



# **SAR Evaluation Report**

in accordance with the requirements of  
FCC Report and Order: ET Docket 93-62, and OET Bulletin 65 Supplement C

for

**802.11 a/b/g Mini PCI Type 3B Card**

**Model: WM3A2915ABG**

**FCC ID: E2K5HCKT**

**July 2, 2004**

**REPORT NO: 04U2824-1A (5G)**

*Prepared for*

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**CERTIFICATE OF COMPLIANCE (SAR EVALUATION)****Dates of Tests:** June 29 – July 2, 2004

<b>APPLICANT:</b>	Dell Computer Corporation One Dell Way Round Rock, TX 78682, United States
<b>MODEL:</b>	WM3A2915ABG
<b>FCC ID:</b>	E2K5HCKT
<b>DEVICE CATEGORY:</b>	PORTABLE DEVICES
<b>EXPOSURE CATEGORY:</b>	GENERAL POPULATION/UNCONTROLLED EXPOSURE

**Test Sample is a:** Production unit

**Modulation type:** Orthogonal Frequency Division Multiplexing (OFDM) for 802.11a

**Tx Frequency:** 5180 to 5320 MHz  
5745 to 5825 MHz

**Max. O/P Power:** 16.3 dBm (Conducted/Average) for 5.2GHz band  
17.2 dBm (Conducted/Average) for 5.8GHz band

**Max. SAR (1g):** 0.870 mW/g for 5.2 GHz band  
0.854 mW/g for 5.8 GHz band

**FCC Rule Part(s):** 15E

**Host Device:** Dell, Model PP02X (Precision M60)

**Note:** The 5.2 & 5.8 GHz bands are applicable to this report; other band of operation (2.4GHz) is documented in a separate report.

This wireless portable device has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment/general population exposure limits specified in ANSI/IEEE Std. C95.1-1992 and had been tested in accordance with the measurement procedures specified in FCC OET 65 Supplement C (released on 6/29/2001 see Test Report).

I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualifications of all persons taking them.



Hsin-Fu Shih (Sunny Shih)  
Senior Engineer

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## 1. EQUIPMENT UNDER TEST (EUT) DESCRIPTION

The EUT is an 802.11a/b/g transceiver Mini PCI card installed in a Dell Laptop Computer, model PP02X (Precision M60).

The radio utilizes two PIFA (metal sheet) antennas for diversity (main and auxiliary), Wistron NeWeb Corporation (WNC), model **CA9-C**.

Alternately - Two other PCB antennas for diversity (main and auxiliary), Hitachi model **HFT04-DL01**.

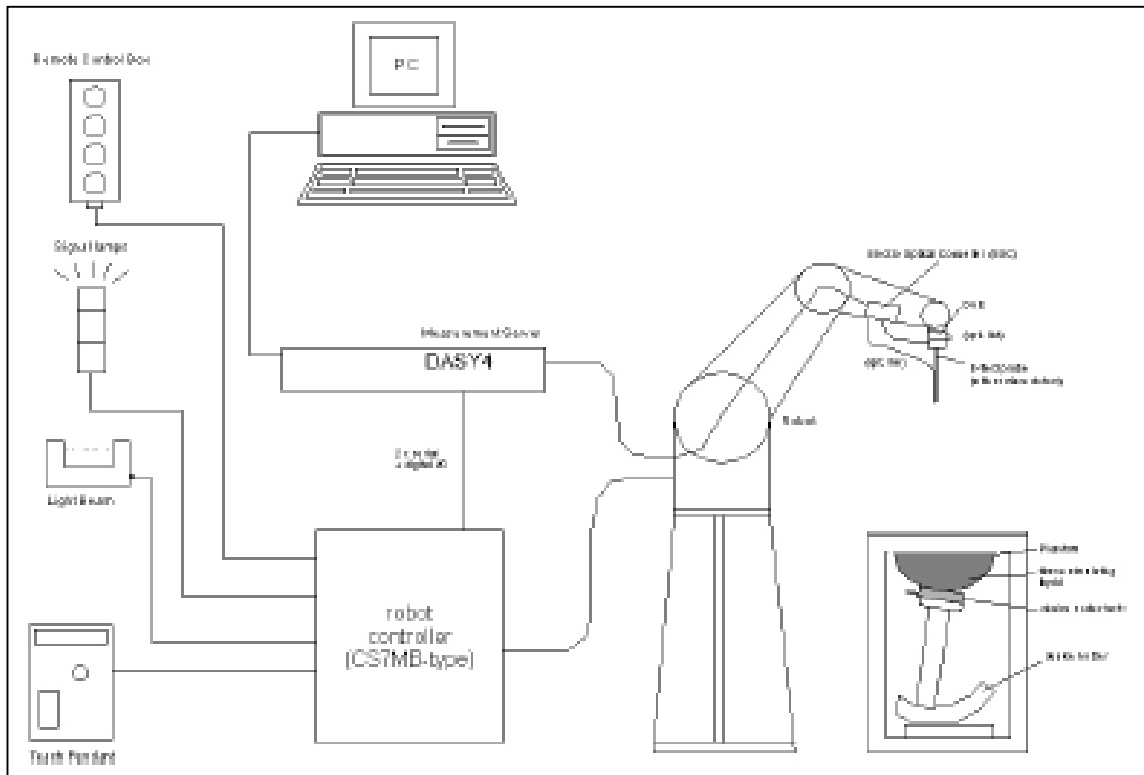
## 2. REQUIREMENTS FOR COMPLIANCE TESTING DEFINED BY THE FCC

The US Federal Communications Commission has released the report and order "Guidelines for Evaluating the Environmental Effects of RF Radiation", ET Docket No. 93-62 in August 1996 [1]. The order requires routine SAR evaluation prior to equipment authorization of portable transmitter devices, including portable telephones. For consumer products, the applicable limit is 1.6 mW/g for an uncontrolled environment and 8.0 mW/g for an occupational/controlled environment as recommended by the ANSI/IEEE standard C95.1-1992 [6]. According to the Supplement C of OET Bulletin 65 "Evaluating Compliance with FCC Guide-lines for Human Exposure to Radio frequency Electromagnetic Fields", released on Jun 29, 2001 by the FCC, the device should be evaluated at maximum output power (radiated from the antenna) under "worst-case" conditions for normal or intended use, incorporating normal antenna operating positions, device peak performance frequencies and positions for maximum RF energy coupling.

## 3. DOSIMETRIC ASSESSMENT SYSTEM

These measurements were performed with the automated near-field scanning system DASY4 from Schmid & Partner Engineering AG (SPEAG). The system is based on a high precision robot (working range greater than 0.9 m) which positions the probes with a positional repeatability of better than  $\pm 0.02$  mm. Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines to the data acquisition unit. The SAR measurements were conducted with the dosimetric probe ES3DV2-SN: 3021 (manufactured by SPEAG), designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe has been calibrated according to the procedure with accuracy of better than  $\pm 10\%$ . The spherical isotropy was evaluated with the procedure and found to be better than  $\pm 0.25$  dB. The phantom used was the SAM Twin Phantom as described in FCC supplement C, IEEE P1528 and EN50361.

### 3.1. MEASUREMENT SYSTEM DIAGRAM



**The DASYS4 system for performing compliance tests consists of the following items:**

- A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion between optical and electrical of the signals for the digital communication to the DAE and for the analog signal from the optical surface detection. The EOC is connected to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 2000 or Windows XP.
- DASYS4 software.
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes.
- Validation dipole kits allowing validating the proper functioning of the system.

### 3.2. SYSTEM COMPONENTS

#### DASY4 MEASUREMENT SERVER



The DASY4 measurement server is based on a PC/104 CPU board with a 166MHz low-power Pentium, 32MB chip disk and 64MB RAM. The necessary circuits for communication with either the DAE3 electronic box as well as the 16-bit AD-converter system for optical detection and digital I/O interface are contained on the DASY4 I/O-board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation. The PC-operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with two expansion slots which are reserved for future applications. Please note that the expansion slots do not have a standardized pinout and therefore only the expansion cards provided by SPEAG can be inserted. Expansion cards from any other supplier could seriously damage the measurement server. Calibration: No calibration required.

#### DATA ACQUISITION ELECTRONICS (DAE)

The data acquisition electronics (DAE3) consists of a highly sensitive electrometer grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection. The input impedance of the DAE3 box is 200M $\Omega$ ; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



#### ES3DV2 ISOTROPIC E-FIELD PROBE FOR DOSIMETRIC MEASUREMENTS

- Construction:** Symmetrical design with triangular core Interleaved sensors Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., glycoether)
- Calibration:** Basic Broad Band Calibration in air: 10-2500 MHz. Conversion Factors (CF) for HSL 900 and HSL 1800 CF-Calibration for other liquids and frequencies upon request.
- Frequency:** 10 MHz to > 6 GHz; Linearity:  $\pm 0.2$  dB
- Directivity:**  $\pm 0.2$  dB in HSL (rotation around probe axis);  
 $\pm 0.3$  dB in tissue material (rotation normal to probe axis)
- Dynamic Range:** 5  $\mu$ W/g to > 100 mW/g; Linearity:  $\pm 0.2$  dB
- Dimensions:** Overall length: 330 mm (Tip: 20 mm)  
Tip diameter: 3.9 mm (Body: 12 mm)  
Distance from probe tip to dipole centers: 2.7 mm
- Application:** General dosimetry up to 6 GHz  
Dosimetry in strong gradient fields  
Compliance tests of mobile phones



Interior of probe



Isotropic E-Field Probe

### SAM PHANTOM (V4.0)

**Construction:** The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528-200X, CENELEC 50361 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.

Shell Thickness: 2 ±0.2 mm

Filling Volume: Approx. 25 liters

Dimensions: Height: 810mm; Length: 1000mm; Width: 500mm



### DEVICE HOLDER FOR SAM TWIN PHANTOM

**Construction:** In combination with the Twin SAM Phantom V4.0 or Twin SAM, the Mounting Device (made from POM) enables the rotation of the mounted transmitter in spherical coordinates, whereby the rotation point is the ear opening. The devices can be easily and accurately positioned according to IEC, IEEE, CENELEC, FCC or other specifications. The device holder can be locked at different phantom locations (left head, right head, flat phantom).



### SYSTEM VALIDATION KITS

**Construction:** Symmetrical dipole with 1/4 balun Enables measurement of feedpoint impedance with NWA Matched for use near flat phantoms filled with brain simulating solutions Includes distance holder and tripod adaptor.

**Frequency:** 450, 900, 1800, 2450, 5800 MHz

**Return loss:** > 20 dB at specified validation position

**Power capability:** > 100 W (f < 1GHz); > 40 W (f > 1GHz)

**Dimensions:**  
 450V2: dipole length: 270 mm; overall height: 330 mm  
 D900V2: dipole length: 149 mm; overall height: 330 mm  
 D1800V2: dipole length: 72 mm; overall height: 300 mm  
 D2450V2: dipole length: 51.5 mm; overall height: 300 mm  
 D5GHzV2: dipole length: 25.5 mm; overall height: 290 mm



## 4. EVALUATION PROCEDURES

### DATA EVALUATION

The DASYS4 post processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	$Norm_i, a_{i0}, a_{i1}, a_{i2}$
	- Conversion factor	$ConvF_i$
	- Diode compression point	$dcp_i$
Device parameters:	- Frequency	$f$
	- Crest factor	$cf$
Media parameters:	- Conductivity	$\sigma$
	- Density	$\rho$

These parameters must be set correctly in the software. They can be found in the component documents or be imported into the software from the configuration files issued for the DASYS components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with	$V_i$	= Compensated signal of channel i	(i = x, y, z)
	$U_i$	= Input signal of channel i	(i = x, y, z)
	$cf$	= Crest factor of exciting field	(DASY parameter)
	$dcp_i$	= Diode compression point	(DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes:

$$E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

H-field probes:

$$H_i = \sqrt{V_i} \cdot \frac{a_{i10} + a_{i11}f + a_{i12}f^2}{f}$$

with	$V_i$	= Compensated signal of channel i	(i = x, y, z)
	$Norm_i$	= Sensor sensitivity of channel i	(i = x, y, z)
		$\mu V/(V/m)^2$ for E0field Probes	
	$ConvF$	= Sensitivity enhancement in solution	
	$a_{ij}$	= Sensor sensitivity factors for H-field probes	
	$f$	= Carrier frequency (GHz)	
	$E_i$	= Electric field strength of channel i in V/m	
	$H_i$	= Magnetic field strength of channel i in A/m	



The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with  $SAR$  = local specific absorption rate in mW/g

$E_{tot}$  = total field strength in V/m

$\sigma$  = conductivity in [mho/m] or [Siemens/m]

$\rho$  = equivalent tissue density in g/cm<sup>3</sup>

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid.

The power flow density is calculated assuming the excitation field as a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770} \quad \text{or} \quad P_{pwe} = H_{tot}^2 \cdot 37.7$$

with  $P_{pwe}$  = Equivalent power density of a plane wave in mW/cm<sup>2</sup>

$E_{tot}$  = total electric field strength in V/m

$H_{tot}$  = total magnetic field strength in A/m

## SAR SYSTEM MEASUREMENT PROCEDURES

The procedure for assessing the peak spatial-average SAR value consists of the following steps:

- **Power Reference Measurement**

The reference and drift jobs are useful jobs for monitoring the power drift of the device under test in the batch process. Both jobs measure the field at a specified reference position, at a selectable distance from the phantom surface. The reference position can be either the selected section's grid reference point or a user point in this section. The reference job projects the selected point onto the phantom surface, orients the probe perpendicularly to the surface, and approaches the surface using the selected detection method.

- **Area Scan**

The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a finer measurement around the hot spot. The sophisticated interpolation routines implemented in DASY4 software can find the maximum locations even in relatively coarse grids. This grid is anchored at the grid reference point of the selected section in the phantom. When the area scan's property sheet is brought-up, grid settings can be edited by a user. When an area scan has measured all reachable points, it computes the field maximum found in the scanned area, within a range of the global maximum. If only one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximums are detected, the number of Zoom Scans has to be increased accordingly.

- **Zoom Scan**

Zoom scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The default zoom scan measures 7 x 7 x 8 points within a cube whose base faces are centered around the maximum found in a preceding area scan job within the same procedure. If the preceding Area Scan job indicates more than one maximum, the number of Zoom Scans has to be enlarged accordingly. For dosimetric application, it is necessary to assess the peak spatial SAR value averaged over a volume. For this purpose, fine resolution volume scans need to be performed at the peak SAR location(s) determined during the Area Scan.

- **Power Drift measurement**

The drift job measures the field at the same location as the most recent reference job within the same procedure, and with the same settings. The drift measurement gives the field difference in dB from the reading conducted within the last reference measurement. Several drift measurements are possible for one reference measurement. This allows a user to monitor the power drift of the device under test within a batch process. In the properties of the Drift job, the user can specify a limit for the drift and have DASY4 software stop the measurements if this limit is exceeded.

- **Z-Scan**

The Z Scan job measures points along a vertical straight line. The line runs along the Z-axis of a one-dimensional grid. A user can anchor the grid to the current probe location. As with any other grids, the local Z-axis of the anchor location establishes the Z-axis of the grid.

## SPATIAL PEAK SAR EVALUATION

The procedure for spatial peak SAR evaluation has been implemented according to the IEEE1529 standard. It can be conducted for 1 g and 10 g.

The DASY4 system allows evaluations that combine measured data and robot positions, such as:

- maximum search
- extrapolation
- boundary correction
- peak search for averaged SAR

During a maximum search, global and local maximum searches are automatically performed in 2-D after each Area Scan measurement with at least 6 measurement points. It is based on the evaluation of the local SAR gradient calculated by the Quadratic Shepard's method. The algorithm will find the global maximum and all local maxima within -2 dB of the global maxima for all SAR distributions.

### Extrapolation

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. Several measurements at different distances are necessary for the extrapolation.

Extrapolation routines require at least 10 measurement points in 3-D space. They are used in the Cube Scan to obtain SAR values between the lowest measurement points and the inner phantom surface. The routine uses the modified Quadratic Shepard's method for extrapolation. For a grid using 5x5x7 measurement points with 5mm resolution amounting to 343 measurement points, the uncertainty of the extrapolation routines is less than 1% for 1 g and 10 g cubes.

### Boundary effect

For measurements in the immediate vicinity of a phantom surface, the field coupling effects between the probe and the boundary influence the probe characteristics. Boundary effect errors of different dosimetric probe types have been analyzed by measurements and using a numerical probe model. As expected, both methods showed an enhanced sensitivity in the immediate vicinity of the boundary. The effect strongly depends on the probe dimensions and disappears with increasing distance from the boundary. The sensitivity can be approximately given as:

$$S \approx S_o + S_b \exp(-\frac{z}{a}) \cos(\pi \frac{z}{\lambda})$$

Since the decay of the boundary effect dominates for small probes ( $a \ll \lambda$ ), the cos-term can be omitted. Factors  $S_b$  (parameter Alpha in the DASY4 software) and  $a$  (parameter Delta in the DASY4 software) are assessed during probe calibration and used for numerical compensation of the boundary effect. Several simulations and measurements have confirmed that the compensation is valid for different field and boundary configurations.

This simple compensation procedure can largely reduce the probe uncertainty near boundaries. It works well as long as:

- the boundary curvature is small
- the probe axis is angled less than 30° to the boundary normal
- the distance between probe and boundary is larger than 25% of the probe diameter
- the probe is symmetric (all sensors have the same offset from the probe tip)

Since all of these requirements are fulfilled in a DASY4 system, the correction of the probe boundary effect in the vicinity of the phantom surface is performed in a fully automated manner via the measurement data extraction during postprocessing.

## 5. MEASUREMENT UNCERTAINTY

UNCERTAINTY BUDGE ACCORDING TO IEEE P1528									
Uncertainty Component	Sec.	Tol. (± %)	Prob.Dist.	Div.	ci (1g)	ci (10g)	ui (1g)	ui (10g)	vi
<b>Measurement System</b>									
Probe Calibration (k=1)	E.2.1	4.8	N	1.0000	1.0000	1.0000	4.8	4.8	
Axial Isotropy	E.2.2	4.7	R	1.7321	0.7071	0.7071	1.9	1.9	
Hemispherical Isotropy	E.2.2	9.6	R	1.7321	0.7071	0.7071	3.9	3.9	
Boundary Effect	E.2.3	1	R	1.7321	1.0000	1.0000	4.8	4.8	
Linearity	E.2.4	4.7	R	1.7321	1.0000	1.0000	2.7	2.7	
System Detection Limits	E.2.5	1	R	1.7321	1.0000	1.0000	0.6	0.6	
Readout Electronics	E.2.6	1	N	1.0000	1.0000	1.0000	1	1	
Response Time	E.2.7	0.8	R	1.7321	1.0000	1.0000	0.5	0.5	
Integration Time	E.2.8	2.6	R	1.7321	1.0000	1.0000	0.8	0.8	
RF Ambient Conditions – Noise	E.6.1	3	R	1.7321	1.0000	1.0000	1.7	1.7	
RF Ambient Conditions – Reflections	E.6.1	3	R	1.7321	1.0000	1.0000	1.7	1.7	
Probe Positioner Mechanical Tolerance	E.6.2	0.4	R	1.7321	1.0000	1.0000	0.2	0.2	
Probe Positioning with respect to Phantom	E.6.3	2.9	R	1.7321	1.0000	1.0000	1.7	1.7	
Extrapolation, interpolation and Integration	E.5	3.9	R	1.7321	1.0000	1.0000	2.3	2.3	
<b>Test sample Related</b>									
Test Sample Positioning	E.4.2	1.1	N	1.0000	1.0000	1.0000	6	6	19
Device Holder Uncertainty	E.4.1	3.6	N	1.0000	1.0000	1.0000	5	5	7
Output Power Variation - SAR drift	6.6.2	5	R	1.7321	1.0000	1.0000	2.9	2.9	
<b>Phantom and Tissue Parameters</b>									
Phantom Uncertainty (shape and thickness)	E.3.1	4	R	1.7321	1.0000	1.0000	2.3	2.3	
Liquid Conductivity - deviation from target	E.3.2	5	R	1.7321	0.6400	0.4300	1.8	1.2	
Liquid Conductivity - measurement	E.3.3	2.5	N	1.0000	0.6400	0.4300	3.5	2.4	5
Liquid Permittivity - deviation from target	E.3.2	5	R	1.7321	0.6000	0.4900	1.7	1.4	
Liquid Permittivity - measurement uncertainty	E.3.3	2.5	N	1.0000	0.6000	0.4900	1.7	1.4	5
<b>DEGREE OF FREEDOME</b>									
Combined Standard Uncertainty							13.580	13.201	
Expanded Uncertainty			k=2				27.160	26.402	

The budge is valid for the frequency range 300 MHz to 6 GHz and represents a worst-case analysis.

**6. EXPOSURE LIMIT****(A) Limits for Occupational/Controlled Exposure (W/kg)**

Whole-Body	Partial-Body	Hands, Wrists, Feet and Ankles
0.4	8.0	20.0

**(B) Limits for General Population/Uncontrolled Exposure (W/kg)**

Whole-Body	Partial-Body	Hands, Wrists, Feet and Ankles
0.08	1.6	4.0

NOTE 1: See Section 1 for discussion of exposure categories.

NOTE 2: Whole-Body SAR is averaged over the entire body, partial-body SAR is averaged over any 1 gram of tissue defined as a tissue volume in the shape of a cube. SAR for hands, wrists, feet and ankles is averaged over any 10 grams of tissue defined as a tissue volume in the shape of a cube.

NOTE 3: At frequencies above 6.0 GHz, SAR limits are not applicable and MPE limits for power density should be applied at 5 cm or more from the transmitting device.

NOTE 4: The time averaging criteria for field strength and power density do not apply to general population SAR limit of 47 CFR §2.1093

<p><b>NOTE</b>  <b>GENERAL POPULATION/UNCONTROLLED EXPOSURE</b>  <b>PARTIAL BODY LIMIT</b>  <b>1.6 mW/g</b></p>
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## 7. PROCEDURES USED TO ESTABLISH TEST SIGNALS

The following procedures had been used to prepare the EUT for the SAR test.

- The client supplied a special driving program (CRTU Version 3.2.11.0000) to program the EUT to continually transmit the specified maximum power. And also to change the channel frequency.
- The conducted power was measured at the high, middle and low channel frequency before and after SAR measurement.

### Conducted Power Measurement Results

Ch. #	f [MHz]	Measured Average Power_ [dBm]	Test Utility SW Setting
36	5180	11.2	8.0
52	5260	16.3	13.5
64	5320	16.2	13.5
Ch. #	f [MHz]	Measured Average Power_ [dBm]	Test Utility SW Setting
149	5745	17.2	17.5
157	5785	17.1	18.0
165	5825	17.1	18.0

## 8. MEASUREMENT RESULTS

### 8.1. SIMULATING LIQUIDS PARAMETER CHECK

The simulating liquids should be checked at the beginning of a series of SAR measurements to determine if the dielectric parameters are within the tolerances of the specified target values. The relative permittivity and conductivity of the tissue material should be within  $\pm 5\%$  of the values given in the table below. 5% may not be easily achieved at certain frequencies. Under such circumstances, 10% tolerance may be used until more precise tissue recipes are available.

#### TISSUE SIMULATING LIQUIDS

In the current guidelines and draft standards for compliance testing of mobile phones (i.e., IEEE P1528, OET 65 Supplement C), the dielectric parameters suggested for head and body tissue simulating liquid are given only at 3.0 GHz and 5.8 GHz. As an intermediate solution, dielectric parameters for the frequencies between 5 to 5.8 GHz were obtained using linear interpolation (see table below).

SPEAG has developed suitable head and body tissue simulating liquids consisting of the following ingredients: de-ionized water, salt and a special composition including mineral oil and an emulgators. Dielectric parameters of these liquids were measured using a HP 8570C Dielectric Probe Kit in conjunction with HP 8753ES Network Analyzer (30 kHz – 6G Hz). The differences with respect to the interpolated values were well within desired  $\pm 5\%$  for the whole 5 to 5.8 GHz range.

f (MHz)	Head Tissue		Body Tissue		Reference
	rel. permittivity	conductivity	rel. permittivity	conductivity	
3000	38.5	2.40	52.0	2.73	Standard
5800	35.3	5.27	48.2	6.00	Standard
5000	36.2	1.45	49.3	5.07	Interpolated
5100	36.1	4.55	49.1	5.18	Interpolated
5200	36.0	4.66	49.0	5.30	Interpolated
5300	35.9	4.76	48.9	5.42	Interpolated
5400	35.8	4.86	48.7	5.53	Interpolated
5500	35.6	4.96	48.6	5.65	Interpolated
5600	35.5	5.07	48.5	5.77	Interpolated
5700	35.4	5.17	48.3	5.88	Interpolated

( $\epsilon_r$  = relative permittivity,  $\sigma$  = conductivity and  $\rho = 1000 \text{ kg/m}^3$ )

**SIMULATING LIQUIDS PARAMETER CHECK RESULTS**

**@ Muscle 5200 MHz**

Ambient Temperature = 25°C; Relative humidity = 41%

**Date:** June 29, 2004

Simulating Liquid				Parameters		Target	Measured	Deviation (%)	Limit (%)
Medium	f (MHz)	Temp. (°C)	Depth (cm)	ε"	Relative Permittivity (ε <sub>r</sub> ):	49.0	48.3064	-1.42	± 5
Muscle	5200	24	15	18.7637	Conductivity (σ):	5.30	5.4280	2.42	± 5

Note: Interpolated medium parameters used for SAR evaluation.

The conductivity (σ) can be given as:

$$\sigma = \omega \epsilon_0 \epsilon'' = 2 \pi f \epsilon_0 \epsilon''$$

where  $f = target f * 10^6$

$$\epsilon_0 = 8.854 * 10^{-12}$$

**Simulating Liquid Parameter Check Results @ 4600-5800 MHz**

Ambient temperature = 25.0 deg. C; Liquid temperature = 24.0 deg.C

June 29, 2004 10:04 AM

Frequency	e'	e''
4.600000000 GHz	49.5072	17.8260
4.650000000 GHz	49.4281	18.0212
4.700000000 GHz	49.3368	17.9773
4.750000000 GHz	49.2072	18.1748
4.800000000 GHz	49.1853	18.1737
4.850000000 GHz	48.9707	18.2648
4.900000000 GHz	48.9490	18.3144
4.950000000 GHz	48.8190	18.4552
5.000000000 GHz	48.7076	18.5197
5.050000000 GHz	48.5687	18.5023
5.100000000 GHz	48.4118	18.6674
5.150000000 GHz	48.4160	18.5956
<b>5.200000000 GHz</b>	<b>48.3064</b>	<b>18.7637</b>
5.250000000 GHz	48.2682	18.7970
5.300000000 GHz	48.1355	18.8893
5.350000000 GHz	48.1076	18.9713
5.400000000 GHz	47.9442	18.9498
5.450000000 GHz	47.8260	19.0847
5.500000000 GHz	47.7763	19.0788
5.550000000 GHz	47.6819	19.2959
5.600000000 GHz	47.5781	19.2598
5.650000000 GHz	47.4914	19.4496
5.700000000 GHz	47.5315	19.3118
5.750000000 GHz	47.2533	19.4382
5.800000000 GHz	47.2811	19.4576
5.850000000 GHz	46.9505	19.5354
5.900000000 GHz	47.0833	19.6683
5.950000000 GHz	46.8177	19.5482
6.000000000 GHz	46.8313	19.7693



**SIMULATING LIQUIDS PARAMETER CHECK RESULTS**

**@ Muscle 5800 MHz**

Ambient Temperature = 25°C; Relative humidity = 43%

**Date:** July 2, 2004

Simulating Liquid				Parameters		Target	Measured	Deviation (%)	Limit (%)
Medium	f (MHz)	Temp. (°C)	Depth (cm)	ε"	Relative Permittivity (ε <sub>r</sub> ):	48.2	47.1370	-2.21	± 5
Muscle	5800	24	15	19.4866	Conductivity (σ):	6.00	6.2876	4.79	± 5

Note: Interpolated medium parameters used for SAR evaluation.

The conductivity (σ) can be given as:

$$\sigma = \omega \epsilon_0 \epsilon'' = 2 \pi f \epsilon_0 \epsilon''$$

where  $f = target f * 10^6$

$$\epsilon_0 = 8.854 * 10^{-12}$$

**Simulating Liquid Parameter Check Results @ 4600-5800 MHz**

Ambient temperature = 25.0 deg. C; Liquid temperature = 24.0 deg.C

July 02, 2004 10:53 AM

Frequency	e'	e''
4.600000000 GHz	49.3698	17.8504
4.650000000 GHz	49.2839	17.9878
4.700000000 GHz	49.1355	17.9762
4.750000000 GHz	49.1175	18.2338
4.800000000 GHz	48.9366	18.1325
4.850000000 GHz	48.8771	18.3481
4.900000000 GHz	48.7819	18.2349
4.950000000 GHz	48.5784	18.4388
5.000000000 GHz	48.5705	18.5238
5.050000000 GHz	48.2609	18.4563
5.100000000 GHz	48.2377	18.6700
5.150000000 GHz	48.1539	18.4580
5.200000000 GHz	48.1092	18.7077
5.250000000 GHz	48.1508	18.6627
5.300000000 GHz	47.8420	18.8339
5.350000000 GHz	48.0646	18.9214
5.400000000 GHz	47.6610	18.8308
5.450000000 GHz	47.7055	19.0642
5.500000000 GHz	47.6146	18.9630
5.550000000 GHz	47.4901	19.2337
5.600000000 GHz	47.4626	19.1906
5.650000000 GHz	47.2124	19.3062
5.700000000 GHz	47.4805	19.3364
5.750000000 GHz	47.1607	19.2703
5.800000000 GHz	47.1370	19.4866
5.850000000 GHz	46.9837	19.4394
5.900000000 GHz	46.8834	19.5731
5.950000000 GHz	46.7674	19.4749
6.000000000 GHz	46.6707	19.7465

## 8.2. SYSTEM PERFORMANCE CHECK

The system performance check is performed prior to any usage of the system in order to guarantee reproducible results. The system performance check verifies that the system operates within its specifications. The system performance check results are tabulated below. And also the corresponding SAR plot is attached as well in the SAR plots files.

### SYSTEM PERFORMANCE CHECK MEASUREMENT CONDITIONS

- The measurements were performed in the flat section of the SAM twin phantom filled with Body simulating liquid of the following parameters.
- The DASY4 system with an Isotropic E-Field Probe ES3DV2-SN: 3021 was used for the measurements.
- The dipole was mounted on the small tripod so that the dipole feed point was positioned below the center marking of the flat phantom section and the dipole was oriented parallel to the body axis (the long side of the phantom). The standard measuring distance was 10 mm (above 1 GHz) from dipole center to the simulating liquid surface.
- The coarse grid with a grid spacing of 10 mm was aligned with the dipole.
- Special 7 x 7 x 8 fine cube was chosen for cube integration (dx=dy= 4.3 mm, dz= 3 mm).
- Distance between probe sensors and phantom surface was set to 3.0 mm.
- The dipole input power (forward power) was 250 mW $\pm$ 3%.
- The results are normalized to 1 W input power.

### REFERENCE SAR VALUES

The reference SAR values were using measurement results indicated in the dipole calibration document (see table below)

f (MHz)	Head Tissue		Body Tissue	
	SAR <sub>1g</sub>	SAR <sub>10g</sub>	SAR <sub>1g</sub>	SAR <sub>10g</sub>
5200	87.2	24.3	84	23.5
5800	89.6	25.1	80.8	22.8

### SYSTEM PERFORMANCE CHECK RESULTS

@ SYSTEM VALIDATION DIPOLE: D5GHzV2 SN 1003

Date: June 29, 2004

Body Simulating Liquid			Mrasured		Target <sub>1g</sub>	Deviation[%]	Limited[%]
f (MHz)	Temp. [°C]	Depth [cm]	1g	Normalized to 1 W			
5200	24	15	22.4	89.6	84	6.67	N/A

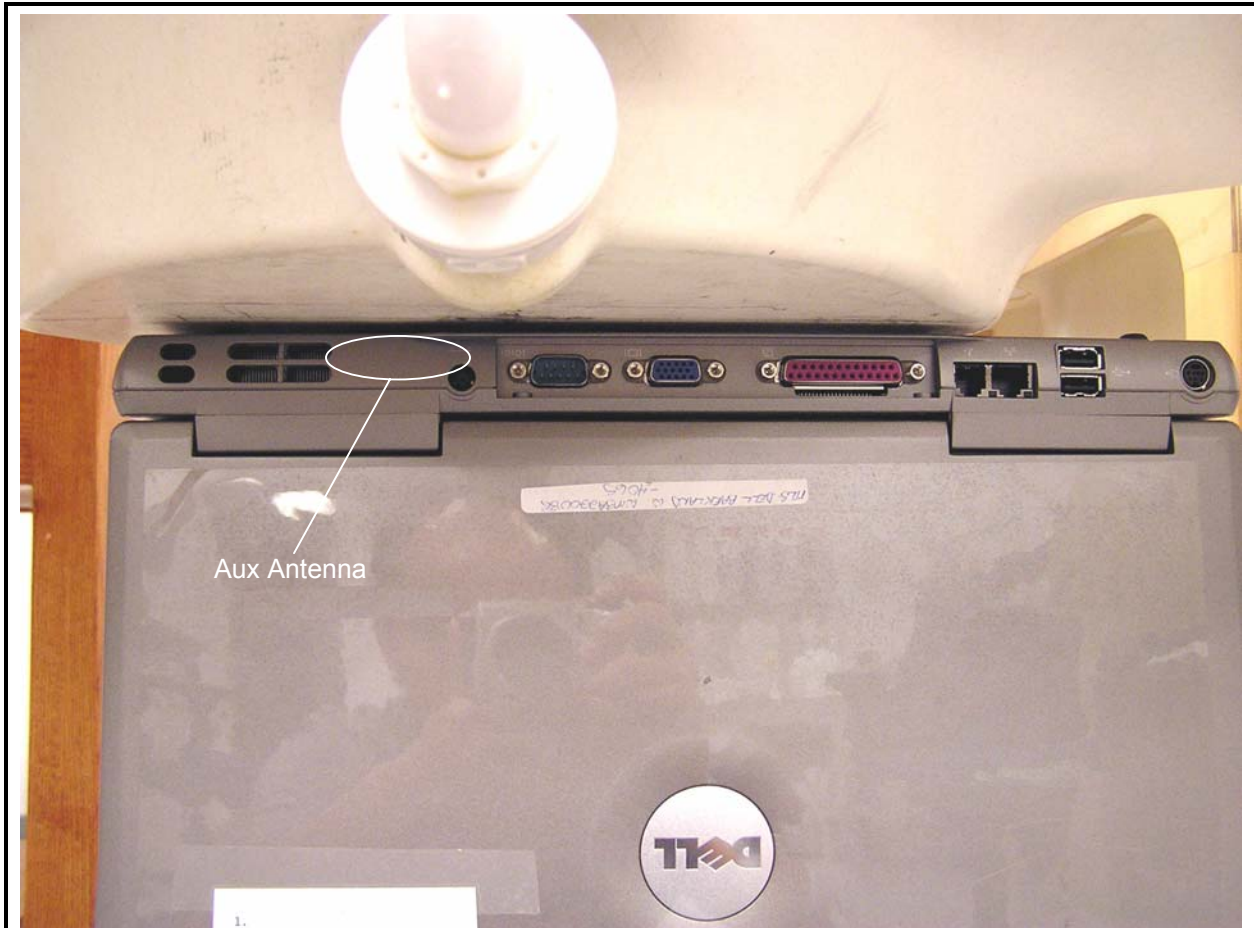
@ SYSTEM VALIDATION DIPOLE: D5GHzV2 SN 1003

Date: July 2, 2004

Body Simulating Liquid			Mrasured		Target <sub>1g</sub>	Deviation[%]	Limited[%]
f (MHz)	Temp. [°C]	Depth [cm]	1g	Normalized to 1 W			
5800	24	15	23.1	92.4	80.8	14.36	N/A

**8.3.SAR MEASUREMENTS RESULTS**

**1-1\_EUT Setup Configuration 1 – Aux Antenna (5.2GHz band)**



Antenna - WNC

Duty cycle: 99%; Crest factor: 1

Depth of liquid: 15 cm

Sep. dist. [mm]	Antenna	Ch. #	f [MHz]	*Conducted Power [dBm]		SAR_1g [mW/g]	
				Before	After	Measured	Limited
0	Aux	36	5180	11.2	11.2	0.102	1.6
0	Aux	52	5260	16.3	16.3	0.302	1.6
0	Aux	64	5320	16.2	16.2	0.287	1.6

Antenna - Hitachi

Duty cycle: 99%; Crest factor: 1

Depth of liquid: 15 cm

Sep. dist. [mm]	Antenna	Ch. #	f [MHz]	*Conducted Power [dBm]		SAR_1g [mW/g]	
				Before	After	Measured	Limited
0	Aux	36	5180	11.2	11.2	0.214	1.6
0	Aux	52	5260	16.3	16.3	0.379	1.6
0	Aux	64	5320	16.2	16.2	0.397	1.6

Notes:

1. \*: Average power.
2. SAR is tested for a lap-held position with the bottom of the laptop in direct contact against a flat phantom.
3. Please see attachment for the detailed measurement data and plots showing the maximum SAR location of the EUT.

**SAR MEASUREMENTS RESULTS**

**1-2\_EUT Setup Configuration 2 – Main Antenna (5.2GHz band)**



Antenna - WNC

Duty cycle: 99%; Crest factor: 1

Depth of liquid: 15 cm

Sep. dist. [mm]	Antenna	Ch. #	f [MHz]	*Conducted Power [dBm]		SAR_1g [mW/g]	
				Before	After	Measured	Limited
0	Main	36	5180	11.2	11.2	**	1.6
0	Main	52	5260	16.3	16.3	0.179	1.6
0	Main	64	5320	16.2	16.2	0.176	1.6

Antenna - Hitachi

Duty cycle: 99%; Crest factor: 1

Depth of liquid: 15 cm

Sep. dist. [mm]	Antenna	Ch. #	f [MHz]	*Conducted Power [dBm]		SAR_1g [mW/g]	
				Before	After	Measured	Limited
0	Main	36	5180	11.2	11.2	0.405	1.6
0	Main	52	5260	16.3	16.3	0.804	1.6
0	Main	64	5320	16.2	16.2	0.870	1.6

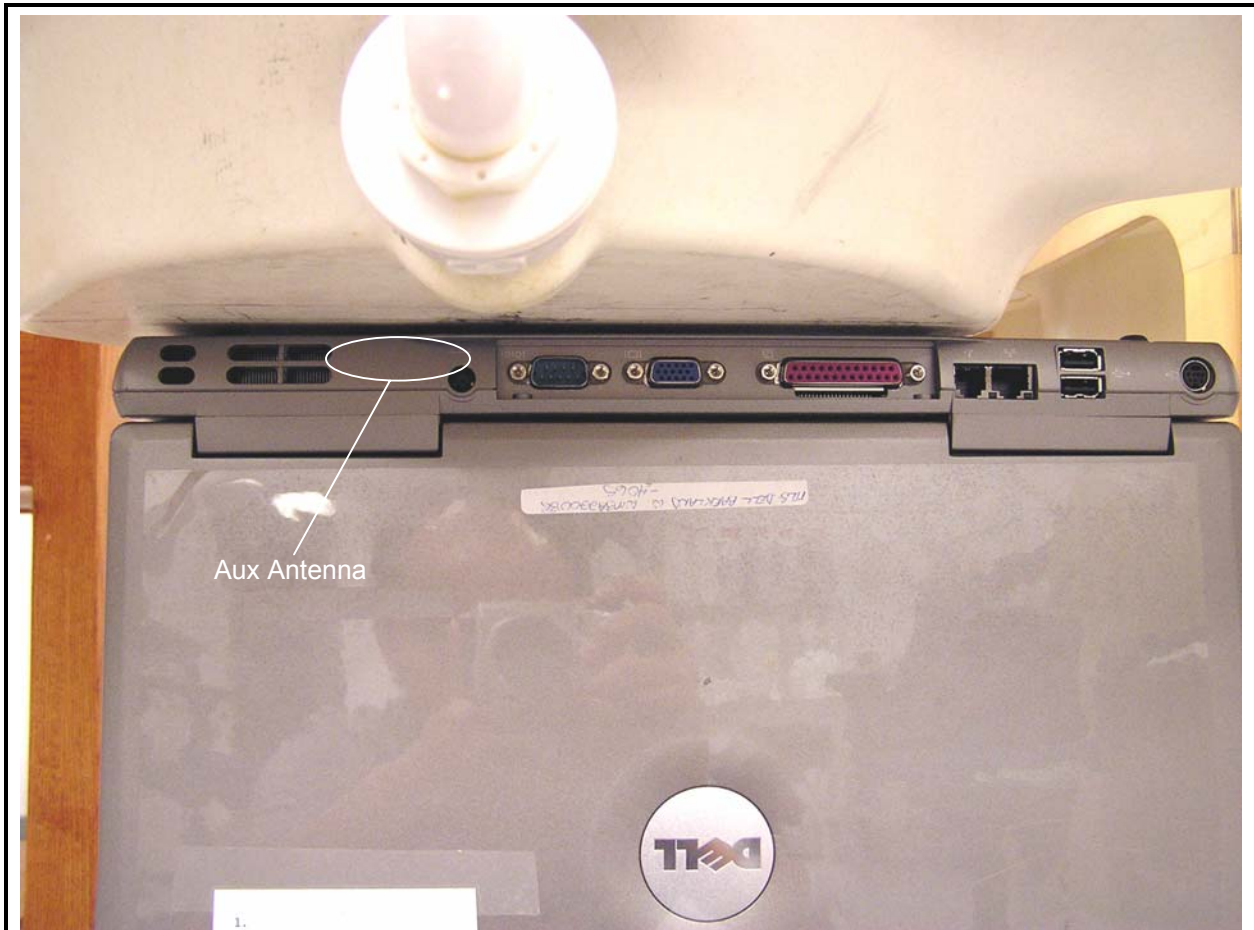
Notes:

1. \*: Average power.
2. \*\*: The SAR measured at the middle and high channel for this configuration were at least 3 dB lower than SAR limit, testing at the low channels is option
3. SAR is tested for a lap-held position with the bottom of the laptop in direct contact against a flat phantom.
4. Please see attachment for the detailed measurement data and plots showing the maximum SAR location of the EUT.



**SAR MEASUREMENTS RESULTS**

**2-1\_EUT Setup Configuration 1 – Aux Antenna (5.5GHz band)**



Antenna - WNC

Duty cycle: 99%; Crest factor: 1

Depth of liquid: 15 cm

Sep. dist. [mm]	Antenna	Ch. #	f [MHz]	*Conducted Power [dBm]		SAR_1g [mW/g]	
				Before	After	Measured	Limited
0	Aux	149	5745	17.2	17.2	0.492	1.6
0	Aux	157	5785	17.1	17.1	0.459	1.6
0	Aux	165	5825	17.1	17.1	0.356	1.6

Antenna - Hitachi

Duty cycle: 99%; Crest factor: 1

Depth of liquid: 15 cm

Sep. dist. [mm]	Antenna	Ch. #	f [MHz]	*Conducted Power [dBm]		SAR_1g [mW/g]	
				Before	After	Measured	Limited
0	Aux	149	5745	17.2	17.2	0.463	1.6
0	Aux	157	5785	17.1	17.1	0.379	1.6
0	Aux	165	5825	17.1	17.1	0.456	1.6

Notes:

1. \*: Average power.
2. SAR is tested for a lap-held position with the bottom of the laptop in direct contact against a flat phantom.
3. Please see attachment for the detailed measurement data and plots showing the maximum SAR location of the EUT.

**SAR MEASUREMENTS RESULTS**

**2-2\_EUT Setup Configuration 2 – Main Antenna (5.8GHz band)**



Antenna - WNC

Duty cycle: 99%; Crest factor: 1

Depth of liquid: 15 cm

Sep. dist. [mm]	Antenna	Ch. #	f [MHz]	*Conducted Power [dBm]		SAR_1g [mW/g]	
				Before	After	Measured	Limited
0	Main	149	5745	17.2	17.2	0.289	1.6
0	Main	157	5785	17.1	17.1	0.278	1.6
0	Main	165	5825	17.1	17.1	0.253	1.6

Antenna - Hitachi

Duty cycle: 99%; Crest factor: 1

Depth of liquid: 15 cm

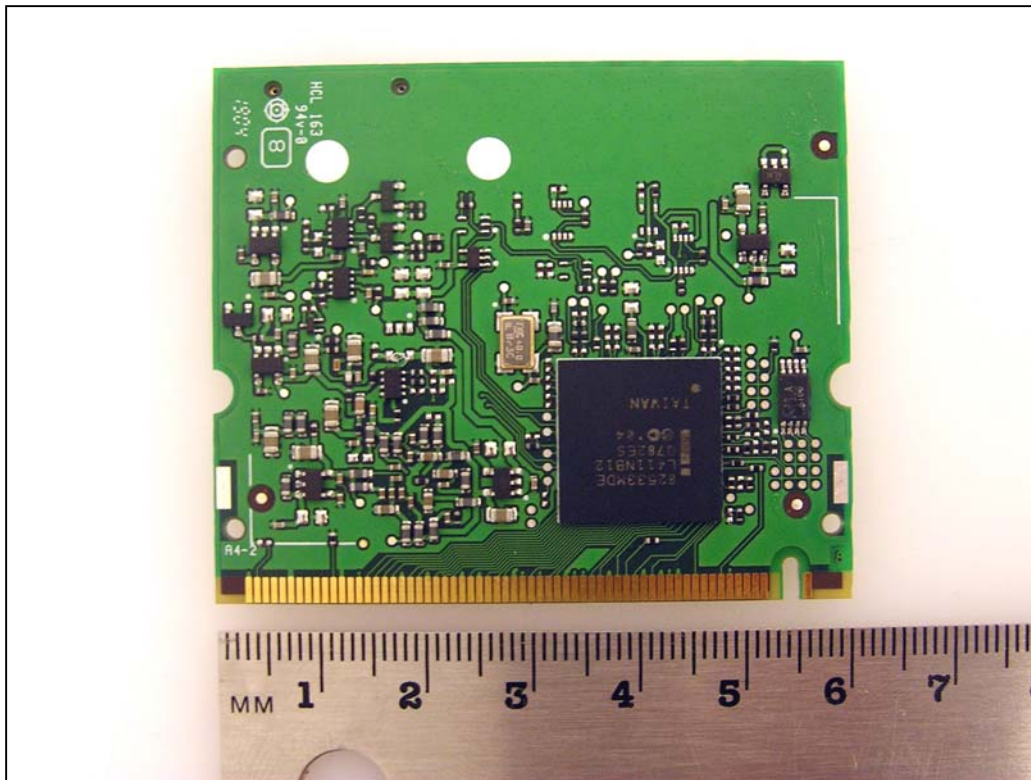
Sep. dist. [mm]	Antenna	Ch. #	f [MHz]	*Conducted Power [dBm]		SAR_1g [mW/g]	
				Before	After	Measured	Limited
0	Main	149	5745	17.2	17.2	0.854	1.6
0	Main	157	5785	17.1	17.1	0.749	1.6
0	Main	165	5825	17.1	17.1	0.588	1.6

Notes:

1. \*: Average power.
2. SAR is tested for a lap-held position with the bottom of the laptop in direct contact against a flat phantom.
3. Please see attachment for the detailed measurement data and plots showing the maximum SAR location of the EUT.

9. PHOTOS

EQUIPMENT UNDER TEST (EUT)





**HOST DEVICE**



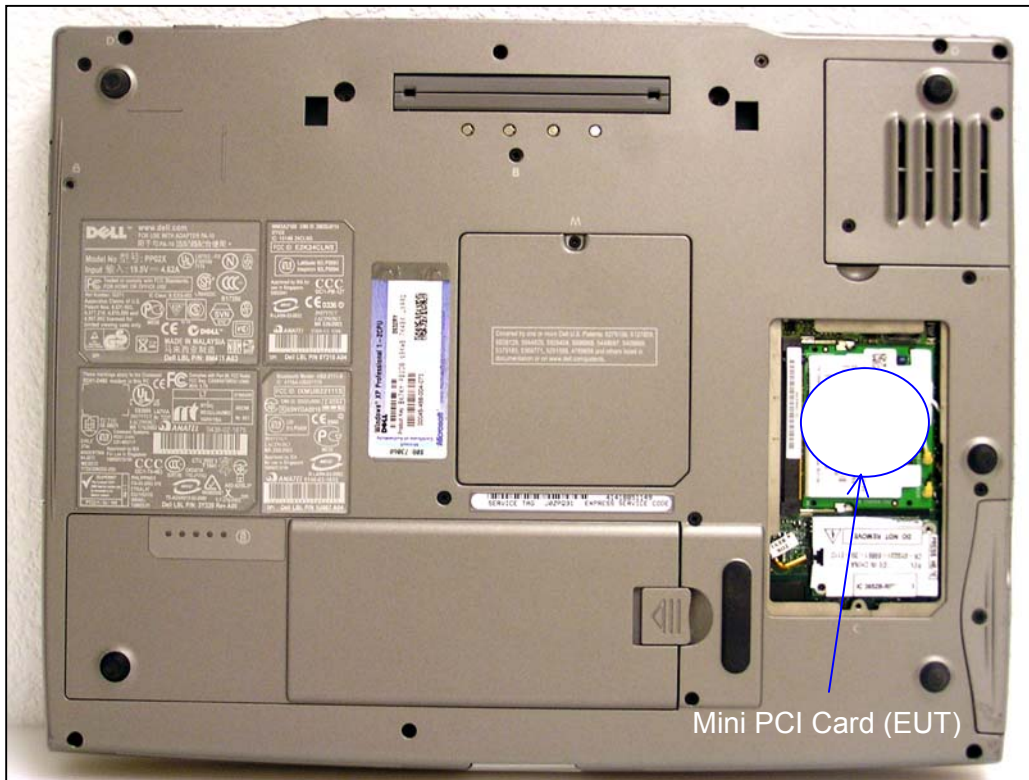
<Front view>



<Rear View>



HOST DEVICE



<Bottom View>

**10. EQUIPMENT LIST & CALIBRATION STATUS**

<u>Name of Equipment</u>	<u>Manufacturer</u>	<u>Type/Model</u>	<u>Serial Number</u>	<u>Cal. Due date</u>
S-Parameter Network Analyzer	Agilent	8753ES-6	US39173569	8/8/04
Electronic Probe kit	Hewlett Packard	85070C	N/A	N/A
Signal General	R&H	SMP 04	DE34210	5/5/05
Power Meter	HP	E4416	GB41291160	11/7/04
Power Sensor	HP	E9327A	US40440755	11/7/04
Amplifier	Mini-Circuits	ZVE-8G	0360	N/A
Amplifier	Mini-Circuits	ZHL-42W	D072701-5	N/A
Radio Communication Tester	Rohde & Schwarz	CMU 200	838114/032	11/1/04
Data Acquisition Electronics (DAE)	SPEAG	DAE3 V1	500	12/23/04
Dosimetric E-Field Probe	SPEAG	ES3DV2	3021	7/29/04
System Validation Dipole	SPEAG	D5GHzV2	1003	10/5/05
Probe Alignment Unit	SPEAG	LB (V2)	261	N/A
Robot	Staubli	RX90B L	F00/5H31A1/A/01	N/A
SAM Twin Phantom	SPEAG	TP-1785	QD 000 P40 CA	N/A
SAM Twin Phantom	SPEAG	TP-1015	N/A	N/A
Simulating Liquids	SPEAG	MSL5800	N/A	Within 24 hrs of first test

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**12. ATTACHMENTS**

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**End of Report**