

SAR TEST REPORT	
Report Reference No.	LCS171204015AEB
FCC ID.	2AOA5CCCC0217002
Testing Laboratory Name	Shenzhen LCS Compliance Testing Laboratory Ltd.
Address	1/F., Xingyuan Industrial Park, Tongda Road, Bao'an Avenue, Bao'an District, Shenzhen, Guangdong, China
Applicant's name	Saturn Technology Group, LLC.
Address	2664-B Saturn St. Brea, Ca. 92821
Test specification	IEEE 1528:2013
Standard	47CFR §2.1093 KDB 865664
Test Report Form No	LCSEMC-1.0
TRF Originator	Shenzhen LCS Compliance Testing Laboratory Ltd.
Master TRF	Dec. 08, 2017
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Test item description	Lingo
Trade Mark	Lingo
Manufacturer	Saturn Technology Group, LLC.
Model/Type reference	FYQ-I
Ratings	DC 3.70V
EUT Type	Production Unit
Exposure category	General population / Uncontrolled environment
Device type	Portable device
Result	PASS

Compiled by:

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Dick Su

Dick Su/ Technique principal

Approved by:

Gavin Liang

Gavin Liang/ Manager

TEST REPORT

Test Report No. :	LCS171204015AEB	Dec. 08, 2017
		Date of issue

Equipment under Test : Lingo

Model /Type : FYQ-I

Applicant : **Saturn Technology Group, LLC.**

Address : 2664-B Saturn St. Brea, Ca. 92821

Manufacturer : **Saturn Technology Group, LLC.**

Address : 2664-B Saturn St. Brea, Ca. 92821

Test Result:	PASS
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The test report merely corresponds to the test sample.

It is not permitted to copy extracts of these test result without the written permission of the test laboratory.

**** Modified History ****

Revision	Description	Issued Date	Remark
Revision 1.0	Initial Test Report Release	2017-12-08	Gavin Liang

Contents

<u>1.</u>	<u>TEST STANDARDS/PROCEDURES REFERENCE/FCC KDBS.....</u>	<u>6</u>
<u>2.</u>	<u>SUMMARY</u>	<u>7</u>
2.1.	General Remarks	7
2.2.	Accessories of EUT	7
2.3.	Short description of the Equipment under Test (EUT)	7
2.4.	TEST Configuration	8
2.5.	EUT operation mode	8
2.6.	EUT configuration	8
<u>3.</u>	<u>TEST ENVIRONMENT.....</u>	<u>9</u>
3.1.	Address of the test laboratory	9
3.2.	Test Facility	9
3.3.	Environmental conditions	9
3.4.	SAR Limits	9
3.5.	Equipments Used during the Test	10
<u>4.</u>	<u>SAR MEASUREMENTS SYSTEM CONFIGURATION</u>	<u>10</u>
4.1.	SAR Measurement Set-up	10
4.2.	DASY5 E-field Probe System	12
4.3.	Phantoms	13
4.4.	Device Holder	13
4.5.	Scanning Procedure	14
4.6.	Data Storage and Evaluation	15
4.7.	SAR Measurement System	17
4.8.	Tissue equivalent liquid properties	18
4.9.	System Check	18
4.10.	SAR measurement procedure	20
<u>5.</u>	<u>TEST CONDITIONS AND RESULTS.....</u>	<u>26</u>
5.1.	Conducted Power Results	26
5.2.	Antenna Location	27
5.3.	SAR Measurement Results	28
5.4.	SAR Reporting Results	30
5.5.	SAR Measurement Variability	31
5.6.	Measurement Uncertainty(300MHz-3GHz)	32
5.7.	System Check Results	36
5.8.	SAR Test Graph Results	37
5.9.	Simultaneous Transmission	38
<u>6.</u>	<u>CALIBRATION CERTIFICATE</u>	<u>39</u>
6.1.	Probe Calibration Ceriticate	39
6.2.	D2450V2 Dipole Calibration Certificate	50

6.3. DAE4 Calibration Certificate	58
7. <u>TEST SETUP PHOTOS</u>	62
8. <u>EXTERNAL PHOTOS OF THE EUT</u>	65

1. TEST STANDARDS/PROCEDURES REFERENCE/FCC KDBs

The tests were performed according to following standards:

[IEEE 1528-2013 \(2014-06\)](#): Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques

[IEEE Std. C95-3 \(2002\)](#): IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields – RF and Microwave

[IEEE Std. C95-1 \(1991\)](#): IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz.

[KDB 865664D01v04 \(August 7, 2015\)](#): SAR Measurement Requirements for 100 MHz to 6 GHz

[KDB 865664D02v01r02 \(October 23, 2015\)](#): RF Exposure Compliance Reporting and Documentation Considerations

[KDB 447498D01v06 \(October 23, 2015\)](#): RF Exposure Procedures and Equipment Authorization Policies for Mobile and Portable Devices

[KDB 248227 D01v02r02 \(October 23, 2015\)](#): SAR GUIDANCE FOR IEEE 802.11 (Wi-Fi) TRANSMITTERS

[IEC 62209-2 \(2010\)](#): Human exposure to radio frequency fields from hand-held and bodymounted wireless communication devices. Human models, instrumentation, and procedures. Procedure to determine the specific absorption rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)

2. SUMMARY

2.1. General Remarks

EUT* Name	:	Lingo
Model Number	:	FYQ-I
EUTfunction description	:	Please reference user manual of this device
Power supply	:	DC 5V from external AC Adapter DC 3.7V built-in battery
Radio Technology	:	IEEE802.11b/g/n
FCC Operation frequency	:	IEEE 802.11b: 2412MHz—2462MHz IEEE 802.11g: 2412MHz—2462MHz IEEE 802.11n HT20: 2412MHz—2462MHz IEEE 802.11n HT40:2422MHz—2452MHz BT Classic and BLE:2402-2480MHz
Modulation	:	IEEE 802.11b: DSSS(CCK,DQPSK,DBPSK) IEEE 802.11g: OFDM(64QAM, 16QAM, QPSK, BPSK) IEEE 802.11n HT20, HT40: OFDM (64QAM, 16QAM, QPSK,BPSK) BT Classic and BLE :GFSK, PI /4 QPSK, 8-DPSK
Transmitter rate	:	IEEE 802.11b: 1, 2, 5.5, 11 Mbps IEEE 802.11g: 6, 9, 12, 18, 24, 36, 48, 54 Mbps IEEE 802.11n HT20: up to 150 Mbps, HT40: up to 300Mbps BT Classic and BLE :1Mbps, 2Mbps, 3Mbps
Maximum Reported SAR Values	:	Body: 0.926 mW/g (100% Duty Cycle)
Antenna Type	:	Integrated antenna, maximum PK gain: 1.89dBi
Sample Type	:	Series production
Exposure category:	:	General population / Uncontrolled environment

Note1: EUT is the ab.of equipment under test.

2.2. Accessories of EUT

N/A

2.3. Short description of the Equipment under Test (EUT)

The spatial peak SAR values were assessed for systems. Battery and accessories shell be specified by the manufacturer. The EUT battery must be fully charged and checked periodically during the test to ascertain uniform power output.

The sample enter into 100% duty cycle continuous transmit controlled by software provied by application. The sample was use test software to control transmit.

2.4. TEST Configuration

Face-Held Configuration

Face-held Configuration- per FCC KDB447498 page 23: "A test separation distance of 25 mm must be applied for in-front-of the face SAR test exclusion and SAR measurements."

2.5. EUT operation mode

The EUT has been tested under typical operating condition and The Transmitter was operated in the normal operating mode. The TX frequency was fixed which was for the purpose of the measurements.

2.6. EUT configuration

The following peripheral devices and interface cables were connected during the measurement:

- - supplied by the manufacturer
- - supplied by the lab

Battery1#: 1600mAh Lithium-ion Battery

The following peripheral devices and interface cables were connected during the measurement:

Accessory name	Internal Identification	Model	Description	Remark
Antenna	A1	N/A	Inner Antenna and Ingrate antenna	performed
Battery	B1	N/A	1600mAh Lithium-ion Battery	performed

AE ID: is used to identify the test sample in the lab internally.

3. TEST ENVIRONMENT

3.1. Address of the test laboratory

Shenzhen LCS Compliance Testing Laboratory Ltd

1/F., Xingyuan Industrial Park, Tongda Road, Bao'an Avenue, Bao'an District, Shenzhen, Guangdong, China
The sites are constructed in conformance with the requirements of ANSI C63.4 (2014) and CISPR Publication 22.

3.2. Test Facility

The test facility is recognized, certified, or accredited by the following organizations:

CNAS Registration Number. is L4595.

FCC Registration Number. is 899208.

Industry Canada Registration Number. is 9642A-1.

VCCI Registration Number. is C-4260 and R-3804.

ESMD Registration Number. is ARCB0108.

UL Registration Number. is 100571-492.

TUV SUD Registration Number. is SCN1081.

TUV RH Registration Number. is UA 50296516-001

NVLAP Registration Code is 600167-0

3.3. Environmental conditions

During the measurement the environmental conditions were within the listed ranges:

Temperature:	18-25 ° C
Humidity:	40-65 %
Atmospheric pressure:	950-1050mbar

3.4. SAR Limits

FCC Limit (1g Tissue)

EXPOSURE LIMITS	SAR (W/kg)	
	(General Population / Uncontrolled Exposure Environment)	(Occupational / Controlled Exposure Environment)
Spatial Average (averaged over the whole body)	0.08	0.4
Spatial Peak (averaged over any 1 g of tissue)	1.60	8.0
Spatial Peak (hands/wrists/feet/ankles averaged over 10 g)	4.0	20.0

Population/Uncontrolled Environments are defined as locations where there is the exposure of individual who have no knowledge or control of their exposure.

Occupational/Controlled Environments are defined as locations where there is exposure that may be incurred by people who are aware of the potential for exposure (i.e. as a result of employment or occupation).

3.5. Equipments Used during the Test

Test Equipment	Manufacturer	Type/Model	Serial Number	Calibration	
				Last Calibration	Calibration Interval
Data Acquisition Electronics DAEx	SPEAG	DAE4	1267	2017/02/23	1
E-field Probe	SPEAG	EX3DV4	3789	2017/01/13	1
System Validation Dipole D2450V2	SPEAG	D2450V2	733	2016/12/07	3
Network analyzer	Agilent	8753E	US37390562	2017/03/01	1
Dielectric Probe Kit	Agilent	85070E	US44020288	/	/
Power meter	Agilent	E4417A	GB41292254	2016/12/13	1
Power sensor	Agilent	8481H	MY41095360	2016/12/13	1
Power sensor	Agilent	8481H	MY41095361	2016/12/13	1
Signal generator	IFR	2032	203002/100	2016/12/13	1
Amplifier	AR	75A250	302205	2016/12/13	1
Attenuator	SHX	TS2-3dB	30704	NCR	NCR
RF Bi-Directional Coupler	Agilent	86205-60001	MY31400031	NCR	NCR

Note:

- 1) Per KDB865664D01 requirements for dipole calibration, the test laboratory has adopted three year extended calibration interval. Each measured dipole is expected to evaluate with following criteria at least on annual interval.
 - a) There is no physical damage on the dipole;
 - b) System check with specific dipole is within 10% of calibrated values;
 - c) The most recent return-loss results, measured at least annually, deviates by no more than 20% from the previous measurement;
 - d) The most recent measurement of the real and imaginary parts of the impedance, measured at least annually is within 5Ω from the previous measurement.
- 2) Network analyzer probe calibration against air, distilled water and a shorting block performed before measuring liquid parameters.

4. SAR Measurements System configuration

4.1. SAR Measurement Set-up

The DASY5 system for performing compliance tests consists of the following items:

A standard high precision 6-axis robot (Stäubli RX family) with controller and software. An arm extension for accommodating the data acquisition electronics (DAE).

A dosimetric probe, i.e. an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.

A data acquisition electronic (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.

A unit to operate the optical surface detector which is connected to the EOC.

The Electro-Optical Coupler (EOC) performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the DASY5 measurement server.

The DASY5 measurement server, which performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation. A computer operating Windows 2003.

DASY5 software and SEMCAD data evaluation software.

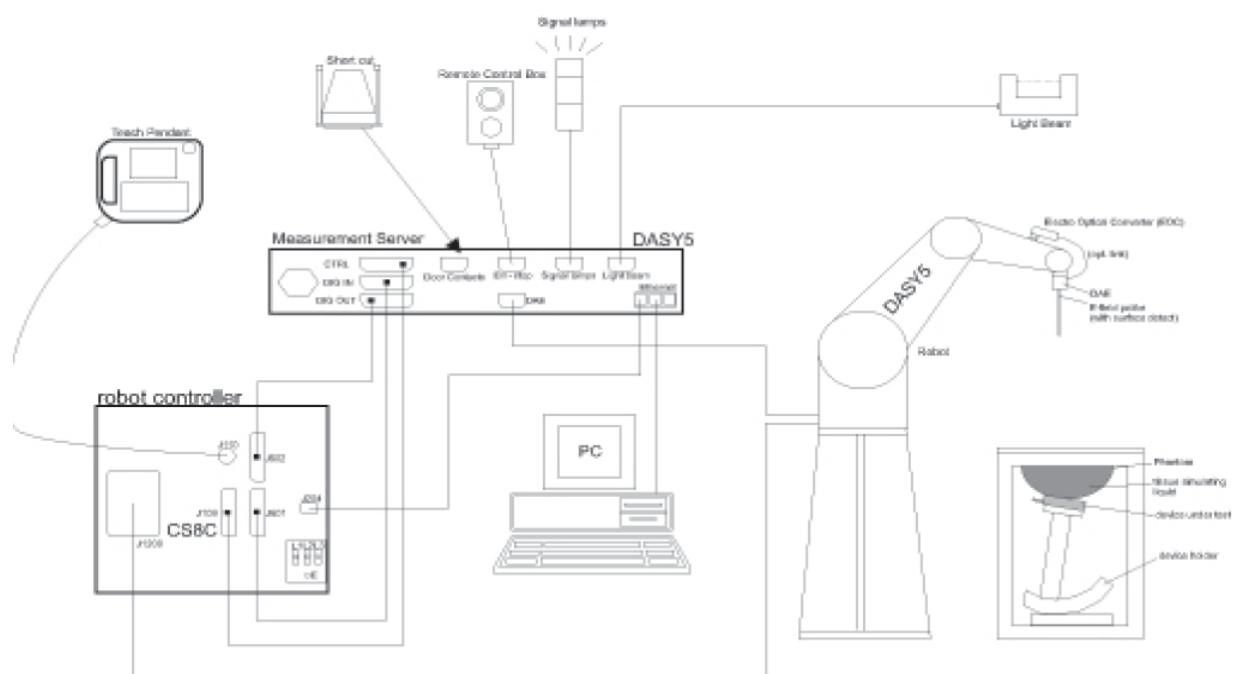
Remote control with teach panel and additional circuitry for robot safety such as warning lamps, etc.

The generic twin phantom enabling the testing of left-hand and right-hand usage.

The device holder for handheld mobile phones.

Tissue simulating liquid mixed according to the given recipes.

System validation dipoles allowing to validate the proper functioning of the system.



4.2. DASY5 E-field Probe System

The SAR measurements were conducted with the dosimetric probe ES3DV3 (manufactured by SPEAG), designed in the classical triangular configuration and optimized for dosimetric evaluation.

Probe Specification

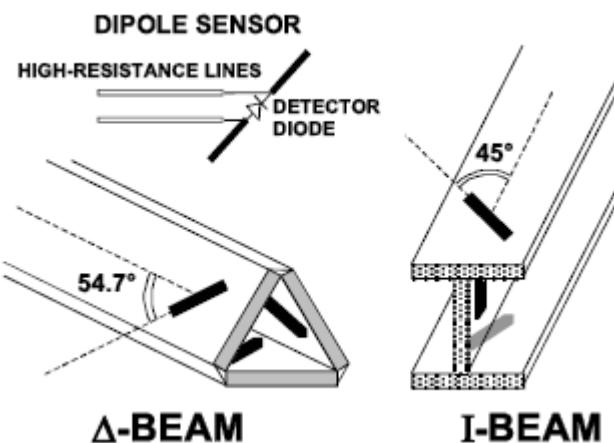
Construction	Symmetrical design with triangular core Interleaved sensors Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)
Calibration	ISO/IEC 17025 calibration service available.
Frequency	10 MHz to 4 GHz; Linearity: ± 0.2 dB (30 MHz to 4 GHz)
Directivity	± 0.2 dB in HSL (rotation around probe axis) ± 0.3 dB in tissue material (rotation normal to probe axis)
Dynamic Range	5 μ W/g to > 100 mW/g; Linearity: ± 0.2 dB
Dimensions	Overall length: 337 mm (Tip: 20 mm) Tip diameter: 3.9 mm (Body: 12 mm) Distance from probe tip to dipole centers: 2.0 mm
Application	General dosimetry up to 4 GHz Dosimetry in strong gradient fields Compliance tests of mobile phones
Compatibility	DASY3, DASY4, DASY52 SAR and higher, EASY4/MRI



Isotropic E-Field Probe

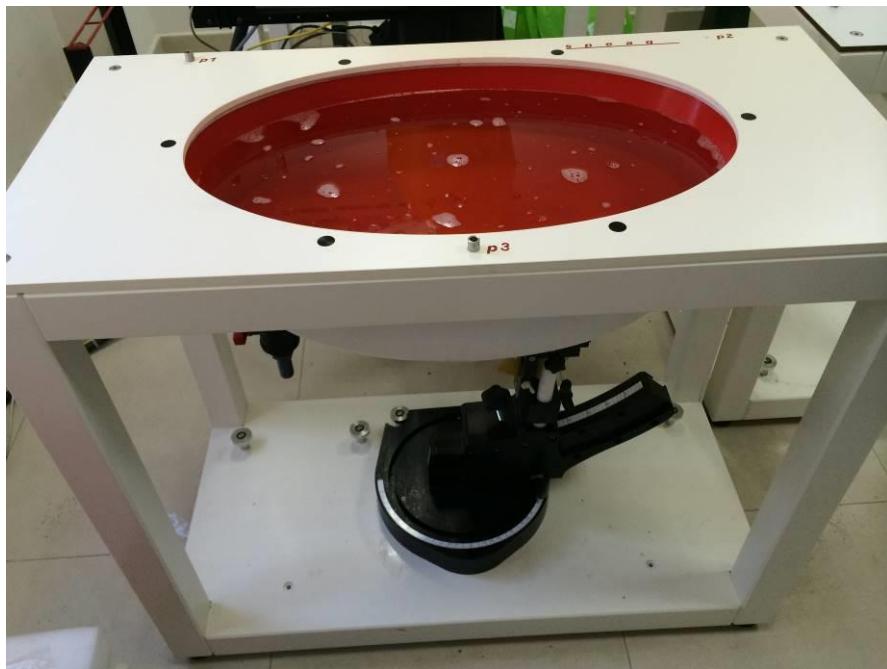
The isotropic E-Field probe has been fully calibrated and assessed for isotropicity, and boundary effect within a controlled environment. Depending on the frequency for which the probe is calibrated the method utilized for calibration will change.

The E-Field probe utilizes a triangular sensor arrangement as detailed in the diagram below:



4.3. Phantoms

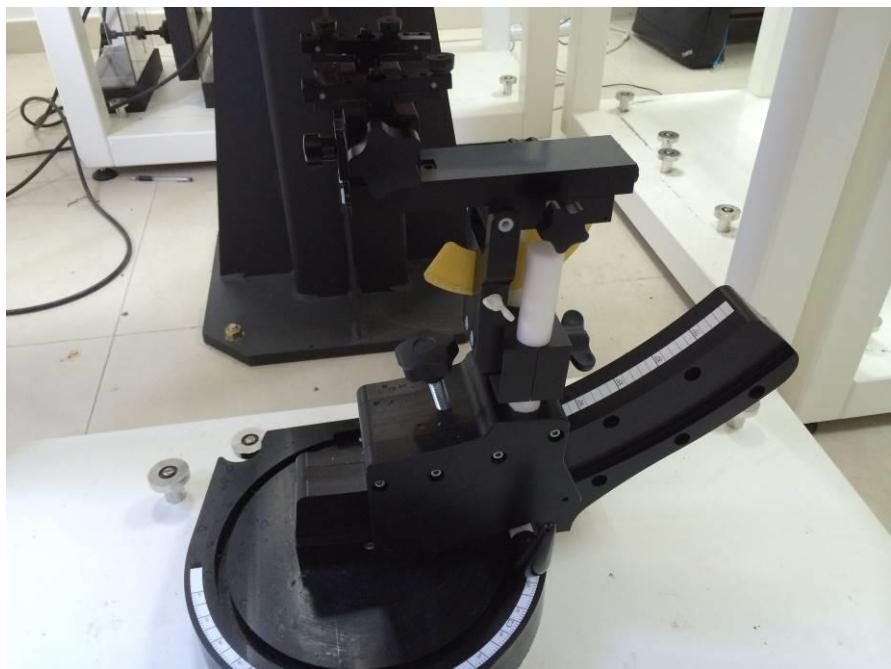
Phantom for compliance testing of handheld andbody-mounted wireless devices in the frequency range of 30 MHz to 6 GHz. ELI is fully compatible with the IEC 62209-2 standard and all known tissue simulating liquids. ELI has been optimized regarding its performance and can be integrated into our standard phantom tables. A cover prevents evaporation of the liquid. Reference markings on the phantom allow installation of the complete setup, including all predefined phantom positions and measurement grids, by teaching three points. The phantom is compatible with all SPEAG dosimetric probes and dipoles.



4.4. Device Holder

The device was placed in the device holder (illustrated below) that is supplied by SPEAG as an integral part of the DASY system.

The DASY device holder is designed to cope with the different positions given in the standard. It has two scales for device rotation (with respect to the body axis) and device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles.



Device holder supplied by SPEAG

4.5. Scanning Procedure

The DASY5 installation includes predefined files with recommended procedures for measurements and validation. They are read-only document files and destined as fully defined but unmeasured masks. All test positions (head or body-worn) are tested with the same configuration of test steps differing only in the grid definition for the different test positions.

The “reference” and “drift” measurements are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the DUT’s output power and should vary max. $\pm 5\%$.

The “surface check” measurement tests the optical surface detection system of the DASY5 system by repeatedly detecting the surface with the optical and mechanical surface detector and comparing the results. The output gives the detecting heights of both systems, the difference between the two systems and the standard deviation of the detection repeatability. Air bubbles or refraction in the liquid due to separation of the sugar-water mixture gives poor repeatability (above $\pm 0.1\text{mm}$). To prevent wrong results tests are only executed when the liquid is free of air bubbles. The difference between the optical surface detection and the actual surface depends on the probe and is specified with each probe (It does not depend on the surface reflectivity or the probe angle to the surface within $\pm 30^\circ$.)

Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values before running a detailed measurement around the hot spot. Before starting the area scan a grid spacing of 15 mm x 15 mm is set. During the scan the distance of the probe to the phantom remains unchanged. After finishing area scan, the field maxima within a range of 2 dB will be ascertained.

Zoom Scan

Zoom Scans are used to estimate the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The default Zoom Scan is done by 7x7x7 points within a cube whose base is centered around the maxima found in the preceding area scan.

Spatial Peak Detection

The procedure for spatial peak SAR evaluation has been implemented and can determine values of masses of 1g and 10g, as well as for user-specific masses. The DASY5 system allows evaluations that combine measured data and robot positions, such as:

- maximum search
- extrapolation
- boundary correction
- peak

search for averaged SAR During a maximum search, global and local maxima searches are automatically performed in 2-D after each Area Scan measurement with at least 6 measurement points. It is based on the evaluation of the local SAR gradient calculated by the Quadratic Shepard's method. The algorithm will find the global maximum and all local maxima within -2 dB of the global maxima for all SAR distributions.

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. Several measurements at different distances are necessary for the extrapolation. Extrapolation routines require at least 10 measurement points in 3-D space. They are used in the Zoom Scan to obtain SAR values between the lowest measurement points and the inner phantom surface. The routine uses the modified Quadratic Shepard's method for extrapolation. For a grid using 7x7x7 measurement points with 5mm resolution amounting to 343 measurement points, the uncertainty of the extrapolation routines is less than 1% for 1g and 10g cubes.

A Z-axis scan measures the total SAR value at the x-and y-position of the maximum SAR value found during the cube 7x7x7 scan. The probe is moved away in z-direction from the bottom of the SAM phantom in 5mm steps.

4.6. Data Storage and Evaluation

Data Storage

The DASY5 software stores the acquired data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension ".DA4". The software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of incorrect parameter settings. For example, if a measurement has been performed with a wrong crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be re-evaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type ([V/m], [A/m], [°C], [mW/g], [mW/cm²], [dBrel], etc.). Some of these units are not available in certain situations or show meaningless results, e.g., a SAR output in a lossless media will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

Data Evaluation

The SEMCAD software automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	Normi, ai0, ai1, ai2
	- Conversion factor	ConvFi
	- Diode compression point	Dcp1
Device parameters:	- Frequency	f
	- Crest factor	cf
Media parameters:	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY5 components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcpi}$$

With V_i = compensated signal of channel i ($i = x, y, z$)
 U_i = input signal of channel i ($i = x, y, z$)
 cf = crest factor of exciting field (DASY parameter)
 $dcpi$ = diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

$$E - \text{fieldprobes} : \quad E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

$$H - \text{fieldprobes} : \quad H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

With V_i = compensated signal of channel i ($i = x, y, z$)
 $Norm_i$ = sensor sensitivity of channel i ($i = x, y, z$)
 $[mV/(V/m)^2]$ for E-field Probes
 $ConvF$ = sensitivity enhancement in solution
 a_{ij} = sensor sensitivity factors for H-field probes
 f = carrier frequency [GHz]
 E_i = electric field strength of channel i in V/m
 H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1'000}$$

with SAR = local specific absorption rate in mW/g
 E_{tot} = total field strength in V/m
 σ = conductivity in [mho/m] or [Siemens/m]
 ρ = equivalent tissue density in g/cm³

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid.

4.7. SAR Measurement System

The SAR measurement system being used is the DASY5 system, the system is controlled remotely from a PC, which contains the software to control the robot and data acquisition equipment. The software also displays the data obtained from test scans.

In operation, the system first does an area (2D) scan at a fixed depth within the liquid from the inside wall of the phantom. When the maximum SAR point has been found, the system will then carry out a 3D scan centred at that point to determine volume averaged SAR level.

4.7.1 Tissue Dielectric Parameters for Head and Body Phantoms

The liquid is consisted of water, salt, Glycol, Sugar, Preventol and Cellulose. The liquid has previously been proven to be suited for worst-case. It's satisfying the latest tissue dielectric parameters requirements proposed by the KDB865664.

Target Frequency (MHz)	Head		Body	
	ϵ_r	σ (S/m)	ϵ_r	σ (S/m)
150	52.3	0.76	61.9	0.80
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	0.98	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800-2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73
5800	35.3	5.27	48.2	6.00

(ϵ_r = relative permittivity, σ = conductivity and $\rho = 1000 \text{ kg/m}^3$)

4.8. Tissue equivalent liquid properties

Dielectric performance of Head and Body tissue simulating liquid.

Ingredients (% by weight)	Frequency (MHz)					
	835		1800-2000		2300-2600	
Tissue Type	Head	Body	Head	Body	Head	Body
Water	40.30	50.75	55.24	70.17	55.00	68.53
Salt (NaCl)	1.38	0.94	0.31	0.39	0.2	0.1
Sucrose	57.90	48.21	0	0	0	0
HEC	0.24	0	0	0	0	0
Bactericide	0.18	0.10	0	0	0	0
Tween	0	0	44.45	29.44	44.80	31.37
Salt: 99+% Pure Sodium Chloride			Sucrose: 98+% Pure Sucrose			
Water: De-ionized, 16 MΩ ⁺ resistivity			HEC: Hydroxyethyl Cellulose			
Tween: Polyoxyethylene (20) sorbitan monolaurate						

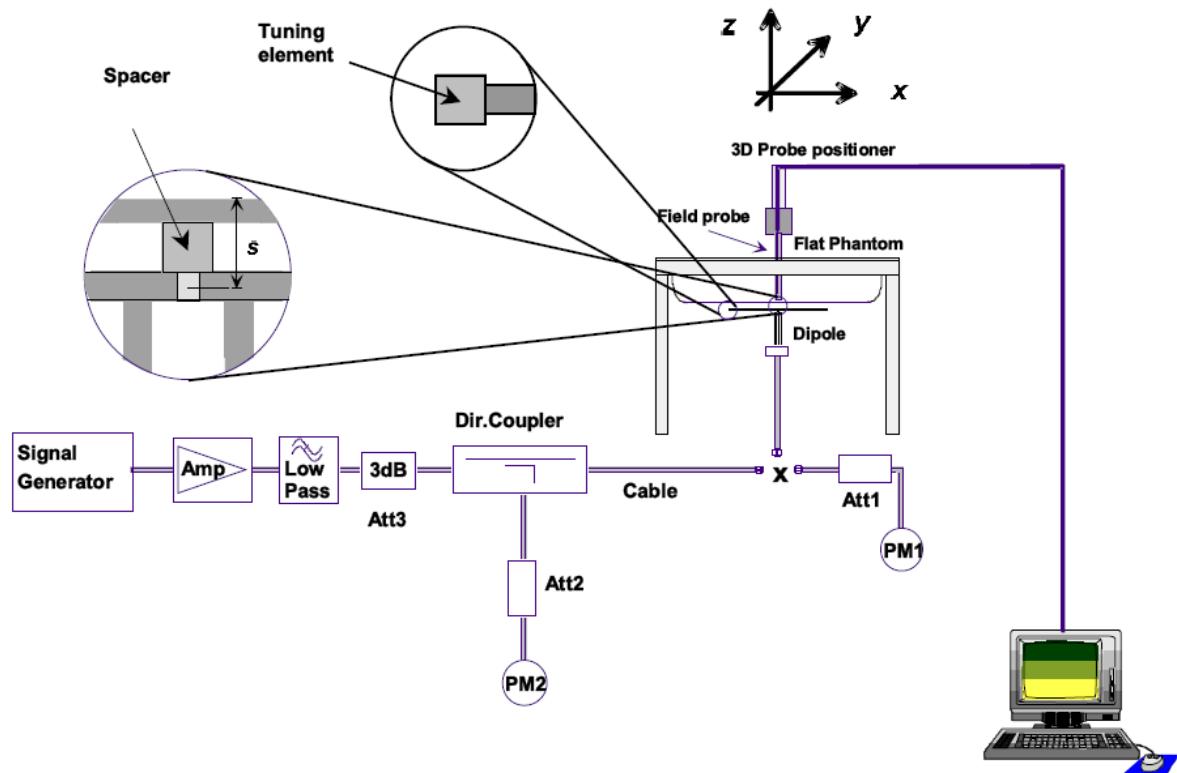
Tissue Type	Measured Frequency (MHz)	Target Tissue		Measured Tissue			Liquid Temp.	Test Data
		ε _r	σ	ε _r	Dev. %	σ		
2450B	2450	52.70	1.95	51.68	-1.94%	1.951	0.05%	22 degree 2017/12/5

4.9. System Check

The purpose of the system check is to verify that the system operates within its specifications at the device test frequency. The system check is simple check of repeatability to make sure that the system works correctly at the time of the compliance test;

System check results have to be equal or near the values determined during dipole calibration with the relevant liquids and test system (±10 %).

System check is performed regularly on all frequency bands where tests are performed with the DASY5 system.



The output power on dipole port must be calibrated to 24 dBm (250mW) before dipole is connected.

Justification for Extended SAR Dipole Calibrations

Referring to KDB 865664D01V01r04, if dipoles are verified in return loss (<-20dB, within 20% of prior calibration), and in impedance (within 5 ohm of prior calibration), the annual calibration is not necessary and the calibration interval can be extended. While calibration intervals not exceed 3 years.

Liquid Type	Target Value:		Measured Value:		verdict	Measured date
	Impedance	Return Loss	Impedance	Return Loss		
Head	52.9Ω+4.11jΩ	-26.3 dB	52.1Ω+4.21jΩ	-26.7 dB	Complied	2017/12/6
Body	49.7Ω+5.9jΩ	-24.6 dB	48.9Ω+5.3jΩ	-24.6 dB	Complied	2017/12/6

System Check in Body Tissue Simulating Liquid

Freq	Test Date	Dielectric Parameters		Temp	250mW Measured		1W Normalized		1W Target		Limit (±10% Deviation)	
		ε _r	σ(s/m)		SAR _{1g}	SAR _{10g}	SAR _{1g}	SAR _{10g}	SAR _{1g}	SAR _{10g}	SAR _{1g}	SAR _{10g}
2450MHz	2017/12/5	51.68	1.951	22	11.7	5.73	46.8	22.92	51	23.5	-8.24%	-2.47%

4.10. SAR measurement procedure

4.10.1 Tests to be performed

In order to determine the highest value of the peak spatial-average SAR of a handset, all device positions, configurations and operational modes shall be tested for each frequency band according to steps 1 to 3 below. A flowchart of the test process is shown in Picture 11.1.

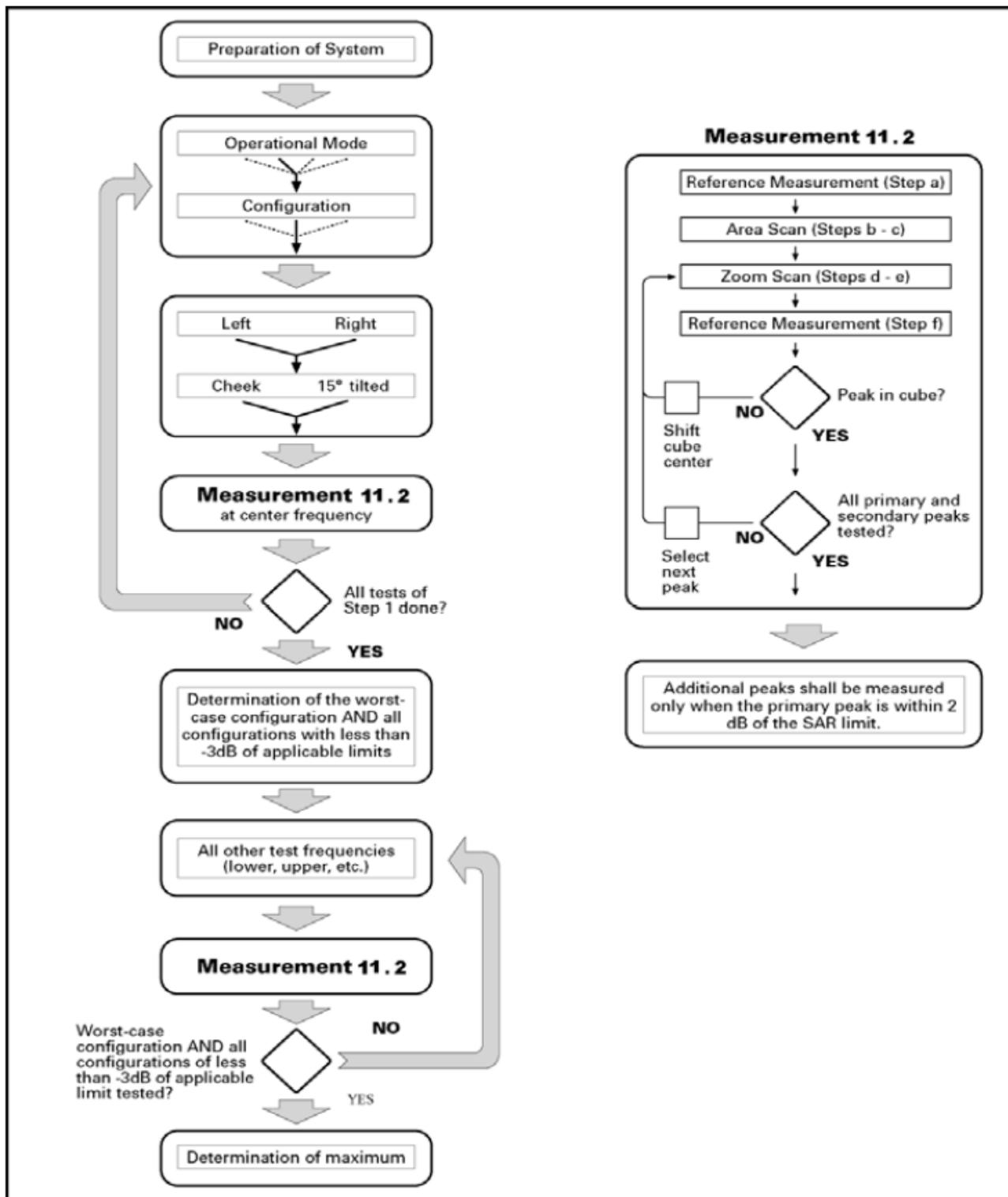
Step 1: The tests described in 11.2 shall be performed at the channel that is closest to the centre of the transmit frequency band (f_c) for:

- a). all device positions (cheek and tilt, for both left and right sides of the SAM phantom);
- b). all configurations for each device position in a), e.g., antenna extended and retracted, and
- c). all operational modes, e.g., analogue and digital, for each device position in a) and configuration in b) in each frequency band.

If more than three frequencies need to be tested according to 11.1 (i.e., $N_c > 3$), then all frequencies, configurations and modes shall be tested for all of the above test conditions.

Step 2: For the condition providing highest peak spatial-average SAR determined in Step 1, perform all tests described in 11.2 at all other test frequencies, i.e., lowest and highest frequencies. In addition, for all other conditions (device position, configuration and operational mode) where the peak spatial-average SAR value determined in Step 1 is within 3 dB of the applicable SAR limit, it is recommended that all other test frequencies shall be tested as well.

Step 3: Examine all data to determine the highest value of the peak spatial-average SAR found in Steps 1 to 2.



Picture 10.1 Block diagram of the tests to be performed

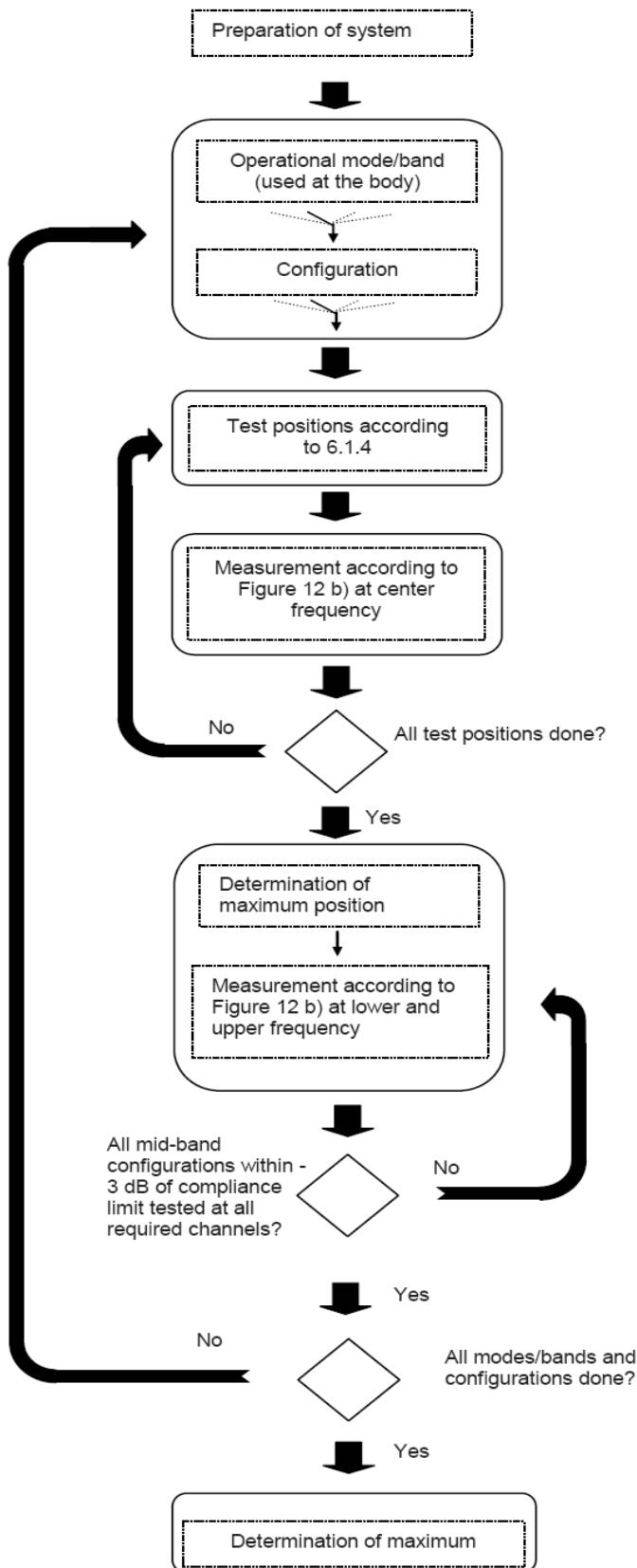


Figure 12a – Tests to be performed

Picture 12 Block diagram of the tests to be performed

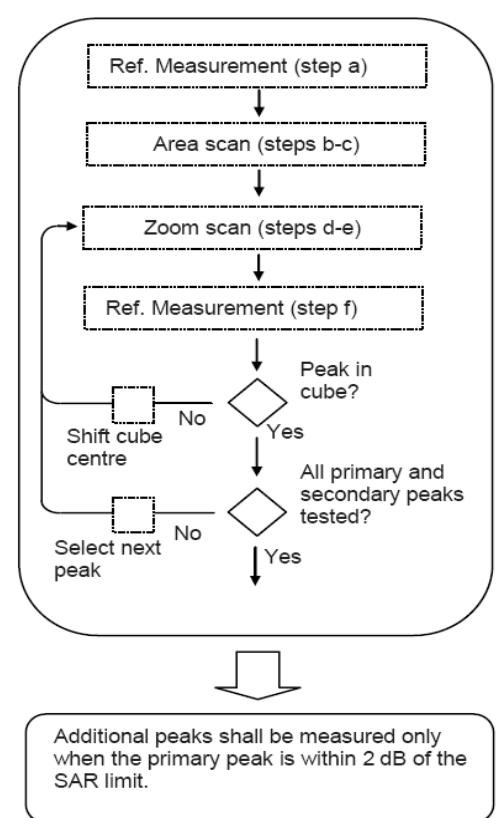


Figure 12b – General procedure

Measurement procedure

The following procedure shall be performed for each of the test conditions (see Picture 11) described in 11.1:

- a) Measure the local SAR at a test point within 8 mm or less in the normal direction from the inner surface of the phantom.
- b) Measure the two-dimensional SAR distribution within the phantom (area scan procedure). The boundary of the measurement area shall not be closer than 20 mm from the phantom side walls. The distance between the measurement points should enable the detection of the location of local maximum with an accuracy of better than half the linear dimension of the tissue cube after interpolation. A maximum grip spacing of 20 mm for frequencies below 3 GHz and $(60/f [GHz])$ mm for frequencies of 3GHz and greater is recommended. The maximum distance between the geometrical centre of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and $\delta\ln(2)/2$ mm for frequencies of 3 GHz and greater, where δ is the plane wave skin depth and $\ln(x)$ is the natural logarithm. The maximum variation of the sensor-phantom surface shall be ± 1 mm for frequencies below 3 GHz and ± 0.5 mm for frequencies of 3 GHz and greater. At all measurement points the angle of the probe with respect to the line normal to the surface should be less than 5°. If this cannot be achieved for a measurement distance to the phantom inner surface shorter than the probe diameter, additional measurement distance to the phantom inner surface shorter than the probe diameter, additional
- c) From the scanned SAR distribution, identify the position of the maximum SAR value, in addition identify the positions of any local maxima with SAR values within 2 dB of the maximum value that are not within the zoom-scan volume; additional peaks shall be measured only when the primary peak is within 2 dB of the SAR limit. This is consistent with the 2 dB threshold already stated;
- d) Measure the three-dimensional SAR distribution at the local maxima locations identified in step
- e) The horizontal grid step shall be $(24 / f[GHz])$ mm or less but not more than 8 mm. The minimum zoom size of 30 mm by 30 mm and 30 mm for frequencies below 3 GHz. For higher frequencies, the minimum zoom size of 22 mm by 22 mm and 22 mm. The grip step in the vertical direction shall be $(8-f[GHz])$ mm or less but not more than 5 mm, if uniform spacing is used. If variable spacing is used in the vertical direction, the maximum spacing between the two closest measured points to the phantom shell shall be $(12 / f[GHz])$ mm or less but not more than 4 mm, and the spacing between father points shall increase by an incremental factor not exceeding 1.5. When variable spacing is used, extrapolation routines shall be tested with the same spacing as used in measurements. The maximum distance between the geometrical centre of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and $\delta\ln(2)/2$ mm for frequencies of 3 GHz and greater, where δ is the plane wave skin depth and $\ln(x)$ is the natural logarithm. Separate grids shall be centered on each of the local SAR maxima found in step c). Uncertainties due to field distortion between the media boundary and the dielectric enclosure of the probe should also be minimized, which is achieved is the distance between the phantom surface and physical tip of the probe is larger than probe tip diameter. Other methods may utilize correction procedures for these boundary effects that enable high precision measurements closer than half the probe diameter. For all measurement points, the angle of the probe with respect to the flat phantom surface shall be less than 5°. If this cannot be achieved an additional uncertainty evaluation is needed.
- f) Use post processing(e.g. interpolation and extrapolation) procedures to determine the local SAR values at the spatial resolution needed for mass averaging.

Measurement procedure

The following procedure shall be performed for each of the test conditions (see Picture 11) described in 11.1:

- g) Measure the local SAR at a test point within 8 mm or less in the normal direction from the inner surface of the phantom.
- h) Measure the two-dimensional SAR distribution within the phantom (area scan procedure). The boundary of the measurement area shall not be closer than 20 mm from the phantom side walls. The distance between the measurement points should enable the detection of the location of local maximum with an accuracy of better than half the linear dimension of the tissue cube after interpolation. A maximum grip spacing of 20 mm for frequencies below 3 GHz and $(60/f [GHz])$ mm for frequencies of 3GHz and greater is recommended. The maximum distance between the geometrical centre of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and $\delta\ln(2)/2$ mm for frequencies of 3 GHz and greater, where δ is the plane wave skin depth and $\ln(x)$ is the natural logarithm. The maximum variation of the sensor-phantom surface shall be ± 1 mm for frequencies below 3 GHz and ± 0.5 mm for frequencies of 3 GHz and greater. At all measurement points the angle of the probe with respect to the line normal to the surface should be less than 5°. If this cannot be achieved for a measurement distance to the phantom inner surface shorter than the probe diameter, additional measurement distance to the phantom inner surface shorter than the probe diameter, additional

- i) From the scanned SAR distribution, identify the position of the maximum SAR value, in addition identify the positions of any local maxima with SAR values within 2 dB of the maximum value that are not within the zoom-scan volume; additional peaks shall be measured only when the primary peak is within 2 dB of the SAR limit. This is consistent with the 2 dB threshold already stated;
- j) Measure the three-dimensional SAR distribution at the local maxima locations identified in step
- k) The horizontal grid step shall be $(24 / f[\text{GHz}])$ mm or less but not more than 8 mm. The minimum zoom size of 30 mm by 30 mm and 30 mm for frequencies below 3 GHz. For higher frequencies, the minimum zoom size of 22 mm by 22 mm and 22 mm. The grip step in the vertical direction shall be $(8-f[\text{GHz}])$ mm or less but not more than 5 mm, if uniform spacing is used. If variable spacing is used in the vertical direction, the maximum spacing between the two closest measured points to the phantom shell shall be $(12 / f[\text{GHz}])$ mm or less but not more than 4 mm, and the spacing between father points shall increase by an incremental factor not exceeding 1.5. When variable spacing is used, extrapolation routines shall be tested with the same spacing as used in measurements. The maximum distance between the geometrical centre of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and $\delta \ln(2)/2$ mm for frequencies of 3 GHz and greater, where δ is the plane wave skin depth and $\ln(x)$ is the natural logarithm. Separate grids shall be centered on each of the local SAR maxima found in step c). Uncertainties due to field distortion between the media boundary and the dielectric enclosure of the probe should also be minimized, which is achieved is the distance between the phantom surface and physical tip of the probe is larger than probe tip diameter. Other methods may utilize correction procedures for these boundary effects that enable high precision measurements closer than half the probe diameter. For all measurement points, the angle of the probe with respect to the flat phantom surface shall be less than 5. If this cannot be achieved an additional uncertainty evaluation is needed.
- l) Use post processing(e.g. interpolation and extrapolation) procedures to determine the local SAR values at the spatial resolution needed for mass averaging.

4.10.2 General Measurement Procedure

The area and zoom scan resolutions specified in the table below must be applied to the SAR measurements and fully documented in SAR reports to qualify for TCB approval. Probe boundary effect error compensation is required for measurements with the probe tip closer than half a probe tip diameter to the phantom surface. Both the probe tip diameter and sensor offset distance must satisfy measurement protocols; to ensure probe boundary effect errors are minimized and the higher fields closest to the phantom surface can be correctly measured and extrapolated to the phantom surface for computing 1-g SAR. Tolerances of the post-processing algorithms must be verified by the test laboratory for the scan resolutions used in the SAR measurements, according to the reference distribution functions specified in IEEE Std 1528-2003. The results should be documented as part of the system validation records and may be requested to support test results when all the measurement parameters in the following table are not satisfied.

		≤ 3 GHz	> 3 GHz
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface		5 ± 1 mm	$\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5$ mm
Maximum probe angle from probe axis to phantom surface normal at the measurement location		$30^\circ \pm 1^\circ$	$20^\circ \pm 1^\circ$
		≤ 2 GHz: ≤ 15 mm $2 - 3$ GHz: ≤ 12 mm	$3 - 4$ GHz: ≤ 12 mm $4 - 6$ GHz: ≤ 10 mm
Maximum area scan spatial resolution: $\Delta x_{\text{Area}}, \Delta y_{\text{Area}}$			When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be \leq the corresponding x or y dimension of the test device with at least one measurement point on the test device.
Maximum zoom scan spatial resolution: $\Delta x_{\text{Zoom}}, \Delta y_{\text{Zoom}}$		≤ 2 GHz: ≤ 8 mm $2 - 3$ GHz: ≤ 5 mm*	$3 - 4$ GHz: ≤ 5 mm* $4 - 6$ GHz: ≤ 4 mm*
Maximum zoom scan spatial resolution, normal to phantom surface	uniform grid: $\Delta z_{\text{Zoom}}(n)$	≤ 5 mm	$3 - 4$ GHz: ≤ 4 mm $4 - 5$ GHz: ≤ 3 mm $5 - 6$ GHz: ≤ 2 mm
	graded grid	$\Delta z_{\text{Zoom}}(1):$ between 1 st two points closest to phantom surface $\Delta z_{\text{Zoom}}(n>1):$ between subsequent points	≤ 4 mm $\leq 1.5 \cdot \Delta z_{\text{Zoom}}(n-1)$
Minimum zoom scan volume	x, y, z	≥ 30 mm	$3 - 4$ GHz: ≥ 28 mm $4 - 5$ GHz: ≥ 25 mm $5 - 6$ GHz: ≥ 22 mm
Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.			
* When zoom scan is required and the <u>reported</u> SAR from the area scan based 1-g SAR estimation procedures of KDB 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.			

4.10.3 Power Drift

To control the output power stability during the SAR test, DASY5 system calculates the power drift by measuring the E-field at the same location at the beginning and at the end of the measurement for each test position. These drift values can be found in Table 14.1 to Table 14.11 labeled as: (Power Drift [dB]). This ensures that the power drift during one measurement is within 5%.

5. TEST CONDITIONS AND RESULTS

5.1. Conducted Power Results

According KDB 447498 D01 General RF Exposure Guidance v06 Section 4.1 2) states that “Unless it is specified differently in the published RF exposure KDB procedures, these requirements also apply to test reduction and test exclusion considerations. Time-averaged maximum conducted output power applies to SAR and, as required by § 2.1091(c), time-averaged ERP applies to MPE.

5.1.1 Output Power Results Of WiFi

Mode	Channel	Frequency (MHz)	Tune-up	Average Power (dBm)
802.11b	1	2412	16.00	15.47
	6	2437	16.00	15.83
	11	2462	16.00	15.42
802.11g	1	2412	13.00	10.20
	6	2437	13.00	12.72
	11	2462	13.00	11.79
802.11n (HT20)	1	2412	13.00	10.06
	6	2437	13.00	12.53
	11	2462	13.00	11.29
802.11n (HT40)	3	2422	11.00	10.05
	6	2437	11.00	10.17
	9	2452	11.00	10.58

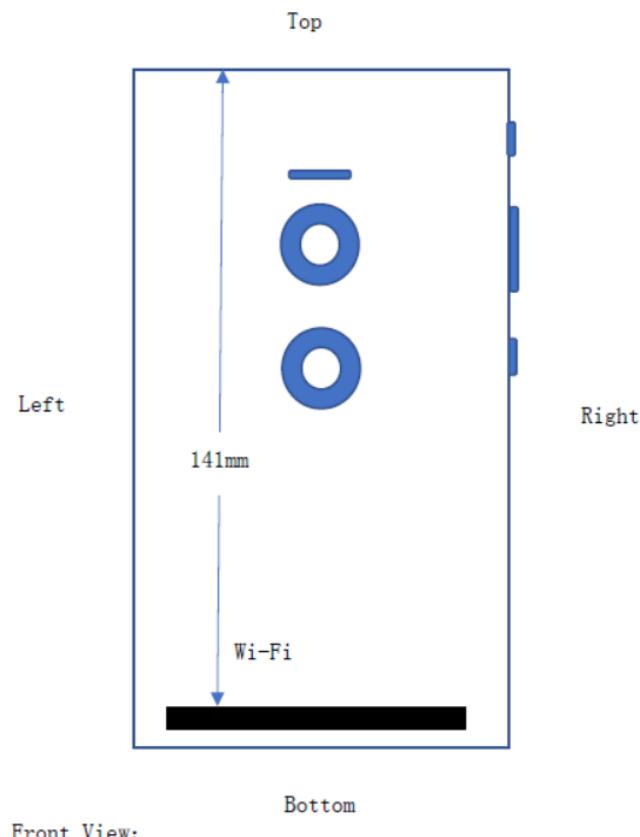
5.5.2 Output Power Results Of BT

The output power of BT is as following:

BT(3.0)	Peak Output Power (dBm)				
	Channel	Tune-up	Data Rates		
			1M	2M	3M
	0CH	6.00	5.90	4.89	4.98
	39CH	7.00	6.36	5.44	5.54
	78CH	5.00	4.45	3.19	4.98

BT(4.0)	Channel	Tune-up	Peak Output Power (dBm)
	0CH	0	-1.46
	19CH	1.00	-0.22
	39CH	-1.00	-2.87

5.2. Antenna Location



Distance of the Antenna to the EUT surface/edge						
Antennas	Front Side	Back Side	Left Side	Right Side	Top Side	Bottom Side
WLAN & BT	≤ 50mm	≤ 50mm	≤ 50mm	≤ 50mm	>50mm	≤ 50mm

5.3. SAR Measurement Results

5.3.1 BT SAR test Reduction

Per FCC KDB 447498D01, the 1-g SAR and 10-g SAR test exclusion thresholds for 100 MHz to 6 GHz at test separation distances \leq 50 mm are determined by:

$[(\text{max. power of channel, including tune-up tolerance, mW}) / (\text{min. test separation distance, mm})] \cdot [\sqrt{f_{(\text{GHz})}}] \leq 3.0$ for 1-g SAR and ≤ 7.5 for 10-g extremity SAR, where:

- $f_{(\text{GHz})}$ is the RF channel transmit frequency in GHz
- Power and distance are rounded to the nearest mW and mm before calculation
- The result is rounded to one decimal place for comparison

When the minimum test separation distance is $<$ 5 mm, a distance of 5 mm is applied to determine SAR test exclusion.

Mode	P_{max} (dBm)	P_{max} (mW)	Distance (mm)	f (GHz)	Calculation Result	SAR Exclusion threshold	SAR test exclusion
BT	7	5.01	5	2.480	1.58	3.0	Yes

NOTE: Standalone SAR test exclusion for BT

5.3.2 Wi-Fi Head SAR test Reduction

(1) The SAR exclusion threshold for distances $<$ 50mm is defined by the following equation:

$$\frac{(\text{max. power of channel, including tune-up tolerance, mW})}{(\text{min. test separation distance, mm})} \cdot \sqrt{f_{(\text{GHz})}} \leq 3.0$$

(2) The SAR exclusion threshold for distances $>$ 50mm is defined by the following equation, as illustrated in KDB 447498 D01 Appendix B:

a) at 100 MHz to 1500 MHz

[Power allowed at numeric threshold for 50 mm in step 1) + (test separation distance - 50 mm) · (f(MHz)/150)] mW

b) at $>$ 1500 MHz and \leq 6 GHz

[Power allowed at numeric Threshold at 50 mm in step 1) + (test separation distance - 50 mm) · 10] mW

For the head SAR, Head SAR is measured with the Top side of the radio positioned at 2.5 cm parallel to a flat phantom

The Top edge of the EUT towards the bottom of the flat phantom.

The threshold: $96 + (166-50) \cdot 10 = 1256 \text{ mW} = 31.0 \text{ dBm} > 16 \text{ dBm}$

So SAR is not required for head SAR

Head SAR Test Considerations Note:

1. **In the top side of the device, there is a microphone, the language will from here to translate, so it used as a "in front of face" device.** Passive body-worn and audio accessories generally do not apply to the head SAR of radios. Head SAR is measured with the Top side of the radio positioned at 2.5 cm parallel to a flat phantom. A phantom shell thickness of 2 mm is required. When the Top side of the radio has a contour or non-uniform surface with a variation of 1.0 cm or more, the average distance of such variations is used to establish the 2.5 cm test separation from the phantom.

5.3.3 Wi-Fi Body SAR test

EUT Sides for SAR Testing						
Mode	Front	Back	Left	Right	Top	Bottom
Wi-Fi (2.4GHz)	Yes	Yes	Yes	Yes	No	Yes

Position	Test Frequency		Mode	P_cond_high (W)	Carry Access.	Audio Access.	Belt Clip Distance (mm)	SAR_meas. (mW/g)	Power Drift (dB)
	Channel	MHz							
Front	6	2437	802.11b	0.0398	A1, B1	n/a	0	0.513	-0.13
Back	6	2437	802.11b	0.0398	A1, B1	n/a	0	0.561	-0.15
Left	6	2437	802.11b	0.0398	A1, B1	n/a	0	0.476	-0.11
Right	6	2437	802.11b	0.0398	A1, B1	n/a	0	0.213	0.12
Bottom	6	2437	802.11b	0.0398	A1, B1	n/a	0	0.891	-0.17
Bottom	1	2412	802.11b	0.0352	A1, B1	n/a	0	0.813	-0.11
Bottom	11	2462	802.11b	0.0348	A1, B1	n/a	0	0.807	-0.13

Body SAR Test Considerations Note:

1. Body SAR is measured positioned against a flat phantom, representative of the normal operating conditions expected by users and typically with a standard default audio accessory supplied with the radio. Since audio accessories, including any default audio accessories supplied with a radio, may be designed to operate with a subset of the combinations of antennas, batteries and body-worn accessories, when a default audio accessory does not fully support all the test configurations required in this section for body-worn accessories testing an alternative audio accessory must be selected to be the default audio accessory for body-worn accessories testing. If an alternative audio accessory cannot be identified, body-worn accessories should be tested without any audio accessory. In general, all sides of the radio that may be positioned facing the user when using a body-worn accessory must be considered for SAR compliance.
2. Testing of other required channels within the operating mode of a frequency band is not required when the reported 1-g or 10-g SAR for the mid-band or highest output power channel is:
 - a. $\leq 0.8 \text{ W/kg}$ or 2.0 W/kg , for 1-g or 10-g respectively, when the transmission band is $\leq 100 \text{ MHz}$
 - b. $\leq 0.6 \text{ W/kg}$ or 1.5 W/kg , for 1-g or 10-g respectively, when the transmission band is between 100 MHz and 200 MHz
 - c. $\leq 0.4 \text{ W/kg}$ or 1.0 W/kg , for 1-g or 10-g respectively, when the transmission band is $\geq 200 \text{ MHz}$
3. Measured SAR based on 100% duty cycle
4. (1) The SAR exclusion threshold for distances $<50\text{mm}$ is defined by the following equation:

$$\frac{(\text{max. power of channel, including tune-up tolerance, mW}) * \sqrt{\text{Frequency (GHz)}}}{(\text{min. test separation distance, mm})} \leq 3.0$$

(2) The SAR exclusion threshold for distances $>50\text{mm}$ is defined by the following equation, as illustrated in KDB 447498 D01 Appendix B:

a) at 100 MHz to 1500 MHz

$$[\text{Power allowed at numeric threshold for } 50 \text{ mm in step 1} + (\text{test separation distance} - 50 \text{ mm}) \cdot (f(\text{MHz})/150)] \text{ mW}$$

b) at $> 1500 \text{ MHz}$ and $\leq 6 \text{ GHz}$

$$[\text{Power allowed at numeric Threshold at } 50 \text{ mm in step 1} + (\text{test separation distance} - 50 \text{ mm}) \cdot 10] \text{ mW}$$

For the Body SAR, SAR is measured with the Top side of the radio positioned at 0 cm parallel to a flat phantom. Then for the top edge of the EUT towards the bottom of the flat phantom.
The threshold: $96 + (141-50) * 10 \text{ mW} = 30.03 \text{ dBm} > 16 \text{ dBm}$.

5.4. SAR Reporting Results

These are not actual measurement SAR values, measurement SAR values taken from Section 5.3 SAR Measurement Results; we also take Section 5.2 formula to calculate maximum report SAR in 100% duty cycle.

$$\text{Max_Calc} = \text{SAR_Adju} * \text{DC} * (\text{P_max} / \text{P_cond})$$

P_max = highest power including turn up tolerance (W)

P_cond_high = highest power in conduct measured (W)

DC = Transmission mode Duty Cycle in %

SAR_adju = Adjust 1-g and 10-g Average SAR from measured SAR (W/kg)

5.4.2 802.11b body SAR test

Position	Test Frequency		Mode	P_cond_high (W)	P_max	Carry Access.	Audio Access.	Belt Clip Distance (mm)	SAR_mea. (mW/g)	Power Drift (dB)	Scaling Factor	Max Calc. SAR _{1-g} (mW/g)	Plot
	Ch.	MHz											
Front	6	2437	802.11b	0.0383	0.0398	A1, B1, n/a	n/a	0	0.513	-0.13	1.039	0.533	
Back	6	2437	802.11b	0.0383	0.0398			0	0.561	-0.15	1.039	0.583	
Left	6	2437	802.11b	0.0383	0.0398			0	0.476	-0.11	1.039	0.495	
Right	6	2437	802.11b	0.0383	0.0398			0	0.213	0.12	1.039	0.221	
Bottom	6	2437	802.11b	0.0383	0.0398			0	0.891	-0.17	1.039	0.926	1
Bottom	1	2412	802.11b	0.0352	0.0398			0	0.813	-0.11	1.129	0.918	
Bottom	11	2462	802.12b	0.0348	0.0398			0	0.807	-0.13	1.143	0.922	
Bottom-repeat	6	2437	802.12b	0.0383	0.0398			0	0.871	-0.13	1.039	0.905	

Note:

1. 2.4 GHz 802.11g/n OFDM SAR Test Exclusion Requirements, SAR is not required for the following 2.4 GHz OFDM conditions.

a) When KDB Publication 447498 D01 SAR test exclusion applies to the OFDM configuration.

b) When the highest *reported* SAR for DSSS is adjusted by the ratio of OFDM to DSSS specified maximum output power and the adjusted SAR is ≤ 1.2 W/kg.

Test Mode	Tune up(dBm)	Reported SAR (W/kg)	Adjusted SAR (W/kg)	SAR required (Y/N)
802.11b	16	0.926	/	/
802.11g	14	/	0.584	N
802.11n20	14	/	0.584	N
802.11n40	12	/	0.369	N

5.5. SAR Measurement Variability

SAR measurement variability must be assessed for each frequency band, which is determined by the SAR probe calibration point and tissue-equivalent medium used for the device measurements. When both head and body tissue-equivalent media are required for SAR measurements in a frequency band, the variability measurement procedures should be applied to the tissue medium with the highest measured SAR, using the highest measured SAR configuration for that tissue-equivalent medium. The following procedures are applied to determine if repeated measurements are required.

- 1) Repeated measurement is not required when the original highest measured SAR is < 0.80 W/kg; steps 2) through 4) do not apply.
- 2) When the original highest measured SAR is ≥ 0.80 W/kg, repeat that measurement once.
- 3) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 1.45 W/kg (~ 10% from the 1-g SAR limit).
- 4) Perform a third repeated measurement only if the original, first or second repeated measurement is ≥ 1.5 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20 .

The same procedures should be adapted for measurements according to extremity and occupational exposure limits by applying a factor of 2.5 for extremity exposure and a factor of 5 for occupational exposure to the corresponding SAR thresholds.

Thus the following procedures are applied to determine if repeated measurements are required for occupational exposure.

- 1) Repeated measurement is not required when the original highest measured SAR is < 4.00 W/kg; steps 6) through 8) do not apply.
- 2) When the original highest measured SAR is ≥ 4.00 W/kg, repeat that measurement once.
- 3) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 6.00 or when the original or repeated measurement is ≥ 7.25 W/kg (~ 10% from the 1-g SAR limit).
- 4) Perform a third repeated measurement only if the original, first or second repeated measurement is ≥ 7.5 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20 .

Test Position	Channel/ Frequency (MHz)	Measured SAR (1g)	1 st Repeated	Ratio	2 nd Repeated	3 rd Repeated SAR (1g)
			SAR (1g)		SAR (1g)	
Bottom Side	6/2437	0.891	0.871	1.02	N/A	N/A
Note: 1) When the original highest measured SAR is ≥ 0.80 W/kg, the measurement was repeated once.						
2) A second repeated measurement was preformed only if the ratio of largest to smallest SAR for the original and first repeated measurements was > 1.20 or when the original or repeated measurement was ≥ 1.45 W/kg (~ 10% from the 1-g SAR limit).						
3) A third repeated measurement was performed only if the original, first or second repeated measurement was ≥ 1.5 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20 .						
4) Repeated measurements are not required when the original highest measured SAR is < 0.80 W/kg						

5.6. Measurement Uncertainty(300MHz-3GHz)

According to IEC62209-1/IEEE 1528:2013										
No.	Error Description	Type	Uncertainty Value	Probably Distribution	Div.	(Ci) 1g	(Ci) 10g	Std. Unc. (1g)	Std. Unc. (10g)	Degree of freedom
Measurement System										
1	Probe calibration	B	5.50%	N	1	1	1	5.50%	5.50%	∞
2	Axial isotropy	B	4.70%	R	$\sqrt{3}$	0.7	0.7	1.90%	1.90%	∞
3	Hemispherical isotropy	B	9.60%	R	$\sqrt{3}$	0.7	0.7	3.90%	3.90%	∞
4	Boundary Effects	B	1.00%	R	$\sqrt{3}$	1	1	0.60%	0.60%	∞
5	Probe Linearity	B	4.70%	R	$\sqrt{3}$	1	1	2.70%	2.70%	∞
6	Detection limit	B	1.00%	R	$\sqrt{3}$	1	1	0.60%	0.60%	∞
7	RF ambient conditions-noise	B	0.00%	R	$\sqrt{3}$	1	1	0.00%	0.00%	∞
8	RF ambient conditions-reflection	B	0.00%	R	$\sqrt{3}$	1	1	0.00%	0.00%	∞
9	Response time	B	0.80%	R	$\sqrt{3}$	1	1	0.50%	0.50%	∞
10	Integration time	B	5.00%	R	$\sqrt{3}$	1	1	2.90%	2.90%	∞
11	RF ambient	B	3.00%	R	$\sqrt{3}$	1	1	1.70%	1.70%	∞
12	Probe positioned mech. restrictions	B	0.40%	R	$\sqrt{3}$	1	1	0.20%	0.20%	∞
13	Probe positioning with respect to phantom shell	B	2.90%	R	$\sqrt{3}$	1	1	1.70%	1.70%	∞
14	Max.SAR evalation	B	3.90%	R	$\sqrt{3}$	1	1	2.30%	2.30%	∞
Test Sample Related										
15	Test sample positioning	A	1.86%	N	1	1	1	1.86%	1.86%	∞
16	Device holder uncertainty	A	1.70%	N	1	1	1	1.70%	1.70%	∞
17	Drift of output power	B	5.00%	R	$\sqrt{3}$	1	1	2.90%	2.90%	∞
Phantom and Set-up										
18	Phantom uncertainty	B	4.00%	R	$\sqrt{3}$	1	1	2.30%	2.30%	∞
19	Liquid conductivity (target)	B	5.00%	R	$\sqrt{3}$	0.64	0.43	1.80%	1.20%	∞
20	Liquid conductivity (meas.)	A	0.50%	N	1	0.64	0.43	0.32%	0.26%	∞

21	Liquid permittivity (target)	B	5.00%	R	$\sqrt{3}$	0.64	0.43	1.80%	1.20%	∞
22	Liquid permittivity (meas.)	A	0.16%	N	1	0.64	0.43	0.10%	0.07%	∞
Combined standard uncertainty	$u_c = \sqrt{\sum_{i=1}^{22} c_i^2 u_i^2}$		/	/	/	/	/	10.20%	10.00%	∞
Expanded uncertainty (confidence interval of 95 %)	$u_e = 2u_c$		/	R	K=2	/	/	20.40%	20.00%	∞

According to IEC62209-2/2010										
No.	Error Description	Type	Uncertainty Value	Probably Distribution	Div.	(Ci) 1g	(Ci) 10g	Std. Unc. (1g)	Std. Unc. (10g)	Degree of freedom
Measurement System										
1	Probe calibration	B	6.20%	N	1	1	1	6.20%	6.20%	∞
2	Axial isotropy	B	4.70%	R	$\sqrt{3}$	0.7	0.7	1.90%	1.90%	∞
3	Hemispherical isotropy	B	9.60%	R	$\sqrt{3}$	0.7	0.7	3.90%	3.90%	∞
4	Boundary Effects	B	2.00%	R	$\sqrt{3}$	1	1	1.20%	1.20%	∞
5	Probe Linearity	B	4.70%	R	$\sqrt{3}$	1	1	2.70%	2.70%	∞
6	Detection limit	B	1.00%	R	$\sqrt{3}$	1	1	0.60%	0.60%	∞
7	RF ambient conditions-noise	B	0.00%	R	$\sqrt{3}$	1	1	0.00%	0.00%	∞
8	RF ambient conditions-reflection	B	0.00%	R	$\sqrt{3}$	1	1	0.00%	0.00%	∞
9	Response time	B	0.80%	R	$\sqrt{3}$	1	1	0.50%	0.50%	∞
10	Integration time	B	5.00%	R	$\sqrt{3}$	1	1	2.90%	2.90%	∞
11	RF Ambient	B	3.00%	R	$\sqrt{3}$	1	1	1.70%	1.70%	∞
12	Probe positioned mech. restrictions	B	0.80%	R	$\sqrt{3}$	1	1	0.50%	0.50%	∞
13	Probe positioning with respect to phantom shell	B	6.70%	R	$\sqrt{3}$	1	1	3.90%	3.90%	∞
14	Max.SAR Evaluation	B	3.90%	R	$\sqrt{3}$	1	1	2.30%	2.30%	∞
15	Modulation Response	B	2.40%	R	$\sqrt{3}$	1	1	1.40%	1.40%	∞
Test Sample Related										

16	Test sample positioning	A	1.86%	N	1	1	1	1.86%	1.86%	∞
17	Device holder uncertainty	A	1.70%	N	1	1	1	1.70%	1.70%	∞
18	Drift of output power	B	5.00%	R	$\sqrt{3}$	1	1	2.90%	2.90%	∞
Phantom and Set-up										
19	Phantom uncertainty	B	6.10%	R	$\sqrt{3}$	1	1	3.50%	3.50%	∞
20	SAR correction	B	1.90%	R	$\sqrt{3}$	1	0.84	1.11%	0.90%	∞
21	Liquid conductivity (target)	B	5.00%	R	$\sqrt{3}$	0.64	0.43	1.80%	1.20%	∞
22	Liquid conductivity (meas.)	A	0.50%	N	1	0.64	0.43	0.32%	0.26%	∞
23	Liquid permittivity (target)	B	5.00%	R	$\sqrt{3}$	0.64	0.43	1.80%	1.20%	∞
24	Liquid cpermittivity (meas.)	A	0.16%	N	1	0.64	0.43	0.10%	0.07%	∞
25	Temp.Unc.-Conductivity	B	3.40%	R	$\sqrt{3}$	0.78	0.71	1.50%	1.40%	∞
26	Temp.Unc.-Permittivity	B	0.40%	R	$\sqrt{3}$	0.23	0.26	0.10%	0.10%	∞
Combined standard uncertainty	$u_c = \sqrt{\sum_{i=1}^{22} c_i^2 u_i^2}$	/	/	/	/	/	12.90%	12.70%	∞	
Expanded uncertainty (confidence interval of 95 %)	$u_e = 2u_c$	/	R	K=2	/	/	25.80%	25.40%	∞	

Uncertainty of a System Performance Check with DASY5 System										
According to IEC62209-2/2010										
No.	Error Description	Type	Uncertainty Value	Probably Distribution	Div.	(Ci) 1g	(Ci) 10g	Std. Unc. (1g)	Std. Unc. (10g)	Degree of freedom
Measurement System										
1	Probe calibration	B	6.00%	N	1	1	1	6.00%	6.00%	∞
2	Axial isotropy	B	4.70%	R	$\sqrt{3}$	0.7	0.7	1.90%	1.90%	∞
3	Hemispherical isotropy	B	0.00%	R	$\sqrt{3}$	0.7	0.7	0.00%	0.00%	∞
4	Boundary Effects	B	1.00%	R	$\sqrt{3}$	1	1	0.60%	0.60%	∞
5	Probe Linearity	B	4.70%	R	$\sqrt{3}$	1	1	2.70%	2.70%	∞
6	Detection limit	B	1.00%	R	$\sqrt{3}$	1	1	0.60%	0.60%	∞
7	RF ambient conditions-noise	B	0.00%	R	$\sqrt{3}$	1	1	0.00%	0.00%	∞

8	RF ambient conditions-reflection	B	0.00%	R	$\sqrt{3}$	1	1	0.00%	0.00%	∞
9	Response time	B	0.80%	R	$\sqrt{3}$	1	1	0.50%	0.50%	∞
10	Integration time	B	5.00%	R	$\sqrt{3}$	1	1	2.90%	2.90%	∞
11	RF Ambient	B	3.00%	R	$\sqrt{3}$	1	1	1.70%	1.70%	∞
12	Probe positioned mech. restrictions	B	0.80%	R	$\sqrt{3}$	1	1	0.50%	0.50%	∞
13	Probe positioning with respect to phantom shell	B	6.70%	R	$\sqrt{3}$	1	1	3.90%	3.90%	∞
14	Max.SAR Evalation	B	3.90%	R	$\sqrt{3}$	1	1	2.30%	2.30%	∞
15	Modulation Response	B	2.40%	R	$\sqrt{3}$	1	1	1.40%	1.40%	∞
Test Sample Related										
16	Test sample positioning	A	0.00%	N	1	1	1	0.00%	0.00%	∞
17	Device holder uncertainty	A	2.00%	N	1	1	1	2.00%	2.00%	∞
18	Drift of output power	B	3.40%	R	$\sqrt{3}$	1	1	2.00%	2.00%	∞
Phantom and Set-up										
19	Phantom uncertainty	B	4.00%	R	$\sqrt{3}$	1	1	2.30%	2.30%	∞
20	SAR correction	B	1.90%	R	$\sqrt{3}$	1	0.84	1.11%	0.90%	∞
21	Liquid conductivity (meas.)	A	0.50%	N	1	0.64	0.43	0.32%	0.26%	∞
22	Liquid cpermittivity (meas.)	A	0.16%	N	1	0.64	0.43	0.10%	0.07%	∞
23	Temp.Unc.-Conductivity	B	1.70%	R	$\sqrt{3}$	0.78	0.71	0.80%	0.80%	∞
24	Temp.Unc.-Permittivity	B	0.40%	R	$\sqrt{3}$	0.23	0.26	0.10%	0.10%	∞
Combined standard uncertainty	$u_c = \sqrt{\sum_{i=1}^{22} c_i^2 u_i^2}$		/	/	/	/	/	12.90%	12.70%	∞
Expanded uncertainty (confidence interval of 95 %)	$u_e = 2u_c$		/	R	K=2	/	/	18.80%	18.40%	∞

5.7. System Check Results

System Performance Check at 2450 MHz Body TSL

DUT: Dipole2450 MHz; Type: D2450V2; Serial: 733

Date/Time: 12/05/2017 08:45:16 AM

Communication System: DuiJiangJi; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium parameters used (interpolated): $f = 2450$ MHz; $\sigma = 1.951$ S/m; $\epsilon_r = 51.68$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

DASY5 Configuration:

Probe: EX3DV4 - SN3789; ConvF(6.98, 6.98, 6.98); Calibrated: 1/13/2017;

Sensor-Surface: 2mm (Mechanical Surface Detection)

Electronics: DAE4 Sn1267; Calibrated: 02/23/2017

Phantom: SAM; Type: SAM V4.0;

Measurement SW: DASY52, Version 52.8 (2); SEMCAD X Version 14.6.6 (6824)

System Performance Check at 2450MHz/Area Scan (61x201x1): Interpolated grid: dx=1.200 mm, dy=1.20 mm

Maximum value of SAR (interpolated) = 11.8 mW/g

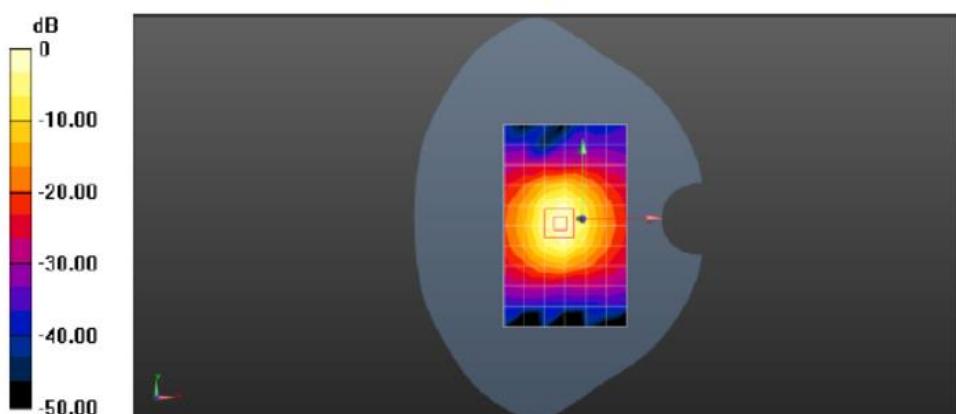
System Performance Check at 2450MHz/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 79.93 V/m; Power Drift = -0.03 dB

Peak SAR (extrapolated) = 25.2 mW/g

SAR(1 g) = 11.7 mW/g; SAR(10 g) = 5.73 mW/g

Maximum value of SAR (measured) = 12.9 mW/g



0 dB = 11.8W/Kg = 10.72 dB mW/g

System Performance Check 2450MHz Body 250mW

5.8. SAR Test Graph Results

Body worn for 802.11b Bottom towards Phantom 0mm

Communication System: Wi-Fi; Frequency: 2437 MHz; Duty Cycle: 1:1

Medium parameters used (interpolated): 2437 MHz; $\sigma = 1.912 \text{ S/m}$; $\epsilon_r = 51.87$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

DASY5 Configuration:

Probe: EX3DV4 - SN3789; ConvF(6.98, 6.98, 6.98); Calibrated: 1/13/2017;

Sensor-Surface: 2mm (Mechanical Surface Detection)

Electronics: DAE4 Sn1267; Calibrated: 02/23/2017

Phantom: SAM; Type: SAM V4.0

Measurement SW: DASY52, Version 52.8.8 (1222); SEMCAD X Version 14.6.10 (7331)

Area Scan (51x101x1): Interpolated grid: $dx=1.200 \text{ mm}$, $dy=1.20 \text{ mm}$

Maximum value of SAR (interpolated) = 0.886 mW/g

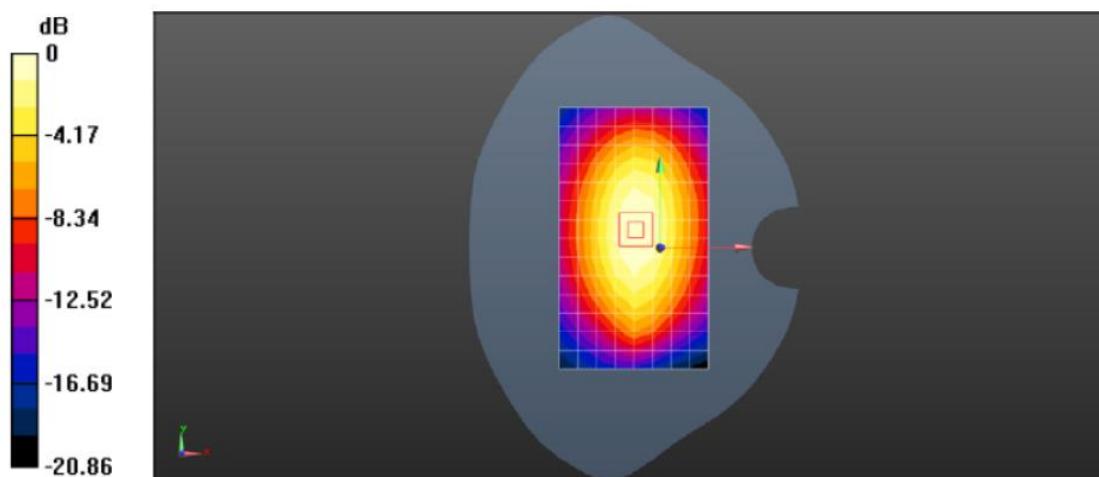
Zoom Scan (7x7x7)/Cube 0: Measurement grid: $dx=5\text{mm}$, $dy=5\text{mm}$, $dz=5\text{mm}$

Reference Value = 30.131 V/m; Power Drift = -0.17 dB

Peak SAR (extrapolated) = 0.971 mW/g

SAR(1 g) = 0.891 mW/g; SAR(10 g) = 0.261 mW/g

Maximum value of SAR (measured) = 0.91 mW/g



0 dB = 0.886 mW/g = -0.53 dB mW/g

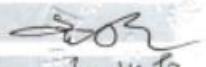
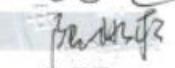
Body worn for 802.11b Bottom towards Phantom 0mm

5.9. Simultaneous Transmission

There is only WiFi&BT antenna, they can't transmit simultaneously.
so there is no simultaneous transmission SAR consideration.

6. Calibration Certificate

6.1. Probe Calibration Certificate

 In Collaboration with  Add: No.51 Xueyuan Road, Haidian District, Beijing, 100191, China Tel: +86-10-62304633-2218 Fax: +86-10-62304633-2209 E-mail: ctts@chinatrl.com Http://www.chinatrl.cn		 中国认可 国际互认 校准 CALIBRATION CNAS L0570	
Client	CIQ (Shenzhen)	Certificate No: Z17-97003	
CALIBRATION CERTIFICATE			
Object	EX3DV4 - SN:3789		
Calibration Procedure(s)	FD-Z11-004-01 Calibration Procedures for Dosimetric E-field Probes		
Calibration date:	January 13, 2017		
This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.			
All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)°C and humidity<70%.			
Calibration Equipment used (M&TE critical for calibration)			
Primary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Power Meter NRP2	101919	27-Jun-16 (CTTL, No.J16X04777)	Jun-17
Power sensor NRP-Z91	101547	27-Jun-16 (CTTL, No.J16X04777)	Jun-17
Power sensor NRP-Z91	101548	27-Jun-16 (CTTL, No.J16X04777)	Jun-17
Reference 10dB Attenuator	18N50W-10dB	13-Mar-16(CTTL, No.J16X01547)	Mar-18
Reference 20dB Attenuator	18N50W-20dB	13-Mar-16(CTTL, No.J16X01548)	Mar-18
Reference Probe EX3DV4	SN 7433	26-Sep-16(SPEAG, No.EX3-7433_Sep16)	Sep-17
DAE4	SN 1331	21-Jan-16(SPEAG, No.DAE4-1331_Jan16)	Jan-17
Secondary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Signal Generator MG3700A	6201052605	27-Jun-16 (CTTL, No.J16X04776)	Jun-17
Network Analyzer E5071C	MY46110673	26-Jan-16 (CTTL, No.J16X00894)	Jan-17
Calibrated by:	Name	Function	Signature
Calibrated by:	Yu Zongying	SAR Test Engineer	
Reviewed by:	QI Dianyuan	SAR Project Leader	
Approved by:	Lu Bingsong	Deputy Director of the laboratory	
Issued: January 14, 2017			
This calibration certificate shall not be reproduced except in full without written approval of the laboratory.			



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Glossary:

TSL tissue simulating liquid
NORM_{x,y,z} sensitivity in free space
ConvF sensitivity in TSL / NORM_{x,y,z}
DCP diode compression point
CF crest factor (1/duty_cycle) of the RF signal
A,B,C,D modulation dependent linearization parameters
Polarization Φ Φ rotation around probe axis
Polarization θ θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i
 $\theta=0$ is normal to probe axis
Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system
Calibration is Performed According to the Following Standards:
a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300MHz to 3GHz)", February 2005
c) IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010
d) KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}: Assessed for E-field polarization $\theta=0$ (f \leq 900MHz in TEM-cell; f $>$ 1800MHz: waveguide). NORM_{x,y,z} are only intermediate values, i.e., the uncertainties of NORM_{x,y,z} does not effect the E^2 -field uncertainty inside TSL (see below ConvF).
- NORM(f)_{x,y,z} = NORM_{x,y,z}*frequency_response (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCP_{x,y,z}: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics.
- Ax,y,z; Bx,y,z; Cx,y,z; VRx,y,z; A,B,C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f \leq 800MHz) and inside waveguide using analytical field distributions based on power measurements for f $>$ 800MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty valued are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORM_{x,y,z}* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from \pm 50MHz to \pm 100MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the NORMx (no uncertainty required).



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Probe EX3DV4

SN: 3789

Calibrated: January 13, 2017

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)

Certificate No: Z17-97003

Page 3 of 11



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DASY/EASY – Parameters of Probe: EX3DV4 – SN: 3789

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm(μ V/(V/m) ²) ^A	0.45	0.50	0.51	\pm 10.8%
DCP(mV) ^B	102.6	100.7	98.5	

Modulation Calibration Parameters

UID	Communication System Name	A dB	B dB/ μ V	C	D dB	VR mV	Unc ^E (k=2)
0	CW	X 0.0	0.0	1.0	0.00	193.3	\pm 2.7%
		Y 0.0	0.0	1.0		195.3	
		Z 0.0	0.0	1.0		199.4	

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2, which for a normal distribution Corresponds to a coverage probability of approximately 95%.

^A The uncertainties of Norm X, Y, Z do not affect the E²-field uncertainty inside TSL (see Page 5 and Page 6).

^B Numerical linearization parameter: uncertainty not required.

^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.



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DASY/EASY – Parameters of Probe: EX3DV4 – SN: 3789

Calibration Parameter Determined in Head Tissue Simulating Media

f [MHz] ^c	Relative Permittivity ^f	Conductivity (S/m) ^f	ConvF X	ConvF Y	ConvF Z	Alpha ^g	Depth ^g (mm)	Unct. (k=2)
750	41.9	0.89	8.89	8.89	8.89	0.35	0.80	± 12%
835	41.5	0.90	8.61	8.61	8.61	0.16	1.40	± 12%
1750	40.1	1.37	7.55	7.55	7.55	0.26	1.07	± 12%
1900	40.0	1.40	7.37	7.37	7.37	0.28	1.02	± 12%
2000	40.0	1.40	7.19	7.19	7.19	0.26	1.05	± 12%
2300	39.5	1.67	7.12	7.12	7.12	0.57	0.72	± 12%
2450	39.2	1.80	6.85	6.85	6.85	0.57	0.74	± 12%
2600	39.0	1.96	6.70	6.70	6.70	0.69	0.68	± 12%
5250	35.9	4.71	5.00	5.00	5.00	0.45	1.20	± 13%
5600	35.5	5.07	4.48	4.48	4.48	0.45	1.30	± 13%
5750	35.4	5.22	4.68	4.68	4.68	0.45	1.40	± 13%

^c Frequency validity above 300 MHz of ±100MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ±50MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

^f At frequency below 3 GHz, the validity of tissue parameters (ε and σ) can be relaxed to ±10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ε and σ) is restricted to ±5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^g Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.



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DASY/EASY – Parameters of Probe: EX3DV4 – SN: 3789

Calibration Parameter Determined in Body Tissue Simulating Media

f [MHz] ^c	Relative Permittivity ^f	Conductivity (S/m) ^f	ConvF X	ConvF Y	ConvF Z	Alpha ^g	Depth ^g (mm)	Unct. (k=2)
750	55.5	0.96	9.13	9.13	9.13	0.40	0.88	±12%
835	55.2	0.97	8.80	8.80	8.80	0.16	1.58	±12%
1750	53.4	1.49	7.36	7.36	7.36	0.25	1.09	±12%
1900	53.3	1.52	7.06	7.06	7.06	0.21	1.21	±12%
2000	53.3	1.52	7.20	7.20	7.20	0.19	1.44	±12%
2300	52.9	1.81	7.19	7.19	7.19	0.61	0.78	±12%
2450	52.7	1.95	6.98	6.98	6.98	0.56	0.84	±12%
2600	52.5	2.16	6.83	6.83	6.83	0.46	0.94	±12%
5250	48.9	5.36	4.64	4.64	4.64	0.50	1.45	±13%
5600	48.5	5.77	3.86	3.86	3.86	0.50	1.76	±13%
5750	48.3	5.94	4.27	4.27	4.27	0.56	1.95	±13%

^c Frequency validity above 300 MHz of ±100MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ±50MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

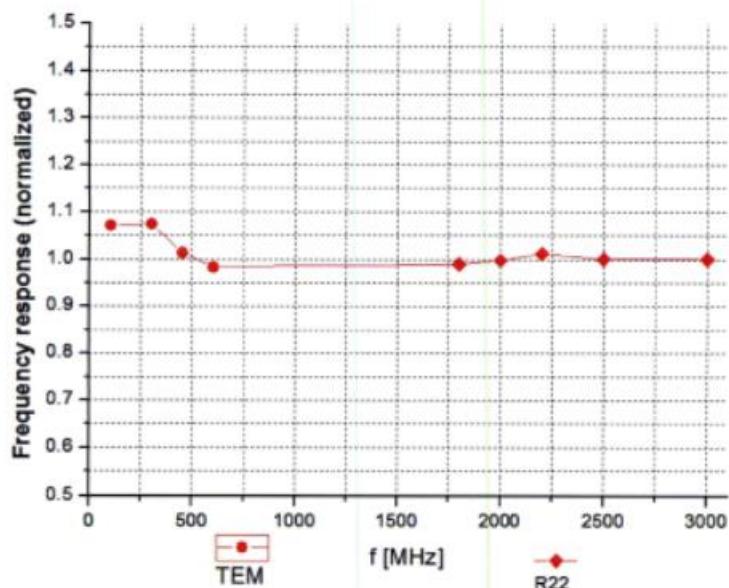
^f At frequency below 3 GHz, the validity of tissue parameters (ε and σ) can be relaxed to ±10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ε and σ) is restricted to ±5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^g Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.



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Frequency Response of E-Field (TEM-Cell: ifi110 EXX, Waveguide: R22)



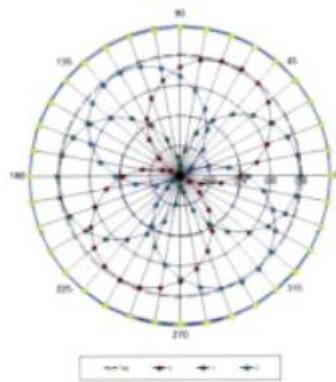
Uncertainty of Frequency Response of E-field: $\pm 7.5\%$ ($k=2$)



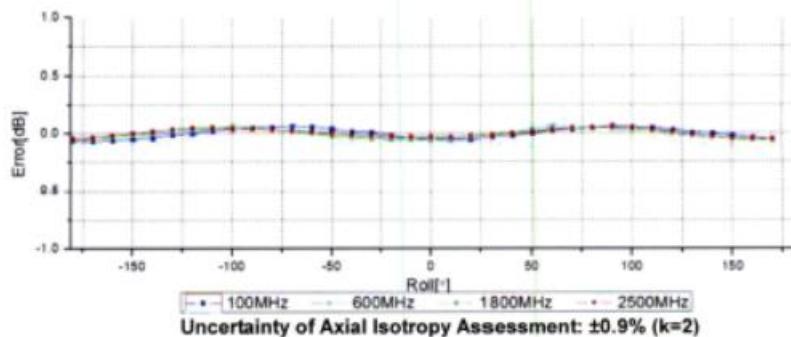
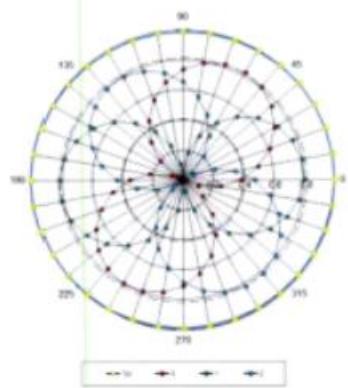
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Receiving Pattern (Φ), $\theta=0^\circ$

f=600 MHz, TEM



f=1800 MHz, R22

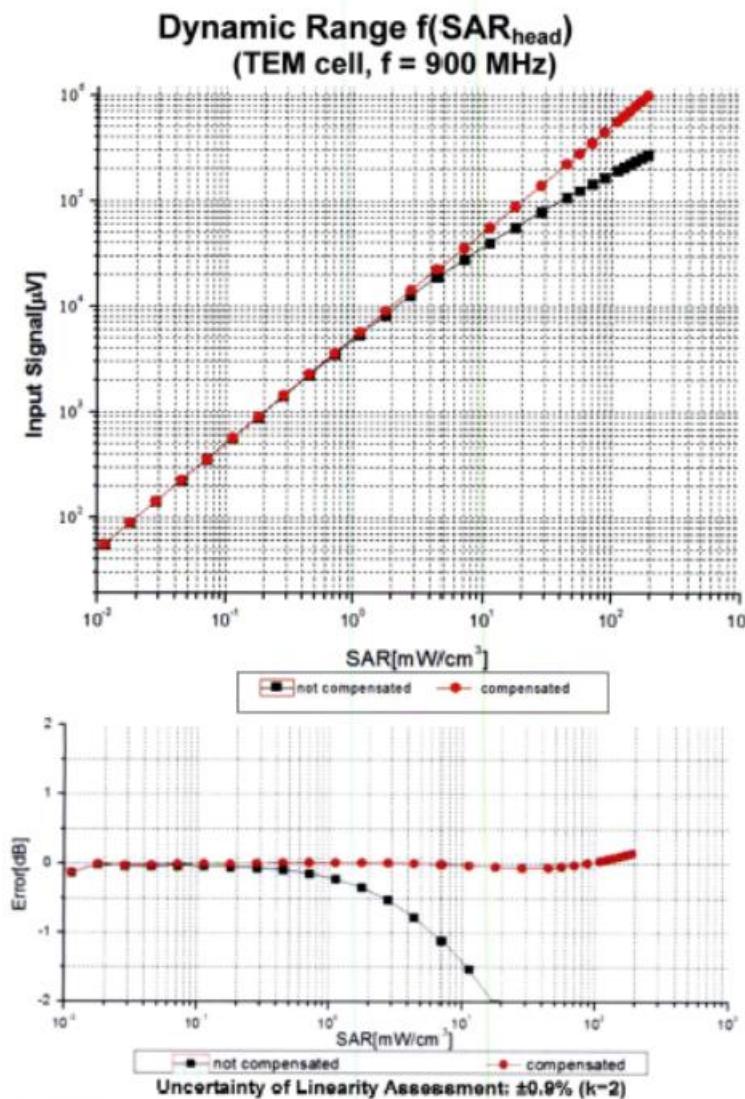


Certificate No: Z17-97003

Page 8 of 11



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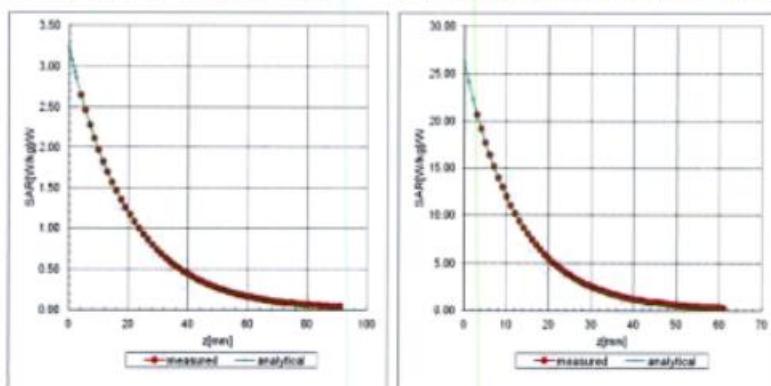
Page 9 of 11



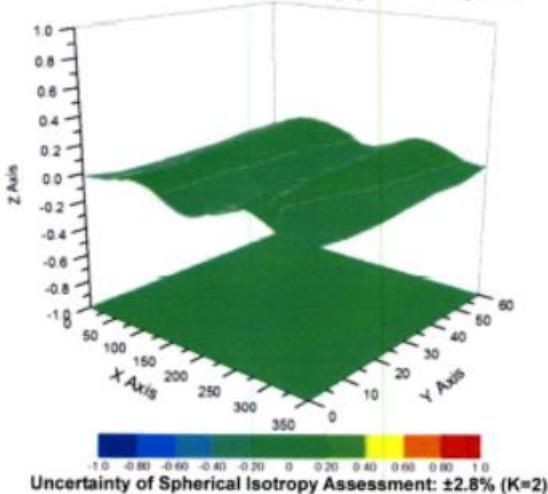
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Conversion Factor Assessment

f=835 MHz, WGLS R9(H_convF) f=1750 MHz, WGLS R22(H_convF)



Deviation from Isotropy in Liquid





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DASY/EASY – Parameters of Probe: EX3DV4 – SN: 3789

Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle (")	47.9
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disable
Probe Overall Length	337mm
Probe Body Diameter	10mm
Tip Length	9mm
Tip Diameter	2.5mm
Probe Tip to Sensor X Calibration Point	1mm
Probe Tip to Sensor Y Calibration Point	1mm
Probe Tip to Sensor Z Calibration Point	1mm
Recommended Measurement Distance from Surface	1.4mm

6.2. D2450V2 Dipole Calibration Certificate



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CNAS L0570

Client

Auden

Certificate No: Z16-97242

CALIBRATION CERTIFICATE

Object D2450V2 - SN: 733

Calibration Procedure(s) FD-Z11-003-01
Calibration Procedures for dipole validation kits

Calibration date: December 7, 2016

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)°C and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Power Meter NRP2	101919	27-Jun-16 (CTTL, No.J16X04777)	Jun-17
Power sensor NRP-Z91	101547	27-Jun-16 (CTTL, No.J16X04777)	Jun-17
Reference Probe EX3DV4	SN 7433	26-Sep-16(SPEAG, No.EX3-7433_Sep16)	Sep-17
DAE4	SN 771	02-Feb-16(CTTL-SPEAG, No.Z16-97011)	Feb-17
Secondary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Signal Generator E4438C	MY49071430	01-Feb-16 (CTTL, No.J16X00893)	Jan-17
Network Analyzer E5071C	MY46110673	26-Jan-16 (CTTL, No.J16X00894)	Jan-17

Calibrated by:	Name	Function	Signature
	Zhao Jing	SAR Test Engineer	
Reviewed by:	Qi Dianyuan	SAR Project Leader	
Approved by:	Lu Bingsong	Deputy Director of the laboratory	

Issued: December 11, 2016

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.



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Glossary:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORMx,y,z
N/A	not applicable or not measured

Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) For hand-held devices used in close proximity to the ear (frequency range of 300MHz to 3GHz)", February 2005
- c) IEC 62209-2, "Procedure to measure the Specific Absorption Rate (SAR) For wireless communication devices used in close proximity to the human body (frequency range of 30MHz to 6GHz)", March 2010
- d) KDB865664, SAR Measurement Requirements for 100 MHz to 6 GHz

Additional Documentation:

- e) DASY4/5 System Handbook

Methods Applied and Interpretation of Parameters:

- **Measurement Conditions:** Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- **Antenna Parameters with TSL:** The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- **Feed Point Impedance and Return Loss:** These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- **Electrical Delay:** One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- **SAR measured:** SAR measured at the stated antenna input power.
- **SAR normalized:** SAR as measured, normalized to an input power of 1 W at the antenna connector.
- **SAR for nominal TSL parameters:** The measured TSL parameters are used to calculate the nominal SAR result.

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2, which for a normal distribution Corresponds to a coverage probability of approximately 95%.



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Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY52	52.8.8.1258
Extrapolation	Advanced Extrapolation	
Phantom	Triple Flat Phantom 5.1C	
Distance Dipole Center - TSL	10 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	2450 MHz ± 1 MHz	

Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	39.2	1.80 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	39.4 ± 6 %	1.81 mho/m ± 6 %
Head TSL temperature change during test	<1.0 °C	---	---

SAR result with Head TSL

SAR averaged over 1 cm ³ (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	13.3 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	53.1 mW / g ± 20.8 % (k=2)
SAR averaged over 10 cm ³ (10 g) of Head TSL	Condition	
SAR measured	250 mW input power	6.22 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	24.9 mW / g ± 20.4 % (k=2)

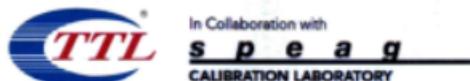
Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	52.7	1.95 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	53.1 ± 6 %	1.94 mho/m ± 6 %
Body TSL temperature change during test	<1.0 °C	----	----

SAR result with Body TSL

SAR averaged over 1 cm ³ (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	12.7 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	51.0 mW / g ± 20.8 % (k=2)
SAR averaged over 10 cm ³ (10 g) of Body TSL	Condition	
SAR measured	250 mW input power	5.85 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	23.5 mW / g ± 20.4 % (k=2)



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Appendix

Antenna Parameters with Head TSL

Impedance, transformed to feed point	52.9Ω+ 4.11jΩ
Return Loss	- 26.3dB

Antenna Parameters with Body TSL

Impedance, transformed to feed point	49.7Ω+ 5.90jΩ
Return Loss	- 24.6dB

General Antenna Parameters and Design

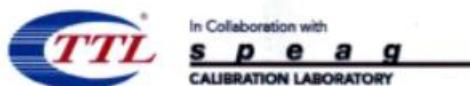
Electrical Delay (one direction)	1.257 ns
----------------------------------	----------

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. On some of the dipoles, small end caps are added to the dipole arms in order to improve matching when loaded according to the position as explained in the "Measurement Conditions" paragraph. The SAR data are not affected by this change. The overall dipole length is still according to the Standard.
No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

Manufactured by	SPEAG
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DASY5 Validation Report for Head TSL

Date: 11.07.2016

Test Laboratory: CTTL, Beijing, China

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN: 733

Communication System: UID 0, CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium parameters used: $f = 2450$ MHz; $\sigma = 1.809$ S/m; $\epsilon_r = 39.42$; $\rho = 1000$ kg/m³

Phantom section: Center Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

- Probe: EX3DV4 - SN7433; ConvF(7.45, 7.45, 7.45); Calibrated: 9/26/2016;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn771; Calibrated: 2/2/2016
- Phantom: Triple Flat Phantom 5.1C; Type: QD 000 P51 CA; Serial: 1161/1
- Measurement SW: DASY52, Version 52.8 (8); SEMCAD X Version 14.6.10 (7372)

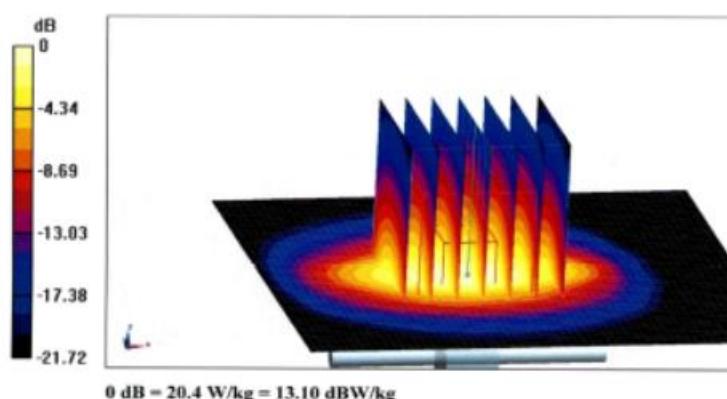
Dipole Calibration/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 106.8 V/m; Power Drift = 0.03 dB

Peak SAR (extrapolated) = 27.5 W/kg

SAR(1 g) = 13.3 W/kg; SAR(10 g) = 6.22 W/kg

Maximum value of SAR (measured) = 20.4 W/kg



Certificate No: Z16-97242

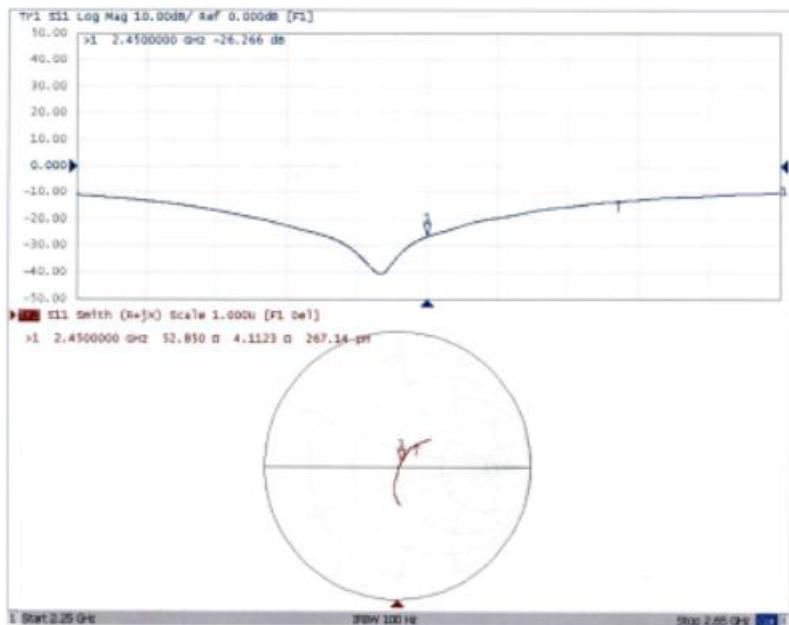
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Impedance Measurement Plot for Head TSL



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Page 6 of 8



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DASY5 Validation Report for Body TSL

Date: 12.07.2016

Test Laboratory: CTTL, Beijing, China

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN: 733

Communication System: UID 0, CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium parameters used: $f = 2450$ MHz; $\sigma = 1.943$ S/m; $\epsilon_r = 53.12$; $\rho = 1000$ kg/m 3

Phantom section: Right Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

- Probe: EX3DV4 - SN7433; ConvF(7.46, 7.46, 7.46); Calibrated: 9/26/2016;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn771; Calibrated: 2/2/2016
- Phantom: Triple Flat Phantom 5.1C; Type: QD 000 P51 CA; Serial: 1161/1
- Measurement SW: DASY52, Version 52.8 (8); SEMCAD X Version 14.6.10 (7372)

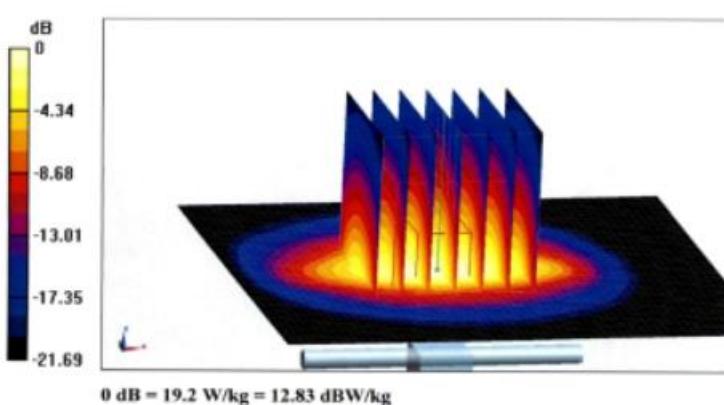
Dipole Calibration/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 98.60 V/m; Power Drift = -0.01 dB

Peak SAR (extrapolated) = 26.0 W/kg

SAR(1 g) = 12.7 W/kg; SAR(10 g) = 5.85 W/kg

Maximum value of SAR (measured) = 19.2 W/kg

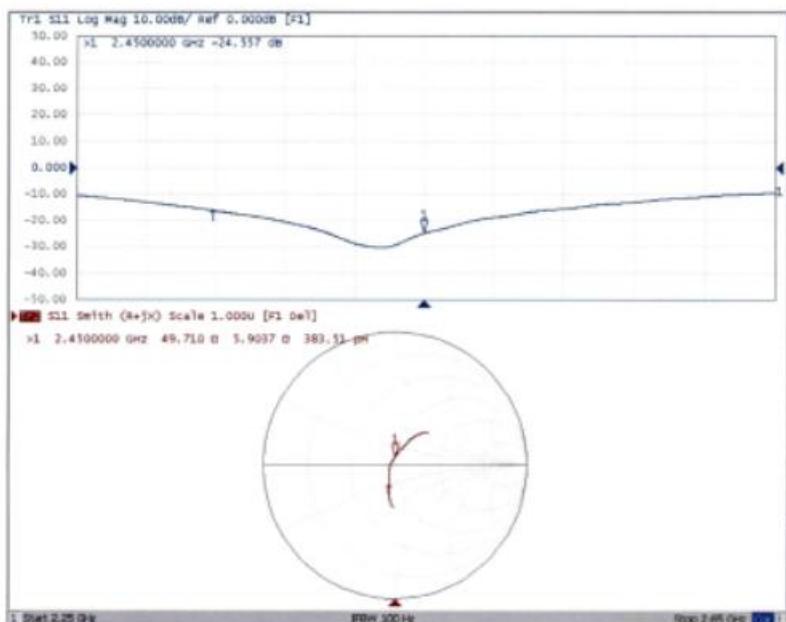




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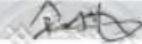
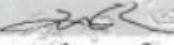
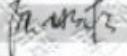
Impedance Measurement Plot for Body TSL

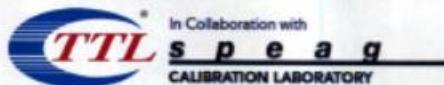


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Page 8 of 8

6.3. DAE4 Calibration Certificate

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Client : CIQ(Shenzhen)		Certificate No: Z17-97025	
CALIBRATION CERTIFICATE			
Object	DAE4 - SN: 1267		
Calibration Procedure(s)	FD-Z11-002-01 Calibration Procedure for the Data Acquisition Electronics (DAEx)		
Calibration date:	February 23, 2017		
This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.			
All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)°C and humidity<70%.			
Calibration Equipment used (M&TE critical for calibration)			
Primary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Process Calibrator 753	1971018	27-June-16 (CTTL, No:J16X04778)	June-17
Calibrated by:	Name Yu Zongying	Function SAR Test Engineer	Signature 
Reviewed by:	Name Qi Dianyuan	Function SAR Project Leader	Signature 
Approved by:	Name Lu Bingsong	Function Deputy Director of the laboratory	Signature 
Issued: February 24, 2017			
This calibration certificate shall not be reproduced except in full without written approval of the laboratory.			



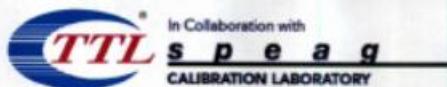
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Glossary:

DAE	data acquisition electronics
Connector angle	information used in DASY system to align probe sensor X to the robot coordinate system.

Methods Applied and Interpretation of Parameters:

- *DC Voltage Measurement:* Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle:* The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The report provide only calibration results for DAE, it does not contain other performance test results.



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DC Voltage Measurement

A/D - Converter Resolution nominal
High Range: 1LSB = $6.1\mu\text{V}$, full range = $-100 \dots +300 \text{ mV}$
Low Range: 1LSB = 61nV , full range = $-1 \dots +3\text{mV}$
DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	$404.393 \pm 0.15\%$ (k=2)	$403.982 \pm 0.15\%$ (k=2)	$404.196 \pm 0.15\%$ (k=2)
Low Range	$3.99704 \pm 0.7\%$ (k=2)	$3.96717 \pm 0.7\%$ (k=2)	$3.99451 \pm 0.7\%$ (k=2)

Connector Angle

Connector Angle to be used in DASY system	$165^\circ \pm 1^\circ$
---	-------------------------



**Acceptable Conditions for SAR Measurements Using Probes and Dipoles
Calibrated under the SPEAG-CTTL Dual-Logo Calibration Program to
Support FCC Equipment Certification**

The acceptable conditions for SAR measurements using probes, dipoles and DAEs calibrated by CTTL (*China Telecommunication Technology Labs*), under the Dual-Logo Calibration Certificate program and quality assurance (QA) protocols established between SPEAG (*Schmid & Partner Engineering AG, Switzerland*) and CTTL, to support FCC (*U.S. Federal Communications Commission*) equipment certification are defined and described in the following. The conditions in this KDB are valid until December 31, 2015.

- 1) The agreement established between SPEAG and CTTL is only applicable to calibration services performed by CTTL where its clients (companies and divisions of such companies) are headquartered in the Greater China Region, including Taiwan and Hong Kong. CTTL shall inform the FCC of any changes or early termination to the agreement.
- 2) Only a subset of the calibration services specified in the SPEAG-CTTL agreement, while it remains valid, are applicable to SAR measurements performed using such equipment for supporting FCC equipment certification. These are identified in the following.
 - a) Calibration of dosimetric (SAR) probes EX3DVx, ET3DVx and ES3DVx.
 - i) Free-space E-field and H-field probes, including those used for HAC (hearing aid compatibility) evaluation, temperature probes, other probes or equipment not identified in this document, when calibrated by CTTL, are excluded and cannot be used for measurements to support FCC equipment certification.
 - ii) Signal specific and bundled probe calibrations based on PMR (probe modulation response) characteristics or probe sensor model based linearization methods that are not fully described in SAR standards are excluded and cannot be used for measurements to support FCC equipment certification.
 - b) Calibration of SAR system validation dipoles, excluding HAC dipoles.
 - c) Calibration of data acquisition electronics DAE3Vx, DAE4Vx and DAEasyVx.
 - d) For FCC equipment certification purposes, the frequency range of SAR probe and dipole calibrations is limited to 700 MHz - 6 GHz and provided it is supported by the equipment identified in the CTTL QA protocol (a separate attachment to this document).
 - e) The identical system and equipment setup, measurement configurations, hardware, evaluation algorithms, calibration and QA protocols, including the format of calibration certificates and reports used by SPEAG shall be applied by CTTL. Equivalent test equipment and measurement configurations may be considered only when agreed by both SPEAG and the FCC.
 - f) The calibrated items are only applicable to SPEAG DASY 4 and DASY 5 systems or higher version systems that satisfy the requirements of this KDB.
- 3) The SPEAG-CTTL agreement includes specific protocols identified in the following to ensure the quality of calibration services provided by CTTL under this SPEAG-

7. Test Setup Photos



Photograph of the depth in the Body Phantom (2450MHz)



Body Front side 0mm



Body Back side 0mm



Body Left side 0mm



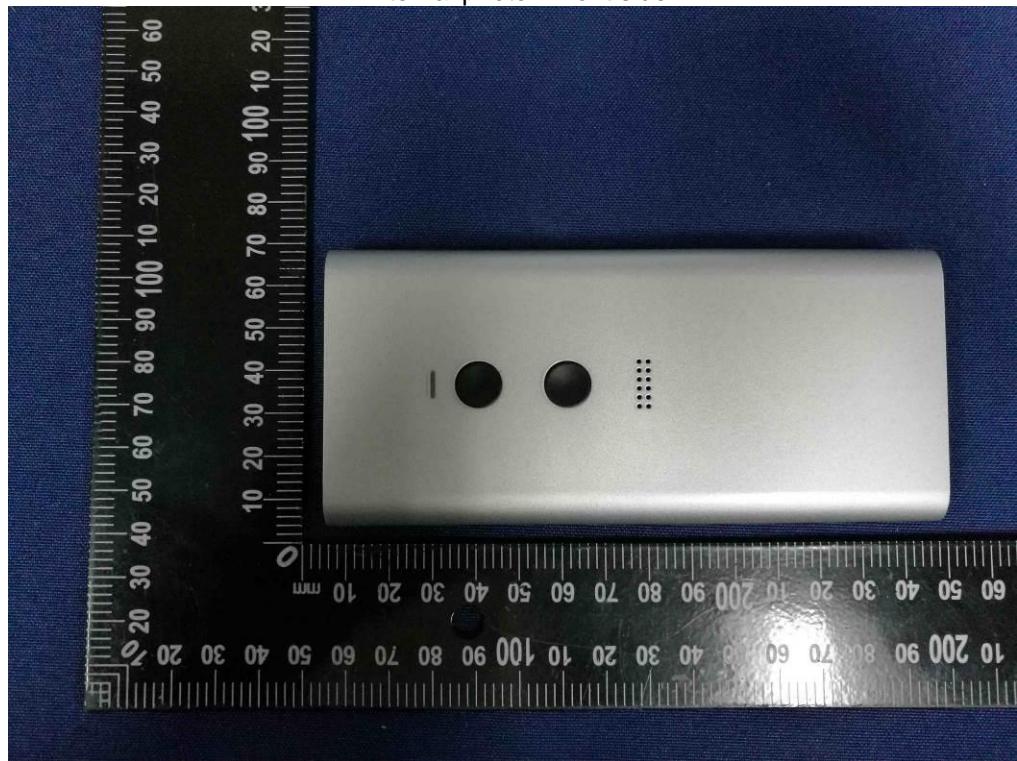
Body Right side 0mm



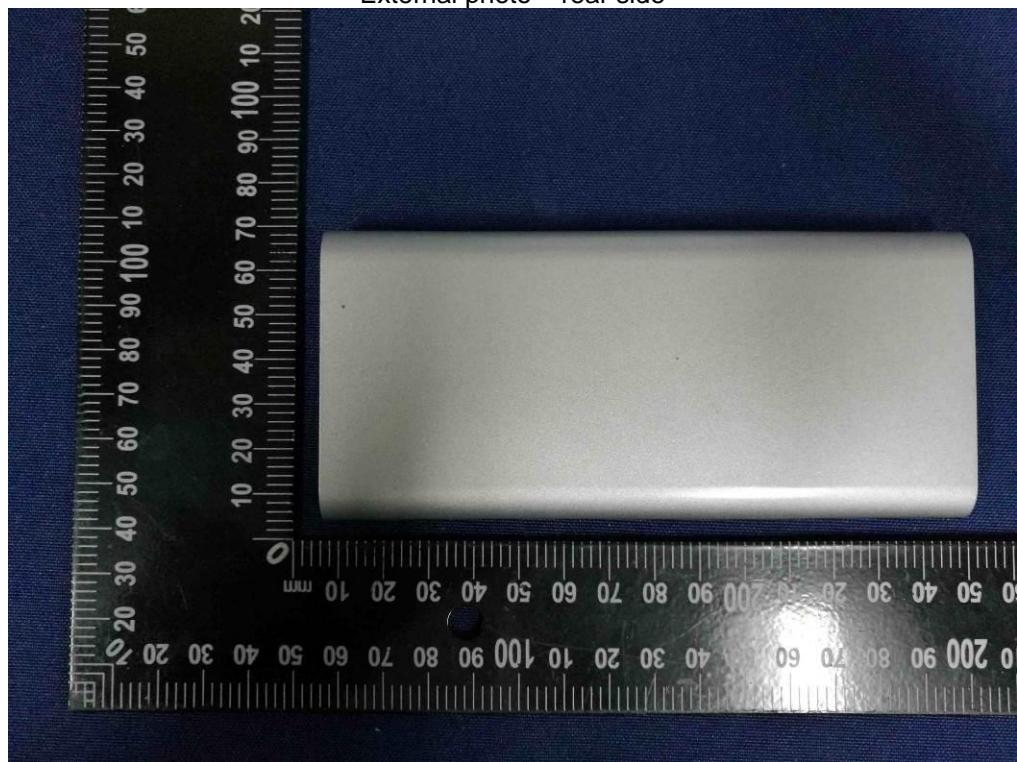
Body Bottom side 0mm

8. External Photos of the EUT

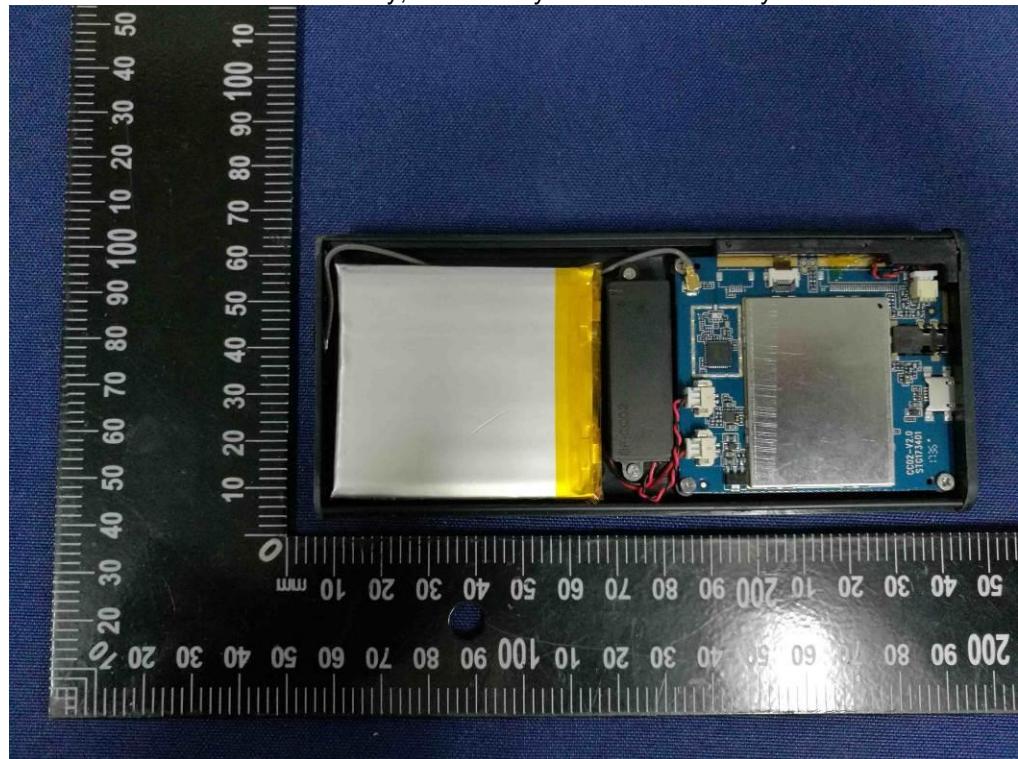
External photo – front side



External photo – rear side



B1 – Battery, Intrinsically Safe Li-ion Battery



.....End of Report.....