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TEST REPORT (SAR EVALUATION)

APPLICANT	:	Matsushita Electric Industrial Co., Ltd. Panasonic System Solutions Company, Sound Engineer Group, Security & Sound Systems Business Unit
ADDRESS	:	4-3-1 Tsunashima-higashi, Kohoku-ku, Yokohama City 223-8639, Japan
PRODUCTS	:	Order Taker
MODEL NO.	:	WX-T3020
SERIAL NO.	:	--
FCC ID	:	ACJ9TAWX-T3020
IC	:	216A-T3020
TEST STANDARD	:	FCC/OET Bulletin 65 Supplement C (Edition 01-01) RSS-102 Issue 2 (November 2005)
TESTING LOCATION	:	Japan Quality Assurance Organization KITA-KANSAI Testing Center 1-7-7, Ishimaru, Minoh-shi, Osaka 562-0027, Japan
TEST RESULTS	:	Passed
DATE OF TEST	:	August 4, 2008

This report must not used by the client to claim product endorsement by NVLAP or NIST or any agency of the U.S. Government.

NVLAP LAB CODE 200191-0

Yuichi Fukumoto
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- The measurement values stated in Test Report was made with traceable to National Institute of Advanced Industrial Science and Technology (AIST) of Japan, National Institute of Information and Communications Technology (NICT) of Japan , and Laboratory for EMF and Microwave Electronics at the Swiss Federal Institute of Technology (ETH) in Zürich, Switzerland.
- The applicable standard, testing condition and testing method which were used for the tests are based on the request of the applicant.
- The test results presented in this report relate only to the offered test sample.
- The contents of this test report cannot be used for the purposes, such as advertisement for consumers.
- This test report shall not be reproduced except in full without the written approval of JQA.

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DEFINITIONS FOR ABBREVIATION AND SYMBOLS USED IN THIS TEST REPORT

EUT	: Equipment Under Test	EMC	: Electromagnetic Compatibility
AE	: Associated Equipment	EMI	: Electromagnetic Interference
N/A	: Not Applicable	EMS	: Electromagnetic Susceptibility
N/T	: Not Tested	SAR	: Specific Absorption Rate

☒ - indicates that the listed condition, standard or equipment is applicable for this report.
☐ - indicates that the listed condition, standard or equipment is not applicable for this report.

Documentation

1 Test Regulation

Applied Standard : FCC/OET Bulletin 65 Supplement C (Edition 01-01)
RSS-102 Issue 2 (November 2005)

Test Procedure : FCC/OET Bulletin 65 Supplement C (Edition 01-01)
IEEE Std.1528–2003

Exposure Limits : ANSI/IEEE Std. C95.1, 1999 Edition

2 Test Location

KITA-KANSAI Testing Center
7-7, Ishimaru, 1-chome, Minoh-shi, Osaka, 562-0027, Japan
KAMEOKA EMC Branch
9-1, Ozaki, Inukanno, Nishibetsuin-cho, Kameoka-shi, Kyoto, 621-0126, Japan

3 Recognition of Test Laboratory

JQA KITA-KANSAI Testing Center Testing Department EMC Division is accredited under ISO/IEC 17025 by following accreditation bodies and the test facility of Testing Division is registered by the following bodies.

VLAC Code : VLAC-001-2 (Effective through : April 3, 2010)
NVLAP Lab Code : 200191-0 (Effective through : June 30, 2009)
BSMI Recognition No. : SL2-IS-E-6006, SL2-IN-E-6006, SL2-AI-E-6006
(Effective through : September 14, 2010)

VCCI Registration No. : R-008, R-1117, C-006, C-007, C-1674, C-2143, T-1418, T-1419
(Effective through : April 3, 2010)
IC Registration No. : IC 4125-1, IC 6217-1, IC 6217-2 (Effective through : November 16, 2008)

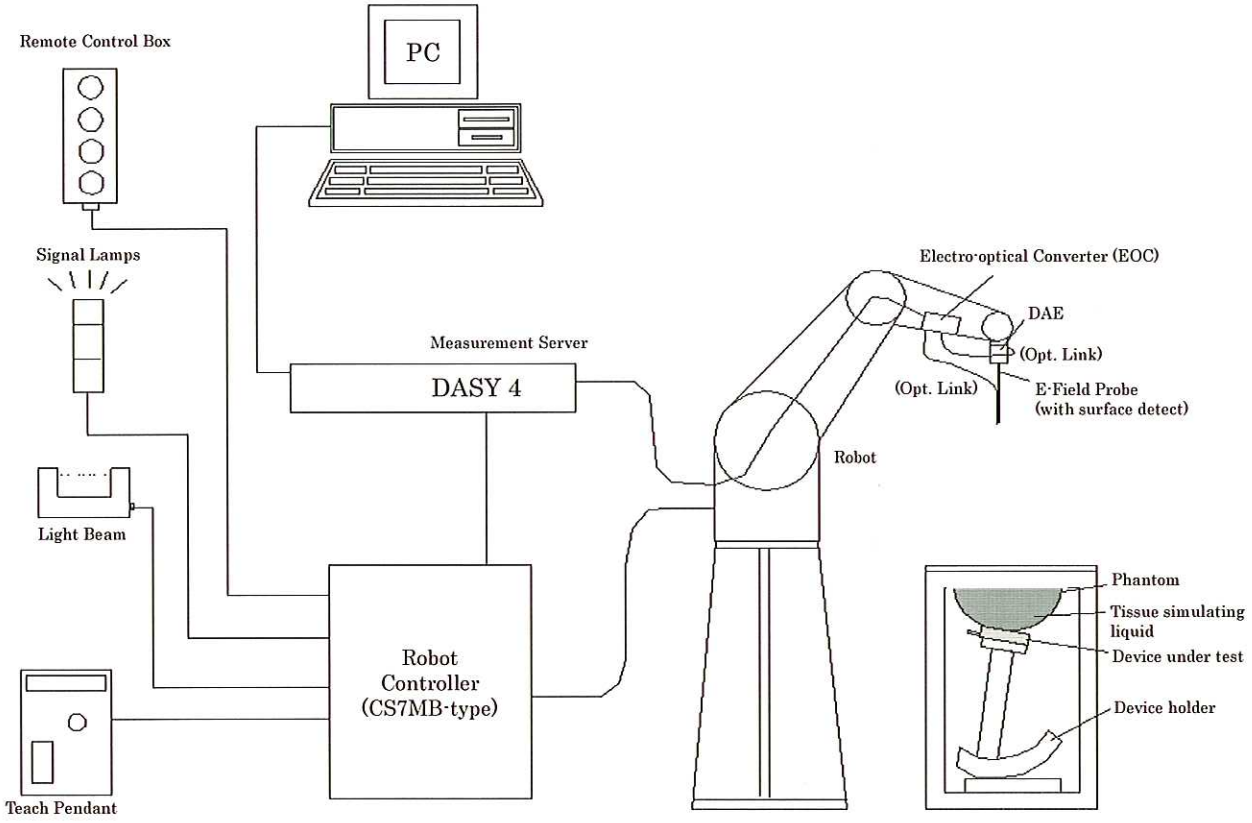
Accredited as conformity assessment body for Japan electrical appliances and material law by METI.
(Effective through : February 22, 2010)

4 Description of the Equipment Under Test

1.	Manufacturer	:	Matsushita Electric Industrial Co., Ltd. Panasonic System Solutions Company, Sound Engineer Group, Security & Sound Systems Business Unit 4-3-1 Tsunashima-higashi, Kohoku-ku, Yokohama City 223-8639, Japan
2.	Products	:	Order Taker
3.	Model No.	:	WX-T3020
4.	Serial No.	:	--
5.	Product Type	:	Pre-production
6.	Date of Manufacture	:	--
7.	Transmitting Frequency	:	1921.5 MHz – 1928.4 MHz
8.	Battery Option	:	Lithium-ion Battery Pack (1100mAh)
9.	Power Rating	:	3.7VDC
10.	EUT Grounding	:	None
11.	Device Category	:	Portable Device (§2.1093)
12.	Exposure Category	:	General Population/Uncontrolled Exposure
13.	FCC Rule Part(s)	:	15(D)
14.	EUT Authorization	:	Certification
15.	Received Date of EUT	:	August 1, 2008

5 Measurement System Diagram

These measurements are performed using the DASY4 automated dosimetric assessment system (manufactured by Schmid & Partner Engineering AG (SPEAG) in Zürich, Switzerland). It consists of high precision robotics system, cell controller system, DASY4 measurement server, personal computer with DASY4 software, data acquisition electronic (DAE) circuit, the Electro-optical converter (EOC), near-field probe, and the twin SAM phantom containing the equivalent tissue. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF).
The Robot is connected to the cell controller to allow software manipulation of the robot. The DAE is connected to the EOC. The DAE performs the signal amplification, signal multiplexing, A/D conversion, offset measurements, mechanical surface detection, collision detection, etc. The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the DASY4 measurement server.



6 System Components

6.1 Probe Specification

Construction : Symmetrical design with triangular core
Built-in optical fiber for surface detection system
Built-in shielding against static changes

Calibration : In air form 10 MHz to 2.5 GHz
In head tissue simulating liquid (HSL) and
muscle tissue simulating liquid
900 MHz (accuracy ± 11.0%; k=2)
1810 MHz (accuracy ± 11.0%; k=2)
1950 MHz (accuracy ± 11.0%; k=2)
2450 MHz (accuracy ± 11.8%; k=2)

Frequency : 10 MHz to 3 GHz (dosimetry);
Linearity: ±0.2 dB (30 MHz to 3 GHz)

Directivity : ± 0.2 dB in HSL (rotation around probe axis)
± 0.4 dB in HSL (rotation normal probe axis)

Dynamic Range : 5 μW/g to >100 mW/g; Linearity: ± 0.2 dB

Surface Detection : ± 0.2 mm repeatability in air and clear liquids over diffuse reflecting surfaces

Dimensions : Overall length 330 mm
Tip length 16 mm
Body diameter 12 mm
Tip diameter 6.8 mm
Distance from probe tip to dipole centers 2.7 mm

6.2 Twin SAM Phantom

The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528-2003, CENELEC 50361 and IEC 62209-1. It enables the dosimetric evaluation of left and right head phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.

Shell Thickness : 2 ± 0.2 mm
Filling Volume : Volume Approx. 25 liters
Dimensions : 810 × 1000 × 500 mm (H × L × W)

6.3 Mounting Device for Transmitters

The Mounting Device enables the rotation of the mounted transmitter in spherical coordinates, whereby the rotation point is the ear opening. The devices can be easily and accurately positioned according to IEC, IEEE, CENELEC, FCC or other specifications. The device holder can be locked at different phantom locations (left head, right head, flat phantom).

6.4 Typical Composition of Ingredients for Liquid Tissue

Ingredients (% by weight)	Frequency (MHz)					
	835		1900		2450	
	Head	Body	Head	Body	Head	Body
Water	41.45	52.40	54.90	40.40	62.70	73.20
Salt (NaCl)	1.45	1.40	0.18	0.50	0.50	0.04
Sugar	56.00	45.00	0.00	58.00	0.00	0.00
HEC	1.00	1.00	0.00	1.00	0.00	0.00
Bactericide	0.10	0.10	0.00	0.10	0.00	0.00
Triton X-100	0.00	0.00	0.00	0.00	36.80	0.00
DGBE	0.00	0.00	44.92	0.00	0.00	26.70

Salt : 99+% Pure Sodium Chloride
Sugar : 98+% Pure Sucrose
Water : De-ionized, 16 MΩ+ resistivity
HEC : Hydroxyethyl Cellulose
DGBE : 99+% Di (ethylene glycol) butyl ether, [2-(2-butoxyethoxy)ethanol]
Triton X-100 (ultra pure) : Polyethylene glycol mono [4-(1,1,3,3-tetramethylbuthyl)phenyl]ether

The composition of ingredients is according to FCC/OET Bulletin 65 Supplement C.

7 Measurement Process

Area Scan for Maximum Search :

The SAR distribution at the exposed side of the head was measured at a distance of 3.9 mm from the inner surface of the shell. The area covered the entire dimension of the head and the horizontal grid spacing was 15 mm × 15 mm. The evaluation on the measured area scan gives the interpolated maximum (hot spot) of the measured area.

Cube Scan for Spatial Peak SAR Evaluation :

The 1g and 10g peak evaluations were available for the predefined cube 5×5×7 scans. The grid spacing was 8 mm × 8 mm × 5 mm. The first procedure is an extrapolation to get the points between the lowest measured plane and the surface. The next step uses 3D interpolation to get all points within the measured volume in a 1mm grid (35000 points). In the last step, a 1g cube is placed numerically into the volume and its averaged SAR is calculated. This cube is moved around until the highest averaged SAR is found. This last procedure is repeated for a 10g cube. If the highest SAR is found at the edge of the measured volume, the system will issue a warning: higher SAR values might be found outside of the measured volume. In that case the cube measurement can be repeated, using the new interpolated maximum as the center.

Extrapolation :

The extrapolation is based on a least square algorithm. Through the points in the first 3 cm in all z-axis, polynomials of order four are calculated. This polynomial is then used to evaluate the points between the surface and the probe tip. The points, calculated from the surface, have a distance of 1 mm from one another.

Interpolation :

The maximum interpolated value is searched with a straightforward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1g or 10g) are computed by the 3D spline algorithm. The 3D spline is composed of three one-dimensional splines with the "Not a knot" –condition (x, y and z –directions). The volume is integrated with the trapezoidal algorithm.

8 Measurement Uncertainties

Uncertainty Component	Tol. (± %)	Prob. Dist.	Div.	c_i (1g)	c_i (10g)	Std. Unc. (± %)		v_i
						1g	10g	
Measurement System								
Probe calibration	5.9	N	1	1	1	5.9	5.9	∞
Axial isotropy	4.7	R	√3	0.7	0.7	1.9	1.9	∞
Hemispherical isotropy	9.6	R	√3	0.7	0.7	3.9	3.9	∞
Boundary effect	1.0	R	√3	1	1	0.6	0.6	∞
Linearity	4.7	R	√3	1	1	2.7	2.7	∞
System detection limits	1.0	R	√3	1	1	0.6	0.6	∞
Readout electronics	0.4	N	1	1	1	0.4	0.4	∞
Response time	0.0	R	√3	1	1	0.0	0.0	∞
Integration time	2.6	R	√3	1	1	1.5	1.5	∞
RF ambient conditions – noise	3.0	R	√3	1	1	1.7	1.7	∞
RF ambient conditions – reflections	3.0	R	√3	1	1	1.7	1.7	∞
Probe positioner mechanical tolerance	0.4	R	√3	1	1	0.2	0.2	∞
Probe positioning with respect to phantom shell	2.9	R	√3	1	1	1.7	1.7	∞
Extrapolation, interpolation and integration algorithms for max. SAR evaluation	1.0	R	√3	1	1	0.6	0.6	∞
Test Sample Related								
Test sample positioning	3.4	N	1	1	1	3.4	3.4	23
Device holder uncertainty	2.9	N	1	1	1	2.9	2.9	5
Output power variation – SAR drift measurement	5.0	R	√3	1	1	2.9	2.9	∞
Phantom and Tissue Parameters								
Phantom uncertainty	4.0	R	√3	1	1	2.3	2.3	∞
Liquid conductivity – deviation from target	5.0	R	√3	0.64	0.43	1.8	1.2	∞
Liquid Conductivity – measurement uncertainty	3.2	N	1	0.64	0.43	2.0	1.4	5
Liquid Permittivity – deviation from target	5.0	R	√3	0.6	0.49	1.7	1.4	∞
Liquid Permittivity – measurement uncertainty	3.0	N	1	0.6	0.49	1.8	1.5	5
Combined Standard Uncertainty		RSS				11.0	10.7	
Expanded Uncertainty (95% Confidence Interval)		k=2				**22.0**	**21.4**	

NOTES
1. Tol. : tolerance in influence quantity
2. Prob. Dist. : probability distributions
3. N, R : normal, rectanglar
4. Div. : divisor used to obtain standard uncertainty
5. c_i : sensitivity coefficient
6. Std. Unc. : standard uncertainty
7. Measurement uncertainties are according to IEEE Std. 1528 and IEC 62209-1.