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# SAR Test Report

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Report No.: AGC15705230931FH01

**FCC ID** : 2BC08-DRONE

**APPLICATION PURPOSE** : Original Equipment

**PRODUCT DESIGNATION** : GPS OBSTACLE AVOIDANCE DRONE

**BRAND NAME** : TRIPLEFINE

**MODEL NAME** : TF15-EX, TF770

**APPLICANT** : Guangzhou Xingde Industrial Development Co., LTD

**DATE OF ISSUE** : Oct. 18, 2023

**STANDARD(S)** : IEEE Std. 1528:2013  
FCC 47 CFR Part 2§2.1093  
IEEE Std C95.1™-2005

**REPORT VERSION** : V1.0

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**Report Revise Record**

Report Version	Revise Time	Issued Date	Valid Version	Notes
V1.0	/	Oct. 18, 2023	Valid	Initial Release

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Test Report	
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Applicant Address	Room 301, No. 2, Yingcai Street, Tianhe District, Guangzhou City, Guangdong province, China
Manufacturer Name	HK TECH SCIENCE&TECHNOLOGY CO., LTD
Manufacturer Address	Chenghai District Laimeilu South Union Industrial Park B District 4 South Building, Shantou City, Guangdong Province, China
Factory Name	Guangzhou Xingde Industrial Development Co., LTD
Factory Address	Room 301, No. 2, Yingcai Street, Tianhe District, Guangzhou City, Guangdong province, China
Product Designation	GPS OBSTACLE AVOIDANCE DRONE
Brand Name	TRIPLEFINE
Model Name	TF15-EX
Series model	TF770
Declaration of Difference	All the same except the appearance color, packaging and model name.
EUT Voltage	DC3.7V by battery
Applicable Standard	IEEE Std. 1528:2013 FCC 47 CFR Part 2§2.1093 IEEE Std C95.1™-2005
Date of receipt of test item	Sep. 12, 2023
Test Date	Oct. 07, 2023
Report Template	AGCRT-US-5G/SAR (2021-04-20)

Note: The results of testing in this report apply to the product/system which was tested only.

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Oct. 07, 2023

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Oct. 18, 2023

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Oct. 18, 2023

Max Zhang (Authorized Officer)

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## 1. SUMMARY OF MAXIMUM SAR VALUE

The maximum results of Specific Absorption Rate (SAR) found during testing for EUT are as follows:

Frequency Band	Highest Reported 10g Extremity-SAR (W/kg) with 0mm separation	SAR Test Limit (W/kg)
5.2 GHz WIFI_Ant.1 802.11a	0.992	4.0
5.2 GHz WIFI_Ant.2 802.11a	0.616	
5.2 GHz WIFI_Ant.1 802.11 n(20)	0.608	
5.2 GHz WIFI_Ant.2 802.11 n(20)	0.474	
MIMO	1.082	
<b>SAR Test Result</b>	<b>PASS</b>	

This device is compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (4.0W/kg) specified in IEEE Std. 1528:2013; FCC 47CFR § 2.1093; IEEE/ANSI C95.1:2005 and the following specific FCC Test Procedures:

- KDB 447498 D01 General RF Exposure Guidance v06
- KDB 865664 D01 SAR Measurement 100MHz to 6GHz v01r04
- KDB 248227 D01 802.11 Wi-Fi SAR v02r02

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## 2. GENERAL INFORMATION

### 2.1. EUT Description

General Information	
Product Designation	GPS OBSTACLE AVOIDANCE DRONE
Test Model	TF15-EX
Hardware Version	V1.0
Software Version	V1.0
Device Category	Portable
RF Exposure Environment	Uncontrolled
Antenna Type	Internal
5GHz WIFI	
WIFI Specification	<input checked="" type="checkbox"/> 802.11a <input checked="" type="checkbox"/> 802.11n20 <input checked="" type="checkbox"/> 802.11ac20 <input type="checkbox"/> 802.11n40 <input type="checkbox"/> 802.11ac40 <input type="checkbox"/> 802.11ac80
Operation Frequency	5.150GHz~5.250GHz
Type of modulation	802.11a/n:(64-QAM, 16-QAM, QPSK, BPSK) OFDM 802.11ac :(256-QAM, 64-QAM, 16-QAM, QPSK, BPSK) OFDM
EIRP	Ant. 1: 10.96dBm; Ant. 2: 10.60dBm; MIMO: 12.90dBm
Antenna Gain	2.4dBi
Power supply	DC3.7V, 1200mAh by battery

Note: 1. The sample used for testing is end product.

2. The test sample has no any deviation to the test method of standard mentioned in page 1.

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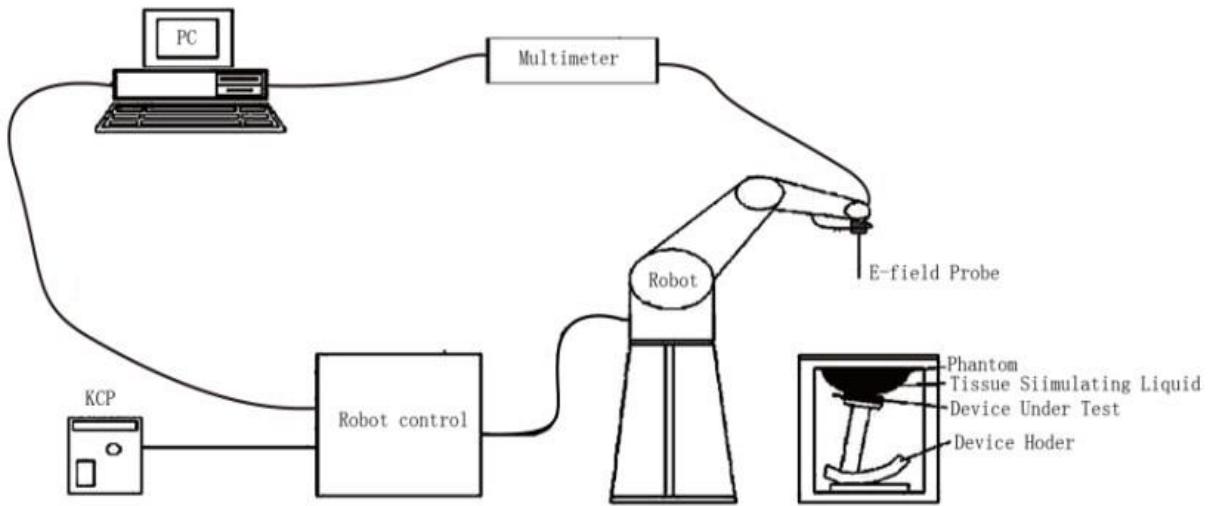
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### 3. SAR MEASUREMENT SYSTEM

#### 3.1. The SATIMO system used for performing compliance tests consists of following items



The COMOSAR system for performing compliance tests consists of the following items:

- The PC. It controls most of the bench devices and stores measurement data. A computer running WinXP and the Opensar software.
- The E-Field probe. The probe is a 3-axis system made of 3 distinct dipoles. Each dipole returns a voltage in function of the ambient electric field.
- The Keithley multimeter measures each probe dipole voltages.
- The SAM phantom simulates a human head. The measurement of the electric field is made inside the phantom.
- The liquids simulate the dielectric properties of the human head tissues.
- The network emulator controls the mobile phone under test.
- The validation dipoles are used to measure a reference SAR. They are used to periodically check the bench to make sure that there is no drift of the system characteristics over time.
- The phantom, the device holder and other accessories according to the targeted measurement.

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### 3.2. COMOSAR E-Field Probe

The SAR measurement is conducted with the dosimetric probe manufactured by SATIMO. The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. SATIMO conducts the probe calibration in compliance with international and national standards (e.g. IEEE1528 etc.) Under ISO17025. The calibration data are in Appendix D.

#### Isotropic E-Field Probe Specification

<b>Model</b>	SSE2
<b>Manufacture</b>	MVG
<b>Identification No.</b>	SN 45/22 EPGO391
<b>Frequency</b>	0.15GHz-6GHz Linearity:±0.09dB(0.15GHz-6GHz)
<b>Dynamic Range</b>	0.01W/kg-100W/kg Linearity:±0.09dB
<b>Dimensions</b>	Overall length:330mm Length of individual dipoles:2mm Maximum external diameter:8mm Probe Tip external diameter:2.5mm Distance between dipoles/ probe extremity:1mm
<b>Application</b>	High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 6 GHz with precision of better 30%.



### 3.3. Robot

The COMOSAR system uses the KUKA robot from SATIMO SA (France). For the 6-axis controller COMOSAR system, the KUKA robot controller version from SATIMO is used.

The XL robot series have many features that are important for our application:

- High precision (repeatability 0.02 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)
- 6-axis controller



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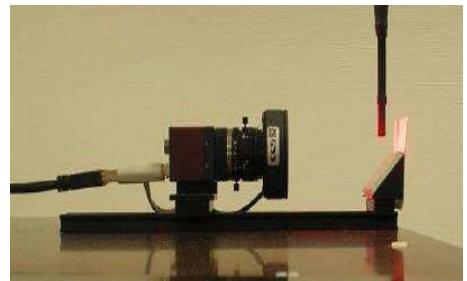
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### 3.4. Video Positioning System

The video positioning system is used in OpenSAR to check the probe. Which is composed of a camera, LED, mirror and mechanical parts. The camera is piloted by the main computer with firewire link. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip. The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.

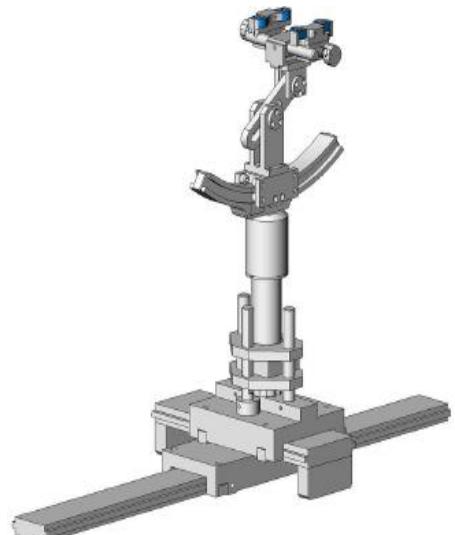


### 3.5. Device Holder

The COMOSAR device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR). Thus the device needs no repositioning when changing the angles.

The COMOSAR device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity

$\epsilon_r = 3$  and loss tangent  $\delta = 0.02$ . The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



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### 3.6. SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

- Left head
- Right head
- Flat phantom



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

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## 4. SAR MEASUREMENT PROCEDURE

### 4.1. Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and occupational/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element(dv) of given mass density (ρ). The equation description is as below:

$$\text{SAR} = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho dV} \right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR can be obtained using either of the following equations:

$$\text{SAR} = \frac{\sigma E^2}{\rho}$$

$$\text{SAR} = c_h \frac{dT}{dt} \Big|_{t=0}$$

Where

SAR	is the specific absorption rate in watts per kilogram;
E	is the r.m.s. value of the electric field strength in the tissue in volts per meter;
σ	is the conductivity of the tissue in siemens per metre;
ρ	is the density of the tissue in kilograms per cubic metre;
c <sub>h</sub>	is the heat capacity of the tissue in joules per kilogram and Kelvin;

$\frac{dT}{dt} \Big|_{t=0}$  is the initial time derivative of temperature in the tissue in kelvins per second

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## 4.2. SAR Measurement Procedure

### Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurement are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface is 2.7mm. This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties,

### Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in SATIMO software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in db) is specified in the standards for compliance testing. For example, a 2db range is required in IEEE Standard 1528 standards, whereby 3db is a requirement when compliance is assessed in accordance with the ARIB standard (Japan). If one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximum are detected, the number of Zoom Scan has to be increased accordingly.

Area Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100MHz to 6GHz

	$\leq 3$ GHz	$> 3$ GHz
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	$5 \pm 1$ mm	$\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5$ mm
Maximum probe angle from probe axis to phantom surface normal at the measurement location	$30^\circ \pm 1^\circ$	$20^\circ \pm 1^\circ$
	$\leq 2$ GHz: $\leq 15$ mm $2 - 3$ GHz: $\leq 12$ mm	$3 - 4$ GHz: $\leq 12$ mm $4 - 6$ GHz: $\leq 10$ mm
Maximum area scan spatial resolution: $\Delta x_{\text{Area}}$ , $\Delta y_{\text{Area}}$	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be $\leq$ the corresponding x or y dimension of the test device with at least one measurement point on the test device.	

### Step 3: Zoom Scan

Zoom Scan are used to assess the peak spatial SAR value within a cubic average volume containing 1g and 10g of simulated tissue. The Zoom Scan measures points (refer to table below) within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1g and 10g and displays these values next to the job's label.

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## Zoom Scan Parameters extracted from KDB865664 d01 SAR Measurement 100MHz to 6GHz

Maximum zoom scan spatial resolution: $\Delta x_{Zoom}$ , $\Delta y_{Zoom}$		$\leq 2$ GHz: $\leq 8$ mm $2 - 3$ GHz: $\leq 5$ mm*	$3 - 4$ GHz: $\leq 5$ mm* $4 - 6$ GHz: $\leq 4$ mm*	
Maximum zoom scan spatial resolution, normal to phantom surface	uniform grid: $\Delta z_{Zoom}(n)$  graded grid	$\leq 5$ mm	$3 - 4$ GHz: $\leq 4$ mm $4 - 5$ GHz: $\leq 3$ mm $5 - 6$ GHz: $\leq 2$ mm	
		$\leq 4$ mm	$3 - 4$ GHz: $\leq 3$ mm $4 - 5$ GHz: $\leq 2.5$ mm $5 - 6$ GHz: $\leq 2$ mm	
Minimum zoom scan volume	x, y, z	$\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$		
		$\geq 30$ mm	$3 - 4$ GHz: $\geq 28$ mm $4 - 5$ GHz: $\geq 25$ mm $5 - 6$ GHz: $\geq 22$ mm	
Note: $\delta$ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.				
* When zoom scan is required and the <u>reported</u> SAR from the <i>area scan based 1-g SAR estimation</i> procedures of KDB 447498 is $\leq 1.4$ W/kg, $\leq 8$ mm, $\leq 7$ mm and $\leq 5$ mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.				

## Step 4: Power Drift Measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the same settings. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

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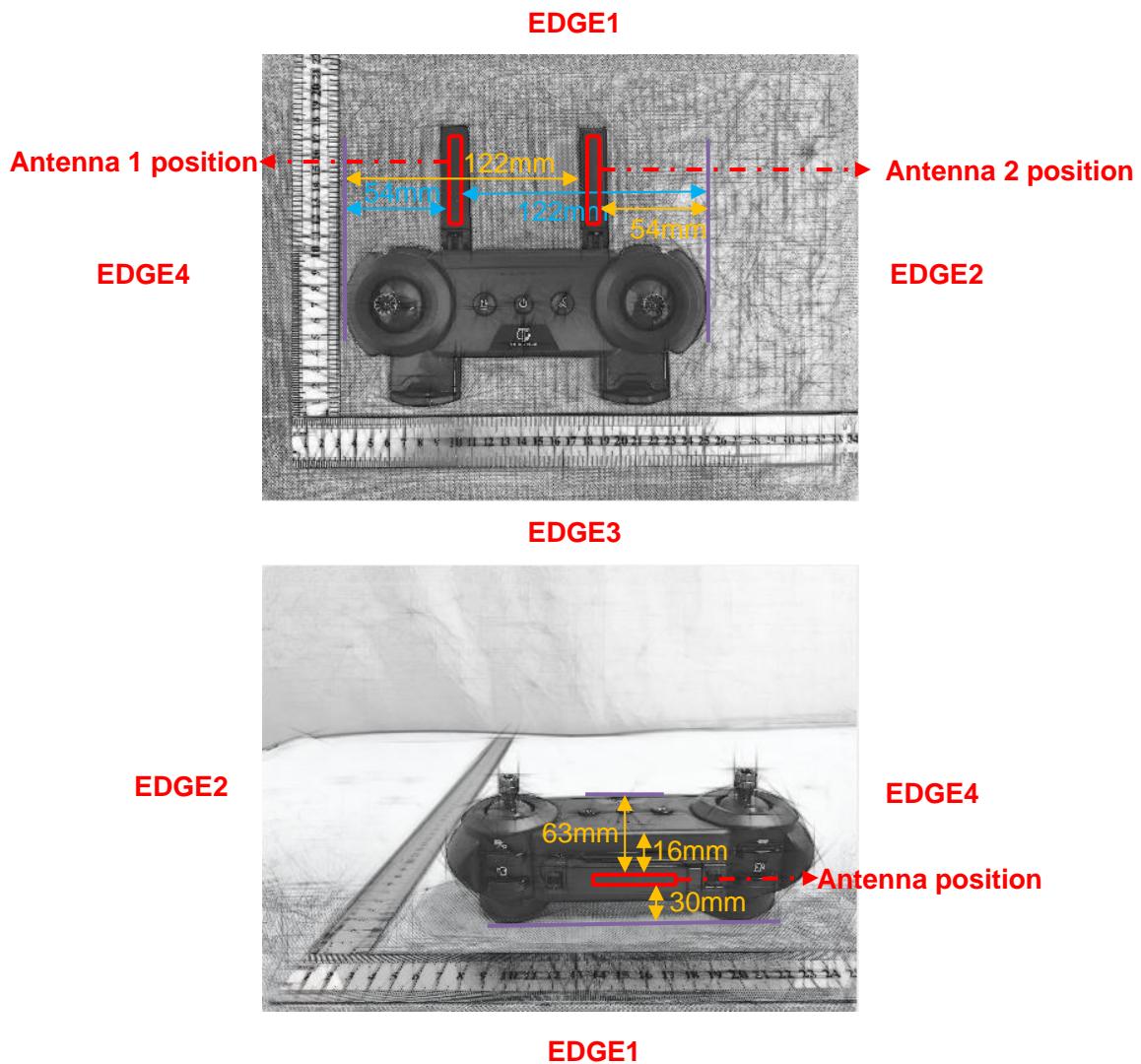
### 4.3. RF Exposure Conditions

Test Configuration and setting:

The device is a controller of GPS bostacle avoidance drone which support 5G WIFI.

For SAR testing, the EUT is configured with the WLAN continuous TX tool through qualcomm software.

**Antenna Location:**



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## 5. TISSUE SIMULATING LIQUID

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 5% are listed in 5.2

### 5.1. The composition of the tissue simulating liquid

Ingredient (% Weight)	Water	NaCl	Polysorbate 20	DGBE	1,2- Propanediol	Triton X-100	Diethylen glycol monohex ylether
Frequency (MHz)							
5000 Head	65.52	0.0	0.0	0.0	0.0	17.24	17.24

### 5.2. Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEEE 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in IEEE 1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations described in Reference [12] and extrapolated according to the head parameters specified in IEEE 1528.

Target Frequency (MHz)	head		body	
	$\epsilon_r$	$\sigma$ (S/m)	$\epsilon_r$	$\sigma$ (S/m)
300	45.3	0.87	45.3	0.87
450	43.5	0.87	43.5	0.87
835	41.5	0.90	41.5	0.90
900	41.5	0.97	41.5	0.97
1450	40.5	1.20	40.5	1.20
1800 – 2000	40.0	1.40	40.0	1.40
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	38.5	2.40
<b>5200</b>	<b>36.0</b>	<b>4.66</b>	49.0	5.30
5300	35.9	4.76	48.9	5.42
5600	35.5	5.07	48.5	5.77
5800	35.3	5.27	48.2	6.00

( $\epsilon_r$  = relative permittivity,  $\sigma$  = conductivity and  $\rho = 1000$  kg/m<sup>3</sup>)

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### 5.3. Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using SATIMO Dielectric Probe Kit and R&S Network Analyzer ZVL6.

Tissue Stimulant Measurement for 5200MHz					
Head	Fr. (MHz)	Dielectric Parameters ( $\pm 5\%$ )		Tissue Temp [°C]	Test time
		$\epsilon_r$ 36(34.2-37.8)	$\delta$ [s/m] 4.66(4.43-4.89)		
	5200	36.58	4.61	21.1	Oct. 07, 2023

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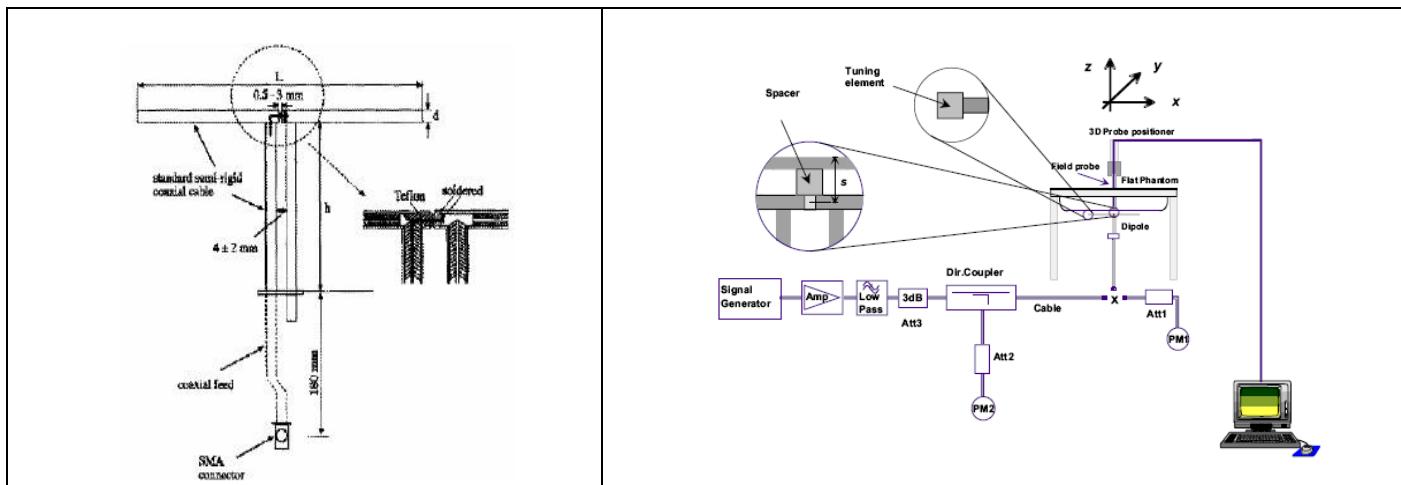
## 6. SAR SYSTEM CHECK PROCEDURE

### 6.1. SAR System Check Procedures

SAR system check is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device. The same SAR probe(s) and tissue-equivalent media combinations used with each specific SAR system for system verification must be used for device testing. When multiple probe calibration points are required to cover substantially large transmission bands, independent system verifications are required for each probe calibration point. A system verification must be performed before each series of SAR measurements using the same probe calibration point and tissue-equivalent medium. Additional system verification should be considered according to the conditions of the tissue-equivalent medium and measured tissue dielectric parameters, typically every three to four days when the liquid parameters are remeasured or sooner when marginal liquid parameters are used at the beginning of a series of measurements.

Each SATIMO system is equipped with one or more system check kits. These units, together with the predefined measurement procedures within the SATIMO software, enable the user to conduct the system check and system validation. System kit includes a dipole, and dipole device holder.

The system check verifies that the system operates within its specifications. It's performed daily or before every SAR measurement. The system check uses normal SAR measurement in the flat section of the phantom with a matched dipole at a specified distance. The system check setup is shown as below.



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## 6.2. SAR System Check

### 6.2.1. Dipoles

	<p>The dipole is based on the IEEE-1528 standard, and is complied with mechanical and electrical specifications in line with the requirements of IEEE. The table below provides details for the mechanical and electrical specifications for the wave guide.</p>
--	--

Frequency	L (mm)	h (mm)	d (mm)
5000MHz	20.6	40.3	3.6

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### 6.2.2. System Check Result

System Performance Check at 5200-5800MHz for Head								
Validation Kit: SN 17/22 DIP 5G000-671								
Frequency [MHz]	Target Value(W/kg)		Reference Result (± 10%)		Normalized to 1W(W/kg)		Tissue Temp. [°C]	Test time
	1g	10g	1g	10g	1g	10g		
5200	73.43	21.83	66.087-80.773	19.647-24.013	69.45	21.89	21.1	Oct. 07, 2023

**Note:**

(1) We use a CW signal of 10dBm for system check, and then all SAR values are normalized to 1W forward power. The result must be within ±10% of target value.

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## 7. EUT TEST POSITION

This EUT was tested in **Edge1**.

### 7.1. Limb Position

- (1) To position the EUT parallel to the phantom surface.
- (2) To adjust the EUT parallel to the flat phantom.
- (3) To adjust the distance between the EUT surface and the flat phantom to **0mm**.

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## 8. SAR EXPOSURE LIMITS

### Limits for General Population/Uncontrolled Exposure (W/kg)

Type Exposure	Uncontrolled Environment Limit (W/kg)
Spatial Peak SAR (1 g cube tissue for brain or body)	1.60
Spatial Average SAR (Whole body)	0.08
Spatial Peak SAR (Limbs)	4.0

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## 9. TEST FACILITY

<b>Test Site</b>	Attestation of Global Compliance (Shenzhen) Co., Ltd
<b>Location</b>	1-2/F, Building 19, Junfeng Industrial Park, Chongqing Road, Heping Community, Fuhai Street, Bao'an District, Shenzhen, Guangdong, China
<b>Designation Number</b>	CN1259
<b>FCC Test Firm Registration Number</b>	975832
<b>A2LA Cert. No.</b>	5054.02
<b>Description</b>	Attestation of Global Compliance(Shenzhen) Co., Ltd is accredited by A2LA

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## 10. TEST EQUIPMENT LIST

Equipment description	Manufacturer/ Model	Identification No.	Software version	Current calibration date	Next calibration date
SAR Probe	MVG	SN 45/22 EPGO391	N/A	Dec. 02, 2022	Dec. 01, 2023
Phantom	SATIMO	SN_4511_SAM90	N/A	Validated. No cal required.	Validated. No cal required.
Liquid	SATIMO	N/A	N/A	Validated. No cal required.	Validated. No cal required.
Multimeter	Keithley 2000	4114939	N/A	Jun. 01, 2023	May 31, 2024
SAR Software	MVG-OpenSAR	N/A	OpenSAR V4_02_35	N/A	N/A
Dipole	SID5000	SN 17/22 DIP 5G000-671	N/A	Apr. 28,2022	Apr. 27, 2025
Signal Generator	Agilent-E4438C	US41461365	V5.03	Jun. 01, 2023	May 31, 2024
EXA Signal Analyzer	Agilent / N9010A	MY53470504	N/A	Jun. 01, 2023	May 31, 2024
Network Analyzer	Rhode & Schwarz ZVL6	SN101443	3.2	Oct. 17, 2022	Oct. 16, 2023
Attenuator	Warison /WATT-6SR1211	S/N:WRJ34AYM2F1	N/A	June 07,2023	June 06,2024
Attenuator	Mini-circuits / VAT-10+	31405	N/A	June 07,2023	June 06,2024
Amplifier	AS0104-55_55	1004793	N/A	N/A	N/A
Directional Couple	Werlatone/ C5571-10	SN99463	N/A	Mar. 10,2022	Mar. 09,2024
Directional Couple	Werlatone/ C6026-10	SN99482	N/A	Mar. 10,2022	Mar. 09,2024
Power Sensor	NRP-Z21	1137.6000.02	N/A	Sep. 05, 2023	Sep. 04, 2024
Power Sensor	NRP-Z23	100323	N/A	Feb. 15,2023	Feb. 14,2024
Power Viewer	R&S	V2.3.1.0		N/A	N/A
Calibration standard parts for network sub - port	R&S/ ZV-Z132	N/A	V2.3.1.0	Nov. 15,2022	Nov. 14,2023

Note: Per KDB 865664 Dipole SAR Validation, AGC Lab has adopted 3 years calibration intervals. On annual basis, every measurement dipole has been evaluated and is in compliance with the following criteria:

1. There is no physical damage on the dipole;
2. System validation with specific dipole is within 10% of calibrated value;
3. Return-loss is within 20% of calibrated measurement;
4. Impedance is within 5Ω of calibrated measurement.

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## 11. MEASUREMENT UNCERTAINTY

SATIMO Uncertainty- SN 45/22 EPGO391 Measurement uncertainty for DUT averaged over 1 gram / 10 gram.									
Uncertainty Component	Sec.	Tol (+- %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	vi
<b>Measurement System</b>									
Probe calibration	E.2.1	7.000	N	1	1	1	7.000	7.000	$\infty$
Axial Isotropy	E.2.2	0.215	R	1.732	0.707	0.707	0.088	0.088	$\infty$
Hemispherical Isotropy	E.2.2	0.215	R	1.732	0.707	0.707	0.088	0.088	$\infty$
Boundary effect	E.2.3	1.000	R	1.732	1	1	0.577	0.577	$\infty$
Linearity	E.2.4	0.995	R	1.732	1	1	0.574	0.574	$\infty$
System detection limits	E.2.4	1.000	R	1.732	1	1	0.577	0.577	$\infty$
Modulation response	E2.5	3.000	R	1.732	1	1	1.732	1.732	$\infty$
Readout Electronics	E.2.6	0.021	N	1	1	1	0.021	0.021	$\infty$
Response Time	E.2.7	0.000	R	1.732	1	1	0.000	0.000	$\infty$
Integration Time	E.2.8	1.400	R	1.732	1	1	0.808	0.808	$\infty$
RF ambient conditions-Noise	E.6.1	3.000	R	1.732	1	1	1.732	1.732	$\infty$
RF ambient conditions-reflections	E.6.1	3.000	R	1.732	1	1	1.732	1.732	$\infty$
Probe positioner mechanical tolerance	E.6.2	1.400	R	1.732	1	1	0.808	0.808	$\infty$
Probe positioning with respect to phantom shell	E.6.3	1.400	R	1.732	1	1	0.808	0.808	$\infty$
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.300	R	1.732	1	1	1.328	1.328	$\infty$
<b>Test sample Related</b>									
Test sample positioning	E.4.2	2.6	N	1	1	1	2.60	2.60	$\infty$
Device holder uncertainty	E.4.1	3	N	1	1	1	3.00	3.00	$\infty$
Output power variation—SAR drift measurement	E.2.9	5	R	1.732	1	1	2.89	2.89	$\infty$
SAR scaling	E.6.5	5	R	1.732	1	1	2.89	2.89	$\infty$
<b>Phantom and tissue parameters</b>									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	1.732	1	1	2.309	2.309	$\infty$
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.900	1.596	$\infty$
Liquid conductivity measurement	E.3.3	4	N	1	0.78	0.71	3.120	2.840	M
Liquid permittivity measurement	E.3.3	5	N	1	0.23	0.26	1.150	1.300	M
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	1.732	0.78	0.71	1.126	1.025	$\infty$
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	1.732	0.23	0.26	0.332	0.375	$\infty$
Combined Standard Uncertainty			RSS				10.529	10.344	
Expanded Uncertainty (95% Confidence interval)			K=2				21.059	20.689	

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SATIMO Uncertainty- SN 45/22 EPGO391 System Validation uncertainty for DUT averaged over 1 gram / 10 gram.									
Uncertainty Component	Sec.	Tol (+- %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	vi
<b>Measurement System</b>									
Probe calibration	E.2.1	7.000	N	1	1	1	7.000	7.000	$\infty$
Axial Isotropy	E.2.2	0.215	R	1.732	1.000	1.000	0.124	0.124	$\infty$
Hemispherical Isotropy	E.2.2	0.215	R	1.732	0.000	0.000	0.000	0.000	$\infty$
Boundary effect	E.2.3	1.000	R	1.732	1.000	1.000	0.577	0.577	$\infty$
Linearity	E.2.4	0.995	R	1.732	1.000	1.000	0.574	0.574	$\infty$
System detection limits	E.2.4	1.000	R	1.732	1.000	1.000	0.577	0.577	$\infty$
Modulation response	E2.5	3.000	R	1.732	0.000	0.000	0.000	0.000	$\infty$
Readout Electronics	E.2.6	0.021	N	1.000	1.000	1.000	0.021	0.021	$\infty$
Response Time	E.2.7	0.000	R	1.732	0.000	0.000	0.000	0.000	$\infty$
Integration Time	E.2.8	1.400	R	1.732	0.000	0.000	0.000	0.000	$\infty$
RF ambient conditions-Noise	E.6.1	3.000	R	1.732	1.000	1.000	1.732	1.732	$\infty$
RF ambient conditions-reflections	E.6.1	3.000	R	1.732	1.000	1.000	1.732	1.732	$\infty$
Probe positioner mechanical tolerance	E.6.2	1.400	R	1.732	1.000	1.000	0.808	0.808	$\infty$
Probe positioning with respect to phantom shell	E.6.3	1.400	R	1.732	1.000	1.000	0.808	0.808	$\infty$
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.300	R	1.732	1.000	1.000	1.328	1.328	$\infty$
<b>System validation source</b>									
Deviation of experimental dipole from numerical dipole	E.6.4	5	N	1	1	1	5	5	$\infty$
Input power and SAR drift measurement	8,E.6.4	5	R	1.732	1	1	2.887	2.887	$\infty$
Dipole axis to liquid distance	8,E.6.6	2	R	1.732	1	1	1.155	1.155	$\infty$
<b>Phantom and set-up</b>									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	1.732	1	1	2.309	2.309	$\infty$
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.9	1.596	$\infty$
Liquid conductivity (temperature uncertainty)	E.3.3	4	N	1	0.78	0.71	3.12	2.84	$\infty$
Liquid conductivity (measured)	E.3.3	5	N	1	0.23	0.26	1.15	1.3	M
Liquid permittivity (temperature uncertainty)	E.3.4	2.5	R	1.732	0.78	0.71	1.126	1.025	$\infty$
Liquid permittivity (measured)	E.3.4	2.5	R	1.732	0.23	0.26	0.332	0.375	M
Combined Standard Uncertainty			RSS				10.462	10.276	
Expanded Uncertainty (95% Confidence interval)			K=2				20.925	20.552	

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SATIMO Uncertainty- SN 45/22 EPGO391 System Check uncertainty for DUT averaged over 1 gram / 10 gram.									
Uncertainty Component	Sec.	Tol (+- %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	vi
<b>Measurement System</b>									
Probe calibration drift	E.2.1.3	7.000	N	1	1	1	7	7	$\infty$
Axial Isotropy	E.2.2	0.215	R	$\sqrt{3}$	0	0	0	0	$\infty$
Hemispherical Isotropy	E.2.2	0.215	R	$\sqrt{3}$	0	0	0	0	$\infty$
Boundary effect	E.2.3	1.000	R	$\sqrt{3}$	0	0	0	0	$\infty$
Linearity	E.2.4	0.995	R	$\sqrt{3}$	0	0	0	0	$\infty$
System detection limits	E.2.4	1	R	$\sqrt{3}$	0	0	0	0	$\infty$
Modulation response	E.2.5	3	R	$\sqrt{3}$	0	0	0	0	$\infty$
Readout Electronics	E.2.6	0.021	N	$\sqrt{3}$	0	0	0	0	$\infty$
Response Time	E.2.7	0	R	$\sqrt{3}$	0	0	0	0	$\infty$
Integration Time	E.2.8	1.4	R	$\sqrt{3}$	0	0	0	0	$\infty$
RF ambient conditions-Noise	E.6.1	3	R	$\sqrt{3}$	0	0	0	0	$\infty$
RF ambient conditions-reflections	E.6.1	3	R	$\sqrt{3}$	0	0	0	0	$\infty$
Probe positioner mechanical tolerance	E.6.2	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	$\infty$
Probe positioning with respect to phantom shell	E.6.3	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	$\infty$
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.3	R	$\sqrt{3}$	0	0	0	0.00	$\infty$
<b>System check source (dipole)</b>									
Deviation of experimental dipoles	E.6.4	2	N	1	1	1	2	2	$\infty$
Input power and SAR drift measurement	8,E.6.4	5	R	$\sqrt{3}$	1	1	2.89	2.89	$\infty$
Dipole axis to liquid distance	8,E.6.6	2	R	$\sqrt{3}$	1	1	1.15	1.15	$\infty$
<b>Phantom and tissue parameters</b>									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	$\sqrt{3}$	1	1	2.31	2.31	$\infty$
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1.000	1	0.84	1.90	1.60	$\infty$
Liquid conductivity measurement	E.3.3	4	N	1.000	0.78	0.71	3.12	2.84	$\infty$
Liquid permittivity measurement	E.3.3	5	N	1.000	0.23	0.26	1.15	1.30	M
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.78	0.71	1.13	1.02	$\infty$
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.23	0.26	0.33	0.38	M
Combined Standard Uncertainty			RSS				8.927	8.708	
Expanded Uncertainty (95% Confidence interval)			K=2				17.853	17.415	

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## 12. CONDUCTED POWER MEASUREMENT

### 5GHz WIFI\_ANT.1

Mode	channel	Frequency	Power(dBm)								
			Data Rate(bps)								
			6M	9M	12M	18M	24M	36M	48M	54M	
802.11a	36	5180	<b>10.96</b>	10.87	10.84	10.79	10.60	10.51	10.41	10.35	
	40	5200	9.95	9.91	9.74	9.54	9.42	9.31	9.22	9.20	
	44	5220	9.62	9.56	9.46	9.28	9.10	9.10	9.04	8.86	
	48	5240	9.73	9.63	9.60	9.53	9.42	9.35	9.26	9.23	
			<b>MCS0</b>	<b>MCS1</b>	<b>MCS2</b>	<b>MCS3</b>	<b>MCS4</b>	<b>MCS5</b>	<b>MCS6</b>	<b>MCS7</b>	
802.11n (20)	36	5180	9.87	9.70	9.68	9.55	9.46	9.30	9.28	9.15	
	40	5200	10.16	10.05	9.96	9.79	9.62	9.54	9.47	9.42	
	44	5220	9.86	9.77	9.66	9.58	9.39	9.29	9.25	9.23	
	48	5240	9.64	9.63	9.45	9.39	9.25	9.20	9.01	8.89	
			<b>MCS0</b>	<b>MCS1</b>	<b>MCS2</b>	<b>MCS3</b>	<b>MCS4</b>	<b>MCS5</b>	<b>MCS6</b>	<b>MCS7</b>	
802.11ac (20)	36	5180	8.77	8.77	8.57	8.56	8.41	8.29	8.26	8.07	
	40	5200	9.33	9.30	9.23	9.21	9.17	8.99	8.86	8.72	
	44	5220	9.22	9.22	9.06	8.99	8.84	8.83	8.67	8.50	
	48	5240	9.57	9.50	9.37	9.34	9.21	9.16	9.14	9.10	

### 5GHz WIFI\_ANT.2

Mode	channel	Frequency	Power(dBm)								
			Data Rate(bps)								
			6M	9M	12M	18M	24M	36M	48M	54M	
802.11a	36	5180	<b>10.60</b>	10.47	10.31	10.22	10.10	9.91	9.83	9.63	
	40	5200	9.18	9.04	8.87	8.82	8.77	8.62	8.47	8.34	
	44	5220	9.12	9.02	8.86	8.68	8.50	8.38	8.32	8.24	
	48	5240	9.38	9.35	9.23	9.12	9.00	8.99	8.81	8.80	
			<b>MCS0</b>	<b>MCS1</b>	<b>MCS2</b>	<b>MCS3</b>	<b>MCS4</b>	<b>MCS5</b>	<b>MCS6</b>	<b>MCS7</b>	
802.11n (20)	36	5180	9.91	9.71	9.55	9.55	9.54	9.49	9.40	9.28	
	40	5200	9.46	9.34	9.31	9.23	9.08	8.96	8.76	8.62	
	44	5220	9.33	9.29	9.12	8.96	8.95	8.87	8.77	8.66	
	48	5240	9.15	9.07	9.04	8.86	8.66	8.50	8.40	8.33	
			<b>MCS0</b>	<b>MCS1</b>	<b>MCS2</b>	<b>MCS3</b>	<b>MCS4</b>	<b>MCS5</b>	<b>MCS6</b>	<b>MCS7</b>	
802.11ac (20)	36	5180	8.40	8.35	8.29	8.20	8.07	7.98	7.84	7.74	
	40	5200	8.85	8.65	8.63	8.45	8.29	8.26	8.11	8.06	
	44	5220	8.65	8.64	8.60	8.43	8.40	8.27	8.24	8.14	
	48	5240	8.77	8.62	8.50	8.48	8.45	8.34	8.15	7.97	

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**5GHz WIFI\_MIMO**

Mode	channel	Frequency	Power(dBm)							
			Data Rate(bps)							
			MCS0	MCS1	MCS2	MCS3	MCS4	MCS5	MCS6	MCS7
802.11n (20)	36	5180	12.90	12.72	12.63	12.56	12.51	12.41	12.35	12.23
	40	5200	12.83	12.72	12.66	12.53	12.37	12.27	12.14	12.05
	44	5220	12.61	12.55	12.41	12.29	12.19	12.10	12.03	11.96
	48	5240	12.41	12.37	12.26	12.14	11.98	11.87	11.73	11.63
			MCS0	MCS1	MCS2	MCS3	MCS4	MCS5	MCS6	MCS7
802.11ac (20)	36	5180	11.60	11.58	11.44	11.39	11.25	11.15	11.07	10.92
	40	5200	12.11	12.00	11.95	11.86	11.76	11.65	11.51	11.41
	44	5220	11.95	11.95	11.85	11.73	11.64	11.57	11.47	11.33
	48	5240	12.20	12.09	11.97	11.94	11.86	11.78	11.68	11.58

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## 13. TEST RESULTS

### 13.1. SAR Test Results Summary

#### 13.1.1. Test position and configuration

1. The EUT is a controller of GPS bostacle avoidance drone.
2. Lab use the head liquid with a separation of 0mm at flat phantom to test;
3. For SAR testing, the device was controlled by software to test at reference fixed frequency points.

#### 13.1.2. Operation Mode

1. Maximum Scaling SAR in order to calculate the Maximum SAR values to test under the standard Peak Power, Calculation method is as follows:  
Maximum Scaling SAR = tested SAR (Max.)  $\times$  [maximum turn-up power (mw)/ maximum measurement output power(mw) ]

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### 13.1.3. SAR Test Results Summary

SAR MEASUREMENT								
Depth of Liquid (cm):>15								
Product: GPS OBSTACLE AVOIDANCE DRONE								
Test Mode: 5.2GHz								
Position	Ch.	Fr. (MHz)	Power Drift (<±5%)	10g-Extremity SAR (W/kg)	Max. Tune-up Power (dBm)	Meas. output Power (dBm)	Scaled SAR (W/kg)	Limit (W/kg)
ANT.1_802.11a								
Edge 1 (Top)_horizontal	40	5200	-0.21	<b>0.779</b>	11.00	9.95	<b>0.992</b>	4.0
Edge 1 (Top)_vertical	40	5200	0.32	0.135	11.00	9.95	0.172	4.0
ANT.2_802.11a								
Edge 1 (Top)_horizontal	40	5200	-0.27	<b>0.434</b>	10.70	9.18	<b>0.616</b>	4.0
Edge 1 (Top)_vertical	40	5200	0.10	0.136	10.70	9.18	0.193	4.0

Note:

- When the 1-g SAR is ≤ 2.0W/kg, testing for low and high channel is optional.
- The test separation of all above table is 0mm.
- Plots are only shown for the bold marked worst case SAR results

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SAR MEASUREMENT								
Depth of Liquid (cm):>15								
Product: GPS OBSTACLE AVOIDANCE DRONE								
Test Mode: 5.2GHz								
Position	Ch.	Fr. (MHz)	Power Drift (<±5%)	10g-Extremity SAR (W/kg)	Max. Tune-up Power (dBm)	Meas. output Power (dBm)	Scaled SAR (W/kg)	Limit (W/kg)
ANT.1_802.11n(20)								
Edge 1 (Top)_horizontal	40	5200	-0.12	<b>0.602</b>	10.20	10.16	<b>0.608</b>	4.0
Edge 1 (Top)_vertical	40	5200	0.03	0.117	10.20	10.16	0.118	4.0
ANT.2_802.11n(20)								
Edge 1 (Top)_horizontal	40	5200	-0.24	<b>0.419</b>	10.00	9.46	<b>0.474</b>	4.0
Edge 1 (Top)_vertical	40	5200	0.10	0.135	10.00	9.46	0.153	4.0

## Note:

- When the 1-g SAR is ≤ 2.0W/kg, testing for low and high channel is optional.
- The test separation of all above table is 0mm.
- Plots are only shown for the bold marked worst case SAR results

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<b>SAR MEASUREMENT</b>						
Depth of Liquid (cm):>15						
Product: FOLDING AIRCRAFT						
Test Mode: 5.2GHz						
Position	Ch.	Fr. (MHz)	Scaled 10g-Extremity SAR_Ant.1 (W/kg)	Scaled 10g-Extremity SAR_Ant.2 (W/kg)	MIMO (W/kg)	Limit (W/kg)
MIMO						
Edge 1 (Top)_horizontal	40	5200	0.608	0.474	<b>1.082</b>	4.0
Edge 1 (Top)_vertical	40	5200	0.118	0.153	0.271	4.0

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## APPENDIX A. SAR SYSTEM CHECK DATA

Test Laboratory: AGC Lab

Date: Oct. 07, 2023

System Check Head 5200 MHz

DUT: Dipole 5000MHz Type: SID5000

Communication System: CW; Communication System Band: D5000 (5000.0 MHz); Duty Cycle: 1:1; Conv.F=1.20  
 Frequency: 5200 MHz; Medium parameters used:  $f = 5200$  MHz;  $\sigma = 4.61$  mho/m;  $\epsilon_r = 36.58$ ;  $\rho = 1000$  kg/m<sup>3</sup> ;  
 Phantom section: Flat Section; Input Power=10dBm

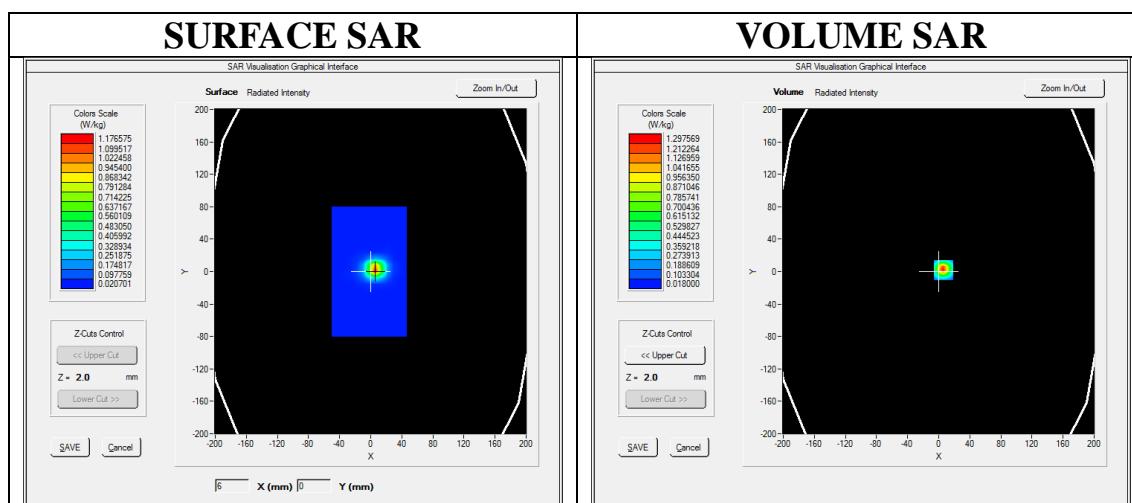
Ambient temperature (°C): 20.9, Liquid temperature (°C): 21.1, Relative Humidity (%): 58.6

SATIMO Configuration:

- Probe: SSE2; Calibrated: Dec. 02, 2022; Serial No.: SN 45/22 EPGO391
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Phantom: SAM twin phantom
- Measurement SW: OpenSAR V4\_02\_35

Configuration/System Check 5200 MHz Head/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/System Check 5200 MHz Head/Zoom Scan: Measurement grid: dx=4mm,dy=4mm, dz=2mm



Maximum location: X=6.00, Y=2.00

SAR Peak: 2.27 W/kg

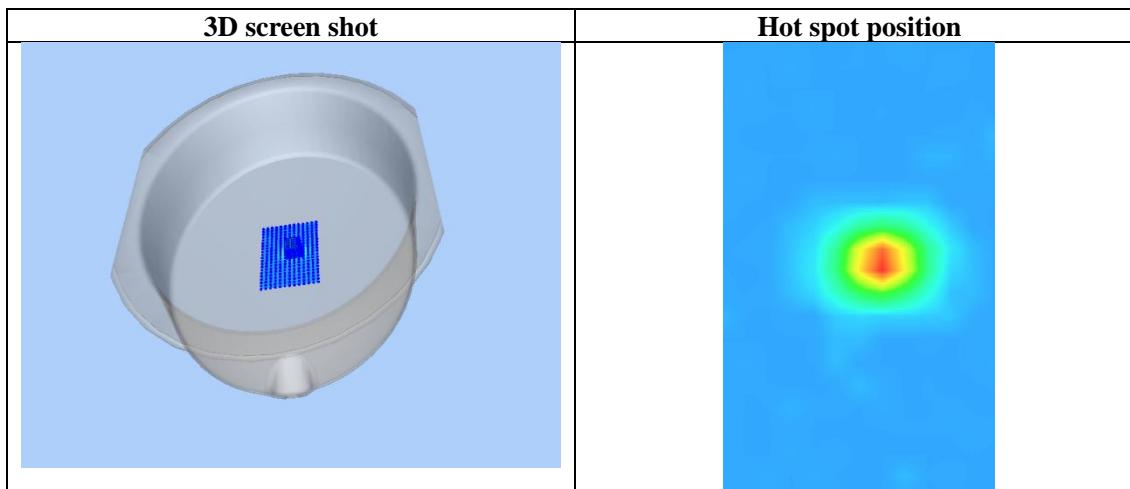
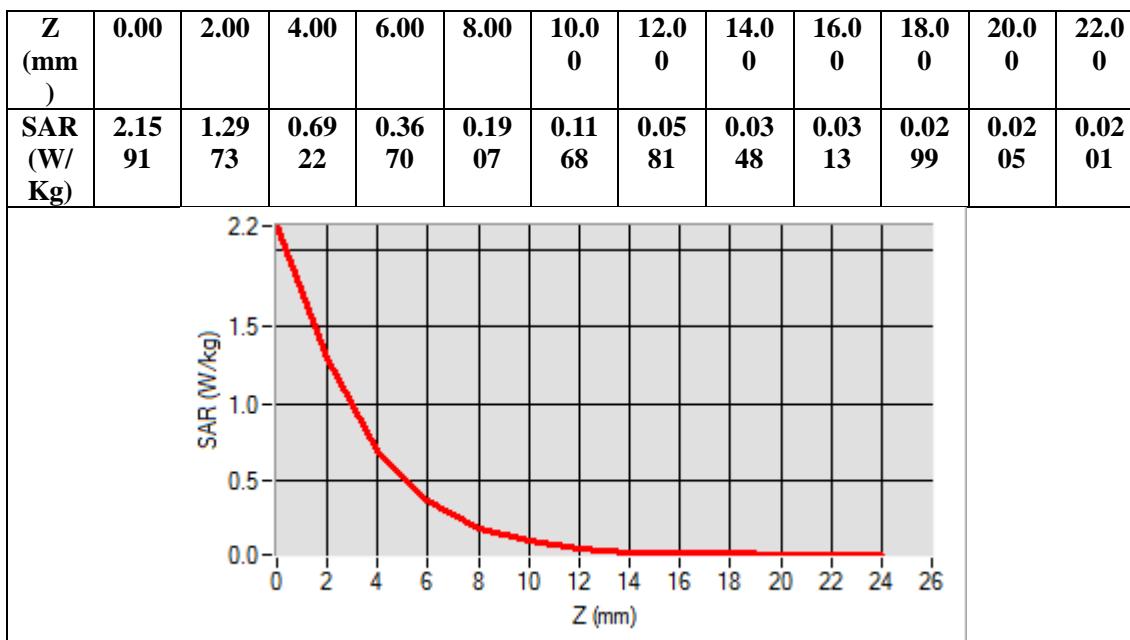
SAR 10g (W/Kg)	0.218894
SAR 1g (W/Kg)	0.694527

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## APPENDIX B. SAR MEASUREMENT DATA

### 5.2GHz ANT.1\_802.11a

Test Laboratory: AGC Lab

Date: Oct. 07, 2023

802.11a CH40- Edge 1 (Top)\_ horizontal

DUT: FOLDING AIRCRAFT; Type: TF35 PRO

Communication System: Wi-Fi; Communication System Band: 802.11a; Duty Cycle: 1:1; Conv.F=1.20;  
 Frequency: 5200MHz; Medium parameters used:  $f = 5200$  MHz;  $\sigma = 4.61$  mho/m;  $\epsilon_r = 36.58$ ;  $\rho = 1000$  kg/m<sup>3</sup> ;  
 Phantom section: Flat Section

Ambient temperature (°C): 20.9, Liquid temperature (°C): 21.1

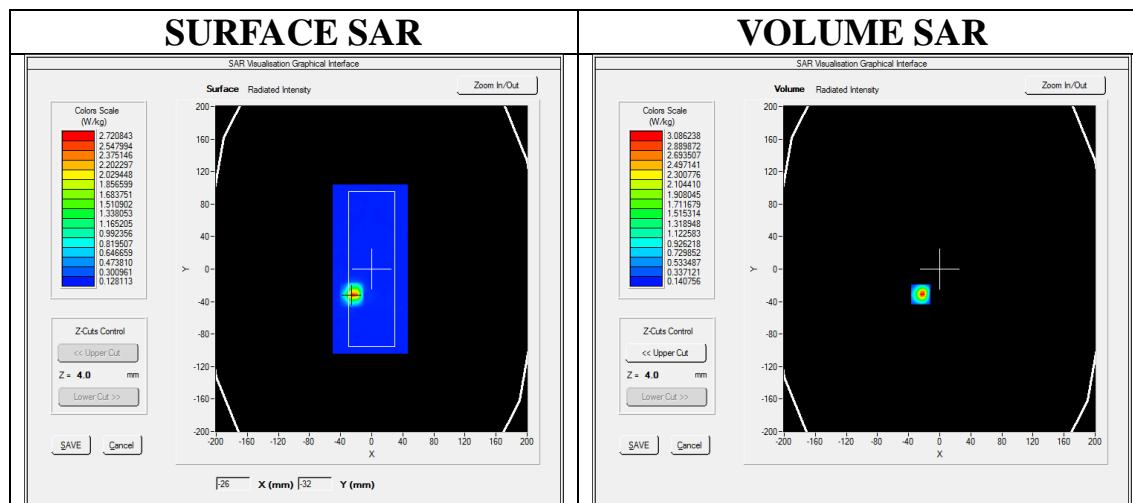
SATIMO Configuration:

- Probe: SSE2; Calibrated: Dec. 02, 2022; Serial No.: SN 45/22 EPGO391
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Phantom: SAM twin phantom
- Measurement SW: OpenSAR V4\_02\_35

**Configuration/802.11a CH40- Edge 1 (Top)\_ horizontal/Area Scan:** Measurement grid: dx=8mm, dy=8mm

**Configuration/802.11a CH40- Edge 1 (Top)\_ horizontal/Zoom Scan:** Measurement grid: dx=4mm,dy=4mm, dz=2mm

<b>Area Scan</b>	sam_direct_droit2_surf8mm.txt
<b>ZoomScan</b>	7x7x12 dx=4mm dy=4mm dz=2mm
<b>Phantom</b>	Validation plane
<b>Device Position</b>	Edge 1 (Top)_ horizontal
<b>Band</b>	5200MHz
<b>Channels</b>	CH40
<b>Signal</b>	Crest factor: 1.0



Maximum location: X=-24.00, Y=-31.00

SAR Peak: 8.64 W/kg

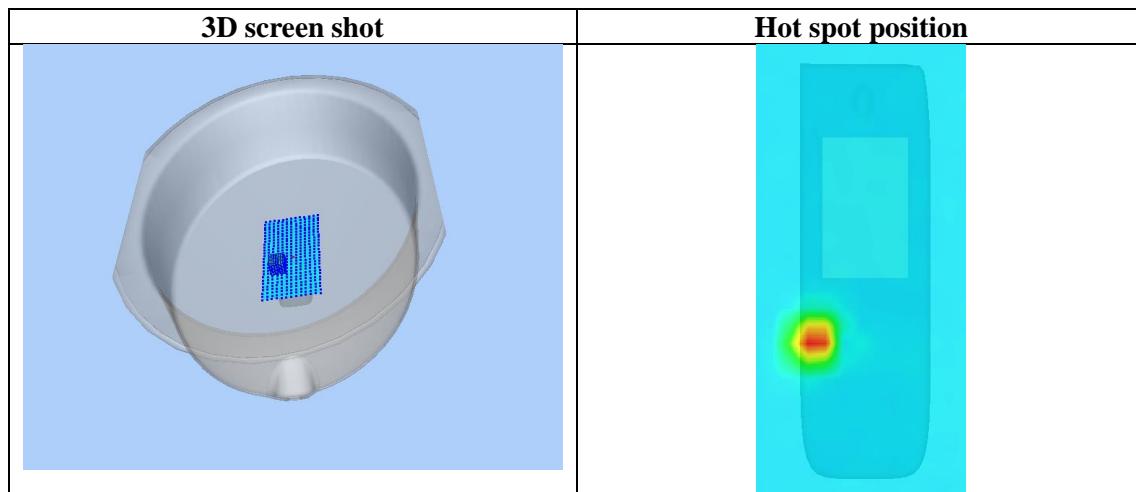
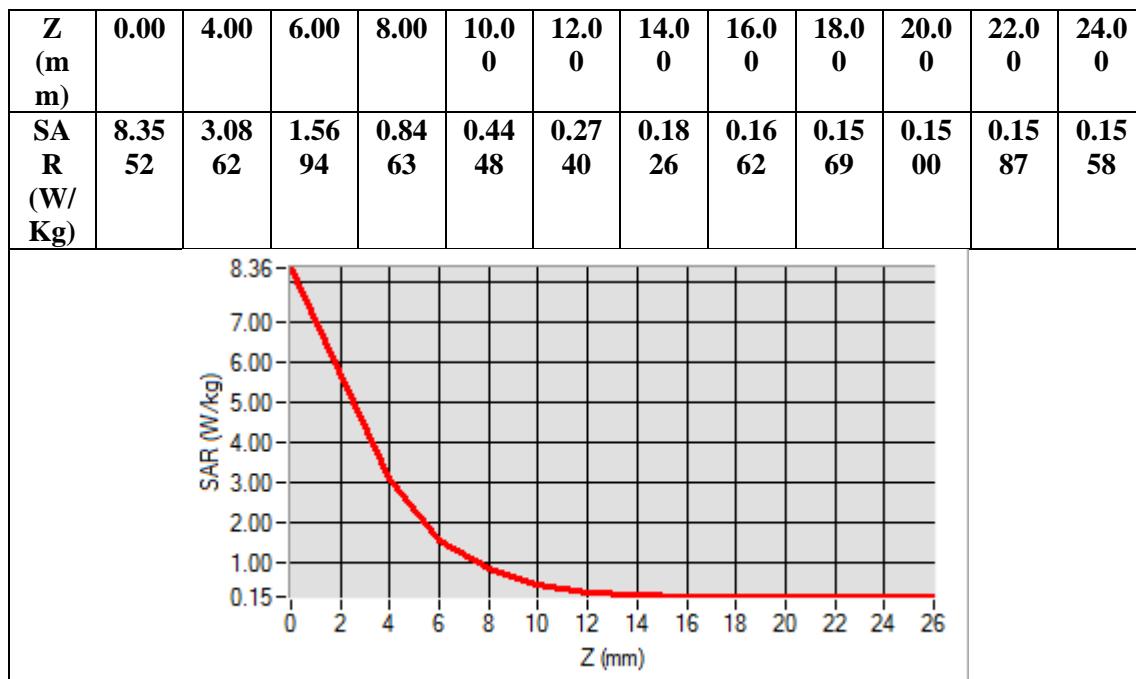
<b>SAR 10g (W/Kg)</b>	0.779496
<b>SAR 1g (W/Kg)</b>	2.769483

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**5.2GHz ANT.2\_802.11a**
**Test Laboratory: AGC Lab**
**802.11a CH40- Edge 1 (Top)\_ horizontal**
**DUT: FOLDING AIRCRAFT; Type: TF35 PRO**
**Date: Oct. 07, 2023**

Communication System: Wi-Fi; Communication System Band: 802.11a; Duty Cycle: 1:1; Conv.F=1.20;  
 Frequency: 5200MHz; Medium parameters used:  $f = 5200$  MHz;  $\sigma = 4.61$  mho/m;  $\epsilon_r = 36.58$ ;  $\rho = 1000$  kg/m<sup>3</sup> ;  
 Phantom section: Flat Section

Ambient temperature (°C): 20.9, Liquid temperature (°C): 21.1

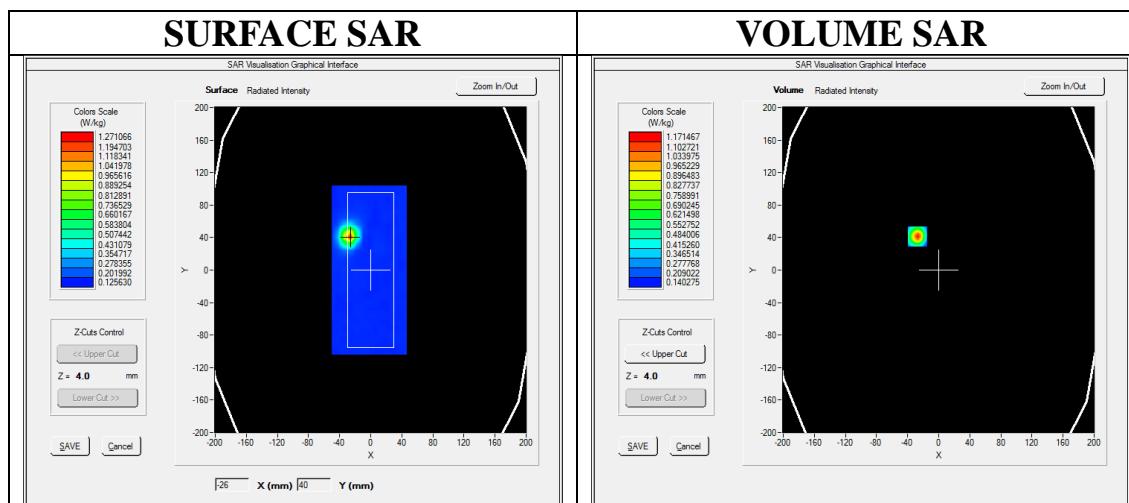
SATIMO Configuration:

- Probe: SSE2; Calibrated: Dec. 02, 2022; Serial No.: SN 45/22 EPGO391
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Phantom: SAM twin phantom
- Measurement SW: OpenSAR V4\_02\_35

**Configuration/802.11a CH40- Edge 1 (Top)\_ horizontal/Area Scan:** Measurement grid: dx=8mm, dy=8mm

**Configuration/802.11a CH40- Edge 1 (Top)\_ horizontal/Zoom Scan:** Measurement grid: dx=4mm, dy=4mm, dz=2mm

<b>Area Scan</b>	sam_direct_droit2_surf8mm.txt
<b>ZoomScan</b>	7x7x12 dx=4mm dy=4mm dz=2mm
<b>Phantom</b>	Validation plane
<b>Device Position</b>	Edge 1 (Top)_ horizontal
<b>Band</b>	5200MHz
<b>Channels</b>	CH40
<b>Signal</b>	Crest factor: 1.0


**Maximum location: X=-27.00, Y=41.00**
**SAR Peak: 3.06 W/kg**

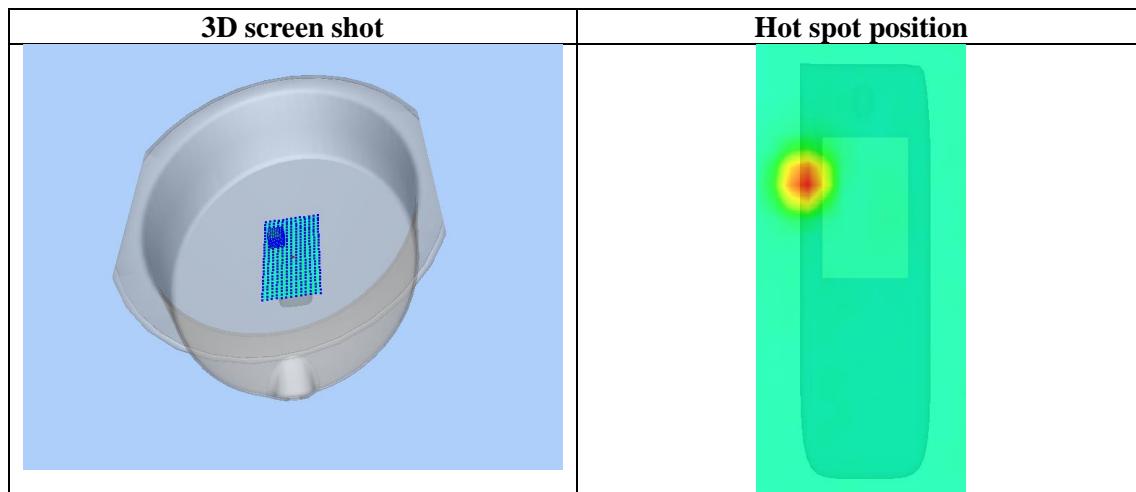
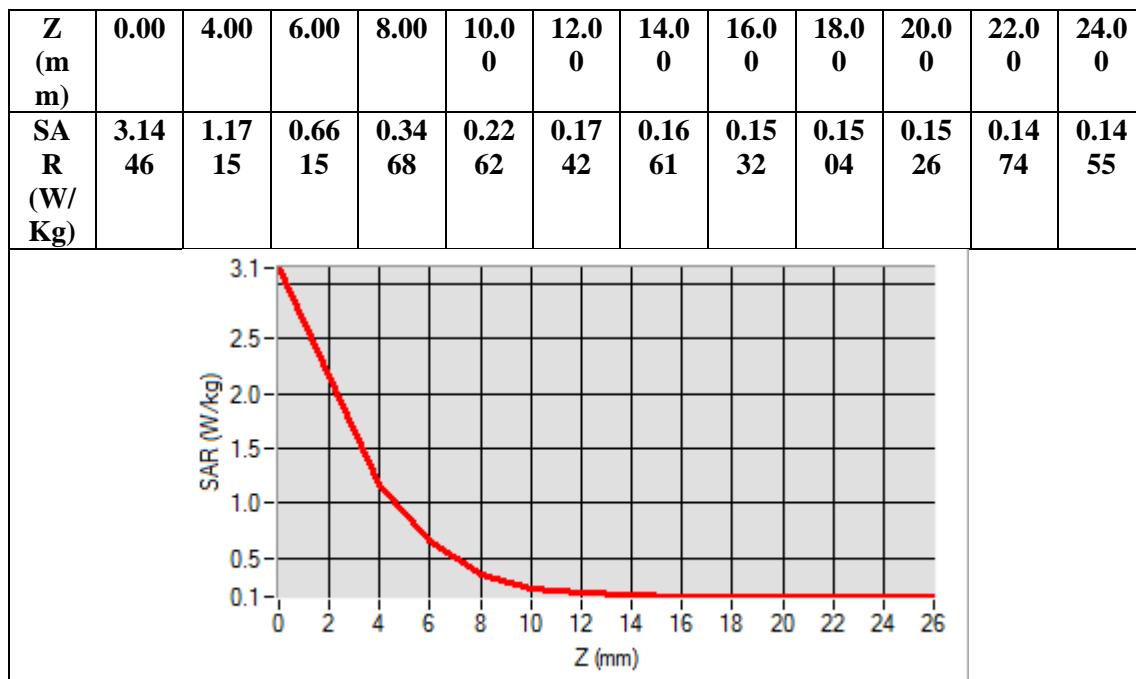
<b>SAR 10g (W/Kg)</b>	0.433919
<b>SAR 1g (W/Kg)</b>	1.122589

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**5.2GHz ANT.1\_802.11n(20)**
**Test Laboratory: AGC Lab**
**Date: Oct. 07, 2023**
**802.11n(20) CH40- Edge 1 (Top)\_ horizontal**
**DUT: FOLDING AIRCRAFT; Type: TF35 PRO**

Communication System: Wi-Fi; Communication System Band: 802.11n(20); Duty Cycle: 1:1; Conv.F=1.20; Frequency: 5200MHz; Medium parameters used:  $f = 5200$  MHz;  $\sigma = 4.61$  mho/m;  $\epsilon_r = 36.58$ ;  $\rho = 1000$  kg/m<sup>3</sup> ; Phantom section: Flat Section

Ambient temperature (°C): 20.9, Liquid temperature (°C): 21.1

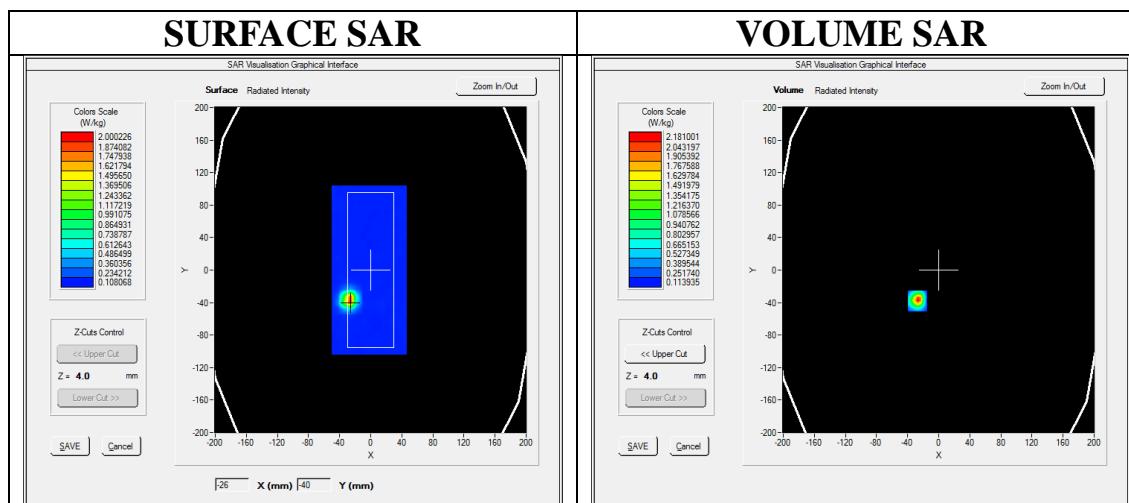
**SATIMO Configuration:**

- Probe: SSE2; Calibrated: Dec. 02, 2022; Serial No.: SN 45/22 EPGO391
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Phantom: SAM twin phantom
- Measurement SW: OpenSAR V4\_02\_35

**Configuration/802.11n(20) CH40- Edge 1 (Top)\_ horizontal/Area Scan:** Measurement grid: dx=8mm, dy=8mm

**Configuration/802.11n(20) CH40- Edge 1 (Top)\_ horizontal/Zoom Scan:** Measurement grid: dx=4mm, dy=4mm, dz=2mm

<b>Area Scan</b>	sam_direct_droit2_surf8mm.txt
<b>ZoomScan</b>	7x7x12 dx=4mm dy=4mm dz=2mm
<b>Phantom</b>	Validation plane
<b>Device Position</b>	Edge 1 (Top)_ horizontal
<b>Band</b>	5200MHz
<b>Channels</b>	CH40
<b>Signal</b>	Crest factor: 1.0


**Maximum location: X=-27.00, Y=-38.00**
**SAR Peak: 5.85 W/kg**

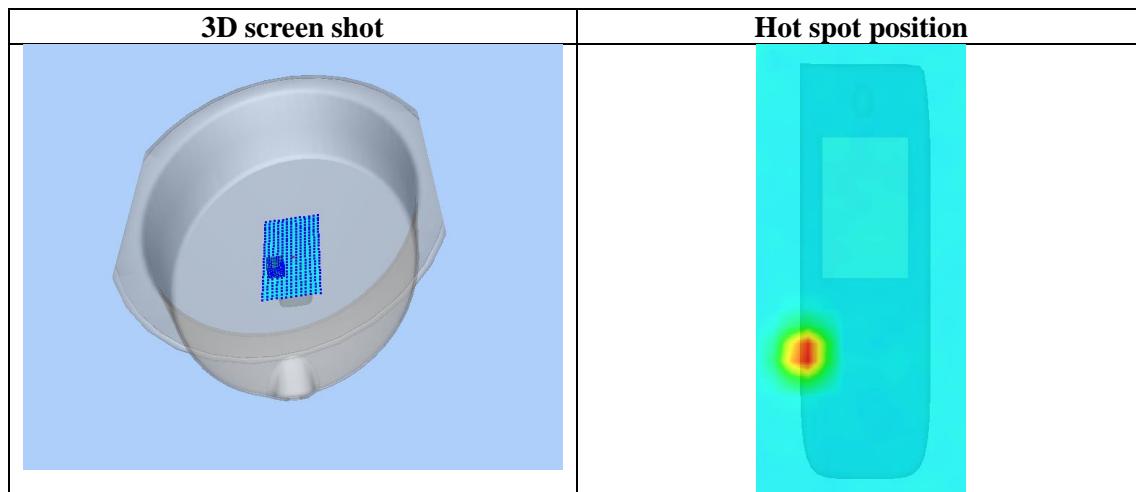
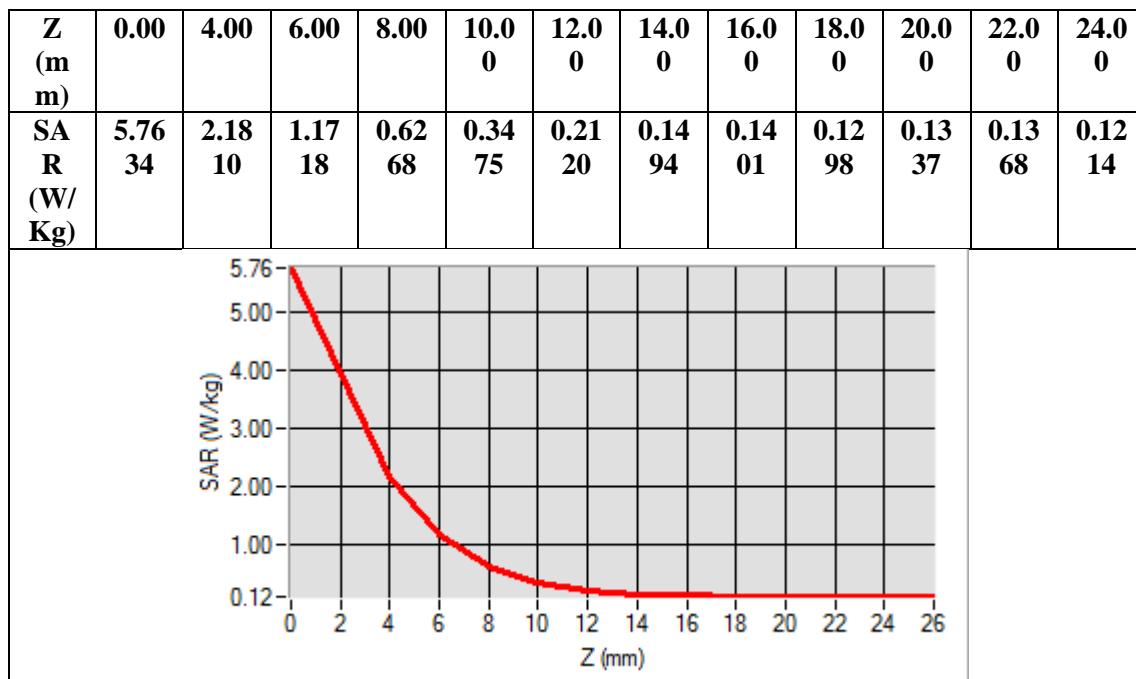
<b>SAR 10g (W/Kg)</b>	0.602486
<b>SAR 1g (W/Kg)</b>	1.978946

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**5.2GHz ANT.2\_802.11n(20)**
**Test Laboratory: AGC Lab**
**Date: Oct. 07, 2023**
**802.11n(20) CH40- Edge 1 (Top)\_ horizontal**
**DUT: FOLDING AIRCRAFT; Type: TF35 PRO**

Communication System: Wi-Fi; Communication System Band: 802.11n(20); Duty Cycle: 1:1; Conv.F=1.20; Frequency: 5200MHz; Medium parameters used:  $f = 5200$  MHz;  $\sigma = 4.61$  mho/m;  $\epsilon_r = 36.58$ ;  $\rho = 1000$  kg/m<sup>3</sup>; Phantom section: Flat Section

Ambient temperature (°C): 20.9, Liquid temperature (°C): 21.1

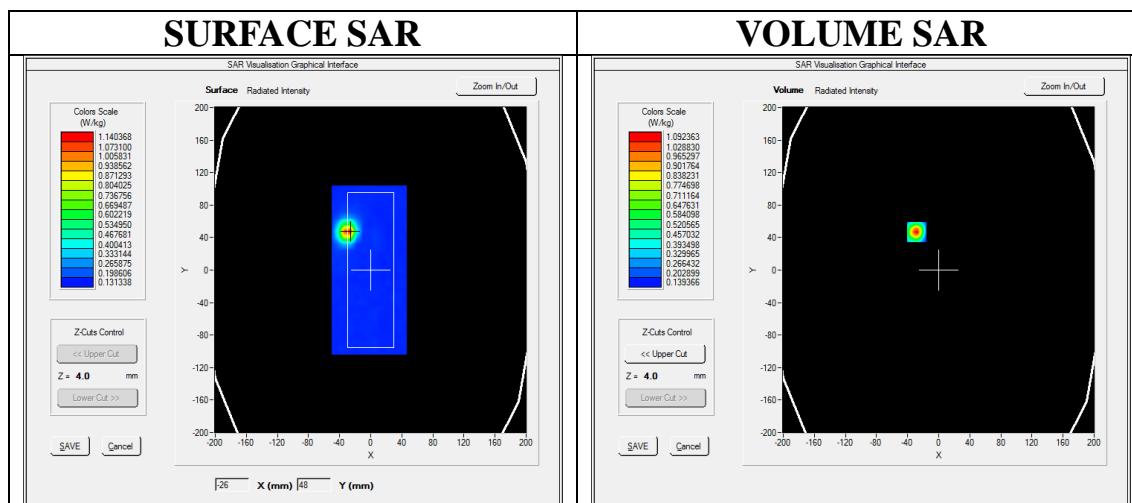
**SATIMO Configuration:**

- Probe: SSE2; Calibrated: Dec. 02, 2022; Serial No.: SN 45/22 EPGO391
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Phantom: SAM twin phantom
- Measurement SW: OpenSAR V4\_02\_35

**Configuration/802.11n(20) CH40- Edge 1 (Top)\_ horizontal/Area Scan:** Measurement grid: dx=8mm, dy=8mm

**Configuration/802.11n(20) CH40- Edge 1 (Top)\_ horizontal/Zoom Scan:** Measurement grid: dx=4mm, dy=4mm, dz=2mm

<b>Area Scan</b>	sam_direct_droit2_surf8mm.txt
<b>ZoomScan</b>	7x7x12 dx=4mm dy=4mm dz=2mm
<b>Phantom</b>	Validation plane
<b>Device Position</b>	Edge 1 (Top)_ horizontal
<b>Band</b>	5200MHz
<b>Channels</b>	CH40
<b>Signal</b>	Crest factor: 1.0


**Maximum location: X=-28.00, Y=47.00**
**SAR Peak: 2.86 W/kg**

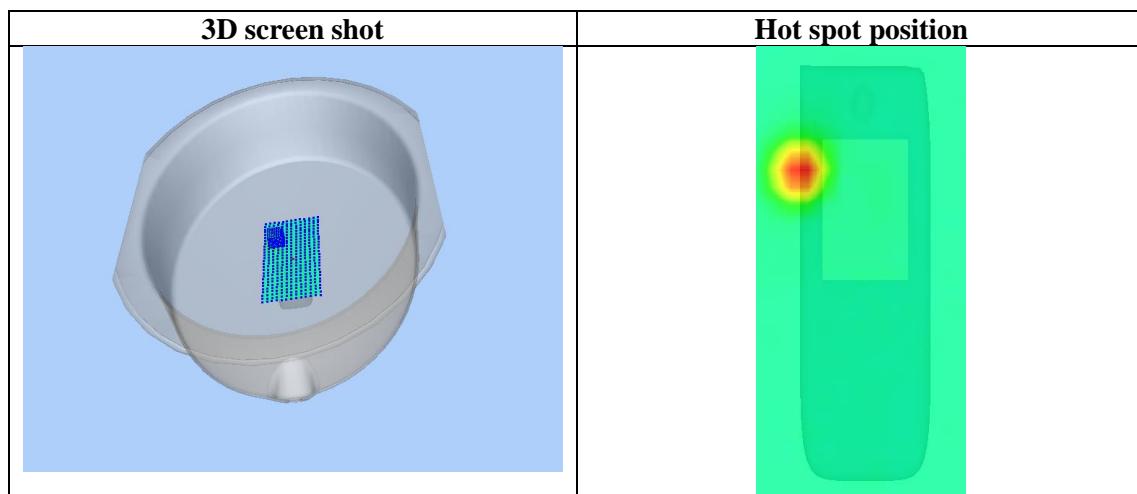
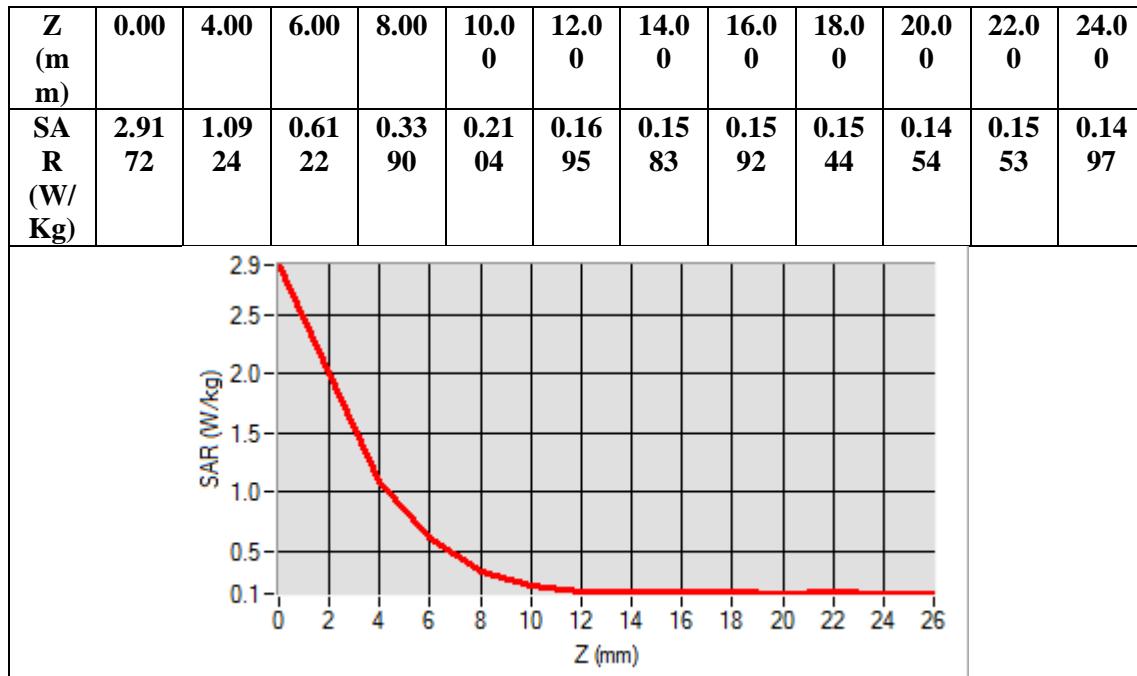
<b>SAR 10g (W/Kg)</b>	0.419044
<b>SAR 1g (W/Kg)</b>	1.064614

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**APPENDIX C. TEST SETUP PHOTOGRAPHS**

Edge 1 (Top)\_ horizontal 0mm



Edge 1 (Top)\_ vertical 0mm



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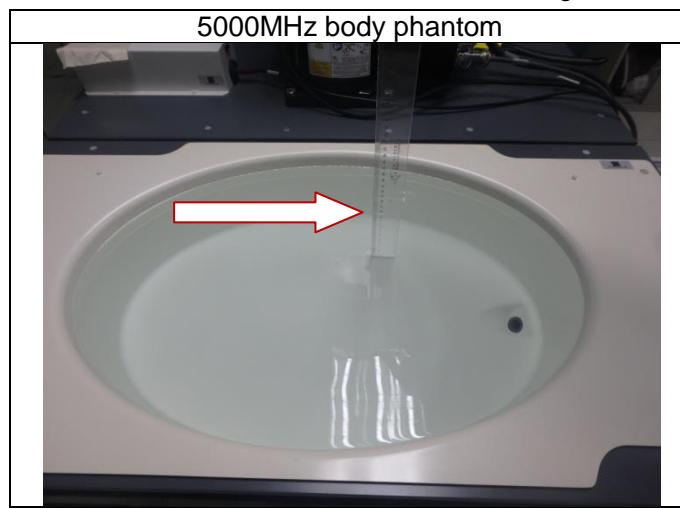
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**DEPTH OF THE LIQUID IN THE PHANTOM—ZOOM IN**

Note : The position used in the measurement were according to IEEE Std. 1528:2013



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## APPENDIX D. CALIBRATION DATA

Refer to Attached files.

----END OF REPORT----

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2. Any report issued by Company as a result of this application for testing services (the "Report") shall be issued in confidence to the Clients and the Report will be strictly treated as such by the Company. It may not be reproduced either in its entirety or in part and it may not be used for advertising or other unauthorized purposes without the written consent of the Company. The Clients to whom the Report is issued may, however, show or send it, or a certified copy thereof prepared by the Company to its customer, supplier or other persons directly concerned. The Company will not, without the consent of the Clients, enter into any discussion or correspondence with any third party concerning the contents of the Report, unless required by the relevant governmental authorities, laws or court orders.
3. The Company shall not be called or be liable to be called to give evidence or testimony on the Report in a court of law without its prior written consent, unless required by the relevant governmental authorities, laws or court orders.
4. In the event of the improper use of the report as determined by the Company, the Company reserves the right to withdraw it, and to adopt any other additional remedies which may be appropriate.
5. Samples submitted for testing are accepted on the understanding that the Report issued cannot form the basis of, or be the instrument for, any legal action against the Company.
6. The Company will not be liable for or accept responsibility for any loss or damage however arising from the use of information contained in any of its Reports or in any communication whatsoever about its said tests or investigations.
7. Clients wishing to use the Report in court proceedings or arbitration shall inform the Company to that effect prior to submitting the sample for testing.
8. The Company is not responsible for recalling the electronic version of the original report when any revision is made to them. The Client assumes the responsibility to providing the revised version to any interested party who uses them.
9. Subject to the variable length of retention time for test data and report stored hereinto as otherwise specifically required by individual accreditation authorities, the Company will only keep the supporting test data and information of the test report for a period of six years. The data and information will be disposed of after the aforementioned retention period has elapsed. Under no circumstances shall we provide any data and information which has been disposed of after retention period. Under no circumstances shall we be liable for damage of any kind, including (but not limited to) compensatory damages, lost profits, lost data, or any form of special, incidental, indirect, consequential or punitive damages of any kind, whether based on breach of contract or warranty, tort (including negligence), product liability or otherwise, even if we are informed in advance of the possibility of such damages.

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