

APPENDIX 2: SAR Measurement data

Appendix 2-1: Evaluation procedure

The SAR evaluation was performed with the following procedure:

Step 1: Measurement of the E-field at a fixed location above the central position of flat phantom was used as a reference value for assessing the power drop.

Step 2: The SAR distribution at the exposed side of head or body position was measured at a distance of each device from the inner surface of the shell. The area covered the entire dimension of the antenna of EUT and suitable horizontal grid spacing of EUT. Based on these data, the area of the maximum absorption was determined by splines interpolation.

Step 3: Around this point found in the Step 2 (area scan), a volume of 30mm(X axis)×30mm(Y axis)×30mm(Z axis) was assessed by measuring 7×7×7 points under 3GHz.
And for any secondary peaks found in the Step2 which are within 2dB of maximum peak and not with this Step3 (Zoom scan) is repeated.

On the basis of this data set, the spatial peak SAR value was evaluated under the following procedure:

- (1) The data at the surface were extrapolated, since the center of the dipoles is 1mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 2mm. The extrapolation was based on a least square algorithm [4]. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.
- (2) The maximum interpolated value was searched with a straightforward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1g or 10g) were computed by the 3D-Spline interpolation algorithm. The 3D-Spline is composed of three one-dimensional splines with the "Not a knot"-condition (in x, y and z-directions) [4], [5]. The volume was integrated with the trapezoidal-algorithm. One thousand points (10×10×10) were interpolated to calculate the average.
- (3) All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.

Step 4: Re-measurement of the E-field at the same location as in Step 1 for the assessment of the power drift.

Step 5: Repeat Step 1-Step 4 with other condition or/and setup of EUT.

Appendix 2-2: Measurement data / Platform(1): DS126401

Step 1: Worst position search

Step 1-1: Top-left & touch (separation distance=0mm) / 11b(1Mbps), 2437MHz

EUT: Wireless module in Platform(1) ; Type: ZC-ST (Platform(1): DS126401); Serial: ES40197 (Platform(1): 559)

Communication System: IEEE 802.11b(1Mbps, DBPSK/DSSS); Frequency: 2437 MHz; Crest Factor: 1.0

Medium: M2450; Medium parameters used: $f = 2437$ MHz; $\sigma = 1.91$ S/m; $\epsilon_r = 51$; $\rho = 1000$ kg/m³

DASY4 Configuration: - Probe: EX3DV4 - SN3540; ConvF(7.64, 7.64, 7.64); Calibrated: 2011/07/21
- Sensor-Surface: 2mm (Mechanical Surface Detection) - Electronics: DAE4 Sn626; Calibrated: 2012/02/15
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1059; Phantom section: Flat Section
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 184

fcc5(re#1),top(1)&touch(d0mm),11b(1m,set12d),m2437/

Area Scan:90x90,15 (7x7x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (measured) = 0.430 mW/g

Area Scan:90x90,15 (61x61x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (interpolated) = 0.635 mW/g

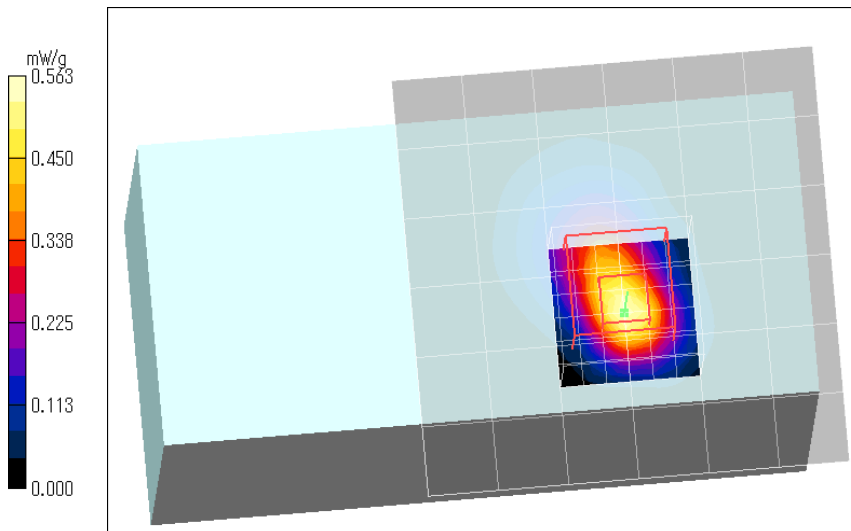
Z Scan:160,5 (1x1x33): Measurement grid: dx=20mm, dy=20mm, dz=5mm; Maximum value of SAR (measured) = 0.559 mW/g

Zoom Scan:30x30x30,5 (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm;

Reference Value = 18.1 V/m; Power Drift = 0.122 dB, Maximum value of SAR (measured) = 0.563 mW/g

Peak SAR (extrapolated) = 0.800 W/kg

SAR(1 g)=0.353 mW/g; SAR(10 g)=0.154 mW/g



Remarks: * Date tested: 2012/06/20; Tested by: Hiroshi Naka; Tested place: No.7 shielded room,
* liquid depth: 155mm; Position: distance of EUT to phantom: 0mm (2mm to liquid); ambient: 24.9deg.C. / 58 %RH,
* liquid temperature: 23.5(start)/23.5(end)/23.5(in check) deg.C.; * White cubic: zoom scan area, Red cubic: big=SAR(10g)/small=SAR(1g)

Appendix 2-2: Measurement data / Platform(1): DS126401 (cont'd)

Step 1: Worst position search (cont'd)

Step 1-2: Front & touch (separation distance=0mm) / 11b(1Mbps), 2437MHz

EUT: Wireless module in Platform(1) ; Type: ZC-ST (Platform(1): DS126401); Serial: ES40197 (Platform(1): 559)

Communication System: IEEE 802.11b(1Mbps, DBPSK/DSSS); Frequency: 2437 MHz; Crest Factor: 1.0

Medium: M2450; Medium parameters used: $f = 2437$ MHz; $\sigma = 1.91$ S/m; $\epsilon_r = 51$; $\rho = 1000$ kg/m³

DASY4 Configuration: - Probe: EX3DV4 - SN3540; ConvF(7.64, 7.64, 7.64); Calibrated: 2011/07/21
- Sensor-Surface: 2mm (Mechanical Surface Detection) - Electronics: DAE4 Sn626; Calibrated: 2012/02/15
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1059; Phantom section: Flat Section
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 184

fcc2,front(1)&touch(d0mm),11b(1m,sef12d),m2437/

Area Scan:105x90,15 (8x7x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (measured) = 0.067 mW/g

Area Scan:105x90,15 (71x61x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (interpolated) = 0.101 mW/g

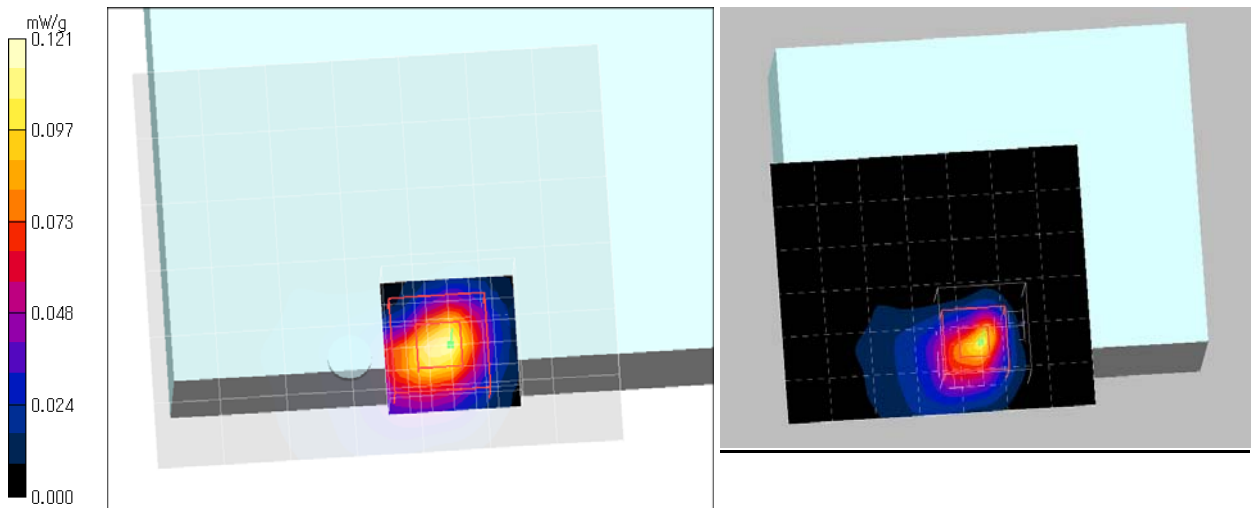
Z Scan:160,5 (1x1x33): Measurement grid: dx=20mm, dy=20mm, dz=5mm; Maximum value of SAR (measured) = 0.122 mW/g

Zoom Scan:30x30x30,5 (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm;

Reference Value = 2.86 V/m; Power Drift = 0.116 dB, Maximum value of SAR (measured) = 0.121 mW/g

Peak SAR (extrapolated) = 0.178 W/kg

SAR(1 g) = 0.077 mW/g; SAR(10 g) = 0.030 mW/g



Remarks: *. Date tested: 2012/06/20; Tested by: Hiroshi Naka; Tested place: No.7 shielded room,
*. liquid depth: 155mm; Position: distance of EUT to phantom: 0mm (2mm to liquid); ambient: 24.9deg.C. / 58 %RH,
*. liquid temperature: 23.5(start)/23.5(end)/23.5(in check) deg.C.; *. White cubic: zoom scan area, Red cubic: big=SAR(10g)/small=SAR(1g)

Appendix 2-2: Measurement data / Platform(1): DS126401 (cont'd)

Step 1: Worst position search (cont'd)

Step 1-3: Front-left & touch (separation distance=0mm) / 11b(1Mbps), 2437MHz

EUT: Wireless module in Platform(1) ; Type: ZC-ST (Platform(1): DS126401); Serial: ES40197 (Platform(1): 559)

Communication System: IEEE 802.11b(1Mbps, DBPSK/DSSS); Frequency: 2437 MHz; Crest Factor: 1.0

Medium: M2450; Medium parameters used: $f = 2437$ MHz; $\sigma = 1.91$ S/m; $\epsilon_r = 51$; $\rho = 1000$ kg/m³

DASY4 Configuration: - Probe: EX3DV4 - SN3540; ConvF(7.64, 7.64, 7.64); Calibrated: 2011/07/21
- Sensor-Surface: 2mm (Mechanical Surface Detection) - Electronics: DAE4 Sn626; Calibrated: 2012/02/15
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1059; Phantom section: Flat Section
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 184

fcc4,front(2)&touch(d0mm),11b(1m,sef12d),m2437/

Area Scan:105x90,15 (8x7x1): Measurement grid: dx=15mm, dy=15mm;Maximum value of SAR (measured) = 0.252 mW/g

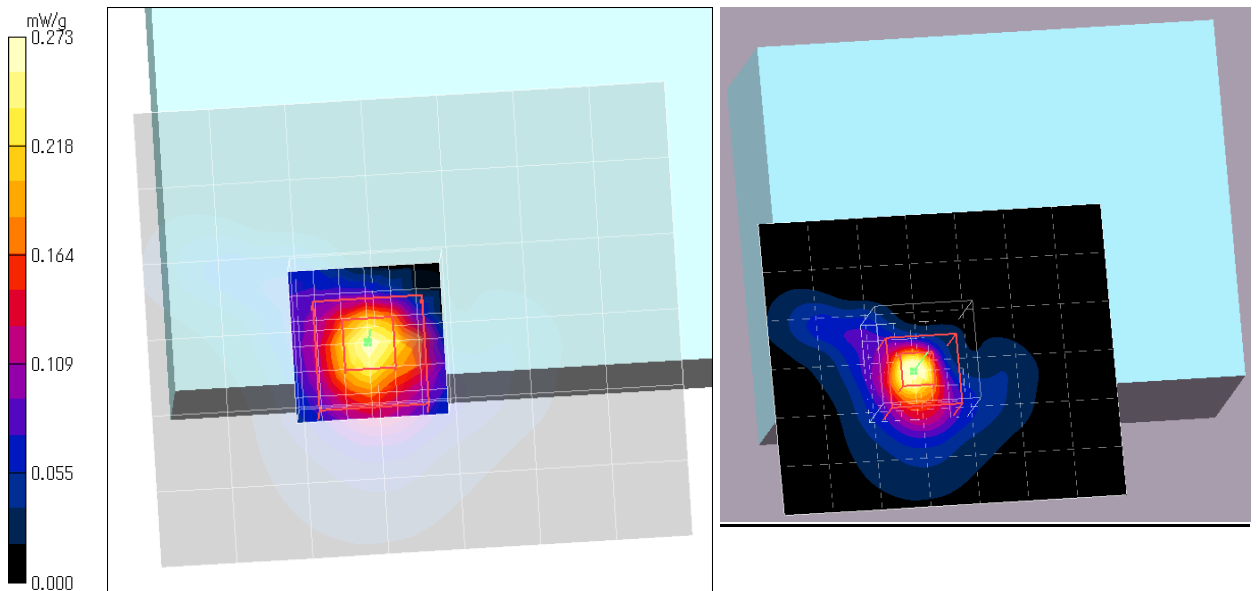
Area Scan:105x90,15 (71x61x1): Measurement grid: dx=15mm, dy=15mm;Maximum value of SAR (interpolated) = 0.304 mW/g

Zoom Scan:30x30x30,5 (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm;

Reference Value = 12.1 V/m; Power Drift = 0.063 dB, Maximum value of SAR (measured) = 0.273 mW/g

Peak SAR (extrapolated) = 0.373 W/kg

SAR(1 g)=0.172 mW/g; SAR(10 g) = 0.075 mW/g



Remarks: * Date tested: 2012/06/20; Tested by: Hiroshi Naka; Tested place: No.7 shielded room,
* liquid depth: 155mm; Position: distance of EUT to phantom: 0mm (2mm to liquid); ambient: 24.9deg.C. / 58 %RH,
* liquid temperature: 23.5(start)/23.5(end)/23.5(in check) deg.C.; * White cubic: zoom scan area, Red cubic: big=SAR(10g)/small=SAR(1g)

Appendix 2-2: Measurement data / Platform(1): DS126401 (cont'd)

Step 2: Change the channels

Step 2-1: 2412MHz / Top-left & touch (separation distance=0mm), 11b(1Mbps)

EUT: Wireless module in Platform(1) ; Type: ZC-ST (Platform(1): DS126401); Serial: ES40197 (Platform(1): 559)

Communication System: IEEE 802.11b(1Mbps, DBPSK/DSSS); Frequency: 2412 MHz; Crest Factor: 1.0

Medium: M2450; Medium parameters used: $f = 2412$ MHz; $\sigma = 1.88$ S/m; $\epsilon_r = 51$; $\rho = 1000$ kg/m³

DASY4 Configuration: - Probe: EX3DV4 - SN3540; ConvF(7.64, 7.64, 7.64); Calibrated: 2011/07/21
- Sensor-Surface: 2mm (Mechanical Surface Detection) - Electronics: DAE4 Sn626; Calibrated: 2012/02/15
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1059; Phantom section: Flat Section
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 184

fcc6,top(1)&touch(d0mm),11b(1m,set12d),m2412/

Area Scan:90x90,15 (7x7x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (measured) = 0.443 mW/g

Area Scan:90x90,15 (61x61x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (interpolated) = 0.538 mW/g

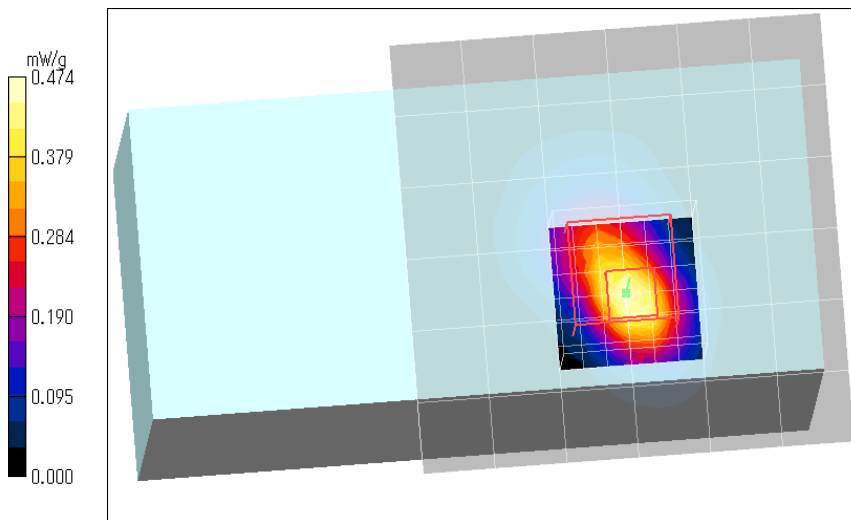
Z Scan:160,5 (1x1x33): Measurement grid: dx=20mm, dy=20mm, dz=5mm; Maximum value of SAR (measured) = 0.471 mW/g

Zoom Scan:30x30x30,5 (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm;

Reference Value = 16.5 V/m; Power Drift = -0.046 dB; Maximum value of SAR (measured) = 0.474 mW/g

Peak SAR (extrapolated) = 0.672 W/kg

SAR(1 g) = 0.302 mW/g; SAR(10 g) = 0.136 mW/g



Remarks: * . Date tested: 2012/06/20; Tested by: Hiroshi Naka; Tested place: No.7 shielded room,
* . liquid depth: 155mm; Position: distance of EUT to phantom: 0mm (2mm to liquid); ambient: 24.9deg.C. / 58 %RH,
* . liquid temperature: 23.5(start)/23.5(end)/23.5(in check) deg.C.; * White cubic: zoom scan area, Red cubic: big=SAR(10g)/small=SAR(1g)

Appendix 2-2: Measurement data / Platform(1): DS126401 (cont'd)

Step 2: Change the channels (cont'd)

Step 2-2: 2462MHz / Top-left & touch (separation distance=0mm), 11b(1Mbps)

EUT: Wireless module in Platform(1) ; Type: ZC-ST (Platform(1): DS126401); Serial: ES40197 (Platform(1): 559)

Communication System: IEEE 802.11b(1Mbps, DBPSK/DSSS); Frequency: 2462 MHz; Crest Factor: 1.0

Medium: M2450; Medium parameters used: $f = 2462$ MHz; $\sigma = 1.95$ S/m; $\epsilon_r = 50.8$; $\rho = 1000$ kg/m³

DASY4 Configuration: - Probe: EX3DV4 - SN3540; ConvF(7.64, 7.64, 7.64); Calibrated: 2011/07/21
- Sensor-Surface: 2mm (Mechanical Surface Detection) - Electronics: DAE4 Sn626; Calibrated: 2012/02/15
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1059; Phantom section: Flat Section
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 184

fcc7,top(1)&touch(d0mm),11b(1m,sef12d),m2462/

Area Scan:90x90,15 (7x7x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (measured) = 0.584 mW/g

Area Scan:90x90,15 (61x61x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (interpolated) = 0.646 mW/g

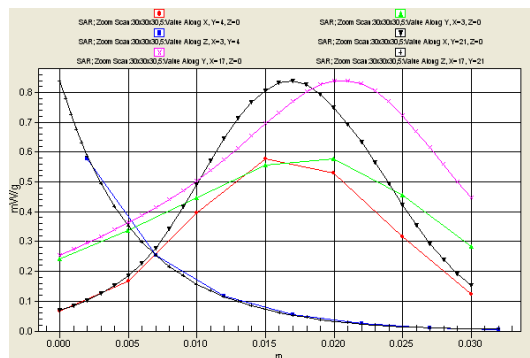
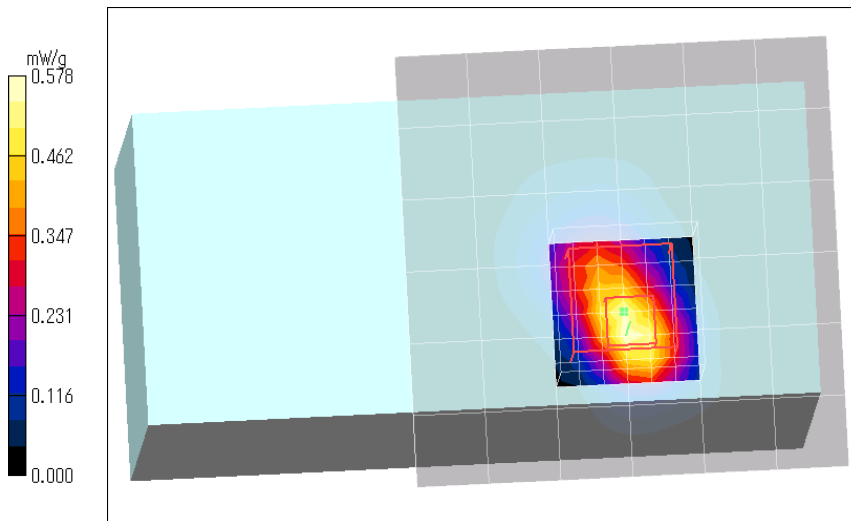
Z Scan:160,5 (1x1x33): Measurement grid: dx=20mm, dy=20mm, dz=5mm; Maximum value of SAR (measured) = 0.578 mW/g

Zoom Scan:30x30x30,5 (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm;

Reference Value = 17.3 V/m; Power Drift = -0.013 dB, Maximum value of SAR (measured) = 0.578 mW/g

Peak SAR (extrapolated) = 0.840 W/kg

SAR(1 g) = 0.371 mW/g; SAR(10 g) = 0.165 mW/g



Remarks: * . Date tested: 2012/06/20; Tested by: Hiroshi Naka; Tested place: No.7 shielded room,
* liquid depth: 155mm; Position: distance of EUT to phantom: 0mm (2mm to liquid); ambient: 24.9deg.C. / 58 %RH,
* liquid temperature: 23.5(start)/23.5(end)/23.5(in check) deg.C.; * White cubic: zoom scan area, Red cubic: big=SAR(10g)/small=SAR(1g)

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Appendix 2-2: Measurement data / Platform(1): DS126401 (cont'd)

Step 3: Change the operation mode, data rate

Step 3-1: 11n(40HT)(MCS0) / Top-left & touch (separation distance=0mm), 2437MHz

EUT: Wireless module in Platform(1) ; Type: ZC-ST (Platform(1): DS126401); Serial: ES40197 (Platform(1): 559)

Communication System: IEEE 802.11n(40HT)(MCS0, BPSK/OFDM); Frequency: 2437 MHz; Crest Factor: 1.0

Medium: M2450; Medium parameters used: $f = 2437$ MHz; $\sigma = 1.91$ S/m; $\epsilon_r = 51$; $\rho = 1000$ kg/m³

DASY4 Configuration: - Probe: EX3DV4 - SN3540; ConvF(7.64, 7.64, 7.64); Calibrated: 2011/07/21
- Sensor-Surface: 2mm (Mechanical Surface Detection) - Electronics: DAE4 Sn626; Calibrated: 2012/02/15
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1059; Phantom section: Flat Section
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 184

fcc8,top(1)&touch(d0mm),11n-40(mcs0,set12d),m2437/

Area Scan:90x90,15 (7x7x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (measured) = 0.489 mW/g

Area Scan:90x90,15 (61x61x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (interpolated) = 0.506 mW/g

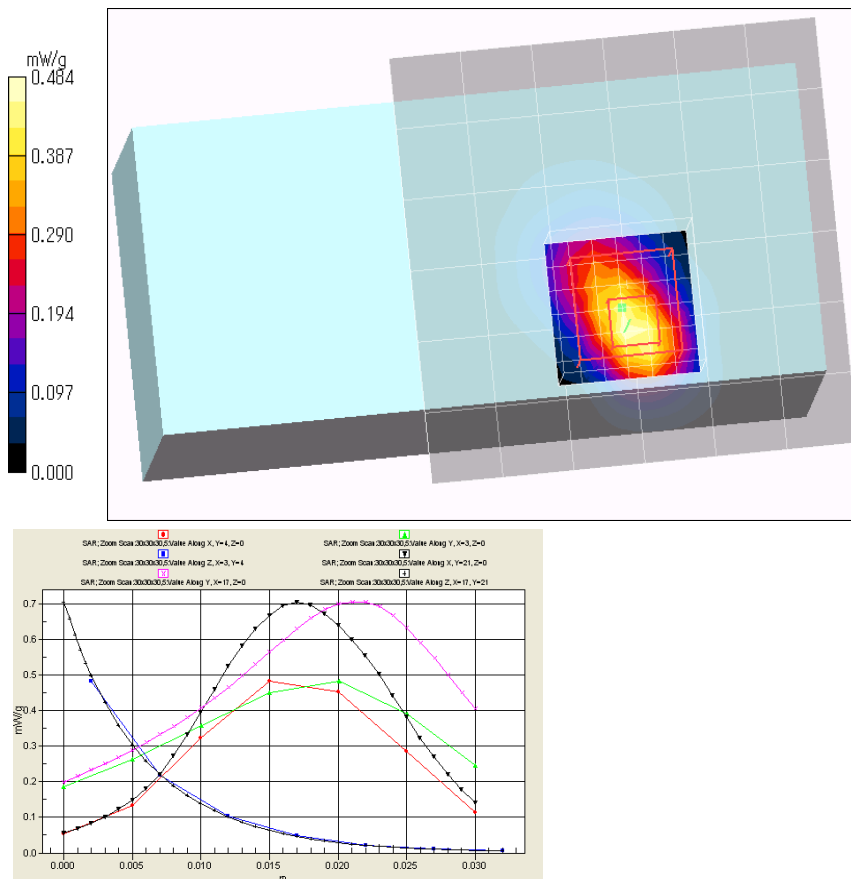
Z Scan:160,5 (1x1x33): Measurement grid: dx=20mm, dy=20mm, dz=5mm; Maximum value of SAR (measured) = 0.480 mW/g

Zoom Scan:30x30x30,5 (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm;

Reference Value = 16.0 V/m; Power Drift = 0.006 dB; Maximum value of SAR (measured) = 0.484 mW/g

Peak SAR (extrapolated) = 0.707 W/kg

SAR(1 g) = 0.311 mW/g; SAR(10 g) = 0.138 mW/g



Remarks: * Date tested: 2012/06/20; Tested by: Hiroshi Naka; Tested place: No.7 shielded room,
* liquid depth: 155mm; Position: distance of EUT to phantom: 0mm (2mm to liquid); ambient: 24.9deg.C. / 58 %RH,
* liquid temperature: 23.5(start)/23.5(end)/23.5(in check) deg.C.; * White cubic: zoom scan area, Red cubic: big=SAR(10g)/small=SAR(1g)

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Appendix 2-2: Measurement data / Platform(1): DS126401 (cont'd)

Step 3: Change the operation mode, data rate (cont'd)

Step 3-2: 11b(11Mbps) / Top-left & touch (separation distance=0mm), 2462MHz

EUT: Wireless module in Platform(1) ; Type: ZC-ST (Platform(1): DS126401); Serial: ES40197 (Platform(1): 559)

Communication System: IEEE 802.11b(11Mbps, CCK/DSSS); Frequency: 2462 MHz; Crest Factor: 1.0

Medium: M2450; Medium parameters used: $f = 2462$ MHz; $\sigma = 1.95$ S/m; $\epsilon_r = 50.8$; $\rho = 1000$ kg/m³

DASY4 Configuration: - Probe: EX3DV4 - SN3540; ConvF(7.64, 7.64, 7.64); Calibrated: 2011/07/21
- Sensor-Surface: 2mm (Mechanical Surface Detection) - Electronics: DAE4 Sn626; Calibrated: 2012/02/15
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1059; Phantom section: Flat Section
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 184

fcc9,top(1)&touch(d0mm),11b(11m,set12d),m2462/

Area Scan:90x90,15 (7x7x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (measured) = 0.533 mW/g

Area Scan:90x90,15 (61x61x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (interpolated) = 0.661 mW/g

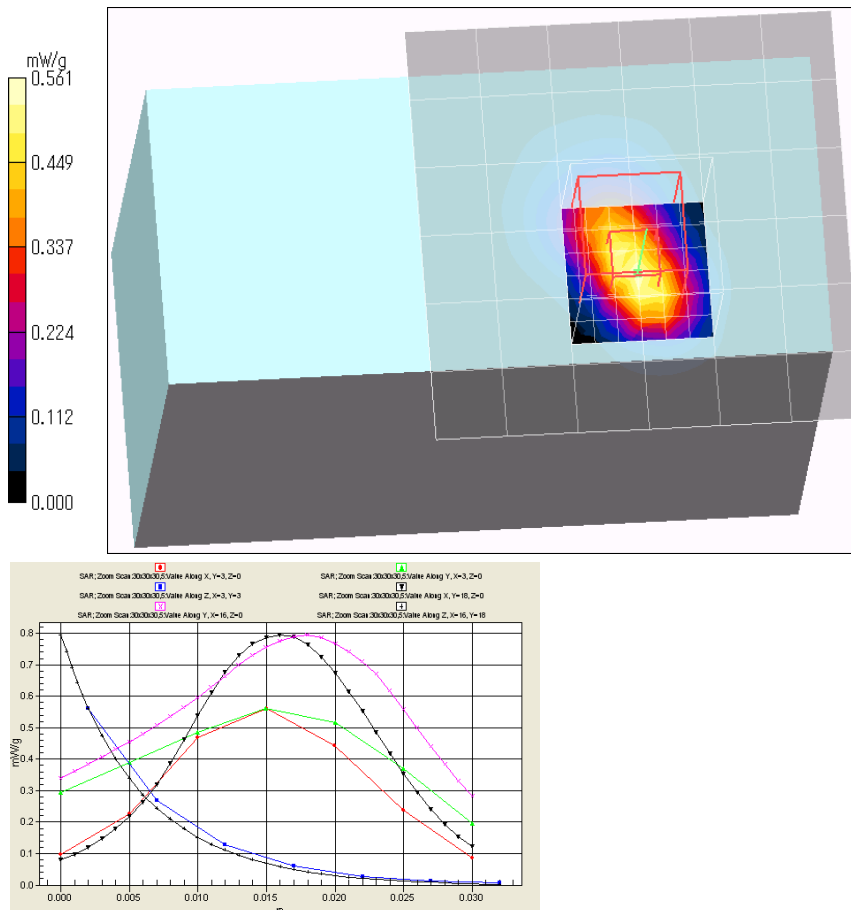
Z Scan:160,5 (1x1x33): Measurement grid: dx=20mm, dy=20mm, dz=5mm; Maximum value of SAR (measured) = 0.561 mW/g

Zoom Scan:30x30x30,5 (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm;

Reference Value = 17.0 V/m; Power Drift = -0.016 dB, Maximum value of SAR (measured) = 0.561 mW/g

Peak SAR (extrapolated) = 0.796 W/kg

SAR(1 g) = 0.359 mW/g; SAR(10 g) = 0.164 mW/g



Remarks: * . Date tested: 2012/06/20; Tested by: Hiroshi Naka; Tested place: No.7 shielded room,
* liquid depth: 155mm; Position: distance of EUT to phantom: 0mm (2mm to liquid); ambient: 24.9deg.C. / 58 %RH,
* liquid temperature: 23.6(start)/23.6(end)/23.5(in check) deg.C.; * . White cubic: zoom scan area, Red cubic: big=SAR(10g)/small=SAR(1g)

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Appendix 2-2: Measurement data / Platform(1): DS126401 (cont'd)

Step 3: Change the operation mode, data rate (cont'd)

Step 3-3: 11g(6Mbps) / Top-left & touch (separation distance=0mm), 2462MHz

EUT: Wireless module in Platform(1) ; Type: ZC-ST (Platform(1): DS126401); Serial: ES40197 (Platform(1): 559)

Communication System: IEEE 802.11g(6Mbps, BPSK/OFDM); Frequency: 2462 MHz; Crest Factor: 1.0

Medium: M2450; Medium parameters used: $f = 2462$ MHz; $\sigma = 1.95$ S/m; $\epsilon_r = 50.8$; $\rho = 1000$ kg/m³

DASY4 Configuration: - Probe: EX3DV4 - SN3540; ConvF(7.64, 7.64, 7.64); Calibrated: 2011/07/21
- Sensor-Surface: 2mm (Mechanical Surface Detection) - Electronics: DAE4 Sn626; Calibrated: 2012/02/15
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1059; Phantom section: Flat Section
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 184

fcc10,top(1)&touch(d0mm),11g(6m,set12d),m2462/

Area Scan:90x90,15 (7x7x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (measured) = 0.516 mW/g

Area Scan:90x90,15 (61x61x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (interpolated) = 0.547 mW/g

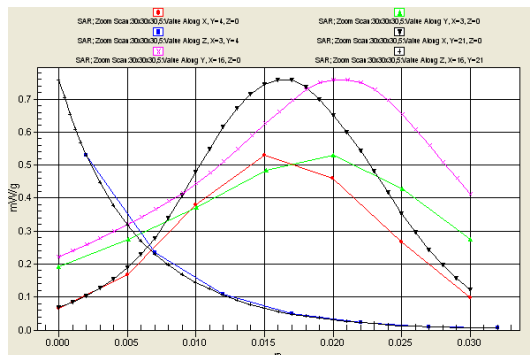
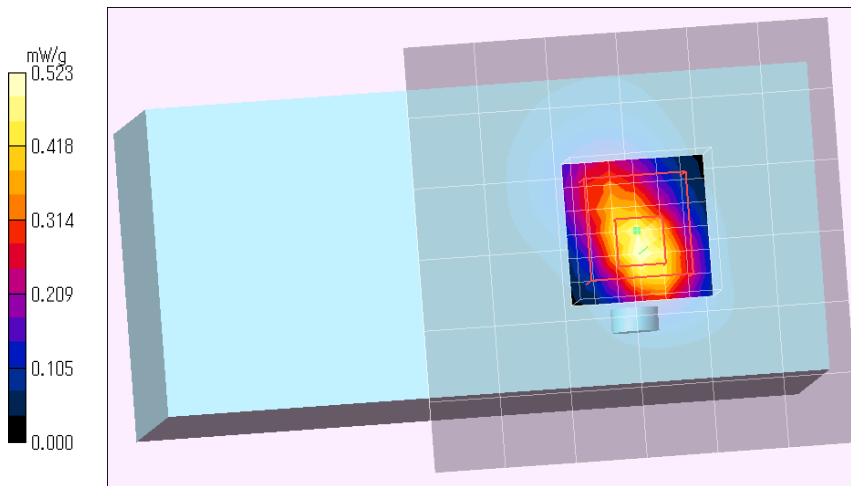
Z Scan:160,5 (1x1x33): Measurement grid: dx=20mm, dy=20mm, dz=5mm; Maximum value of SAR (measured) = 0.523 mW/g

Zoom Scan:30x30x30,5 (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm;

Reference Value = 9.42 V/m; Power Drift = -0.030 dB, Maximum value of SAR (measured) = 0.529 mW/g

Peak SAR (extrapolated) = 0.759 W/kg

SAR(1 g) = 0.332 mW/g; SAR(10 g) = 0.146 mW/g



Remarks: *. Date tested: 2012/06/20; Tested by: Hiroshi Naka; Tested place: No.7 shielded room,
*. liquid depth: 155mm; Position: distance of EUT to phantom: 0mm (2mm to liquid); ambient: 24.9deg.C. / 58 %RH,
*. liquid temperature: 23.6(start)/23.6(end)/23.5(in check) deg.C.; *. White cubic: zoom scan area, Red cubic: big=SAR(10g)/small=SAR(1g)

Appendix 2-2: Measurement data / Platform(1): DS126401 (cont'd)

Step 4: Additional position search and change the channels

Step 4-1: Top-left-front & touch (separation distance=0mm) / 11b(11Mbps), 2437MHz

EUT: Wireless module in Platform(1) ; Type: ZC-ST (Platform(1): DS126401); Serial: ES40197 (Platform(1): 559)

Communication System: IEEE 802.11b(1Mbps, DBPSK/DSSS); Frequency: 2437 MHz; Crest Factor: 1.0

Medium: M2450; Medium parameters used: $f = 2437$ MHz; $\sigma = 1.91$ S/m; $\epsilon_r = 51$; $\rho = 1000$ kg/m³

DASY4 Configuration: - Probe: EX3DV4 - SN3540; ConvF(7.64, 7.64, 7.64); Calibrated: 2011/07/21
- Sensor-Surface: 2mm (Mechanical Surface Detection) - Electronics: DAE4 Sn626; Calibrated: 2012/02/15
- Phantom: ELI4.0; Type: QDOVA001BA; Serial: 1059; Phantom section: Flat Section
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 184

fcc11(re#3),side(1)&touch(d0mm),11b(1m,set12d),m2437/

Area Scan:90x105,15 (7x8x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (measured) = 0.397 mW/g

Area Scan:90x105,15 (61x71x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (interpolated) = 0.663 mW/g

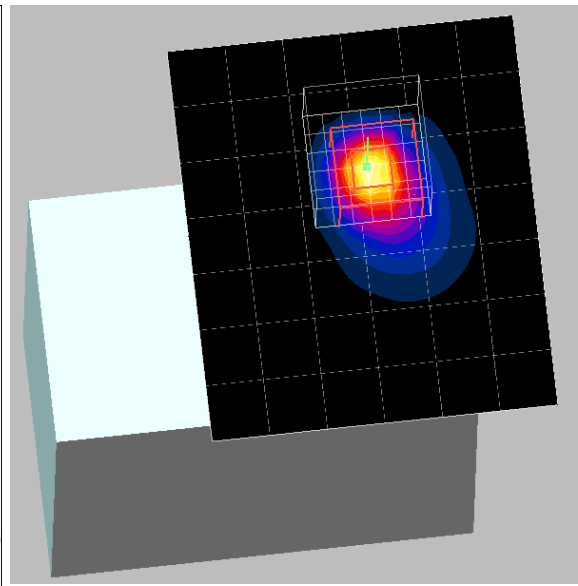
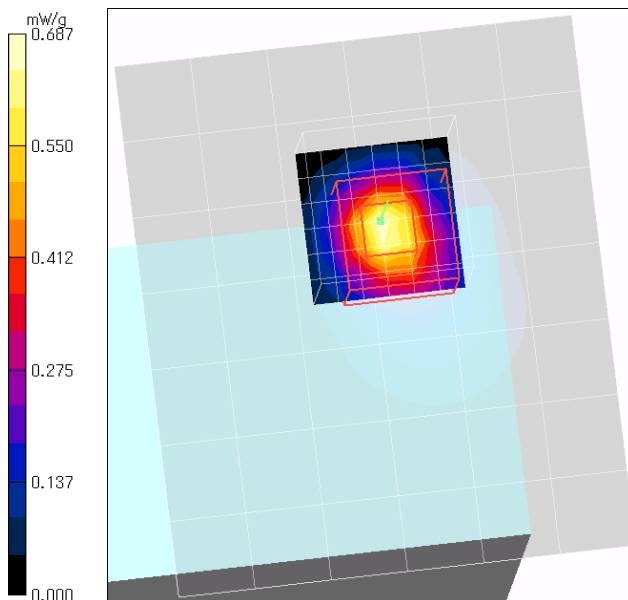
Z Scan:160,5 (1x1x33): Measurement grid: dx=20mm, dy=20mm, dz=5mm; Maximum value of SAR (measured) = 0.680 mW/g

Zoom Scan:30x30x30,5 (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm;

Reference Value = 15.1 V/m; Power Drift = 0.001 dB; Maximum value of SAR (measured) = 0.687 mW/g

Peak SAR (extrapolated) = 1.02 W/kg

SAR(1 g) = 0.425 mW/g; SAR(10 g) = 0.172 mW/g



Remarks: * Date tested: 2012/06/20; Tested by: Hiroshi Naka; Tested place: No.7 shielded room,
* liquid depth: 155mm; Position: distance of EUT to phantom: 0mm (2mm to liquid); ambient: 24.9deg.C. / 58 %RH,
* liquid temperature: 23.6(start)/23.6(end)/23.5(in check) deg.C.; * White cubic: zoom scan area, Red cubic: big=SAR(10g)/small=SAR(1g)

Appendix 2-2: Measurement data / Platform(1): DS126401 (cont'd)

Step 4: Additional position search and change the channels (cont'd)

Step 4-2: 2412MHz / Top-left-front & touch (separation distance=0mm), 11b(11Mbps)

EUT: Wireless module in Platform(1) ; Type: ZC-ST (Platform(1): DS126401); Serial: ES40197 (Platform(1): 559)

Communication System: IEEE 802.11b(1Mbps, DBPSK/DSSS); Frequency: 2412 MHz; Crest Factor: 1.0

Medium: M2450; Medium parameters used: $f = 2412$ MHz; $\sigma = 1.88$ S/m; $\epsilon_r = 51$; $\rho = 1000$ kg/m³

DASY4 Configuration: - Probe: EX3DV4 - SN3540; ConvF(7.64, 7.64, 7.64); Calibrated: 2011/07/21
- Sensor-Surface: 2mm (Mechanical Surface Detection) - Electronics: DAE4 Sn626; Calibrated: 2012/02/15
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1059; Phantom section: Flat Section
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 184

fcc12,side(1)&touch(d0mm),11b(1m,sef12d),m2412/

Area Scan:90x105,15 (7x8x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (measured) = 0.485 mW/g

Area Scan:90x105,15 (61x71x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (interpolated) = 0.592 mW/g

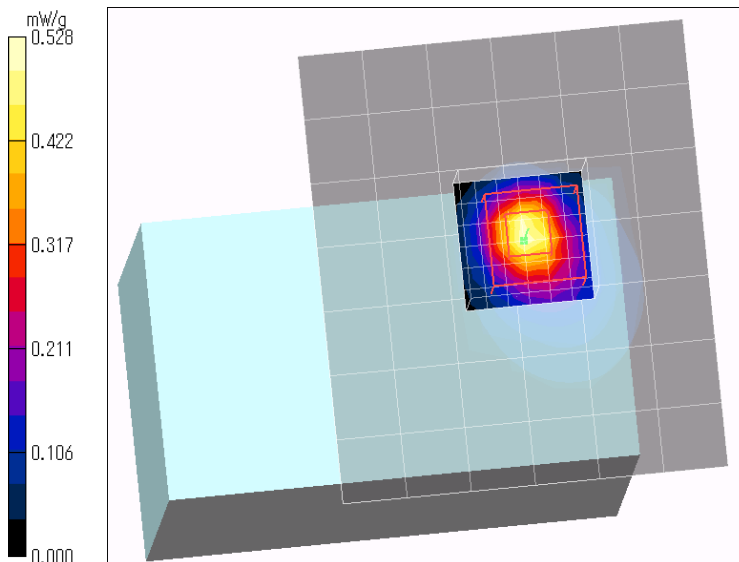
Z Scan:160,5 (1x1x33): Measurement grid: dx=20mm, dy=20mm, dz=5mm; Maximum value of SAR (measured) = 0.527 mW/g

Zoom Scan:30x30x30,5 (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm;

Reference Value = 16.7 V/m; Power Drift = -0.027 dB, Maximum value of SAR (measured) = 0.528 mW/g

Peak SAR (extrapolated) = 0.786 W/kg

SAR(1 g) = 0.332 mW/g; SAR(10 g) = 0.134 mW/g



Remarks: * Date tested: 2012/06/20; Tested by: Hiroshi Naka; Tested place: No.7 shielded room,
* liquid depth: 155mm; Position: distance of EUT to phantom: 0mm (2mm to liquid); ambient: 24.9deg.C. / 58 %RH,
* liquid temperature: 23.6(start)/23.6(end)/23.5(in check) deg.C.; * White cubic: zoom scan area, Red cubic: big=SAR(10g)/small=SAR(1g)

Appendix 2-2: Measurement data / Platform(1): DS126401 (cont'd)

Step 4: Additional position search and change the channels (cont'd)

Step 4-3: 2462MHz / Top-left-front & touch (separation distance=0mm), 11b(11Mbps)

-> Worst SAR(1g) of EUT at platform(1)

EUT: Wireless module in Platform(1) ; Type: ZC-ST (Platform(1): DS126401); Serial: ES40197 (Platform(1): 559)

Communication System: IEEE 802.11b(1Mbps, DBPSK/DSSS); Frequency: 2462 MHz; Crest Factor: 1.0

Medium: M2450; Medium parameters used: $f = 2462$ MHz; $\sigma = 1.95$ S/m; $\epsilon_r = 50.8$; $\rho = 1000$ kg/m³

DASY4 Configuration: - Probe: EX3DV4 - SN3540; ConvF(7.64, 7.64, 7.64); Calibrated: 2011/07/21
- Sensor-Surface: 2mm (Mechanical Surface Detection) - Electronics: DAE4 Sn626; Calibrated: 2012/02/15
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1059; Phantom section: Flat Section
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 184

fcc13,side(1)&touch(d0mm),11b(1m,sef12d),m2462/

Area Scan:90x105,15 (7x8x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (measured) = 0.502 mW/g

Area Scan:90x105,15 (61x71x1): Measurement grid: dx=15mm, dy=15mm; Maximum value of SAR (interpolated) = 0.663 mW/g

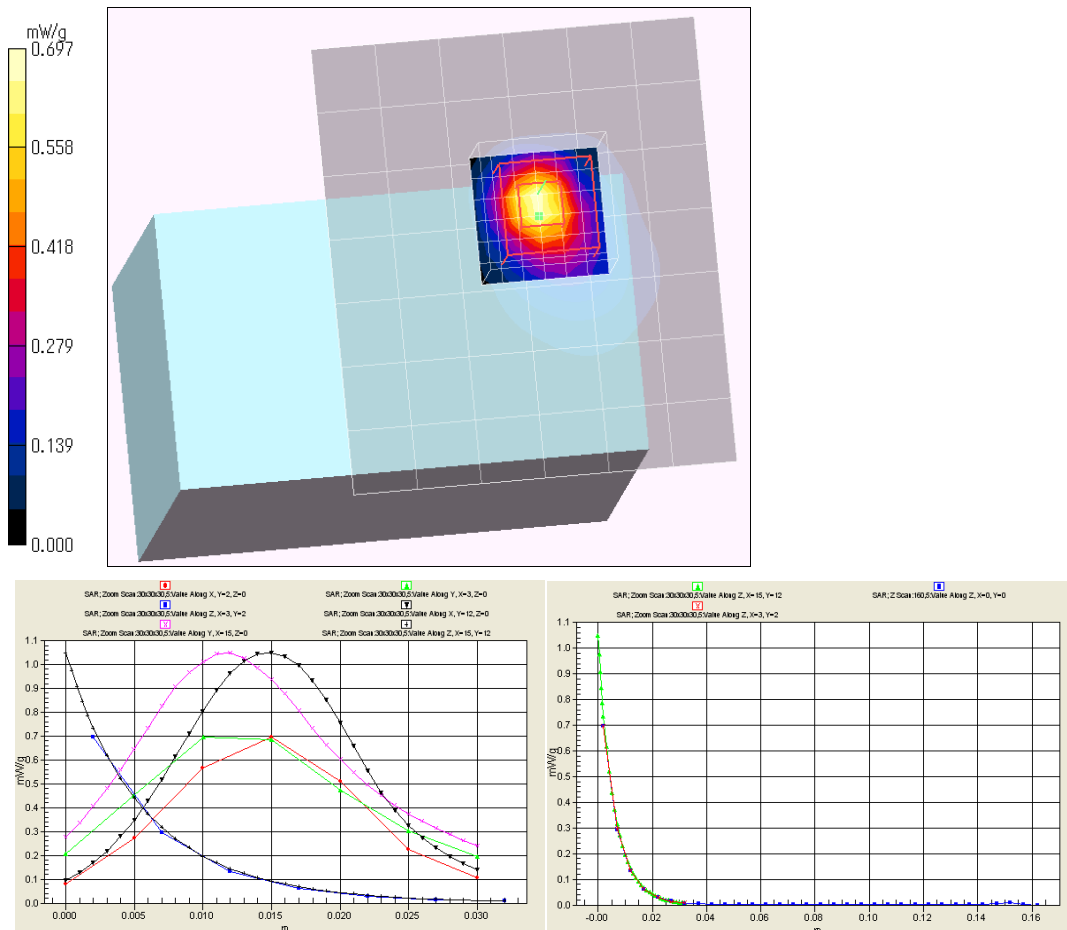
Z Scan:160,5 (1x1x33): Measurement grid: dx=20mm, dy=20mm, dz=5mm; Maximum value of SAR (measured) = 0.697 mW/g

Zoom Scan:30x30x30,5 (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm;

Reference Value = 16.3 V/m; Power Drift = -0.012 dB, Maximum value of SAR (measured) = 0.697 mW/g

Peak SAR (extrapolated) = 1.05 W/kg

SAR(1 g) = 0.437 mW/g; SAR(10 g) = 0.176 mW/g



Remarks: * Date tested: 2012/06/20; Tested by: Hiroshi Naka; Tested place: No.7 shielded room,
* liquid depth: 155mm; Position: distance of EUT to phantom: 0mm (2mm to liquid); ambient: 24.9deg.C. / 58 %RH,
* liquid temperature: 23.6(start)/23.6(end)/23.5(in check) deg.C.; * White cubic: zoom scan area, Red cubic: big=SAR(10g)/small=SAR(1g)

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APPENDIX 3: Test instruments

Appendix 3-1: Equipment used

Control No.	Instrument	Manufacturer	Model No	Serial No	Test Item	Calibration Date * Interval(month)
COTS-KSAR-01	DASY4	Schmid&Partner Engineering AG	DASY4 V4.7 B80	-	SAR	-
COTS-KSEP-01	Dielectric measurement	Agilent	85070	1	SAR	-
KSAR-01	SAR measurement system	Schmid&Partner Engineering AG	DASY4	1088	SAR	Pre Check
SSRBT-01	SAR robot	Schmid&Partner Engineering AG	RX60B L	F04/5Z71A1/A /01	SAR	2012/02/06 * 12
KDAE-01	Data Acquisition Electronics	Schmid&Partner Engineering AG	DAE4	626	SAR	2012/02/15 * 12
KPB-R02	Dosimetric E-Field Probe	Schmid&Partner Engineering AG	EX3DV4	3540	SAR	2011/07/21 * 12
KSDA-01	Dipole Antenna	Schmid&Partner Engineering AG	D2450V2	822	SAR	2012/01/10 * 12
KPFL-01	Flat Phantom	Schmid&Partner Engineering AG	Oval flat phantom ELI 4.0	1059	SAR	2011/10/26 * 12
SSNA-01	Network Analyzer	Agilent	8753ES	US39171777	SAR	2011/12/15 * 12
KEPP-01	Dielectric probe	Agilent	85070E/8710-2036	2540	SAR	2012/02/20 * 12
KSG-08	Signal Generator	Rohde & Schwarz	SMT06	100763	SAR(daily)	2011/06/07 * 12
KPA-12	RF Power Amplifier	MILMEGA	AS2560-50	1018582	SAR(daily)	Pre Check
KCPL-07	Directional Coupler	Pulsar Microwave Corp.	CCS30-B26	0621	SAR(daily)	Pre Check
KPM-06	Power Meter	Rohde & Schwarz	NRVD	101599	SAR(daily)	2011/09/13 * 12
KIU-08	Power sensor	Rohde & Schwarz	NRV-Z4	100372	SAR(daily)	2011/09/13 * 12
KIU-09	Power sensor	Rohde & Schwarz	NRV-Z4	100371	SAR(daily)	2011/09/13 * 12
KPM-05	Power meter	Agilent	E4417A	GB41290718	SAR(daily)	2012/03/22 * 12
KPSS-01	Power sensor	Agilent	E9327A	US40440544	SAR(daily)	2012/03/22 * 12
KAT10-P1	Attenuator	Weinschel	24-10-34	BY5927	SAR(daily)	2012/02/15 * 12
KAT10-CS1	Attenuator	HUBER+SUHNER	6810.17.A	768898-1	SAR(daily)	2012/01/10 * 12
KAT10-CS2	Attenuator	HUBER+SUHNER	6810.17.A	768898-2	SAR(daily)	2012/01/10 * 12
KRU-01	Ruler(300mm)	Shinwa	13134	-	SAR	2012/03/08 * 12
KRU-02	Ruler(150mm,L)	Shinwa	12103	-	SAR	2012/03/08 * 12
KRU-04	Ruler(300mm)	Shinwa	13134	-	SAR	2012/05/29 * 12
KRU-05	Ruler(100x50mm,L)	Shinwa	12101	-	SAR	2012/05/29 * 12
KOS-13	Digital thermometer	HANNA	Checktemp-2	KOS-13	SAR	2012/01/06 * 12
KOS-14	Thermo-Hygrometer data logger	SATO KEIRYOKI	SK-L200THII α / SK-LTHII α -2	015246/08169	SAR	2012/01/06 * 12
SOS-11	Humidity Indicator	A&D	AD-5681	4063424	SAR	2012/02/06 * 12
KPM-08	Power meter	Anritsu	ML2495A	6K00003356	Ant.pwr.	2011/09/12 * 12
KPSS-04	Power sensor	Anritsu	MA2411B	012088	Ant.pwr.	2011/09/12 * 12
KAT10-S3	Attenuator	Agilent	8490D 010	50924	Ant.pwr.	2012/02/15 * 12
KCC-D23	Microwave cable	Hirose Electric	U.FL-2LP-066J1-A-(200)	-	Ant.pwr.	Pre Check
SSA-04	Spectrum Analyzer	Advantest	R3272	101100994	SAR(mon.)	2011/12/28 * 12
SWTR-03	DI water	MonotaRo	34557433	-	SAR	Pre Check
KSLM245-01	Tissue simulation liquid (2450MHz,body)	Schmid&Partner Engineering AG	SL AAM 245	-	SAR	(Daily check) Target value ±5%
No.7 Shielded room	SAR shielded room (2.76m(W)x3.76m(D)x2.4m(H))	TDK	-	-	SAR	(Daily check) Ambient noise: < 12mW/kg

The expiration date of calibration is the end of the expired month.

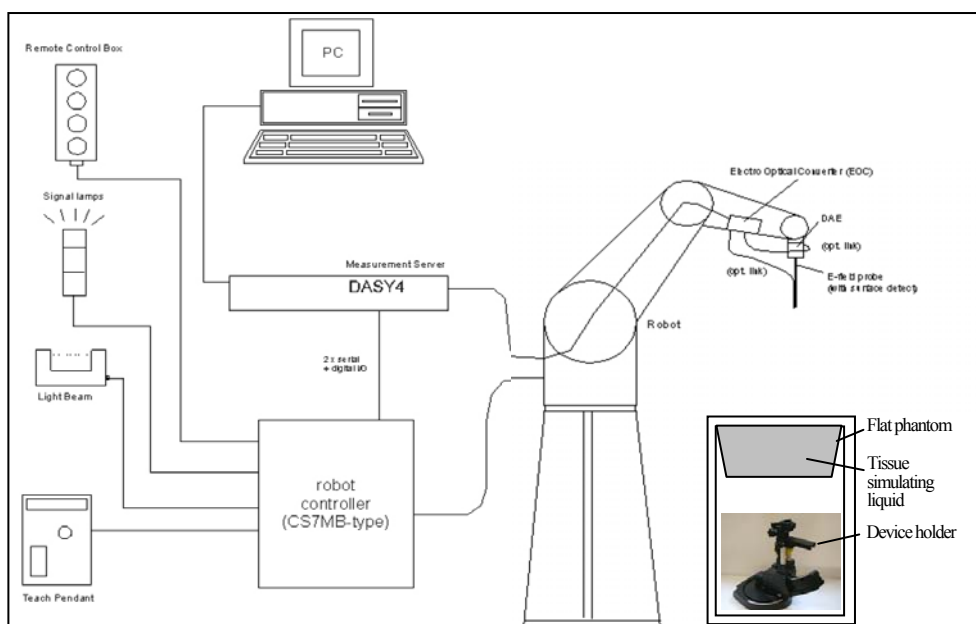
As for some calibrations performed after the tested dates, those test equipment have been controlled by means of an unbroken chains of calibrations. All equipment is calibrated with valid calibrations. Each measurement data is traceable to the national or international standards.

[Test Item] SAR: Specific Absorption Rate, Ant.pwr: Antenna terminal conducted power

Appendix 3-2: Dosimetry assessment setup

These measurements were performed with the automated near-field scanning system DASY4 from Schmid & Partner Engineering AG (SPEAG). The system is based on a high precision robot (working range greater than 0.9 m), which positions the probes with a positional repeatability of better than ± 0.02 mm. Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines to the data acquisition unit. The SAR measurements were conducted with the dosimetry probes EX3DV4 (manufactured by SPEAG), designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe has been calibrated according to the procedure described in [2] with accuracy of better than $\pm 10\%$. The spherical isotropy was evaluated with the procedure described in [3] and found to be better than ± 0.25 dB.

Appendix 3-3: Configuration and peripherals



The DASY4 system for performing compliance tests consist of the following items:

1	A standard high precision 6-axis robot (Stäubli RX family) with controller and software. An arm extension for accommodating the data acquisition electronics (DAE).
2	A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
3	A data acquisition electronic (DAE), which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
4	The Electro-optical converter (EOC) performs the conversion between optical and electrical of the signals for the digital communication to the DAE and for the analog signal from the optical surface detection. The EOC is connected to the measurement server.
5	The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
6	A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
7	A computer operating Windows XP.
8	DASY4 software.
9	Remote control with teaches pendant and additional circuitry for robot safety such as warning lamps, etc.
10	The phantom.
11	The device holder for EUT. (low-loss dielectric palette) (*. when it was used.)
12	Tissue simulating liquid mixed according to the given recipes.
13	Validation dipole kits allowing to validate the proper functioning of the system.

Appendix 3-4: System components

1) EX3DV4 Probe Specification

Construction:

- Symmetrical design with triangular core.
- Built-in shielding against static charges.
- PEEK enclosure material (resistant to organic solvents, e.g., DGBE).

Calibration (S/N 3540):

Basic broad band calibration in air.

Conversion Factors(Head and Body): 2450, 2600, 3600, 5200, 5300, 5500, 5600, 5800MHz

Frequency:

10 MHz to > 6GHz, Linearity: ± 0.2 dB (30MHz to 6GHz)

Directivity:

± 0.3 dB in HSL (rotation around probe axis)

± 0.5 dB in tissue material (rotation normal to probe axis)

Dynamic Range:

$10\mu\text{W/g}$ to $> 100\text{ mW/g}$; Linearity: ± 0.2 dB (noise: typically $< 1\mu\text{W/g}$)

Dimensions:

Overall length: 330mm (Tip: 20mm)

Tip diameter: 2.5mm (Body: 12mm)

Typical distance from probe tip to dipole centers: 1mm

Application:

High precision dosimetric measurement in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 6GHz with precision of better 30%.



EX3DV4 E-field Probe



2) Phantom (Flat type)

Construction:

A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom position and measurement grids by manually teaching three points with the robot.

Shell Thickness:

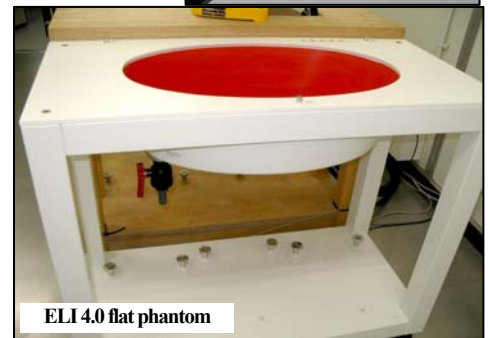
Bottom plate: $2 \pm 0.2\text{mm}$

Dimensions:

Bottom elliptical: 600×400mm, Depth: 190mm

Filling Volume:

Approx. 30 liters



ELI 4.0 flat phantom

3) Device Holder

For this measurement, the urethane foam was used as device holder.

In combination with the Twin SAM Phantom V4.0/V4.0c or ELI4, the Mounting Device enables the rotation of the mounted transmitter device in spherical coordinates. Transmitter devices can be easily and accurately positioned.

The low-loss dielectric urethane foam was used for the mounting section of device holder.

Device holder



Appendix 3-5: Test system specification

RX60L Robot

•Number of Axes	: 6	•Payload	: 1.6 kg
•Reach	: 800mm	•Repeatability	: ± 0.025 mm
•Control Unit	: CS7M	•Programming Language	: V+
•Manufacture	: Stäubli Unimation Corp. Robot Model: RX60		

DASY4 Measurement server

•Features	: 166MHz low power Pentium MMX. 32MB chipdisk and 64MB RAM Serial link to DAE (with watchdog supervision) 16 Bit A/D converter for surface detection system. Two serial links to robot (one for real-time communication which is supervised by watchdog) Ethernet link to PC (with watchdog supervision). Emergency stop relay for robot safety chain. Two expansion slots for future applications.		
•Manufacture	: Schmid & Partner Engineering AG		

Data Acquisition Electronic (DAE)

•Features	: Signal amplifier, multiplexer, A/D converter and control logic. Serial optical link for communication with DASY4 embedded system (fully remote controlled). 2 step probe touch detector for mechanical surface detection and emergency robot stop (not in -R version)		
•Measurement Range	: 1 μ V to > 200mV (16bit resolution and two range settings: 4mV, 400mV)		
•Input Offset voltage	: < 1 μ V (with auto zero)		
•Input Resistance	: 200M Ω	•Battery Power	: > 10hr of operation (with two 9V battery)
•Dimension	: 60×60×68mm	•Manufacture	: Schmid & Partner Engineering AG

Software

•Item	: Dosimetric Assessment System DASY4		
•Software version No.	: DASY4, V4.7 B80	•Manufacture / Origin	: Schmid & Partner Engineering AG

E-Field Probe

•Model	: EX3DV4 (sn: 3540)	•Construction	: Symmetrical design with triangular core
•Frequency	: 10MHz to 6GHz	•Linearity	: ± 0.2 dB (30MHz to 3GHz)
•Manufacture	: Schmid & Partner Engineering AG		

Phantom

•Type	: ELI 4.0 oval flat phantom	•Shell Material	: Fiberglass
•Shell Thickness	: Bottom plate: 2 $\pm$ 0.2mm	•Dimensions	: Bottom elliptical: 600×400mm, Depth: 190mm
•Manufacture	: Schmid & Partner Engineering AG		

Appendix 3-6: Simulated tissue composition

Liquid type	☐ / Head, HSL 2450	☒ / Body, MSL 2450
M/N / Control No.	SL AAH 245 / KSLH245-01	SL AAM 245 / KSLM245-01
Ingredient	Mixture (%)	Mixture (%)
Water	52-75 %	52-75 %
C ₈ H ₁₈ O ₃ (DGBE) (Diethylene glycol monobutyl ether)	25-48%	25-48%
NaCl	<1.0%	<1.0%
Manufacture	Schmid&Partner Engineering AG	Schmid&Partner Engineering AG

Appendix 3-7: Simulated tissue parameter confirmation

The dielectric parameters were checked prior to assessment using the 85070E dielectric probe kit. The dielectric parameters measurement is reported in each correspondent section.

Dielectric parameter measurement results											
Date	Freq. [MHz]	Ambient		Liq.T. [deg.C.]		Liquid Depth [mm]	Parameters	Target value		Measured	Deviation for #1 (Std.) [%]
		Temp [deg.C.]	Humidity [%RH]	Before	After			#1:Std. (*1)	#2:Cal. (*2)		Limit [%]
June 20, 2012	2450	23.6	65	23.5	23.5	155	Relative permittivity: ϵ_r [-]	52.7	50.6	50.73	-3.7
							Conductivity: σ [S/m]	1.95	2.01	1.939	-0.6
											±5
											±5
											±5

*1. The target value is a parameter defined in OET65, Supplement C.

*2. The target value is a parameter defined in the calibration data sheet of D2450V2 (sn:822) dipole calibrated by Schmid & Partner Engineering AG (Certification No. D2450V2-822_Jan12, the data sheet was filed in this report.).

*. Decision on Simulated Tissues of 2450MHz

In the current standards (e.g., IEEE 1528, OET 65 Supplement C), the dielectric parameters suggested for head and body tissue simulating liquid are given at 2000MHz, 2450 and 3000MHz. As an intermediate solution, dielectric parameters for the frequencies between 2000 to 2450 MHz and 2450-3000MHz were obtained using linear interpolation. Therefore the dielectric parameters of Wi-Fi frequency of 2.4GHz band which were SAR tested were decided as following.

Standard					Interpolated				
f (MHz)	Head Tissue		Body Tissue		f (MHz)	Head Tissue		Body Tissue	
	ϵ_r	σ [S/m]	ϵ_r	σ [S/m]		ϵ_r	σ [S/m]	ϵ_r	σ [S/m]
(1800-)2000	40.0	1.40	53.3	1.52	2412	39.26	1.771	52.75	1.914
2450	39.2	1.80	52.7	1.95	2437	39.21	1.793	52.72	1.938
3000	38.5	2.40	52.0	2.73	2462	39.18	1.819	52.68	1.967

Appendix 3-8: System check data

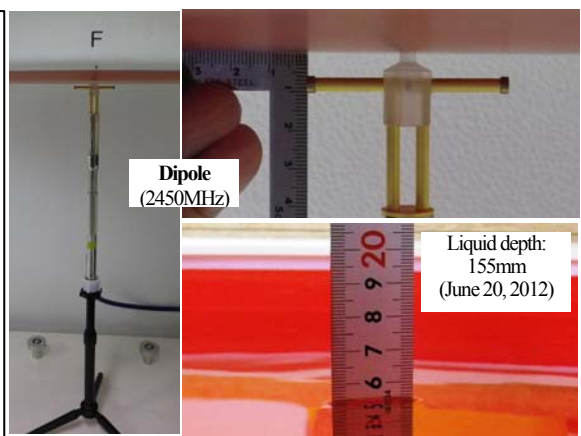
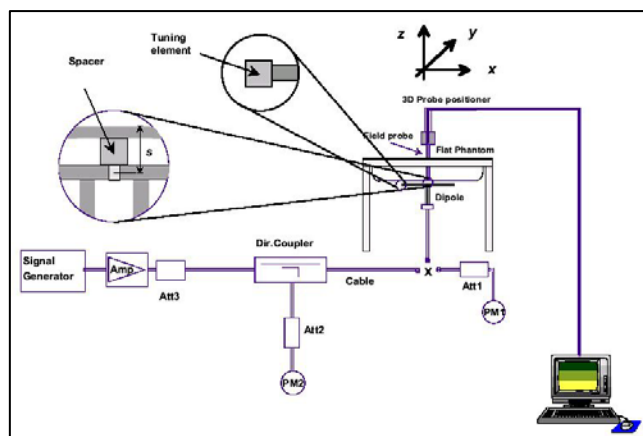
Prior to the SAR assessment of EUT, the system validation kit was used to test whether the system was operating within its specifications of $\pm 10\%$. The system check results are in the table below.

System check results															
Date	Freq. [MHz]	Liquid Type	Ambient		Liquid Temp. [deg.C.]			Liquid Depth [mm]	Permittivity measured ϵ_r [-]	Conductivity measured σ [S/m]	Power drift [dB]	System check target & measured			
			Temp [deg.C.]	Humidity [%RH]	Check	Before	After					SAR Ig [W/kg] (at 250mW)		Deviation [%]	Limit [%]
												Target value	Measured		
June 20, 2012	2450	Body	24.0	65	23.5	23.3	23.3	155	50.7	1.94	0.086	13.2 (*3)	12.2	-7.6	±10

Note: Refer to Appendix 3-9 System Check measurement data for the above result representation in plot data.

*3. The target value is a parameter defined in the calibration data sheet of D2450V2 (sn:822) dipole calibrated by Schmid & Partner Engineering AG (Certification No. D2450V2-822_Jan12, the data sheet was filed in this report.).

*. We performed the system check based on FCC requirement, "The 1-g or 10-g SAR values measured using the required tissue dielectric parameters should be within 10% of manufacturer calibrated dipole SAR values. However these manufacturer calibrated dipole target SAR values should be substantially similar to those defined in IEEE Standard 1528." and FCC permits "SAR system verification with the actual liquid used for EUT's SAR measurement, should be the default operating procedures." We confirmed the this dipole manufacture's validation data for head is within 5% against IEEE Standard 1528 (manufacture's cal.: 52.1W/kg (-0.6%, vs. standard=52.4W/kg). so we can only use Body liquid validation data for our system check procedure



Test setup for the system performance check

Appendix 3-9: System check measurement data

2450MHz system check (Body) / Forward conducted power: 250mW

EUT: Dipole 2450 MHz; Type: D2450V2; Serial: 822

Communication System: CW; Frequency: 2450 MHz; Crest Factor: 1.0

Medium: M2450; Medium parameters used: $f = 2450$ MHz; $\sigma = 1.94$ S/m; $\epsilon_r = 50.7$; $\rho = 1000$ kg/m³

DASY4 Configuration: - Probe: EX3DV4 - SN3540; ConvF(7.64, 7.64, 7.64); Calibrated: 2011/07/21
- Sensor-Surface: 2mm (Mechanical Surface Detection) - Electronics: DAE4 Sn626; Calibrated: 2012/02/15
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1059; Phantom section: Flat Section
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 184

Area Scan:60x60,15 (5x5x1): Measurement grid: dx=15mm, dy=15mm;Maximum value of SAR (measured) = 18.0 mW/g

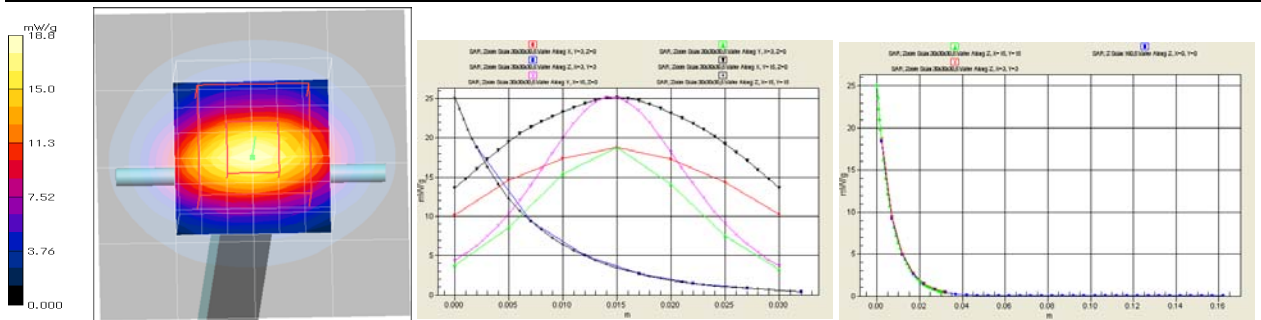
Area Scan:60x60,15 (41x41x1): Measurement grid: dx=15mm, dy=15mm;Maximum value of SAR (interpolated) = 18.5 mW/g

Z Scan:160,5 (1x1x33): Measurement grid: dx=20mm, dy=20mm, dz=5mm; Maximum value of SAR (measured) = 18.4 mW/g

Zoom Scan:30x30x30,5 (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm;
Reference Value = 97.3 V/m; Power Drift = 0.086 dB, Maximum value of SAR (measured) = 18.8 mW/g

Peak SAR (extrapolated) = 25.1 W/kg (-7.1%, vs.speag-cal.=27.1 W/kg)

SAR(1 g) = 12.2 mW/g (-7.6%, vs.speag-cal.=13.2 mW/g); SAR(10 g) = 5.75 mW/g



Remarks: * Date tested: 2012/06/20; Tested by: Hiroshi Naka; Tested place: No.7 shielded room,
* liquid depth: 155mm; Position: distance of dipole to phantom: 8mm (10mm to liquid); ambient: 24.0 deg.C. / 65 %RH,
* liquid temperature: 23.3(start)/23.3(end)/23.5(in check) deg.C.; * White cubic: zoom scan area, Red cubic: big=SAR(10g)/small=SAR(1g)

Appendix 3-10: System check uncertainty

Uncertainty of system validation (v04)	Under 3GHz (v04)	
	1g SAR	10g SAR
	± 9.5%	± 9.2%
Combined measurement uncertainty of the measurement system (k=1)		
Expanded uncertainty (k=2)	± 19.0%	± 18.4%

	Error Description (Under 3GHz) (v04)	Uncertainty Value	Probability distribution	Divisor	ci (1g)	ci (10g)	ui (1g)	ui (10g)	Vi, veff
A Measurement System							(std. uncertainty)	(std. uncertainty)	
1	Probe Calibration Error(2.45GHz±100MHz)	±6.0 %	Normal	1	1	1	±6.0 %	±6.0 %	∞
2	Axial isotropy	±4.7 %	Rectangular	√3	0.7	0.7	±1.9 %	±1.9 %	∞
3	Hemispherical isotropy (*flat phantom, <5°)	±9.6 %	Rectangular	√3	0.7	0.7	±3.9 %	±3.9 %	∞
4	Boundary effects	±1.4 %	Rectangular	√3	1	1	±0.8 %	±0.8 %	∞
5	Probe linearity	±4.7 %	Rectangular	√3	1	1	±2.7 %	±2.7 %	∞
6	System detection limit	±1.0 %	Rectangular	√3	1	1	±0.6 %	±0.6 %	∞
7	Response Time Error (<5ms/100ms wait)	±0.0 %	Rectangular	√3	1	1	±0.0 %	±0.0 %	∞
8	Integration Time Error(100% duty cycle)	±0.0 %	Rectangular	√3	1	1	±0.0 %	±0.0 %	∞
9	System readout electronics (DAE)	±0.3 %	Normal	1	1	1	±0.3 %	±0.3 %	∞
10	RF ambient conditions-noise (<0.12mW/g)	±3.0 %	Rectangular	√3	1	1	±1.7 %	±1.7 %	∞
11	RF ambient conditions-reflections (<0.12mW/g)	±3.0 %	Rectangular	√3	1	1	±1.7 %	±1.7 %	∞
12	Probe positioner mechanical tolerance	±1.1 %	Rectangular	√3	1	1	±0.6 %	±0.6 %	∞
13	Probe positioning with respect to phantom shell	±2.9 %	Rectangular	√3	1	1	±1.7 %	±1.7 %	∞
14	Max.SAR evaluation	±1.0 %	Rectangular	√3	1	1	±0.6 %	±0.6 %	∞
B Dipole									
15	Dipole to liquid distance(10mm±0.2mm,<2deg.)	±2.0 %	Rectangular	√3	1	1	±1.2 %	±1.2 %	∞
16	Drift of output power (measured, <0.2dB)	±2.5 %	Rectangular	√3	1	1	±1.4 %	±1.4 %	∞
C Phantom and Setup									
17	Phantom uncertainty	±2.0 %	Rectangular	√3	1	1	±1.2 %	±1.2 %	∞
18	Liquid conductivity (target) (<5%)	±5.0 %	Rectangular	√3	0.64	0.43	±1.8 %	±1.2 %	∞
19	Liquid conductivity (meas.)	±2.9 %	Normal	1	0.64	0.43	±1.9 %	±1.2 %	3
20	Liquid permittivity (target) (<5%)	±5.0 %	Rectangular	√3	0.6	0.49	±1.7 %	±1.4 %	∞
21	Liquid permittivity (meas.)	±2.9 %	Normal	1	0.6	0.49	±1.7 %	±1.4 %	3
	Combined Standard Uncertainty						±9.5 %	±9.2 %	7711
	Expanded Uncertainty (k=2)						±19.0 %	±18.4 %	

* This measurement uncertainty budget is suggested by IEEE 1528 and determined by Schmid & Partner Engineering AG.[6]