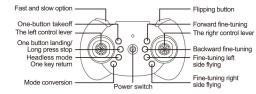
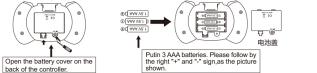
# AGES14+

# R/C QUADCOPTER



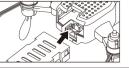
## 1. REMOTE CONTROL BATTERY INSTALLATION

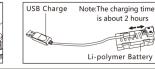
Open the battery cover on the back of remote controller. Insert 3X1.5V "AAA" batteries in accordance with the instructions on battery box. (Battery should be purchased separately, old and new or different types of batteries shouldn't be mixed )



# 2. AIRCRAFT BATTERY INSTALLATION AND CHARGING

- 2.1 Insert use charger into the USB interface on the computer of other chargers and then plug in, the indicator
- 2.2 Take off the battery from the aerocraft and then connect the battery socket with that on USB charger
- 2.3 The indicator light will be off in the battery charging process; the indicator light will be on after full charging.





# 3. INSTALL THE BLADE AND PROTECTIVE COVER

- 3.1 Prepare screwdriver and protect cover
- 3.2 Insert four protection covers into the holes of the the protection cover, which beside the four blades, and use the screw knife to lock four screws lightly.
- 3.3 Each paddle of flying device are not same, on each blade is marked with "A" or "B". When installing or paddle, please perform correctly installation according to the corresponding labels as shown in figure below. When paddle is not correctly installed, flying device can't take off, roll over, nd skating fly.













# 4. AIRCRAFT OPERATION AND CONTROL



5. FINE TUNING

6. SENSITIVITY SETTING

The left control level controls the

The right control lever is to control turning

marching / retreating t of flying device

When the flying device is in the flight, it appears deviations (turning

left/right; marching/retreating; left/right side); it is to adjust them by

turning the opposition direction corresponding slight keys. For

example: the flying device is deviated to front. So it is to adjust by

turning the backward "marching/ retreating slight" key as shown in

This aircraft can achieve three modes of operation: low (30%), intermediate (60%) and advanced (100%)

Press the "fast/slow" button once= the aircraft enters the intermediate mode (sensitivity up to 60%).

Press the "fast/slow" button again = the aircraft enters the advanced mode (sensitivity up to 100%).

Press the fast/slow button again to restore the original default low mode (30% slow).

rising and falling of flying device.









The left control lever is to control turning left /right of flying device

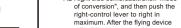




The right control lever is to contro

aircraft left and right side fly













# 7. FLIP MODE

The flying device can perform rolling flight of 360 degrees by following operation. In order to better implement rolling function, and endure flying device is kept five meters height above the ground, it is better to operate rolling in the process of rising up. In this case, the flying device can be kept with height after flying device performs rolling action.

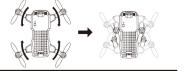
- 7.1 Left side somersault: Click "mode of conversion", andthen push the right-control lever to left in maximum. After the flying device rolls, it is to turn control lever to the middle position.
- 7.2 Right side somersault: Click "mode rolls, it is to turn control lever to
- 7.3 Front somersault: Click "mode of conversion", and then push the right-control lever to front in maximum. After the flying device rolls, it is to turn control lever to the middle position.
- 7.4 Backward somersault: Click "mode of conversion", and then push the right-control lever to backward in maximum. After the flying device rolls, it is to turn control lever to the middle position.



# 8. FOUR-AXIS FOLDING INSTRUCTIONS

The wing is capable of expansion and contraction and folded toward the direction of the arrow

Note: the protective cover must be removed in the process of folding.



# 9. HEADLESS MODE WITH ONE KEY RETURN

on the headless mode button, automatic locking direction aircraft takeoff. When found in aircraft flight has left you very far when you could not tell the direction, then click on the headless mode key you can not recognize the direction to control the aircraft return; return key or click the auto-off direction of the vehicle will automatically return. 9.1 Of the code of the aircraft must head toward the front (or rear headless mode and automatic mode opening direction will return disorder)

- 9.2 When you need to use the headless mode, click on the headless mode key, the vehicle will automatically lock the direction of takeoff.
- .3 When you do not use the headless mode, then click the headless mode button to exit the headless mode. 9.4 When you want to automatically return, click the button to automatically return the aircraft is in the direction of takeoff will be automatically refunded.
- 9.5 Automatic return process can be controlled manually about the direction of the aircraft, pushing the joystick

Warning: Try to choose less vision and pedestrians at the place with this aircraft, so as to avoid unnecessary losses!

## Automatic Altitude Mode

This aircraft adopts "barometer" module to achieve fixed height and hovering, use the left joystick (accelerator) to control rise/fall, loosen the left joystick (accelerator), the aircraft will hover at that height.

That is in pant, no matter what position the aircraft is, no matter what direction it's attiuce, as long as you click

## I. CAMERA USE

- 11.1 After connected with power supply of flying device, then it is to start up remote control device and proofreading
- 11.2 To turn up the "camera" key on the remote control device, and then the camera will take a photo (camera's
- 11.3 To turn up the 'camera' key on the remote control device, and then the camera will enter to mode of camera (camera's red light will keep flashing), and turn down the "camera" key on the remote control device, at this moment, the camera returns from camera mode.
- 11.4 To exit the camera mode, then turn off the power, and finally remove out the SD card.

# 12. TROUBLE SHOOTING DURING FLIGHT

Tail still off trim after tab adjustment. 1 Damaged tail rotors

Flight vehicle still wonders

during hover.

13. ACCESSORIES

6 or inconsistent speed during | 2. Damaged tail drive motor

forwardafter trim adjustment | Gyroscope midpoint not

Main motor A/B Receiver board

Flight vehicle still wonders left/ 1 Motor off

d right after trim adjustment 2. Cone loose

| situation   | Cause   | Way to deal  |
|---|---|--|
| Receiver staus LED blinks continuously for more than 4 seconds after flight vehicle battery inserted. No response to control input. | Unable to bind to transmitter.  | Repeat the power up initializing process.  |
| No response after battery is connected to flight vehicle.   | Power to transmitter and receiver.     Check transmitter and receiver voltage.     Poor contact on battery terminals. | Turn on transmitter and ensure flight vehicle battery is inserted properly.     Use fully charged batteries.     Re-seat the battery and ensure good contact between battery contacts. |
| Motor does not respond to throttle stick,receiver LED flashes.  | Flight vehicle battery depleted.  | Fully charge the battery, or replace with a fully charged battery.   |
| Main rotor spins but unable to take off.  | Deformed main blades.     Flight vehicle battery depleted   | Replace main blades     Charge or replace with fully charged battery.  |
| Strong vibration of flight vehicle  | Deformed main blades  | Replace main blades  |

Replace main blades

neutral point reboot

Replace the motor

. Installed tight cone

Replace the main motor

he boot will lift fine-tune the normalized

# uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is

no guarantee that interference will not occur in a particular installation.

could void the user's authority to operate the equipment.

If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two

conditions: (1) this device may not cause harmful interference, and (2) this device must accept

any interference received, including interference that may cause undesired operation.

changes or modifications not expressly approved by the party responsible for compliance

This equipment has been tested and found to comply with the limits for a Class B digital

device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable

protection against harmful interference in a residential installation. This equipment generates.

- Reorient or relocate the receiving antenna.
- -- Increase the separation between the equipment and receiver.
  - Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
  - Consult the dealer or an experienced radio/TV technician for help.

