

## Micro Tracker user guide



**Micro Tracker**

**Firmware V1.6**

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## Table of contents

1	Introduction .....	3
1.1	General Description .....	3
1.2	Applications .....	3
2	Features .....	3
3	Installation .....	4
3.1	Getting started.....	4
3.2	Fixation .....	4
4	Functioning .....	5
4.1	Main operating modes .....	5
4.2	Side operations .....	6
4.3	User interface .....	6
4.4	Geolocation strategies .....	8
5	Uplink messages.....	9
6	Remote configuration using ADA .....	10
6.1	Operating Mode Configuration .....	10
6.2	Position on demand .....	10
6.3	Parameters configuration.....	10
7	Downlink messages .....	11
7.1	Ack Token.....	11
7.2	Mode Configuration.....	12
7.3	Position on demand .....	12
7.4	Parameters configuration.....	12
8	Specifications .....	15
8.1	Physical configuration .....	15
8.2	Estimated lifetime .....	15
8.3	Data communication support.....	15
8.4	Position accuracy .....	16
8.5	Power management.....	16
9	Products References.....	16

## 1 Introduction

### 1.1 General Description

The Abeeeway Micro Tracker is a multi-mode tracker combining GPS/Low power GPS, Wi-Fi, LoRa, BLE radios with embedded sensors to support accurate outdoor and indoor geolocation. A button, a buzzer and 3 LEDs are available to interface with the user. The Micro Tracker, with its small size and long battery lifetime, is the ideal product for many tracking applications.

### 1.2 Applications

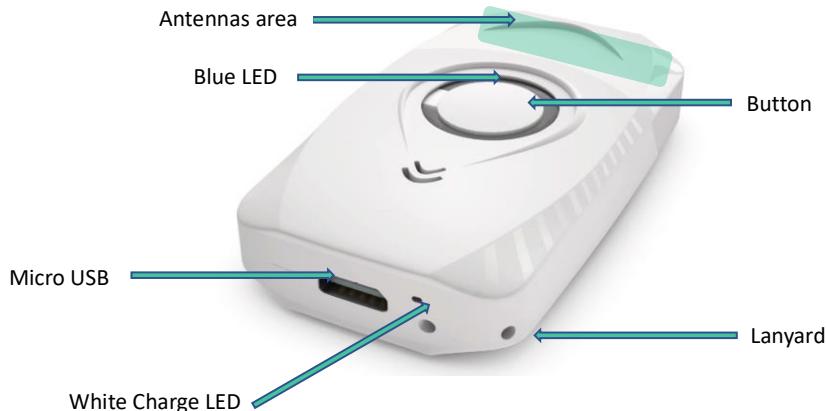
Commenté [AD1]: Need to be aligned with dataheet

- Asset tracking at fixed frequency updates or on demand.
- Personal tracking with help button.
- Safety monitoring for isolated workers inside facilities or in outdoor.
- Anti-theft; Notification and location when device is moving.
- Geofencing applications.

## 2 Features

- **Multiple operating modes**
  - **Motion tracking:** Get the tracker position at a given cycle when motion is detected.
  - **Permanent tracking:** Get permanently a position of the tracker.
  - **Start/End motion tracking:** Get position messages during motion start and end events.
  - **Activity tracking:** Monitor activity rate with embedded sensors.
  - **OFF:** device stopped
- **Position on demand:** Receive the tracker position only when needed (very low power operating mode).
- **Used geolocation technologies**
  - **GPS:** Precise outdoor position.
  - **Low power GPS:** get quick position outdoors and daylight indoor conditions.
  - **WI-FI:** Position indoors and urban area.
- **Buzzer and LEDs**
- **Temperature monitoring**
- **Embedded antennas**
- **LoRa™ Class A radio**
- **Water-spray resistant enclosure (IP64)**

### 3 Installation



#### 3.1 Getting started

- Charge your device using a micro USB cable. While charging the white led is ON. When the battery is fully charged the white LED goes OFF.
- A long press is needed to turn ON the device (starting in motion tracking mode in standard configuration).
- Your network can use two activation modes:
  - OTAA (Over The Air Activation) that requires the following keys to make the join: DEVEUI, APPEUI and APPKEY for each device. (the most used)
  - ABP (Activation by personalization) that requires the following keys to make the join: DEVEUI, DEVADDR and NWKSKEY for each device
- Depending on your operator, some actions need to be done to activate the transfer of the data through Abeeway servers. Please refer to your vendor for more information.

#### 3.2 Fixation

The device can be attached with the provided lanyard or placed in bag, or inside an asset.

Note: the environment and orientation of the tracker can influence the radio performance. For optimum results keep the zone around the antenna area clear from any conducting material or magnetic field.

## 4 Functioning

### 4.1 Main operating modes

This section describes the different operational modes supported by the trackers.

**OFF mode:** The tracker is in deep low power mode. No uplinks are sent in this mode. A long button press is required to wake it up. Three possibilities to set the tracker in OFF mode:

- User action (long button press)
- Low battery
- Downlink request

**Standby mode:** The tracker is sending periodically short LoRa messages, called heartbeat at the chosen period (*lora\_period*). Device position can be obtained in this mode by using the side operations features (see next section).

**Motion tracking mode:** The tracker provides positions when the device is moving. The reporting is done at the chosen period (*ul\_period*). The positions are acquired based on the *geoloc\_sensor* geolocation technology. If the device is not moving, heartbeat messages are sent regularly at the *lora\_period* frequency. Additional positions can be obtained by using the on-demand side operations features.

**Note:** Whatever the chosen geolocation policy, the first position is always established via WI-FIWi-Fi sent immediately after the beginning of the motion.

**Permanent tracking mode:** The device reports its positions at *ul\_period* frequency regardless the motion. It uses the *geoloc\_sensor* geolocation technology. Heartbeat messages are sent if there are no uplink message during *lora\_period* seconds.

**Motion Start/End tracking mode:** In this mode, position messages are sent twice, at the start and at the end of a motion (one Wi-Fi and one using the *geoloc\_sensor* geolocation technology). The end of the motion is detected when there is no movement detection for a period of 120 seconds. Heartbeat messages are sent if there are no uplink message during *lora\_period* seconds. Additional positions can be obtained by using the on-demand side operation feature.

**Activity mode:** This mode sends activity reports instead of positions. The tracker focuses on detecting movements. Each shake detection increases a counter (after applying an integration period). The value of the counter is reported up the LoRa link at the *ul\_period* frequency. Heartbeat messages are sent if there are no uplink messages during *lora\_period* seconds. Additional positions can be obtained by using the on-demand side operations features.

**Note:** The accuracy of the different frequencies is not guaranteed as extra delay may be introduced by the LoRa network duty cycle.

## 4.2 Side operations

Whatever the mode, optional messages can be sent according to the configuration. The side operations can be:

**Periodic position message:** The device sends periodically its position at *periodic\_pos\_period* frequency. Usually, this reporting frequency is very long. The position is sent three times (six if the device is moving).

**Position on Demand:** Position requests are done via LORA downlink message. The device answers with its current position.

**Alert position:** A double press on the button generates a LORA uplink message containing the position.

Notes:

- The geolocation strategy used in these cases is *geoloc\_method* one.
- The side operations can be cumulated.

## 4.3 User interface

### 4.3.1 Button management

Sequence	Action	Output
One short press	Show current mode and state	Led state pattern (see next section)
Two short presses	Trigger an alert position	Other Led pattern (see next section)
Any press when battery low (short or long press)	Go to OFF mode	Buzzer melody other Led pattern (see next section)
One long press when device OFF and good battery	Wake up	Other Led pattern (see next section) only for the first wake up after reset
One very long press (5 s) when device ON.	Go to the OFF mode	Buzzer melody
Button down when device is ON		Blue LED ON

#### 4.3.2 Blue LEDs mode and state patterns

This interface output is triggered by a single short button press. It generates two main sequences. The two sequences are consecutive. The first one indicates the mode, and is followed by the state of the tracker. The LED behavior are provided below.

##### Show current mode

- **Mode Standby:** No blink.
- **Mode Motion Track:** One long blink.
- **Mode Permanent Track:** Two long blinks.
- **Mode Motion Start/End Track:** Three long blinks.
- **Mode Activity:** Four long blinks.

##### Show current state

- **State Idle:** No blink.
- **State Tracking:** Two fast blinks.

#### 4.3.3 Other blue LEDs patterns

Three fast blinks	Go to the OFF mode (Low battery)
Three slow blinks	Device starting for the first time
Long fast blink of blue LED	LORA join operation in progress
Fast blink of blue LED after two button clicks	Device acknowledges the alert position

#### 4.3.4 Buzzer melodies

There are three different melodies:

Melody	Meaning
Major rising scale	Device is starting
Major falling scale	Device is going to OFF mode
Low battery	Low battery detected

## 4.4 Geolocation strategies

### 4.4.1 Main operating modes

The following geolocation policies (*geoloc\_sensor* parameter) are used when the operating mode is either motion-tracking, permanent-tracking, or start/end tracking.

- **Wi-Fi only** → Only Wi-Fi scans are used for position determination.
- **GPS only** → Only the GPS is used for position determination.
- **LP-GPS only** → GPS and LP-GPS are used for position determination.
- **Multimode (Wi-Fi + AGPS + GPS)** → Alternate Wi-Fi, LP-GPS and GPS technologies on failure, with timeout.
- **Wi-Fi-GPS only** → Wi-Fi then GPS if Wi-Fi fails in one geolocation cycle.
- **Wi-Fi-LPGPS only** → Wi-Fi then LP-GPS if Wi-Fi fails in one geolocation cycle.
- **Wi-Fi-LPGPS/ Wi-Fi-GPS** → Wi-Fi-LPGPS first, then Wi-Fi-GPS if Wi-Fi-LPGPS fails until timeout, then back to Wi-Fi-LGPS.

Note: The first position is always a Wi-Fi one whatever the chosen geolocation strategy.

### 4.4.2 Side operations

The following geolocation policies (*geoloc\_method* parameter) are used for periodic-reporting or on-demand actions.

- **Wi-Fi only** → Only Wi-Fi scans are used for position determination.
- **GPS only** → Only the GPS is used for position determination.
- **LP-GPS only** → GPS and LP-GPS are used for position determination.
- **Wi-Fi-GPS only** → Wi-Fi then GPS if Wi-Fi fails in one geolocation cycle.
- **Wi-Fi-LPGPS only** → Wi-Fi then LP-GPS if Wi-Fi fails in one geolocation cycle.

## 5 Uplink messages

Type of message	Content
<b>Heartbeat message</b>	Notify the server the tracker is operational and under LoRa coverage
<b>Position message</b>	GPS, low power GPS or Wi-Fi position data
<b>Energy status message</b>	Used by the server to estimate the battery level. Contain information related to the power consumption
<b>Activity Status message</b>	Reports the activity counter. Used only by the activity tracking operating mode
<b>Debug message</b>	Internal used only
<b>Frame pending</b>	When additional downlink messages are available on gateway, this uplink message is sent to trigger the sending (and speed up the configuration of the tracker)
<b>OFF message</b>	Notify the move to the OFF state

## 6 Remote configuration using ADA

All following parameters are configurable in Abeeway Data Analyzer (ADA) application

### 6.1 Operating Mode Configuration

All modes can be set using ADA application:

- Standby
- Motion tracking
- Permanent tracking
- Motion start/end tracking
- Activity tracking
- OFF

### 6.2 Position on demand

Position of the tracker can be requested.

### 6.3 Parameters configuration

Following parameters are configurable:

- Parameters used in the main operating modes:
  - ✓ LoRa Heartbeat: period of Lora Heartbeat messages
  - ✓ Position report: period of LoRa position messages
  - ✓ Geolocation methodology (geoloc sensor)
- Parameters used in side operating modes:
  - ✓ Periodic position: activation, and period of LoRa position messages
  - ✓ Geolocation methodology (geoloc method)

## 7 Downlink messages

These messages are sent from the server to the tracker through the LoRa network. They are used to configure the tracker or request a position. Each message contains a header including:

- A message type
- An acknowledgement token

The remaining of the message depends on the message type. The tracker accepts three types of downlink messages, listed in the following table:

Message type	ID	Description
POD	0x01	Position on demand
Set Mode	0x02	Change the tracker mode
Set Param	0x0B	Modify a parameter

### Notes

1. Any unexpected message (unknown message type, bad length, ...) is discarded. However, the ack token is updated even if the message is discarded (if the payload is at least 2 bytes long).
2. The LoRa port to be used for downlink is 2.

### 7.1 Ack Token

It provides a way to indicate to the application that a given message has been received and processed by the tracker.

The ack token is transmitted in every uplink message, and it is updated when the tracker receives a LoRa message. This way, each time the server receives a LoRa uplink, it knows whether the previous message has been received.

The ack token is four bits long. Its value ranges from 0 to 15(0x0F).

### Notes

1. The ack token value should be updated for each downlink to be used by the application.
2. It's up to the application to process or not the ack tokens.
3. It's up to the application to manage the confirmations. It can either wait for the matching ack token in the uplink message before sending another downlink or send multiple downlink and later waits for the acks.

## 7.2 Mode Configuration

The operating mode can be remotely configured with a downlink LoRa message built as follow:

Byte 0	Byte 1	Byte 2
0x02	ACK	Mode

ACK: Ack token. Refer to the associated section.

Mode: operating modes. Acceptable values are:

- 0- Standby
- 1- Motion tracking
- 2- Permanent tracking
- 3- Motion start/end tracking
- 4- Activity tracking
- 5- OFF

Example:

Changing the operating mode to “motion tracking” (01) with an ack token of 3: **0x020301**.

## 7.3 Position on demand

Whatever the state, a position can be requested from the tracker by the message:

Byte 0	Byte 1
0x01	ACK

Example:

Position on demand message with ack token of 2: **0x0102**.

## 7.4 Parameters configuration

Any parameter can be remotely modified with a downlink LoRa message.

Such messages are built according to the following format:

Byte 0	Byte 1	Byte 2	Byte 3-6
0x0B	ACK	Parameter ID	New value [31-00]

The parameters identifier and the values are given in the following table

Parameter	ID	Unit	Range	Description
Position period <i>ul_period</i>	0x00	second	60 - 86400	Period of position or activity messages in motion tracking, start end tracking, activity mode or permanent operating mode
heartbeat period <i>lora_period</i>	0x01	second	300 - 86400	Period of heartbeat messages (sent only in idle state)
Periodic position report period * <i>periodic_pos_period</i>	0x03	second	0, 900 - 604800	Period of the periodic position report. When 0, no periodic position report is transmitted.
Geolocation sensor profile <i>Geoloc_sensor</i>	0x05	none	0 - 9	Geolocation policy used in motion, start end or permanent tracking operating mode 0- Wi-Fi only 1- GPS only 2- LP-GPS (AGPS/GPS) 3- Reserved (do not use) 4- Reserved (do not use) 5- Multimode (Wi-Fi + LP-GPS + GPS) (with reset to Wi-Fi on timeout) 6- Wi-Fi-GPS only (Wi-Fi then GPS if Wi-Fi fails in one geolocation cycle) 7- Wi-Fi-LPGPS only (Wi-Fi then LP-GPS if Wi-Fi fails in one geolocation cycle) 8- Reserved (do not use) 9- Wi-Fi-LPGPS first, the Wi-Fi-GPS until timeout, then back to Wi-Fi-LGPS
Oneshot geolocation method <i>Geoloc_method</i>	0x06	none	0-4	Geolocation policy used for periodic or on demand positions: 0- WI-FI 1- GPS 2- XGPS (Low power GPS/GPS) 3- Wi-Fi-GPS only (Wi-Fi then GPS if Wi-Fi fails in one geolocation cycle) 4- Wi-Fi-LPGPS only (Wi-Fi then LP-GPS if Wi-Fi fails in one geolocation cycle)

**Example:**

To modify the heartbeat period to 1 hour, the command **0x0B020100000E10** should be sent.

**Description:**

- (0x0B) : set the parameter.
- (0x02) : with an ack token of 2
- (0x01) : heartbeat message period.
- (0x 00 00 0E 10) : to a value of 3600s = 1 hour.

It is possible to modify two parameters in the same message by using the following format:

		Parameter 1		Parameter 2	
Byte 0	Byte 1	Byte 2	Byte 3-6	Byte 2	Byte 3-6
0x0B	ACK	ID	New value1 [31-00]	ID	New value2 [31-00]

## 8 Specifications

### 8.1 Physical configuration

<b>Size</b>	59mm x 34 mm x13 mm (L x l x h)
<b>Weight</b>	21g
<b>Waterproof capability</b>	IP64
<b>Operating temperature</b>	0°C to 45 °C (Charge) -10°C to 55 °C (Operation)
<b>Storage temperature</b>	10°C to 30 °C (recommended)
<b>Humidity</b>	5% to 95% non-condensing
<b>Time storage max</b>	6 months
<b>Power supply</b>	5v (using micro USB connector)

(1) In static, 5 satellites or more at -130 dBm

### 8.2 Estimated lifetime

Use Case	Battery Life (Approx.)
Standby mode	10 months at 20°C
Movement detection (120 positions per day)	>10 days <sup>(3)</sup>

(3) Using WIFI modes

### 8.3 Data communication support

<b>LoRa™ Modem</b>	Semtech transceiver SX1272
<b>Protocol</b>	LoRaWAN v1.0.2 Class A
<b>Frequencies bands</b>	EU 868MHz ISM band US 902-928MHz
<b>Configuration supported</b>	OTA or ABP
<b>RF power</b>	14 dBm (EU) 16.5 dBm (max)
<b>Min sensitivity of LoRa receiver</b>	-130 dBm in SF10
<b>WiFi Frequency band</b>	2412 – 2472MHz
<b>WiFi sniffer max emission</b>	3 dBm
<b>BLE sensitivity</b>	-88 dBm
<b>BLE RF output power</b>	4 dBm max
<b>BLE frequency band</b>	2402 – 2480MHz
<b>GNSS band</b>	1559 – 1610MHz

## 8.4 Position accuracy

<b>GPS</b>	Position Accuracy (50%-90%) <sup>(2)</sup>	10 to 20 meters	
	Time to have a position <sup>(2)</sup>	Cold start	50-210 seconds
		Hot start	15 seconds
Acquisition sensitivity		-140 dBm	
<b>Low power GPS</b>	Position Accuracy (50%-90%) <sup>(2)</sup>	15 - 30 meters	
	Time to have a position <sup>(2)</sup>	10 - 30 seconds	
	Acquisition sensitivity	-160 dBm	
<b>Wi-Fi</b>	Indoor Position accuracy	20 - 50 meters	
	Time to have a position	3 seconds	

(2) In static, >5 satellites at -130 dBm

## 8.5 Power management

Rechargeable Battery	3.7V	0.45 Ah
Battery type	Lithium Polymer	
Charger supply	5V from a standard micro USB charger	
Power consumption	Stand-by: 0,01mA/h	
	GPS tracking in cold start <sup>(1)</sup> : 1,5mA/h (per position)	
	Low power GPS tracking <sup>(1)</sup> : 0,3mA/h (per position)	
	WiFi tracking: 0,1mA/h (per position)	

(1) In static, 6 satellites or more at -130 dBm

## 9 Instructions / Warnings

*This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.*

*Any changes or modifications to this equipment not expressly approved by ABEEWAY may cause, harmful interference and void the FCC authorization to operate this equipment.*

*This portable equipment with it's antenna complies with FCC's radiation exposure limits set forth for an uncontrolled environment. To maintain compliance, follow the instructions below :*

1. *This transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.*
2. *Avoid direct contact to the antenna, or keep contact to a minimum while using this equipment.*

*This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:*

- Reorient or relocate the receiving antenna.*
- Increase the separation between the equipment and receiver.*
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.*
- Consult the dealer or an experienced radio/TV technician for help*

## 10 Products References

Product definition	SKU
MICRO TRACKER WHITE EU868 (option small packing box)	DEABE003-xxxEU
MICRO TRACKER WHITE US915 (option small packing box)	DEABE001-xxxUS
MICRO TRACKER WHITE US915 (option retail packing box)	DEABE004-xxxUS

Minor version updates are defined by suffix xxx