6660 - B Dobbin Road Columbia, MD 21045 USA Telephone 410.290.6652 / Fax 410.290.6654

http://www.pctestlab.com (email: randy@pctestlab.com)





#### **APPLICANT NAME & ADDRESS:**

Panasonic Corporation of North America One Panasonic Way, 4B-8 Secaucus, NJ 07094

#### **DATE & LOCATION OF TESTING:**

Dates of Tests: June 10 & 13, 2005 Test Report S/N: 0506150441

Test Site: PCTEST Lab, Columbia MD

Project No.: ITPD-04-F108A

FCC ID: ACJ9TGCF-185A

APPLICANT: Matsushita Electric Industrial Co., Ltd.

EUT Type: Notebook PC w/ WLAN, EGPRS and Bluetooth

Tx/Rx Frequency: 2412 – 2462 MHz (DSSS/OFDM)

5180 - 5320 MHz / 5745 - 5825 MHz (OFDM)

824.70 - 848.31 MHz (CDMA)/1851.25 - 1908.75 MHz (PCS CDMA)

Max. RF Output Power: 16.13 dBm Peak Conducted (2.4 GHz DSSS/OFDM)

14.08 dBm Peak Conducted (5.8 GHz OFDM) 15.86 dBm Peak Conducted (5.2 GHz OFDM)

Max. SAR Measurement: 0.345 W/kg GSM850 Body SAR; 0.157 W/kg GSM 1900 Body SAR;

0.263 W/kg 802.11b Body SAR;

0.716 W/kg 802.11a (5300MHz) Body SAR; 0.782 W/kg 802.11a (5800MHz) Body SAR

Trade Name/Model(s): CF-18mk3

FCC Classification(s): Digital Transmission System (DTS)

Unlicensed National Information Infrastructure (NII) Licensed Portable Transmitter Held to Ear (PCE)

FCC Rule Part(s): §2.1093; FCC/OET Bulletin 65 Supplement C [July 2001]

Application Type: Certification

Test Device Serial No.: identical prototype [S/N: #DVT 3]

This wireless portable device has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment/general population exposure limits specified in ANSI/IEEE Std. C95.1-1992 and had been tested in accordance with the measurement procedures specified in FCC/OET Bulletin 65 Supplement C (2001) and IEEE Std. 1528 - 2003

I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualifications of all persons taking them.

Grant Conditions: Output power listed is Conducted. SAR compliance for body-worn operating configuration is based on a separation distance of 0.0 cm between the bottom of the unit and the body of the user. End-users must be informed of the body-worn operating configurations for satisfying RF exposure compliance.

PCTEST certifies that no party to this application has been denied the FCC benefits pursuant to Section 5301 of the Anti-Drug Abuse Act of 1988, 21 U.S.C. 862.

Alfred Cirwithian
Vice President Engineering

### 

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## 1. INTRODUCTION / SAR DEFINITION

The FCC has adopted the guidelines for evaluating the environmental effects of radiofrequency radiation in ET Docket 93-62 on Aug. 6, 1996 to protect the public and workers from the potential hazards of RF emissions due to FCC-regulated portable devices.[1]

The safety limits used for the environmental evaluation measurements are based on the criteria published by the American National Standards Institute (ANSI) for localized specific absorption rate (SAR) in IEEE/ANSI C95.1-1992 Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz. (c) 1992 by the Institute of Electrical and Electronics Engineers, Inc., New York, New York 10017.[2] The measurement procedure described in IEEE/ANSI C95.3-1992 Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields - RF and Microwave[3] is used for guidance in measuring SAR due to the RF radiation exposure from the Equipment Under Test (EUT). These criteria for SAR evaluation are similar to those recommended by the National Council on Radiation Protection and Measurements (NCRP) in Biological Effects and Exposure Criteria for Radiofrequency Electromagnetic Fields," NCRP Report No. 86 (c) NCRP, 1986, Bethesda, MD 20814.[6] SAR is a measure of the rate of energy absorption due to exposure to an RF transmitting source. SAR values have been related to threshold levels for potential biological hazards.

## **SAR Definition**

Specific Absorption Rate (SAR) is defined as the time derivative (rate) of the incremental energy (dU) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dV) of a given density (r). It is also defined as the rate of RF energy absorption per unit mass at a point in an absorbing body (see Fig. 1.1).

$$S A R = \frac{d}{d t} \left( \begin{array}{c} \frac{d U}{d m} \end{array} \right) = \frac{d}{d t} \left( \begin{array}{c} \frac{d U}{r d v} \end{array} \right)$$

Figure 1.1 SAR Mathematical Equation

SAR is expressed in units of Watts per Kilogram (W/kg).

 $SAR = sE^2/r$ 

where:

**S** = conductivity of the tissue-simulant material (S/m)

r = mass density of the tissue-simulant material (kg/m³)

*E* = Total RMS electric field strength (V/m)

NOTE: The primary factors that control rate of energy absorption were found to be the wavelength of the incident field in relations to the dimensions and geometry of the irradiated organism, the orientation of the organism in relation to the polarity of field vectors, the presence of reflecting surfaces, and whether conductive contact is made by the organism with a ground plane.[6]

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## 2. SAR MEASUREMENT SETUP

## **Robotic System**

Measurements are performed using the DASY4 automated dosimetric assessment system. The DASY4 is made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland and consists of high precision robotics system (Staubli), robot controller, Pentium III computer, near-field probe, probe alignment sensor, and the generic twin phantom containing the brain equivalent material. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF) (see Fig. 2.1).

## **System Hardware**

A cell controller system contains the power supply, robot controller, teach pendant (Joystick), and a remote control used to drive the robot motors. The PC consists of the Gateway Pentium 4 2.53 GHz computer with Windows XP system and SAR Measurement Software DASY4, A/D interface card, monitor, mouse, and keyboard. The Staubli Robot is connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE) circuit that performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card.

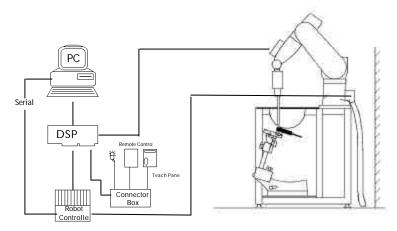


Figure 2.1 SAR Measurement System Setup

## **System Electronics**

The DAE3 consists of a highly sensitive electrometer-grade preamplifier with autozeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer. The system is described in detail in [7].

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## 3. DASY4 E-FIELD PROBE SYSTEM

## **Probe Measurement System**



Figure 3.1 DAE System

The SAR measurements were conducted with the dosimetric probe ET3DV6, designed in the classical triangular configuration [7] (see Fig. 3.2) and optimized for dosimetric evaluation. The probe is constructed using the thick film technique: with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip (see Fig. 3.3). It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 software reads the reflection during a software approach and looks for the maximum using a 2<sup>nd</sup> order fitting (see Fig. 3.1). The approach is stopped at reaching the maximum.

## **Probe Specifications**

Calibration: In air from 10 MHz to 6 GHz

In brain and muscle simulating tissue at

Frequencies of 150 MHz, 450 MHz, 835 MHz, 900 MHz, 1900MHz, 2450MHz, 5300MHz,

& 5800MHz

Frequency: 10 MHz to > 6 GHz; Linearity:  $\pm$  0.2 dB

(30 MHz to 6 GHz)

Directivity:  $\pm 0.2$  dB in HSL (rotation around probe axis)

 $\pm$  0.4 dB in HSL (rotation normal probe axis)

Dynamic: 5 : W/g to > 100 mW/g;Range: Linearity:  $\pm 0.2 \text{ dB}$ 

Dimensions: Overall length: 330 mm

Tip length: 16 mm

Body diameter: 12 mm Tip diameter: 3 mm

Distance from probe tip to dipole centers: 2 mm

Application: General dosimetry up to 6 GHz

Compliance tests of mobile phones

Fast automatic scanning in arbitrary phantoms

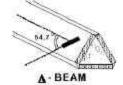


Figure 3.1 Triangular Probe Configuration



Figure 3.2 Probe Thick-Film Technique

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## 4. PROBE CALIBRATION PROCESS

### **Dosimetric Assessment Procedure**

Each probe is calibrated according to a dosimetric assessment procedure described in [8] with accuracy better than +/- 10%. The spherical isotropy was evaluated with the procedure described in [9] and found to be better than +/-0.25dB. The sensitivity parameters (NormX, NormY, NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe is tested.

## **Free Space Assessment**

The free space Efield from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies below 1 GHz (see Fig. 4.1), and in a waveguide above 1 GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity at the proper orientation with the field. The probe is then rotated 360 degrees.

## **Temperature Assessment \***

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium correlates to temperature rise in a dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe (see Fig. 4.2).

$$SAR = C \frac{\Delta T}{\Delta t}$$

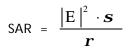
where:

 $\Delta t$  = exposure time (30 seconds),

C = heat capacity of tissue (brain or muscle),

 $\Delta T$  = temperature increase due to RF exposure.

SAR is proportional to  $\Delta T/\Delta t$ , the initial rate of tissue heating, before thermal diffusion takes place. Now it's possible to quantify the electric field in the simulated tissue by equating the thermally derived SAR to the E- field;



where:

 $\sigma$  = simulated tissue conductivity,

 $\rho$  = Tissue density (1.25 g/cm<sup>3</sup> for brain tissue)

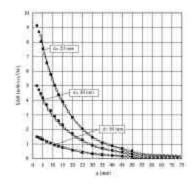


Figure 4.1 E-Field and Temperature measurements at 900MHz [7]

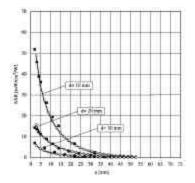


Figure 4.2 E-Field and temperature measurements at 1.9GHz [7]

\*NOTE: The temperature calibration was not performed by PCTEST. For information use only.

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## 5. PHANTOM & EQUIVALENT TISSUES

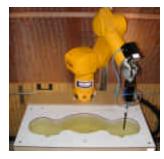
#### **SAM Phantom**



Figure 5.1 SAM Twin Phantom

The SAM Twin Phantom V4.0 is constructed of a fiberglass shell integrated in a wooden table. The shape of the shell is based on data from an anatomical study designed to determine the maximum exposure in at least 90% of all users [11][12]. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents the evaporation of the liquid. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. (see Fig. 5.1)

## **Brain & Muscle Simulating Mixture Characterization**



The brain and muscle mixtures consist of a viscous gel using hydroxethylcellullose (HEC) gelling agent and saline solution (see Table 6.1). Preservation with a bacteriacide is added and visual inspection is made to make sure air bubbles are not trapped during the mixing process. The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the desired tissue. The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 have been incorporated in the following table. Other head and body tissue parameters that have not bee specified in P1528 are derived from the issue dielectric parameters computed from the 4-Cole-Cole equations The mixture characterizations used for the brain and muscle tissue simulating liquids are according to the data by C. Gabriel and G. Hartsgrove [13].(see Fig. 5.2)

Figure 5.2 Simulated

Table 5.1 Composition of the Brain & Muscle Tissue Equivalent Matter

1133UE	Tissue Table of Techniques and Elam a massic rissue Equitation matter					
		SIMULATING TISSUE				
INGREDIENTS		2450MHz Brain	2450MHz Muscle	5800MHz Brain	5800MHz Muscle	
Mixture Percentage						
WATER		62.70	73.2	Propriety Recipe	Propriety Recipe	
DGBE		0.000	26.7	Propriety Recipe	Propriety Recipe	
SUGAR		0.000	0.000	Propriety Recipe	Propriety Recipe	
SALT		0.5	0.04	Propriety Recipe	Propriety Recipe	
BACTERIACIDE		0.000	0.000	Propriety Recipe	Propriety Recipe	
HEC		0.000	0.000	Propriety Recipe	Propriety Recipe	
Dielectric Constant	Target	40.3	52.7	35.84	48.2	
Conductivity (S/m)	Target	1.88	1.95	5.28	6.000	

### **Device Holder for Transmitters**



Figure 5.2 Mounting Device

In combination with the SAM Twin Phantom V4.0, the Mounting Device (see Fig. 5.2) enables the rotation of the mounted transmitter in spherical coordinates whereby the rotation point is the ear opening. The devices can be easily, accurately, and repeatably be positioned according to the FCC specifications. The device holder can be locked at different phantom locations (left head, right head, flat phantom).

\* Note: A simulating human hand is not used due to the complex anatomical and geometrical structure of the hand that may produce infinite number of configurations [12]. To produce the worst-case condition (the hand absorbs antenna output power), the hand is omitted during the tests.

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## 6. TEST SYSTEM SPECIFICATIONS

## **Automated Test System Specifications**

#### **Positioner**

Robot: Stäubli Unimation Corp. Robot Model: RX60L

Repeatability: 0.02 mm

No. of axis: 6

#### **Data Acquisition Electronic (DAE) System**

Cell Controller

Processor: Pentium 4
Clock Speed: 2.53 GHz

Operating System: Windows XP Professional

**Data Converter** 

Features: Signal Amplifier, multiplexer, A/D converter, & control logic

Figure 6.1 DASY4 Test System

**Software**: DASY4 software

**Connecting Lines:** Optical downlink for data and status info.

Optical uplink for commands and clock

**PC Interface Card** 

**Function:** 24 bit (64 MHz) DSP for real time processing

Link to DAE3

16 bit A/D converter for surface detection system

serial link to robot

direct emergency stop output for robot

**E-Field Probes** 

**Model:** EX3DV4 S/N: 3550

**Construction:** Triangular core **Frequency:** 10 MHz to 6 GHz

**Linearity:**  $\pm$  0.2 dB (30 MHz to 6 GHz)

**Phantom** 

**Phantom:** SAM Twin Phantom (V4.0)

Shell Material: VIVAC Composite Thickness:  $2.0 \pm 0.2 \text{ mm}$ 

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## 7. DOSIMETRIC ASSESSMENT & PHANTOM SPECS

#### **Measurement Procedure**

The evaluation was performed using the following procedure:

- 1. The SAR measurement was taken at a selected spatial reference point to monitor power variations during testing. This fixed location point was measured and used as a reference value.
- 2. The SAR distribution at the exposed side of the head was measured at a distance of 3.9mm from the inner surface of the shell. The area covered the entire dimension of the head and the horizontal grid spacing was 15mm x 15mm.
- 3. Based on the area scan data, the area of the maximum absorption was determined by spline interpolation. Around this point, a volume of 32mm x 32mm x 34mm (fine resolution volume scan, zoom scan) was assessed by measuring 7 x 7 x 7 points. On this basis of this data set, the spatial peak SAR value was evaluated with the following procedure (see Fig. 7.1):
- a. The data at the surface was extrapolated, since the center of the dipoles is 2.7mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.2mm. The extrapolation was based on a least square algorithm [15]. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.
- b. The maximum interpolated value was searched with a straight-forward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1g or 10g) were computed using the 3D-Spline interpolation algorithm. The 3D-spline is composed of three one-dimensional splines with the "Not a knot" condition (in x, y, and z directions) [15][16]. The volume was integrated with the trapezoidal algorithm. One thousand points (10 x 10 x 10) were interpolated to calculate the average.
- c. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.
- 4. The SAR reference value, at the same location as procedure #1, was re-measured. If the value changed by more than 5%, the evaluation is repeated.

Deviation from measurement procedure - None



The phantom for handset SAR assessment testing is a low-loss dielectric shell, with shape and dimensions derived from the anthropometric data of the 90<sup>th</sup> percentile adult male head dimensions as tabulated by the US Army. The SAM Twin Phantom shell is bisected along the mid-sagittal plane into right and left halves (see Fig. 7.2). The perimeter sidewalls of each phantom halves are extended to allow filling with liquid to a depth that is sufficient to minimized reflections from the upper surface. The liquid depth is maintained at a minimum depth of 15cm to minimize reflections from the upper surface.



Figure 7.2 SAM Twin Phantom shell

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Figure 7.1 Sample SAR Area Scan



## 8. DEFINITION OF REFERENCE POINTS

#### **EAR Reference Point**

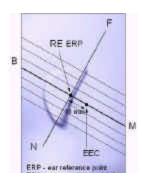


Figure 8.2 Close-up side view of ERPs

Figure 8.1 shows the front, back and side views of the SAM Twin Phantom. The point "M" is the reference point for the center of the mouth, "LE" is the left ear reference point (ERP), and "RE" is the right ERP. The ERPs are 15mm posterior to the entrance to the ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 9.2. The plane passing through the two ear canals and M is defined as the Reference Plane. The line N-F (Neck-Front) is perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting Line (see Figure 8.2). Line B-M is perpendicular to the N-F line. Both N-F and B-M lines are marked on the external phantom shell to facilitate handset positioning [5].

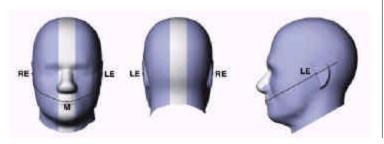


Figure 8.1 Front, back and side view of SAM Twin Phantom

### **Handset Reference Points**

Two imaginary lines on the handset were established: the vertical centerline and the horizontal line. The test device was placed in a normal operating position with the "test device reference point" located along the "vertical centerline" on the front of the device aligned to the "ear reference point" (See Fig. 8.3). The "test device reference point" was than located at the same level as the center of the ear reference point. The test device was positioned so that the "vertical centerline" was bisecting the front surface of the handset at it's top and bottom edges, positioning the "ear reference point" on the outer surface of the both the left and right head phantoms on the ear reference point.

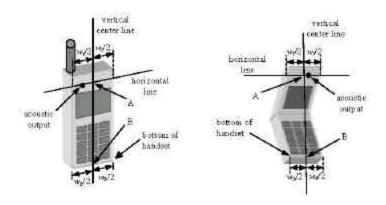


Figure 8.3 Handset Vertical Center & Horizontal Line Reference Points

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## 9. TEST CONFIGURATION POSITIONS

## **Body Holster /Belt Clip Configurations**

Body-worn operating configurations are tested with the belt-clips and holsters attached to

the device and positioned against a flat phantom in a normal use configuration (see Figure 9.5). A device with a headset output is tested with a headset connected to the device. Body dielectric parameters are used.

Accessories for Body-worn operation configurations are divided into two categories: those that do not contain metallic components and those that do contain metallic components. When multiple accessories that do not contain metallic components are supplied with the device, the device is tested with only the accessory that dictates the closest spacing to the body. Then multiple accessories that contain metallic components are supplied with the device, the device is tested with each accessory that contains a unique metallic component. If multiple accessories share an identical metallic component (i.e. the same metallic belt-clip used with different holsters with no other metallic components) only the accessory that dictates the closest spacing to the body is tested.





Figure 9.5 Body Belt Clip & Holster Configurations

Body-worn accessories may not always be supplied or available as options for some devices intended to be authorized for body-worn use. In this case, a test configuration where a separation distance between the back of the device and the flat phantom is used. All test position spacings are documented.

Transmitters that are designed to operate in front of a person's face, as in push-to-talk configurations, are tested for SAR compliance with the front of the device positioned to face the flat phantom. For devices that are carried next to the body such as a shoulder, waist or chest-worn transmitters, SAR compliance is tested with the accessory(ies), including headsets and microphones, attached to the device and positioned against a flat phantom in a normal use configuration.

In all cases SAR measurements are performed to investigate the worst-case positioning. Worst-case positioning is then documented and used to perform Body SAR testing.

In order for users to be aware of the body-worn operating requirements for meeting RF exposure compliance, operating instructions and cautions statements are included in the user's manual.

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## 10. ANSI/IEEE C95.1 - 1992 RF EXPOSURE LIMITS

### **Uncontrolled Environment**

UNCONTROLLED ENVIRONMENTS are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure. The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity.

### **Controlled Environment**

CONTROLLED ENVIRONMENTS are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation). In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means.

Table 10.1. Safety Limits for Partial Body Exposure [2]

	HUMAN EXPOSURE LIMITS	
	UNCONTROLLED ENVIRONMENT	CONTROLLED ENVIRONMENT
	General Population	General Population
	(W/kg) or (mW/g)	(W/kg) or (mW/g)
SPATIAL PEAK SAR <sup>1</sup> Brain	1.60	8.00
SPATIAL AVERAGE SAR <sup>2</sup> Whole Body	0.08	0.40
SPATIAL PEAK SAR <sup>3</sup> Hands, Feet, Ankles, Wrists	4.00	20.00

<sup>3</sup> The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

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<sup>1</sup> The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

<sup>2</sup> The Spatial Average value of the SAR averaged over the whole body.



## 11. MEASUREMENT UNCERTAINTIES 5 GHz Band

a	b	С	d	e=	f	g	h =	i =	k
u u		Ŭ	ď			9	cxf/e		
				f(d,k)				cxg/e	
Uncertainty		Tol.	Prob.		C <sub>i</sub>	C <sub>i</sub>	1 - g	10 - g	
Component	Sec.	(± %)	Dist.	Div.	(1 - g)	(10 - g)	U <sub>i</sub>	U <sub>i</sub>	Vi
							(± %)	(± %)	
Measurement System				_	_	_			
Probe Calibration	E1.1	4.8	N	1	1	1	8.3	8.3	∞
Axial Isotropy	E1.2	4.7	R	√3	0.7	0.7	1.9	1.9	∞
Hemishperical Isotropy	E1.2	9.6	R	√3	0.7	0.7	3.9	3.9	∞
Boundary Effect	E1.3	1.0	R	√3	1	1	0.6	0.6	∞
Linearity	E1.4	4.7	R	√3	1	1	2.7	2.7	$\infty$
System Detection Limits	E1.5	1.0	R	√3	1	1	0.6	0.6	$\infty$
Readout Electronics	E1.6	1.0	N	1	1	1	1.0	1.0	∞
Response Time	E1.7	0.8	R	√3	1	1	0.5	0.5	$\infty$
Integration Time	E1.8	2.6	R	√3	1	1	1.5	1.5	$\infty$
RF Ambient Conditions	E5.1	3.0	R	$\sqrt{3}$	1	1	1.7	1.7	$\infty$
Probe Positioner Mechanical Tolerance	E5.2	0.4	R	$\sqrt{3}$	1	1	0.2	0.2	$\infty$
Probe Positioning w/ respect to Phantom	E5.3	2.9	R	$\sqrt{3}$	1	1	1.7	1.7	$\infty$
Extrapolation, Interpolation & Integration	E4.2	1.0	R	√3	1	1	0.6	0.6	∞
Algorithms for Max. SAR Evaluation									
Test Sample Related									
Test Sample Positioning	E3.2.1	2.9	Ν	1	1	1	2.9	2.9	145
Device Holder Uncertainty	E3.1.1	3.6	N	1	1	1	3.6	3.6	5
Output Power Variation - SAR drift	5.6.2	5.0	R	√3	1	1	2.9	2.9	$\infty$
measurement									
Phantom & Tissue Parameters									
Phantom Uncertainty (Shape & Thickness	E2.1	4.0	R	<sub>√</sub> /3	1	1	2.3	2.3	∞
tolerances)									
Liquid Conductivity - deviation from	E2.2	5.0	R	<sub>√</sub> /3	0.64	0.43	1.8	1.2	∞
target values				·					
Liquid Conductivity - measurement	E2.2	2.5	N	1	0.64	0.43	1.6	1.1	$\infty$
uncertainty									
Liquid Permittivity - deviation from	E2.2	5.0	R	√3	0.6	0.5	1.7	1.4	$\infty$
target values				V					
Liquid Permittivity - measurement	E2.2	2.5	N	1	0.6	0.5	1.5	1.2	∞
uncertainty	]			-					
Combined Standard Uncertainty (k=1)			RSS				12.3	12.1	
Expanded Uncertainty (k=2)							24.6	24.2	
(95% CONFIDENCE LEVEL)									
		!						l	-

The above measurement uncertainties are according to IEEE 1528-2003

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## 11. MEASUREMENT UNCERTAINTIES 2.4 GHz Band

a	b	С	d	e=	f	g	h =	i =	k
				f(d,k)			cxf/e	cxg/e	
Uncertainty		Tol.	Prob.		C <sub>i</sub>	C <sub>i</sub>	1 - g	10 - g	
Component	Sec.	(± %)	Dist.	Div.	(1 - g)	(10 - g)	ui	Ui	Vi
							(± %)	(± %)	
Measurement System									
Probe Calibration	E1.1	4.8	N	1	1	1	4.8	4.8	∞
Axial Isotropy	E1.2	4.7	R	$\sqrt{3}$	0.7	0.7	1.9	1.9	$\infty$
Hemishperical Isotropy	E1.2	9.6	R	$\sqrt{3}$	0.7	0.7	3.9	3.9	$\infty$
Boundary Effect	E1.3	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
Linearity	E1.4	4.7	R	√3	1	1	2.7	2.7	∞
System Detection Limits	E1.5	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	$\infty$
Readout Electronics	E1.6	1.0	N	1	1	1	1.0	1.0	∞
Response Time	E1.7	8.0	R	√3	1	1	0.5	0.5	∞
Integration Time	E1.8	2.6	R	$\sqrt{3}$	1	1	1.5	1.5	$\infty$
RF Ambient Conditions	E5.1	3.0	R	√3	1	1	1.7	1.7	∞
Probe Positioner Mechanical Tolerance	E5.2	0.4	R	√3	1	1	0.2	0.2	∞
Probe Positioning w/ respect to Phantom	E5.3	2.9	R	$\sqrt{3}$	1	1	1.7	1.7	$\infty$
Extrapolation, Interpolation & Integration	E4.2	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	$\infty$
Algorithms for Max. SAR Evaluation									
Test Sample Related									
Test Sample Positioning	E3.2.1	2.9	N	1	1	1	2.9	2.9	145
Device Holder Uncertainty	E3.1.1	3.6	N	1	1	1	3.6	3.6	5
Output Power Variation - SAR drift	5.6.2	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	$\infty$
measurement									
Phantom & Tissue Parameters									
Phantom Uncertainty (Shape & Thickness	E2.1	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	$\infty$
tolerances)									
Liquid Conductivity - deviation from	E2.2	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	$\infty$
target values									
Liquid Conductivity - measurement	E2.2	2.5	Ν	1	0.64	0.43	1.6	1.1	$\infty$
uncertainty									
Liquid Permittivity - deviation from	E2.2	5.0	R	$\sqrt{3}$	0.6	0.5	1.7	1.4	$\infty$
target values									
Liquid Permittivity - measurement	E2.2	2.5	N	1	0.6	0.5	1.5	1.2	$\infty$
uncertainty									
Combined Standard Uncertainty (k=1)			RSS				10.3	10.0	<u> </u>
Expanded Uncertainty (k=2)							20.6	20.1	
(95% CONFIDENCE LEVEL)									

The above measurement uncertainties are according to IEEE 1528-2003

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## 12. SYSTEM VERIFICATION

## **Tissue Verification**

Table 12.1 Simulated Tissue Verification [5]

	MEASURED TISSUE PARAMETERS								
		835MHz Brain		835MHz Muscle		1900MHz Brain		1900MHz Muscle	
Liquid Temperature (°C)	20.4	Target	Measured	Target	Measured	Target	Measured	Target	Measured
Dielectric Constant:	ielectric Constant: ε 41.50 42.08		42.08	55.20	53.02	40.00	39.83	53.30	52.38
Conductivity: σ		0.900	0.910	0.970	0.990	1.400	1.440	1.520	1.580
		MEAS	SURED TIS	SUE PAR	AMETERS				
		2450N	1Hz Brain	2450MHz Muscle 5300MHz Brain			ЛНz Brain	5300MI	Hz Muscle
Liquid Temperature (°C)	20.4	Target	Measured	Target	Measured	Target	Measured	Target	Measured
Dielectric Constant:	ε	39.20 40.43		52.70	53.23	36.00	-	49.00	47.98
Conductivity: σ		1.800	1.860	1.950	1.920	1.800	-	5.300	5.450

MEASURED TISSUE PARAMETERS							
		5800 MHz Brain 5800 MHz Muscle					
Liquid 20.1 Target Measured Target Measured							
Dielectric Constant: ε		35.30	36.18	48.20	46.85		
Conductivity: σ		5.270	5.440	6.000	5.950		

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## **Test System Validation**

Prior to assessment, the system is verified to the  $\pm 10\%$  of the specifications at 835MHz, 1900MHz, 2450MHz, 5300MHz and 5800MHz by using the system validation kit(s). (Graphic Plots Attached)

Table 12.2 System Validation [5]

	System Validation TARGET & MEASURED									
Date:	Amb. Temp (℃)	Liquid Temp(℃)	Input Power (W)	Measured SAR <sub>1g</sub> (mW/g)	Deviation (%)					
06/10/2005	23.8	22.3	0.250	835MHz Brain	2.375	2.300	-3.15			
06/10/2005	23.6	22.1	0.100	1900MHz Brain	3.970	4.110	3.52			
06/10/2005	23.5	22.0	0.100	2450MHz Brain	5.240	5.040	-3.81			
06/13/2005	23.5	22.1	0.025	5800MHz Brain	2.250	2.110	-6.22			

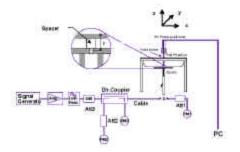




Figure 12.1 Dipole Validation Test Setup

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## 13. SAR TEST DATA SUMMARY

## See Measurement Result Data Pages

The EUT was placed into continuous transmit mode using the manufacturer's software. Such test signals offer a consistent means for testing SAR and are recommended for evaluating SAR [4].

## **Device Test Conditions**

The EUT is powered through the internal battery. In order to verify that the device was tested at full power, conducted output power measurements were performed before and after each SAR measurement to confirm the maximum output power. If a power deviation of more than 5% occurred, the test was repeated.

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## 14. SAR DATA SUMMARY

Mixture Type: 835MHz Muscle

14.1	4.1 MEASUREMENT RESULTS (GSM 850, Tablet)										
FREQU	QUENCY Modulation		Begin / End Average POWER <sup>‡</sup>	Test	Data Rate	Separation Distance	SAK	Remarks			
MHz	Ch.		PCL Code	Position	(Mbps)	(cm)	(W/kg)				
836.60	190	EGPRS	5 (33 dBm)	Tablet	-	0.0 cm	0.338	-			
		Spatial Pea	- SAFETY LIMIT k eneral Population			Muscl 1.6 W/kg (r averaged over	mW/g)				

#### **NOTES:**

- 1. The test data reported are the worst-case SAR value with the antenna position set in a typical configuration. Test procedures used are according to FCC/OET Bulletin 65, Supp.C [July 2001].
- 2. All modes of operation were investigated, and worst-case results are reported.
- 3. Battery is fully charged for all readings. Standard Batteries are the only options.

<sup>‡</sup> Power Measured	X	Conducted		ERP		EIRP
SAR Measurement System	X	DASY4		IDX		
Phantom Configuration		Left Head	X	Flat Phantom		Right Head
SAR Configuration		Head	X	Body		Hand
Test Signal Call Mode		Manu. Test Codes	X	Base Station Simulat	tor	
	SAR Measurement System Phantom Configuration SAR Configuration	SAR Measurement System   Phantom Configuration   SAR Configuration □	SAR Measurement System   DASY4  Phantom Configuration  Left Head  SAR Configuration  Head	SAR Measurement System   DASY4  Phantom Configuration  Left Head  Market Head  Head  Head	SAR Measurement System  DASY4  IDX  Phantom Configuration  Left Head  Flat Phantom  SAR Configuration  Head  Body	SAR Measurement System

- 7. Tissue parameters and temperatures are listed on the SAR plots.
- 8. Liquid tissue depth is 15.1 cm.  $\pm$  0.1

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## **SAR DATA SUMMARY (Continued)**

Mixture Type: 835MHz Muscle

14.2	4.2 MEASUREMENT RESULTS (GSM 1900, Tablet)											
FREQU	JENCY	Modulation	Begin / End Average POWER <sup>‡</sup>	Test	Data Rate	Separation Distance	SAK	Remarks				
MHz	Ch.	Modulation	PCL Code (dBm)	Position	(Mbps)	(cm)	(W/kg)					
1880.0	661	EGPRS	5 (33 dBm)	Tablet	-	0.0 cm	0.157					
l		Spatial	92 - SAFETY LIMIT Peak e/General Population			Muscle 6 W/kg (m\ veraged over 1 g						

#### **NOTES:**

- 1. The test data reported are the worst-case SAR value with the antenna-head position set in a typical configuration. Test procedures used are according to FCC/OET Bulletin 65, Supp.C [July 2001].
- 2. All modes of operation were investigated, and worst-case results are reported.

3.	Battery is fully charged for all readings. Standard Batteries are the only options.						
	<sup>‡</sup> Power Measured	X	Conducted		ERP		EIRP
4.	SAR Measurement System	X	DASY4		IDX		
	Phantom Configuration		Left Head	X	Flat Phantom		Right Head
5.	SAR Configuration		Head	X	Body		Hand
6.	Test Signal Call Mode		Manu. Test Codes	X	Base Station Simulat	tor	

- 7. Tissue parameters and temperatures are listed on the SAR plots.
- 8. Liquid tissue depth is 15.1 cm.  $\pm$  0.1

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## 14. SAR DATA SUMMARY

Mixture Type: 2450MHz Muscle

14.3	14.3 MEASUREMENT RESULTS (802.11b, Tablet)											
FREQU	FREQUENCY Modulati		•	nd Average WER <sup>‡</sup>	Test	Data Rate (Mbps)	Separation Distance (cm)	SAR (W/kg)	Remarks			
MHz	Ch.	PCL	Code	Position								
2437	06	DSSS	16.13	16.32	Tablet	1	0.0 cm	0.154	Main Antenna			
2437	06	DSSS	16.13	16.31	Tablet	1	0.0 cm	0.263	Aux Antenna			
	ANSI / IEEE C95.1 1992 - SAFETY LIMIT  Spatial Peak Uncontrolled Exposure/General Population						Muscle 1.6 W/kg (m averaged over 1	•				

#### NOTES:

- 1. The test data reported are the worst-case SAR value with the antenna position set in a typical configuration. Test procedures used are according to FCC/OET Bulletin 65, Supp.C [July 2001].
- 2. All modes of operation were investigated, and worst-case results are reported.

3.	Battery is fully	charged for	all readings.	Standard Batteries are	the only options.
----	------------------	-------------	---------------	------------------------	-------------------

	<sup>‡</sup> Power Measured	X	Conducted		ERP		EIRP
4.	SAR Measurement System	X	DASY4		IDX		
	Phantom Configuration		Left Head	X	Flat Phantom		Right Head
5.	SAR Configuration		Head	X	Body		Hand
6.	Test Signal Call Mode		Manu. Test Codes	X	Base Station Simula	tor	
_							

- 7. Tissue parameters and temperatures are listed on the SAR plots.
- 8. Liquid tissue depth is 15.1 cm.  $\pm$  0.1

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## **SAR DATA SUMMARY (Continued)**

Mixture Type: 53000MHz Muscle

14.4											
FREQUE	FREQUENCY Modu		Begin / End Average POWER <sup>‡</sup> PCL Code		Test	Data Rate	Separation	SAR	Remarks		
MHz	Ch.				Position	(Mbps)	Distance	(W/kg)	Nomal Ro		
5260	52	OFDM	14.63	14.43	Tablet	12	0.0 cm	0.124	Main Antenna		
5260	52	OFDM	14.63	14.76	Tablet	12	0.0 cm	0.716	Aux Antenna		
ANSI / IEEE C95.1 1992 - SAFETY LIMIT  Spatial Peak  Uncontrolled Exposure/General Population							Muscle 1.6 W/kg (m averaged over 1	nW/g)			

#### **NOTES:**

- 1. The test data reported are the worst-case SAR value with the antenna-head position set in a typical configuration. Test procedures used are according to FCC/OET Bulletin 65, Supp.C [July 2001].
- 2. All modes of operation were investigated, and worst-case results are reported.
- 3. Battery is fully charged for all readings. Standard Batteries are the only options.

	<sup>‡</sup> Power Measured	X	Conducted		ERP		EIRP
1.	SAR Measurement System	X	DASY4		IDX		
	Phantom Configuration		Left Head	X	Flat Phantom		Right Head
5.	SAR Configuration		Head	X	Body		Hand
ó.	Test Signal Call Mode		Manu. Test Codes	X	Base Station Simula	tor	

- 7. Tissue parameters and temperatures are listed on the SAR plots.
- 8. Liquid tissue depth is 15.1 cm.  $\pm$  0.1

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## **SAR DATA SUMMARY (Continued)**

Mixture Type: 5800MHz Muscle

14.5 MEASUREMENT RESULTS (802.11a, Tablet)									
FREQUE	NCY	Modulation	Begin / End Average POWER <sup>‡</sup>		Test	Data Rate	Separation	SAR	Remarks
MHz	Ch.			Position (Mbps)	Distance (cm)	(W/kg)	Kemarks		
5785	157	OFDM	14.03	14.15	Tablet	12	0.0 cm	0.098	Main Antenna
5785	157	OFDM	14.03	14.20	Tablet	21	0.0 cm	0.782	Aux Antenna
ANSI / IEEE C95.1 1992 - SAFETY LIMIT							Muscle		
Spatial Peak Uncontrolled Exposure/General Population							1.6 W/kg (mV averaged over 1 gr	٠.	

#### **NOTES:**

- 1. The test data reported are the worst-case SAR value with the antenna-head position set in a typical configuration. Test procedures used are according to FCC/OET Bulletin 65, Supp.C [July 2001].
- 2. All modes of operation were investigated, and worst-case results are reported.

3.	Rattory is fully	y charged for all readings.	Standard Rattorios	are the only ontions
J.	Dattery is full	y charged for all readings.	Stariuaru Datteries	are the offin options.

	<sup>‡</sup> Power Measured	X	Conducted		ERP		EIRP
4.	SAR Measurement System	X	DASY4		IDX		
	Phantom Configuration		Left Head	X	Flat Phantom		Right Head
5.	SAR Configuration		Head	X	Body		Hand
6.	Test Signal Call Mode		Manu. Test Codes	X	Base Station Simula	ator	

- 7. Tissue parameters and temperatures are listed on the SAR plots.
- 8. Liquid tissue depth is 15.1 cm.  $\pm$  0.1

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## 15. SAR TEST EQUIPMENT

## **Equipment Calibration**

**Table 15.1 Test Equipment Calibration** 

EQUIPMENT SPECIFICATIONS					
Туре	Calibration Date	Serial Number			
Stäubli Robot RX60L	October 2004	599131-01			
Stäubli Robot Controller	October 2004	PCT592			
Stäubli Teach Pendant (Joystick)	October 2004	3323-00161			
Micron Computer, 450 MHz Pentium III, Windows NT	October 2004	PCT577			
SPEAG EDC3	October 2004	321			
SPEAG DAE3	January 2006	455			
SPEAG E-Field Probe ES3DV2	September 2004	3022			
SPEAG Dummy Probe	October 2004	PCT583			
SPEAG SAM Twin Phantom V4.0	October 2004	PCT666			
SPEAG Light Alignment Sensor	October 2004	205			
PCTEST Validation Dipole D300V2	September 2004	PCT301			
SPEAG Validation Dipole D835V2	January 2006	PCT512			
SPEAG Validation Dipole D1900V2	January 2006	PCT613			
Brain Equivalent Matter (300MHz)	June 2005	PCTBEM601			
Brain Equivalent Matter (835MHz)	June 2005	PCTBEM101			
Brain Equivalent Matter (1900MHz)	June 2005	PCTBEM301			
Muscle Equivalent Matter (300MHz)	June 2005	PCTMEM701			
Muscle Equivalent Matter (835MHz)	June 2005	PCTMEM201			
Muscle Equivalent Matter (1900MHz)	June 2005	PCTMEM401			
Microwave Amp. Model: 5S1G4, (800MHz - 4.2GHz)	January 2006	22332			
Gigatronics 8651A Power Meter	January 2006	1835299			
HP-8648D (9kHz ~ 4GHz) Signal Generator	January 2006	PCT530			
Amplifier Research 5S1G4 Power Amp	January 2006	PCT540			
HP-8753E (30kHz ~ 3GHz) Network Analyzer	January 2006	PCT552			
HP85070B Dielectric Probe Kit	January 2006	PCT501			
Ambient Noise/Reflection, etc. January 2004	Anechoic Room PCT01	Anechoic Room PCT01			

### NOTE:

The E-field probe was calibrated by SPEAG, by waveguide technique procedure. Dipole Validation measurement is performed by PCTEST Lab. before each test. The brain simulating material is calibrated by PCTEST using the dielectric probe system and network analyzer to determine the conductivity and permittivity (dielectric constant) of the brain-equivalent material.

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## 16. CONCLUSION

### **Measurement Conclusion**

The SAR measurement indicates that the EUT complies with the RF radiation exposure limits of the FCC. These measurements are taken to simulate the RF effects exposure under worst-case conditions. Precise laboratory measures were taken to assure repeatability of the tests. The tested device complies with the requirements in respect to all parameters subject to the test. The test results and statements relate only to the item(s) tested.

Please note that the absorption and distribution of electromagnetic energy in the body are very complex phenomena that depend on the mass, shape, and size of the body, the orientation of the body with respect to the field vectors, and the electrical properties of both the body and the environment. Other variables that may play a substantial role in possible biological effects are those that characterize the environment (e.g. ambient temperature, air velocity, relative humidity, and body insulation) and those that characterize the individual (e.g. age, gender, activity level, debilitation, or disease). Because innumerable factors may interact to determine the specific biological outcome of an exposure to electromagnetic fields, any protection guide shall consider maximal amplification of biological effects as a result of field-body interactions, environmental conditions, and physiological variables.[3]

PCTESTÔ SAR REPORT	POTENT	FCC CERTIFICATION  Panasonic		Reviewed by: Quality Manager
SAR Filename:	Test Dates:	Phone Type: Panasonic Notebook PC w/	FCC ID:	Page 24 of 25
0506150441	June 10 & 13, 2005	WLAN, EGPRS and Bluetooth	ACJ9TGCF-185A	



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PCTESTÔ SAR REPORT	POTEST	FCC CERTIFICATION		Reviewed by: Quality Manager
<b>SAR Filename:</b> 0506150441	<b>Test Dates:</b> June 10 & 13, 2005	Phone Type: Panasonic Notebook PC w/ WLAN, EGPRS and Bluetooth	FCC ID: ACJ9TGCF-185A	Page 25 of 25

## APPENDIX A: SAR TEST DATA

### DUT: CF -18; Type: Panasonic Notebook PC with WLAN, EGPRS & Bluetooth; Serial: DVT 3

Communication System: GSM 850 GPRS; 2 Tx slots; Frequency: 836.6 MHz;Duty Cycle: 1:4.15 Medium: 835 Muscle ( $\sigma$  = 0.99 mho/m,  $\epsilon_r$  = 53.02,  $\rho$  = 1000 kg/m³) Phantom section: Flat Section; Space: 0.0 cm

Test Date: 06-10-2005; Ambient Temp: 23.8°C; Tissue Temp: 22.3°C

Probe: EX3DV4 - SN3550; ConvF(7.99, 7.99, 7.99); Calibrated: 10/26/2004 Sensor-Surface: 3mm (Mechanical Surface Detection) Electronics: DAE3 Sn455; Calibrated: 6/23/2004

Phantom: SAM Sub; Type: SAM 4.0; Serial: TP:1357

Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

## Mode: GSM850 EGPRS, Tablet position, Right side, Ch.190

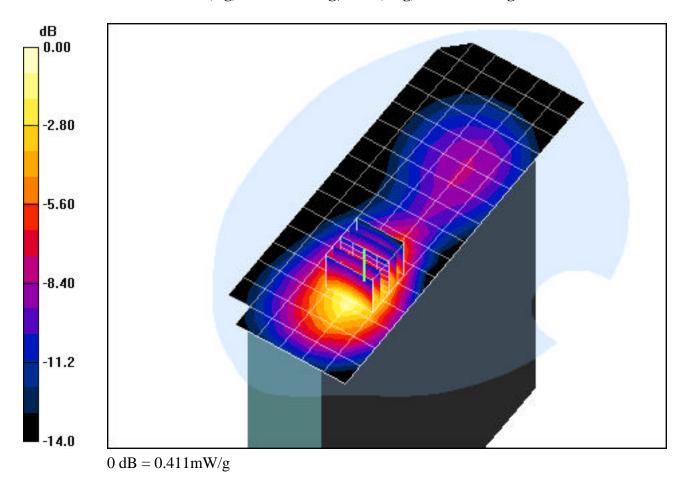
Area Scan (7x17x1): Measurement grid: dx=15mm, dy=15mm

Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 6.74 V/m

Peak SAR (extrapolated) = 0.551 W/kg

SAR(1 g) = 0.345 mW/g; SAR(10 g) = 0.210 mW/g



#### DUT: CF -18; Type: Panasonic Notebook PC with WLAN, EGPRS & Bluetooth; Serial: DVT 3

Communication System: GSM1900 GPRS; Frequency: 1880 MHz; Duty Cycle: 1:4.15 Medium: 1900 Muscle ( $\sigma$  = 1.58 mho/m,  $\epsilon_r$  = 52.38,  $\rho$  = 1000 kg/m<sup>3</sup>) Phantom section: Flat Section; Space: 0.0 cm

Test Date: 06-10-2005; Ambient Temp: 23.9°C; Tissue Temp: 22.1°C

Probe: EX3DV4 - SN3550; ConvF(6.35, 6.35, 6.35); Calibrated: 10/26/2004 Sensor-Surface: 3mm (Mechanical Surface Detection) Electronics: DAE3 Sn455; Calibrated: 6/23/2004

Phantom: SAM Main; Type: SAM 4.0; Serial: TP:1197

Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

## Mode: GSM1900 EGPRS, Tablet position, Right side, Ch.661

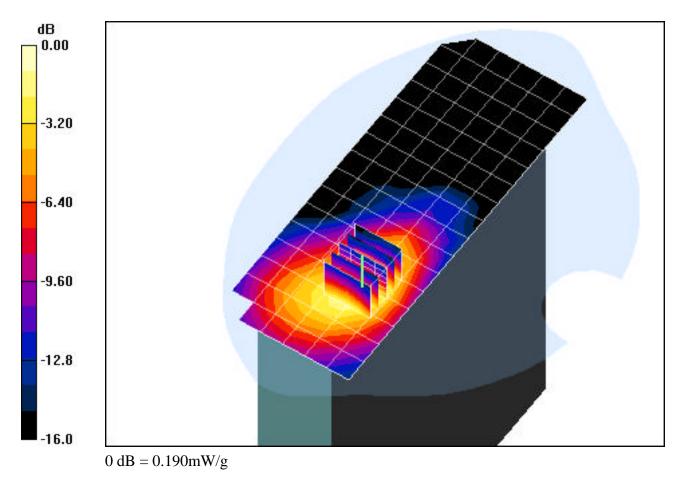
Area Scan (7x17x1): Measurement grid: dx=15mm, dy=15mm

Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 2.95 V/m

Peak SAR (extrapolated) = 0.255 W/kg

SAR(1 g) = 0.157 mW/g; SAR(10 g) = 0.091 mW/g



### DUT: CF -18; Type: Panasonic Notebook PC with WLAN, EGPRS & Bluetooth; Serial: DVT 3

Communication System: IEEE 802.11b; Frequency: 2437 MHz; Duty Cycle: 1:1 Medium: 2450 Muscle ( $\sigma$  = 1.92 mho/m,  $\epsilon_r$  = 53.23,  $\rho$  = 1000 kg/m<sup>3</sup>) Phantom section: Flat Section; Space: 0.0 cm

Test Date: 06-10-2005; Ambient Temp: 23.5°C; Tissue Temp: 22.4°C

Probe: EX3DV4 - SN3550; ConvF(6.27, 6.27, 6.27); Calibrated: 10/26/2004 Sensor-Surface: 3mm (Mechanical Surface Detection)

Electronics: DAE3 Sn455; Calibrated: 6/23/2004 Phantom: SAM Sub; Type: SAM 4.0; Serial: TP:1357

Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

### Mode: IEEE 802.11b, Tablet position, Right Side, ch.06, 5.5Mbps, Aux Ant

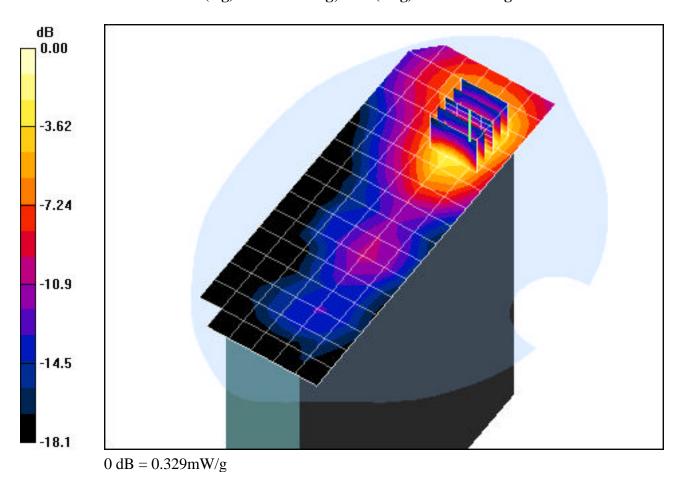
Area Scan (7x17x1): Measurement grid: dx=15mm, dy=15mm

Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 3.21 V/m

Peak SAR (extrapolated) = 0.482 W/kg

SAR(1 g) = 0.263 mW/g; SAR(10 g) = 0.140 mW/g



### DUT: CF -18; Type: Panasonic Notebook PC with WLAN, EGPRS & Bluetooth; Serial: DVT 3

Communication System: IEEE 802.11a; Frequency: 5260 MHz; Duty Cycle: 1:1 Medium: 5300 Muscle ( $\sigma$  = 5.45 mho/m,  $\epsilon_r$  = 47.94,  $\rho$  = 1000 kg/m<sup>3</sup>) Phantom section: Flat Section; Space: 0.0 cm

Test Date: 06-13-2005; Ambient Temp: 23.6°C; Tissue Temp: 22.3°C

Probe: EX3DV4 - SN3550; ConvF(3.72, 3.72, 3.72); Calibrated: 10/26/2004 Sensor-Surface: 3mm (Mechanical Surface Detection) Electronics: DAE3 Sn455; Calibrated: 6/23/2004

Phantom: SAM Main; Type: SAM 4.0; Serial: TP:1197 Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

### Mode: IEEE 802.11a, Tablet position, Right side, ch.52, 12Mbps, Aux Antenna

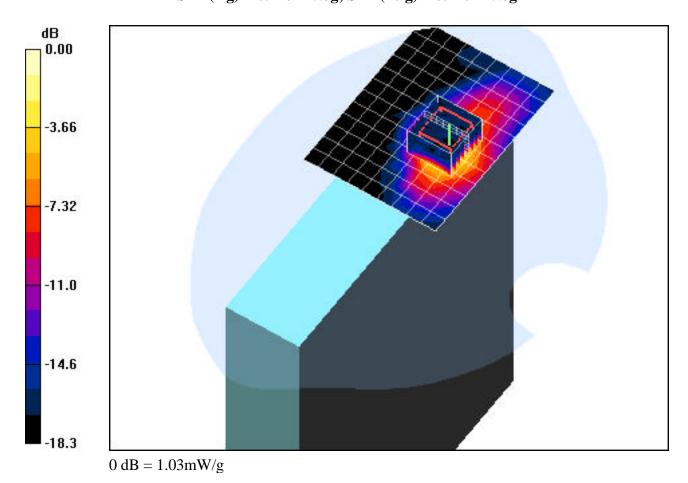
Area Scan (10x13x1): Measurement grid: dx=10mm, dy=10mm

Zoom Scan (8x8x8)/Cube 0: Measurement grid: dx=4.3mm, dy=4.3mm, dz=3mm

Reference Value = 2.15 V/m

Peak SAR (extrapolated) = 1.96 W/kg

SAR(1 g) = 0.716 mW/g; SAR(10 g) = 0.270 mW/g



### DUT: CF -18; Type: Panasonic Notebook PC with WLAN, EGPRS & Bluetooth; Serial: DVT 3

Communication System: IEEE 802.11a; Frequency: 5785 MHz;Duty Cycle: 1:1 Medium: 5800 Muscle ( $\sigma$  = 5.95 mho/m,  $\epsilon_r$  = 46.85,  $\rho$  = 1000 kg/m<sup>3</sup>) Phantom section: Flat Section; Space: 0.0 cm

Test Date: 06-13-2005; Ambient Temp: 23.9°C; Tissue Temp: 22.4°C

Probe: EX3DV4 - SN3550; ConvF(3.48, 3.48, 3.48); Calibrated: 10/26/2004 Sensor-Surface: 3mm (Mechanical Surface Detection) Electronics: DAE3 Sn455; Calibrated: 6/23/2004

Phantom: SAM Main; Type: SAM 4.0; Serial: TP:1197

Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

## Mode: IEEE 802.11a, Tablet position, Right side, ch.157, 12Mbps, Aux Antenna

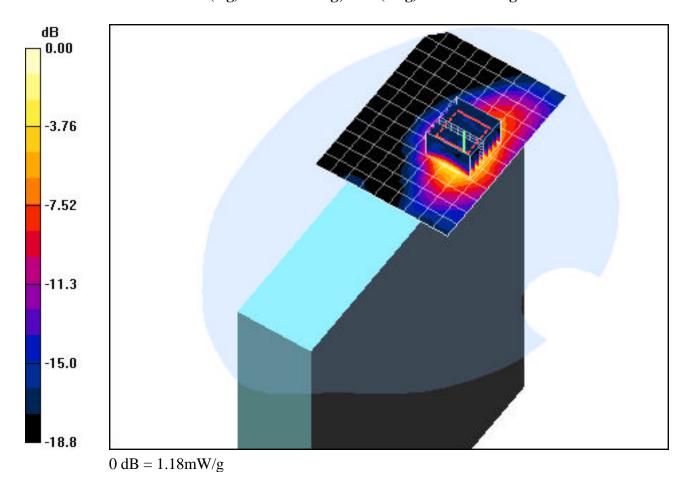
Area Scan (10x13x1): Measurement grid: dx=10mm, dy=10mm

Zoom Scan (8x8x8)/Cube 0: Measurement grid: dx=4.3mm, dy=4.3mm, dz=3mm

Reference Value = 2.04 V/m

Peak SAR (extrapolated) = 2.32 W/kg

SAR(1 g) = 0.782 mW/g; SAR(10 g) = 0.304 mW/g



## DUT: CF -18; Type: Panasonic Notebook PC with WLAN, EGPRS & Bluetooth; Serial: DVT 3

Communication System: GSM 850 GPRS; 2 Tx slots; Frequency: 836.6 MHz; Duty Cycle: 1:4.15 Medium: 835 Muscle ( $\sigma$  = 0.99 mho/m,  $\epsilon_{\rm r}$  = 53.02,  $\rho$  = 1000 kg/m<sup>3</sup>) Phantom section: Flat Section; Space: 0.0 cm

Test Date: 06-10-2005; Ambient Temp: 23.8°C; Tissue Temp: 22.3°C

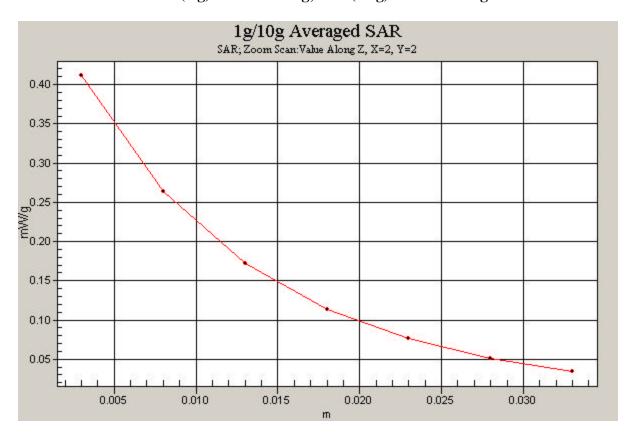
Probe: EX3DV4 - SN3550; ConvF(7.99, 7.99, 7.99); Calibrated: 10/26/2004 Sensor-Surface: 3mm (Mechanical Surface Detection)

Electronics: DAE3 Sn455; Calibrated: 6/23/2004 Phantom: SAM Sub; Type: SAM 4.0; Serial: TP:1357

Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

## Mode: GSM850 EGPRS, Tablet position, Right side, Ch.190

Area Scan (7x17x1): Measurement grid: dx=15mm, dy=15mm Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 6.74 V/m Peak SAR (extrapolated) = 0.551 W/kg SAR(1 g) = 0.345 mW/g; SAR(10 g) = 0.210 mW/g



### DUT: CF -18; Type: Panasonic Notebook PC with WLAN, EGPRS & Bluetooth; Serial: DVT 3

Communication System: GSM1900 GPRS; Frequency: 1880 MHz; Duty Cycle: 1:4.15 Medium: 1900 Muscle ( $\sigma = 1.58 \text{ mho/m}$ ,  $\varepsilon_r = 52.38$ ,  $\rho = 1000 \text{ kg/m}^3$ )

Phantom section: Flat Section; Space: 0.0 cm

Test Date: 06-10-2005; Ambient Temp: 23.9°C; Tissue Temp: 22.1°C

Probe: EX3DV4 - SN3550; ConvF(6.35, 6.35, 6.35); Calibrated: 10/26/2004 Sensor-Surface: 3mm (Mechanical Surface Detection) Electronics: DAE3 Sn455; Calibrated: 6/23/2004

Phantom: SAM Main; Type: SAM 4.0; Serial: TP:1197

Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

## Mode: GSM1900 EGPRS, Tablet position, Right side, Ch.661

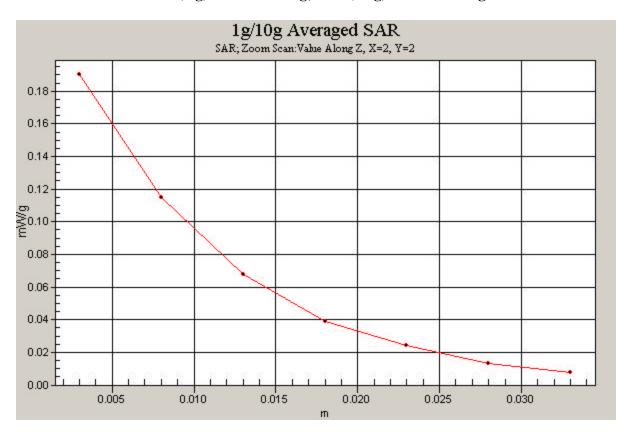
Area Scan (7x17x1): Measurement grid: dx=15mm, dy=15mm

Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 2.95 V/m

Peak SAR (extrapolated) = 0.255 W/kg

SAR(1 g) = 0.157 mW/g; SAR(10 g) = 0.091 mW/g



### DUT: CF -18; Type: Panasonic Notebook PC with WLAN, EGPRS & Bluetooth; Serial: DVT 3

Communication System: IEEE 802.11b; Frequency: 2437 MHz; Duty Cycle: 1:1 Medium: 2450 Muscle ( $\sigma$  = 1.92 mho/m,  $\epsilon_r$  = 53.23,  $\rho$  = 1000 kg/m<sup>3</sup>) Phantom section: Flat Section; Space: 0.0 cm

Test Date: 06-10-2005; Ambient Temp: 23.5°C; Tissue Temp: 22.4°C

Probe: EX3DV4 - SN3550; ConvF(6.27, 6.27, 6.27); Calibrated: 10/26/2004

Sensor-Surface: 3mm (Mechanical Surface Detection) Electronics: DAE3 Sn455; Calibrated: 6/23/2004 Phantom: SAM Sub; Type: SAM 4.0; Serial: TP:1357

Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

## Mode: IEEE 802.11b, Tablet position, Right Side, ch.06, 5.5Mbps, Aux Antenna

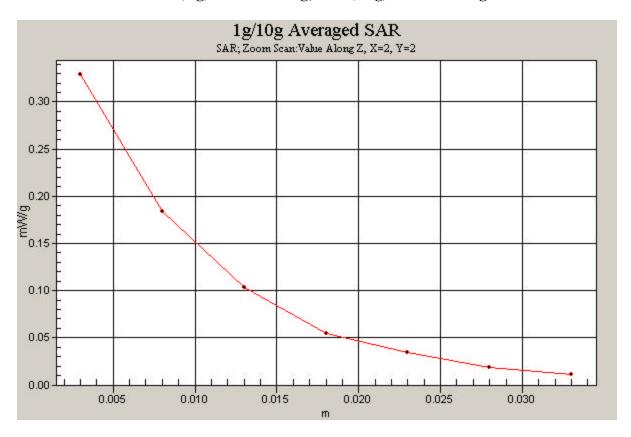
Area Scan (7x17x1): Measurement grid: dx=15mm, dy=15mm

Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 3.21 V/m

Peak SAR (extrapolated) = 0.482 W/kg

SAR(1 g) = 0.263 mW/g; SAR(10 g) = 0.140 mW/g



### DUT: CF -18; Type: Panasonic Notebook PC with WLAN, EGPRS & Bluetooth; Serial: DVT 3

Communication System: IEEE 802.11a; Frequency: 5260 MHz; Duty Cycle: 1:1 Medium: 5300 Muscle ( $\sigma$  = 5.45 mho/m,  $\epsilon_r$  = 47.94,  $\rho$  = 1000 kg/m<sup>3</sup>) Phantom section: Flat Section; Space: 0.0 cm

Test Date: 06-13-2005; Ambient Temp: 23.6°C; Tissue Temp: 22.3°C

Probe: EX3DV4 - SN3550; ConvF(3.72, 3.72, 3.72); Calibrated: 10/26/2004 Sensor-Surface: 3mm (Mechanical Surface Detection) Electronics: DAE3 Sn455; Calibrated: 6/23/2004

Phantom: SAM Main; Type: SAM 4.0; Serial: TP:1197

Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Mode: IEEE 802.11a, Tablet position, Right side, ch.52, 12Mbps, Aux Antenna

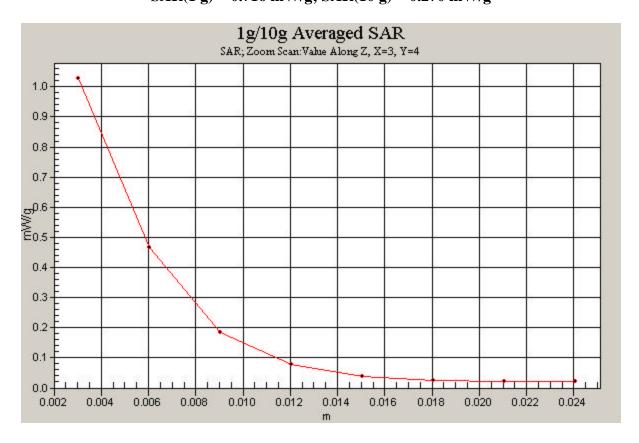
Area Scan (10x13x1): Measurement grid: dx=10mm, dy=10mm

Zoom Scan (8x8x8)/Cube 0: Measurement grid: dx=4.3mm, dy=4.3mm, dz=3mm

Reference Value = 2.15 V/m

Peak SAR (extrapolated) = 1.96 W/kg

SAR(1 g) = 0.716 mW/g; SAR(10 g) = 0.270 mW/g



### DUT: CF -18; Type: Panasonic Notebook PC with WLAN, EGPRS & Bluetooth; Serial: DVT 3

Communication System: IEEE 802.11a; Frequency: 5785 MHz;Duty Cycle: 1:1 Medium: 5800 Muscle ( $\sigma$  = 5.95 mho/m,  $\epsilon_r$  = 46.85,  $\rho$  = 1000 kg/m<sup>3</sup>) Phantom section: Flat Section; Space: 0.0 cm

Test Date: 06-13-2005; Ambient Temp: 23.9°C; Tissue Temp: 22.4°C

Probe: EX3DV4 - SN3550; ConvF(3.48, 3.48, 3.48); Calibrated: 10/26/2004 Sensor-Surface: 3mm (Mechanical Surface Detection) Electronics: DAE3 Sn455; Calibrated: 6/23/2004

Phantom: SAM Main; Type: SAM 4.0; Serial: TP:1197

Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Mode: IEEE 802.11a, Tablet position, Right side, ch.157, 12Mbps, Aux Antenna

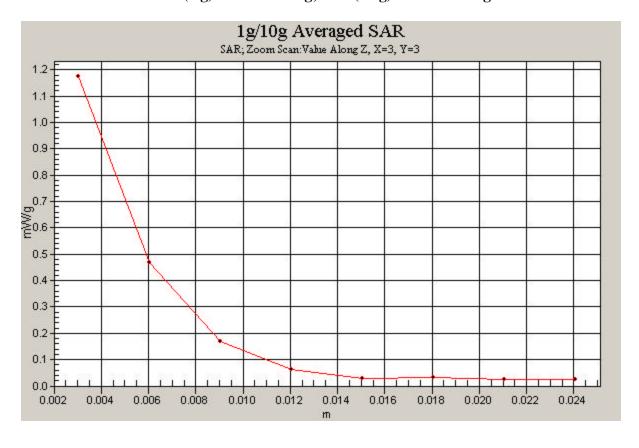
Area Scan (10x13x1): Measurement grid: dx=10mm, dy=10mm

Zoom Scan (8x8x8)/Cube 0: Measurement grid: dx=4.3mm, dy=4.3mm, dz=3mm

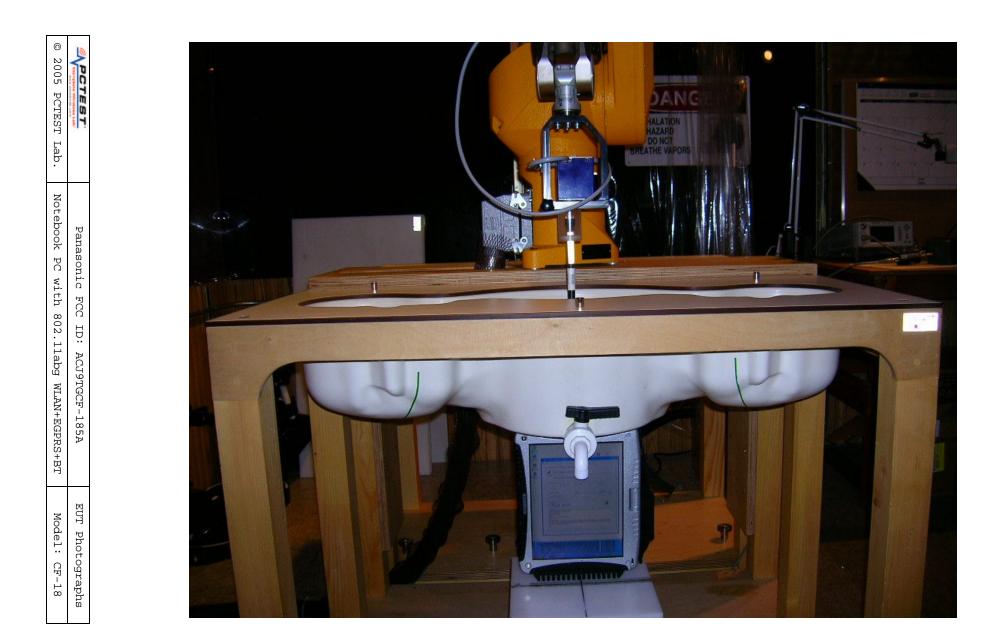
Reference Value = 2.04 V/m

Peak SAR (extrapolated) = 2.32 W/kg

SAR(1 g) = 0.782 mW/g; SAR(10 g) = 0.304 mW/g



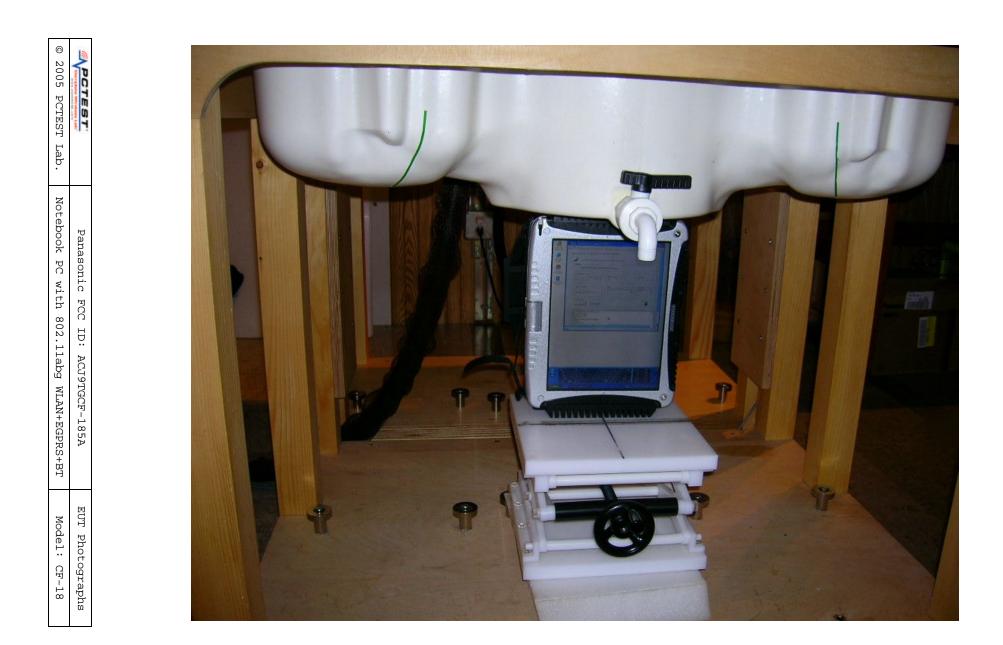
## APPENDIX B: SAR TEST SETUP PHOTOGRAPHS



© 2005 PCTEST Lab.	STREET STREET	
Notebook PC with 802.11abg WLAN+EGPRS+BT	Panasonic FCC ID: ACJ9TGCF-185A	
Model: CF-18	EUT Photographs	







© 2005 PCTEST Lab.	Correlate Windows Lab	
Notebook PC with 802.11abg WLAN+EGPRS+BT	Panasonic FCC ID: ACJ9TGCF-185A	
Model: CF-18	EUT Photographs	

# APPENDIX C: DIPOLE VALIDATION

DUT: Dipole 835 MHz; Type: D835V2; Serial: 406

Communication System: CW; Frequency: 835 MHz; Duty Cycle: 1:1 Medium: 835 Brain ( $\sigma$  = 0.91 mho/m,  $\epsilon_r$  = 42.08,  $\rho$  = 1000 kg/m<sup>3</sup>)

Phantom section: Flat Section; Space: 1.5 cm

Test Date: 06-10-2005; Ambient Temp: 23.8°C; Tissue Temp: 22.3°C

Probe: EX3DV4 - SN3550; ConvF(8.12, 8.12, 8.12); Calibrated: 10/26/2004

Sensor-Surface: 3mm (Mechanical Surface Detection) Electronics: DAE3 Sn455; Calibrated: 6/23/2004 Phantom: SAM Sub; Type: SAM 4.0; Serial: TP:1357

Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

#### 835MHz Dipole Validation

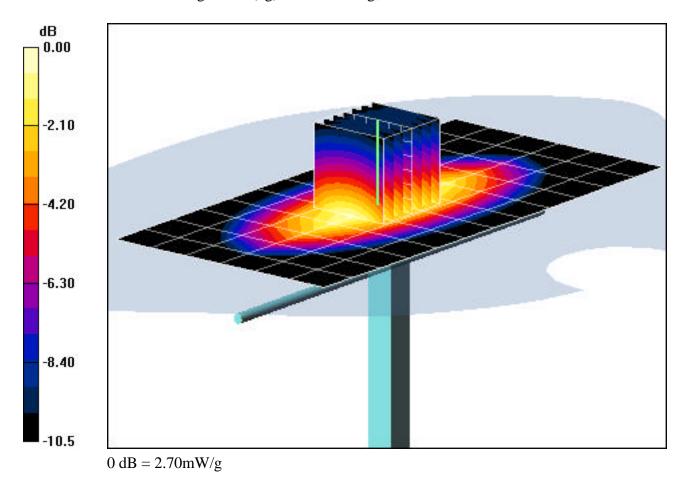
Area Scan (7x13x1): Measurement grid: dx=15mm, dy=15mm

Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Input Power = 24.0 dBm (250 mW)

SAR(1 g) = 2.3 mW/g; SAR(10 g) = 1.5 mW/g

Target SAR(1g) = 2.375 mW/g; Deviation = -3.15 %



#### DUT: Dipole 1900 MHz; Type: D1900V2; Serial: 502

Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1 Medium: 1900 Brain ( $\sigma$  = 1.44 mho/m,  $\epsilon_r$  = 39.83,  $\rho$  = 1000 kg/m<sup>3</sup>)

Phantom section: Flat Section; Space: 1.0 cm

Test Date: 06-10-2005; Ambient Temp: 23.6°C; Tissue Temp: 22.1°C

Probe: EX3DV4 - SN3550; ConvF(6.75, 6.75, 6.75); Calibrated: 10/26/2004
Sensor Surface: 3mm (Mechanical Surface Detection)

Sensor-Surface: 3mm (Mechanical Surface Detection) Electronics: DAE3 Sn455; Calibrated: 6/23/2004 Phantom: SAM Main; Type: SAM 4.0; Serial: TP:1197

Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

#### 1900MHz Dipole Validation

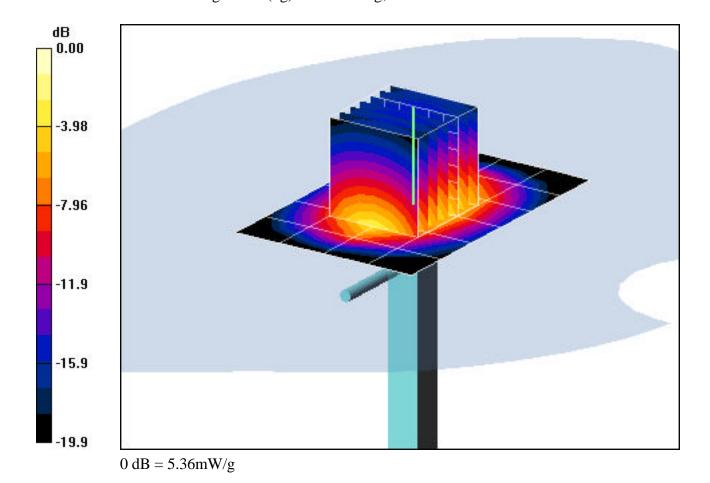
Area Scan (5x7x1): Measurement grid: dx=15mm, dy=15mm

Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Input Power = 20.0 dBm (100 mW)

SAR(1 g) = 4.11 mW/g; SAR(10 g) = 2.05 mW/g

Target SAR(1g) = 3.97 mW/g; Deviation = +3.52 %



#### DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN:719

Communication System: CW; Frequency: 2450 MHz; Duty Cycle: 1:1 Medium: 2450 Brain ( $\sigma$  = 1.86 mho/m,  $\epsilon_r$  = 40.43,  $\rho$  = 1000 kg/m<sup>3</sup>) Phantom section: Flat Section; Space: 1.0 cm

Test Date: 06-10-2005; Ambient Temp: 23.5°C; Tissue Temp: 22.0°C

Probe: EX3DV4 - SN3550; ConvF(6.33, 6.33, 6.33); Calibrated: 10/26/2004 Sensor-Surface: 3mm (Mechanical Surface Detection)

Electronics: DAE3 Sn455; Calibrated: 6/23/2004 Phantom: SAM Sub; Type: SAM 4.0; Serial: TP:1357

Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

#### 2450MHz Dipole Validation

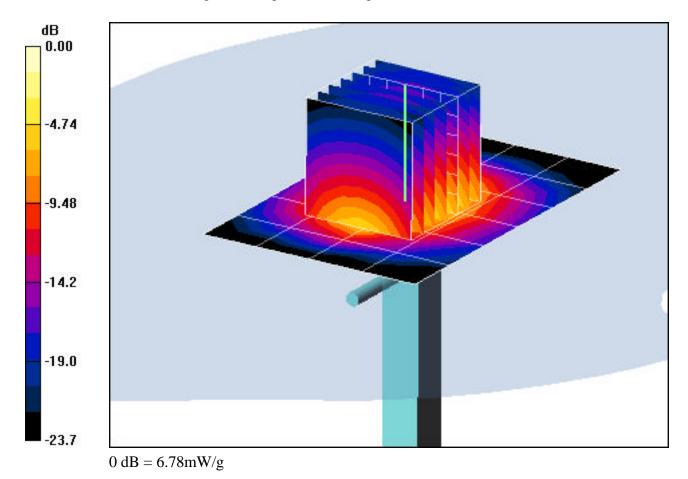
Area Scan (5x7x1): Measurement grid: dx=15mm, dy=15mm

Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Input Power = 20.0 dBm (100 mW)

SAR(1 g) = 5.04 mW/g; SAR(10 g) = 2.26 mW/g

Target SAR(1g) = 5.24 mW/g; Deviation = -3.81 %



DUT: Dipole 5800 MHz; Type: D5GHzV2; Serial: 1007

Communication System: CW; Frequency: 5800 MHz; Duty Cycle: 1:1 Medium: 5800 Brain ( $\sigma$  = 5.44 mho/m,  $\epsilon_r$  = 36.18,  $\rho$  = 1000 kg/m<sup>3</sup>)

Phantom section: Flat Section; Space: 1.0 cm

Test Date: 06-13-2005; Ambient Temp: 23.5°C; Tissue Temp: 22.1°C

Probe: EX3DV4 - SN3550; ConvF(3.74, 3.74, 3.74); Calibrated: 10/26/2004

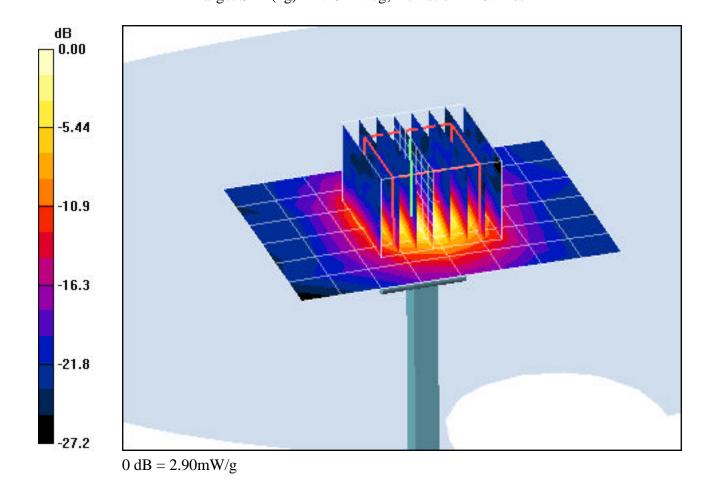
Sensor-Surface: 3mm (Mechanical Surface Detection) Electronics: DAE3 Sn455; Calibrated: 6/23/2004 Phantom: SAM Main; Type: SAM 4.0; Serial: TP:1197

Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

#### **5800MHz Dipole Validation**

**Area Scan (7x9x1):** Measurement grid: dx=10mm, dy=10mm **Zoom Scan (8x8x8)/Cube 0:** Measurement grid: dx=4.3mm, dy=4.3mm, dz=3mm

Input Power = 14.0 dBm (25 mW) **SAR(1 g) = 2.11 mW/g; SAR(10 g) = 0.583 mW/g**Target SAR(1g) = 2.25 mW/g; Deviation = -6.22 %



## **APPENDIX D: PROBE CALIBRATION**

#### Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland



S Schweizerischer Kalibrierdienst
Service suisse d'étalonnage
Servizio svizzero di taratura
Swiss Calibration Service

Accredited by the Swiss Federal Office of Metrology and Accreditation The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Certificate No: EX3-3550 Oct04

Accreditation No.: SCS 108

Client

**PC Test** 

**CALIBRATION CERTIFICATE** 

Object EX3DV4 - SN:3550

Calibration procedure(s) QA CAL-01.v5 and QA CAL-12.v4

Calibration procedure for dosimetric E-field probes

Calibration date: October 26, 2004

Condition of the calibrated item In Tolerance

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID#	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	5-May-04 (METAS, No. 251-00388)	May-05
Power sensor E4412A	MY41495277	5-May-04 (METAS, No. 251-00388)	May-05
Reference 3 dB Attenuator	SN: S5054 (3c)	3-Apr-03 (METAS, No. 251-00403)	Aug-05
Reference 20 dB Attenuator	SN: S5086 (20b)	3-May-04 (METAS, No. 251-00389)	May-05
Reference 30 dB Attenuator	SN: S5129 (30b)	3-Apr-03 (METAS, No. 251-00404)	Aug-05
Reference Probe ES3DV2	SN:3013	8-Jan-04 (SPEAG, No. ES3-3013_Jan04)	Jan-05
DAE4	SN: 617	26-May-04 (SPEAG, No. DAE4-617_May04)	May-05
Secondary Standards	ID#	Check Date (in house)	Scheduled Check
Power sensor HP 8481A	MY41092180	18-Sep-02 (SPEAG, in house check Oct-03)	In house check: Oct 05
RF generator HP 8648C	US3642U01700	4-Aug-99 (SPEAG, in house check Dec-03)	In house check: Dec-05
Network Analyzer HP 8753E	US37390585	18-Oct-01 (SPEAG, in house check Nov-03)	In house check: Nov 04
	Name	Function	Signature
Calibrated by:	Katja Pokovic	Technical Manager	20 - 11 A
			Polipi : Kritz
		and the second second second, to be about the second second second second second second second second second s	
Approved by:	Niels Kuster	Quality Manager / /	1 1100
		/ /	/./WW
1			

Issued: October 30, 2004

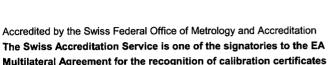
This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Certificate No: EX3-3550\_Oct04 Page 1 of 10

#### **Calibration Laboratory of**

Schmid & Partner **Engineering AG** 

Zeughausstrasse 43, 8004 Zurich, Switzerland





Schweizerischer Kalibrierdienst S Service suisse d'étalonnage C Servizio svizzero di taratura Swiss Calibration Service

Accreditation No.: SCS 108

#### Glossary:

tissue simulating liquid TSL NORMx,y,z sensitivity in free space

sensitivity in TSL / NORMx,y,z ConF

**DCP** diode compression point φ rotation around probe axis Polarization φ

3 rotation around an axis that is in the plane normal to probe axis (at Polarization 9

measurement center), i.e.,  $\vartheta = 0$  is normal to probe axis

#### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001

#### Methods Applied and Interpretation of Parameters:

- NORMx, y, z: Assessed for E-field polarization  $\vartheta = 0$  (f  $\leq 900$  MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx.v.z does not effect the  $E^2$ -field uncertainty inside TSL (see below ConvF).
- $NORM(f)x,y,z = NORMx,y,z * frequency_response$  (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCPx.v.z: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z \* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY 4.3 B17 and higher which allows extending the validity from  $\pm$  50 MHz to  $\pm$  100 MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

Certificate No: EX3-3550\_Oct04 Page 2 of 10 EX3DV4 SN:3550 October 26, 2004

# Probe EX3DV4

SN:3550

Manufactured:

Calibrated:

May 19, 2004

October 26, 2004

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

October 26, 2004 EX3DV4 SN:3550

#### DASY - Parameters of Probe: EX3DV4 SN:3550

Diode Compression<sup>B</sup>

NormX	<b>0.47</b> ± 9.9%	$\mu V/(V/m)^2$	DCP X	<b>92</b> mV
NormY	<b>0.49</b> ± 9.9%	$\mu V/(V/m)^2$	DCP Y	<b>92</b> mV
NormZ	$0.47 \pm 9.9\%$	$\mu$ V/(V/m) <sup>2</sup>	DCP Z	<b>92</b> mV

Sensitivity in Tissue Simulating Liquid (Conversion Factors)

Please see Page 8.

#### **Boundary Effect**

**TSL** 

900 MHz Typical SAR gradient: 5 % per mm

Sensor Center t	2.0 mm	3.0 mm	
SAR <sub>be</sub> [%]	Without Correction Algorithm	3.8	1.1
SAR <sub>be</sub> [%]	With Correction Algorithm	0.1	0.4

TSL 1750 MHz Typical SAR gradient: 10 % per mm

Sensor Center to	2.0 mm	3.0 mm	
SAR <sub>be</sub> [%]	Without Correction Algorithm	4.8	2.4
SAR <sub>be</sub> [%]	With Correction Algorithm	0.8	0.9

#### Sensor Offset

Probe Tip to Sensor Center

1.0 mm

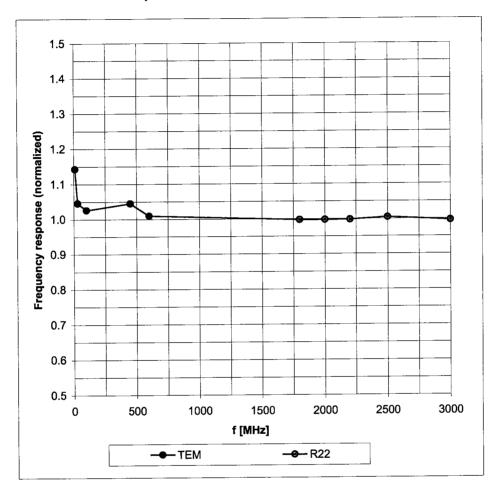
The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

<sup>&</sup>lt;sup>A</sup> The uncertainties of NormX,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Page 8).

<sup>&</sup>lt;sup>B</sup> Numerical linearization parameter: uncertainty not required.

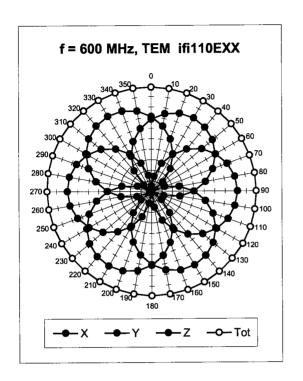
# Frequency Response of E-Field

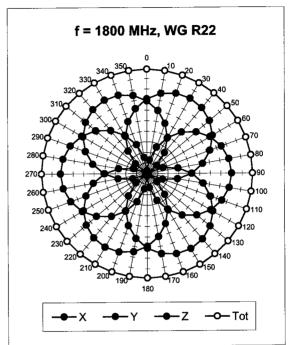
(TEM-Cell:ifi110 EXX, Waveguide: R22)

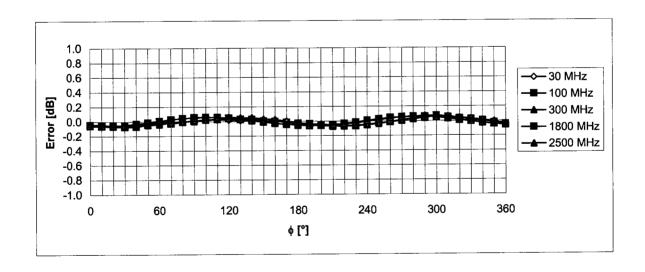


Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

Receiving Pattern ( $\phi$ ),  $\vartheta = 0^{\circ}$ 



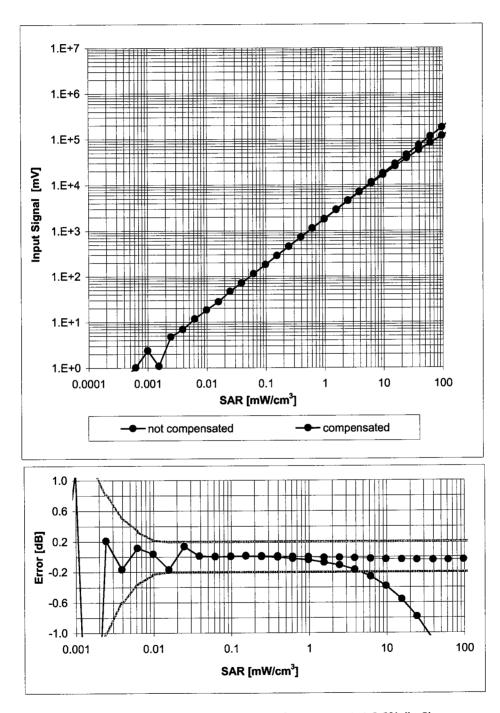




Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

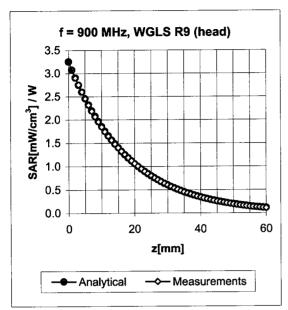
# Dynamic Range f(SAR<sub>head</sub>)

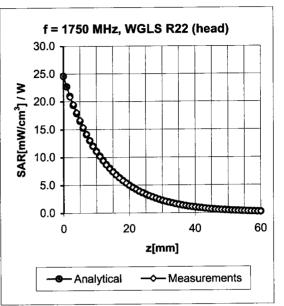
(Waveguide R22, f = 1800 MHz)



Uncertainty of Linearity Assessment: ± 0.6% (k=2)

### **Conversion Factor Assessment**





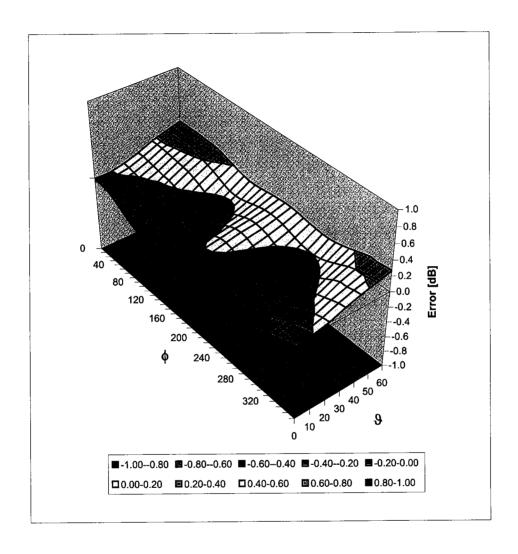
f [MHz]	Validity [MHz] <sup>C</sup>	TSL	Permittivity	Conductivity	Alpha	Depth	ConvF Uncertainty
450	± 50 / ± 100	Head	43.5 ± 5%	0.87 ± 5%	-0.03	2.33	8.28 ± 13.3% (k=2)
835	± 50 / ± 100	Head	41.5 ± 5%	0.90 ± 5%	0.92	0.65	8.12 ± 11.0% (k=2)
900	± 50 / ± 100	Head	41.5 ± 5%	0.97 ± 5%	0.97	0.62	7.76 ± 11.0% (k=2)
1640	± 50 / ± 100	Head	40.3 ± 5%	1.29 ± 5%	0.69	0.73	7.28 ± 11.0% (k=2)
1750	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.64	0.80	6.97 ± 11.0% (k=2)
1900	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.54	0.96	6.75 ± 11.0% (k=2)
1950	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.57	0.88	6.62 ± 11.0% (k=2)
2450	± 50 / ± 100	Head	39.2 ± 5%	1.80 ± 5%	0.61	0.78	6.33 ± 11.8% (k=2)
450	± 50 / ± 100	Body	56.7 ± 5%	0.94 ± 5%	-0.08	2.62	8.05 ± 13.3% (k=2)
835	± 50 / ± 100	Body	55.2 ± 5%	0.97 ± 5%	0.98	0.65	7.99 ± 11.0% (k=2)
900	± 50 / ± 100	Body	55.0 ± 5%	1.05 ± 5%	1.01	0.63	7.75 ± 11.0% (k=2)
1640	± 50 / ± 100	Body	53.8 ± 5%	1.40 ± 5%	0.58	0.99	6.82 ± 11.0% (k=2)
1750	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.50	1.16	6.48 ± 11.0% (k=2)
1900	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.47	1.32	6.35 ± 11.0% (k=2)
1950	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.64	0.83	6.53 ± 11.0% (k=2)
2450	± 50 / ± 100	Body	52.7 ± 5%	1.95 ± 5%	0.83	0.64	6.27 ± 11.8% (k=2)

 $<sup>^{\</sup>rm c}$  The validity of  $\pm$  100 MHz only applies for DASY 4.3 B17 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

EX3DV4 SN:3550 October 26, 2004

# **Deviation from Isotropy in HSL**

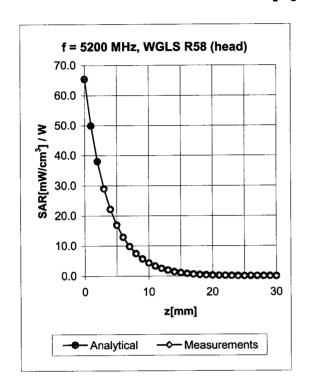
Error ( $\phi$ ,  $\vartheta$ ), f = 900 MHz

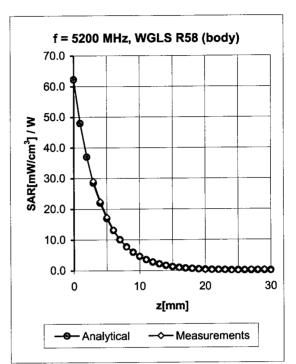


Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

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# **Appendix**<sup>D</sup>





f [MHz]D Validity [MHz]		TSL	Permittivity	Conductivity	Alpha	Depth	ConvF Uncertainty
5200	± 50	Head	36.0 ± 5%	4.76 ± 5%	0.45	1.80	4.17 ± 13.6% (k=2)
5500	± 50	Head	35.6 ± 5%	4.96 ± 5%	0.47	1.80	3.77 ± 13.6% (k=2)
5800	± 50	Head	35.3 ± 5%	5.27 ± 5%	0.48	1.80	3.74 ± 13.6% (k=2)
5200	± 50	Body	49.0 ± 5%	5.30 ± 5%	0.50	1.90	3.72 ± 13.6% (k=2)
5500	± 50	Body	48.6 ± 5%	5.65 ± 5%	0.50	1.95	3.47 ± 13.6% (k=2)
5800	± 50	Body	48.2 ± 5%	6.00 ± 5%	0.50	1.95	3.48 ± 13.6% (k=2)

<sup>&</sup>lt;sup>D</sup> Accreditation for ConvF assessment above 3000 MHz is currently applied for. Accreditation is expected at the beginning of 2005.