

CHAPTER 3

VIBRATION TEST

5.1 ADMINISTRATIVE INFORMATION

3.1.1 CLIENT

ACR Electronics Inc.

3.1.2. REPRESENTATIVES PRESENT

For the Client : C. HAVENS ACR & G. PEYROU ITS/EQ

For the Test Laboratory : J. M. BUCHMAN

3.1.3. DATES

Start of test : 25 June 2004

End of test : 28 June 2004

3.1.4. INTESPACE FILE REFERENCE : E5503-RTCM

3.2. UNIT UNDER TEST (UUT)

Beacon Unit : 1/3

Name : ACR / TeraFixTM 406GPS I/O PLB

Type : PLB200

Number : 07

3.3. PURPOSE OF THE TEST

Functional checkout of hardware after vibration testing.

3.4. TEST EQUIPMENT

3.4.1. TEST DEVICES

Electrodynamic vibration table, type 27 with GR3

Spectral Dynamics SD2225 digital control panel

3.4.2. METROLOGICAL EQUIPMENT

Vibration Control : accelerometer (analysis and processing)

Vibration Measurements : Spectral Dynamics SD2225

Electrical Beacon Checking : Argos - Cospas/Sarsat Test Bench.

3.5. TEST PROCEDURE

3.5.1. AXIS (See photograph in § 3.7)

X-axis : parallel to the Beacon fixing plane and Beacon « widthways »

Y-axis : perpendicular to the Beacon fixing plane

Z-axis : parallel to the Beacon fixing plane and Beacon « lengthways »

3.5.2. MOUNTING

The beacon in its bracket is secured to a light-alloy supporting square.
 The complete assembly is firmly attached to the moving part of the vibration table according to the required axis.

3.5.3. TEST SPECIFICATIONS AND SEQUENCE

Vibrations following Section A3.0 of RTCM Recommended Standards for 406 MHz Satellite PLBs (Version 1.1 Feb 4, 2003)

Sinewave vibrations on three axis :

Frequency (Hz)	Peak to Peak Amplitude (mm)
4-10	5
10-15	1.6
15-25	0.8
25-33	0.4

Sweep rate : 1.2 oct/min

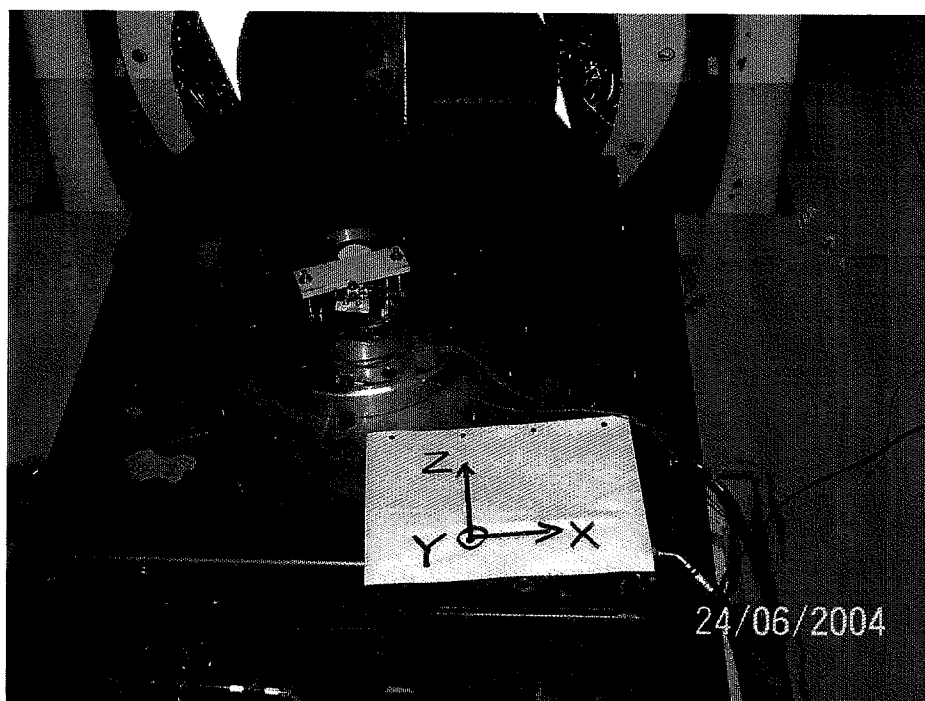
Duration : 30 minutes on each axis

Beacon control : Visual inspection and Aliveness test after the Vibrations Tests

3.6 LIST OF SERVO AND CONTROL SENSORS

Sensor	Location	N° acc.	Cable	Sensitivity pC/g
P (servo)	Screwed on test holder sheet	CP91	BU03	9.24
1X (control)	Glued on the Beacon	12889	BU13	2.97
1Y (control)	Glued on the Beacon	5368	Rge	6.44
1Z (control)	Glued on the Beacon	2574	BU11	6.435

3.7. PHOTOGRAPH



5.8. TEST SCHEDULE

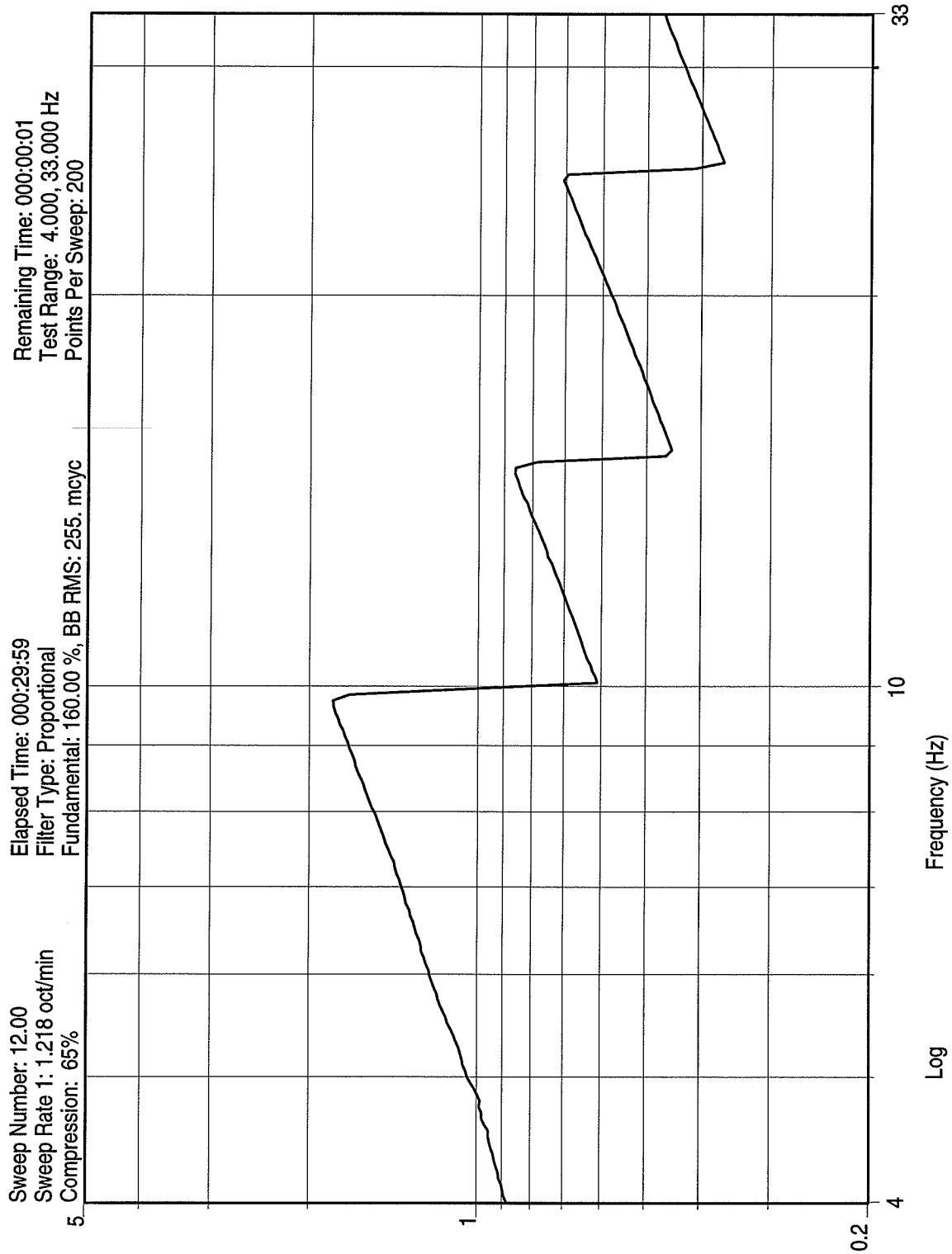
Date / Test n°	Specifications	Paragraph	Events - Observations	
			Test equipment	Unit under test
June 25 th , 2004 001Y	Sinewave vibrations : Y axis 5 mm p-p from 4 to 10 Hz 1.6 mm p-p from 10 to 15 Hz 0.8 mm p-p from 15 to 25 Hz 0.4 mm p-p from 25 to 33 Hz Sweep duration : 2 min 30 s Total test duration : 30 min	3.9.1	Nominal.	Set up the beacon on test table on Yaxis. Functional testing : nominal.
June 28 th , 2004 003X	Sinewave vibrations : X axis 5 mm p-p from 4 to 10 Hz 1.6 mm p-p from 10 to 15 Hz 0.8 mm p-p from 15 to 25 Hz 0.4 mm p-p from 25 to 33 Hz Sweep duration : 2 min 30 s Total test duration : 30 min	3.9.2	Nominal	Set up the beacon on test table on X axis Functional testing : nominal.

Date / Test n°	Specifications	Paragraph	Events - Observations	
			Test equipment	Unit under test
June 28 th , 2004 004Z	Sinewave vibrations : Z axis 5 mm p-p from 4 to 10 Hz 1.6 mm p-p from 10 to 15 Hz 0.8 mm p-p from 15 to 25 Hz 0.4 mm p-p from 25 to 33 Hz Sweep duration : 2 min 30 s Total test duration : 30 min	3.9.3	Nominal	Set up the beacon on test table on Z axis Functional testing : nominal Removal of beacon
Visual inspection		3.9.4.1		Nothing abnormal to note
PLB Aliveness Test		3.9.4.2	Cospas Sarsat Test Bench	Nominal

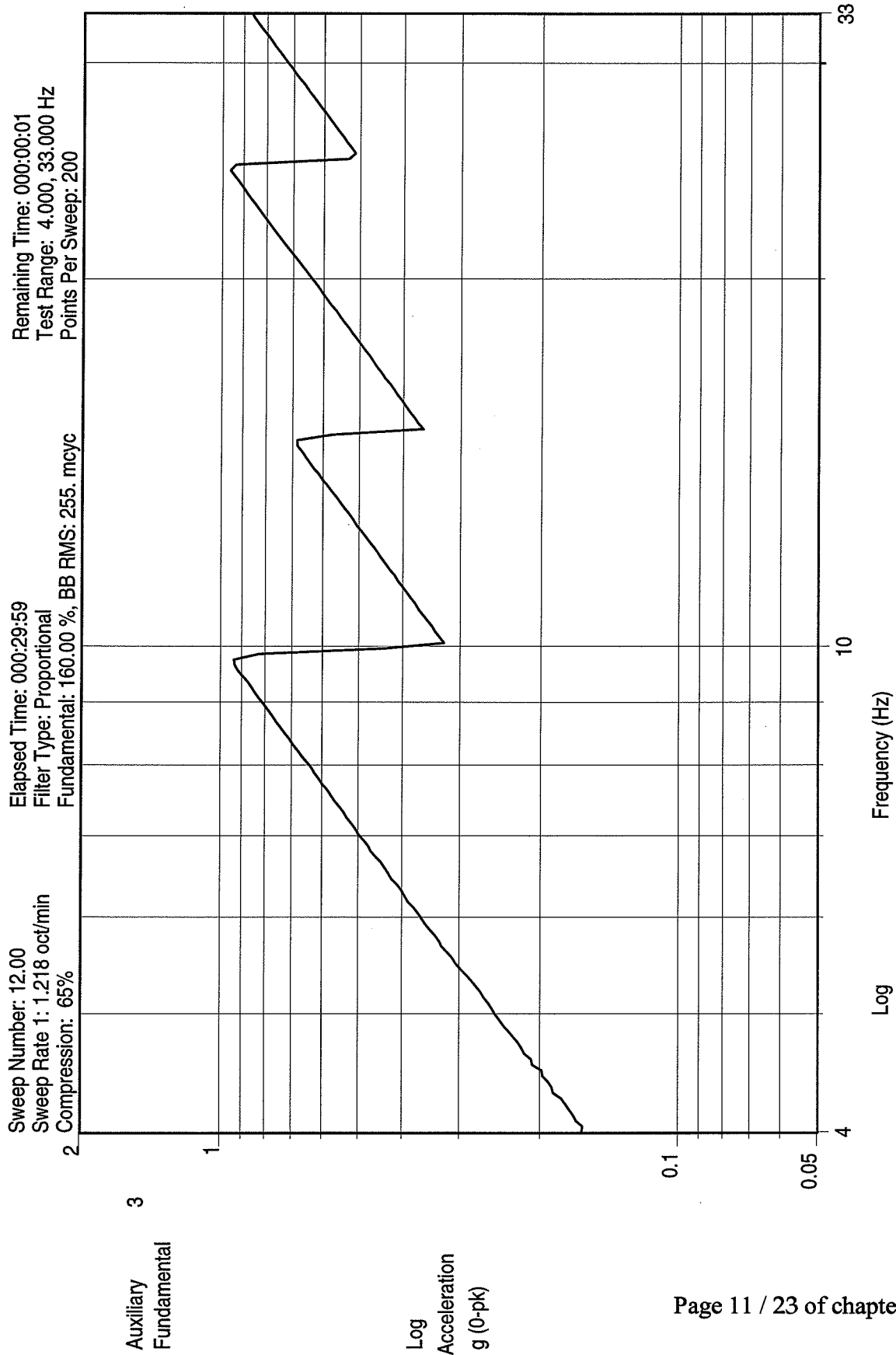
3.9. TEST RESULTS

3.9.1. RESULTS OF Y VIBRATION AXIS

%Test: RTCM.001 Y
%Log: /user/client/e5503/sine/log/RTCM.001.log
06/24/04
18:01:12 Nulling Internal Offsets.
18:01:49 Nulling Completed.
18:01:50 Loop Check Started...
18:01:50 Measuring Ambient Noise...
18:01:59 Searching for Threshold...
18:02:05 Loop Check Completed.
18:02:07 Increasing to Test Level...
18:02:10 Minimum Drive Reached.
18:03:23 Start Level Reached.
18:03:23 Test Starts at 4.000 Hz
18:05:53 Saved Sweep Number 1.00
18:08:23 Saved Sweep Number 2.00
18:10:53 Saved Sweep Number 3.00
18:13:23 Saved Sweep Number 4.00
18:15:53 Saved Sweep Number 5.00
18:18:23 Saved Sweep Number 6.00
18:20:53 Saved Sweep Number 7.00
18:23:23 Saved Sweep Number 8.00
18:25:52 Saved Sweep Number 9.00
18:28:23 Saved Sweep Number 10.00
18:30:52 Saved Sweep Number 11.00
18:33:23 Shutdown Initiated...
18:33:27 Saved Sweep Number 12.00

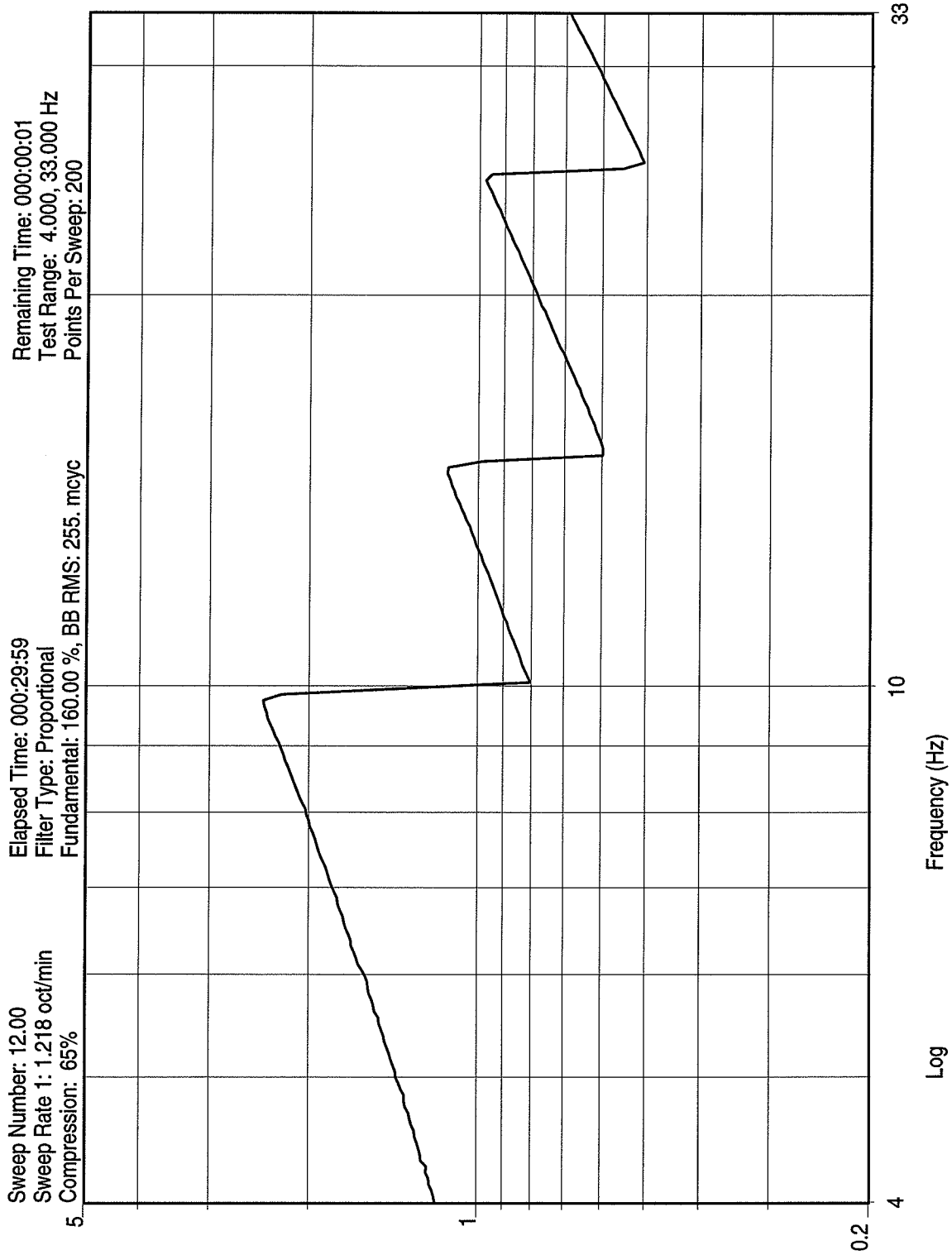


RTCM VIBRATION TEST _ RTCM_Axe Y
 E5503 - Beacon ACR PLB 200/201 S/N : 07
 Sine Data Review Name: RTCM.001



3.9.2. RESULTS OF X VIBRATION AXIS

%Test: RTCM.003 X
%Log: /user/client/e5503/sine/log/RTCM.003.log
06/28/04
09:37:34 Loop Check Started...
09:37:34 Measuring Ambient Noise...
09:38:01 Searching for Threshold...
09:38:06 Loop Check Completed.
09:40:10 Increasing to Test Level...
09:40:54 Start Level Reached.
09:40:54 Test Starts at 4.000 Hz
09:43:24 Saved Sweep Number 1.00
09:45:54 Saved Sweep Number 2.00
09:48:24 Saved Sweep Number 3.00
09:50:54 Saved Sweep Number 4.00
09:53:24 Saved Sweep Number 5.00
09:55:54 Saved Sweep Number 6.00
09:58:24 Saved Sweep Number 7.00
10:00:54 Saved Sweep Number 8.00
10:03:24 Saved Sweep Number 9.00
10:05:54 Saved Sweep Number 10.00
10:08:24 Saved Sweep Number 11.00
10:10:54 Shutdown Initiated...
10:10:59 Saved Sweep Number 12.00

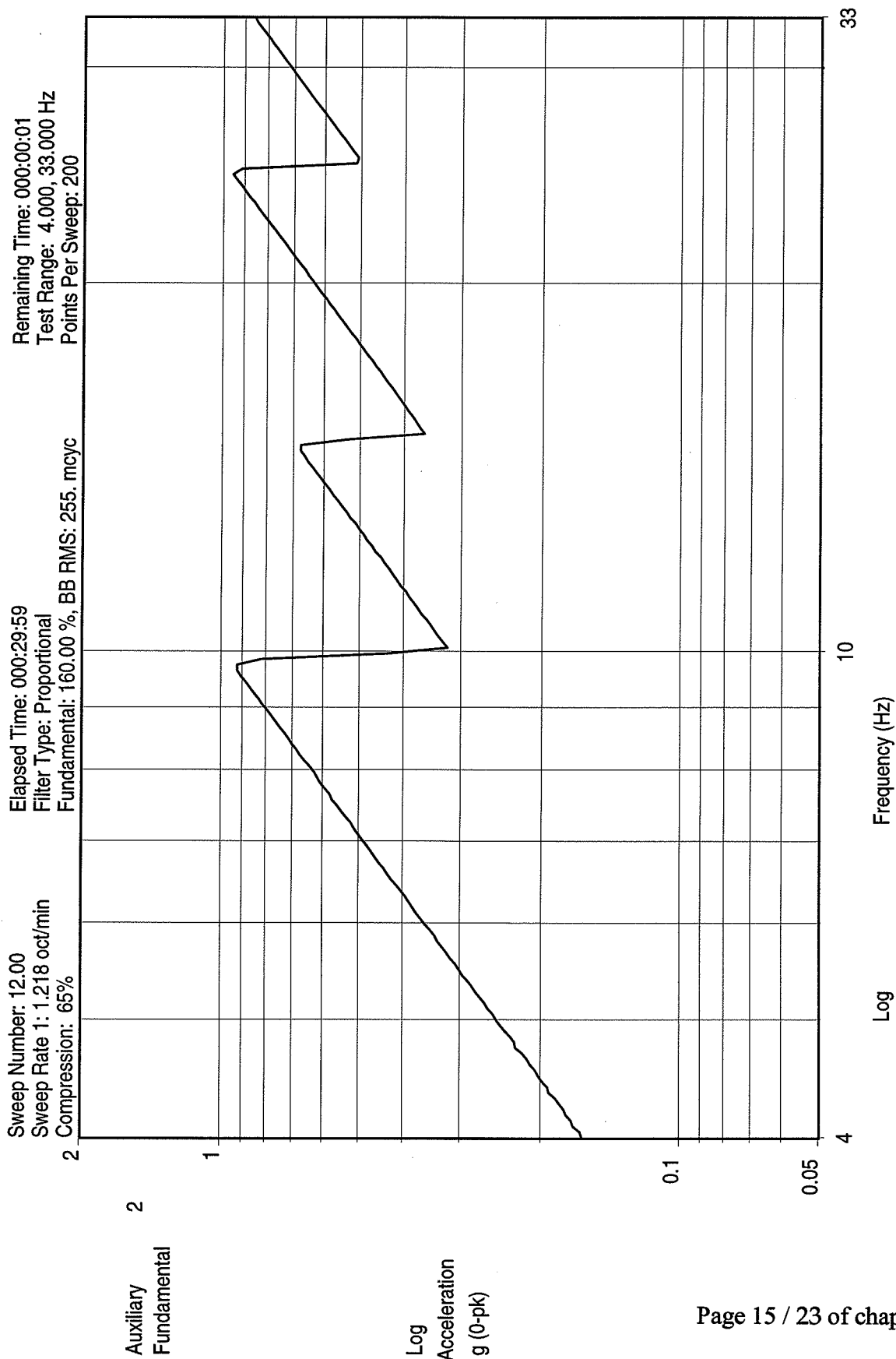


RTCM VIBRATION TEST _ RTCM_Axe X
 E5503 - Beacon ACR PLB 200/201 S/N : 07
 Sine Test Name: RTCM.003

Drive

Log

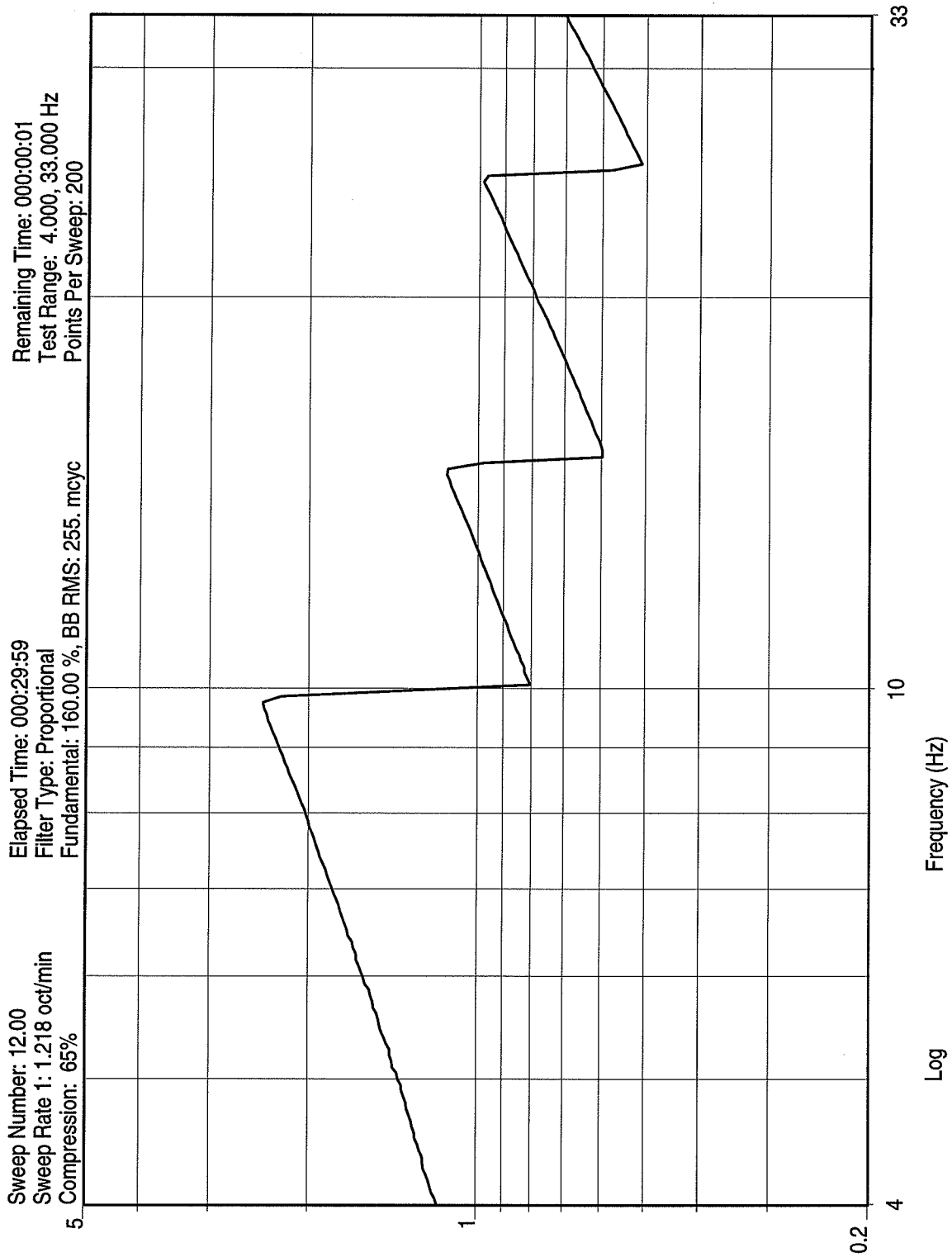
V (0-pk)



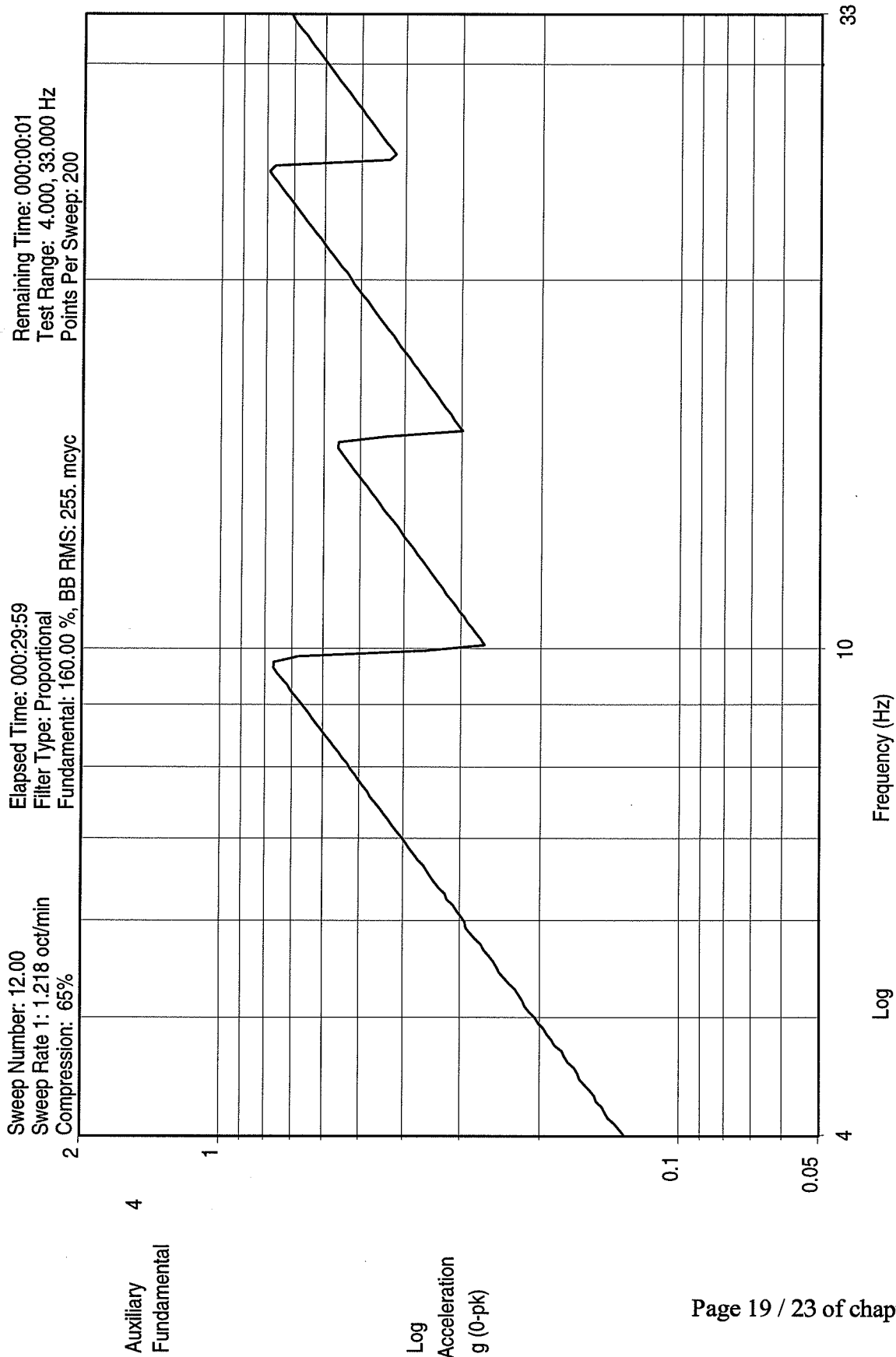


3.9.3. RESULTS OF Z VIBRATION AXIS

%Test: RTCM.004Z
%Log: /user/client/e5503/sine/log/RTCM.004.log
06/28/04
16:09:05 Nulling Internal Offsets.
16:09:10 Nulling Completed.
16:09:11 Loop Check Started...
16:09:11 Measuring Ambient Noise...
16:09:22 Searching for Threshold...
16:09:28 Loop Check Completed.
16:09:38 Increasing to Test Level...
16:10:18 Start Level Reached.
16:10:18 Test Starts at 4.000 Hz
16:12:48 Saved Sweep Number 1.00
16:15:18 Saved Sweep Number 2.00
16:17:48 Saved Sweep Number 3.00
16:20:18 Saved Sweep Number 4.00
16:22:48 Saved Sweep Number 5.00
16:25:18 Saved Sweep Number 6.00
16:27:48 Saved Sweep Number 7.00
16:30:18 Saved Sweep Number 8.00
16:32:48 Saved Sweep Number 9.00
16:35:18 Saved Sweep Number 10.00
16:37:48 Saved Sweep Number 11.00
16:40:18 Shutdown Initiated...
16:40:23 Saved Sweep Number 12.00



RTCM VIBRATION TEST _ RTCM_Axe Z
 E5503 - Beacon ACR PLB 200/201 S/N : 07
 Sine Test Name: RTCM.004



3.9.4. BEACON CHECKOUT

Test using a portable test bench and visual inspection confirmed that the beacon does not activate in an untimely manner during vibration testing.

3.9.5. FINAL CONTROL

3.9.5.1.External mechanical inspection.

A visual inspection was done on all external mechanical parts.

Result : nominal.

3.9.5.2.Aliveness test results

Result : nominal.

Data and graphs are reported next page

VIBRATION ALIVENESS TEST RESULTS

Beacon Unit : 1/3
 Name : ACR / TeraFix™ 406GPS I/O PLB
 Type : PLB200
 Number : 07

Date : June 29th, 2004

406 MHz Measurements

1 - Environmental Temperature (° C)			+ 22° C
2 - POWER OUTPUT			
- Transmission power	dBm	37 ± 2	37.17
- Power risetime	ms	< 5	-
- Power falltime	ms	< 5	-
3 - SPURIOUS OUTPUT *			
- In band			OK
- Carrier harmonics			
4 -DIGITAL MESSAGE GENERATOR *			
- Repetition rate			-
- Bit rate	bits/S	400 ± 4	398.35
- Transmission time	ms	440 ± 4.4 / 520 ± 5.2	522.43
- CW preamble	ms	160 ± 1.6	160.70
5 - DIGITAL MESSAGE *			
- Bit and frame sync	bits	1-24	FFFE2F
- Format flag	bit	25	1
- Protocol flag	bit	26	0
- Country code	bits	27-36	0366
- Protocol	bits	37-40	1110
- Encoded Position Data Source	bits	111	1
- Homing	bits	112	1
- BCH 1 code read / calculated	bits	86-106 / 25-85	00B717 / 00B717
- BCH 2 code read / calculated	bits	133-144 / 107-132	9E3 / 9E3
6 - FREQUENCY			
- Nominal value	KHz	406 025 ± 2 or 406 028 ± 1	406 027.875
- Short term stability		< 210 ⁻⁹ /100 ms	3.5 x 10 ⁻¹⁰

* See data and graphs next pages

Laboratoire de certification
Contrôle balise ARGOS/SARSAT

After vibrations and Bumps tests

Constructeur **ACR**
Modele **PLB 206**
Numero de serie **7**
Reference **E5503-07**
Type **SARSAT**

Date de l'essai **28 JUN 2004 17:13:43**
Température **22.2 °C**

Message balise

Message reçu (1-144): FFFR2F96FR3240072R80302DC5F78R0159R3
Format flag (25): 1
Protocole flag (26): 0
Code pays (27-36): 0366
Pays : USA
Code protocole (37-40): 1110
Protocole utilise : Standard - Test
Identification :
Numero :
RCH 1 lu/calculé (86-106/25-85): 00R717/00R717
RCH 2 lu/calculé (133-144/107-132): 9R3/9R3
Pos. Data Source (111): Internal
121.5 MHz Homing (112): Yes
Position GPS de reference lab : N 43°33'34'' E 1°28'48''
Position GPS : Yes
Position GPS par défaut : No
Latitude position : 43.5°3'32'' Nord
Longitude position : 1.5°58'40'' Est
Delta position : 254984532731 km

Contrôle message

Durée de la porteuse pure 160.70ms +- 0.00
Durée de l'émission 522.43 ms

Fréquence de modulation 398.35Hz +- 0.00

Stabilité de fréquence

Fréquence moyenne F2 406027874.84 Hz

SIGMA2 F2-F1 3.901E-10
SIGMA3 F3-F2 3.535E-10

Mesures d'indice

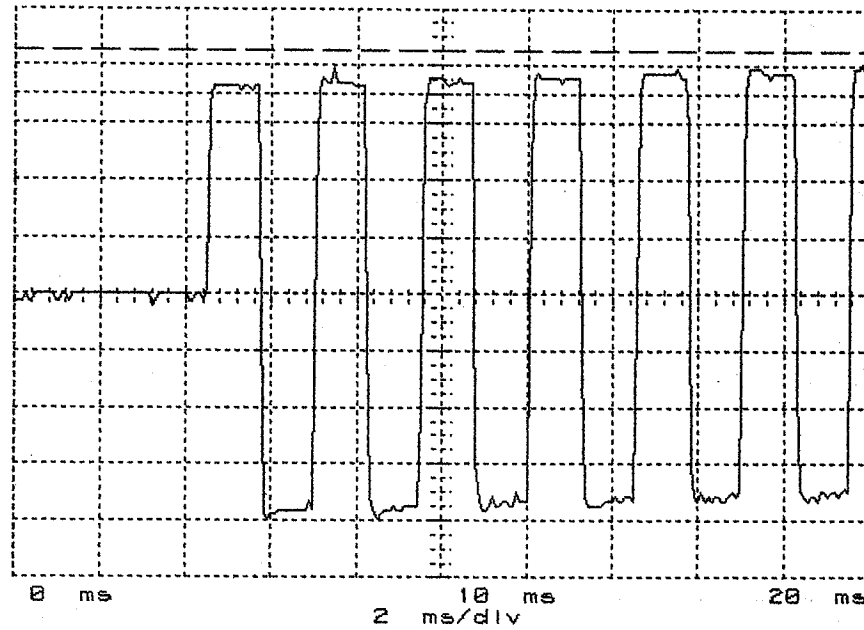
F	F1	G1
49875.35	250	61
49875.23	250	61

	rd	<=	
Excursion de phase totale	rd	<= 2.48	2.20
Excursion de phase positive	rd	0.96< <1.24	1.09
Excursion de phase negative	rd	-1.24< <-0.96	-1.11
Symétrie de l'excursion	%	<= 5	.88

Mesures de puissance

Puissance dBm 37.17

Oscillo



Spectre de fréquence

