
SAR Test Report

Report No.: AGC02787240505FH01

FCC ID : 2BGBVBTOKWRC

APPLICATION PURPOSE : Original Equipment

PRODUCT DESIGNATION : Digital radio system

BRAND NAME : N/A

MODEL NAME : TKO Wireless Remote Controller

APPLICANT : The Kinetic Option Pte. Ltd.

DATE OF ISSUE : 18 Jun.2024

STANDARD(S) : IEEE Std. 1528:2013
FCC 47 CFR Part 2§2.1093
IEEE Std C95.1™-2005

REPORT VERSION : V1.0

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Report Revise Record

| Report Version | Revise Time | Issued Date | Valid Version | Notes |
|----------------|-------------|-------------|---------------|-----------------|
| V1.0 | / | 18 Jun.2024 | Valid | Initial Release |

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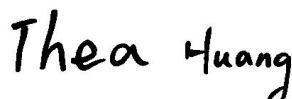
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| Test Report | |
|------------------------------|-------------------------------------------------------------------------------------------|
| Applicant Name | The Kinetic Option Pte. Ltd. |
| Applicant Address | 110 Lorong 23 Geylang #02-01 Singapore, 388410 |
| Manufacturer Name | FrSky Electronic Co., Ltd. |
| Manufacturer Address | F-4, Building C, Zhongxiu Technology Park, No.3 Yuanxi Road, Wuxi, 214125, Jiangsu, China |
| Factory Name | FrSky Electronic Co., Ltd. |
| Factory Address | F-4, Building C, Zhongxiu Technology Park, No.3 Yuanxi Road, Wuxi, 214125, Jiangsu, China |
| Product Designation | Digital radio system |
| Brand Name | N/A |
| Model Name | TKO Wireless Remote Controller |
| Different Description | N/A |
| EUT Voltage | Rated Voltage: 3.7V Charge Limit Voltage: 4.2V Capacity: 1410mAh |
| Applicable Standard | IEEE Std. 1528:2013 FCC 47 CFR Part 2§2.1093 IEEE Std C95.1™-2005 |
| Date of receipt of test item | 30 May.2024 |
| Test Date | 30 May.2024 |
| Report Template | AGCRT-US-2.4G/SAR (2021-04-20) |

Note: The results of testing in this report apply to the product/system which was tested only.

Prepared By



Thea Huang
(Project Engineer)

18 Jun.2024

Reviewed By



Calvin Liu
(Reviewer)

18 Jun.2024

Approved By



Max Zhang
(Authorized Officer)

18 Jun.2024

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1. SUMMARY OF MAXIMUM SAR VALUE

The maximum results of Specific Absorption Rate (SAR) found during testing for EUT are as follows:

| Frequency Band | Highest Reported 1g-SAR(W/kg) | SAR Test Limit (W/kg) |
|------------------------|--------------------------------|-----------------------|
| | Body-worn(with 0mm separation) | |
| 2.4G | 0.064 | 1.6 |
| SAR Test Result | PASS | |

This device is compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (1.6W/kg) specified in IEEE Std. 1528:2013; FCC 47CFR § 2.1093; IEEE/ANSI C95.1:2005 and the following specific FCC Test Procedures:

- KDB 447498 D01 General RF Exposure Guidance v06
- KDB 648474 D04 Handset SAR v01r03
- KDB 865664 D01 SAR Measurement 100MHz to 6GHz v01r04

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2. GENERAL INFORMATION

2.1. EUT Description

| General Information | |
|-------------------------|--------------------------------|
| Product Designation | Digital radio system |
| Test Model | TKO Wireless Remote Controller |
| Hardware Version | Rev1.4 |
| Software Version | 1.1.2 |
| Device Category | Portable |
| RF Exposure Environment | Uncontrolled |
| Antenna Type | Ceramic |
| 2.4GHz | |
| Operation Frequency | 2404.27-2473.27 MHz |
| Avg. Burst Power | 6.47dBm |
| Antenna Gain | 2.85dBi |

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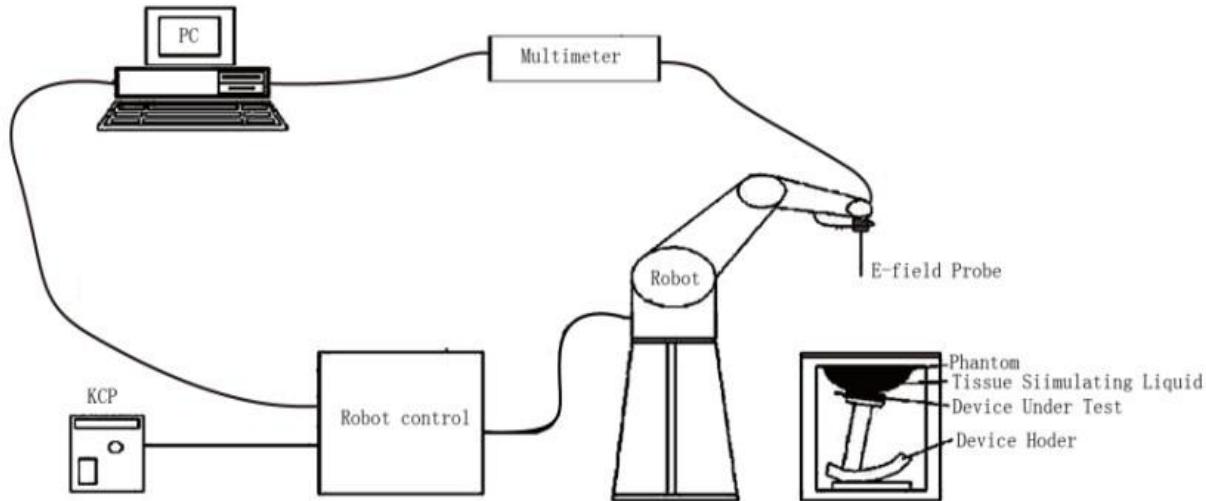
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3. SAR MEASUREMENT SYSTEM

3.1. The SATIMO system used for performing compliance tests consists of following items



The COMOSAR system for performing compliance tests consists of the following items:

- The PC. It controls most of the bench devices and stores measurement data. A computer running WinXP and the Opensar software.
- The E-Field probe. The probe is a 3-axis system made of 3 distinct dipoles. Each dipole returns a voltage in function of the ambient electric field.
- The Keithley multimeter measures each probe dipole voltages.
- The SAM phantom simulates a human head. The measurement of the electric field is made inside the phantom.
- The liquids simulate the dielectric properties of the human head tissues.
- The network emulator controls the mobile phone under test.
- The validation dipoles are used to measure a reference SAR. They are used to periodically check the bench to make sure that there is no drift of the system characteristics over time.
- The phantom, the device holder and other accessories according to the targeted measurement.

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3.2. COMOSAR E-Field Probe

The SAR measurement is conducted with the dosimetric probe manufactured by SATIMO. The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. SATIMO conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528 and relevant KDB files.) The calibration data are in Appendix D.

Isotropic E-Field Probe Specification

| | |
|---------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Model | SSE2 |
| Manufacture | MVG |
| Identification No. | 2023-EPGO-414 |
| Frequency | 0.15GHz-7.5GHz Linearity:±0.09dB(0.15GHz-7.5GHz) |
| Dynamic Range | 0.01W/kg-100W/kg Linearity:±0.09dB |
| Dimensions | Overall length:330mm Length of individual dipoles:24.5mm Maximum external diameter:8mm Probe Tip external diameter:2.55mm Distance between dipoles/ probe extremity:12.7mm |
| Application | High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 6 GHz with precision of better 30%. |



3.3. Robot

The COMOSAR system uses the KUKA robot from SATIMO SA (France). For the 6-axis controller COMOSAR system, the KUKA robot controller version from SATIMO is used.

The XL robot series have many features that are important for our application:

- High precision (repeatability 0.02 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)
- 6-axis controller



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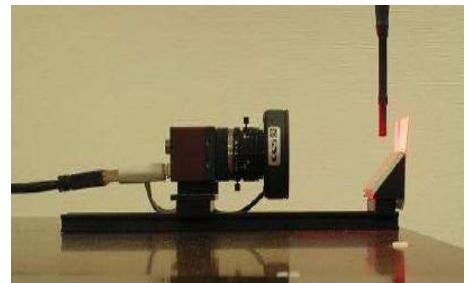
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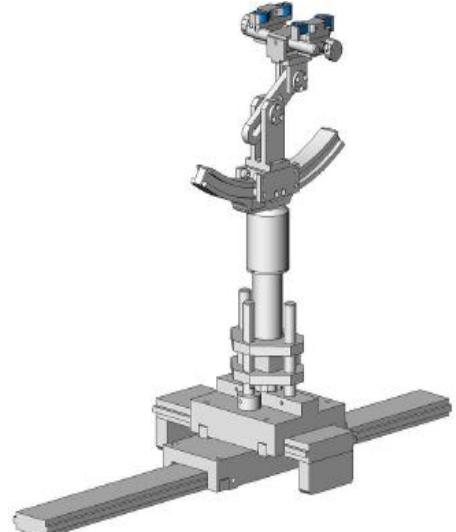
3.4. Video Positioning System

The video positioning system is used in OpenSAR to check the probe. Which is composed of a camera, LED, mirror and mechanical parts. The camera is piloted by the main computer with firewire link. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip. The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.



3.5. Device Holder

The COMOSAR device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR). Thus the device needs no repositioning when changing the angles. The COMOSAR device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity $\epsilon_r = 3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



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3.6. SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

- Left head
- Right head
- Flat phantom



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

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4. SAR MEASUREMENT PROCEDURE

4.1. Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and occupational/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element(dv) of given mass density (ρ). The equation description is as below:

$$\text{SAR} = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dV} \right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR can be obtained using either of the following equations:

$$\text{SAR} = \frac{\sigma E^2}{\rho}$$

$$\text{SAR} = c_h \frac{dT}{dt} \Big|_{t=0}$$

Where

| | |
|----------------|--------------------------------------------------------------------------------------|
| SAR | is the specific absorption rate in watts per kilogram; |
| E | is the r.m.s. value of the electric field strength in the tissue in volts per meter; |
| σ | is the conductivity of the tissue in siemens per metre; |
| ρ | is the density of the tissue in kilograms per cubic metre; |
| c _h | is the heat capacity of the tissue in joules per kilogram and Kelvin; |

$\frac{dT}{dt} \Big|_{t=0}$ is the initial time derivative of temperature in the tissue in kelvins per second

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4.2. SAR Measurement Procedure

Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurement are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface is 2.7mm. This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties,

Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in SATIMO software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in db) is specified in the standards for compliance testing. For example, a 2db range is required in IEEE Standard 1528 standards, whereby 3db is a requirement when compliance is assessed in accordance with the ARIB standard (Japan). If one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximum are detected, the number of Zoom Scan has to be increased accordingly.

Area Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100MHz to 6GHz

| | ≤ 3 GHz | > 3 GHz |
|--------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------|
| Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface | 5 ± 1 mm | $\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5$ mm |
| Maximum probe angle from probe axis to phantom surface normal at the measurement location | $30^\circ \pm 1^\circ$ | $20^\circ \pm 1^\circ$ |
| | ≤ 2 GHz: ≤ 15 mm $2 - 3$ GHz: ≤ 12 mm | $3 - 4$ GHz: ≤ 12 mm $4 - 6$ GHz: ≤ 10 mm |
| Maximum area scan spatial resolution: $\Delta x_{\text{Area}}, \Delta y_{\text{Area}}$ | When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be \leq the corresponding x or y dimension of the test device with at least one measurement point on the test device. | |

Step 3: Zoom Scan

Zoom Scan are used to assess the peak spatial SAR value within a cubic average volume containing 1g and 10g of simulated tissue. The Zoom Scan measures points (refer to table below) within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1g and 10g and displays these values next to the job's label.

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Zoom Scan Parameters extracted from KDB865664 d01 SAR Measurement 100MHz to 6GHz

| | | | | |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------|--------------------------------------------------------|-------------------------------------------------------------------------------------|--|
| Maximum zoom scan spatial resolution: Δx_{Zoom} , Δy_{Zoom} | | ≤ 2 GHz: ≤ 8 mm $2 - 3$ GHz: ≤ 5 mm* | $3 - 4$ GHz: ≤ 5 mm* $4 - 6$ GHz: ≤ 4 mm* | |
| Maximum zoom scan spatial resolution, normal to phantom surface | uniform grid: $\Delta z_{Zoom}(n)$ graded grid | ≤ 5 mm | $3 - 4$ GHz: ≤ 4 mm $4 - 5$ GHz: ≤ 3 mm $5 - 6$ GHz: ≤ 2 mm | |
| | | ≤ 4 mm | $3 - 4$ GHz: ≤ 3 mm $4 - 5$ GHz: ≤ 2.5 mm $5 - 6$ GHz: ≤ 2 mm | |
| Minimum zoom scan volume | x, y, z | $\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$ | | |
| | | ≥ 30 mm | $3 - 4$ GHz: ≥ 28 mm $4 - 5$ GHz: ≥ 25 mm $5 - 6$ GHz: ≥ 22 mm | |
| Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details. | | | | |
| * When zoom scan is required and the <u>reported</u> SAR from the <i>area scan based 1-g SAR estimation</i> procedures of KDB 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz. | | | | |

Step 4: Power Drift Measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the same settings. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

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4.3. RF Exposure Conditions

Test Configuration and setting:

The EUT is a model of. It supports 2.4G SAR testing, the device was controlled by using a base station emulator.

For 2.4G testing, the EUT is configured with the 2.4G continuous TX tool through engineering command.

Antenna Location: (the Right view)



EUT Bottom Edge

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For 2.4G mode:

| Test Configurations | Antenna to edges/surface | SAR required | Note |
|---------------------|--------------------------|--------------|------------------------------------------------------------------------------------------------------|
| Body | | | |
| Back | 50mm | NO | SAR is not required for the distance between the antenna and the edge is >25mm as per KDB 941225 D06 |
| Front | <25mm | Yes | |
| Edge 1 (Left) | <25mm | Yes | |
| Edge 2 (Top) | <25mm | Yes | |
| Edge 3 (Right) | <25mm | Yes | |
| Edge 4 (Bottom) | 150mm | No | SAR is not required for the distance between the antenna and the edge is >25mm as per KDB 941225 D06 |

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5. TISSUE SIMULATING LIQUID

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 10% are listed in 6.2

5.1. The composition of the tissue simulating liquid

| Frequency (MHz) | Ingredient (% Weight) | Water | NaCl | Polysorbate 20 | DGBE | 1,2-Propanediol | Triton X-100 | Diethylen glycol monohex ylether |
|-----------------|-----------------------|-------|-------|----------------|------|-----------------|--------------|----------------------------------|
| 750 Head | 35 | 2 | 0.0 | 0.0 | 63 | 0.0 | 0.0 | 0.0 |
| 835 Head | 50.36 | 1.25 | 48.39 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 |
| 1750 Head | 52.64 | 0.36 | 0.0 | 47 | 0.0 | 0.0 | 0.0 | 0.0 |
| 1900 Head | 54.9 | 0.18 | 0.0 | 44.92 | 0.0 | 0.0 | 0.0 | 0.0 |
| 2300 Head | 62.82 | 0.51 | 0.0 | 36.67 | 0.0 | 0.0 | 0.0 | 0.0 |
| 2450 Head | 71.88 | 0.16 | 0.0 | 7.99 | 0.0 | 19.97 | 0.0 | 0.0 |
| 2600 Head | 55.242 | 0.306 | 0 | 44.452 | 0 | 0 | 0 | 0.0 |
| 5000 Head | 65.52 | 0.0 | 0.0 | 0.0 | 0.0 | 17.24 | 17.24 | 17.24 |

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5.2. Tissue Dielectric Parameters for Head and Body Phantoms

The head and body tissue dielectric parameters recommended by the IEEE Std. 1528 have been incorporated in the following table.

| Target Frequency (MHz) | head | | body | |
|---------------------------|--------------|----------------|--------------|----------------|
| | ϵ_r | σ (S/m) | ϵ_r | σ (S/m) |
| 300 | 45.3 | 0.87 | 45.3 | 0.87 |
| 450 | 43.5 | 0.87 | 43.5 | 0.87 |
| 750 | 41.9 | 0.89 | 41.9 | 0.89 |
| 835 | 41.5 | 0.90 | 41.5 | 0.90 |
| 900 | 41.5 | 0.97 | 41.5 | 0.97 |
| 915 | 41.5 | 1.01 | 41.5 | 1.01 |
| 1450 | 40.5 | 1.20 | 40.5 | 1.20 |
| 1610 | 40.3 | 1.29 | 40.3 | 1.29 |
| 1750 | 40.1 | 1.37 | 40.1 | 1.37 |
| 1800 – 2000 | 40.0 | 1.40 | 40.0 | 1.40 |
| 2300 | 39.5 | 1.67 | 39.5 | 1.67 |
| 2450 | 39.2 | 1.80 | 39.2 | 1.80 |
| 2600 | 39.0 | 1.96 | 39.0 | 1.96 |
| 3000 | 38.5 | 2.40 | 38.5 | 2.40 |
| 5200 | 36.0 | 4.66 | 36.0 | 4.66 |
| 5300 | 35.9 | 4.76 | 35.9 | 4.76 |
| 5600 | 35.5 | 5.07 | 35.5 | 5.07 |
| 5800 | 35.3 | 5.27 | 35.3 | 5.27 |

(ϵ_r = relative permittivity, σ = conductivity and $\rho = 1000$ kg/m³

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5.3. Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using SATIMO Dielectric Probe Kit and R&S Network Analyzer ZVL6.

| Tissue Stimulant Measurement for 2450MHz | | | | | |
|------------------------------------------|--------------|--------------------------------------|-------------------------------|------------------------|-----------|
| Head | Fr. (MHz) | Dielectric Parameters ($\pm 10\%$) | | Tissue Temp [°C] | Test time |
| | | ϵ_r 39.2(35.28-43.12) | δ [s/m]1.80(1.62-1.98) | | |
| 2404.27 | 40.57 | 1.75 | 22.3 | 2024-05-30 | |
| | 39.37 | 1.77 | | | |
| | 40.52 | 1.80 | | | |
| | 40.02 | 1.88 | | | |

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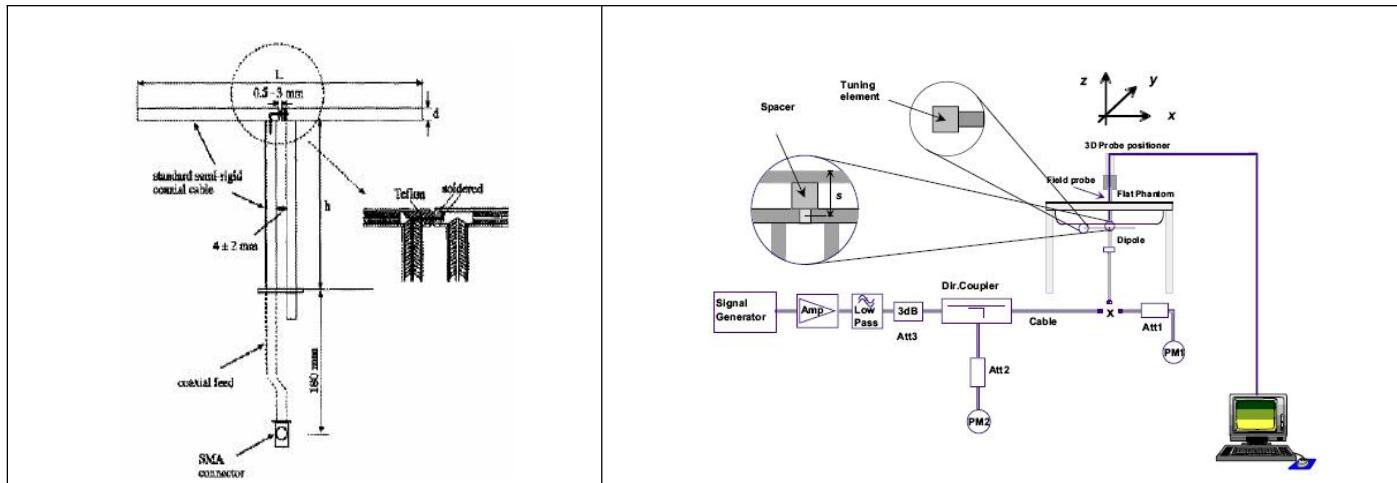
6. SAR SYSTEM CHECK PROCEDURE

6.1. SAR System Check Procedures

SAR system check is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device. The same SAR probe(s) and tissue-equivalent media combinations used with each specific SAR system for system verification must be used for device testing. When multiple probe calibration points are required to cover substantially large transmission bands, independent system verifications are required for each probe calibration point. A system verification must be performed before each series of SAR measurements using the same probe calibration point and tissue-equivalent medium. Additional system verification should be considered according to the conditions of the tissue-equivalent medium and measured tissue dielectric parameters, typically every three to four days when the liquid parameters are remeasured or sooner when marginal liquid parameters are used at the beginning of a series of measurements.

Each SATIMO system is equipped with one or more system check kits. These units, together with the predefined measurement procedures within the SATIMO software, enable the user to conduct the system check and system validation. System kit includes a dipole, and dipole device holder.

The system check verifies that the system operates within its specifications. It's performed daily or before every SAR measurement. The system check uses normal SAR measurement in the flat section of the phantom with a matched dipole at a specified distance. The system check setup is shown as below.



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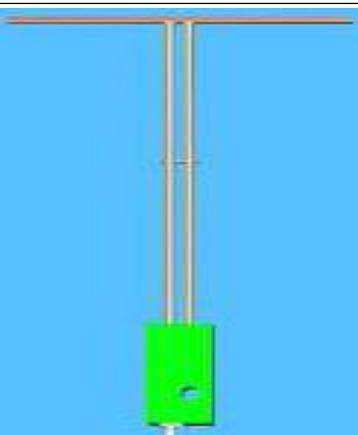
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6.2. SAR System Check

6.2.1. Dipoles

| | |
|------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|  | <p>The dipoles are based on the IEEE-1528 standard, and are complied with mechanical and electrical specifications in line with the requirements of IEEE. the table below provides details for the mechanical and electrical Specifications for the dipoles.</p> |
|  | <p>The dipole is based on the IEEE-1528 standard, and is complied with mechanical and electrical specifications in line with the requirements of IEEE. The table below provides details for the mechanical and electrical specifications for the wave guide.</p> |

| Frequency | L (mm) | h (mm) | d (mm) |
|-----------|--------|--------|--------|
| 750MHz | 176 | 100 | 6.35 |
| 835MHz | 161.0 | 89.8 | 3.6 |
| 1800MHz | 71.6 | 41.7 | 3.6 |
| 1900MHz | 68 | 39.5 | 3.6 |
| 2300MHz | 55.5 | 32.6 | 3.6 |
| 2450MHz | 51.5 | 30.4 | 3.6 |
| 2600MHz | 48.5 | 28.8 | 3.6 |
| 5000MHz | 20.6 | 40.3 | 3.6 |

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6.2.2. System Check Result

| System Performance Check at 2450MHz for Head | | | | | | | | |
|----------------------------------------------|--------------------|-------|---------------------------------|---------------|--------------------|----------|-------------------|------------|
| Validation Kit: SN 29/15 DIP 2G450-393 | | | | | | | | |
| Frequency [MHz] | Target Value(W/kg) | | Reference Result ($\pm 10\%$) | | Tested Value(W/kg) | | Tissue Temp. [°C] | Test time |
| | 1g | 10g | 1g | 10g | 1g | 10g | | |
| 2450 | 54.32 | 24.25 | 48.888-59.752 | 21.825-26.675 | 55.23906 | 22.15285 | 22.3 | 2024-05-30 |

Note:

(1) We use a CW signal of 20dBm for system check, and then all SAR value are normalized to 1W forward power. The result must be within $\pm 10\%$ of target value.

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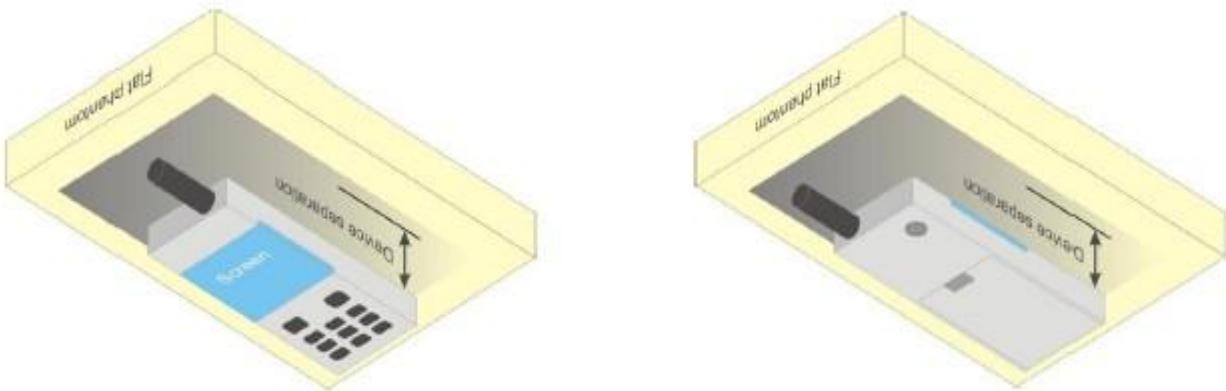
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7. EUT TEST POSITION

This EUT was tested in **Body back, Body front and 4 edges**.

7.1. Body Worn Position

- (1) To position the EUT parallel to the phantom surface.
- (2) To adjust the EUT parallel to the flat phantom.
- (3) To adjust the distance between the EUT surface and the flat phantom to **0mm**.



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8. SAR EXPOSURE LIMITS

Limits for General Population/Uncontrolled Exposure (W/kg)

| Type Exposure | Uncontrolled Environment Limit (W/kg) |
|-----------------------------------------------------|---------------------------------------|
| Spatial Peak SAR (1g cube tissue for brain or body) | 1.60 |
| Spatial Average SAR (Whole body) | 0.08 |
| Spatial Peak SAR (Limbs) | 4.0 |

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9. TEST FACILITY

| | |
|------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------|
| Test Site | Attestation of Global Compliance (Shenzhen) Co., Ltd |
| Location | 1-2/F, Building 19, Junfeng Industrial Park, Chongqing Road, Heping Community, Fuhai Street, Bao'an District, Shenzhen, Guangdong, China |
| Designation Number | CN1259 |
| FCC Test Firm Registration Number | 975832 |
| A2LA Cert. No. | 5054.02 |
| Description | Attestation of Global Compliance(Shenzhen) Co., Ltd is accredited by A2LA |

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10. TEST EQUIPMENT LIST

| Equipment description | Manufacturer/ Model | Identification No. | Software version | Current calibration date | Next calibration date |
|---------------------------------------------------|-------------------------|------------------------|------------------|-----------------------------|-----------------------------|
| SAR Probe | MVG | 2023-EPGO-414 | N/A | Apr. 30, 2024 | Apr. 29, 2025 |
| Phantom | SATIMO | SN_4511_SAM90 | N/A | Validated. No cal required. | Validated. No cal required. |
| Liquid | SATIMO | N/A | N/A | Validated. No cal required. | Validated. No cal required. |
| Comm Tester | Agilent-8960 | GB46310822 | A.13.07 | Jun. 03, 2023 | Jun. 02, 2024 |
| Comm Tester | R&S- CMW500 | 121209 | V3.7.40 | Jun. 01, 2023 | May 31, 2024 |
| Multimeter | Keithley 2000 | 4114939 | N/A | Jun. 01, 2023 | May 31, 2024 |
| SAR Software | MVG-OpenSAR | N/A | OpenSAR V4_02_35 | N/A | N/A |
| Dipole | SATIMO SID2450 | SN 29/15 DIP 2G450-393 | N/A | Apr. 28,2022 | Apr. 27,2025 |
| Signal Generator | Agilent-E4438C | US41461365 | V5.03 | Jun. 01, 2023 | May 31, 2024 |
| Vector Analyzer | Agilent / E4440A | MY44303916 | N/A | Jun. 01, 2023 | May 31, 2024 |
| Network Analyzer | Rhode & Schwarz ZVL6 | SN101443 | 3.2 | Sep. 21, 2023 | Sep. 20, 2024 |
| Attenuator | Warison /WATT-6SR1211 | S/N:WRJ34AYM2F1 | N/A | June 07, 2023 | June 06, 2024 |
| Attenuator | Mini-circuits / VAT-10+ | 31405 | N/A | June 07, 2023 | June 06, 2024 |
| Amplifier | AS0104-55_55 | 1004793 | N/A | N/A | N/A |
| Directional Couple | Werlatone/ C5571-10 | SN99463 | N/A | Feb. 01, 2024 | Jan. 31, 2026 |
| Directional Couple | Werlatone/ C6026-10 | SN99482 | N/A | Feb. 01, 2024 | Jan. 31, 2026 |
| Power Sensor | NRP-Z21 | 1137.6000.02 | N/A | Sep. 05, 2023 | Sep. 04, 2024 |
| Power Sensor | NRP-Z23 | 100323 | N/A | Jun. 06, 2023 | Jun. 05, 2024 |
| Power Viewer | R&S | V2.3.1.0 | N/A | N/A | N/A |
| Calibration standard parts for network sub - port | R&S/ ZV-Z132 | N/A | V2.3.1.0 | Nov. 11, 2023 | Nov. 10, 2024 |

Note: Per KDB 865664 Dipole SAR Validation, AGC Lab has adopted 3 years calibration intervals. On annual basis, every measurement dipole has been evaluated and is in compliance with the following criteria:

1. There is no physical damage on the dipole;
2. System validation with specific dipole is within 10% of calibrated value;
3. Return-loss is within 20% of calibrated measurement;
4. Impedance is within 5Ω of calibrated measurement.

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11. MEASUREMENT UNCERTAINTY

| SATIMO Uncertainty- 2023-EPGO-414 Measurement uncertainty for DUT averaged over 1 gram / 10 gram. | | | | | | | | | |
|------------------------------------------------------------------------------------------------------|-------|----------------|----------------|-------|---------|----------|------------------|-------------------|----------|
| Uncertainty Component | Sec. | Tol (+ - %) | Prob. Dist. | Div. | Ci (1g) | Ci (10g) | 1g Ui (+ - %) | 10g Ui (+ - %) | vi |
| Measurement System | | | | | | | | | |
| Probe calibration | E.2.1 | 7.000 | N | 1 | 1 | 1 | 7.000 | 7.000 | ∞ |
| Axial Isotropy | E.2.2 | 1.695 | R | 1.732 | 0.707 | 0.707 | 0.692 | 0.692 | ∞ |
| Hemispherical Isotropy | E.2.2 | 1.695 | R | 1.732 | 0.707 | 0.707 | 0.692 | 0.692 | ∞ |
| Boundary effect | E.2.3 | 1.000 | R | 1.732 | 1 | 1 | 0.577 | 0.577 | ∞ |
| Linearity | E.2.4 | 2.250 | R | 1.732 | 1 | 1 | 1.299 | 1.299 | ∞ |
| System detection limits | E.2.4 | 1.000 | R | 1.732 | 1 | 1 | 0.577 | 0.577 | ∞ |
| Modulation response | E2.5 | 3.000 | R | 1.732 | 1 | 1 | 1.732 | 1.732 | ∞ |
| Readout Electronics | E.2.6 | 0.021 | N | 1 | 1 | 1 | 0.021 | 0.021 | ∞ |
| Response Time | E.2.7 | 0.000 | R | 1.732 | 1 | 1 | 0.000 | 0.000 | ∞ |
| Integration Time | E.2.8 | 1.400 | R | 1.732 | 1 | 1 | 0.808 | 0.808 | ∞ |
| RF ambient conditions-Noise | E.6.1 | 3.000 | R | 1.732 | 1 | 1 | 1.732 | 1.732 | ∞ |
| RF ambient conditions-reflections | E.6.1 | 3.000 | R | 1.732 | 1 | 1 | 1.732 | 1.732 | ∞ |
| Probe positioner mechanical tolerance | E.6.2 | 1.400 | R | 1.732 | 1 | 1 | 0.808 | 0.808 | ∞ |
| Probe positioning with respect to phantom shell | E.6.3 | 1.400 | R | 1.732 | 1 | 1 | 0.808 | 0.808 | ∞ |
| Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation | E.5 | 2.300 | R | 1.732 | 1 | 1 | 1.328 | 1.328 | ∞ |
| Test sample Related | | | | | | | | | |
| Test sample positioning | E.4.2 | 2.6 | N | 1 | 1 | 1 | 2.60 | 2.60 | ∞ |
| Device holder uncertainty | E.4.1 | 3 | N | 1 | 1 | 1 | 3.00 | 3.00 | ∞ |
| Output power variation—SAR drift measurement | E.2.9 | 5 | R | 1.732 | 1 | 1 | 2.89 | 2.89 | ∞ |
| SAR scaling | E.6.5 | 5 | R | 1.732 | 1 | 1 | 2.89 | 2.89 | ∞ |
| Phantom and tissue parameters | | | | | | | | | |
| Phantom shell uncertainty—shape, thickness, and permittivity | E.3.1 | 4 | R | 1.732 | 1 | 1 | 2.309 | 2.309 | ∞ |
| Uncertainty in SAR correction for deviations in permittivity and conductivity | E.3.2 | 1.9 | N | 1 | 1 | 0.84 | 1.900 | 1.596 | ∞ |
| Liquid conductivity measurement | E.3.3 | 4 | N | 1 | 0.78 | 0.71 | 3.120 | 2.840 | M |
| Liquid permittivity measurement | E.3.3 | 5 | N | 1 | 0.23 | 0.26 | 1.150 | 1.300 | M |
| Liquid conductivity—temperature uncertainty | E.3.4 | 2.5 | R | 1.732 | 0.78 | 0.71 | 1.126 | 1.025 | ∞ |
| Liquid permittivity—temperature uncertainty | E.3.4 | 2.5 | R | 1.732 | 0.23 | 0.26 | 0.332 | 0.375 | ∞ |
| Combined Standard Uncertainty | | | RSS | | | | 10.616 | 10.432 | |
| Expanded Uncertainty (95% Confidence interval) | | | K=2 | | | | 21.232 | 20.865 | |

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| SATIMO Uncertainty- 2023-EPGO-414 System Validation uncertainty for DUT averaged over 1 gram / 10 gram. | | | | | | | | | |
|------------------------------------------------------------------------------------------------------------|---------|---------------|----------------|-------|---------|----------|----------------|-----------------|----------|
| Uncertainty Component | Sec. | Tol (+- %) | Prob. Dist. | Div. | Ci (1g) | Ci (10g) | 1g Ui (+-%) | 10g Ui (+-%) | vi |
| Measurement System | | | | | | | | | |
| Probe calibration | E.2.1 | 7.000 | N | 1 | 1 | 1 | 7.000 | 7.000 | ∞ |
| Axial Isotropy | E.2.2 | 1.695 | R | 1.732 | 1.000 | 1.000 | 0.979 | 0.979 | ∞ |
| Hemispherical Isotropy | E.2.2 | 1.695 | R | 1.732 | 0.000 | 0.000 | 0.000 | 0.000 | ∞ |
| Boundary effect | E.2.3 | 1.000 | R | 1.732 | 1.000 | 1.000 | 0.577 | 0.577 | ∞ |
| Linearity | E.2.4 | 2.250 | R | 1.732 | 1.000 | 1.000 | 1.299 | 1.299 | ∞ |
| System detection limits | E.2.4 | 1.000 | R | 1.732 | 1.000 | 1.000 | 0.577 | 0.577 | ∞ |
| Modulation response | E2.5 | 3.000 | R | 1.732 | 0.000 | 0.000 | 0.000 | 0.000 | ∞ |
| Readout Electronics | E.2.6 | 0.021 | N | 1.000 | 1.000 | 1.000 | 0.021 | 0.021 | ∞ |
| Response Time | E.2.7 | 0.000 | R | 1.732 | 0.000 | 0.000 | 0.000 | 0.000 | ∞ |
| Integration Time | E.2.8 | 1.400 | R | 1.732 | 0.000 | 0.000 | 0.000 | 0.000 | ∞ |
| RF ambient conditions-Noise | E.6.1 | 3.000 | R | 1.732 | 1.000 | 1.000 | 1.732 | 1.732 | ∞ |
| RF ambient conditions-reflections | E.6.1 | 3.000 | R | 1.732 | 1.000 | 1.000 | 1.732 | 1.732 | ∞ |
| Probe positioner mechanical tolerance | E.6.2 | 1.400 | R | 1.732 | 1.000 | 1.000 | 0.808 | 0.808 | ∞ |
| Probe positioning with respect to phantom shell | E.6.3 | 1.400 | R | 1.732 | 1.000 | 1.000 | 0.808 | 0.808 | ∞ |
| Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation | E.5 | 2.300 | R | 1.732 | 1.000 | 1.000 | 1.328 | 1.328 | ∞ |
| System validation source | | | | | | | | | |
| Deviation of experimental dipole from numerical dipole | E.6.4 | 5 | N | 1 | 1 | 1 | 5 | 5 | ∞ |
| Input power and SAR drift measurement | 8,6.6.4 | 5 | R | 1.732 | 1 | 1 | 2.887 | 2.887 | ∞ |
| Dipole axis to liquid distance | 8,E.6.6 | 2 | R | 1.732 | 1 | 1 | 1.155 | 1.155 | ∞ |
| Phantom and set-up | | | | | | | | | |
| Phantom shell uncertainty—shape, thickness, and permittivity | E.3.1 | 4 | R | 1.732 | 1 | 1 | 2.309 | 2.309 | ∞ |
| Uncertainty in SAR correction for deviations in permittivity and conductivity | E.3.2 | 1.9 | N | 1 | 1 | 0.84 | 1.9 | 1.596 | ∞ |
| Liquid conductivity (temperature uncertainty) | E.3.3 | 4 | N | 1 | 0.78 | 0.71 | 3.12 | 2.84 | ∞ |
| Liquid conductivity (measured) | E.3.3 | 5 | N | 1 | 0.23 | 0.26 | 1.15 | 1.3 | M |
| Liquid permittivity (temperature uncertainty) | E.3.4 | 2.5 | R | 1.732 | 0.78 | 0.71 | 1.126 | 1.025 | ∞ |
| Liquid permittivity (measured) | E.3.4 | 2.5 | R | 1.732 | 0.23 | 0.26 | 0.332 | 0.375 | M |
| Combined Standard Uncertainty | | | RSS | | | | 10.572 | 10.387 | |
| Expanded Uncertainty (95% Confidence interval) | | | K=2 | | | | 21.143 | 20.775 | |

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| SATIMO Uncertainty- 2023-EPGO-414 System Check uncertainty for DUT averaged over 1 gram / 10 gram. | | | | | | | | | |
|-------------------------------------------------------------------------------------------------------|---------|---------------|----------------|------------|---------|----------|----------------|-----------------|----------|
| Uncertainty Component | Sec. | Tol (+- %) | Prob. Dist. | Div. | Ci (1g) | Ci (10g) | 1g Ui (+-%) | 10g Ui (+-%) | vi |
| Measurement System | | | | | | | | | |
| Probe calibration drift | E.2.1.3 | 0.5 | N | 1 | 1 | 1 | 0.5 | 0.5 | ∞ |
| Axial Isotropy | E.2.2 | 1.695 | R | $\sqrt{3}$ | 0 | 0 | 0 | 0 | ∞ |
| Hemispherical Isotropy | E.2.2 | 1.695 | R | $\sqrt{3}$ | 0 | 0 | 0 | 0 | ∞ |
| Boundary effect | E.2.3 | 1.000 | R | $\sqrt{3}$ | 0 | 0 | 0 | 0 | ∞ |
| Linearity | E.2.4 | 2.250 | R | $\sqrt{3}$ | 0 | 0 | 0 | 0 | ∞ |
| System detection limits | E.2.4 | 1 | R | $\sqrt{3}$ | 0 | 0 | 0 | 0 | ∞ |
| Modulation response | E2.5 | 3 | R | $\sqrt{3}$ | 0 | 0 | 0 | 0 | ∞ |
| Readout Electronics | E.2.6 | 0.021 | N | $\sqrt{3}$ | 0 | 0 | 0 | 0 | ∞ |
| Response Time | E.2.7 | 0 | R | $\sqrt{3}$ | 0 | 0 | 0 | 0 | ∞ |
| Integration Time | E.2.8 | 1.4 | R | $\sqrt{3}$ | 0 | 0 | 0 | 0 | ∞ |
| RF ambient conditions-Noise | E.6.1 | 3 | R | $\sqrt{3}$ | 0 | 0 | 0 | 0 | ∞ |
| RF ambient conditions-reflections | E.6.1 | 3 | R | $\sqrt{3}$ | 0 | 0 | 0 | 0 | ∞ |
| Probe positioner mechanical tolerance | E.6.2 | 1.4 | R | $\sqrt{3}$ | 1 | 1 | 0.81 | 0.81 | ∞ |
| Probe positioning with respect to phantom shell | E.6.3 | 1.4 | R | $\sqrt{3}$ | 1 | 1 | 0.81 | 0.81 | ∞ |
| Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation | E.5 | 2.3 | R | $\sqrt{3}$ | 0 | 0 | 0 | 0.00 | ∞ |
| System check source (dipole) | | | | | | | | | |
| Deviation of experimental dipoles | E.6.4 | 2 | N | 1 | 1 | 1 | 2 | 2 | ∞ |
| Input power and SAR drift measurement | 8,E.6.4 | 5 | R | $\sqrt{3}$ | 1 | 1 | 2.89 | 2.89 | ∞ |
| Dipole axis to liquid distance | 8,E.6.6 | 2 | R | $\sqrt{3}$ | 1 | 1 | 1.15 | 1.15 | ∞ |
| Phantom and tissue parameters | | | | | | | | | |
| Phantom shell uncertainty—shape, thickness, and permittivity | E.3.1 | 4 | R | $\sqrt{3}$ | 1 | 1 | 2.31 | 2.31 | ∞ |
| Uncertainty in SAR correction for deviations in permittivity and conductivity | E.3.2 | 1.9 | N | 1.000 | 1 | 0.84 | 1.90 | 1.60 | ∞ |
| Liquid conductivity measurement | E.3.3 | 4 | N | 1.000 | 0.78 | 0.71 | 3.12 | 2.84 | ∞ |
| Liquid permittivity measurement | E.3.3 | 5 | N | 1.000 | 0.23 | 0.26 | 1.15 | 1.30 | M |
| Liquid conductivity—temperature uncertainty | E.3.4 | 2.5 | R | $\sqrt{3}$ | 0.78 | 0.71 | 1.13 | 1.02 | ∞ |
| Liquid permittivity—temperature uncertainty | E.3.4 | 2.5 | R | $\sqrt{3}$ | 0.23 | 0.26 | 0.33 | 0.38 | M |
| Combined Standard Uncertainty | | | RSS | | | | 5.562 | 5.203 | |
| Expanded Uncertainty (95% Confidence interval) | | | K=2 | | | | 11.124 | 10.406 | |

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12. CONDUCTED POWER MEASUREMENT**2.4G**

| 2.4G | | | | |
|------|----------------|-----------------|---------------------|-------------------|
| Mode | Channel Number | Frequency (MHz) | Average Power (dBm) | Output Power (mW) |
| 2.4G | Low | 2404.27 | 6.36 | 4.33 |
| | Mid | 2438.77 | 6.34 | 4.31 |
| | High | 2473.27 | 6.47 | 4.44 |

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13. TEST RESULTS

13.1. SAR Test Results Summary

13.1.1. Test position and configuration

Use a device with a distance of 0mm from the phantom according to IEEE 1528-2013 configuration for body wearing and 4-edge SAR.

13.1.2. Operation Mode

1. Per KDB 447498 D01 v06 ,for each exposure position, if the highest 1-g SAR is ≤ 0.8 W/kg, testing for low and high channel is optional.
2. Per KDB 865664 D01 v01r04,for each frequency band, if the measured SAR is ≥ 0.8 W/kg, testing for repeated SAR measurement is required , that the highest measured SAR is only to be tested. When the SAR results are near the limit, the following procedures are required for each device to verify these types of SAR measurement related variation concerns by repeating the highest measured SAR configuration in each frequency band.
 - (1) When the original highest measured SAR is ≥ 0.8 W/kg, repeat that measurement once.
 - (2) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is >1.20 or when the original or repeated measurement is ≥ 1.45 W/kg.
 - (3) Perform a third repeated measurement only if the original, first and second repeated measurement is ≥ 1.5 W/kg and ratio of largest to smallest SAR for the original, first and second measurement is ≥ 1.20 .
3. Body-worn exposure conditions are intended to voice call operations, therefore GSM voice call mode is selected to be test.
4. Per KDB 648474 D04 v01r03,when the reported SAR for a body-worn accessory measured without a headset connected to the handset is ≤ 1.2 W/kg, SAR testing with a headset connected is not required.
5. Maximum Scaling SAR in order to calculate the Maximum SAR values to test under the standard Peak Power, Calculation method is as follows:
Maximum Scaling SAR = tested SAR (Max.) \times [maximum turn-up power (mw)/ maximum measurement output power(mw)]
6. Proximity sensor, just for avoiding the wrong operation in the phone screen when call, and has no influence on output power or SAR result

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13.1.3. Test Result

| SAR MEASUREMENT | | | | | | | | | | | | | | | |
|-------------------------------|------|------|-----------|---------------------------|-----------------|--------------------------|--------------------------|-------------------|--------------|--|--|--|--|--|--|
| Depth of Liquid (cm):>15 | | | | Relative Humidity (%): 55 | | | | | | | | | | | |
| Product: Digital radio system | | | | | | | | | | | | | | | |
| Test Mode:2.4G | | | | | | | | | | | | | | | |
| Position | Mode | Ch. | Fr. (MHz) | Power Drift (<±5%) | SAR (1g) (W/kg) | Max. Tune-up Power (dBm) | Meas. output Power (dBm) | Scaled SAR (W/kg) | Limit (W/kg) | | | | | | |
| Body front | DTS | High | 2473.27 | -3.76 | 0.023 | 6.5 | 6.47 | 0.023 | 1.6 | | | | | | |
| Edge 2 (Top) | DTS | Low | 2404.27 | -1.16 | 0.052 | 6.5 | 6.36 | 0.054 | 1.6 | | | | | | |
| Edge 2 (Top) | DTS | Mid | 2438.77 | -1.77 | 0.050 | 6.5 | 6.34 | 0.052 | 1.6 | | | | | | |
| Edge 2 (Top) | DTS | High | 2473.27 | 1.87 | 0.064 | 6.5 | 6.47 | 0.064 | 1.6 | | | | | | |
| Edge 3(Right) | DTS | High | 2473.27 | -3.38 | 0.027 | 6.5 | 6.47 | 0.027 | 1.6 | | | | | | |
| Edge 1(Left) | DTS | High | 2473.27 | 2.04 | 0.028 | 6.5 | 6.47 | 0.028 | 1.6 | | | | | | |

Note:

- When the 1-g Reported SAR is ≤ 0.8 W/kg, testing for low and high channel is optional. Refer to KDB 447498.
- The test separation for body back, body front and 4 Edges is 0mm of all above table.

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APPENDIX A. SAR SYSTEM CHECK DATA

Test Laboratory: AGC Lab

Date: 2024-05-30

System Check Head 2450 MHz

DUT: Dipole 2450 MHz Type: SID 2450

Communication System CW; Communication System Band: D2450 (2450.0 MHz); Duty Cycle: 1:1; Conv.F=2.16

Frequency: 2450 MHz; Medium parameters used: $f = 2450$ MHz; $\sigma = 1.80$ mho/m; $\epsilon_r = 40.52$; $\rho = 1000$ kg/m³ ;

Phantom section: Flat Section; Input Power=20dBm

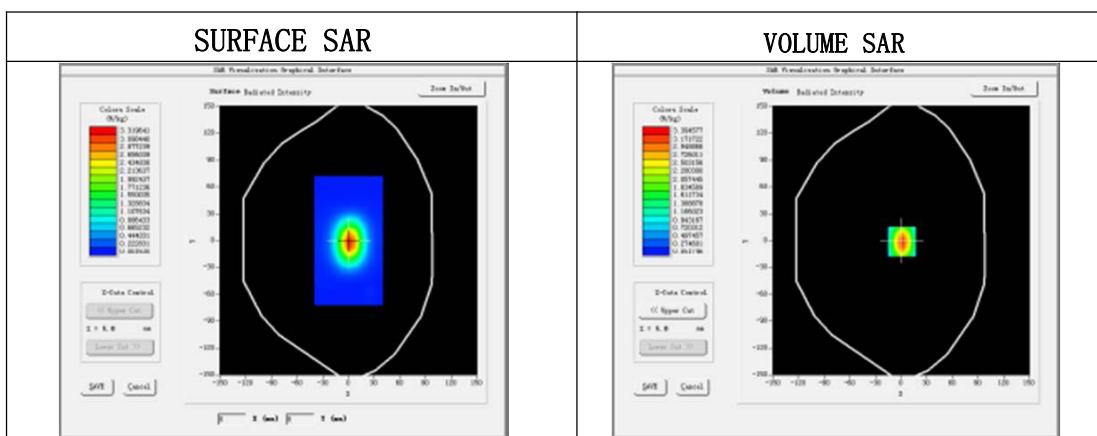
Ambient temperature (°C):22.6, Liquid temperature (°C): 22.3

SATIMO Configuration

- Probe: SSE2; Calibrated: Apr 30, 2024; Serial No.: 2023-EPGO-414
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Phantom: SAM twin phantom
- Measurement SW: OpenSAR V4_02_35

Configuration/System Check 2450MHz Head/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/System Check 2450MHz Head/Zoom Scan: Measurement grid: dx=8mm,dy=8mm, dz=5mm



Maximum location: X=3.00, Y=1.00

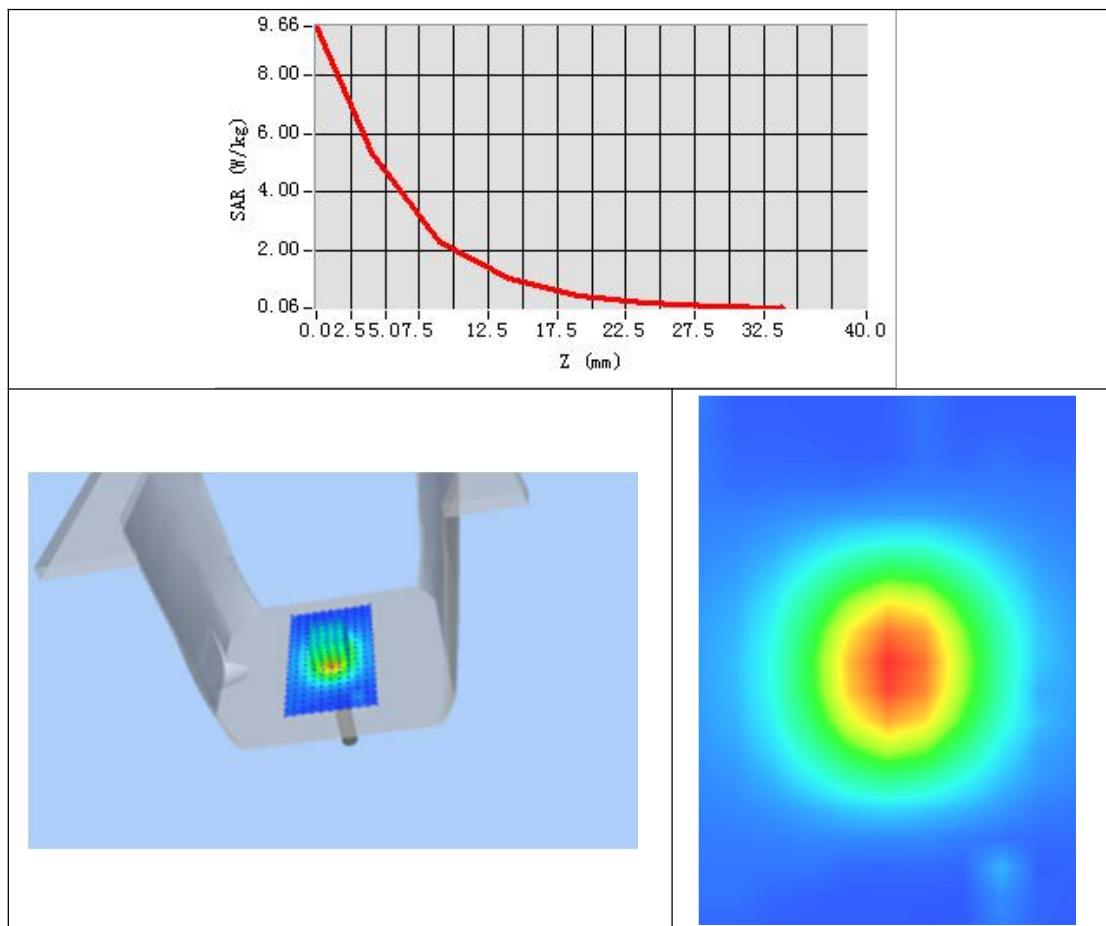
| | |
|----------------|----------|
| SAR 10g (W/Kg) | 2.215285 |
| SAR 1g (W/Kg) | 5.523906 |

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Z Axis Scan

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APPENDIX B. SAR MEASUREMENT DATA

Test Laboratory: AGC Lab

Date: 2024-05-30

2.4G High-Body-Worn-Top

DUT: Digital radio system; Type: TKO Wireless Remote Controller

Communication System: 2.4G; Communication System Band: 2.4G; Duty Cycle: 1:1; Conv.F=2.16;
 Frequency: 2473.27 MHz; Medium parameters used: $f = 2450$ MHz; $\sigma = 1.88$ mho/m; $\epsilon_r = 40.02$; $\rho = 1000$ kg/m³;
 Phantom section: Flat Section
 Ambient temperature (°C): 22.6, Liquid temperature (°C): 22.3

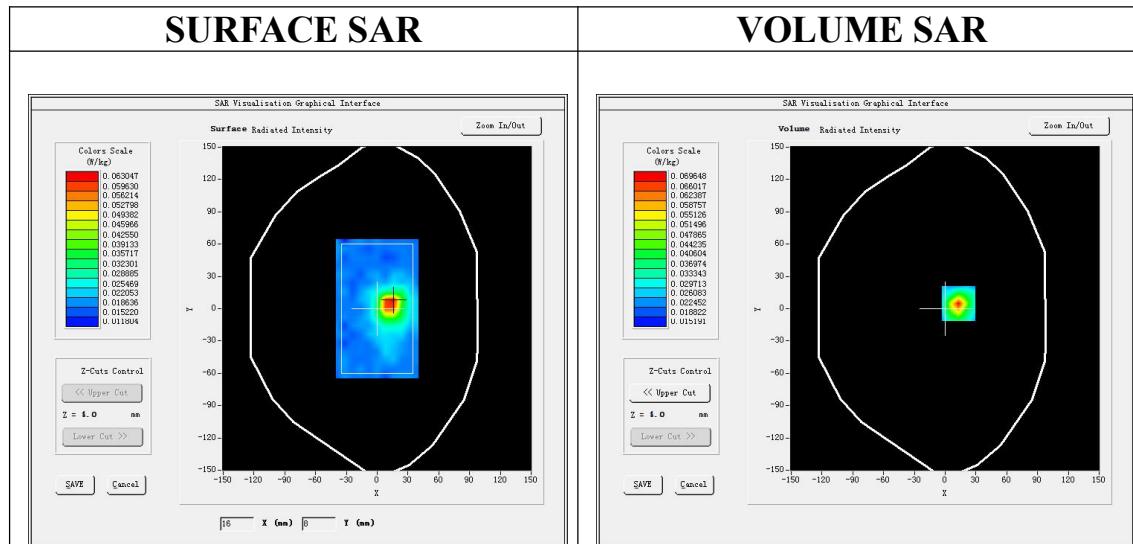
SATIMO Configuration:

- Probe: SSE2; Calibrated: Apr 30, 2024; Serial No.: 2023-EPGO-414
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Phantom: SAM twin phantom
- Measurement SW: OpenSAR V4_02_35

Configuration/2.4G High - Body- Top /Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/2.4G High - Body- Top /Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm;

| | |
|------------------------|-------------------------------|
| Area Scan | surf_sam_plan.txt, h= 5.00 mm |
| ZoomScan | 5x5x7,dx=8mm dy=8mm dz=5mm |
| Phantom | Validation plane |
| Device Position | BodyTop |
| Band | 2473.27MHz |
| Channels | High |
| Signal | Crest factor: 1.0 |



Maximum location: X=13.00, Y=5.00

SAR Peak: 0.10 W/kg

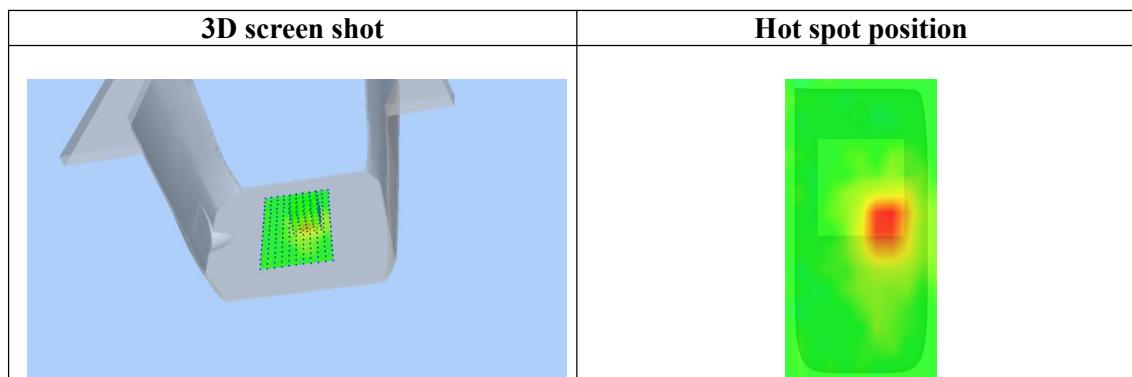
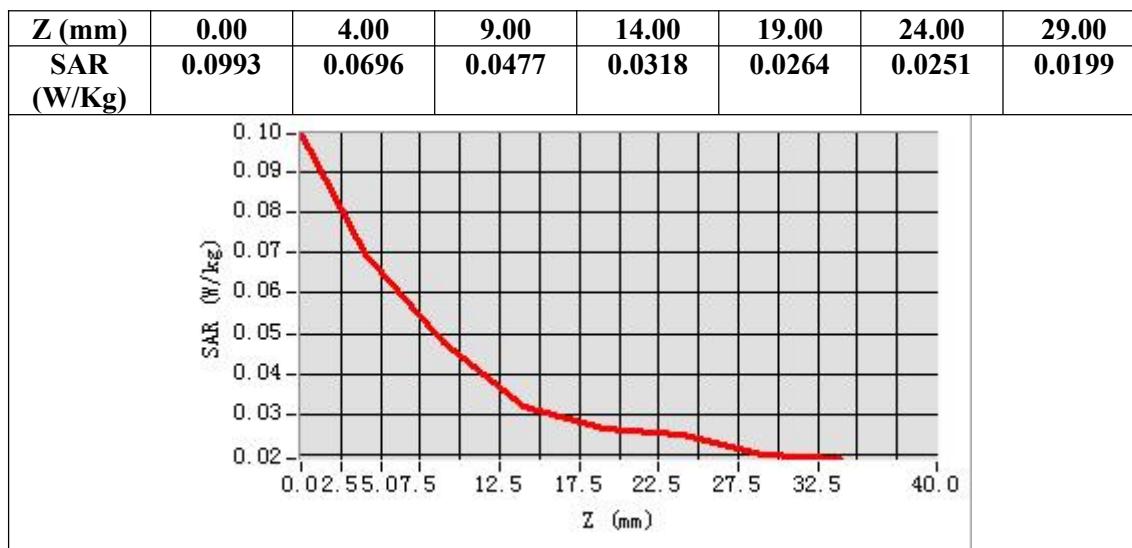
| | |
|-----------------------|----------|
| SAR 10g (W/Kg) | 0.037674 |
| SAR 1g (W/Kg) | 0.064238 |

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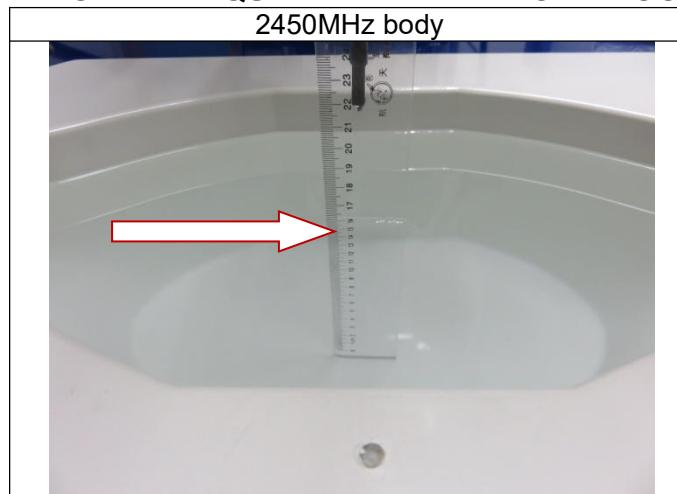


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DEPTH OF THE LIQUID IN THE PHANTOM—ZOOM IN

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APPENDIX C. TEST SETUP PHOTOGRAPHS

Refer to Attached files.

APPENDIX D. CALIBRATION DATA

Refer to Attached files.

----END OF REPORT----

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4. In the event of the improper use of the report as determined by the Company, the Company reserves the right to withdraw it, and to adopt any other additional remedies which may be appropriate.
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