

**SAR EVALUATION REPORT****Applicant Name:**

Logitech Far East Ltd.
No. 2, Creation Road IV Science-Based Industrial Park
Hsin-Chu,
Taiwan

Date of Testing:

03/13/17

Test Site/Location:

PCTEST Lab, Columbia, MD, USA

Document Serial No.:

1M1703090100-01-R2.JNZ

FCC ID:**JNZPR0001****APPLICANT:****LOGITECH FAR EAST LTD.****DUT Type:**

Mouse Pad

Application Type:

Certification

FCC Rule Part(s):

CFR §2.1093

Model:

P-R0001

Technology	Tx Frequency	SAR
		10 gm Extremity (W/kg)
A4WP	6.78 MHz	0.19

Note: This revised Test Report (S/N: 1M1703090100-01-R2.JNZ) supersedes and replaces the previously issued test report on the same subject device for the same type of testing as indicated. Please discard or destroy the previously issued test report(s) and dispose of it accordingly

I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualifications of all persons taking them. Test results reported herein relate only to the item(s) tested.



Randy Ortanez
President



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1 DEVICE UNDER TEST

1.1 Device Overview

Technology	Operating Modes	Tx Frequency
A4WP	Power Transfer	6.78 MHz
Bluetooth LE	Data	2402 - 2480 MHz
CC2544 Proprietary 2.4 GHz	Data	2400 - 2483.5 MHz

1.2 Simultaneous Transmission Capabilities

According to FCC KDB Publication 447498 D01v06, transmitters are considered to be transmitting simultaneously when there is overlapping transmission, with the exception of transmissions during network hand-offs with maximum hand-off duration less than 30 seconds. This device contains multiple transmitters that may operate simultaneously, and therefore requires a simultaneous transmission analysis according to FCC KDB Publication 447498 D01v06 4.3.2 procedures.

This device can transmit A4WP simultaneously with Bluetooth LE and the CC2544 Proprietary 2.4 GHz transmitter.

1.3 Miscellaneous SAR Test Considerations

The device also contains Bluetooth LE and proprietary 2.4 GHz DTS transmitters. The RF exposure evaluation for these transmitters and for the simultaneous transmissions with the wireless charging signal evaluated in this report will be assessed under a separate report.

1.4 Guidance Applied

- FCC KDB Publication 447498 D01v06, Section 4.4 (General SAR Guidance)
- FCC KDB Publication 865664 D01v01r04 (SAR Measurements up to 6 GHz)
- FCC KDB Publication 680106 D01v02
- February 17th, 2016 TCB Conference Call
- April 2015 TCB Workshop RF Exposure
- April 2016 TCB Workshop Notes

1.5 Device Serial Numbers

	Device Serial Number
A4WP	1703LZ0E0BY8

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2 INTRODUCTION

The FCC and Innovation, Science, and Economic Development Canada have adopted the guidelines for evaluating the environmental effects of radio frequency (RF) radiation in ET Docket 93-62 on Aug. 6, 1996 and Health Canada Safety Code 6 to protect the public and workers from the potential hazards of RF emissions due to FCC-regulated portable devices. [1]

The safety limits used for the environmental evaluation measurements are based on the criteria published by the American National Standards Institute (ANSI) for localized specific absorption rate (SAR) in IEEE/ANSI C95.1-1992 Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz [3] and Health Canada RF Exposure Guidelines Safety Code 6 [22]. The measurement procedure described in IEEE/ANSI C95.3-2002 Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields - RF and Microwave [4] is used for guidance in measuring the Specific Absorption Rate (SAR) due to the RF radiation exposure from the Equipment Under Test (EUT). These criteria for SAR evaluation are similar to those recommended by the International Committee for Non-Ionizing Radiation Protection (ICNIRP) in Biological Effects and Exposure Criteria for Radiofrequency Electromagnetic Fields,” Report No. Vol 74. SAR is a measure of the rate of energy absorption due to exposure to an RF transmitting source. SAR values have been related to threshold levels for potential biological hazards.

2.1 SAR Definition

Specific Absorption Rate is defined as the time derivative (rate) of the incremental energy (dU) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dV) of a given density (ρ). It is also defined as the rate of RF energy absorption per unit mass at a point in an absorbing body (see Equation 2-1).

Equation 2-1
SAR Mathematical Equation

$$SAR = \frac{d}{dt} \left(\frac{dU}{dm} \right) = \frac{d}{dt} \left(\frac{dU}{\rho dV} \right)$$

SAR is expressed in units of Watts per Kilogram (W/kg).

$$SAR = \frac{\sigma \cdot E^2}{\rho}$$

where:

- σ = conductivity of the tissue-simulating material (S/m)
- ρ = mass density of the tissue-simulating material (kg/m³)
- E = Total RMS electric field strength (V/m)

NOTE: The primary factors that control rate of energy absorption were found to be the wavelength of the incident field in relation to the dimensions and geometry of the irradiated organism, the orientation of the organism in relation to the polarity of field vectors, the presence of reflecting surfaces, and whether conductive contact is made by the organism with a ground plane.[6]

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3 SAR MEASUREMENT SETUP

3.1 Robotic System

Measurements are performed using the DASY5 automated dosimetric assessment system. The DASY5 is made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland and consists of a high precision robotics system (Staubli), robot controller, desktop computer, near-field probe, probe alignment sensor, and the SAM phantom containing the head or body equivalent material. The robot is a six-axis industrial robot, performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF) (see Figure 3-1).

3.2 System Hardware

A cell controller system contains the power supply, robot controller, teach pendant (Joystick), and a remote control used to drive the robot motors. The PC consists of the SAR Measurement Software DASY52, A/D interface card, monitor, mouse, and keyboard. The Staubli Robot is connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE) circuit that performs the signal amplification, signal multiplexing, A/D conversion, offset measurements, mechanical surface detection, collision detection, etc. is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal from the DAE and transfers data to the PC card.

3.3 System Electronics

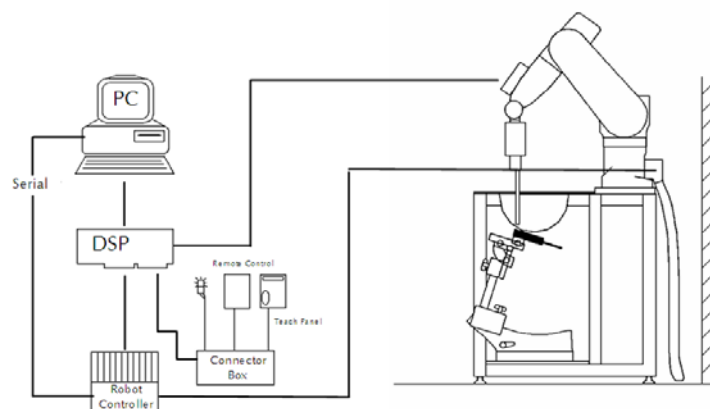


Figure 3-1
SAR Measurement System Setup

The DAE consists of a highly sensitive electrometer-grade auto-zeroing preamplifier, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer.

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3.4 Automated Test System Specifications

Test Software: SPEAG DASY52 version 52.8 Measurement Software
Robot: Stäubli Unimation Corp. Robot RX60L, Robot TX90XL
Repeatability: 0.02 mm
No. of Axes: 6

Data Acquisition Electronic System (DAE)

Data Converter

Features: Signal Amplifier, multiplexer, A/D converter & control logic
Software: SEMCAD X software
Connecting Lines: Optical Downlink for data and status info
Optical upload for commands and clock

PC Interface Card

Function: Link to DAE
16-bit A/D converter for surface detection system
Two Serial & Ethernet link to robotics
Direct emergency stop output for robot

Phantom

Type: ELI V4.0/5.0/6.0
Shell Material: Composite
Thickness: 2.0 ± 0.2 mm



ELI is constructed of a fiberglass shell and can be integrated into standard phantom tables. ELI Phantom is made for compliance testing of handheld and body-mounted wireless devices. ELI is fully compatible with the IEC 62209-2 standard and all known tissue simulating liquids. Reference markings on the phantom allow installation of the complete setup, including all predefined phantom positions and measurement grids, by teaching three points. The shell phantom has a 2 mm shell thickness.

Figure 3-2
ELI Phantoms

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4 DASY E-FIELD PROBE SYSTEM

4.1 Probe Measurement System



**Figure 4-1
SAR System**

The SAR measurements were conducted with the dosimetric probe designed in the classical triangular configuration (see Figure 4-3) and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multi-fiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY5 software reads the reflection during a software approach and looks for the maximum using a 2nd order curve fitting. The approach is stopped at reaching the maximum.

4.2 Probe Specifications

Model(s):	EX3DV4
Frequency Range:	4 MHz – 6.0 GHz (EX3DV4)
Calibration:	In head and body simulating tissue at Frequencies from 4 up to 6000MHz
Linearity:	± 0.2 dB (4 MHz to 6 GHz) for EX3DV4
Dynamic Range:	10 mW/kg – 100 W/kg
Probe Length:	337 mm
Probe Tip Length:	9 mm
Body Diameter:	10 mm
Tip Diameter:	2.5 mm for EX3DV4
Tip-Center:	1 mm for EX3DV4
Application:	SAR Dosimetry Testing Compliance tests of mobile phones Dosimetry in strong gradient fields



**Figure 4-2
Near-Field Probe**



**Figure 4-3
Triangular Probe Configuration**

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5 DOSIMETRIC ASSESSMENT

5.1 Measurement Procedure

The evaluation was performed using the following procedure compliant to FCC KDB Publication 865664 D01v01r04 and IEEE 1528-2013:

1. The SAR distribution at the exposed side of the head or body was measured at a distance no greater than 5.0 mm from the inner surface of the shell. The area covered the entire dimension of the device-head and body interface and the horizontal grid resolution was determined per FCC KDB Publication 865664 D01v01r04 (See Table 5-1) and IEEE 1528-2013.
2. The point SAR measurement was taken at the maximum SAR region determined from Step 1 to enable the monitoring of SAR fluctuations/drifts during the 1g/10g cube evaluation. SAR at this fixed point was measured and used as a reference value.
3. Based on the area scan data, the peak of the region with maximum SAR was determined by spline interpolation. Around this point, a volume was assessed according to the measurement resolution and volume size requirements of FCC KDB Publication 865664 D01v01r04 (See Table 5-1) and IEEE 1528-2013. On the basis of this data set, the spatial peak SAR value was evaluated with the following procedure (see references or the DASY manual online for more details):
 - a. SAR values at the inner surface of the phantom are extrapolated from the measured values along the line away from the surface with spacing no greater than that in Table 5-1. The extrapolation was based on a least-squares algorithm. A polynomial of the fourth order was calculated through the points in the z-axis (normal to the phantom shell).
 - b. After the maximum interpolated values were calculated between the points in the cube, the SAR was averaged over the spatial volume (1g or 10g) using a 3D-Spline interpolation algorithm. The 3D-spline is composed of three one-dimensional splines with the "Not a knot" condition (in x, y, and z directions). The volume was then integrated with the trapezoidal algorithm. One thousand points (10 x 10 x 10) were obtained through interpolation, in order to calculate the averaged SAR.
 - c. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.
4. The SAR reference value, at the same location as step 2, was re-measured after the zoom scan was complete to calculate the SAR drift. If the drift deviated by more than 5%, the SAR test and drift measurements were repeated.

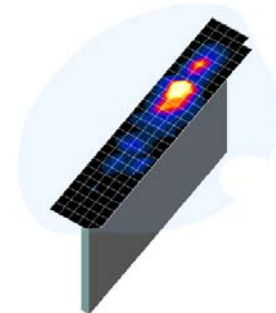


Figure 5-1
Sample SAR Area
Scan

Table 5-1
Area and Zoom Scan Resolutions per FCC KDB Publication 865664 D01v01r04*

Frequency	Maximum Area Scan Resolution (mm) ($\Delta x_{\text{area}}, \Delta y_{\text{area}}$)	Maximum Zoom Scan Resolution (mm) ($\Delta x_{\text{zoom}}, \Delta y_{\text{zoom}}$)	Maximum Zoom Scan Spatial Resolution (mm)			Minimum Zoom Scan Volume (mm) (x,y,z)
			Uniform Grid $\Delta z_{\text{zoom}}(n)$	Graded Grid		
				$\Delta z_{\text{zoom}}(1)^*$	$\Delta z_{\text{zoom}}(n>1)^*$	
≤ 2 GHz	≤ 15	≤ 8	≤ 5	≤ 4	≤ 1.5* $\Delta z_{\text{zoom}}(n-1)$	≥ 30
2-3 GHz	≤ 12	≤ 5	≤ 5	≤ 4	≤ 1.5* $\Delta z_{\text{zoom}}(n-1)$	≥ 30
3-4 GHz	≤ 12	≤ 5	≤ 4	≤ 3	≤ 1.5* $\Delta z_{\text{zoom}}(n-1)$	≥ 28
4-5 GHz	≤ 10	≤ 4	≤ 3	≤ 2.5	≤ 1.5* $\Delta z_{\text{zoom}}(n-1)$	≥ 25
5-6 GHz	≤ 10	≤ 4	≤ 2	≤ 2	≤ 1.5* $\Delta z_{\text{zoom}}(n-1)$	≥ 22

*Also compliant to IEEE 1528-2013 Table 6

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6 TEST CONFIGURATION POSITIONS

6.1 Device Holder

The device holder is made out of low-loss POM material having the following dielectric parameters: relative permittivity $\epsilon = 3$ and loss tangent $\delta = 0.02$.

6.2 Position of the device under test in relation to the phantom

Per FCC Guidance, the DUT was tested against a flat phantom. The DUT was positioned as close to the phantom as possible so that the peak spatial-average SAR can be measured. The DUT was oriented in accordance with the intended use conditions, as indicated in Figure 6-1. 4. Per FCC Guidance, the only expected exposure condition is the top surface for extremity SAR.

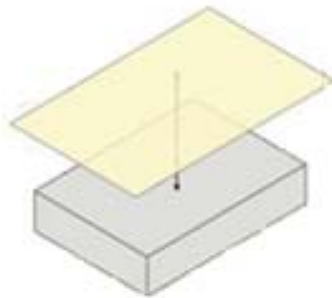


Figure 6-1
Required Test Positions for FCC Guidance

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7 RF EXPOSURE LIMITS

7.1 Uncontrolled Environment

UNCONTROLLED ENVIRONMENTS are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure. The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity.

7.2 Controlled Environment

CONTROLLED ENVIRONMENTS are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation). In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means.

Table 7-1
SAR Human Exposure Specified in ANSI/IEEE C95.1-1992 and Health Canada Safety Code 6

HUMAN EXPOSURE LIMITS		
	UNCONTROLLED ENVIRONMENT <i>General Population</i> (W/kg) or (mW/g)	CONTROLLED ENVIRONMENT <i>Occupational</i> (W/kg) or (mW/g)
Peak Spatial Average SAR Head	1.6	8.0
Whole Body SAR	0.08	0.4
Peak Spatial Average SAR Hands, Feet, Ankle, Wrists, etc.	4.0	20

1. The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.
2. The Spatial Average value of the SAR averaged over the whole body.
3. The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

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8 SYSTEM VERIFICATION

8.1 Tissue Verification

**Table 8-1
Measured Tissue Properties**

Calibrated for Tests Performed on:	Tissue Type	Tissue Temp During Calibration (°C)	Measured Frequency (MHz)	Measured Conductivity, σ (S/m)	Measured Dielectric Constant, ϵ	TARGET Conductivity, σ (S/m)	TARGET Dielectric Constant, ϵ	%dev σ	%dev ϵ
3/13/2017	6 MHz	22.2	6	0.737	55.867	0.750	55.500	-1.77%	0.66%
			7	0.738	55.573	0.750	55.500	-1.62%	0.13%

The above measured tissue parameters were used in the DASY software. The DASY software was used to perform interpolation to determine the dielectric parameters at the SAR test device frequencies (per KDB Publication 865664 D01v01r04 and IEEE 1528-2013 6.6.1.2). The tissue parameters listed in the SAR test plots may slightly differ from the table above due to significant digit rounding in the software.

Per the April 2016 TCB Workshop Slides, the desired average muscle dielectric parameters are $\epsilon_R = 211$ and $\sigma = 0.63$ S/m at 6.78 MHz. However, numerical simulation results have determined that SAR is not sensitive to ϵ_R at 6.78 MHz for $\epsilon_R = 50\sim 300$ and $\sigma = 0.63$ S/m. Therefore, the IEC 30 MHz target values were used for the evaluation.

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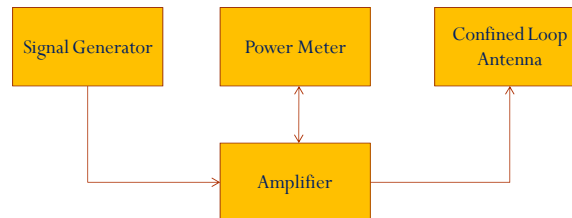
8.2 Test System Verification

Prior to SAR assessment, the system is verified to $\pm 10\%$ of the SAR measurement on the Confined Loop Antenna at the time of calibration by the calibration facility.

Table 8-2
System Verification Results

System Verification TARGET & MEASURED											
SAR System #	Tissue Frequency (MHz)	Date:	Amb. Temp (°C)	Liquid Temp (°C)	Input Power (W)	CLA SN	Probe SN	Measured SAR _{10g} (W/kg)	1 W Target SAR _{10g} (W/kg)	1 W Normalized SAR _{10g} (W/kg)	Deviation _{10g} (%)
D	6	03/13/2017	20.5	21.2	1.000	1002	7420	0.103	0.113	0.103	-8.85%

Figure 8-1
System Verification Setup Diagram



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9 SAR DATA SUMMARY

9.1 Standalone Extremity SAR Data

Table 9-1
A4WP Extremity SAR Data

MEASUREMENT RESULTS									
FREQUENCY	Mode	Device Configuration	Drift [dB]	Spacing	Device Serial Number	Side	SAR (1g)	SAR (10g)	Plot #
MHz							(W/kg)	(W/kg)	
6.78	A4WP	Device Only	0.20	0 mm	1703LZ0E0BY8	Top	0.337	0.185	A1
6.78	A4WP	Device with Soft Cover	0.13	0 mm	1703LZ0E0BY8	Top	0.304	0.178	
6.78	A4WP	Device with Hard Cover	0.00	0 mm	1703LZ0E0BY8	Top	0.303	0.181	
ANSI / IEEE C95.1 1992 - SAFETY LIMIT Spatial Peak Uncontrolled Exposure/General Population			Extremity 4.0 W/kg (mW/g) averaged over 10 gram						

9.2 SAR Test Notes

General Notes:

1. The test data reported are the worst-case SAR values according to test procedures specified from FCC KDB Publication 447498 D01v06, FCC KDB Publication 865664 D01v01r04, February 17th 2016 TCB Conference Call, April 2015 TCB Workshop RF Exposure Notes, April 2016 TCB Workshop Notes.
2. Liquid tissue depth was at least 15.0 cm for all frequencies.
3. Per FCC Guidance, the only expected exposure condition is the top surface for extremity SAR.
4. Device was configured to transmit continuously at a constant field (CW) with the test current in the coil at about 350 mA.
5. The device supports soft cover and hard cover accessories that can be placed on top of the device between the pad and the user's hands. SAR tests were additionally performed with the accessories per FCC KDB Publication 648474 D04v01r03.

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10 SAR MEASUREMENT VARIABILITY

10.1 Measurement Variability

Per FCC KDB Publication 865664 D01v01, SAR measurement variability was not assessed for any frequency band since all measured SAR values were less than 0.80 W/kg (1g) and 2.0 W/kg (10g).

10.2 Measurement Uncertainty

The measured 1g SAR was <1.5 W/kg and measured 10g SAR was <3.75 W/kg for all frequency bands. Therefore, per KDB Publication 865664 D01v01r04, the extended measurement uncertainty analysis per IEEE 1528-2013 was not required.

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11 EQUIPMENT LIST

Manufacturer	Model	Description	Cal Date	Cal Interval	Cal Due	Serial Number
Agilent	8594A	(9kHz-2.9GHz) Spectrum Analyzer	N/A	N/A	N/A	3051A00187
Narda	4772-3	Attenuator (3dB)	CBT	N/A	CBT	9406
SPEAG	CLA-6	Confined Loop Antenna	10/3/2016	Annual	10/3/2017	1002
SPEAG	DAE4	Dasy Data Acquisition Electronics	1/16/2017	Annual	1/16/2018	1466
Mini-Circuits	BW-N20W5+	DC to 18 GHz Precision Fixed 20 dB Attenuator	CBT	N/A	CBT	N/A
Mini-Circuits	NLP-1200+	Low Pass Filter DC to 1000 MHz	CBT	N/A	CBT	N/A
Mini-Circuits	NLP-2950+	Low Pass Filter DC to 2700 MHz	CBT	N/A	CBT	N/A
Mini-Circuits	PWR-SENS-4RMS	USB Power Sensor	4/4/2016	Annual	4/4/2017	11210140001
Mini-Circuits	PWR-SENS-4RMS	USB Power Sensor	4/4/2016	Annual	4/4/2017	11210140001
Mini-Circuits	TVA-11-422	RF Power Amp	CBT	N/A	CBT	QA1303002
Agilent	N9020A	MXA Signal Analyzer	10/28/2016	Annual	10/28/2017	US46470561
Agilent	N5182A	MXG Vector Signal Generator	10/27/2016	Annual	10/27/2017	MY47420603
SPEAG	DAK-12	Dielectric Assessment Kit	3/1/2016	Biennial	3/1/2018	1102
Mini-Circuits	BW-N20W5	Power Attenuator	CBT	N/A	CBT	1226
SPEAG	EX3DV4	SAR Probe	11/15/2016	Annual	11/15/2017	7420
Agilent	8753ES	S-Parameter Vector Network Analyzer	8/19/2016	Annual	8/19/2017	MY40003841
Pasternack	NC-100	Torque Wrench	5/21/2015	Biennial	5/21/2017	N/A
Control Company	4352	Ultra Long Stem Thermometer	3/8/2016	Biennial	3/8/2018	160261701

Note: CBT (Calibrated Before Testing). Prior to testing, the measurement paths containing a cable, amplifier, attenuator, coupler or filter were connected to a calibrated source (i.e. a signal generator) to determine the losses of the measurement path. The power meter offset was then adjusted to compensate for the measurement system losses. This level offset is stored within the power meter before measurements are made. This calibration verification procedure applies to the system verification and output power measurements. The calibrated reading is then taken directly from the power meter after compensation of the losses for all final power measurements.

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12 MEASUREMENT UNCERTAINTIES

a	b	c	d	e= f(d,k)	f	g	h = c x f/e	i = c x g/e	k
Uncertainty Component	IEEE 1528 Sec.	Tol. (± %)	Prob. Dist.	Div.	c _i 1gm	c _i 10 gms	1gm u _i (± %)	10gms u _i (± %)	v _i
Measurement System									
Probe Calibration	E.2.1	6.65	N	1	1	1	6.7	6.7	∞
Axial Isotropy	E.2.2	0.25	N	1	0.7	0.7	0.2	0.2	∞
Hemishperical Isotropy	E.2.2	1.3	N	1	0.7	0.7	0.9	0.9	∞
Boundary Effect	E.2.3	1	R	1.73	1	1	0.6	0.6	∞
Linearity	E.2.4	0.3	N	1	1	1	0.3	0.3	∞
System Detection Limits	E.2.4	0.25	R	1.73	1	1	0.1	0.1	∞
Modulation Response	E.2.5	0	R	1.73	1	1	0.0	0.0	∞
Readout Electronics	E.2.6	0.3	N	1	1	1	0.3	0.3	∞
Response Time	E.2.7	0.8	R	1.73	1	1	0.5	0.5	∞
Integration Time	E.2.8	2.6	R	1.73	1	1	1.5	1.5	∞
RF Ambient Conditions - Noise	E.6.1	3	R	1.73	1	1	1.7	1.7	∞
RF Ambient Conditions - Reflections	E.6.1	3	R	1.73	1	1	1.7	1.7	∞
Probe Positioner Mechanical Tolerance	E.6.2	0.4	R	1.73	1	1	0.2	0.2	∞
Probe Positioning w/ respect to Phantom	E.6.3	2.9	R	1.73	1	1	1.7	1.7	∞
Extrapolation, Interpolation & Integration algorithms for Max. SAR Evaluation	E.5	2	R	1.73	1	1	1.2	1.2	∞
Test Sample Related									
Test Sample Positioning	E.4.2	3.12	N	1	1	1	3.1	3.1	35
Device Holder Uncertainty	E.4.1	0	N	1	1	1	0.0	0.0	5
Output Power Variation - SAR drift measurement	E.2.9	5	R	1.73	1	1	2.9	2.9	∞
SAR Scaling	E.6.5	0	R	1.73	1	1	0.0	0.0	∞
Phantom & Tissue Parameters									
Phantom Uncertainty (Shape & Thickness tolerances)	E.3.1	5.7	R	1.73	1.0	1.0	3.3	3.3	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1.0	0.8	1.9	1.6	∞
Liquid Conductivity - measurement uncertainty	E.3.3	4.3	N	1	0.78	0.71	3.3	3.0	76
Liquid Permittivity - measurement uncertainty	E.3.3	4.2	N	1	0.23	0.26	1.0	1.1	75
Liquid Conductivity - Temperature Uncertainty	E.3.4	3.4	R	1.73	0.78	0.71	1.5	1.4	∞
Liquid Permittivity - Temperature Uncertainty	E.3.4	0.6	R	1.73	0.23	0.26	0.1	0.1	∞
Liquid Conductivity - deviation from target values	E.3.2	5.0	R	1.73	0.64	0.43	1.8	1.2	∞
Liquid Permittivity - deviation from target values	E.3.2	5.0	R	1.73	0.60	0.49	1.7	1.4	∞
Combined Standard Uncertainty (k=1)							RSS	10.6	10.3
Expanded Uncertainty (95% CONFIDENCE LEVEL)							k=2	21.1	20.5

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13 CONCLUSION

13.1 Measurement Conclusion

The SAR evaluation indicates that the EUT complies with the RF radiation exposure limits of the FCC and Innovation, Science, and Economic Development Canada, with respect to all parameters subject to this test. These measurements were taken to simulate the RF effects of RF exposure under worst-case conditions. Precise laboratory measures were taken to assure repeatability of the tests. The results and statements relate only to the item(s) tested.

Please note that the absorption and distribution of electromagnetic energy in the body are very complex phenomena that depend on the mass, shape, and size of the body, the orientation of the body with respect to the field vectors, and the electrical properties of both the body and the environment. Other variables that may play a substantial role in possible biological effects are those that characterize the environment (e.g. ambient temperature, air velocity, relative humidity, and body insulation) and those that characterize the individual (e.g. age, gender, activity level, debilitation, or disease). Because various factors may interact with one another to vary the specific biological outcome of an exposure to electromagnetic fields, any protection guide should consider maximal amplification of biological effects as a result of field-body interactions, environmental conditions, and physiological variables. [3]

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