



FCC SAR Test Report

APPLICANT : Motorola Mobility, Inc.
EQUIPMENT : Mobile Phone
BRAND NAME : MOTOROLA
MODEL NAME : XT316
GPPD NUMBER : 3039
FCC ID : IHDT56ML1
STANDARD : FCC 47 CFR Part 2 (2.1093)
IEEE C95.1-1991
IEEE 1528-2003
FCC OET Bulletin 65 Supplement C (Edition 01-01)

The product was received on Mar. 04, 2011 and completely tested on Mar. 20, 2011. We, SPORTON INTERNATIONAL INC., would like to declare that the tested sample has been evaluated in accordance with the procedures and shown the compliance with the applicable technical standards.

The test results in this report apply exclusively to the tested model / sample. Without written approval of SPORTON INTERNATIONAL INC., the test report shall not be reproduced except in full.

Reviewed by:

Roy Wu / Manager



SPORTON INTERNATIONAL INC.

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1. Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) found during testing for **Motorola Mobility, Inc. Mobile Phone MOTOROLA XT316** are as follows (with expanded uncertainty 21.4 % for 300 MHz to 3 GHz, and 25.6% for 3 GHz to 6 GHz).

| Band | Position | SAR _{1g} (W/kg) | SAR _{1g} Limit (W/kg) | SAR _{10g} (W/kg) | SAR _{10g} Limit (W/kg) |
|-------------|----------|--------------------------|--------------------------------|---------------------------|---------------------------------|
| 802.11b/g/n | Head | 0.338 | 1.6 | 0.145 | 2.0 |
| | Body | 0.235 | | 0.112 | |
| Bluetooth | Head | N/A | | N/A | |
| | Body | N/A | | N/A | |

This device is in compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits specified in FCC 47 CFR part 2 (2.1093), ANSI/IEEE C95.1-1991, and ICNIRP, and had been tested in accordance with the measurement methods and procedures specified in IEEE 1528-2003 and FCC OET Bulletin 65 Supplement C (Edition 01-01).



2. Administration Data

2.1 Testing Laboratory

| | |
|--------------------|---|
| Test Site | SPORTON INTERNATIONAL INC. |
| Test Site Location | No. 52, Hwa Ya 1 st Rd., Hwa Ya Technology Park, Kwei-Shan Hsiang, Tao Yuan Hsien, Taiwan, R.O.C. TEL: +886-3-327-3456 FAX: +886-3-328-4978 |

2.2 Applicant

| | |
|--------------|---|
| Company Name | Motorola Mobility, Inc. |
| Address | 8F., No. 9, Songgao Rd., Taipei 110, Taiwan, R.O.C. |

2.3 Manufacturer

| | |
|--------------|---|
| Company Name | Chi Mei Communication Systems, Inc. |
| Address | No. 4, Mingsheng Street, Tucheng District, New Taipei City, 23678, Taiwan |

2.4 Application Details

| | |
|--------------------------------|---------------|
| Date of Receipt of Application | Mar. 04, 2011 |
| Date of Start during the Test | Mar. 20, 2011 |
| Date of End during the Test | Mar. 20, 2011 |

3. General Information

3.1 Description of Device Under Test (DUT)

| Product Feature & Specification | |
|---------------------------------|--|
| DUT Type | Mobile Phone |
| Brand Name | MOTOROLA |
| Model Name | XT316 |
| FCC ID | IHDT56ML1 |
| Tx Frequency | 802.11b/g/n : 2400 MHz ~ 2483.5 MHz Bluetooth : 2400 MHz ~ 2483.5 MHz |
| Rx Frequency | 802.11b/g/n : 2400 MHz ~ 2483.5 MHz Bluetooth : 2400 MHz ~ 2483.5 MHz |
| Maximum Output Power to Antenna | 802.11b : 15.12 dBm 802.11g : 11.91 dBm 802.11n (BW 20MHz) : 10.12 dBm Bluetooth : 9.19 dBm |
| Antenna Type | PIFA Antenna |
| HW Version | V2.0 |
| SW Version | V3.190 |
| Type of Modulation | 802.11b : DSSS (BPSK / QPSK / CCK) 802.11g/n : OFDM (BPSK / QPSK / 16QAM / 64QAM) Bluetooth (1Mbps) : GFSK Bluetooth EDR (2Mbps) : π /4-DQPSK Bluetooth EDR (3Mbps) : 8-DPSK |
| DUT Stage | Identical Prototype |

List of Accessory:

| Specification of Accessory | | |
|----------------------------|------------|----------------|
| AC Adapter | Brand Name | Motorola |
| | Model Name | SPN5440B |
| Battery | Brand Name | Motorola |
| | Model Name | BP6X(SNN5843A) |

Remark: The above DUT's information was declared by manufacturer. Please refer to the specifications or user's manual for more detailed description.

3.2 Product Photos

Please refer to Appendix D.



3.3 Applied Standards

The Specific Absorption Rate (SAR) testing specification, method and procedure for this device is in accordance with the following standards:

- FCC 47 CFR Part 2 (2.1093)
- IEEE C95.1-1991
- IEEE 1528-2003
- FCC OET Bulletin 65 Supplement C (Edition 01-01)
- FCC KDB 248227 D01 v01r02
- FCC KDB 648474 D01 v01r05

3.4 Device Category and SAR Limits

This device belongs to portable device category because its radiating structure is allowed to be used within 20 centimeters of the body of the user. Limit for General Population/Uncontrolled exposure should be applied for this device, it is 1.6 W/kg as averaged over any 1 gram of tissue.

3.5 Test Conditions

3.5.1 *Ambient Condition*

| | |
|---------------------|-------------|
| Ambient Temperature | 20 to 24 °C |
| Humidity | < 60 % |

3.5.2 *Test Configuration*

For WLAN SAR testing, WLAN engineering testing software installed on the DUT can provide continuous transmitting RF signal. This RF signal utilized in SAR measurement has almost 100% duty cycle and its crest factor is 1.

According to the unlicensed transmitters of KDB 648474,

- test highest output channel only if SAR is ≤ 0.8 W/kg
- test all required channels if SAR is > 0.8 W/kg



The data rates for WLAN SAR testing were set in 1Mbps for 802.11b, 6Mbps for 802.11g, and M0 for 802.11n (BW 20MHz) due to the highest RF output power as below :

| 802.11b | Data Rate | 1 Mbps | | 2 Mbps | | 5.5 Mbps | | 11 Mbps | |
|---------|-----------|--------|--------|---------|---------|----------|---------|---------|---------|
| | CH 01 | 14.03 | | - | | - | | - | |
| | CH 06 | 14.48 | | - | | - | | - | |
| | CH 11 | 15.12 | | 15.04 | | 15.08 | | 15.10 | |
| 802.11g | Data Rate | 6 Mbps | 9 Mbps | 12 Mbps | 18 Mbps | 24 Mbps | 36 Mbps | 48 Mbps | 54 Mbps |
| | CH 01 | 11.21 | - | - | - | - | - | - | - |
| | CH 06 | 11.66 | 11.61 | 11.63 | 11.56 | 11.48 | 11.34 | 11.22 | 11.30 |
| | CH 11 | 11.91 | - | - | - | - | - | - | - |
| 802.11n | Data Rate | M0 | M1 | M2 | M3 | M4 | M5 | M6 | M7 |
| | CH 01 | 9.39 | - | - | - | - | - | - | - |
| | CH 06 | 9.67 | 9.53 | 9.57 | 9.64 | 9.45 | 9.41 | 9.22 | 9.55 |
| | CH 11 | 10.12 | - | - | - | - | - | - | - |

<Maximum SAR list for each band and position>

| | GSM 850 | GSM 1900 | WCDMA Band V | 802.11b/g | Max. SAR Summation |
|--------------|---------|----------|--------------|-----------|--------------------|
| Right Cheek | 0.678 | 0.56 | 0.957 | 0.338 | 1.295 |
| Right Tilted | 0.377 | 0.16 | 0.449 | 0.201 | 0.65 |
| Left Cheek | 0.628 | 0.456 | 0.698 | 0.152 | 0.85 |
| Left Tilted | 0.332 | 0.157 | 0.402 | 0.193 | 0.595 |
| Rear Face | 0.979 | 0.521 | 1.11 | 0.235 | 1.345 |
| Front Face | 0.711 | 0.354 | 0.712 | 0.084 | 0.796 |
| Left Side | 0.469 | 0.158 | 0.48 | 0.212 | 0.692 |
| Right Side | 0.485 | 0.128 | 0.521 | 0 | 0.521 |
| Top Side | 0 | 0 | 0 | 0.091 | 0.091 |
| Bottom Side | 0.071 | 0.19 | 0.069 | 0 | 0.19 |

Note: The maximum SAR summation is calculated based on the same configuration and test position.

According to KDB 648474, the simultaneous transmission SAR for WWAN and WLAN was not required, because the SAR summation is less than 1.6 W/kg. The simultaneous transmission SAR for WWAN and BT was not required, because the closest separation distance of these antennas (6.15 cm) is larger than 5 cm and the output power of Bluetooth (9.19 dBm) is less than $2P_{Ref}$ (13.8 dBm). WLAN and BT share the same antenna. Furthermore, Bluetooth standalone SAR and WLAN/Bluetooth simultaneous transmission SAR are not required because the Bluetooth power (9.19 dBm) is less than P_{Ref} (10.8 dBm) and WLAN SAR is less than 1.2 W/kg.

4. Specific Absorption Rate (SAR)

4.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

4.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ). The equation description is as below:

$$\text{SAR} = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dv} \right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$\text{SAR} = C \left(\frac{\delta T}{\delta t} \right)$$

Where: C is the specific heat capacity, δT is the temperature rise and δt is the exposure duration, or related to the electrical field in the tissue by

$$\text{SAR} = \frac{\sigma |E|^2}{\rho}$$

Where: σ is the conductivity of the tissue, ρ is the mass density of the tissue and E is the RMS electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

5. SAR Measurement System

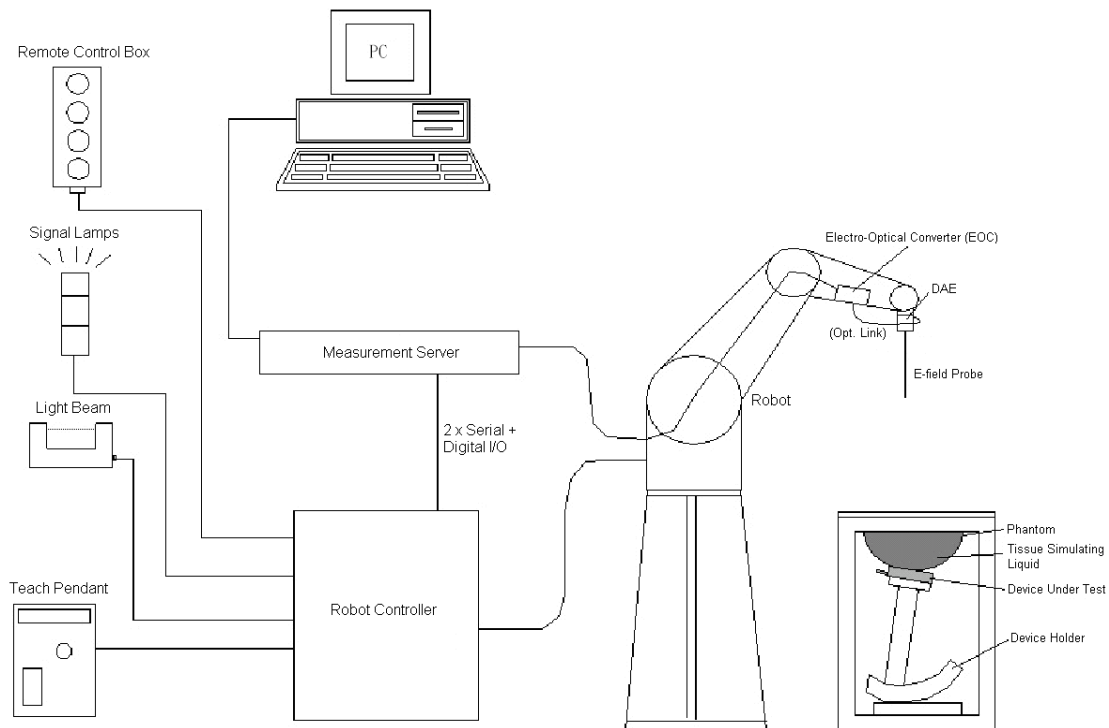


Fig 5.1 SPEAG DASY4 or DASY5 System Configurations

The DASY4 or DASY5 system for performance compliance tests is illustrated above graphically. This system consists of the following items:

- A standard high precision 6-axis robot with controller, a teach pendant and software
- A data acquisition electronic (DAE) attached to the robot arm extension
- A dosimetric probe equipped with an optical surface detector system
- The electro-optical converter (ECO) performs the conversion between optical and electrical signals
- A measurement server performs the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the accuracy of the probe positioning
- A computer operating Windows XP
- DASY4 or DASY5 software
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom
- A device holder
- Tissue simulating liquid
- Dipole for evaluating the proper functioning of the system

Some of the components are described in details in the following sub-sections.

5.1 E-Field Probe

The SAR measurement is conducted with the dosimetric probe (manufactured by SPEAG). The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. This probe has a built in optical surface detection system to prevent from collision with phantom.

5.1.1 E-Field Probe Specification

<ET3DV6>

| | |
|----------------------|--|
| Construction | Symmetrical design with triangular core Built-in optical fiber for surface detection system. Built-in shielding against static charges. PEEK enclosure material (resistant to organic solvents, e.g., DGBE) |
| Frequency | 10 MHz to 3 GHz; Linearity: ± 0.2 dB |
| Directivity | ± 0.2 dB in HSL (rotation around probe axis) ± 0.4 dB in HSL (rotation normal to probe axis) |
| Dynamic Range | 5 μ W/g to 100 mW/g; Linearity: ± 0.2 dB |
| Dimensions | Overall length: 330 mm (Tip: 16 mm) Tip diameter: 6.8 mm (Body: 12 mm) Distance from probe tip to dipole centers: 2.7 mm |

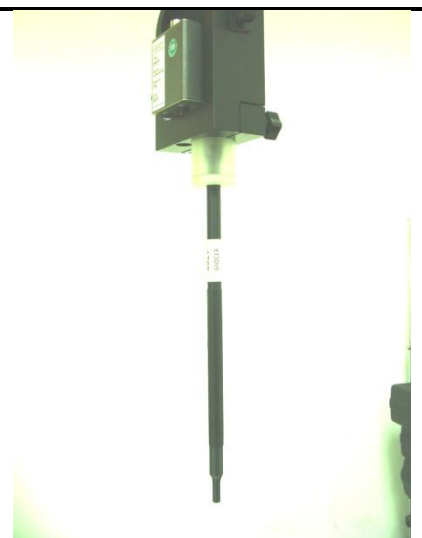


Fig 5.2 Photo of ET3DV6

<EX3DV4 Probe>

| | |
|----------------------|---|
| Construction | Symmetrical design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE) |
| Frequency | 10 MHz to 6 GHz; Linearity: ± 0.2 dB |
| Directivity | ± 0.3 dB in HSL (rotation around probe axis) ± 0.5 dB in tissue material (rotation normal to probe axis) |
| Dynamic Range | 10 μ W/g to 100 mW/g; Linearity: ± 0.2 dB (noise: typically < 1 μ W/g) |
| Dimensions | Overall length: 330 mm (Tip: 20 mm) Tip diameter: 2.5 mm (Body: 12 mm) Typical distance from probe tip to dipole centers: 1 mm |



Fig 5.3 Photo of EX3DV4

5.1.2 E-Field Probe Calibration

Each probe needs to be calibrated according to a dosimetric assessment procedure with accuracy better than $\pm 10\%$. The spherical isotropy shall be evaluated and within ± 0.25 dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested. The calibration data can be referred to appendix C of this report.

5.2 Data Acquisition Electronics (DAE)

The data acquisition electronics (DAE) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The input impedance of the DAE is 200 MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



Fig 5.4 Photo of DAE

5.3 Robot

The SPEAG DASY system uses the high precision robots (DASY4: RX90BL; DASY5: TX90XL) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version (DASY4: CS7MB; DASY5: CS8c) from Stäubli is used. The Stäubli robot series have many features that are important for our application:

- High precision (repeatability ± 0.035 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)



Fig 5.5 Photo of DASY4



Fig 5.6 Photo of DASY5

5.4 Measurement Server

The measurement server is based on a PC/104 CPU board with CPU (DASY4: 166 MHz, Intel Pentium; DASY5: 400 MHz, Intel Celeron), chipdisk (DASY4: 32 MB; DASY5: 128 MB), RAM (DASY4: 64 MB, DASY5: 128 MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all the real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operations.




Fig 5.7 Photo of Server for DASY4



Fig 5.8 Photo of Server for DASY5


5.5 Phantom

<SAM Twin Phantom>

| | | |
|--------------------------|--|--|
| Shell Thickness | 2 ± 0.2 mm; Center ear point: 6 ± 0.2 mm |  <p>Fig 5.9 Photo of SAM Phantom</p> |
| Filling Volume | Approx. 25 liters | |
| Dimensions | Length: 1000 mm; Width: 500 mm; Height: adjustable feet | |
| Measurement Areas | Left Hand, Right Hand, Flat Phantom | |

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

<ELI4 Phantom>

| | | |
|------------------------|--|--|
| Shell Thickness | 2 ± 0.2 mm (sagging: <1%) |  <p>Fig 5.10 Photo of ELI4 Phantom</p> |
| Filling Volume | Approx. 30 liters | |
| Dimensions | Major ellipse axis: 600 mm Minor axis: 400 mm | |

The ELI4 phantom is intended for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30 MHz to 6 GHz. ELI4 is fully compatible with standard and all known tissue simulating liquids.

5.6 Device Holder

<Device Holder for SAM Twin Phantom>

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5 mm distance, a positioning uncertainty of ± 0.5 mm would produce a SAR uncertainty of ± 20 %. Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR). Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss POM material having the following dielectric parameters: relative permittivity $\epsilon = 3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



Fig 5.11 Device Holder

<Laptop Extension Kit>

The extension is lightweight and made of POM, acrylic glass and foam. It fits easily on the upper part of the mounting device in place of the phone positioned. The extension is fully compatible with the SAM Twin and ELI phantoms.

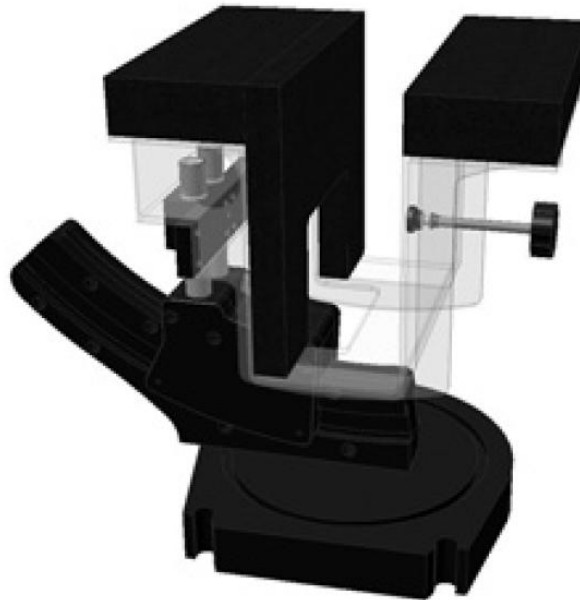


Fig 5.12 Laptop Extension Kit

5.7 Data Storage and Evaluation

5.7.1 Data Storage

The DASY software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files. The post-processing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type (e.g., [V/m], [A/m], [mW/g]). Some of these units are not available in certain situations or give meaningless results, e.g., a SAR-output in a non-lose media, will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

5.7.2 Data Evaluation

The DASY post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software :

| | | |
|----------------------------|---------------------------|---|
| Probe parameters : | - Sensitivity | Norm _i , a ₁₀ , a ₁₁ , a ₁₂ |
| | - Conversion factor | ConvF _i |
| | - Diode compression point | dcp _i |
| Device parameters : | - Frequency | f |
| | - Crest factor | cf |
| Media parameters : | - Conductivity | σ |
| | - Density | ρ |

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power.

The formula for each channel can be given as :

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with V_i = compensated signal of channel i, (i = x, y, z)
 U_i = input signal of channel i, (i = x, y, z)
 cf = crest factor of exciting field (DASY parameter)
 dcp_i = diode compression point (DASY parameter)

From the compensated input signals, the primary field data for each channel can be evaluated :

$$\text{E-field Probes : } E_i = \sqrt{\frac{V_i}{\text{Norm}_i \cdot \text{ConvF}}}$$

$$\text{H-field Probes : } H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

with V_i = compensated signal of channel i, (i = x, y, z)
 Norm_i = sensor sensitivity of channel i, (i = x, y, z), $\mu\text{V}/(\text{V/m})^2$ for E-field Probes
 ConvF = sensitivity enhancement in solution
 a_{ij} = sensor sensitivity factors for H-field probes
 f = carrier frequency [GHz]
 E_i = electric field strength of channel i in V/m
 H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude) :

$$E_{\text{tot}} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$\text{SAR} = E_{\text{tot}}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with SAR = local specific absorption rate in mW/g
 E_{tot} = total field strength in V/m
 σ = conductivity in [mho/m] or [Siemens/m]
 ρ = equivalent tissue density in g/cm³

Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.



5.8 Test Equipment List

| Manufacturer | Name of Equipment | Type/Model | Serial Number | Calibration | |
|--------------|---------------------------------|---------------|---------------|---------------|---------------|
| | | | | Last Cal. | Due Date |
| SPEAG | Dosimetric E-Field Probe | ET3DV6 | 1787 | May 18, 2010 | May 17, 2011 |
| SPEAG | 2450MHz System Validation Kit | D2450V2 | 735 | Jun. 17, 2010 | Jun. 16, 2012 |
| SPEAG | Data Acquisition Electronics | DAE3 | 577 | Jan. 13, 2011 | Jan. 12, 2012 |
| SPEAG | Device Holder | N/A | N/A | NCR | NCR |
| SPEAG | SAM Phantom | QD 000 P40 C | TP-1303 | NCR | NCR |
| SPEAG | SAM Phantom | QD 000 P40 C | TP-1383 | NCR | NCR |
| SPEAG | SAM Phantom | QD 000 P40 C | TP-1446 | NCR | NCR |
| SPEAG | SAM Phantom | QD 000 P40 C | TP-1478 | NCR | NCR |
| SPEAG | ELI4 Phantom | QD 0VA 001 BB | 1026 | NCR | NCR |
| SPEAG | ELI4 Phantom | QD 0VA 001 BA | 1029 | NCR | NCR |
| Agilent | PNA Series Network Analyzer | E8358A | US40260131 | May 06, 2010 | May 05, 2011 |
| Agilent | Wireless Communication Test Set | E5515C | MY48360820 | Jan. 12, 2010 | Jan. 11, 2012 |
| Agilent | Dielectric Probe Kit | 85070D | US01440205 | NCR | NCR |
| Agilent | Dual Directional Coupler | 778D | 50422 | NCR | NCR |
| AR | Power Amplifier | 5S1G4M2 | 0328767 | NCR | NCR |
| R&S | Spectrum Analyzer | FSP30 | 101329 | Apr. 26, 2010 | Apr. 25, 2011 |

Table 5.1 Test Equipment List

Note: The calibration certificate of DASY can be referred to appendix C of this report.

6. Tissue Simulating Liquids

For the measurement of the field distribution inside the SAM phantom with DASY, the phantom must be filled with around 25 liters of homogeneous body tissue simulating liquid. For head SAR testing, the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15 cm, which is shown in Fig. 6.1. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15 cm, which is shown in Fig. 6.2.

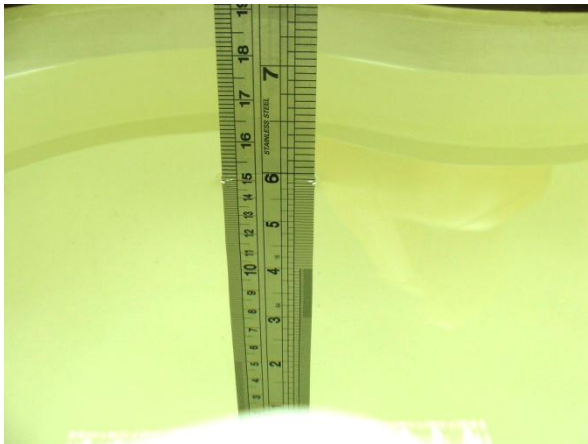


Fig 6.1 Photo of Liquid Height for Head SAR



Fig 6.2 Photo of Liquid Height for Body SAR

The following table gives the recipes for tissue simulating liquid.

| Frequency (MHz) | Water (%) | Sugar (%) | Cellulose (%) | Salt (%) | Preventol (%) | DGBE (%) | Conductivity (σ) | Permittivity (ϵ_r) |
|------------------|-----------|-----------|---------------|----------|---------------|----------|---------------------------|-------------------------------|
| For Head | | | | | | | | |
| 835 | 40.3 | 57.9 | 0.2 | 1.4 | 0.2 | 0 | 0.90 | 41.5 |
| 900 | 40.3 | 57.9 | 0.2 | 1.4 | 0.2 | 0 | 0.97 | 41.5 |
| 1800, 1900, 2000 | 55.2 | 0 | 0 | 0.3 | 0 | 44.5 | 1.40 | 40.0 |
| 2450 | 55.0 | 0 | 0 | 0 | 0 | 45.0 | 1.80 | 39.2 |
| For Body | | | | | | | | |
| 835 | 50.8 | 48.2 | 0 | 0.9 | 0.1 | 0 | 0.97 | 55.2 |
| 900 | 50.8 | 48.2 | 0 | 0.9 | 0.1 | 0 | 1.05 | 55.0 |
| 1800, 1900, 2000 | 70.2 | 0 | 0 | 0.4 | 0 | 29.4 | 1.52 | 53.3 |
| 2450 | 68.6 | 0 | 0 | 0 | 0 | 31.4 | 1.95 | 52.7 |

Table 6.1 Recipes of Tissue Simulating Liquid



The following table gives the targets for tissue simulating liquid.

| Frequency (MHz) | Liquid Type | Conductivity (σ) | $\pm 5\%$ Range | Permittivity (ϵ_r) | $\pm 5\%$ Range |
|-----------------|-------------|---------------------------|-----------------|-------------------------------|-----------------|
| 2450 | Head | 1.80 | 1.71 ~ 1.89 | 39.2 | 37.2 ~ 41.2 |
| 5200 | Head | 4.66 | 4.43 ~ 4.89 | 36.0 | 34.2 ~ 37.8 |
| 5500 | Head | 4.96 | 4.71 ~ 5.21 | 35.6 | 33.8 ~ 37.4 |
| 5800 | Head | 5.27 | 5.01 ~ 5.53 | 35.3 | 33.5 ~ 37.1 |
| 2450 | Body | 1.95 | 1.85 ~ 2.05 | 52.7 | 50.1 ~ 55.3 |
| 5200 | Body | 5.30 | 5.04 ~ 5.57 | 49.0 | 46.6 ~ 51.5 |
| 5500 | Body | 5.65 | 5.37 ~ 5.93 | 48.6 | 46.2 ~ 51.0 |
| 5800 | Body | 6.00 | 5.70 ~ 6.30 | 48.2 | 45.8 ~ 50.6 |

Table 6.2 Targets of Tissue Simulating Liquid

The dielectric parameters of the liquids were verified prior to the SAR evaluation using an Agilent 85070D Dielectric Probe Kit and an Agilent Network Analyzer.

The following table shows the measuring results for simulating liquid.

| Frequency (MHz) | Liquid Type | Temperature ($^{\circ}\text{C}$) | Conductivity (σ) | Permittivity (ϵ_r) | Measurement Date |
|-----------------|-------------|------------------------------------|---------------------------|-------------------------------|------------------|
| 2450 | Head | 21.6 | 1.85 | 39.3 | Mar. 20, 2011 |
| 2450 | Body | 21.4 | 1.96 | 54.5 | Mar. 20, 2011 |

Table 6.3 Measuring Results for Simulating Liquid

7. Uncertainty Assessment

The component of uncertainty may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainty by the statistical analysis of a series of observations is termed a Type A evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience and knowledge of the behavior and properties of relevant materials and instruments, manufacture’s specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table 7.1

| Uncertainty Distributions | Normal | Rectangular | Triangular | U-Shape |
|------------------------------------|--------------------|--------------------|-------------------|----------------|
| Multi-plying Factor ^(a) | 1/k ^(b) | 1/√3 | 1/√6 | 1/√2 |

(a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity

(b) κ is the coverage factor

Table 7.1 Standard Uncertainty for Assumed Distribution

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual “root-sum-squares” (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %. The DASY uncertainty Budget is showed in Table 7.2 and Table 7.3.



| Error Description | Uncertainty Value (±%) | Probability Distribution | Divisor | Ci (1g) | Standard Uncertainty (1g) |
|--------------------------------------|------------------------|--------------------------|---------|---------|---------------------------|
| Measurement System | | | | | |
| Probe Calibration | 5.5 | Normal | 1 | 1 | ± 5.5 % |
| Axial Isotropy | 4.7 | Rectangular | √3 | 0.7 | ± 1.9 % |
| Hemispherical Isotropy | 9.6 | Rectangular | √3 | 0.7 | ± 3.9 % |
| Boundary Effects | 1.0 | Rectangular | √3 | 1 | ± 0.6 % |
| Linearity | 4.7 | Rectangular | √3 | 1 | ± 2.7 % |
| System Detection Limits | 1.0 | Rectangular | √3 | 1 | ± 0.6 % |
| Readout Electronics | 0.3 | Normal | 1 | 1 | ± 0.3 % |
| Response Time | 0.8 | Rectangular | √3 | 1 | ± 0.5 % |
| Integration Time | 2.6 | Rectangular | √3 | 1 | ± 1.5 % |
| RF Ambient Noise | 3.0 | Rectangular | √3 | 1 | ± 1.7 % |
| RF Ambient Reflections | 3.0 | Rectangular | √3 | 1 | ± 1.7 % |
| Probe Positioner | 0.4 | Rectangular | √3 | 1 | ± 0.2 % |
| Probe Positioning | 2.9 | Rectangular | √3 | 1 | ± 1.7 % |
| Max. SAR Eval. | 1.0 | Rectangular | √3 | 1 | ± 0.6 % |
| Test Sample Related | | | | | |
| Device Positioning | 2.9 | Normal | 1 | 1 | ± 2.9 % |
| Device Holder | 3.6 | Normal | 1 | 1 | ± 3.6 % |
| Power Drift | 5.0 | Rectangular | √3 | 1 | ± 2.9 % |
| Phantom and Setup | | | | | |
| Phantom Uncertainty | 4.0 | Rectangular | √3 | 1 | ± 2.3 % |
| Liquid Conductivity (Target) | 5.0 | Rectangular | √3 | 0.64 | ± 1.8 % |
| Liquid Conductivity (Meas.) | 2.5 | Normal | 1 | 0.64 | ± 1.6 % |
| Liquid Permittivity (Target) | 5.0 | Rectangular | √3 | 0.6 | ± 1.7 % |
| Liquid Permittivity (Meas.) | 2.5 | Normal | 1 | 0.6 | ± 1.5 % |
| Combined Standard Uncertainty | | | | | ± 10.7 % |
| Coverage Factor for 95 % | | | | | K = 2 |
| Expanded Uncertainty | | | | | ± 21.4 % |

Table 7.2 Uncertainty Budget of DASY for frequency range 300 MHz to 3 GHz



| Error Description | Uncertainty Value (±%) | Probability Distribution | Divisor | Ci (1g) | Standard Uncertainty (1g) |
|--------------------------------------|------------------------|--------------------------|---------|---------|---------------------------|
| Measurement System | | | | | |
| Probe Calibration | 6.55 | Normal | 1 | 1 | ± 6.55 % |
| Axial Isotropy | 4.7 | Rectangular | √3 | 0.7 | ± 1.9 % |
| Hemispherical Isotropy | 9.6 | Rectangular | √3 | 0.7 | ± 3.9 % |
| Boundary Effects | 2.0 | Rectangular | √3 | 1 | ± 1.2 % |
| Linearity | 4.7 | Rectangular | √3 | 1 | ± 2.7 % |
| System Detection Limits | 1.0 | Rectangular | √3 | 1 | ± 0.6 % |
| Readout Electronics | 0.3 | Normal | 1 | 1 | ± 0.3 % |
| Response Time | 0.8 | Rectangular | √3 | 1 | ± 0.5 % |
| Integration Time | 2.6 | Rectangular | √3 | 1 | ± 1.5 % |
| RF Ambient Noise | 3.0 | Rectangular | √3 | 1 | ± 1.7 % |
| RF Ambient Reflections | 3.0 | Rectangular | √3 | 1 | ± 1.7 % |
| Probe Positioner | 0.8 | Rectangular | √3 | 1 | ± 0.5 % |
| Probe Positioning | 9.9 | Rectangular | √3 | 1 | ± 5.7 % |
| Max. SAR Eval. | 4.0 | Rectangular | √3 | 1 | ± 2.3 % |
| Test Sample Related | | | | | |
| Device Positioning | 2.9 | Normal | 1 | 1 | ± 2.9 % |
| Device Holder | 3.6 | Normal | 1 | 1 | ± 3.6 % |
| Power Drift | 5.0 | Rectangular | √3 | 1 | ± 2.9 % |
| Phantom and Setup | | | | | |
| Phantom Uncertainty | 4.0 | Rectangular | √3 | 1 | ± 2.3 % |
| Liquid Conductivity (Target) | 5.0 | Rectangular | √3 | 0.43 | ± 1.8 % |
| Liquid Conductivity (Meas.) | 2.5 | Normal | 1 | 0.43 | ± 1.6 % |
| Liquid Permittivity (Target) | 5.0 | Rectangular | √3 | 0.49 | ± 1.7 % |
| Liquid Permittivity (Meas.) | 2.5 | Normal | 1 | 0.49 | ± 1.5 % |
| Combined Standard Uncertainty | | | | | ± 12.8 % |
| Coverage Factor for 95 % | | | | | K = 2 |
| Expanded Uncertainty | | | | | ± 25.6 % |

Table 7.3 Uncertainty Budget of DASY for frequency range 3 GHz to 6 GHz

8. SAR Measurement Evaluation

Each DASY system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system performance check and system validation. System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder.

8.1 Purpose of System Performance check

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

8.2 System Setup

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:

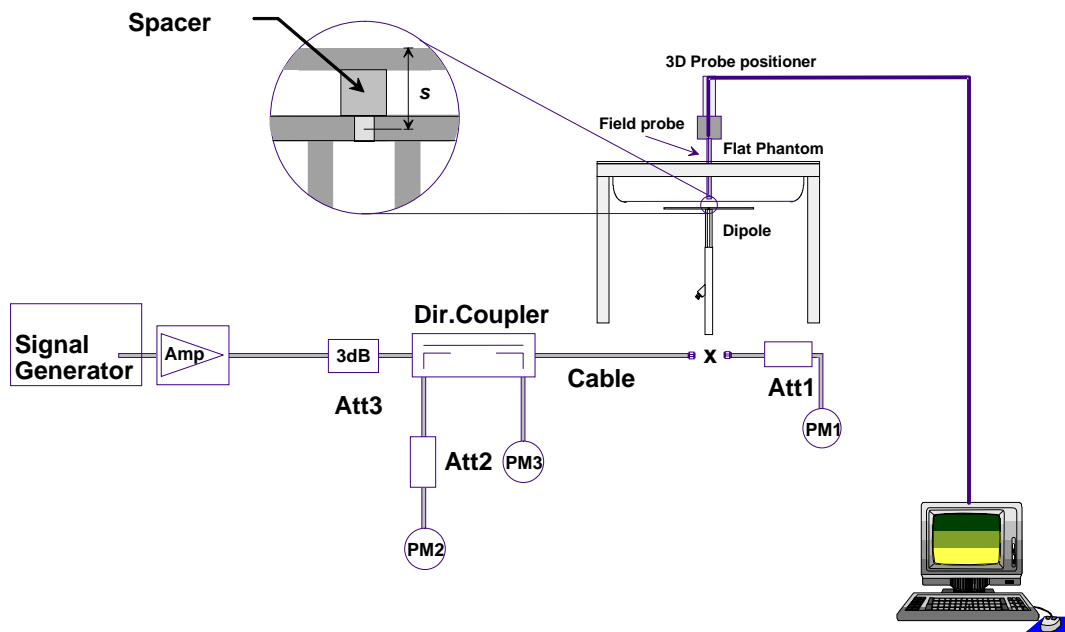


Fig 8.1 System Setup for System Evaluation

1. Signal Generator
2. Amplifier
3. Directional Coupler
4. Power Meter
5. Calibrated Dipole

The output power on dipole port must be calibrated to 24 dBm (250 mW) before dipole is connected.

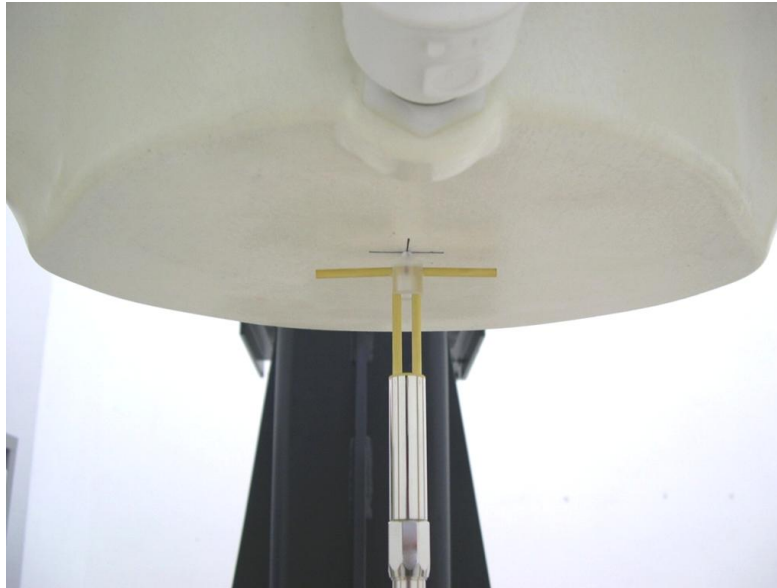


Fig 8.2 Photo of Dipole Setup

8.3 Validation Results

Comparing to the original SAR value provided by SPEAG, the validation data should be within its specification of 10 %. Table 8.1 shows the target SAR and measured SAR after normalized to 1W input power. The table below indicates the system performance check can meet the variation criterion and the plots can be referred to Appendix A of this report.

| Measurement Date | Frequency (MHz) | Targeted SAR _{10g} (W/kg) | Measured SAR _{10g} (W/kg) | Normalized SAR _{10g} (W/kg) | Deviation (%) |
|------------------|-----------------|------------------------------------|------------------------------------|--------------------------------------|---------------|
| Mar. 20, 2011 | 2450 | 52.20 | 14.10 | 56.40 | 8.05 |
| Mar. 20, 2011 | 2450 | 53.50 | 13.50 | 54.00 | 0.93 |

Table 8.1 Target and Measurement SAR after Normalized

9. DUT Testing Position

This DUT was tested in ten different positions. They are Right Cheek, Right Tilted, Left Cheek, Left Tilted, Rear Face of the DUT with phantom 1 cm gap, Front Face of the DUT with phantom 1 cm gap, Left Side of the DUT with phantom 1 cm gap, Right Side of the DUT with phantom 1 cm gap, Top Side of the DUT with phantom 1 cm gap, and Bottom Side of the DUT with phantom 1 cm gap, and as illustrated below:

1. Define two imaginary lines on the handset

- (a) The vertical centerline passes through two points on the front side of the handset - the midpoint of the width w_t of the handset at the level of the acoustic output, and the midpoint of the width w_b of the bottom of the handset.
- (b) The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output. The horizontal line is also tangential to the face of the handset at point A.
- (c) The two lines intersect at point A. Note that for many handsets, point A coincides with the center of the acoustic output; however, the acoustic output may be located elsewhere on the horizontal line. Also note that the vertical centerline is not necessarily parallel to the front face of the handset, especially for clamshell handsets, handsets with flip covers, and other irregularly shaped handsets.

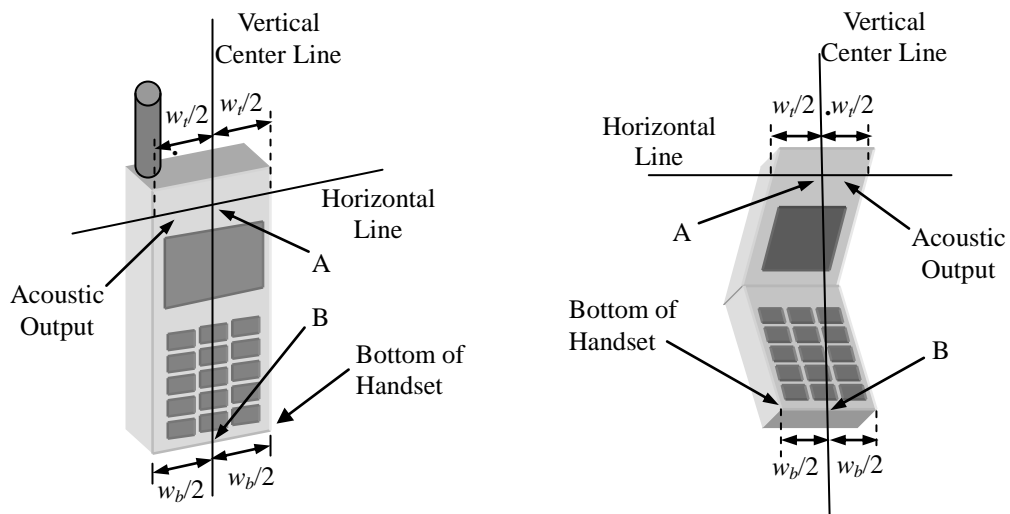


Fig 9.1 Illustration for Handset Vertical and Horizontal Reference Lines

2. Cheek Position

- (a) To position the device with the vertical center line of the body of the device and the horizontal line crossing the center piece in a plane parallel to the sagittal plane of the phantom. While maintaining the device in this plane, align the vertical center line with the reference plane containing the three ear and mouth reference point (M: Mouth, RE: Right Ear, and LE: Left Ear) and align the center of the ear piece with the line RE-LE.
- (b) To move the device towards the phantom with the ear piece aligned with the line LE-RE until the phone touched the ear. While maintaining the device in the reference plane and maintaining the phone contact with the ear, move the bottom of the phone until any point on the front side is in contact with the cheek of the phantom or until contact with the ear is lost (see Fig. 9.2).

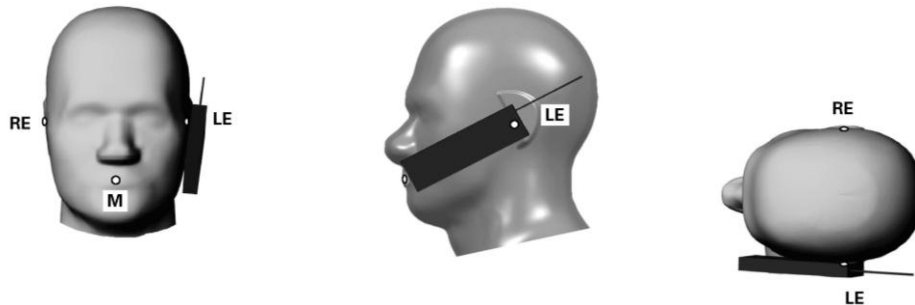


Fig 9.2 Illustration for Cheek Position

3. Tilted Position

- (a) To position the device in the “cheek” position described above.
- (b) While maintaining the device the reference plane described above and pivoting against the ear, moves it outward away from the mouth by an angle of 15 degrees or until contact with the ear is lost (see Fig. 9.3).

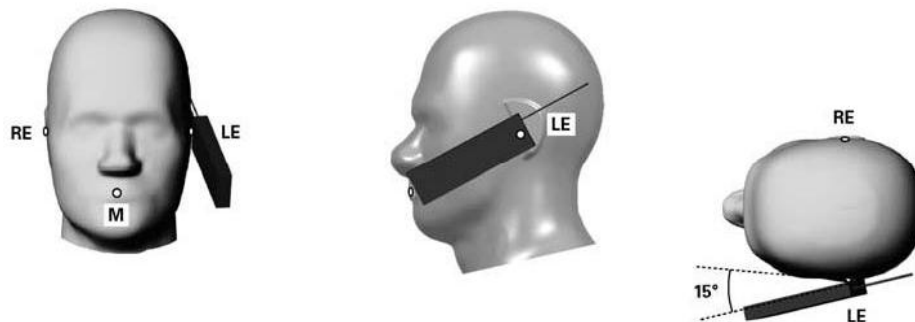


Fig 9.3 Illustration for Tilted Position

4. Body Worn Position

- (a) To position the device parallel to the phantom surface
- (b) To adjust the device parallel to the flat phantom.
- (c) To adjust the distance between the device surface and the flat phantom to 1 cm.

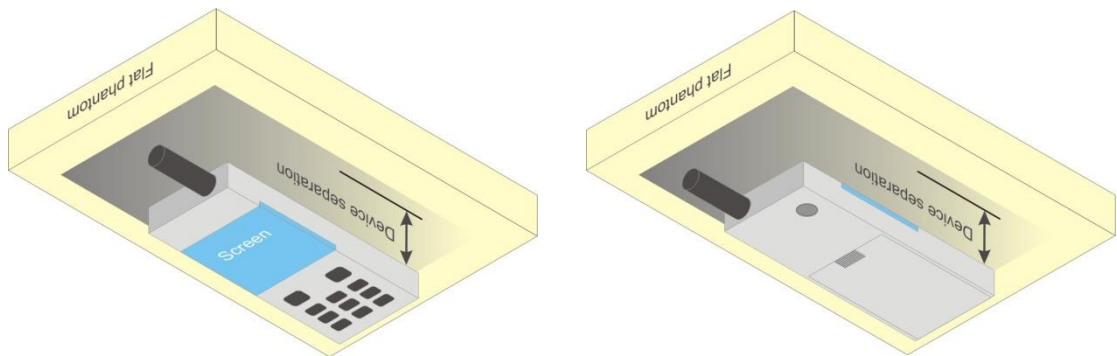


Fig 9.4 Illustration for Body Worn Position

5. DUT Setup Photos

Please refer to Appendix E for the test setup photos.

10. Measurement Procedures

The measurement procedures are as follows:

- (a) Use engineering software to transmit RF power continuously (continuous Tx) in the highest power channel
- (b) Measure output power through RF cable and power meter
- (c) Place the DUT in the positions described in the last section
- (d) Set scan area, grid size and other setting on the DASY software
- (e) Taking data for the middle channel on each testing position
- (f) Find out the largest SAR result on these testing positions of each band
- (g) Measure SAR results for other channels in worst SAR testing position if the SAR of highest power channel is larger than 0.8 W/kg

According to the test standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- (a) Power reference measurement
- (b) Area scan
- (c) Zoom scan
- (d) Power drift measurement

10.1 Spatial Peak SAR Evaluation

The procedure for spatial peak SAR evaluation has been implemented according to the test standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

The entire evaluation of the spatial peak values is performed within the post-processing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- (a) Extraction of the measured data (grid and values) from the Zoom Scan
- (b) Calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- (c) Generation of a high-resolution mesh within the measured volume
- (d) Interpolation of all measured values from the measurement grid to the high-resolution grid
- (e) Extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- (f) Calculation of the averaged SAR within masses of 1g and 10g



10.2 Area & Zoom Scan Procedures

First Area Scan is used to locate the approximate location(s) of the local peak SAR value(s). The measurement grid within an Area Scan is defined by the grid extent, grid step size and grid offset. Next, in order to determine the EM field distribution in a three-dimensional spatial extension, Zoom Scan is required. The Zoom Scan measures 5x5x7 points with step size 8, 8 and 5 mm for 300 MHz to 3 GHz, and 8x8x8 points with step size 4, 4 and 2.5 mm for 3 GHz to 6 GHz. The Zoom Scan is performed around the highest E-field value to determine the averaged SAR-distribution over 10 g.

10.3 Volume Scan Procedures

The volume scan is used for assess overlapping SAR distributions for antennas transmitting in different frequency bands. It is equivalent to an oversized zoom scan used in standalone measurements. The measurement volume will be used to enclose all the simultaneous transmitting antennas. For antennas transmitting simultaneously in different frequency bands, the volume scan is measured separately in each frequency band. In order to sum correctly to compute the 1g aggregate SAR, the DUT remain in the same test position for all measurements and all volume scan use the same spatial resolution and grid spacing (step-size is 4, 4 and 2.5 mm). When all volume scan were completed, the software, SEMCAD postprocessor can combine and subsequently superpose these measurement data to calculating the multiband SAR.

10.4 SAR Averaged Methods

In DASy, the interpolation and extrapolation are both based on the modified Quadratic Shepard's method. The interpolation scheme combines a least-square fitted function method and a weighted average method which are the two basic types of computational interpolation and approximation.

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. The uncertainty increases with the extrapolation distance. To keep the uncertainty within 1% for the 1 g and 10 g cubes, the extrapolation distance should not be larger than 5 mm.

10.5 Power Drift Monitoring

All SAR testing is under the DUT install full charged battery and transmit maximum output power. In DASy measurement software, the power reference measurement and power drift measurement procedures are used for monitoring the power drift of DUT during SAR test. Both these procedures measure the field at a specified reference position before and after the SAR testing. The software will calculate the field difference in dB. If the power drift more than 5%, the SAR will be retested.

11. SAR Test Results

11.1 Conducted Power (Unit: dBm)

| Band | 802.11b | | | 802.11g | | |
|-----------------|---------|-------|-------|---------|-------|-------|
| Channel | 1 | 6 | 11 | 1 | 6 | 11 |
| Frequency (MHz) | 2412 | 2437 | 2462 | 2412 | 2437 | 2462 |
| Peak Power | 16.13 | 16.46 | 16.94 | 18.46 | 18.81 | 18.64 |
| Average Power | 14.03 | 14.48 | 15.12 | 11.21 | 11.66 | 11.91 |

| Band | 802.11n (BW 20MHz) | | |
|-----------------|--------------------|-------|-------|
| Channel | 1 | 6 | 11 |
| Frequency (MHz) | 2412 | 2437 | 2462 |
| Peak Power | 17.82 | 18.39 | 18.16 |
| Average Power | 9.39 | 9.67 | 10.12 |

11.2 Test Records for Head SAR Test

| Plot No. | Band | Test Position | Channel | SAR _{1g} (W/kg) | SAR _{10g} (W/kg) |
|----------|---------|---------------|---------|--------------------------|---------------------------|
| 25 | 802.11b | Right Cheek | 11 | 0.338 | 0.145 |
| 26 | 802.11b | Right Tilted | 11 | 0.201 | 0.102 |
| 27 | 802.11b | Left Cheek | 11 | 0.152 | 0.07 |
| 28 | 802.11b | Left Tilted | 11 | 0.193 | 0.095 |

11.3 Test Records for Body SAR Test

| Plot No. | Band | Test Position | Separation Distance (cm) | Channel | Earphone | SAR _{1g} (W/kg) | SAR _{10g} (W/kg) |
|----------|---------|---------------|--------------------------|---------|----------|--------------------------|---------------------------|
| 29 | 802.11b | Rear Face | 1 | 11 | w/o | 0.235 | 0.112 |
| 30 | 802.11b | Front Face | 1 | 11 | w/o | 0.084 | 0.045 |
| 31 | 802.11b | Left Side | 1 | 11 | w/o | 0.212 | 0.097 |
| 33 | 802.11b | Top Side | 1 | 11 | w/o | 0.091 | 0.048 |
| 35 | 802.11b | Rear Face | 1 | 11 | w/ | 0.211 | 0.098 |

Note: According to October 2010 TCB Workshop RF Exposure Procedures Update, the WLAN Antenna SAR for hotspot mode only Rear Face, Front Face, Left Side, and Top Side are needed due to the antenna location is within 2.5 cm from the edge.

Test Engineer : A-Rod Chen and Robert Liu



12. References

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- [5] SPEAG DASY System Handbook
- [6] FCC KDB 248227 D01 v01r02, “SAR Measurement Procedures for 802.11 a/b/g Transmitters”, May 2007
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- [9] FCC KDB 616217 D01 v01r01, “SAR Evaluation Considerations for Laptop Computers with Antennas Built-in on Display Screens”, November 2009
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- [13] FCC KDB 941225 D03 v01, “Recommended SAR Test Reduction Procedures for GSM / GPRS / EDGE”, December 2008
- [14] FCC KDB 941225 D04 v01, “Evaluating SAR for GSM/(E)GPRS Dual Transfer Mode”, January 27 2010



Appendix A. Plots of System Performance Check

The plots are shown as follows.

System Check_Head_2450MHz_110320

DUT: Dipole 2450 MHz

Communication System: CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: HSL_2450_110320 Medium parameters used: $f = 2450$ MHz; $\sigma = 1.85$ mho/m; $\epsilon_r = 39.3$; $\rho = 1000$ kg/m³

Ambient Temperature : 22.6 °C; Liquid Temperature : 21.6 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.5, 4.5, 4.5); Calibrated: 2010/5/18
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 2011/1/13
- Phantom: SAM-Left; Type: QD 000 P40 C; Serial: TP-1477
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Pin=250mW/Area Scan (61x61x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 16.9 mW/g

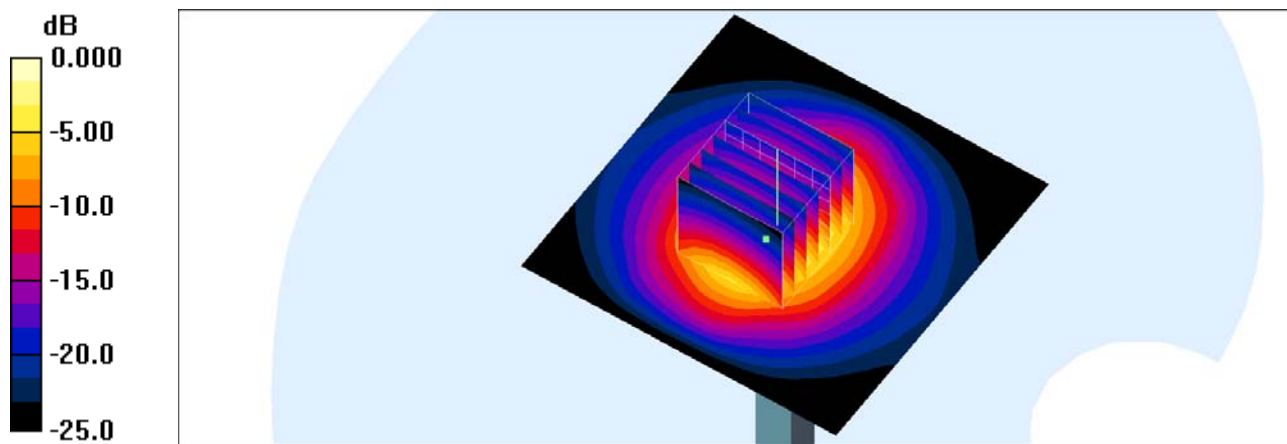
Pin=250mW/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 95.8 V/m; Power Drift = 0.009 dB

Peak SAR (extrapolated) = 31.8 W/kg

SAR(1 g) = 14.1 mW/g; SAR(10 g) = 6.33 mW/g

Maximum value of SAR (measured) = 15.6 mW/g



0 dB = 15.6mW/g

System Check_Body_2450MHz_110320

DUT: Dipole 2450 MHz

Communication System: CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: MSL_2450_110320 Medium parameters used: $f = 2450$ MHz; $\sigma = 1.96$ mho/m; $\epsilon_r = 54.5$; $\rho = 1000$ kg/m³

Ambient Temperature : 22.4 °C ; Liquid Temperature : 21.4 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.03, 4.03, 4.03); Calibrated: 2010/5/18
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 2011/1/13
- Phantom: SAM-Right; Type: QD 000 P40 C; Serial: TP-1383
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Pin=250mW/Area Scan (91x91x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 15.0 mW/g

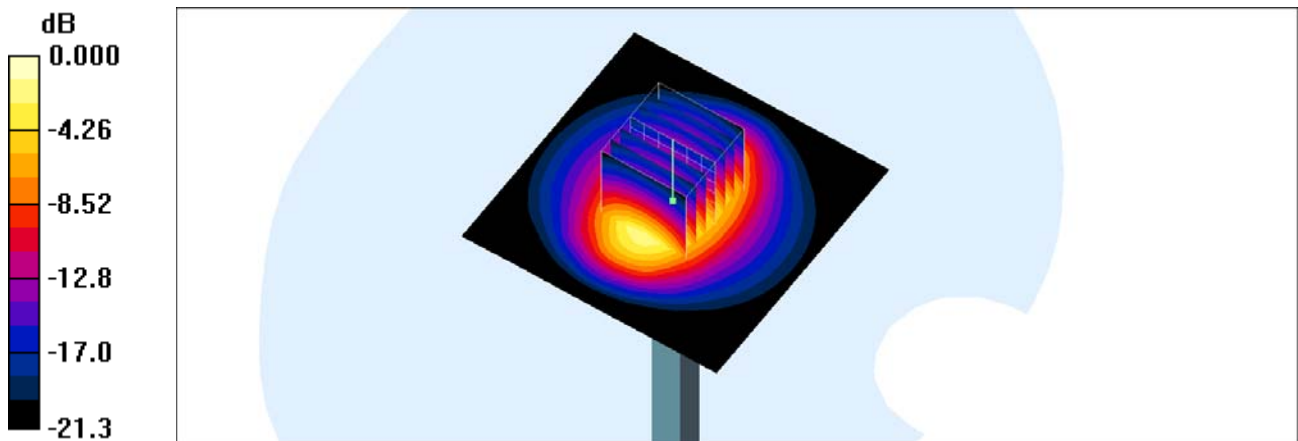
Pin=250mW/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 89.5 V/m; Power Drift = -0.038 dB

Peak SAR (extrapolated) = 32.2 W/kg

SAR(1 g) = 13.5 mW/g; SAR(10 g) = 6.39 mW/g

Maximum value of SAR (measured) = 14.7 mW/g



0 dB = 14.7mW/g



Appendix B. Plots of SAR Measurement

The plots are shown as follows.

#25 802.11b_Right Cheek_Ch11

DUT: 130415

Communication System: 802.11b ; Frequency: 2462 MHz;Duty Cycle: 1:1

Medium: HSL_2450_110320 Medium parameters used: $f = 2462$ MHz; $\sigma = 1.86$ mho/m; $\epsilon_r = 39.2$; $\rho = 1000$ kg/m³

Ambient Temperature : 22.5 °C ; Liquid Temperature : 21.6 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.5, 4.5, 4.5); Calibrated: 2010/5/18
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 2011/1/13
- Phantom: SAM-Left; Type: QD 000 P40 C; Serial: TP-1477
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Ch11/Area Scan (41x81x1): Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.306 mW/g

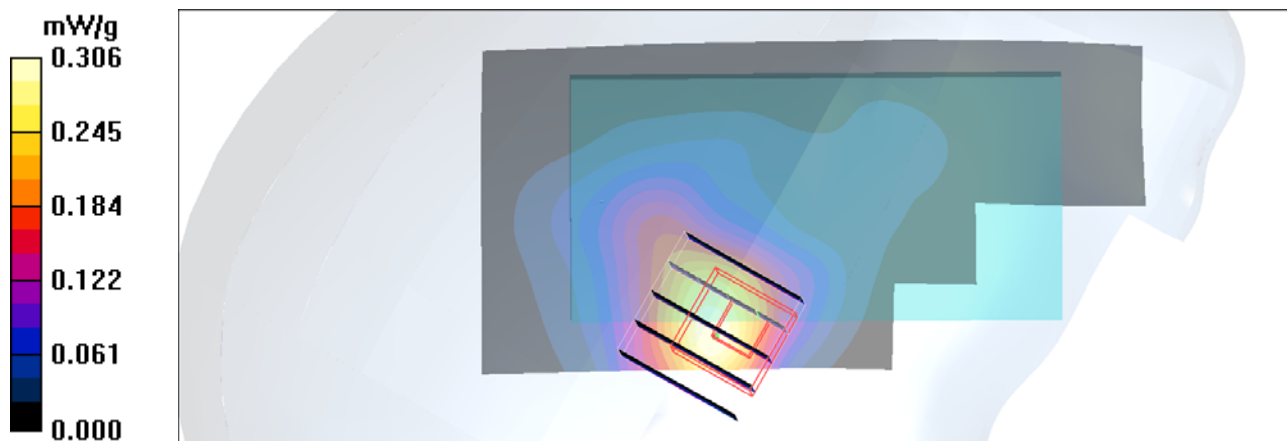
Ch11/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 7.97 V/m; Power Drift = -0.132 dB

Peak SAR (extrapolated) = 0.922 W/kg

SAR(1 g) = 0.338 mW/g; SAR(10 g) = 0.145 mW/g

Maximum value of SAR (measured) = 0.355 mW/g



#25 802.11b_Right Cheek_Ch11_2D

DUT: 130415

Communication System: 802.11b ; Frequency: 2462 MHz;Duty Cycle: 1:1

Medium: HSL_2450_110320 Medium parameters used: $f = 2462$ MHz; $\sigma = 1.86$ mho/m; $\epsilon_r = 39.2$; $\rho = 1000$ kg/m³

Ambient Temperature : 22.5 °C ; Liquid Temperature : 21.6 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.5, 4.5, 4.5); Calibrated: 2010/5/18
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 2011/1/13
- Phantom: SAM-Left; Type: QD 000 P40 C; Serial: TP-1477
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Ch11/Area Scan (41x81x1): Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.306 mW/g

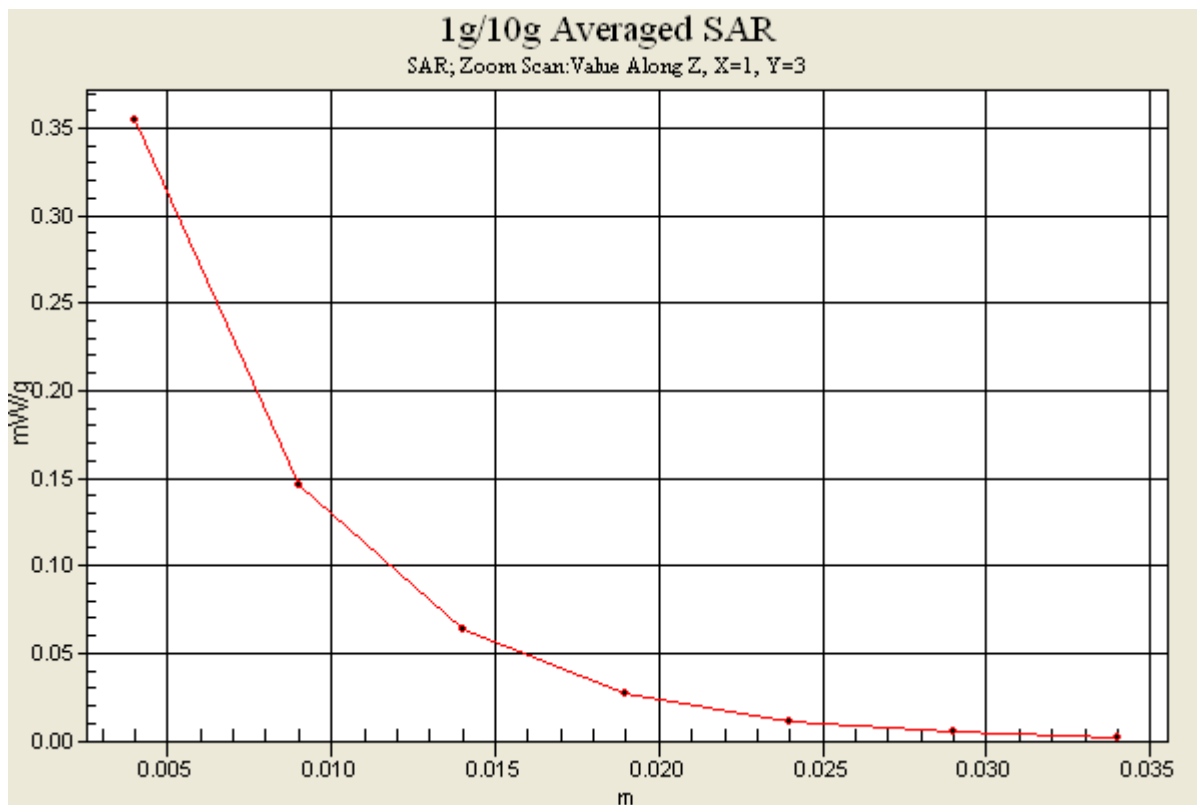
Ch11/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 7.97 V/m; Power Drift = -0.132 dB

Peak SAR (extrapolated) = 0.922 W/kg

SAR(1 g) = 0.338 mW/g; SAR(10 g) = 0.145 mW/g

Maximum value of SAR (measured) = 0.355 mW/g



#26 802.11b_Right Tilted_Ch11

DUT: 130415

Communication System: 802.11b ; Frequency: 2462 MHz;Duty Cycle: 1:1

Medium: HSL_2450_110320 Medium parameters used: $f = 2462$ MHz; $\sigma = 1.86$ mho/m; $\epsilon_r = 39.2$; $\rho = 1000$ kg/m³

Ambient Temperature : 22.4 °C ; Liquid Temperature : 21.6 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.5, 4.5, 4.5); Calibrated: 2010/5/18
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 2011/1/13
- Phantom: SAM-Left; Type: QD 000 P40 C; Serial: TP-1477
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Ch11/Area Scan (41x81x1): Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.208 mW/g

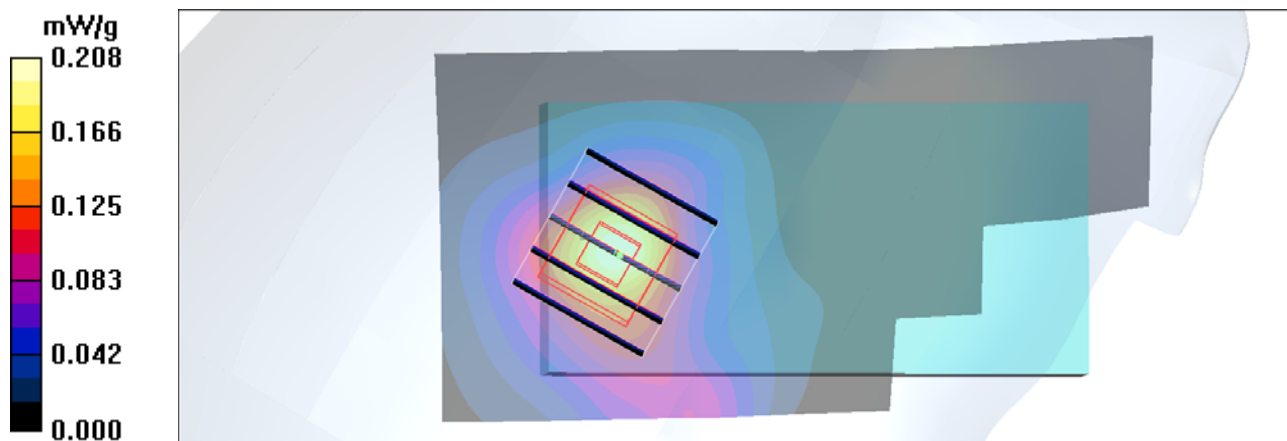
Ch11/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 10.7 V/m; Power Drift = -0.022 dB

Peak SAR (extrapolated) = 0.403 W/kg

SAR(1 g) = 0.201 mW/g; SAR(10 g) = 0.102 mW/g

Maximum value of SAR (measured) = 0.217 mW/g



#27 802.11b_Left Cheek_Ch11

DUT: 130415

Communication System: 802.11b ; Frequency: 2462 MHz;Duty Cycle: 1:1

Medium: HSL_2450_110320 Medium parameters used: $f = 2462$ MHz; $\sigma = 1.86$ mho/m; $\epsilon_r = 39.2$; $\rho = 1000$ kg/m³

Ambient Temperature : 22.6 °C ; Liquid Temperature : 21.6 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.5, 4.5, 4.5); Calibrated: 2010/5/18
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 2011/1/13
- Phantom: SAM-Left; Type: QD 000 P40 C; Serial: TP-1477
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Ch11/Area Scan (41x81x1): Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.132 mW/g

Ch11/Zoom Scan (5x5x7)/Cube 1: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 8.26 V/m; Power Drift = 0.090 dB

Peak SAR (extrapolated) = 0.364 W/kg

SAR(1 g) = 0.152 mW/g; SAR(10 g) = 0.070 mW/g

Maximum value of SAR (measured) = 0.167 mW/g

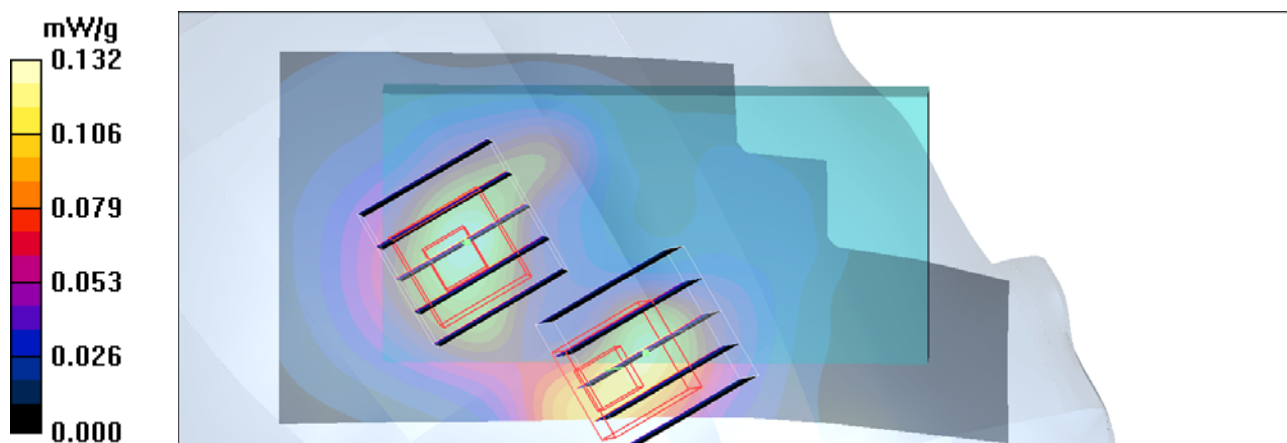
Ch11/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 8.26 V/m; Power Drift = 0.090 dB

Peak SAR (extrapolated) = 0.250 W/kg

SAR(1 g) = 0.132 mW/g; SAR(10 g) = 0.068 mW/g

Maximum value of SAR (measured) = 0.140 mW/g



#28 802.11b_Left Tilted_Ch11

DUT: 130415

Communication System: 802.11b ; Frequency: 2462 MHz;Duty Cycle: 1:1

Medium: HSL_2450_110320 Medium parameters used: $f = 2462$ MHz; $\sigma = 1.86$ mho/m; $\epsilon_r = 39.2$; $\rho = 1000$ kg/m³

Ambient Temperature : 22.5 °C ; Liquid Temperature : 21.6 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.5, 4.5, 4.5); Calibrated: 2010/5/18
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 2011/1/13
- Phantom: SAM-Left; Type: QD 000 P40 C; Serial: TP-1477
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Ch11/Area Scan (41x81x1): Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.185 mW/g

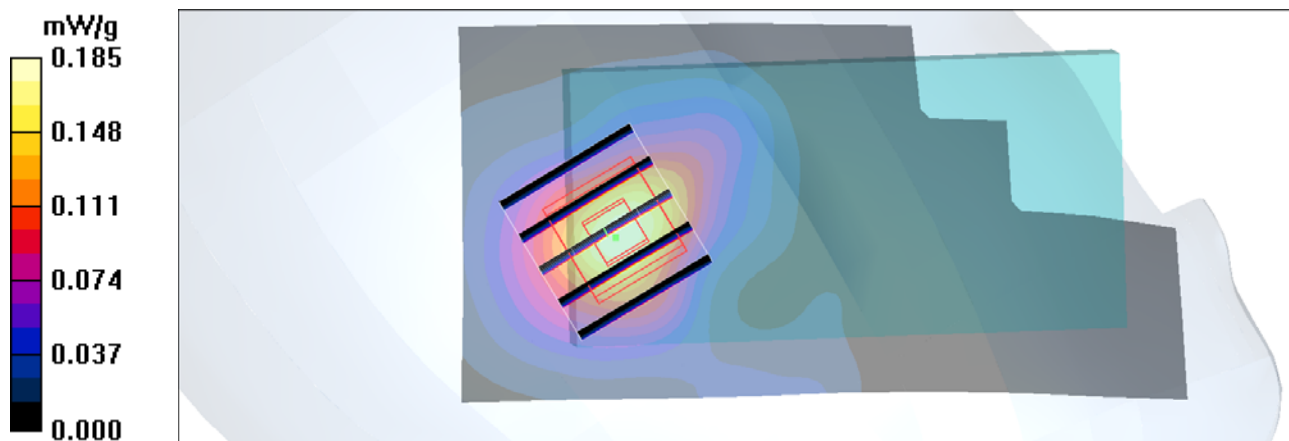
Ch11/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 10.9 V/m; Power Drift = -0.120 dB

Peak SAR (extrapolated) = 0.391 W/kg

SAR(1 g) = 0.193 mW/g; SAR(10 g) = 0.095 mW/g

Maximum value of SAR (measured) = 0.215 mW/g



#29 802.11b_Tgct' Heg_1cm_Ch11

DUT: 130415

Communication System: 802.11b ; Frequency: 2462 MHz; Duty Cycle: 1:1

Medium: MSL_2450_110320 Medium parameters used: $f = 2462$ MHz; $\sigma = 1.98$ mho/m; $\epsilon_r = 54.5$; $\rho = 1000$ kg/m³

Ambient Temperature : 22.4 °C ; Liquid Temperature : 21.4 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.03, 4.03, 4.03); Calibrated: 2010/5/18
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 2011/1/13
- Phantom: SAM-Right; Type: QD 000 P40 C; Serial: TP-1383
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Ch11/Area Scan (41x71x1): Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.233 mW/g

Ch11/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 6.18 V/m; Power Drift = -0.139 dB

Peak SAR (extrapolated) = 0.607 W/kg

SAR(1 g) = 0.235 mW/g; SAR(10 g) = 0.112 mW/g

Maximum value of SAR (measured) = 0.238 mW/g

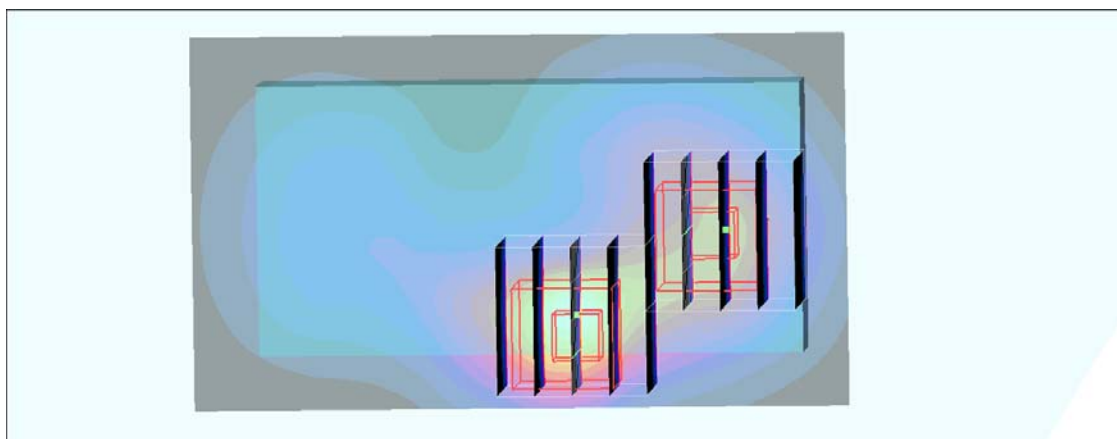
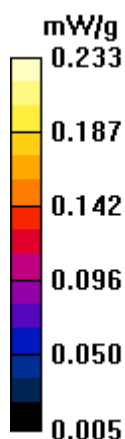
Ch11/Zoom Scan (5x5x7)/Cube 1: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 6.18 V/m; Power Drift = -0.139 dB

Peak SAR (extrapolated) = 0.324 W/kg

SAR(1 g) = 0.155 mW/g; SAR(10 g) = 0.084 mW/g

Maximum value of SAR (measured) = 0.158 mW/g



#29 802.11b_Tgct' Heg_1cm_Ch11_2D

DUT: 130415

Communication System: 802.11b ; Frequency: 2462 MHz; Duty Cycle: 1:1

Medium: MSL_2450_110320 Medium parameters used: $f = 2462$ MHz; $\sigma = 1.98$ mho/m; $\epsilon_r = 54.5$;

$\rho = 1000$ kg/m³

Ambient Temperature : 22.4 °C ; Liquid Temperature : 21.4 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.03, 4.03, 4.03); Calibrated: 2010/5/18

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn577; Calibrated: 2011/1/13

- Phantom: SAM-Right; Type: QD 000 P40 C; Serial: TP-1383

- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Ch11/Area Scan (41x71x1): Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.233 mW/g

Ch11/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 6.18 V/m; Power Drift = -0.139 dB

Peak SAR (extrapolated) = 0.607 W/kg

SAR(1 g) = 0.235 mW/g; SAR(10 g) = 0.112 mW/g

Maximum value of SAR (measured) = 0.238 mW/g

Ch11/Zoom Scan (5x5x7)/Cube 1: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 6.18 V/m; Power Drift = -0.139 dB

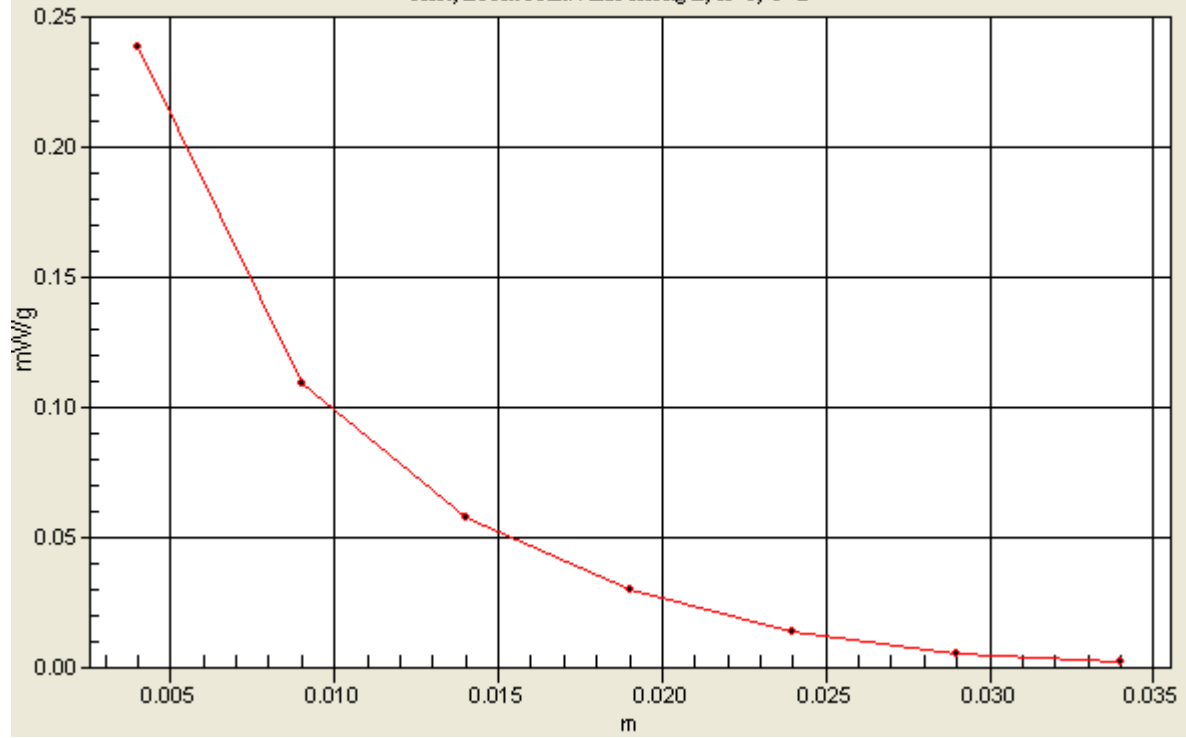
Peak SAR (extrapolated) = 0.324 W/kg

SAR(1 g) = 0.155 mW/g; SAR(10 g) = 0.084 mW/g

Maximum value of SAR (measured) = 0.158 mW/g

1g/10g Averaged SAR

SAR; Zoom Scan: Value Along Z, X=1, Y=2



#30 802.11b_HttpvFace_1cm_Ch11

DUT: 130415

Communication System: 802.11b ; Frequency: 2462 MHz;Duty Cycle: 1:1

Medium: MSL_2450_110320 Medium parameters used: $f = 2462$ MHz; $\sigma = 1.98$ mho/m; $\epsilon_r = 54.5$; ρ

$= 1000$ kg/m³

Ambient Temperature : 22.5 °C ; Liquid Temperature : 21.4 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.03, 4.03, 4.03); Calibrated: 2010/5/18
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 2011/1/13
- Phantom: SAM-Right; Type: QD 000 P40 C; Serial: TP-1383
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Ch11/Area Scan (41x71x1): Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.087 mW/g

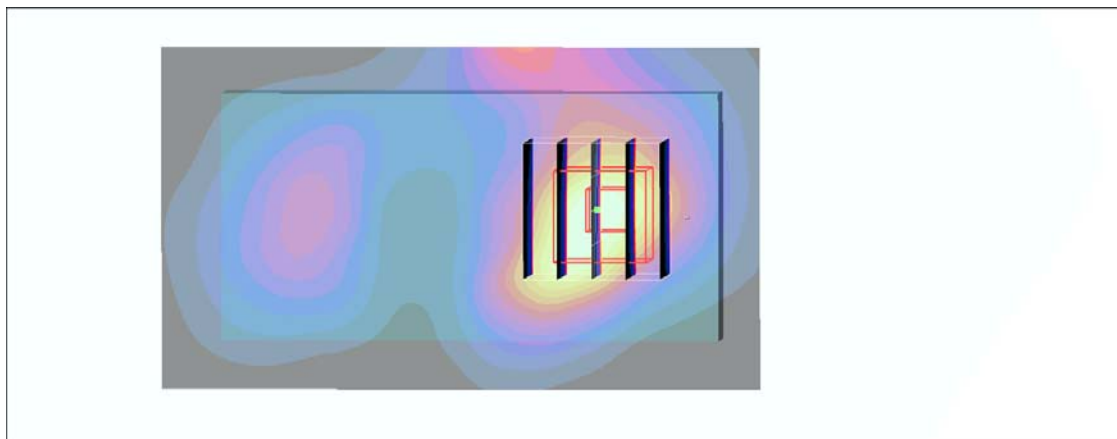
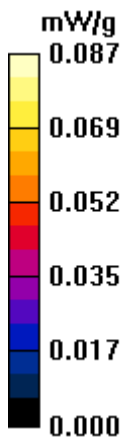
Ch11/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 2.60 V/m; Power Drift = 0.143 dB

Peak SAR (extrapolated) = 0.186 W/kg

SAR(1 g) = 0.084 mW/g; SAR(10 g) = 0.045 mW/g

Maximum value of SAR (measured) = 0.088 mW/g



#31 802.11b_Left Side_1cm_Ch11

DUT: 130415

Communication System: 802.11b ; Frequency: 2462 MHz;Duty Cycle: 1:1

Medium: MSL_2450_110320 Medium parameters used: $f = 2462$ MHz; $\sigma = 1.98$ mho/m; $\epsilon_r = 54.5$; ρ

$= 1000$ kg/m³

Ambient Temperature : 22.3 °C ; Liquid Temperature : 21.4 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.03, 4.03, 4.03); Calibrated: 2010/5/18
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 2011/1/13
- Phantom: SAM-Right; Type: QD 000 P40 C; Serial: TP-1383
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Ch11/Area Scan (31x71x1): Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.205 mW/g

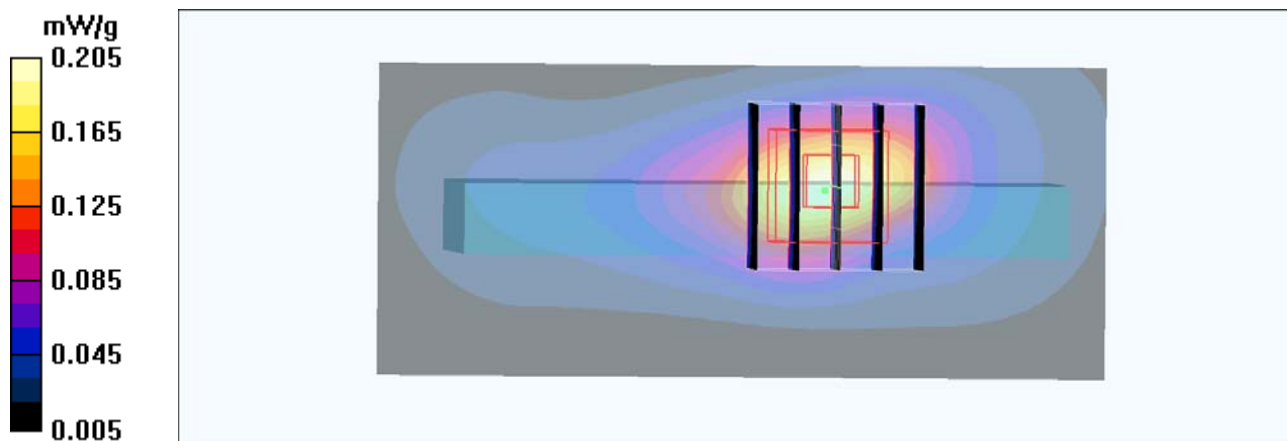
Ch11/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 8.27 V/m; Power Drift = 0.061 dB

Peak SAR (extrapolated) = 0.533 W/kg

SAR(1 g) = 0.212 mW/g; SAR(10 g) = 0.097 mW/g

Maximum value of SAR (measured) = 0.234 mW/g



#33 802.11b_Top Side_1cm_Ch11

DUT: 130415

Communication System: 802.11b ; Frequency: 2462 MHz;Duty Cycle: 1:1

Medium: MSL_2450_110320 Medium parameters used: $f = 2462$ MHz; $\sigma = 1.98$ mho/m; $\epsilon_r = 54.5$; $\rho = 1000$ kg/m³

Ambient Temperature : 22.4 °C ; Liquid Temperature : 21.4 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.03, 4.03, 4.03); Calibrated: 2010/5/18
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 2011/1/13
- Phantom: SAM-Right; Type: QD 000 P40 C; Serial: TP-1383
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Ch11/Area Scan (31x41x1): Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.093 mW/g

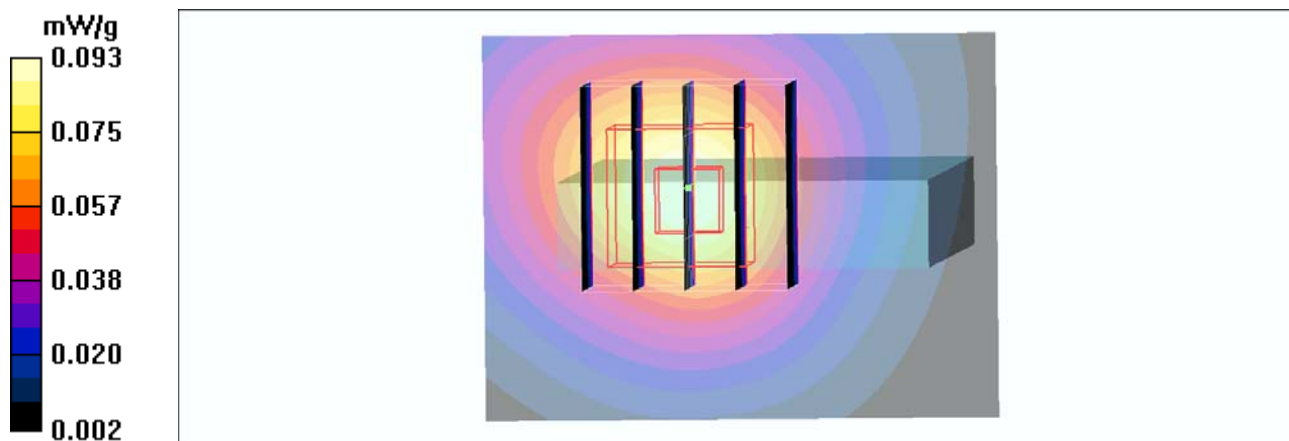
Ch11/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 6.61 V/m; Power Drift = 0.108 dB

Peak SAR (extrapolated) = 0.196 W/kg

SAR(1 g) = 0.091 mW/g; SAR(10 g) = 0.048 mW/g

Maximum value of SAR (measured) = 0.094 mW/g





Appendix C. DAS Y Calibration Certificate

The DAS Y calibration certificates are shown as follows.



Calibration Laboratory of Schmid & Partner Engineering AG, Zeughausstrasse 43, 8004 Zurich, Switzerland



S Schweizerischer Kalibrierdienst, C Service suisse d'étalonnage, S Servizio svizzero di taratura, S Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS) The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: SCS 108

Client Auden

Certificate No: D2450V2-735_Jun10

CALIBRATION CERTIFICATE

Object: D2450V2 - SN: 735
Calibration procedure(s): QA CAL-05.v7
Calibration date: June 17, 2010
This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.
Calibration Equipment used (M&TE critical for calibration)
Primary Standards table with columns: Primary Standards, ID #, Cal Date (Certificate No.), Scheduled Calibration.
Secondary Standards table with columns: Secondary Standards, ID #, Check Date (in house), Scheduled Check.
Calibrated by: Claudio Leubler, Laboratory Technician
Approved by: Katja Pokovic, Technical Manager
Issued: June 21, 2010

**Calibration Laboratory of
Schmid & Partner
Engineering AG**
Zeughausstrasse 43, 8004 Zurich, Switzerland



S Schweizerischer Kalibrierdienst
S Service suisse d'étalonnage
C Servizio svizzero di taratura
S Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)
The Swiss Accreditation Service is one of the signatories to the EA
Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Glossary:

| | |
|-------|---------------------------------|
| TSL | tissue simulating liquid |
| ConvF | sensitivity in TSL / NORM x,y,z |
| N/A | not applicable or not measured |

Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005
- Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

Additional Documentation:

- DASY4/5 System Handbook

Methods Applied and Interpretation of Parameters:

- Measurement Conditions:** Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL:** The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss:** These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- Electrical Delay:** One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured:** SAR measured at the stated antenna input power.
- SAR normalized:** SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters:** The measured TSL parameters are used to calculate the nominal SAR result.



Measurement Conditions

DASY system configuration, as far as not given on page 1.

| | | |
|------------------------------|---------------------------|-------------|
| DASY Version | DASY5 | V52.2 |
| Extrapolation | Advanced Extrapolation | |
| Phantom | Modular Flat Phantom V4.9 | |
| Distance Dipole Center - TSL | 10 mm | with Spacer |
| Zoom Scan Resolution | dx, dy, dz = 5 mm | |
| Frequency | 2450 MHz ± 1 MHz | |

Head TSL parameters

The following parameters and calculations were applied.

| | Temperature | Permittivity | Conductivity |
|----------------------------------|-----------------|--------------|------------------|
| Nominal Head TSL parameters | 22.0 °C | 39.2 | 1.80 mho/m |
| Measured Head TSL parameters | (22.0 ± 0.2) °C | 38.9 ± 6 % | 1.78 mho/m ± 6 % |
| Head TSL temperature during test | (22.0 ± 0.2) °C | ---- | ---- |

SAR result with Head TSL

| SAR averaged over 1 cm ³ (1 g) of Head TSL | Condition | |
|---|--------------------|----------------------------------|
| SAR measured | 250 mW input power | 13.0 mW / g |
| SAR normalized | normalized to 1W | 52.0 mW / g |
| SAR for nominal Head TSL parameters | normalized to 1W | 52.2 mW /g ± 17.0 % (k=2) |

| SAR averaged over 10 cm ³ (10 g) of Head TSL | condition | |
|---|--------------------|----------------------------------|
| SAR measured | 250 mW input power | 6.10 mW / g |
| SAR normalized | normalized to 1W | 24.4 mW / g |
| SAR for nominal Head TSL parameters | normalized to 1W | 24.4 mW /g ± 16.5 % (k=2) |



Body TSL parameters

The following parameters and calculations were applied.

| | Temperature | Permittivity | Conductivity |
|---|-----------------|--------------|------------------|
| Nominal Body TSL parameters | 22.0 °C | 52.7 | 1.95 mho/m |
| Measured Body TSL parameters | (22.0 ± 0.2) °C | 52.7 ± 6 % | 1.96 mho/m ± 6 % |
| Body TSL temperature during test | (22.0 ± 0.2) °C | ---- | ---- |

SAR result with Body TSL

| SAR averaged over 1 cm³ (1 g) of Body TSL | Condition | |
|---|--------------------|-----------------------------------|
| SAR measured | 250 mW input power | 13.4 mW / g |
| SAR normalized | normalized to 1W | 53.6 mW / g |
| SAR for nominal Body TSL parameters | normalized to 1W | 53.5 mW / g ± 17.0 % (k=2) |

| SAR averaged over 10 cm³ (10 g) of Body TSL | condition | |
|---|--------------------|-----------------------------------|
| SAR measured | 250 mW input power | 6.28 mW / g |
| SAR normalized | normalized to 1W | 25.1 mW / g |
| SAR for nominal Body TSL parameters | normalized to 1W | 25.1 mW / g ± 16.5 % (k=2) |



Appendix

Antenna Parameters with Head TSL

| | |
|--------------------------------------|--------------------------------|
| Impedance, transformed to feed point | 53.8 Ω + 3.4 j Ω |
| Return Loss | - 25.1 dB |

Antenna Parameters with Body TSL

| | |
|--------------------------------------|--------------------------------|
| Impedance, transformed to feed point | 50.5 Ω + 3.7 j Ω |
| Return Loss | - 26.5 dB |

General Antenna Parameters and Design

| | |
|----------------------------------|----------|
| Electrical Delay (one direction) | 1.154 ns |
|----------------------------------|----------|

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.

No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

| | |
|-----------------|--------------|
| Manufactured by | SPEAG |
| Manufactured on | May 07, 2003 |

DASY5 Validation Report for Head TSL

Date/Time: 16.06.2010 10:56:25

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN:735

Communication System: CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: HSL U11 BB

Medium parameters used: $f = 2450$ MHz; $\sigma = 1.78$ mho/m; $\epsilon_r = 38.9$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

- Probe: ES3DV3 - SN3205; ConvF (4.53, 4.53, 4.53); Calibrated: 30.04.2010
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 10.06.2010
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; Serial: 1001
- Measurement SW: DASY52, V52.2 Build 0, Version 52.2.0 (163)
- Postprocessing SW: SEMCAD X, V14.2 Build 2, Version 14.2.2 (1685)

Head/d=10mm, Pin=250 mW, dist=3.0mm (ES-Probe)/Zoom Scan (7x7x7) (7x7x7)/Cube 0:

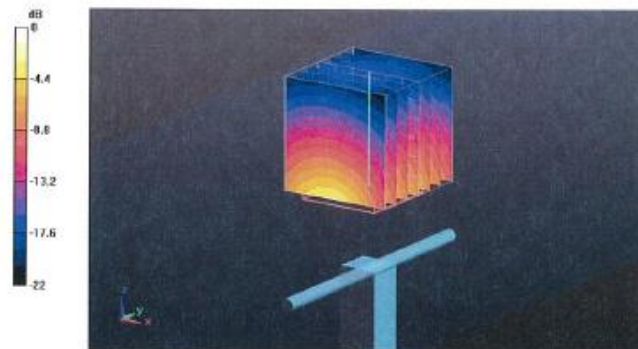
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 100.3 V/m; Power Drift = 0.046 dB

Peak SAR (extrapolated) = 26.6 W/kg

SAR(1 g) = 13 mW/g; SAR(10 g) = 6.1 mW/g

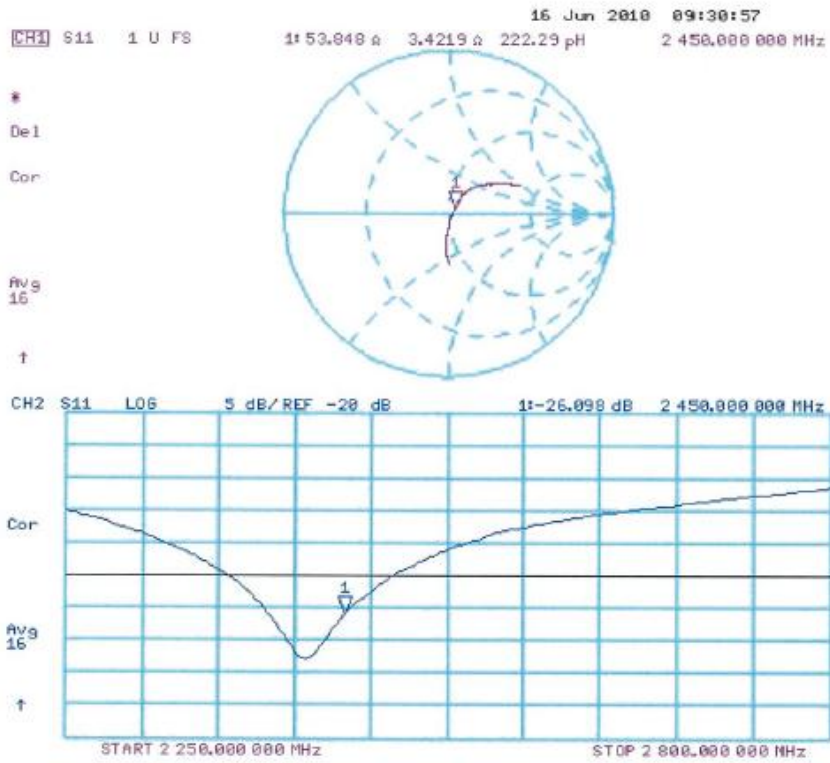
Maximum value of SAR (measured) = 16.6 mW/g



0 dB = 16.6mW/g



Impedance Measurement Plot for Head TSL



DASY5 Validation Report for Body

Date/Time: 17.06.2010 11:28:23

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN:735

Communication System: CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: MSL U11 BB

Medium parameters used: $f = 2450$ MHz; $\sigma = 1.96$ mho/m; $\epsilon_r = 52.7$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

Measurement Standard: DASYS (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

- Probe: ES3DV3 - SN3205; ConvF(4.31, 4.31, 4.31); Calibrated: 30.04.2010
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 10.06.2010
- Phantom: Flat Phantom 5.0 (back); Type: QD000P50AA; Serial: 1002
- Measurement SW: DASYS2, V52.2 Build 0, Version 52.2.0 (163)
- Postprocessing SW: SEMCAD X, V14.2 Build 2, Version 14.2.2 (1685)

Body/d=10mm, Pin250 mW, dist=3.0mm (ES-Probe)/Zoom Scan (7x7x7) (7x7x7)/Cube 0:

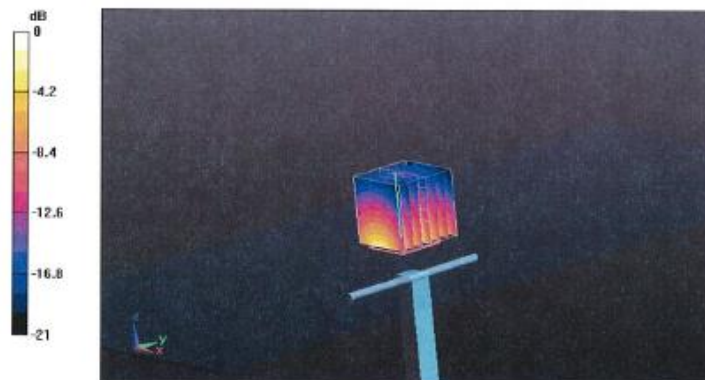
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 94.8 V/m; Power Drift = 0.073 dB

Peak SAR (extrapolated) = 27.7 W/kg

SAR(1 g) = 13.4 mW/g; SAR(10 g) = 6.28 mW/g

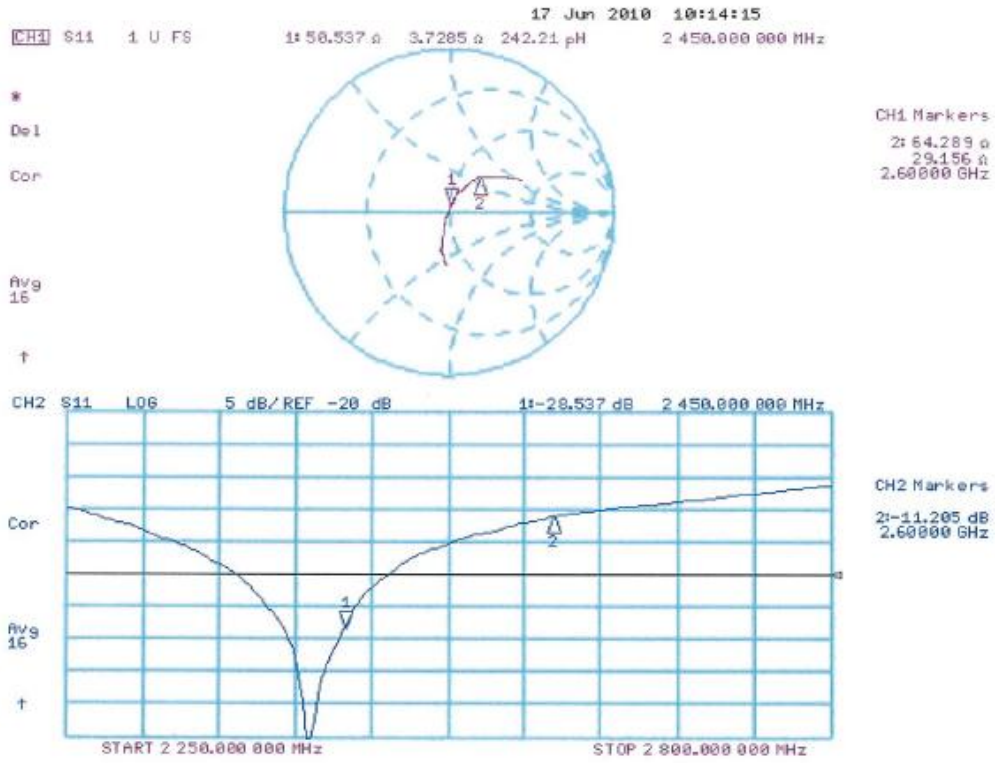
Maximum value of SAR (measured) = 16.7 mW/g



0 dB = 16.7mW/g



Impedance Measurement Plot for Body TSL





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Accreditation No.: SCS 108

Client Sporton (Auden)

Certificate No: DAE3-577_Jan11

CALIBRATION CERTIFICATE

Object: DAE3 - SD 000 D03 AA - SN: 577
Calibration procedure(s): QA CAL-06.v22 Calibration procedure for the data acquisition electronics (DAE)
Calibration date: January 13, 2011

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Table with 4 columns: Standards, ID #, Date, and Calibration/Check status. Includes Primary Standards (Keithley Multimeter) and Secondary Standards (Calibrator Box).

Calibrated by: Andrea Guntli, Technician
Approved by: Fin Bomholt, R&D Director

Issued: January 13, 2011

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Accreditation No.: SCS 108

Glossary

DAE data acquisition electronics
Connector angle information used in DAS Y system to align probe sensor X to the robot coordinate system.

Methods Applied and Interpretation of Parameters

- *DC Voltage Measurement*: Calibration Factor assessed for use in DAS Y system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle*: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
 - *DC Voltage Measurement Linearity*: Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
 - *Common mode sensitivity*: Influence of a positive or negative common mode voltage on the differential measurement.
 - *Channel separation*: Influence of a voltage on the neighbor channels not subject to an input voltage.
 - *AD Converter Values with inputs shorted*: Values on the internal AD converter corresponding to zero input voltage
 - *Input Offset Measurement*: Output voltage and statistical results over a large number of zero voltage measurements.
 - *Input Offset Current*: Typical value for information; Maximum channel input offset current, not considering the input resistance.
 - *Input resistance*: Typical value for information: DAC input resistance at the connector, during internal auto-zeroing and during measurement.
 - *Low Battery Alarm Voltage*: Typical value for information. Below this voltage, a battery alarm signal is generated.
 - *Power consumption*: Typical value for information. Supply currents in various operating modes.



DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1µV , full range = -100...+300 mV

Low Range: 1LSB = 61nV , full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| Calibration Factors | X | Y | Z |
|---------------------|----------------------|----------------------|----------------------|
| High Range | 404.389 ± 0.1% (k=2) | 403.857 ± 0.1% (k=2) | 404.295 ± 0.1% (k=2) |
| Low Range | 3.93277 ± 0.7% (k=2) | 3.93544 ± 0.7% (k=2) | 3.95803 ± 0.7% (k=2) |

Connector Angle

| | |
|---|---------------|
| Connector Angle to be used in DASY system | 102.0 ° ± 1 ° |
|---|---------------|



Appendix

1. DC Voltage Linearity

| High Range | Heading (μV) | Difference (μV) | Error (%) |
|-------------------|---------------------------|------------------------------|-----------|
| Channel X + Input | 200005.8 | 1.57 | 0.00 |
| Channel X + Input | 20004.13 | 3.33 | 0.02 |
| Channel X - Input | -19995.53 | 4.67 | -0.02 |
| Channel Y + Input | 200003.4 | 0.31 | 0.00 |
| Channel Y + Input | 19999.89 | 0.09 | 0.00 |
| Channel Y - Input | -20000.18 | -0.28 | 0.00 |
| Channel Z + Input | 200002.7 | 0.22 | 0.00 |
| Channel Z + Input | 19999.37 | -0.63 | -0.00 |
| Channel Z - Input | -19999.27 | 0.43 | -0.00 |

| Low Range | Reading (μV) | Difference (μV) | Error (%) |
|-------------------|---------------------------|------------------------------|-----------|
| Channel X + Input | 2000.0 | -0.14 | -0.01 |
| Channel X + Input | 199.95 | -0.05 | -0.03 |
| Channel X - Input | -200.10 | -0.10 | 0.05 |
| Channel Y + Input | 2000.0 | -0.12 | -0.01 |
| Channel Y + Input | 199.43 | -0.57 | -0.29 |
| Channel Y - Input | -201.05 | -1.25 | 0.63 |
| Channel Z + Input | 1999.5 | -0.28 | -0.01 |
| Channel Z + Input | 198.64 | -1.56 | -0.78 |
| Channel Z - Input | -200.91 | -0.81 | 0.40 |

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| | Common mode Input Voltage (mV) | High Range Average Reading (μV) | Low Range Average Reading (μV) |
|-----------|--------------------------------|--|---|
| Channel X | 200 | 14.61 | 12.98 |
| | - 200 | -11.87 | -13.38 |
| Channel Y | 200 | -6.98 | -7.04 |
| | - 200 | 5.39 | 5.42 |
| Channel Z | 200 | -1.74 | -1.94 |
| | - 200 | 0.61 | 0.35 |

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| | Input Voltage (mV) | Channel X (μV) | Channel Y (μV) | Channel Z (μV) |
|-----------|--------------------|-----------------------------|-----------------------------|-----------------------------|
| Channel X | 200 | - | 3.35 | 0.10 |
| Channel Y | 200 | 2.66 | - | 2.41 |
| Channel Z | 200 | 2.57 | 0.13 | - |



4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| | High Range (LSB) | Low Range (LSB) |
|-----------|------------------|-----------------|
| Channel X | 15969 | 16221 |
| Channel Y | 15855 | 15246 |
| Channel Z | 16222 | 17974 |

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10M Ω

| | Average (μ V) | min. Offset (μ V) | max. Offset (μ V) | Std. Deviation (μ V) |
|-----------|--------------------|------------------------|------------------------|---------------------------|
| Channel X | -1.07 | -4.93 | 0.31 | 0.67 |
| Channel Y | -0.69 | -1.59 | 0.48 | 0.40 |
| Channel Z | -1.47 | -2.56 | -0.81 | 0.32 |

6. Input Offset Current

Nominal input circuitry offset current on all channels: <25fA

7. Input Resistance (Typical values for information)

| | Zeroing (kOhm) | Measuring (MOhm) |
|-----------|----------------|------------------|
| Channel X | 200 | 200 |
| Channel Y | 200 | 200 |
| Channel Z | 200 | 200 |

8. Low Battery Alarm Voltage (Typical values for information)

| Typical values | Alarm Level (VDC) |
|----------------|-------------------|
| Supply (+ Vcc) | +7.9 |
| Supply (- Vcc) | -7.6 |

9. Power Consumption (Typical values for information)

| Typical values | Switched off (mA) | Stand by (mA) | Transmitting (mA) |
|----------------|-------------------|---------------|-------------------|
| Supply (+ Vcc) | +0.01 | +6 | +14 |
| Supply (- Vcc) | -0.01 | -8 | -9 |



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Accreditation No.: SCS 108

Client Sporton (Auden)

Certificate No: ET3-1787_May10

CALIBRATION CERTIFICATE

Object: ET3DV6 - SN:1787
Calibration procedure(s): QA CAL-01.v6, QA CAL-23.v3 and QA CAL-25.v2
Calibration date: May 18, 2010

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Table with 4 columns: Primary Standards, ID #, Cal Date (Certificate No.), Scheduled Calibration. Lists various power meters, sensors, attenuators, and probes with their respective IDs and calibration dates.

Table with 4 columns: Secondary Standards, ID #, Check Date (in house), Scheduled Check. Lists RF generator and Network Analyzer with their IDs and check dates.

Calibrated by: Jeton Kastrali, Laboratory Technician
Approved by: Katja Pokovic, Technical Manager

Handwritten signatures of Jeton Kastrali and Katja Pokovic.

Issued: May 22, 2010

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

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Accreditation No.: **SCS 108**

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Glossary:

| | |
|--------------------------|---|
| TSL | tissue simulating liquid |
| NORM _{x,y,z} | sensitivity in free space |
| ConvF | sensitivity in TSL / NORM _{x,y,z} |
| DCP | diode compression point |
| CF | crest factor (1/duty_cycle) of the RF signal |
| A, B, C | modulation dependent linearization parameters |
| Polarization φ | φ rotation around probe axis |
| Polarization ϑ | ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis |

Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}**: Assessed for E-field polarization $\vartheta = 0$ ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide). NORM_{x,y,z} are only intermediate values, i.e., the uncertainties of NORM_{x,y,z} does not effect the E²-field uncertainty inside TSL (see below *ConvF*).
- NORM(f)_{x,y,z}** = NORM_{x,y,z} * *frequency_response* (see Frequency Response Chart). This linearization is implemented in DAS Y4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of *ConvF*.
- DCP_{x,y,z}**: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; VR_{x,y,z}**: A, B, C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters**: Assessed in flat phantom using E-field (or Temperature Transfer Standard for $f \leq 800$ MHz) and inside waveguide using analytical field distributions based on power measurements for $f > 800$ MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DAS Y4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORM_{x,y,z} * *ConvF* whereby the uncertainty corresponds to that given for *ConvF*. A frequency dependent *ConvF* is used in DAS Y version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy)**: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset**: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.



ET3DV6 SN:1787

May 18, 2010

Probe ET3DV6

SN:1787

| | |
|------------------|--------------|
| Manufactured: | May 28, 2003 |
| Last calibrated: | May 26, 2009 |
| Recalibrated: | May 18, 2010 |

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)



ET3DV6 SN:1787

May 18, 2010

DASY/EASY - Parameters of Probe: ET3DV6 SN:1787

Basic Calibration Parameters

| | Sensor X | Sensor Y | Sensor Z | Unc (k=2) |
|---|----------|----------|----------|--------------|
| Norm ($\mu\text{V}/(\text{V}/\text{m})^2$) ^A | 1.60 | 1.79 | 2.10 | $\pm 10.1\%$ |
| DCP (mV) ^B | 92.4 | 95.5 | 91.0 | |

Modulation Calibration Parameters

| UID | Communication System Name | PAR | | A dB | B dBuV | C | VR mV | Unc ^E (k=2) |
|-------|---------------------------|------|---|---------|-----------|------|----------|---------------------------|
| 10000 | CW | 0.00 | X | 0.00 | 0.00 | 1.00 | 300.0 | $\pm 1.5\%$ |
| | | | Y | 0.00 | 0.00 | 1.00 | 300.0 | |
| | | | Z | 0.00 | 0.00 | 1.00 | 300.0 | |

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^A The uncertainties of NormX,Y,Z do not affect the E-field uncertainty inside TSL (see Pages 5 and 6).

^B Numerical linearization parameter: uncertainty not required.

^E Uncertainty is determined using the maximum deviation from linear response applying rectangular distribution and is expressed for the square of the field value.



ET3DV6 SN:1787

May 18, 2010

DASY/EASY - Parameters of Probe: ET3DV6 SN:1787

Calibration Parameter Determined in Head Tissue Simulating Media

| f [MHz] | Validity [MHz] [□] | Permittivity | Conductivity | ConvF X | ConvF Y | ConvF Z | Alpha | Depth Unc (k=2) |
|---------|-----------------------------|--------------|--------------|---------|---------|---------|-------|-----------------|
| 750 | ± 50 / ± 100 | 41.5 ± 5% | 0.90 ± 5% | 6.56 | 6.56 | 6.56 | 0.52 | 1.96 ± 11.0% |
| 835 | ± 50 / ± 100 | 41.9 ± 5% | 0.89 ± 5% | 6.21 | 6.21 | 6.21 | 0.42 | 2.23 ± 11.0% |
| 1750 | ± 50 / ± 100 | 40.1 ± 5% | 1.37 ± 5% | 5.36 | 5.36 | 5.36 | 0.49 | 1.18 ± 11.0% |
| 1900 | ± 50 / ± 100 | 40.0 ± 5% | 1.40 ± 5% | 5.09 | 5.09 | 5.09 | 0.66 | 2.20 ± 11.0% |
| 2450 | ± 50 / ± 100 | 39.2 ± 5% | 1.80 ± 5% | 4.50 | 4.50 | 4.50 | 0.99 | 1.63 ± 11.0% |

[□] The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.



ET3DV6 SN:1787

May 18, 2010

DASY/EASY - Parameters of Probe: ET3DV6 SN:1787

Calibration Parameter Determined in Body Tissue Simulating Media

| f [MHz] | Validity [MHz] ^c | Permittivity | Conductivity | ConvF X | ConvF Y | ConvF Z | Alpha | Depth Unc (k=2) |
|---------|-----------------------------|--------------|--------------|---------|---------|---------|-------|-----------------|
| 750 | ± 50 / ± 100 | 55.5 ± 5% | 0.96 ± 5% | 6.22 | 6.22 | 6.22 | 0.48 | 2.20 ± 11.0% |
| 835 | ± 50 / ± 100 | 55.2 ± 5% | 0.97 ± 5% | 6.12 | 6.12 | 6.12 | 0.39 | 2.45 ± 11.0% |
| 1750 | ± 50 / ± 100 | 53.4 ± 5% | 1.49 ± 5% | 4.72 | 4.72 | 4.72 | 0.63 | 2.90 ± 11.0% |
| 1900 | ± 50 / ± 100 | 53.3 ± 5% | 1.52 ± 5% | 4.47 | 4.47 | 4.47 | 0.88 | 2.39 ± 11.0% |
| 2450 | ± 50 / ± 100 | 52.7 ± 5% | 1.95 ± 5% | 4.03 | 4.03 | 4.03 | 0.99 | 1.35 ± 11.0% |

^c The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

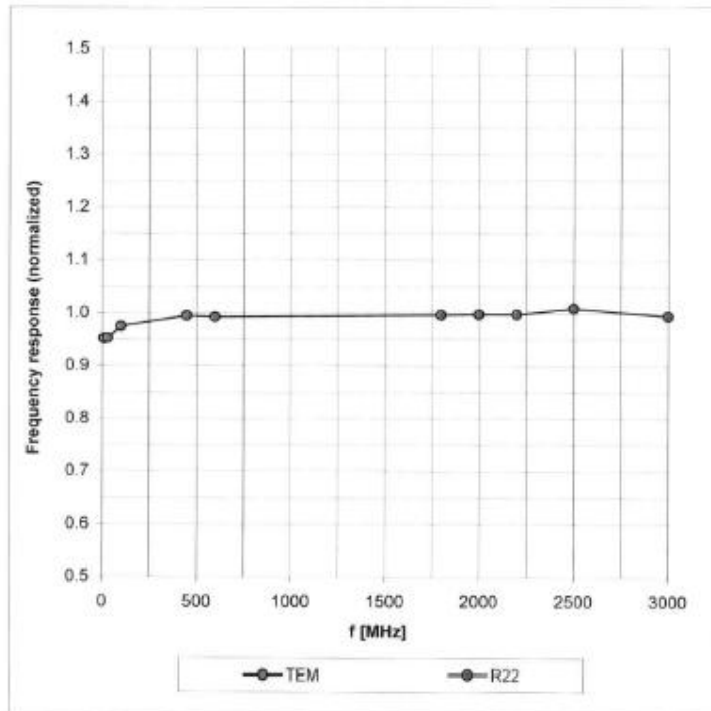


ET3DV6 SN:1787

May 18, 2010

Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide: R22)



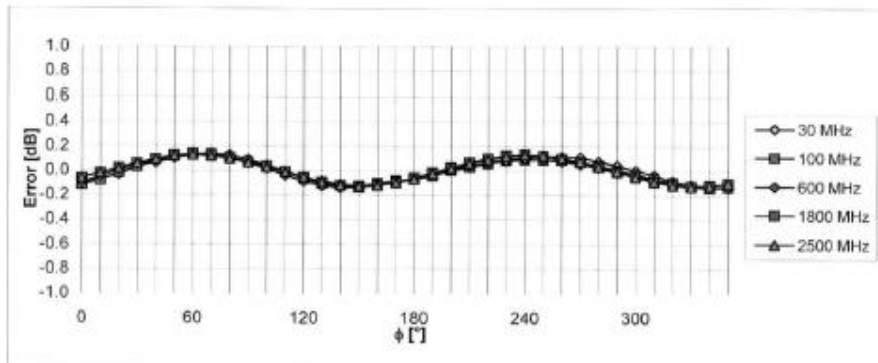
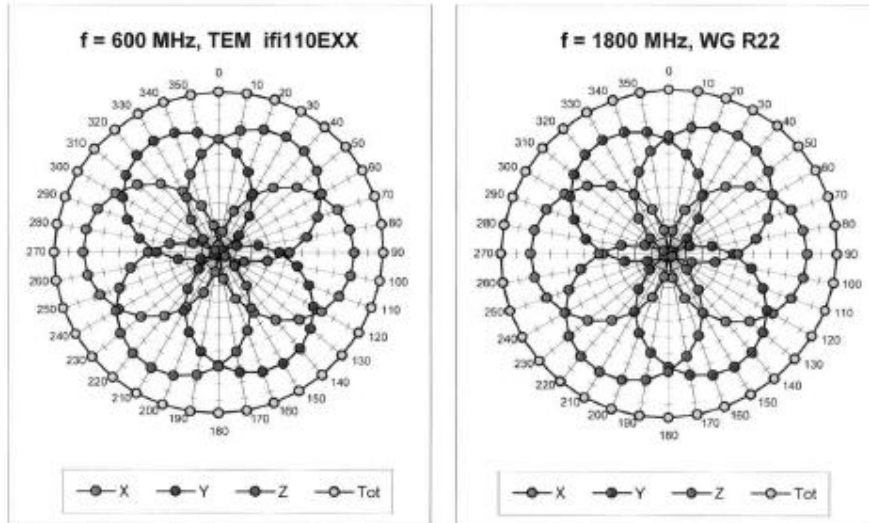
Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ (k=2)



ET3DV6 SN:1787

May 18, 2010

Receiving Pattern (ϕ), $\vartheta = 0^\circ$



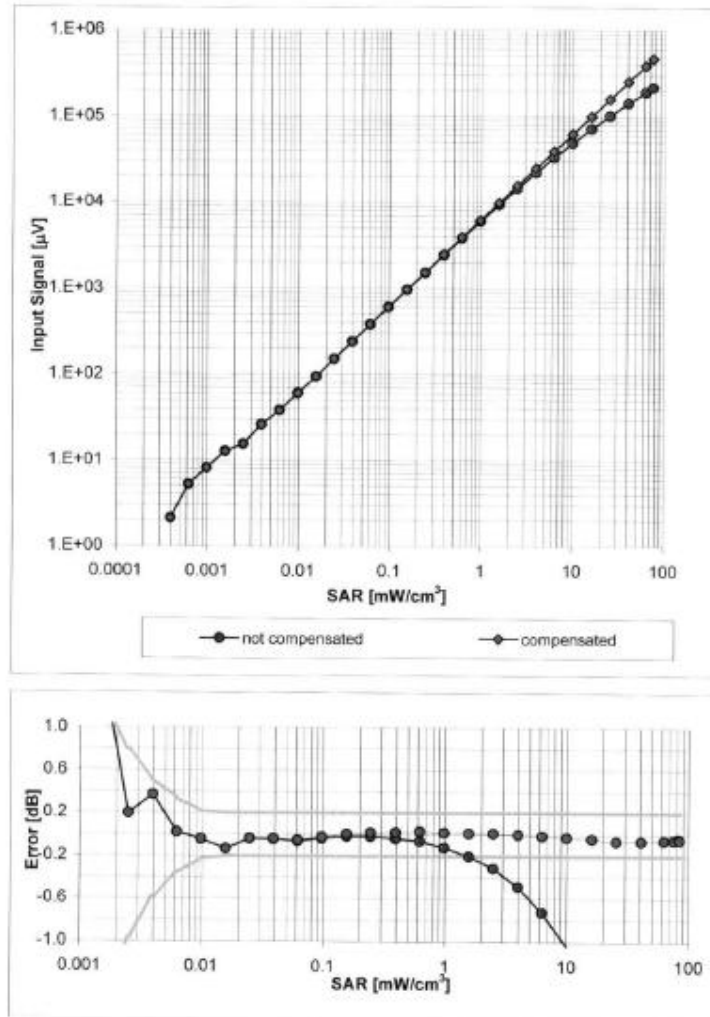
Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)



ET3DV6 SN:1787

May 18, 2010

Dynamic Range f(SAR_{head}) (Waveguide R22, f = 1800 MHz)

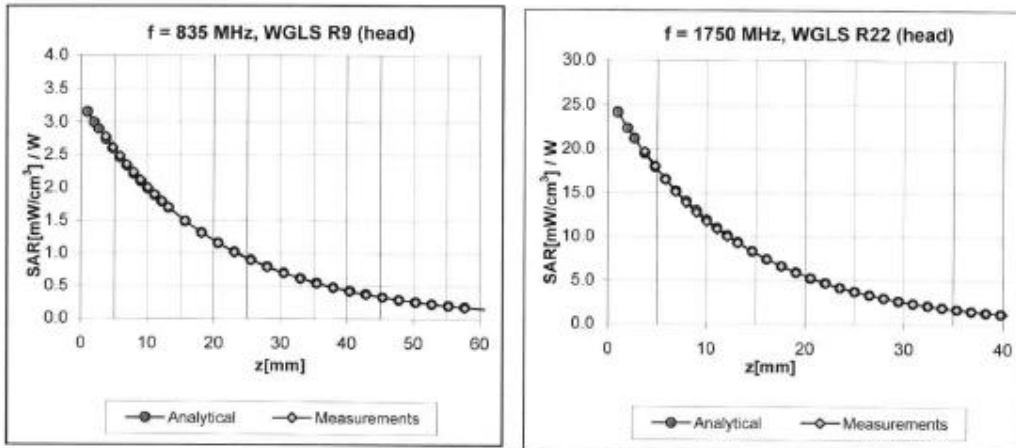


Uncertainty of Linearity Assessment: ± 0.6% (k=2)

ET3DV6 SN:1787

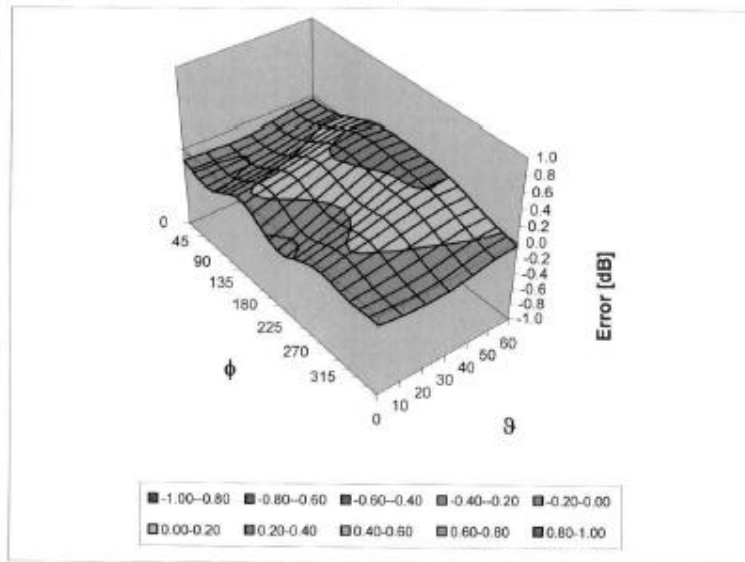
May 18, 2010

Conversion Factor Assessment



Deviation from Isotropy in HSL

Error (ϕ , θ), f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ (k=2)



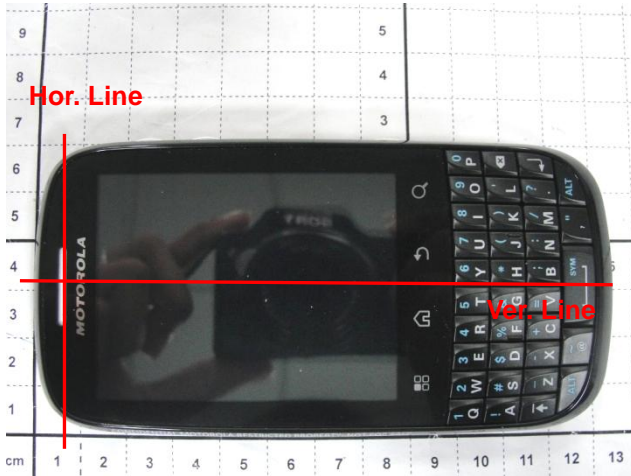
ET3DV6 SN:1787

May 18, 2010

Other Probe Parameters

| | |
|---|----------------|
| Sensor Arrangement | Triangular |
| Connector Angle (°) | Not applicable |
| Mechanical Surface Detection Mode | enabled |
| Optical Surface Detection Mode | disabled |
| Probe Overall Length | 337 mm |
| Probe Body Diameter | 10 mm |
| Tip Length | 10 mm |
| Tip Diameter | 6.8 mm |
| Probe Tip to Sensor X Calibration Point | 2.7 mm |
| Probe Tip to Sensor Y Calibration Point | 2.7 mm |
| Probe Tip to Sensor Z Calibration Point | 2.7 mm |
| Recommended Measurement Distance from Surface | 4 mm |

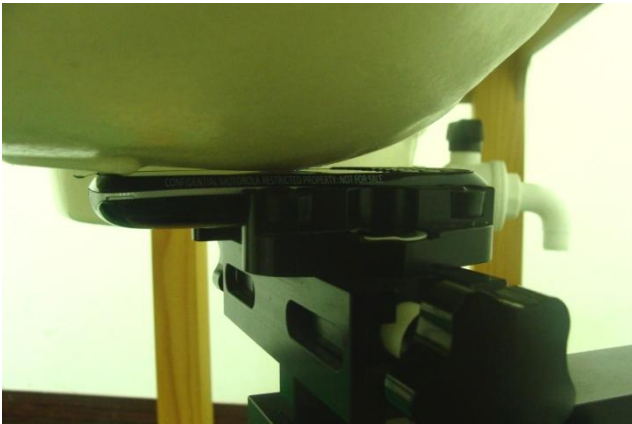
Appendix D. Product Photos



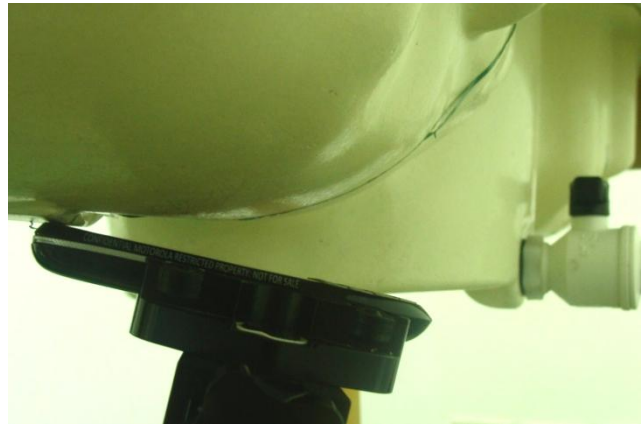
Antenna Location :



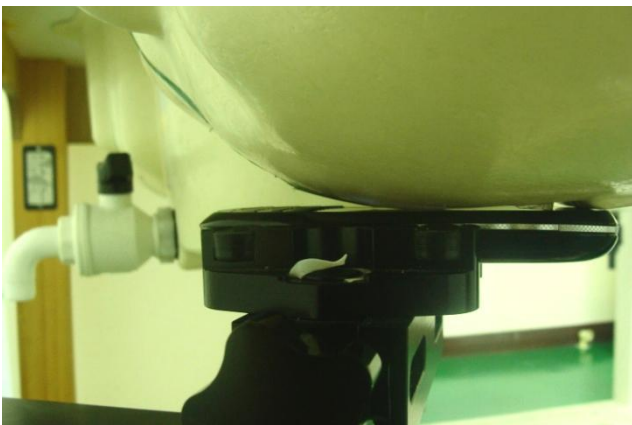
Appendix E. Test Setup Photos



Right Cheek



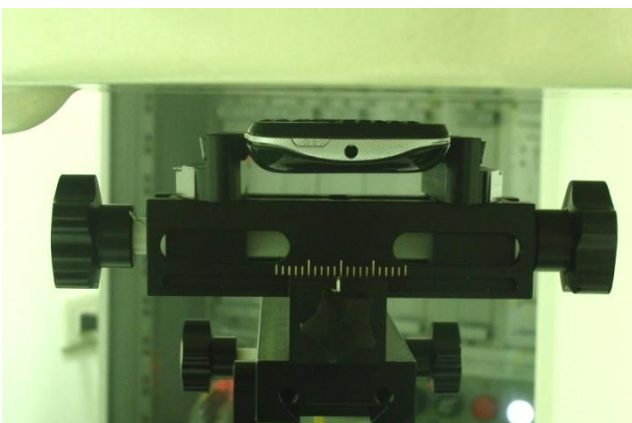
Right Tilted



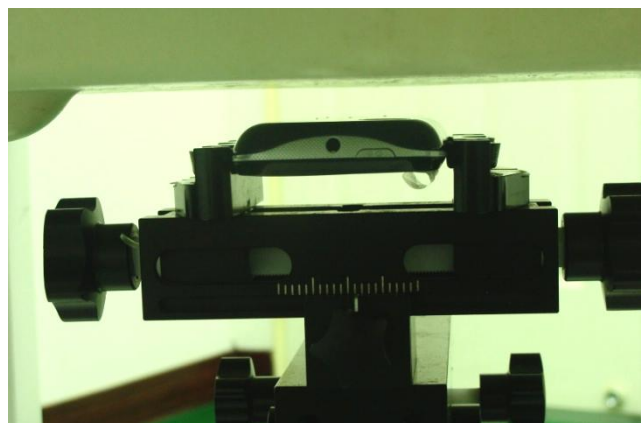
Left Cheek



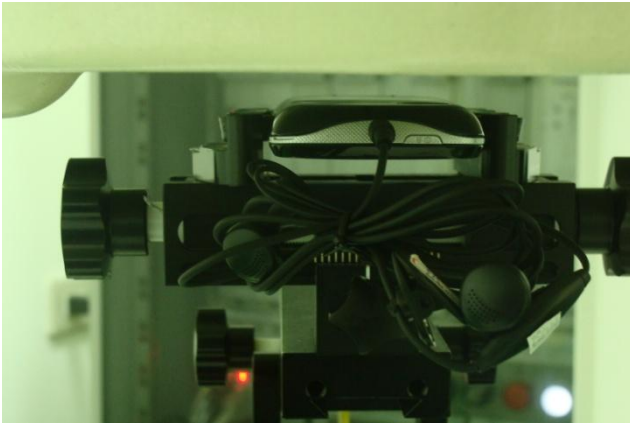
Left Tilted



Front Face of the DUT with Phantom 1 cm Gap
(DUT without Earphone)



Rear Face of the DUT with Phantom 1 cm Gap
(DUT without Earphone)



Rear Face of the DUT with Phantom 1 cm Gap
(DUT with Earphone)



Left Side of the DUT with Phantom 1 cm Gap
(DUT without Earphone)



Top Side of the DUT with Phantom 1 cm Gap
(DUT without Earphone)