



# Poseidon Pro II Black

## User Manual

# Contents

**Thank you very much for choosing this product. When you need to know more about this product than what is found in this user manual, please visit our official website [www.idea-fly.com](http://www.idea-fly.com) or contact your local dealer. Any subsequent updates to the user manual will be found on this website.**

**Before using this product, please read this manual carefully and ensure you understand it. Once you use this drone, you will be deemed to have read & accepted the contents of this manual.**

**Please strictly follow the user manual to install and use the product. In the event of improper installation and use, IDFTECH will not be liable for damages and compensation.**

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# Disclaimer

These warnings and safety precautions are very important; please read the following carefully and follow the instructions in this operating manual to ensure safety.

## Propeller safety:

The Poseidon pro II Black's propeller is very strong and very sharp & is made from carbon fiber. This material gives the propeller high strength and improves the flight of the quadcopter.

- When updating the firmware of your flight controller or if the aircraft is experiencing any issues, or you are doing calibrations please make sure the propellers are removed from the aircraft to prevent the propeller from injuring you and others.
- When one of the propellers is damaged, do not fly, as the damaged propeller can cause the aircraft to not perform as expected and at worst could possibly lead to the drone being unmanageable, which can be very dangerous.
- Make sure the propellers are installed in the correct order and that the propeller retaining clips and screws are in place.

## Precautions:

- This quadcopter can be extremely dangerous and cause personal injury. Be careful when flying and operating it. Please follow the contents of this manual and comply with relevant laws and regulations when flying.
- Before each flight, please ensure that all parts of the aircraft are properly installed and that the order of rotation of the four motors is in accordance with the rotation sequence in this manual.  
If the propellers are installed incorrectly or are in the wrong direction for the motor rotation, the aircraft will NOT fly, and it may cause damage to the aircraft.
- When flying, please fly in open areas away from people and animals, and make sure you are fully aware of different flight modes.
- The lithium batteries should be taken out of the aircraft after each flight. When not in use for a long time, the lithium batteries should be placed in a fireproof container to avoid accidents & should ONLY be stored at half-charge.
- When flying in GPS mode, if you find that the aircraft is flying unstable or uncontrollable please switch the flight mode to Attitude Mode (also called Stabilize mode) very quickly, to hopefully gain back full control of the aircraft to avoid accidents

## Items in box

Included in your box:

A



B



C



D



E



F



G



H



I



## Items in box

- Ⓐ Poseidon pro II Black drone X 1
- Ⓑ Remote X 1
- Ⓒ Balance charger X 1
- Ⓓ Bait drop + 4K camera & Single axis gimbal X 1
- Ⓔ 1355 propeller X 2 pairs
- Ⓕ 6S 8000 mAh high voltage battery X 1
- Ⓖ Digital battery capacity checker X 1
- Ⓗ USB flash drive X 1
- Ⓘ Carry case X 1

### Note:

The USB flash drive contains the Poseidon pro II Black drone training videos.

## Items in box

The remote control has been coded/paired with the receiver of the aircraft at the factory. It is not necessary to modify the settings of the remote control. Do not touch the fine-tuning buttons of each channel of the remote controller. Otherwise, the aircraft/remote controller will not work.

(The picture of remote control below in Mode 2/Factory Setting)



**Note:** When switching on the remote control, ensure the switches are set to the top position, otherwise the remote control will display a warning.

**IMPORTANT:** The FLIGHT MODE Switch should be set to "GPS Hover" for new Pilots at ALL Times during normal Flight (Please refer to the Flight Mode Section later in this Product Manual).

## Initial Setup

Pay attention to the RED Markings on the Drone to identify which is the front and the rear of the drone.



This chapter will guide you to familiarize and assemble the Poseidon pro II Black and to learn more about the flight characteristics of the Poseidon pro II Black . It is recommended that you read this chapter carefully and follow the steps in this section to prepare for the Poseidon pro II Black before flight. Improper installation may cause the Poseidon pro II Black to malfunction or damage the aircraft.

## Initial Setup

1. Be sure to calibrate the compass when you are flying for the first time or changing to a new flight area ;
2. When calibrating, please make sure that the surrounding area is relatively empty, away from strong magnetic environments, such as magnetic fields, high-voltage lines, parking lots, building areas with steel bar strengthening, cars etc.
3. Do not carry magnets or metal objects with you when calibrating, such as keys, mobile phones, etc.;
4. If there is a circle or hovering instability in the GPS hover mode during flight, please land immediately and refer to the above requirements for the environment (points 1-3) & calibrate compass.

First fit each of the two landing gear into the base of the Drone – one on each side of the drone. These should easily slide into the metal supports.

Don't worry about any slight movement as the legs will not come out.

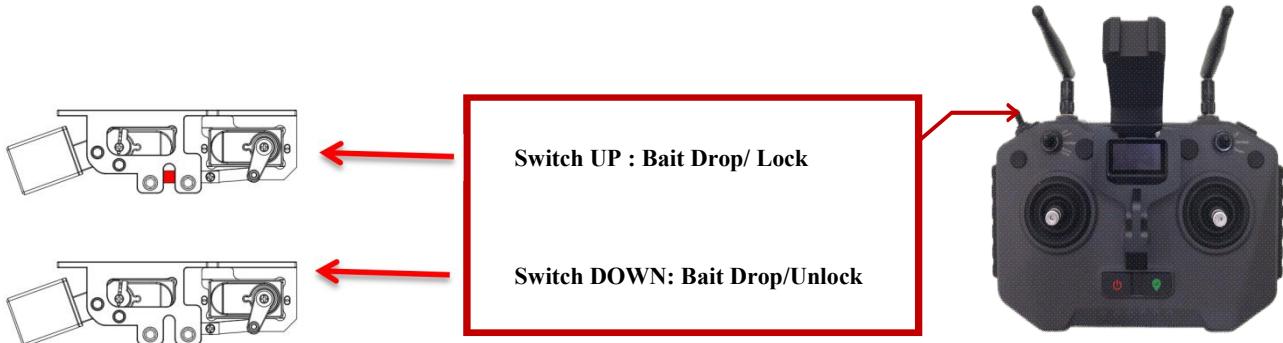
1. Ensure the drone is placed on a flat surface & Install a fully charged battery into the drone, then make sure that the battery cover is fully secured back down using the thumb screws.

**Note: Once the Battery Cable is Plugged in - make sure that the Battery Cable is tucked securely behind the battery to ensure it remains some distance away from the GPS Sensor on the LID, before attaching the LID.**

2. Make sure all switches are in the UP position & turn on the Remote Control switch. Then power on the drone using the large ON/OFF Switch on the Outside of the Drone. (IMPORTANT: Please DO NOT install propellers until after the drone has been calibrated and everything is normal)

**Note: Once the drone is powered on do not move it for 20 seconds to wait for the system to fully initialize.**

3. Operate the switch to confirm that the bait drop is working properly.



## LED Indicators

After following the above, the drone lights will then flash as in the below diagram. These lights are the ones located on the **UNDERSIDE** of the Drone.

NOTE:

It is recommended to check the drone telemetry (on your phone & APP Screen) including calibration status when you encounter an error

When the drone voltage is too low, (red LED flashing)

“Armed” below Means the Drone has just been Powered On – but not yet ready for take-off. It is recommended to ONLY Takeoff when lights are “SLOW BLUE FLASHING” and under GPS Hover Mode.

Please do not attempt to fly this drone on low battery (lower than 22V). The battery should always be fully charged.

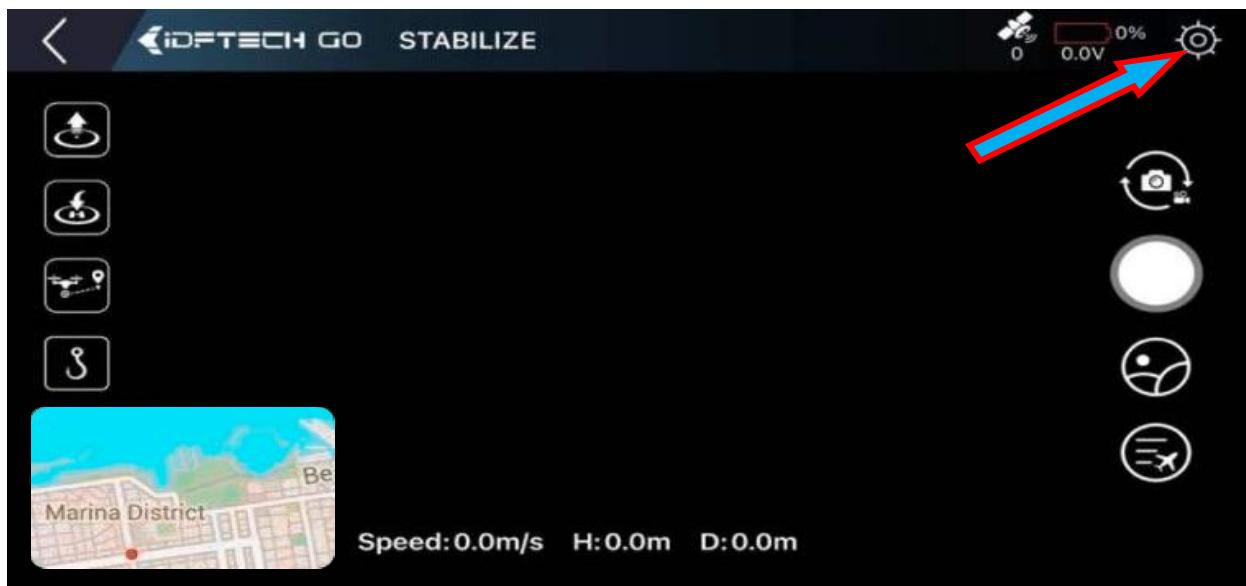
|                           |                         |       |       |       |       |       |       |       |       |       |       |       |
|---------------------------|-------------------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| Armed, No GPS             | Green light, fast flash | Green | Green | White |
| Armed, GPS                | Blue light, fast flash  | Blue  |
| Ready, No GPS             | Green light, slow flash | Green | White | Green |
| Ready, GPS                | Blue light, slow flash  | Blue  | White | Blue  |
| Low Battery               | Red light               | Red   |
| Flight Controller failure | Blue light              | Blue  |

## Compass calibration

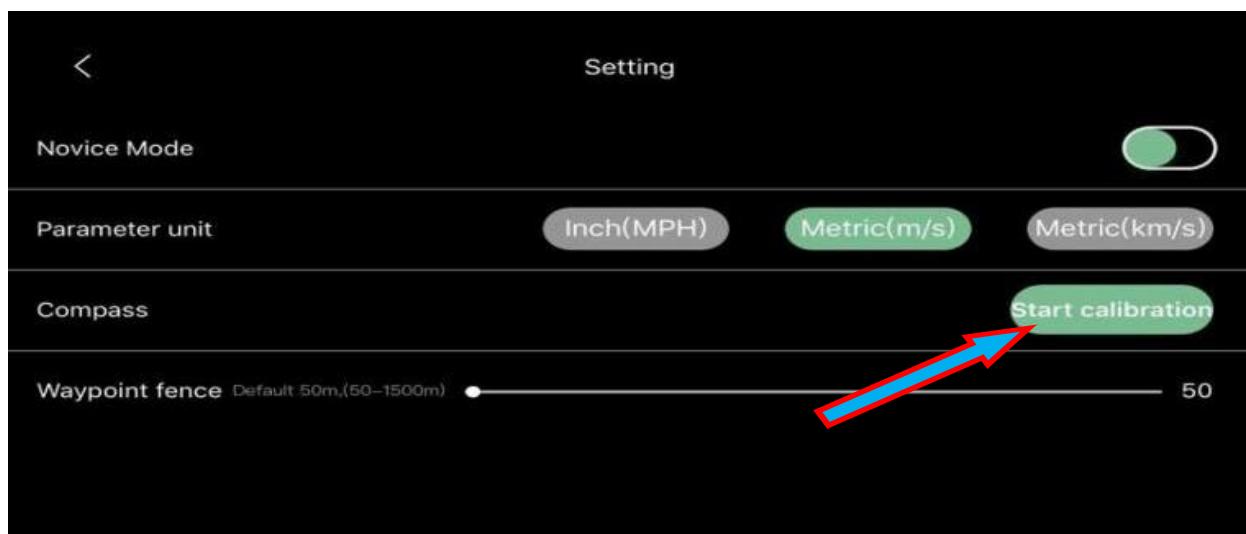
- 1) After confirming that the initialization of the drone is completed and the signal light is flashing normally (slow flashing BLUE Lights), perform the magnetic compass calibration
- 2) Open the main interface of the mobile APP and click the “Setting” icon, as shown by the **BLUE ARROW** in figure (A).

Click the “Start Calibration” button, as shown by the **BLUE ARROW** in figure (B), and click the start calibration icon to start the magnetic compass calibration.

As you begin to spin the drone – you will see a % Completion bar appear on the APP Screen. Once the bar reaches its 100% Mark – Please place the drone back on the flat ground & switch both the drone and remote control OFF.



(A)



(B)

## Compass calibration

3) The drone needs to be calibrated on six sides, by spinning the drone in a Clockwise Direction as shown below:



(A)



(B)



(C)



(D)



(E)



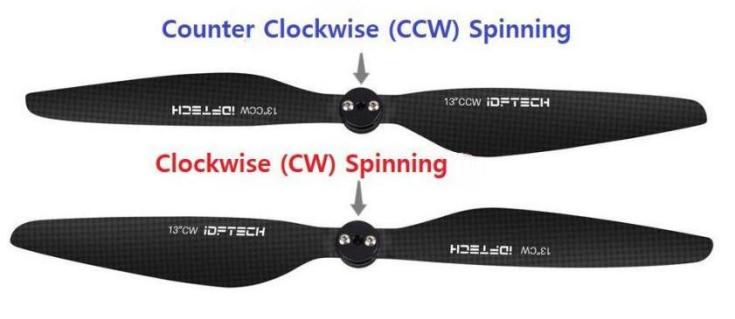
(F)

4) **IMPORTANT: After the Drone compass calibration is completed please switch off the Drone & then the Remote Control - and then back on, to lock in the calibration.**

## Compass calibration

5) **Installing the Propellers:** The second figure below shows the spin of the propellers while in flight.

To attach the propellers you need to reverse the Spin of the Propeller (shown in the image below) to screw it on correctly. Propellers need to only be hand tightened as they will self tighten while in flight.



## Starting and Stopping the Motors

1. **Starting/ARMING the Motors.** First keep the drone horizontally and still (15 seconds). Push the LEFT & RIGHT JOYSTICKS DOWN & IN to start the motors & the motors will go into idle (as shown in the diagram):



**Note:** In GPS mode, after starting/arming the drone, if the throttle is not pushed above 10%, the drone will automatically enter the disarm mode, and the propeller will automatically stop after about 5 seconds.

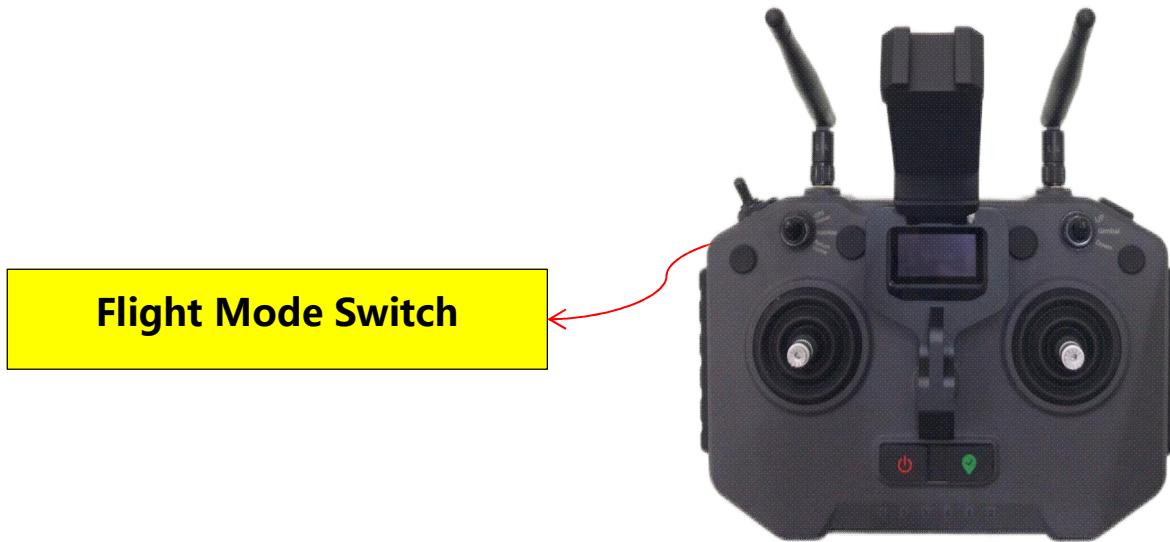
**Do NOT attempt to take off with any less than 13 Satellites, as shown on the Poseidon APP Main Screen at the top.**

2. **Shutting Down/DISARMING the Motors** Perform the following actions to stop the propellers and power down the drone. Push the LEFT & RIGHT JOYSTICKS DOWN & OUT to STOP the motors – as shown in the diagram below. (Note: Do not try the above actions while the drone is in flight)



# Flight Modes

The Flight Mode Switch on the Remote Control is very important to ensure safe flight at all times. Listed below are the THREE Flight Modes available on your new Poseidon. It is recommended that you familiarize yourself with all of them.



## GPS HOVER.

This is the Flight Mode that you will generally remain in while you are flying your drone. All Sensors are switched on and therefore your drone is easiest to fly in this mode.

## STABILIZE.

This Flight Mode Setting is also known as Attitude or Manual Mode. It Should only be used in Emergencies or by those experienced Pilots. This is because putting your Drone into Stabilize turns off several of the important sensors that the drone relies on for safe flight. For this reason, putting your drone into Stabilize mode allows it to drift with the wind and will NOT hold GPS Position.

Stabilize mode is often used by Fishing Drone Pilots if the Drone becomes unstable in flight or is not responding to Joystick controls. By Switching to this mode quickly might allow you to regain control of your Aircraft.

## RETURN TO HOME.

In “Return to Home” MODE, The Drone will go into Autopilot and Initiate a return to it’s original take-off point. This is very useful for a Fisherman as it means once you have dropped your bait, switching on this Flight Mode will allow the Poseidon to Automatically Fly home and land itself without fisherman intervention.

Note: “Return to Home” Mode should NOT be used in emergencies. If the Drone is experiencing issues while in flight – Please use the “Stabilize” Flight Mode instead.

## Drone Operation Controls

### 3. Main Operation using Joysticks (Mode 2/Factory Setting)

#### Remote control

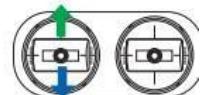
##### Drone

##### THROTTLE:

Takeoff-Lift / Descend

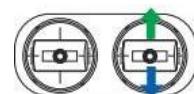


#### Joystick position



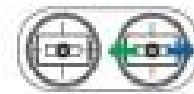
##### PITCH:

Forward / Backward



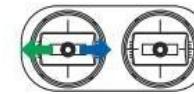
##### ROLL:

Fly left / Fly right



##### YAW:

Rotate Left  
A n d  
Rotate Right



# APP Download & Setup and Use

## 1. APP installation method (Android system):

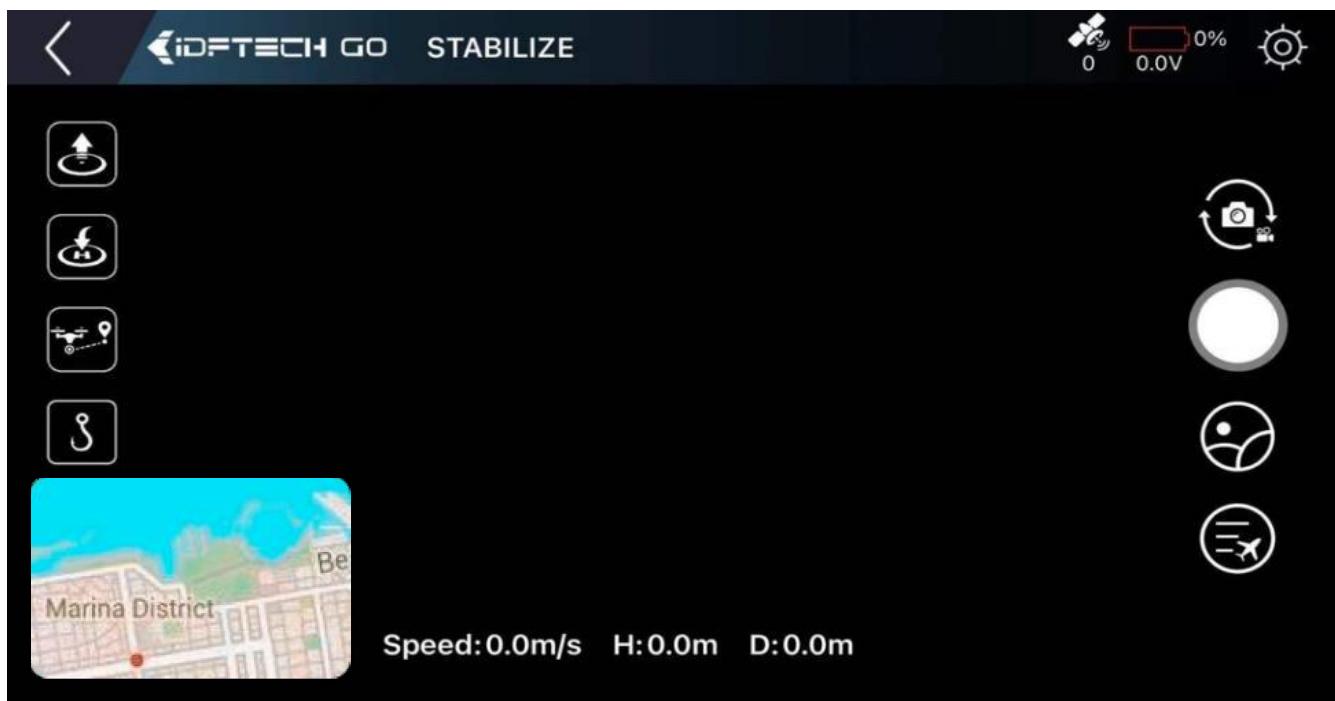
Enter IDFTECH GO in the Google PLAY Store on your Android phone to download the APP

## 2. APP installation method (IOS system):

Enter IDFTECH GO in the APP store of the iPhone to download the APP.

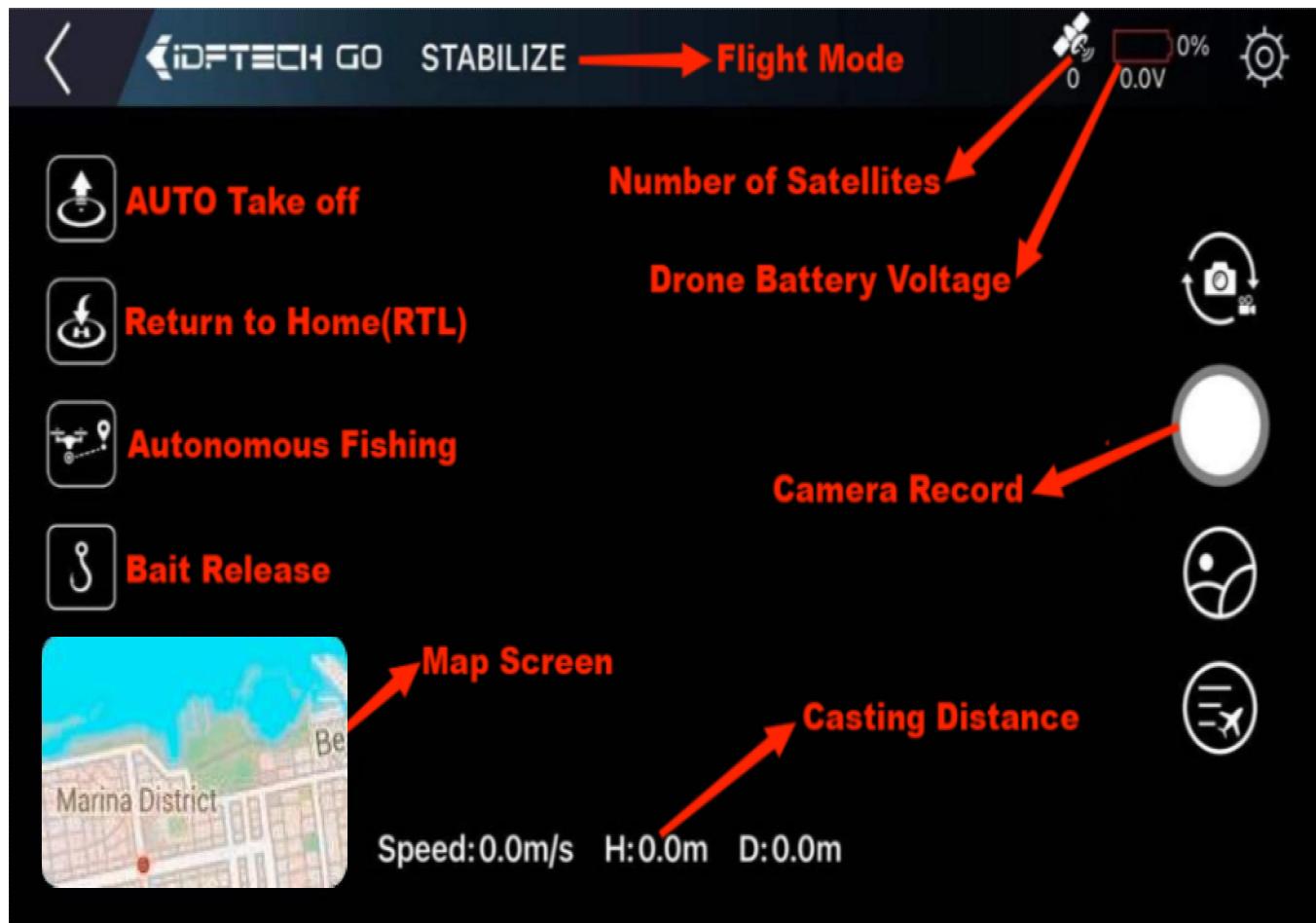
**Once Downloaded, (and with both the Phone and the Remote Control Switched on) you will need to connect the Phones WIFI to the Remote Control WIFI. In the WIFI Settings on your phone, Please search for the Poseidon Drone (you are looking for Idftech-XXXXXX-XXX) in your phone's WIFI List. Then the Password to connect the Remote Controller to the Phone is “0123456789”. ONCE you have paired the Rwmote control with the Phone's WIFI – THEN the IDFTECH GO APP can be started.**

**NOTE: ONLY connect the phone (and APP) to the remote control AFTER you have first paired the drone to the remote control**



## APP Setup and Use

KEY for each of the APP Onscreen ICONS (Both Android and Apple Phone)



It is possible to either use the controls on the APP OR the controls on the Remote Control.

### IMPORTANT:

Please pay close attention to the Important Telemetry Information displayed on the APP Screen as shown in the image above – in particular the Drone Battery Voltage, and the Number of Satellites, Please land your drone As soon as possible if the drone battery voltage gets below 22 volts.

## Charging the battery

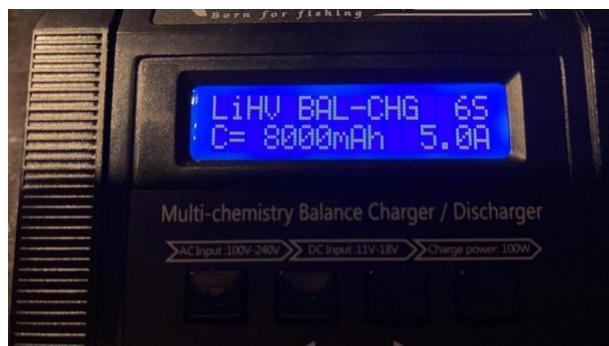
Charging steps for both the drone battery & remote control battery:

- 1) Connect the Battery Charger to a Wall Outlet.
- 2) Connect the Battery to the charger as shown in the image below and Power On the Charger.



- 3) Adjust the charger menu and set the correct parameters:

## Charging the battery



The Correct Settings (as shown in the image) should be:

**Battery type => LiHV (Note: the battery is a high-voltage battery)**

**Charging method => BAL-CHG (Balance Charge)**

**Number of battery cells for this 22.8V Battery => 6S**

**Battery Capacity = 8000 mAh Battery**

**Charging current => Recommended to set charging 5.0A or Less**

After confirming that the settings are correct, press and hold "START/ENTER" for more than 3 seconds to automatically start charging

- 4) After the battery is fully charged, disconnect the battery from the charger at this time;

# Technical Parameter

|                                   |                                     |
|-----------------------------------|-------------------------------------|
| flight control                    | IDF-9                               |
| Packing size( carton packaging)   | 56*46*18cm                          |
| Image transmission distance       | 2000m                               |
| Diagonal size (without propeller) | 480mm                               |
| Propeller blade size              | 1355                                |
| Motor mode                        | 4218                                |
| ESC parameters                    | 40A                                 |
| Maximum rising speed              | 6m/s                                |
| Maximum falling speed             | 4.5m/s                              |
| Maximum horizontal flight speed   | 18m/s                               |
| Maximum tilt angle                | 35°                                 |
| Working temperature               | -40°C--85°C                         |
| Satellite positioning module      | UBX-M8030-KT GPS / GLONASS receiver |
| Hover accuracy                    | Vertical +0.8m. horizontal+2. 5m    |
| Maximum wind speed level          | 25+ knots                           |
| Maximum load                      | 2.8KG (max)                         |
| Flight time(No load)              | 30min                               |
| Flight time( Load 1kg)            | 22min                               |
| Flight time( Load 2.5kg)          | 9.5min                              |
| Camera parameters                 | 4K                                  |

For more information please contact your local dealer or visit Website:

[www.idea-fly.com](http://www.idea-fly.com)

This manual is subject to update or change without notice!

Please visit the website above for the latest and most updated information.

## FCC Warning

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

(1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

NOTE 1: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

NOTE 2: Any changes or modifications to this unit not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

## RF Exposure Statement

To maintain compliance with FCC'S RF Exposure guidelines, This equipment should be installed and operated with minimum distance of 20cm between the radiator and your body. This device and its antenna(s) must not be co-located or operation in conjunction with any other antenna or transmitter.