

COMGROW T-500

User Manual



WELCOME TO COMGROW !

Founded in 2017, Comgrow was formed by people passionate about technology that helps you make things. With this deep-rooted dedication, we wanted to make digital manufacturing processes more accessible, giving educators, engineers, a manufacturer, small businesses, and tinkerers the power to make anything.

Headquartered in Southern China, Shenzhen, Comgrow's dedicated staffs are committed to providing impressive service. We offer top-class quality materials, machines, and accessories - from industrial-grade 3D printers to DIY laser cutters - all of which have been tested and approved by our industry experts. Our fantastic team in customer service is here from Monday to Saturday to help with any problem you have encountered, from suggesting suitable filaments for your specific projects to discussing which 3d printer is best for you. We're here to make 3D printing, laser cutting, and CNC milling possible.

Service Email: service@comgrow.com

For related installation files, please check:
<https://www.comgrow.com>

Join our Facebook support group:
<https://www.facebook.com/groups/comgrow/>

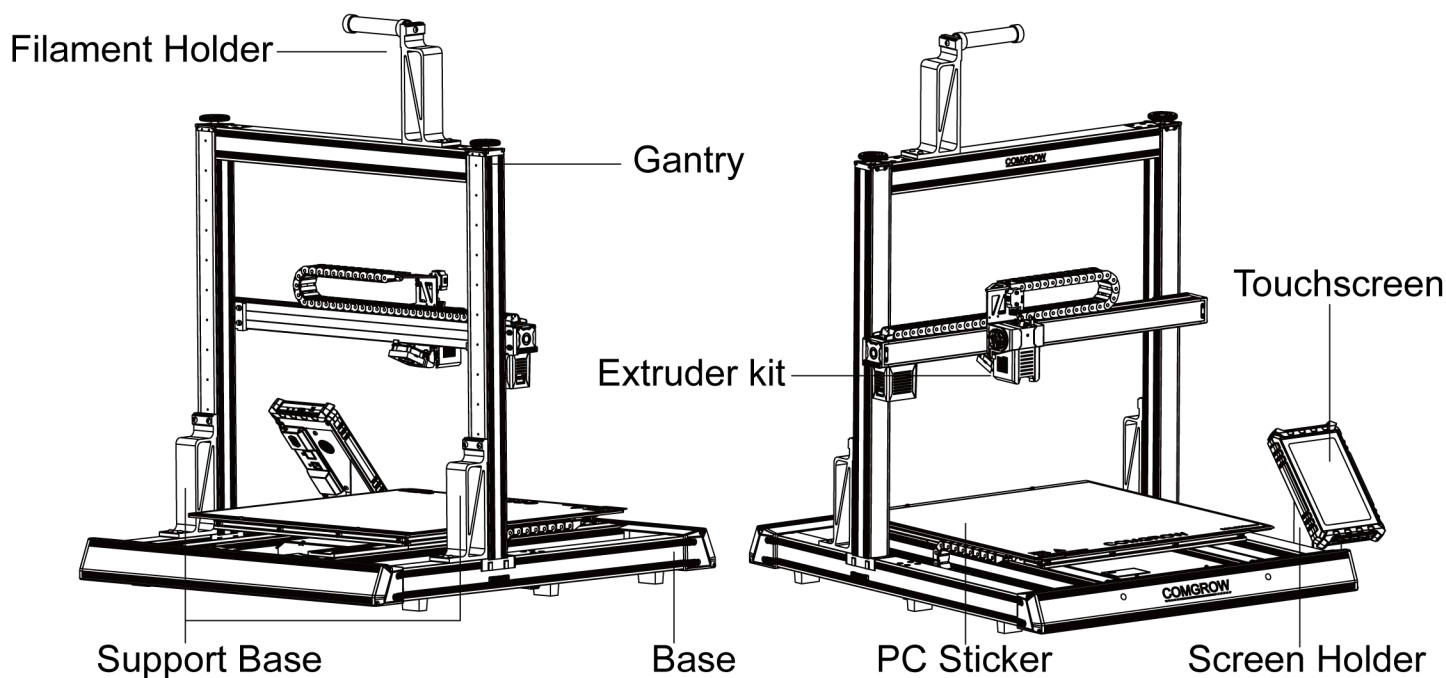
Comgrow Amazon after-sale service:
laserengravingcnc@comgrow.com

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Note

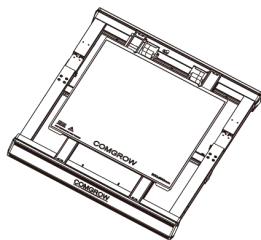
- For your safety, using T500 for any purpose other than 3d printing is not recommended, or the risks are on yourself.
- To ensure best print quality, please don't place T500 on a tilt or wagging platform.
- The shaking of the machine will affect the printing quality of the printer.
- Please do not place the machine near flammable and explosive materials or near highheat sources.
- Please place the machine in a ventilated, cool and dust free environment.
- It is recommended to use the material recommended by the manufacturer to avoid machine damage.
- Do not use any other power cable except the one supplied in package. Always use a grounded three-prong power outlet.
- Wearing cotton gloves when operating the printer is strictly prohibited. Such gloves may become tangled in the printer's moving parts which leads to burns, possible injury, or printer damage.
- Please wait until the print bed cools down to remove the print.
- It's not recommended to use the third party firmware or mainboard etc, or the warranty will be void.
- Clean the printer frequently. Always turn the power off when cleaning, and wipe with a dry cloth to remove dust, adhered printing plastics or any other material off the frame, guide rails, or wheels. Use glass cleaner or isopropyl alcohol to clean the print surface.
- Children under 10 years old should not use the printer without supervision.
- Do not manually move the extruder and printing platform while printing.
- Users should comply with the laws and regulations of the corresponding countries and regions where the equipment is located (used), abide by professional ethics, pay attention to safety obligations, and strictly prohibit the use of our products or equipment for any illegal purposes. Comgrow will not be responsible for any violators' legal liability under any circumstance.

Parameters

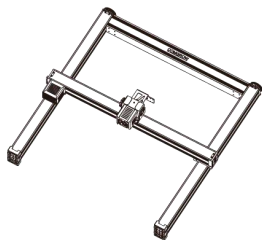


Model	T-500
Language	English
Print Method	USB flash drive, Wifi connection
Molding	FDM
Nozzle Quantity	1
Build Volume	500*500*500mm
Recommend Printing Speed	≤200mm/s
Printing Accuracy	±0.1mm
Nozzle Diameter	0.4mm(Replaceable)
Nozzle Temperature	≤300 °C
Hotbed Temperature	≤80 °C
Supporting Materials	PLA/PETG/TPU
Material Diameter	1.75mm
Support File Format	G-code
Voltage	Input:115/230V 50/60HZ Output:24V
Operation System	Windows/Linux/Mac
Power	MW 600W/24V

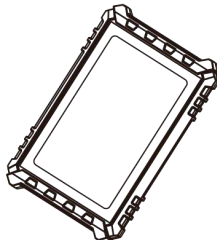
Package List



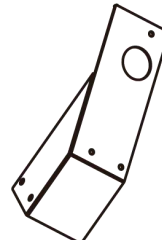
Base



Gantry



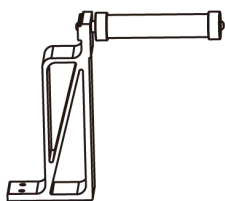
Screen



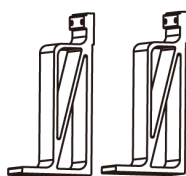
Screen holder



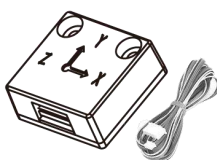
Filament



Filament Holder



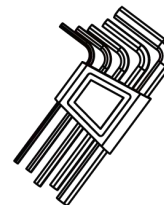
Support Base



Accelerometer



Power Cable



Allen Wrench



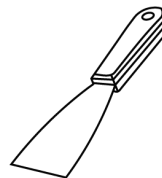
Diagonal Pliers



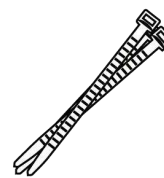
Slotted
Screwdriver



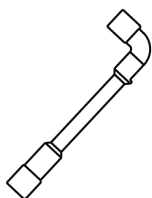
Phillips
screwdriver



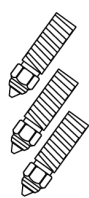
Spatula



Zip Tie



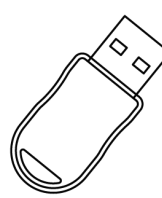
Socket Spanner



Spare Nozzle



Nozzle
Cleaner Needle



USB
Flash Drive



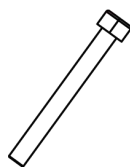
Tweezers



Cable clamp



M3X30*2



M5X35*8



M5X10*2



M4X10*3



M3X6*4

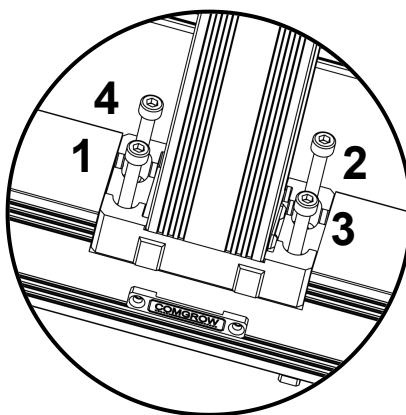
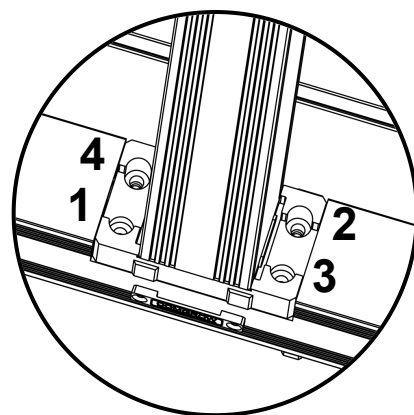
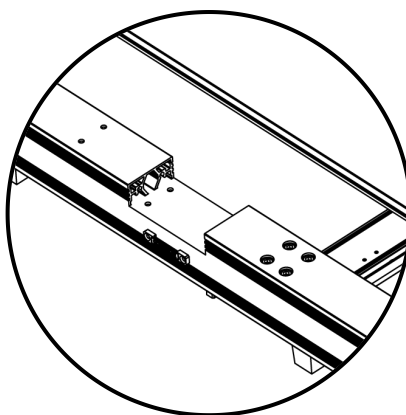
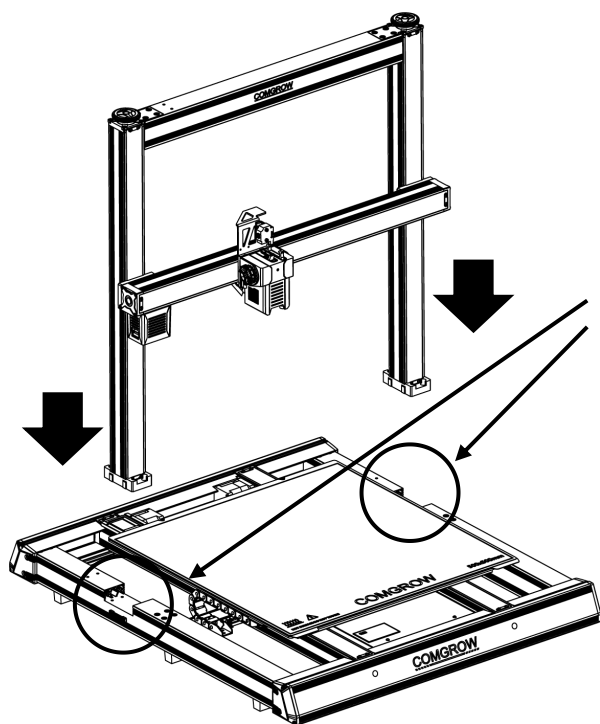


M5X18*10



M3X16*2

Gantry



1. Install the gantry frame into the grooves on the left and right ends of the base. Use four **M5X35** screws to secure each side, totaling eight screws.



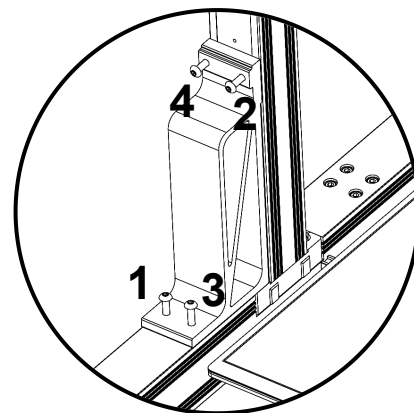
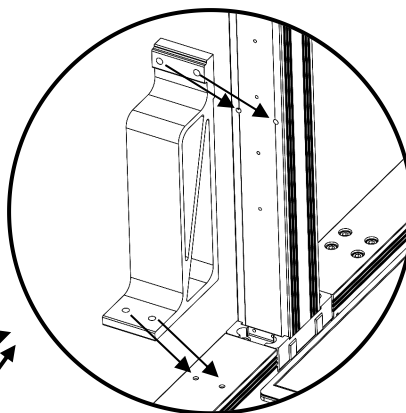
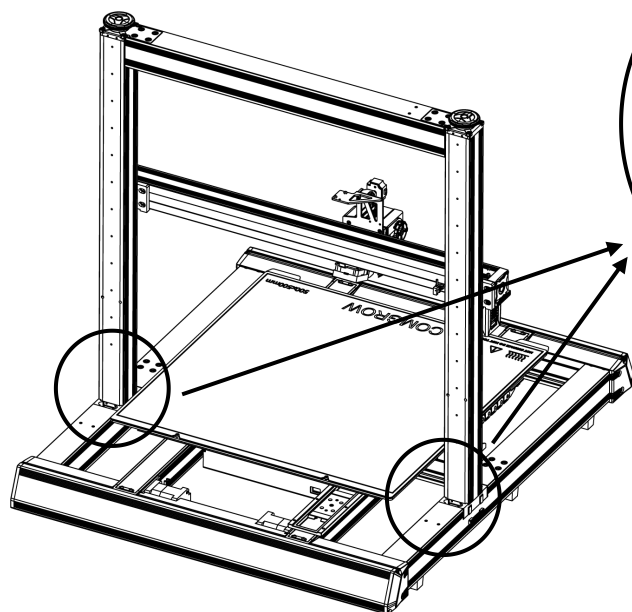
The extruder kit should face the front of the machine.



Note that the machine components are heavy.

Please place it on a stable platform before installation to prevent accidents and avoid causing harm to person and objects.

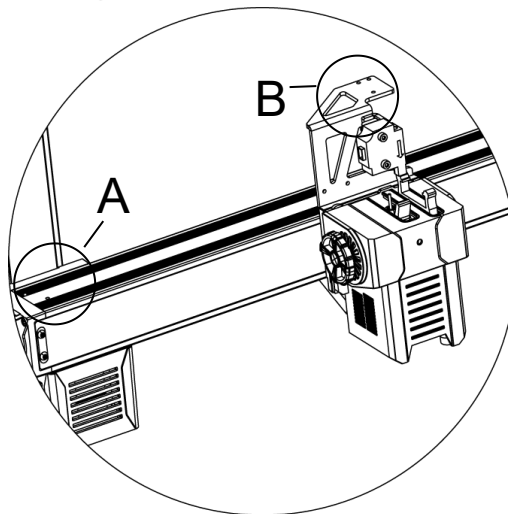
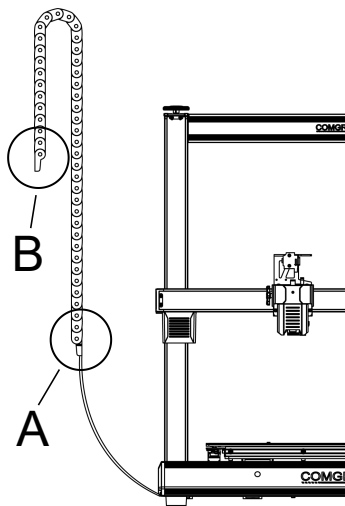
Support Base



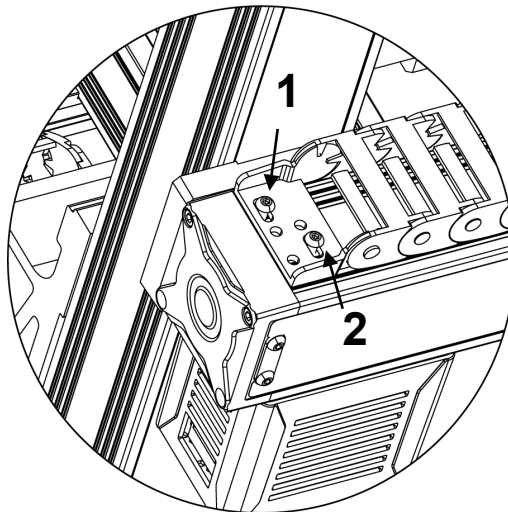
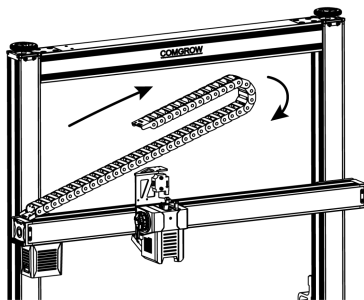
The support base is not left or right-specific.

1. Install the support base on the back of the machine, at the connection point between the gantry frame and the base. Use four **M5X18** screws on each side, totaling eight screws.

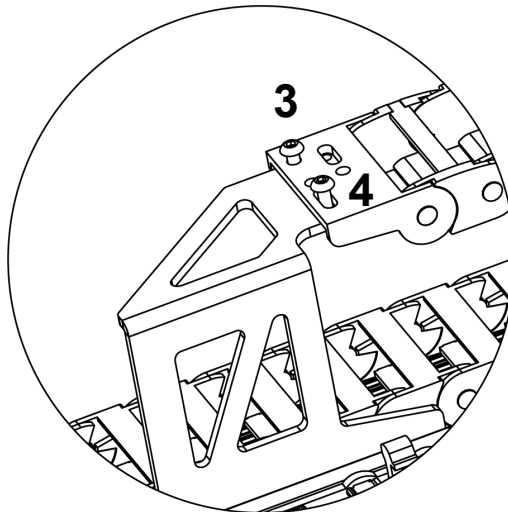
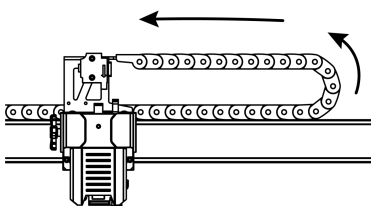
Cable Drag Chain



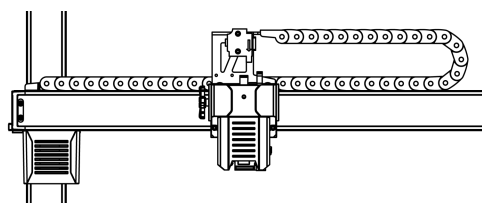
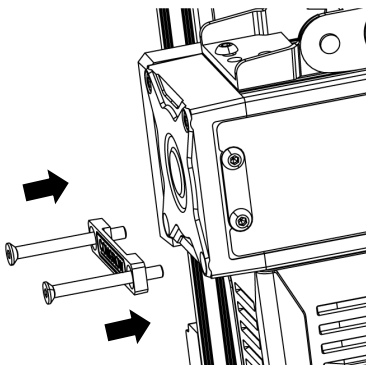
★ The following are the corresponding points for the installation position of the Cable drag chain.



1. Lay the drag chain on the right as shown, use two **M3X6** screws to install the drag chain at the end A

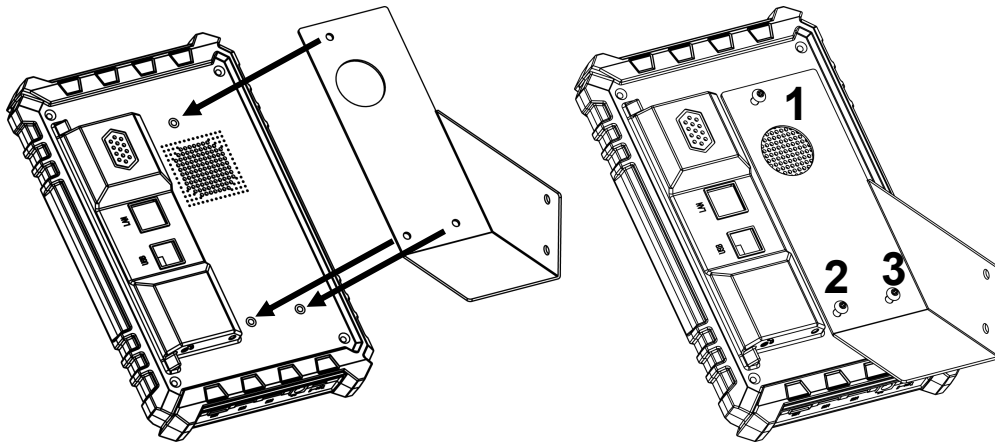


2. Bend the drag chain to the left as shown, use two **M3X6** screws to install the drag chain at the end B

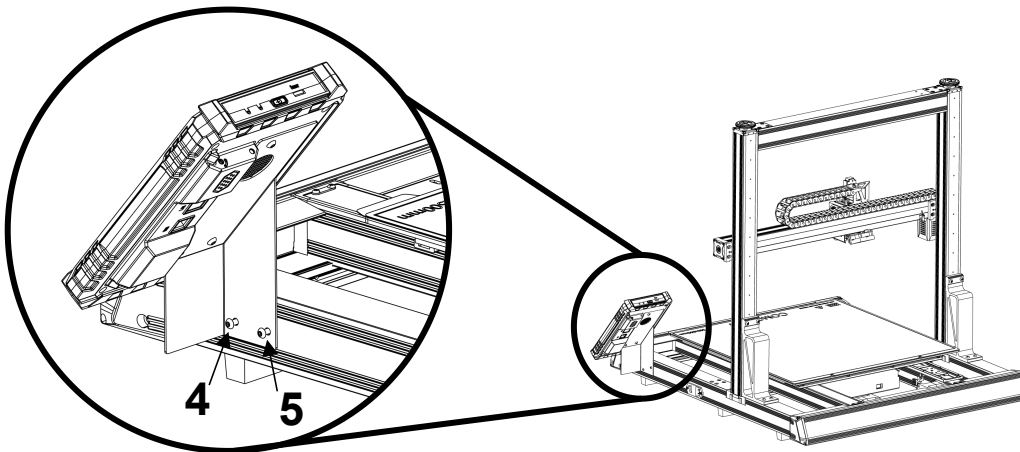


3. Use two **M3X30** screws to install the cable clamp, after installation it should be like the second picture

Touchscreen



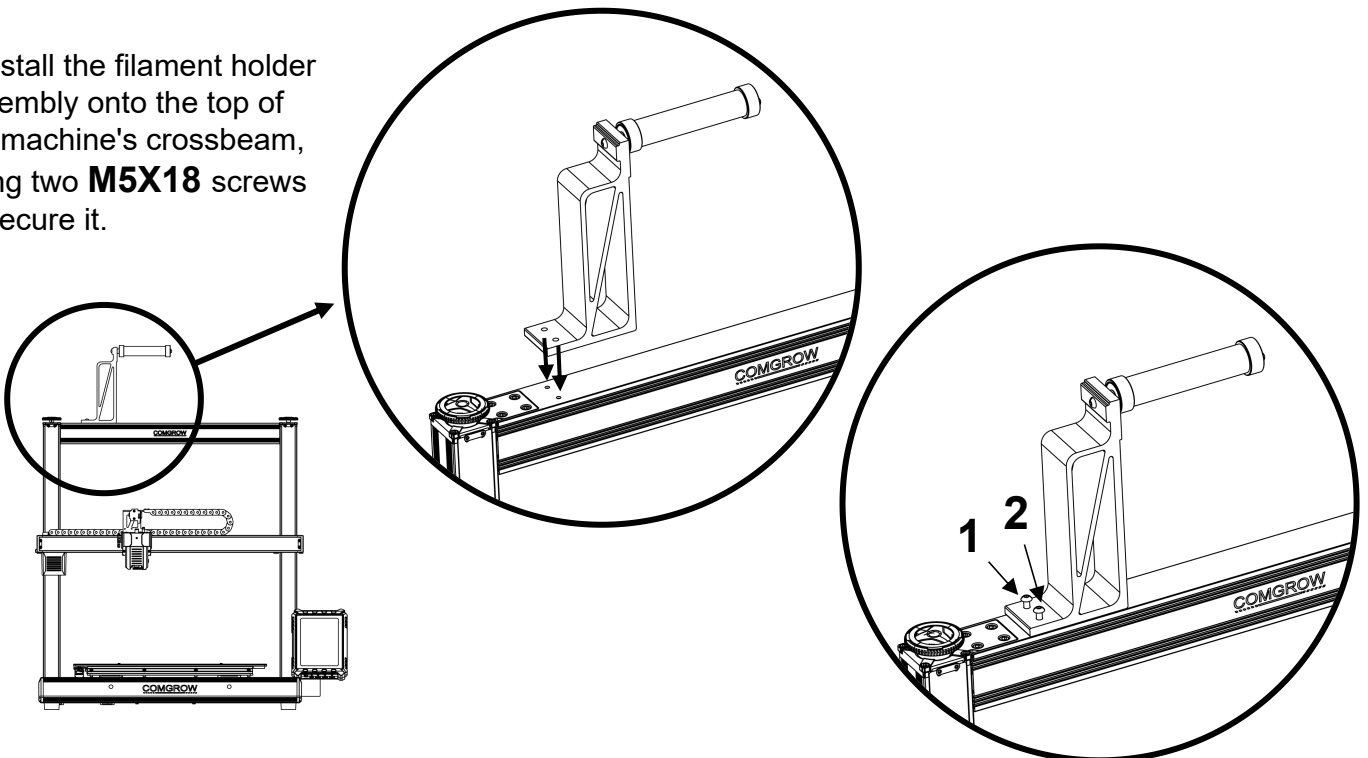
1.First, attach the touch screen mounting plate to the back of the touch screen, using three **M4X10** screws to secure it.



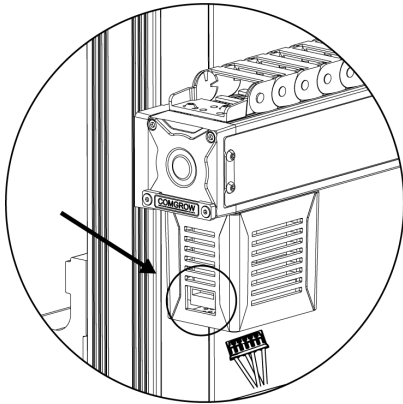
2.Then, install the entire touch screen assembly to the right front of the machine base, using the remaining two **M5X10** screws to secure it.

Filament Holder

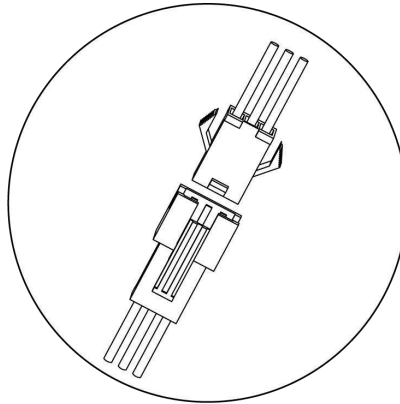
1.Install the filament holder assembly onto the top of the machine's crossbeam, using two **M5X18** screws to secure it.



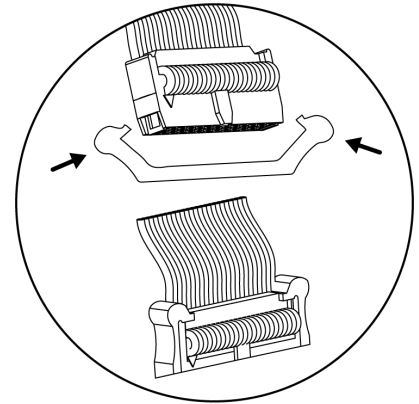
Connect Wires



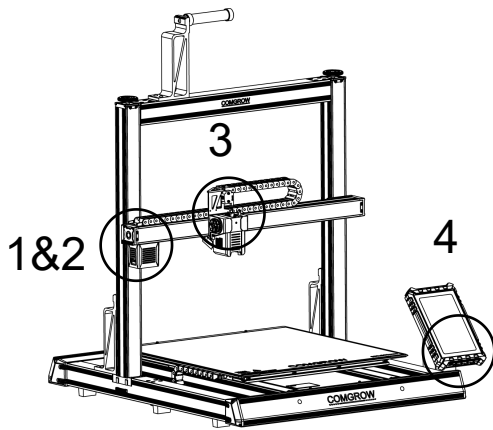
1. X Motor



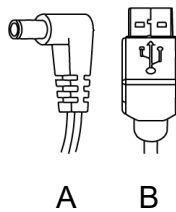
2. X Limit Switch



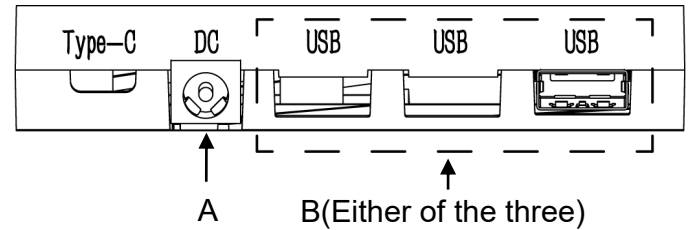
3. Extruder kit



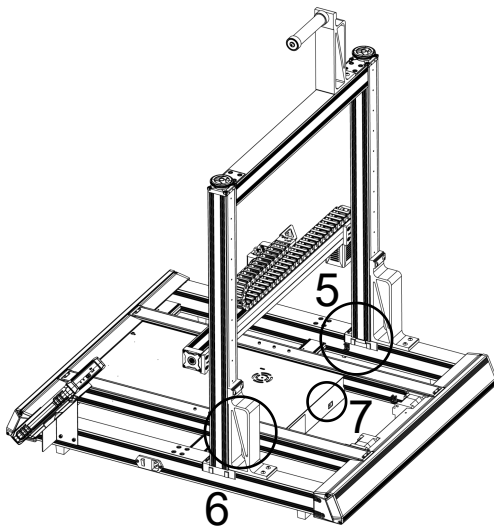
4. Touchscreen



5. Z1 Motor



6. Z2 Motor



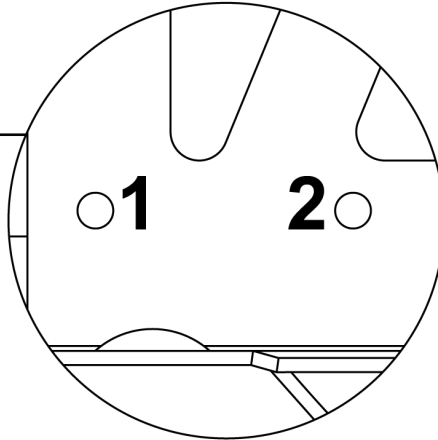
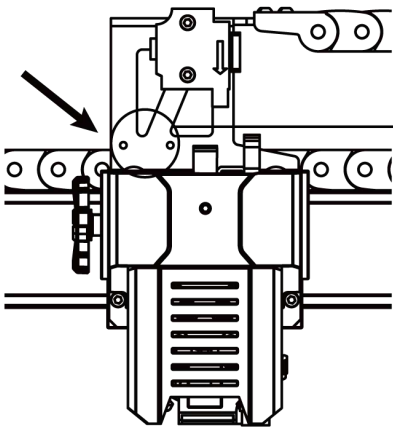
7. Power

★ Please select the correct input voltage to match your local mains (230V or 115V).

230V ◀ ▶ 115V

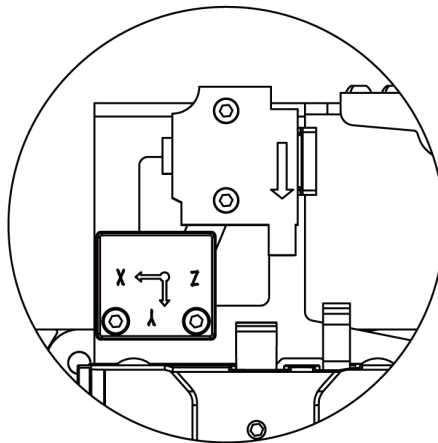
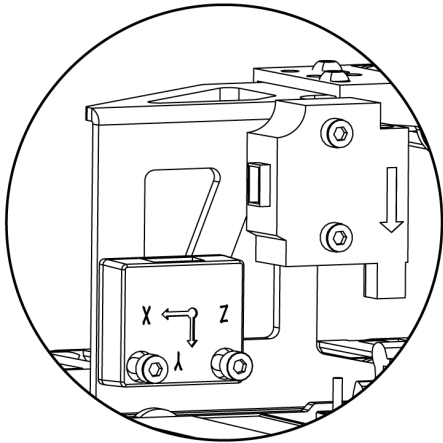
115/230V is selected manually!
Please switch to your local voltage before plug-in the power cable in case of damage.

Accelerometer



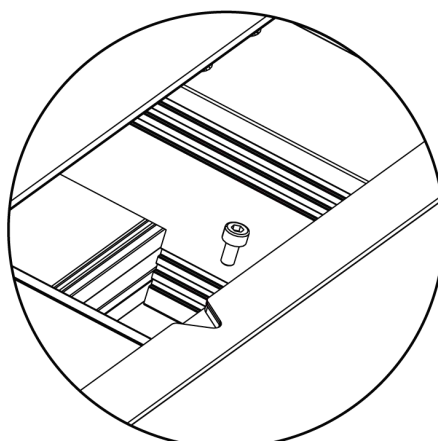
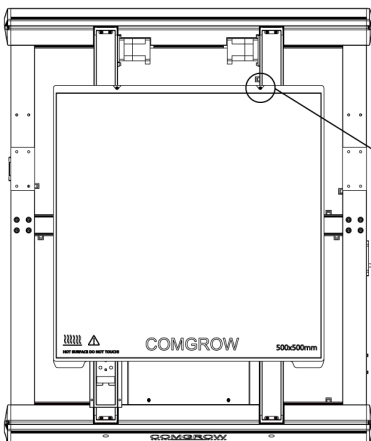
★ The accelerometer is an optional module, you can choose whether to install it according to your needs

1. Please pay attention to the two screw holes here on the nozzle
2. Mount the accelerometer here with two **M3X16** screws

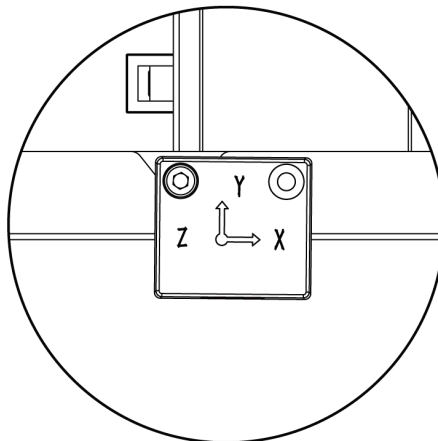
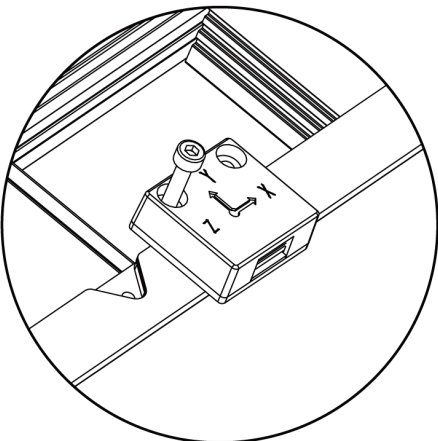


★ Please pay attention to the installing direction of the accelerometer in the figure, the interface should face the upper, do not install it reverse

X Axis Y Axis

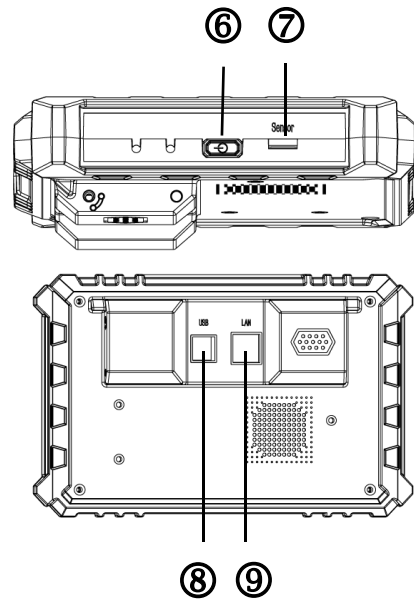
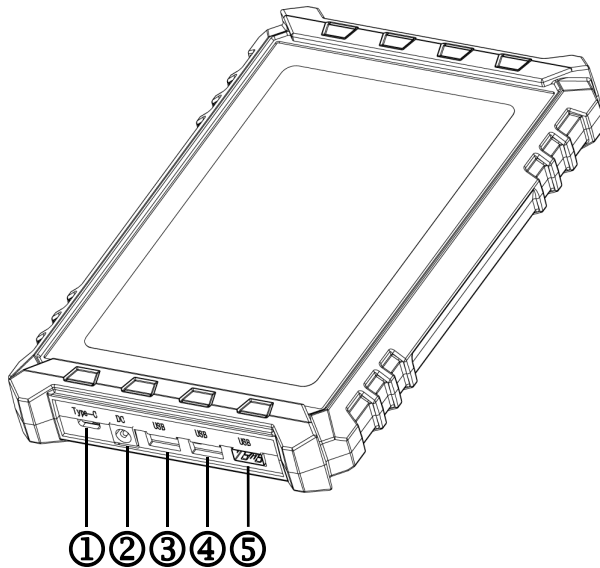


1. Unscrew one screw here on the hotbed
2. Mount the accelerometer using a **M3X16** screws as shown



★ Please pay attention to the installing direction of the accelerometer in the figure, the interface should face the front, do not install it reverse

Touchscreen



- ① Type-C
- ② DC 12~24V
- ③ USB2.0
- ④ USB2.0
- ⑤ USB3.0
- ⑥ Power
- ⑦ Accelerometer
- ⑧ USB2.0X2
- ⑨ LAN

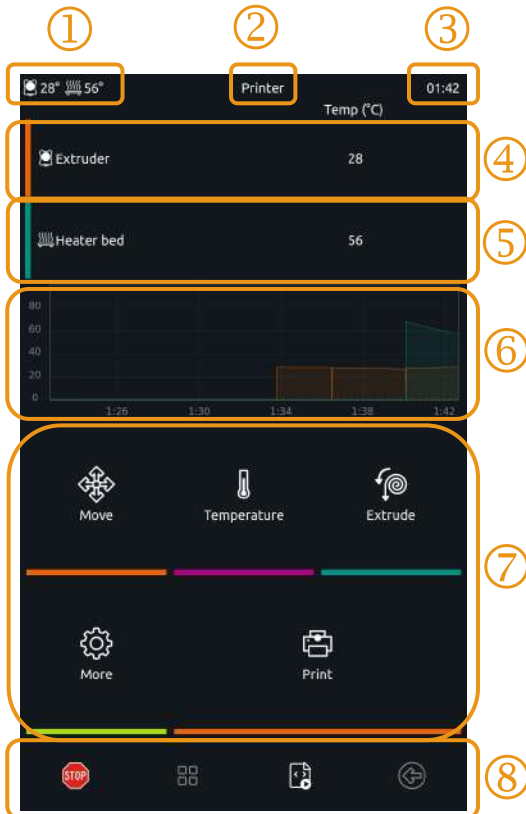
⑥ Power:

- Press the Power button for more than 5s at power on status, the klipper system will closed.
- Press the Power button for 1s at power off status, it will power on.



After closing the klipper system, the printing will be stopped, even though you didn't turn off the machine's power.

Main Menu



1. Nozzle, hot bed, Real-time temperature preview
2. Model|Current Menu
3. Time
4. Nozzle Temp: Click number to adjust nozzle temp
5. Hotbed Temp: Click number to adjust hotbed temp
6. Temperature curve: Click on the names of "Extruder" and "Heater Bed" above to turn on and off their temperature curves
7. Main menu: Please read the following introduction.
8. Bottom option



Emergency stop



Macros



Home



Back

Move



Move



X+: Move X axis to right

X-: Move X axis to left

Y+: Move Y axis forward

Y-: Move Y axis backward

Z+: Move Z axis up

Z-: Move Z axis down

1. Homing
2. Disable Motors
3. X/Y/Z axis's current coordinates
4. Settings
5. The distance per move

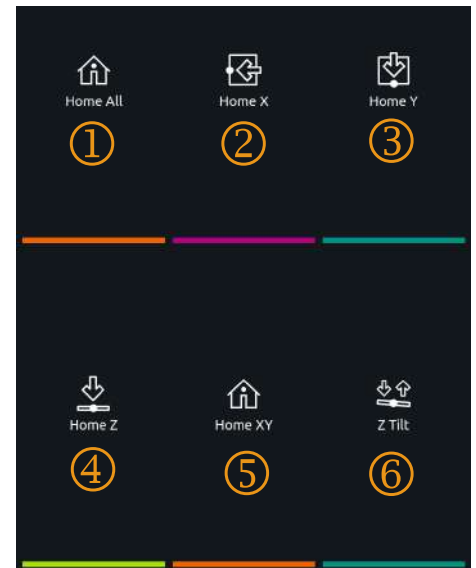


Settings

1. Reverse the movement direction
2. Adjust the speed of moving X/Y axis
3. Adjust the speed of moving Z axis



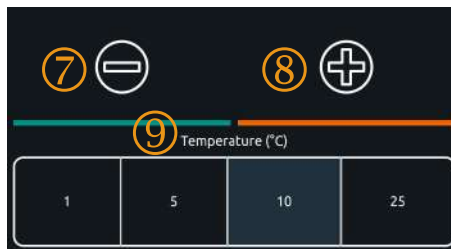
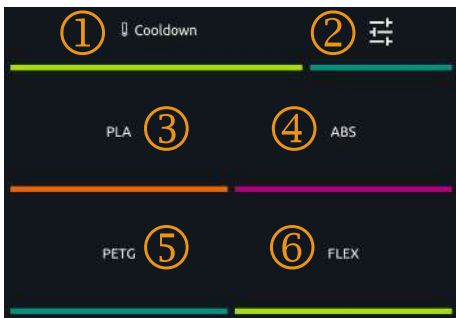
Homing



1. X/Y/Z axis all auto home
2. X axis auto home
3. Y axis auto home
4. Z axis auto home
5. X/Y axis auto home
6. Z tilt



Temperature



Temperature

1. Cancel heating for all
2. Adjust temperature
3. Preheat PLA
4. Preheat ABS
5. Preheat PETG
6. Preheat FLEX
7. Reduce the temperature
8. Raise the temperature
9. Increase/decrease temperature per click

Extruder



Extrude



①



When temconnect to wifip is not enough, it is not allowed to have related operation about the extruder.

②

1. Nozzle real-time temperature, click*Temperature* to adjust temperature.

③

2. Extrude: extrude filament

Retract: retract filament

3. Load: Execute a macro command to load filament.

Unload: Execute a macro command to withdraw the filament

④

4. Distance: The extrusion distance/ retraction distance.

⑤

5. Speed: The extrusion speed/ retraction speed.

⑥

6. Filament Sensor On/Off

More



1. Bed Mesh: detect hotbed mesh flattening data.

2. Z Calibrate: adjust the Z-axis offset from the hotbed to the nozzle.

3. Limits: adjust the speed and acceleration of the printer.

4. Fan: control the switch and speed of the fan.

5. Macros: check out the macro command.

6. Led: control the on and off of the nozzle LED

7. Console: open console to check out or input the command

8. System: update, restore factory, restart, shutdown

9. Input Shaper: adjust the vibration compensation of the XY axis

10. Save Config: save current configuration

11. KlipperScreen: screen settings

12. Network: connect to wifi

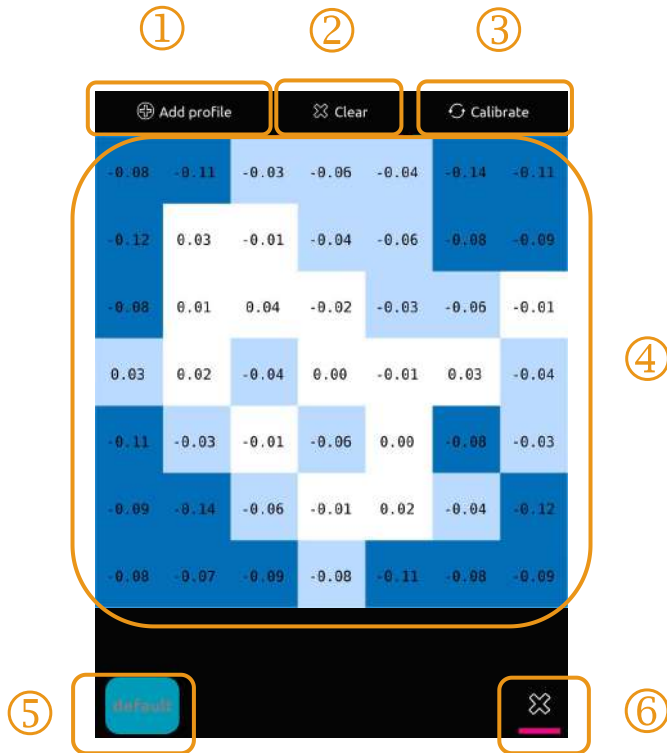


For more details, see the follow-up content

Bed Mesh



Bed Mesh



1. Add profile
2. Clear the saved leveling data in current profile
3. Start calibrate
4. Leveling data preview
5. Current profile name
6. Delete current profile

Z Calibrate



Z Calibrate



1. Start Z calibrate
2. The value of Z calibrate
3. Raise nozzle according to the setted height
4. Apply the settings (Saving settings requires a system restart)
5. Lower nozzle according to the setted height
6. Abort Z calibrate
7. Set the distance of per move

Limits



Limits

Max Acceleration (mm/s²) 8000

Max Acceleration to Deceleration (mm/s²) 1500

Max Velocity (mm/s) 300

Square Corner Velocity (mm/s) 3

1. Max Acceleration
2. Max Deceleration
3. Max Speed
4. Square Corner Velocity

★ Click the number on the right side of the value bar to enter the value manually

★ We have adjusted to the best settings for you out of the factory, if you do not know these parameters very well, please do not change the parameters arbitrarily, in case cause the printing failure.

Fan, Macros



Fan

Part Fan 0 Max

Fan_Board 0%

hotend_fan 0%

Part Fan: can be controlled manually
The Fan_Board and hotend_fan are uncontrollable, and will be turned on automatically when the hotend starts to heat up



Macros

Name ⬆ Settings

CANCEL_PRINT

clear_last_file

END_PRINT

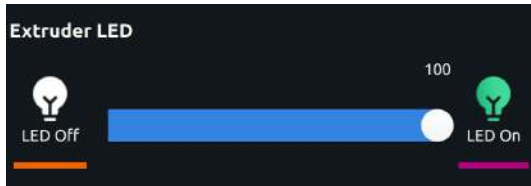
G31

You can view or test and run the macro command

Led, Console



Led



Control the on and off of the nozzle LED



Console



Open console to check out or input the command

Save config, KlipperScreen

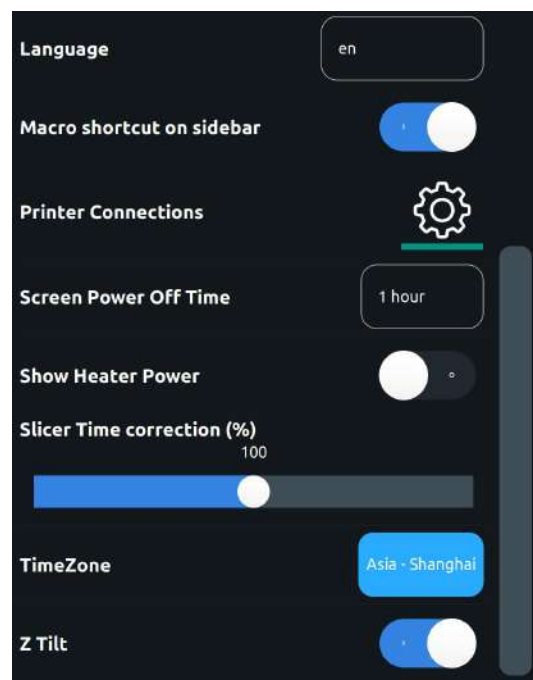
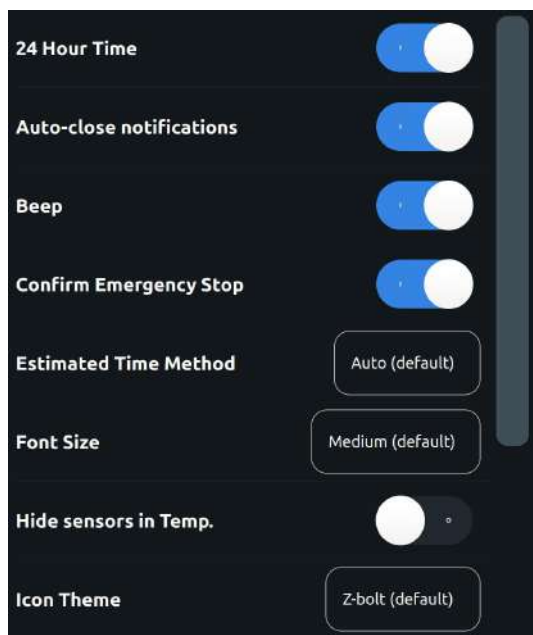


Save config

Save the current configuration, the system will restart.



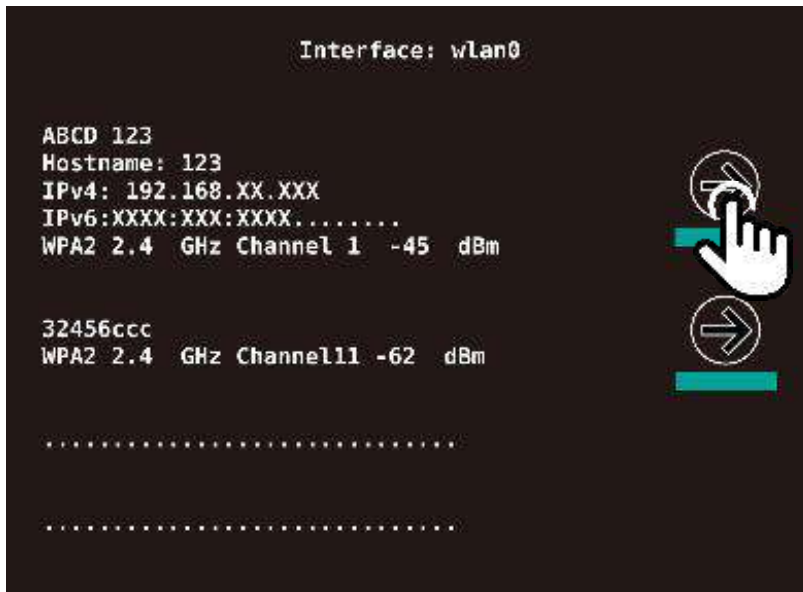
Settings



Network



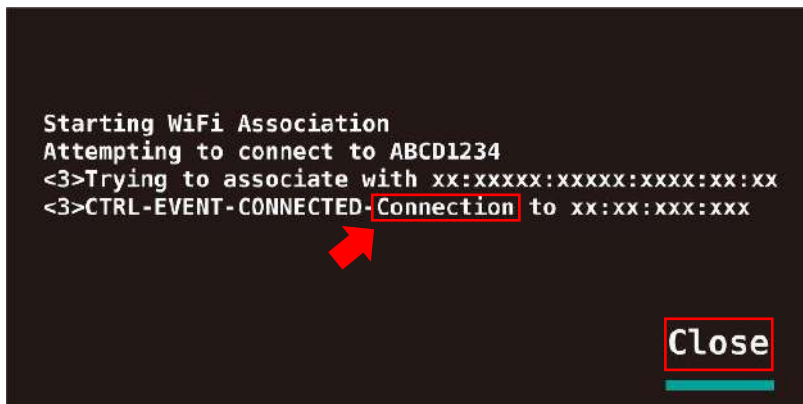
Network



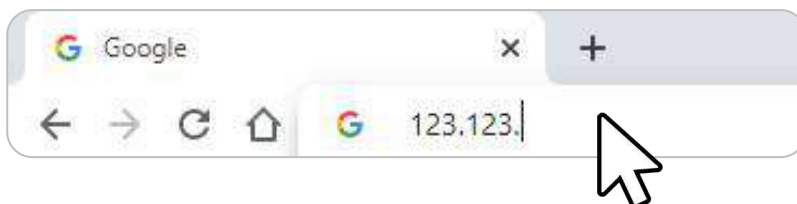
1. Choose a Wifi connection



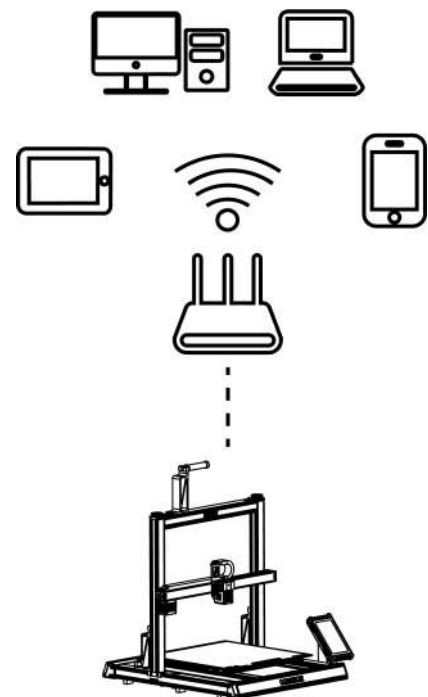
2. After entering the password, click *save* on the top right, not *✓* on the right bottom.



3. When there shows "Connection" or after click *close* on the right bottom and back to wifi interface, it shows "(connected)" after that wifi name, it means that is connecting successfully.

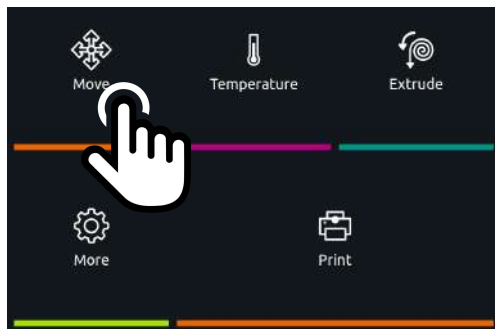


4. After connecting to Wifi, Check the IP address of this machine, Enter this IP address in the website address column of the browser to enter the printing page.

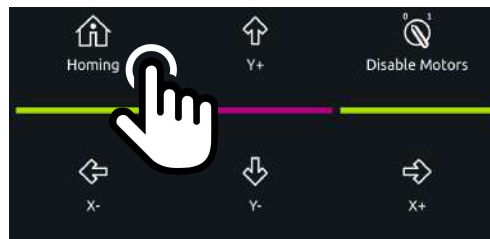


- ★ The network PC/mobile /tablet needs to be under the same router as the network of printer, so that they are able to connected remotely.

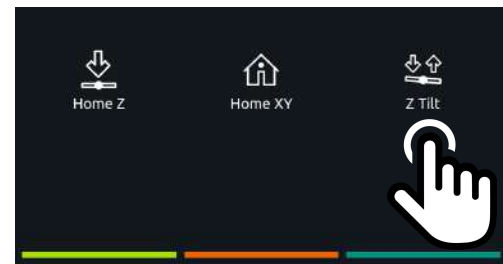
Bed Leveling



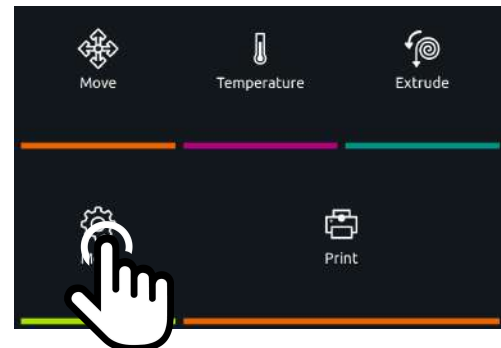
1. Click *Move* on the home page.



2. Click *Homing*.



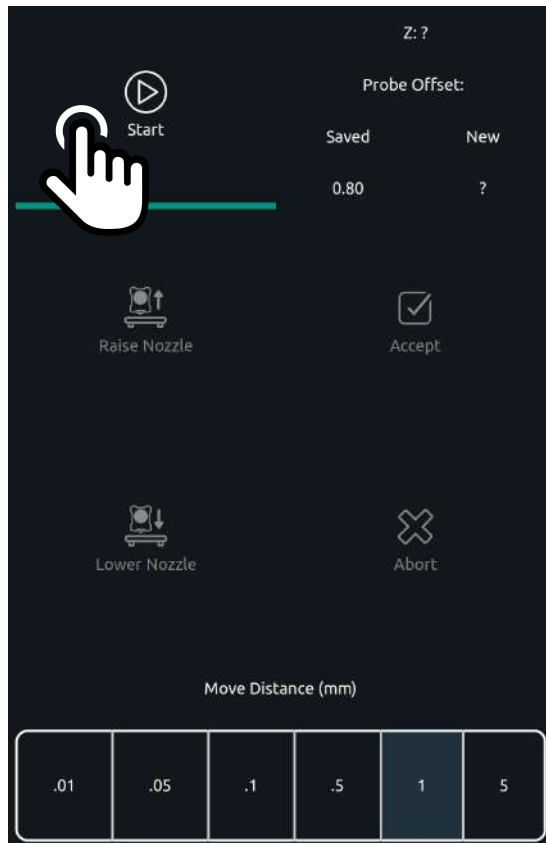
3. Click * Z Tilt*. The machine will detect the left and right sides of the hot bed, and automatically calibrate the level of the X-axis beam



4. After machine calibration stops, Click *More* on the home page.



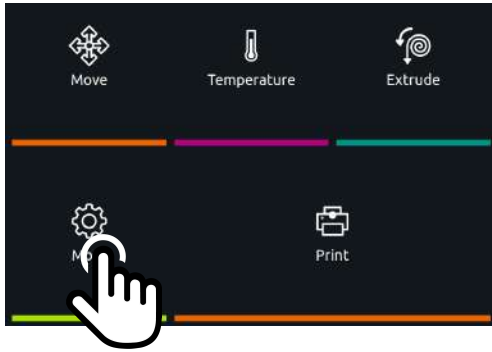
5. Click * Z calibrate*.



★ Please do not move a large distance at one time to avoid the nozzle hitting the hotbed.

6. Click *start*, the printer will auto home first.
7. After the printer auto home, the nozzle will slowly move to the center of the bed, put a piece of A4 paper between the nozzle and the hotbed.
8. Select the suitable move distance then click *raise nozzle * or * lower nozzle *, to adjust the distance between the nozzle and the hotbed.
9. Adjust the distance between the nozzle and the hotbed (please keep pulling the paper during the period, when you feel resistance to pulling the paper and the nozzle does not completely press the paper, the distance is appropriate.
10. Click *accept* to apply the values, then confirm and restart the system.

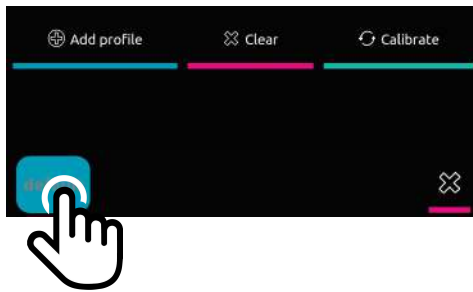
Bed Leveling



11. Click * More* on home page.

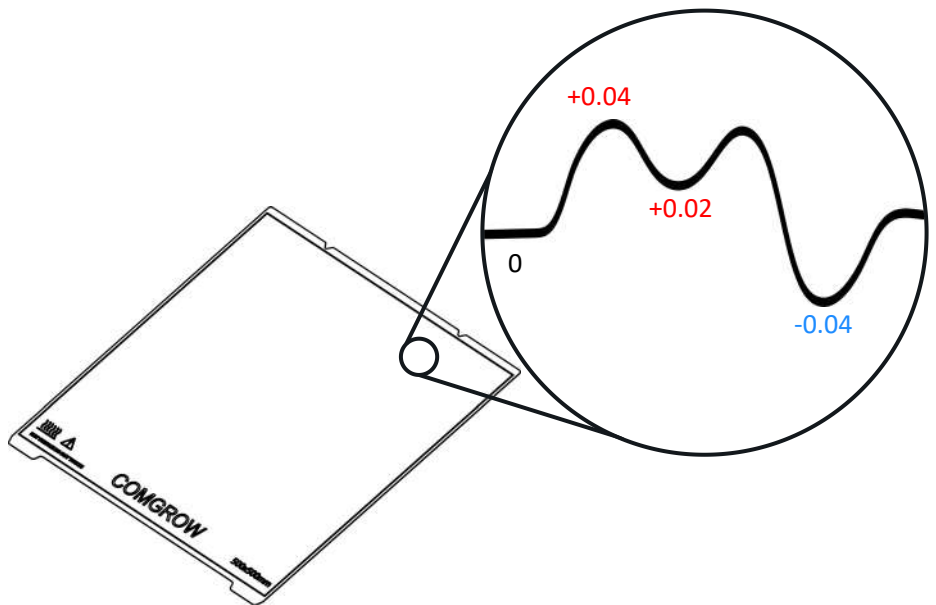
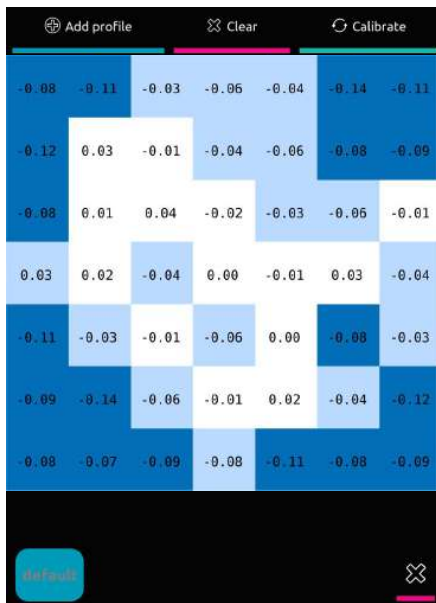


12. Click *Bed Mesh*, then click *Calibrate* after the detection is complete, restart the system, Leveling complete.



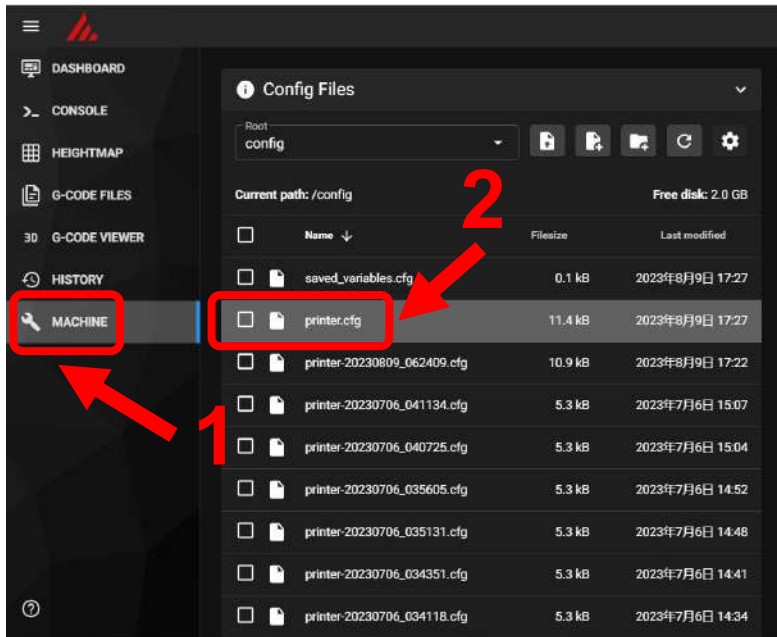
★ If you want to view the bed mesh data later, please return to this interface and click the current configuration name "default" to view

★ It is recommended that you fine-tune the Z offset value again according to the actual situation when printing



The bed mesh data reflects the concave and convex of the hotbed. The detection data divides the hotbed into 25 small areas to detect the concave and convex. When 0 means flat, the positive value means relatively high, and the negative value means equivalent low. Which can reflect the level of the hot bed, The subsequent printer will adjust the offset value between the nozzle and the hot bed based on these data to compensate

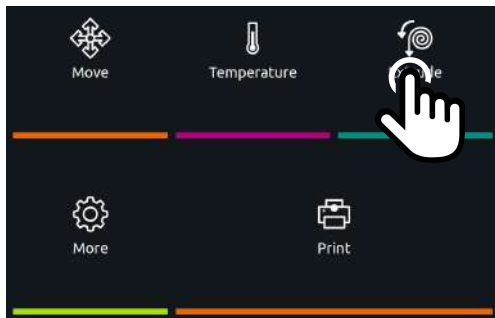
Change Configuration



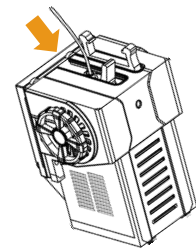
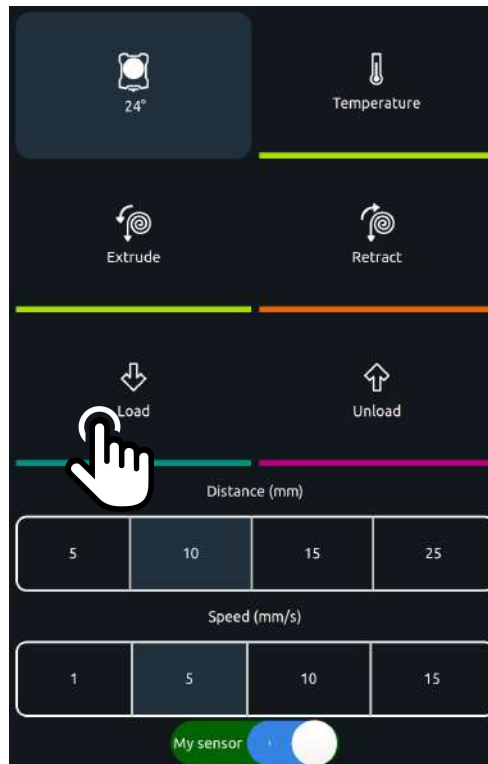
1. If you want to change the printer configuration, after entering the web page by IP, click the "configuration" option on the left menu bar
2. Click the "Printer.cfg" file (the one without the date) to configure
3. After the configuration is complete, click the "SAVE & RESTART" option in the upper right corner (the klipper system will restart)



Load/unload filament



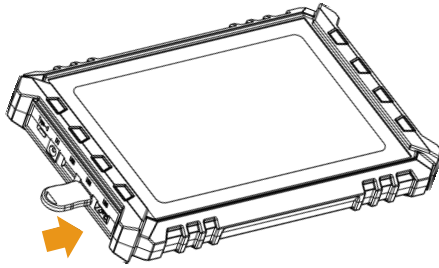
1. Click *Extrude* on the home page.



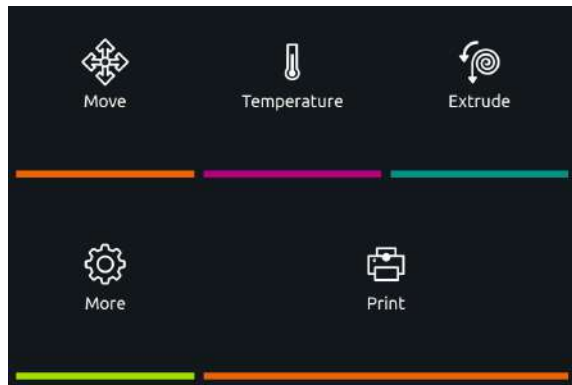
3. Then insert the filament in to the extruder, click *load*, the extruder will load the filament automatically, if you need custom adjustment. click *Extrude*, *Retract*, *Distance* or *Speed* to adjust.

- ★ Each machine has been tested before leaving the factory, and it is normal to have residual filament in the nozzle.
- ★ When the nozzle temp is so low, it is not allowed to have related operation about the extruder. Please pre-heat nozzle first.

Print



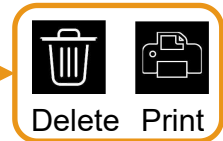
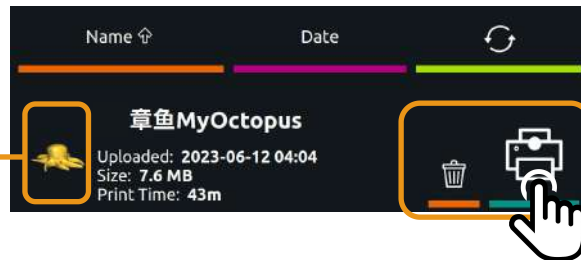
1. You can remotely upload files on the web page and print, or directly insert a U disk into the USB port on the display to print.



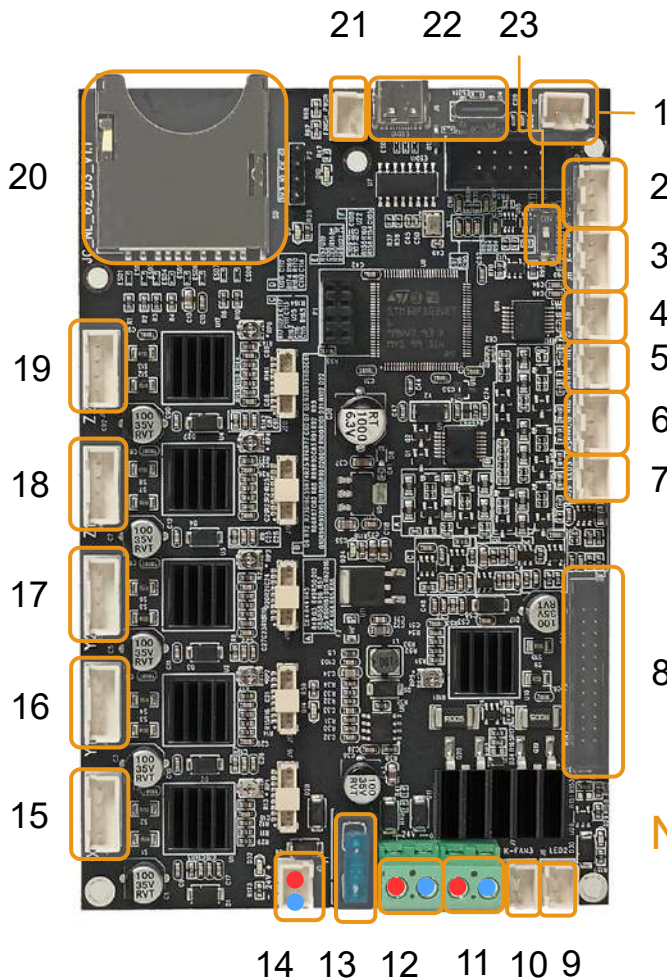
2. Click "Print" on the main interface.

3. Click the print icon or the STL thumbnail to print.

When this icon appears, it means it is a folder.



Mainboard



● + Positive ● - Negative

- | | | |
|---------------------------|---------------------------|---------------------|
| 1: Z Limit | 2: Y Limit | 3: X Limit |
| 4: Hotbed thermistor | 5: Chamber thermistor | |
| 6: Filament runout sensor | 7: LED | |
| 8: Extruder kit cable | 9: LED | |
| 10: K-Fan | 11: Hotbed Power | |
| 12: Power(24V) | 13: Fuse | |
| 14: Screen Power(24V) | 15: X Motor | |
| 16: Y1 Motor | 17: Y2 Motor | 18: Z1 Motor |
| 19: Z2 Motor | 20: SD card | 21: Shutdown module |
| 22: Type-C | 23: No Limit/Limit Switch | |

NOTE: 5,7,9,21 are reserved ports, and they are not connected to any parts out of factory.



comgrow facebook group



comgrow.com

SHENZHEN Comgrow Technology CO.,LTD.

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Email : service@comgrow.com



FCC Statement

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

Caution: Any changes or modifications to this device not explicitly approved by manufacturer could void your authority to operate this equipment.

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

RF Exposure Information

This equipment complies with FCC radiation exposure limits set forth for an uncontrolled environment. This equipment should be installed and operated with minimum distance 20cm between the radiator and your body.