Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland

ilac-MRA

SWISS CALIBRATION

S Schweizerischer Kalibrierdienst
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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Glossary

DAE   data acquisition electronics
Connector angle   information used in DASY system to align probe sensor X to the robot
                coordinate system.

Methods Applied and Interpretation of Parameters

- *DC Voltage Measurement*: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.

- *Connector angle*: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.

- The following parameters contain technical information as a result from the performance test and require no uncertainty.

- *DC Voltage Measurement Linearity*: Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.

- *Common mode sensitivity*: Influence of a positive or negative common mode voltage on the differential measurement.

- *Channel separation*: Influence of a voltage on the neighbor channels not subject to an input voltage.

- *AD Converter Values with inputs shorted*: Values on the internal AD converter corresponding to zero input voltage

- *Input Offset Measurement*: Output voltage and statistical results over a large number of zero voltage measurements.

- *Input Offset Current*: Typical value for information; Maximum channel input offset current, not considering the input resistance.

- *Input resistance*: DAE input resistance at the connector, during internal auto-zeroing and during measurement.

- *Low Battery Alarm Voltage*: Typical value for information. Below this voltage, a battery alarm signal is generated.

- *Power consumption*: Typical value for information. Supply currents in various operating modes.

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DC Voltage Measurement

A/D - Converter Resolution nominal

High Range:	1LSB =	6.1µV ,	full range =	-100…+300 mV
Low Range:	1LSB =	61nV ,	full range =	-1…….+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	404.715 ± 0.1% (k=2)	403.520 ± 0.1% (k=2)	405.065 ± 0.1% (k=2)
Low Range	3.99539 ± 0.7% (k=2)	3.96323 ± 0.7% (k=2)	3.97102 ± 0.7% (k=2)

Connector Angle

Connector Angle to be used in DASY system	309 º ± 1 º

Appendix

1. DC Voltage Linearity

High Range		Input (μV)	Reading (μV)	Error (%)
Channel X	+ Input	200000	199999.5	0.00
Channel X	+ Input	20000	20004.41	0.02
Channel X	- Input	20000	-20002.56	0.01
Channel Y	+ Input	200000	200000.3	0.00
Channel Y	+ Input	20000	20003.67	0.02
Channel Y	- Input	20000	-20003.41	0.02
Channel Z	+ Input	200000	200000.3	0.00
Channel Z	+ Input	20000	20002.49	0.01
Channel Z	- Input	20000	-20006.25	0.03

Low Range		Input (μV)	Reading (μV)	Error (%)
Channel X	+ Input	2000	1999.9	0.00
Channel X	+ Input	200	199.47	-0.26
Channel X	- Input	200	-200.56	0.28
Channel Y	+ Input	2000	2000.1	0.00
Channel Y	+ Input	200	199.15	-0.43
Channel Y	- Input	200	-200.77	0.39
Channel Z	+ Input	2000	2000	0.00
Channel Z	+ Input	200	199.22	-0.39
Channel Z	- Input	200	-201.39	0.69

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	-6.00	-6.42
	- 200	7.17	6.60
Channel Y	200	-2.49	-2.64
	- 200	2.04	1.25
Channel Z	200	-10.83	-10.80
	- 200	9.19	8.80

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Y (μV)	Channel Z (μV)
Channel X	200	-	2.57	0.15
Channel Y	200	0.11	-	4.08
Channel Z	200	-1.80	1.03	-

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4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	16068	16321
Channel Y	16180	16239
Channel Z	16405	16167

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10MΩ

	Average (μV)	min. Offset (μV)	max. Offset (μV)	Std. Deviation (μV)
Channel X	-0.14	-1.23	0.61	0.34
Channel Y	-0.85	-2.24	0.48	0.49
Channel Z	-1.24	-2.43	0.38	0.51

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance

	Zeroing (MOhm)	Measuring (MOhm)
Channel X	0.2000	201.7
Channel Y	0.2000	201.7
Channel Z	0.1999	202.5

8. Low Battery Alarm Voltage (verified during pre test)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption (verified during pre test)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.0	+6	+14
Supply (- Vcc)	−0.01	-8	-9

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Client **Sporton (Auden)**

Certificate No: **ET3-1787_Aug07**

CALIBRATION CERTIFICATE

Object	ET3DV6 - SN:1787
Calibration procedure(s)	QA CAL-01.v6 Calibration procedure for dosimetric E-field probes
Calibration date:	August 28, 2007
Condition of the calibrated item	In Tolerance

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	29-Mar-07 (METAS, No. 217-00670)	Mar-08
Power sensor E4412A	MY41495277	29-Mar-07 (METAS, No. 217-00670)	Mar-08
Power sensor E4412A	MY41498087	29-Mar-07 (METAS, No. 217-00670)	Mar-08
Reference 3 dB Attenuator	SN: S5054 (3c)	8-Aug-07 (METAS, No. 217-00719)	Aug-08
Reference 20 dB Attenuator	SN: S5086 (20b)	29-Mar-07 (METAS, No. 217-00671)	Mar-08
Reference 30 dB Attenuator	SN: S5129 (30b)	8-Aug-07 (METAS, No. 217-00720)	Aug-08
Reference Probe ES3DV2	SN: 3013	4-Jan-07 (SPEAG, No. ES3-3013_Jan07)	Jan-08
DAE4	SN: 654	20-Apr-07 (SPEAG, No. DAE4-654_Apr07)	Apr-08

Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (SPEAG, in house check Nov-05)	In house check: Nov-07
Network Analyzer HP 8753E	US37390585	18-Oct-01 (SPEAG, in house check Oct-06)	In house check: Oct-07

	Name	Function	Signature
Calibrated by:	Katja Pokovic	Technical Manager	
Approved by:	Niels Kuster	Quality Manager	

Issued: August 29, 2007

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

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Glossary:

TSL	tissue simulating liquid
NORMx,y,z	sensitivity in free space
ConF	sensitivity in TSL / NORMx,y,z
DCP	diode compression point
Polarization φ	φ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis

Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

Methods Applied and Interpretation of Parameters:

- *NORMx,y,z*: Assessed for E-field polarization $\vartheta = 0$ (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E^2-field uncertainty inside TSL (see below ConF).
- *NORM(f)x,y,z = NORMx,y,z * frequency_response* (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConF.
- *DCPx,y,z*: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- *ConF and Boundary Effect Parameters*: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z * ConF whereby the uncertainty corresponds to that given for ConF. A frequency dependent ConF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- *Spherical isotropy (3D deviation from isotropy)*: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- *Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

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Probe ET3DV6

SN:1787

Manufactured: May 28, 2003
Last calibrated: May 31, 2006
Recalibrated: August 28, 2007

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

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DASY - Parameters of Probe: ET3DV6 SN:1787

Sensitivity in Free Space[A]   Diode Compression[B]

NormX	$1.63 \pm 10.1\%$	$\mu V/(V/m)^2$	DCP X	92 mV
NormY	$1.66 \pm 10.1\%$	$\mu V/(V/m)^2$	DCP Y	96 mV
NormZ	$2.08 \pm 10.1\%$	$\mu V/(V/m)^2$	DCP Z	91 mV

Sensitivity in Tissue Simulating Liquid (Conversion Factors)

Please see Page 8.

Boundary Effect

TSL   900 MHz   Typical SAR gradient: 5 % per mm

		3.7 mm	4.7 mm
Sensor Center to Phantom Surface Distance			
SAR_{be} [%]	Without Correction Algorithm	4.7	2.0
SAR_{be} [%]	With Correction Algorithm	0.1	0.0

TSL   1810 MHz   Typical SAR gradient: 10 % per mm

		3.7 mm	4.7 mm
Sensor Center to Phantom Surface Distance			
SAR_{be} [%]	Without Correction Algorithm	11.8	7.0
SAR_{be} [%]	With Correction Algorithm	0.2	0.4

Sensor Offset

Probe Tip to Sensor Center   **2.7** mm

> The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

[A] The uncertainties of NormX,Y,Z do not affect the E^2-field uncertainty inside TSL (see Page 8).
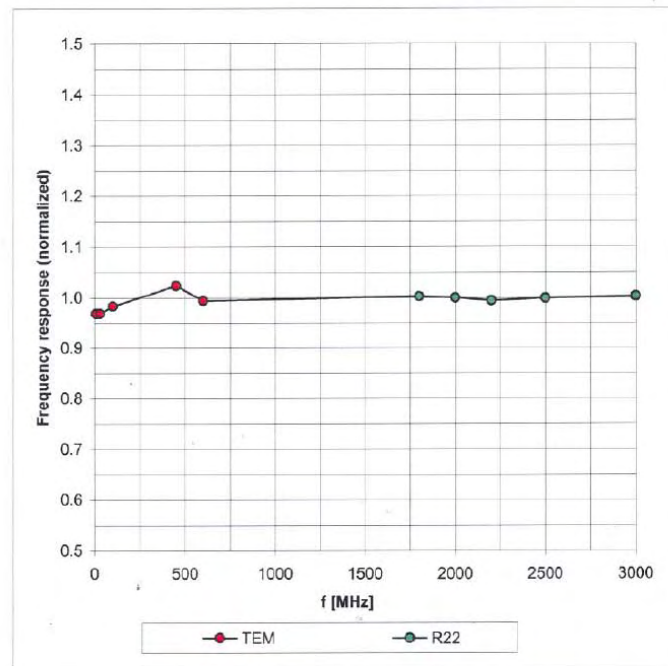[B] Numerical linearization parameter: uncertainty not required.

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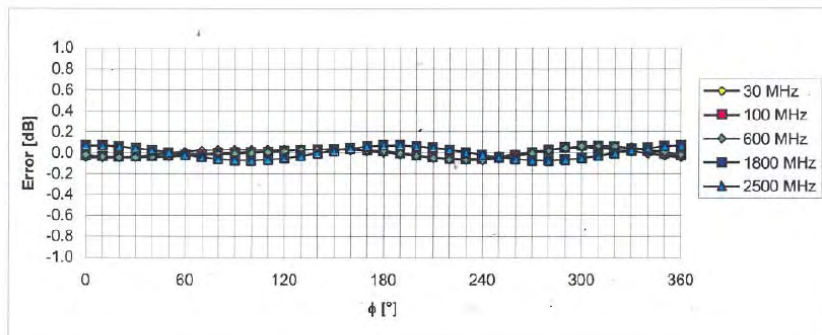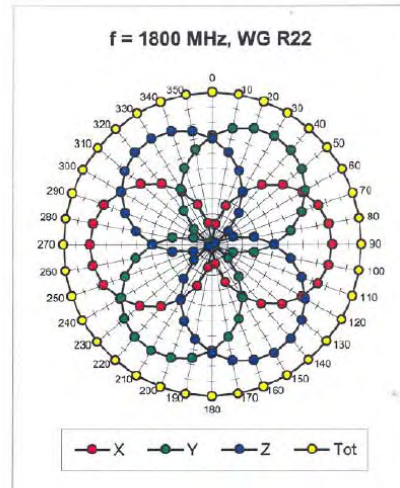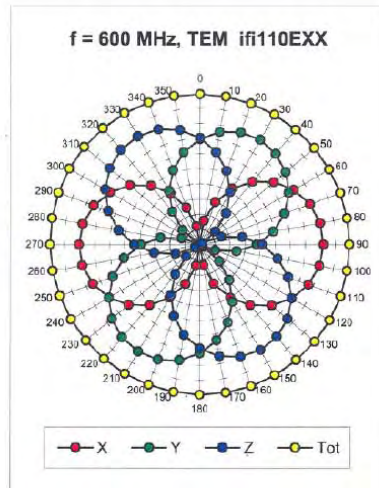## Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide: R22)

Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

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Receiving Pattern (φ), ϑ = 0°

Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

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Dynamic Range f(SAR_{head})

(Waveguide R22, f = 1800 MHz)
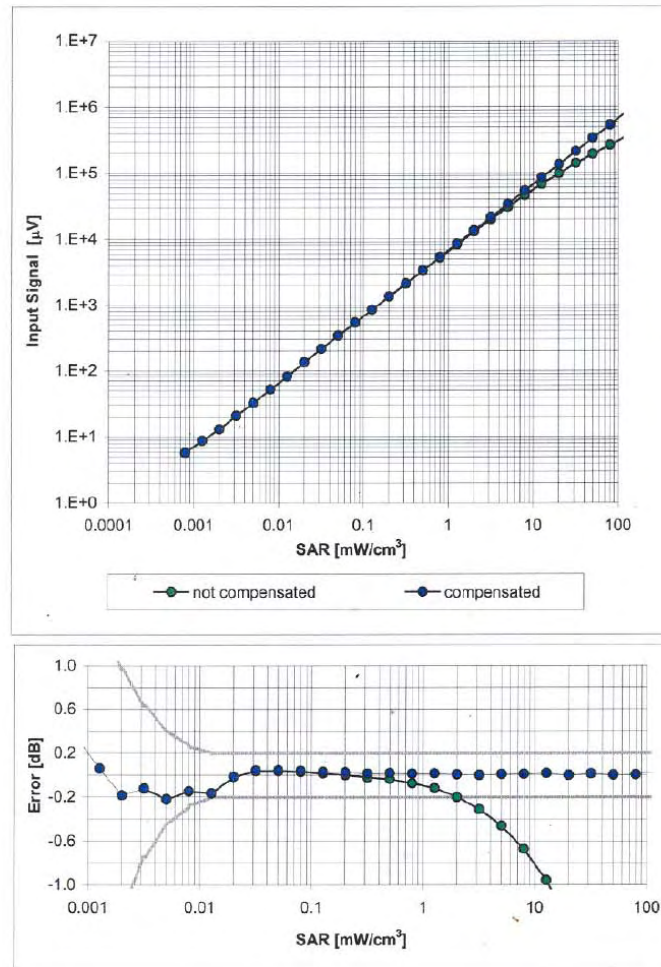
Uncertainty of Linearity Assessment: ± 0.6% (k=2)

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Conversion Factor Assessment
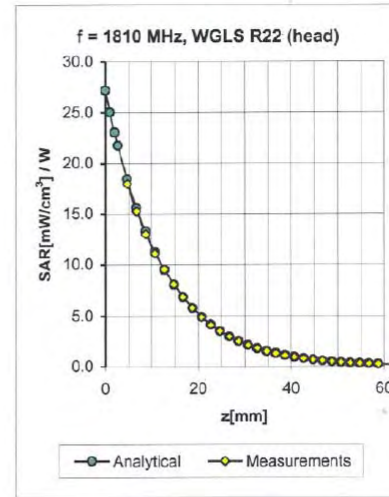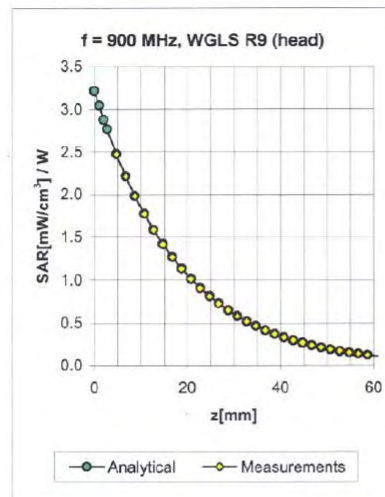
f [MHz]	Validity [MHz]^c	TSL	Permittivity	Conductivity	Alpha	Depth	ConvF	Uncertainty
900	± 50 / ± 100	Head	41.5 ± 5%	0.97 ± 5%	0.32	2.42	6.58	± 11.0% (κ=2)
1810	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.50	2.61	5.16	± 11.0% (κ=2)
2000	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.55	2.45	4.80	± 11.0% (κ=2)
2450	± 50 / ± 100	Head	39.2 ± 5%	1.80 ± 5%	0.67	1.81	4.50	± 11.8% (κ=2)
900	± 50 / ± 100	Body	55.0 ± 5%	1.05 ± 5%	0.36	2.52	6.10	± 11.0% (κ=2)
1810	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.61	2.56	4.68	± 11.0% (κ=2)
2000	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.60	2.40	4.30	± 11.0% (κ=2)
2450	± 50 / ± 100	Body	52.7 ± 5%	1.95 ± 5%	0.65	2.15	4.02	± 11.8% (κ=2)

^{c} The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.
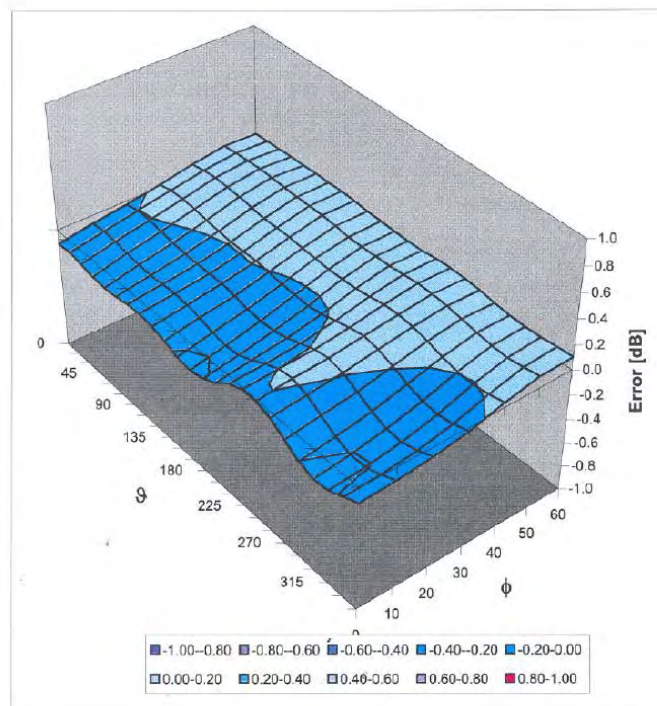
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Deviation from Isotropy in HSL
Error (φ, ϑ), f = 900 MHz

Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

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Appendix D - Product Photo

Appendix E - Test Setup Photo

Bottom of Tablet with 0cm Gap

Bottom Top Position with 0cm Gap

Right Top Position with 0cm Gap

Left Top Position with 0cm Gap