for this configuration is at least 3 dB lower than SAR limit, testing at the high and low channels is option.

- 10. Appendix A: Photographs of Test Setup**
- 11. Appendix B: Photographs of EUT**
- 12. Appendix C: SAR System Validation Data**
- 13. Appendix D: SAR measurement Data**
- 14. Appendix E: Probe calibration data**
- 15. Appendix F: Dipole calibration data**