

SAR TEST REPORT

No. B16N01294-SAR

For

Olive Oil Computer Limited

Tablet PC

Model Name: CT4

With

Hardware Version: 0x17

Software Version: 20161129

FCC: 2AKHP-CT4-US

Issued Date: 2016-12-12

Note:

The test results in this test report relate only to the devices specified in this report. This report shall not be reproduced except in full without the written approval of CTTL.

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REPORT HISTORY

Report Number	Revision	Issue Date	Description
B16N01294-SAR	Rev.0	2016-12-12	Initial creation of test report



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1 Test Laboratory

1.1 Testing Location

Company Name:	CTTL(Shenzhen)		
A ddraga.	TCL International E City No.1001 Zhongshanyuan Road, Nanshan		
Address:	District, Shenzhen, Guangdong Province P.R.China		

1.2 Testing Environment

Temperature:	18°C~25 °C
Relative humidity:	30%~ 70%
Ground system resistance:	<4Ω
Ambient noise & Reflection:	< 0.012 W/kg

1.3 Project Data

Project Leader:	Cao Junfei
Test Engineer:	Zhang Yunzhuan
Testing Start Date:	November 09, 2016
Testing End Date:	November 09, 2016

1.4 Signature





2 Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) found during testing for Olive Oil Computer Limited Tablet PC CT4 are as follows:

Table 2.1: Highest Reported SAR (1g)

Exposure Configuration	Technology Band	Highest Reported SAR	Equipment Class
Body-worn(Data) (Separation Distance 10mm	WLAN 2.4GHz	0.35	DTS

The SAR values found for the Mobile Phone are below the maximum recommended levels of 1.6 W/Kg as averaged over any 1g tissue according to the ANSI C95.1-1999.

For body worn operation, this device has been tested and meets FCC RF exposure guidelines when used with any accessory that contains no metal and which provides a minimum separation distance of 10 mm between this device and the body of the user. Use of other accessories may not ensure compliance with FCC RF exposure guidelines.

The EUT battery must be fully charged and checked periodically during the test to ascertain uniform power output.

The measurement together with the test system set-up is described in annex C of this test report. A detailed description of the equipment under test can be found in chapter 4 of this test report.

The highest reported SAR value is obtained at the case of (Table 2.1), and the values are: 0.35W/kg(1g).



3 Client Information

3.1 Applicant Information

Company Name:	Olive Oil Computer Limited	
Address /Post:	Level 15, Langham Place, 8 Argyle Street, Mongkok, Kowloon, Hong	
Address /Post.	Kong.	
Contact:	Tim Cheung	
Email:	tim.cheung.wehc@com.cn	
Telephone:	852 6813 7442	
Fax:	(86) 755 82215189	

3.2 Manufacturer Information

Company Name:	Welco Wong's Technology (ShenZhen) Limited		
	2-3 floor of block 14, 1-4 floor of block 17, 1-3 floor of block 34, No.2 of		
Address /Post:	WanFeng WanZhangPu Industrial Estate, ShaJing Bao'an ShenZhen,		
	China.		
Contact:	Tim Cheung		
Email:	tim.cheung.wehc.com.cn		
Telephone:	(86) 755-27263128		
Fax:	(86) 755-27263885		



4 Equipment Under Test (EUT) and Ancillary Equipment (AE)

4.1 About EUT

Description:	Tablet PC
Model Name:	CT4
Operating mode(s):	Wi-Fi 2.4G,BT
Tested Tx Frequency:	2412 – 2462 MHz (Wi-Fi 2.4G)
Test device Production information:	Production unit
Device type:	Portable device
Antenna type:	Integrated antenna
Accessories/Body-worn configurations:	/
Hotspot mode:	1

4.2 Internal Identification of EUT used during the test

EUT ID*	SN or IMEI	HW Version	SW Version
EUT1	/	0x17	20161129

^{*}EUT ID: is used to identify the test sample in the lab internally.

Note: It is performed to test SAR with the EUT 1.

4.3 Internal Identification of AE used during the test

AE ID*	Description	Model	SN	Manufacturer
AE1	Battery	HT HT-T-P-1639-LF910	/	Highpower Technology Co., Ltd.

^{*}AE ID: is used to identify the test sample in the lab internally.



5 TEST METHODOLOGY

5.1 Applicable Limit Regulations

ANSI C95.1–1999:IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz.

It specifies the maximum exposure limit of **1.6 W/kg** as averaged over any 1 gram of tissue for portable devices being used within 20 cm of the user in the uncontrolled environment.

5.2 Applicable Measurement Standards

IEEE 1528–2013: Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Experimental Techniques.

KDB 447498 D01 General RF Exposure Guidance v06: Mobile and Portable Devices RF Exposure Procedures and Equipment Authorization Policies.

KDB 248227 D01 802.11 Wi-Fi SAR v02r02: SAR Guidance for IEEE 802.11 (Wi-Fi) Transmitters.

KDB 865664 D01 SAR measurement 100 MHz to 6 GHz v01r04: SAR Measurement Requirements for 100 MHz to 6 GHz.

KDB 865664 D02 RF Exposure Reporting v01r02: RF Exposure Compliance Reporting and Documentation Considerations



6 Specific Absorption Rate (SAR)

6.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

6.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt}(\frac{dW}{dm}) = \frac{d}{dt}(\frac{dW}{\rho dv})$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$SAR = c(\frac{\delta T}{\delta t})$$

Where: C is the specific head capacity, δT is the temperature rise and δt is the exposure duration, or related to the electrical field in the tissue by

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where: σ is the conductivity of the tissue, ρ is the mass density of tissue and E is the RMS electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.



7 Tissue Simulating Liquids

7.1 Targets for tissue simulating liquid

Table 7.1: Targets for tissue simulating liquid

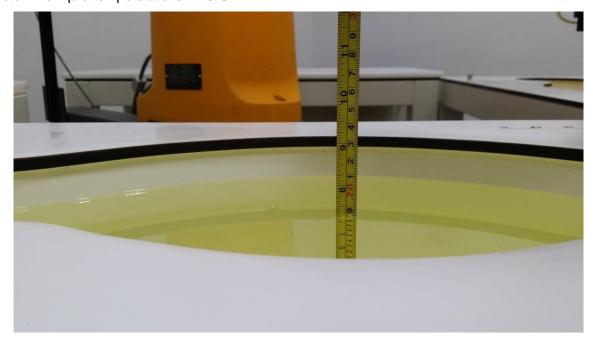
		3) 1	
Frequency (MHz)	Liquid Type	Conductivity (σ)	± 5% Range	Permittivity (ε)	± 5% Range
2450	Body	1.95	1.85~2.05	52.7	50.1~55.3

7.2 Dielectric Performance

Table 7.2: Dielectric Performance of Tissue Simulating Liquid

Measurement Dat	e _{Type}	Eroguenev	Permittivity	Drift	Conductivity	Drift		
(yyyy-mm-dd)	Туре	Frequency	ε	(%)	σ (S/m)	(%)		
2016-11-09	Body	2450	53.15	0.85	1.972	1.13		

Note: The liquid temperature is 22.0°C



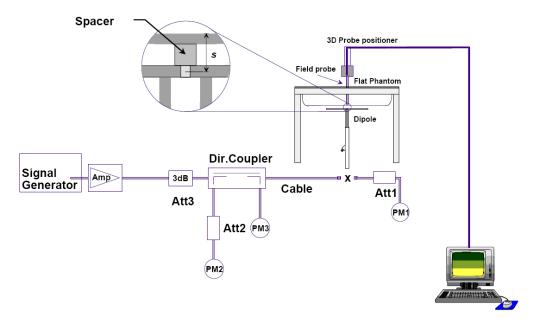
Picture 7-1: Liquid depth in the Flat Phantom(2450MHz)



8System verification

8.1 System Setup

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:



Picture 8.1 System Setup for System Evaluation



Picture 8.2 Photo of Dipole Setup



8.2 System Verification

SAR system verification is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device.

The system verification results are required that the area scan estimated 1-g SAR is within 3% of the zoom scan 1-g SAR. The details are presented in annex B.

Table 8.1: System Verification of Body

			•		<u> </u>		
Measurement		Target val	ue (W/kg)	Measured v	value (W/kg)	Devia	ation
Date	Frequency	10 g	1 g	10 g	1 g	10 g	1 g
(yyyy-mm-dd)		Average	Average	Average	Average	Average	Average
2016-11-09	2450 MHz	24.4	52.3	23.52	50.40	-3.61	-3.63



9 Measurement Procedures

9.1 Tests to be performed

In order to determine the highest value of the peak spatial-average SAR of a handset, all device positions, configurations and operational modes shall be tested for each frequency band according to steps 1 to 3 below. A flowchart of the test process is shown in picture 9.1.

Step 1: The tests described in 9.2 shall be performed at the channel that is closest to the center of the transmit frequency band (f_c) for:

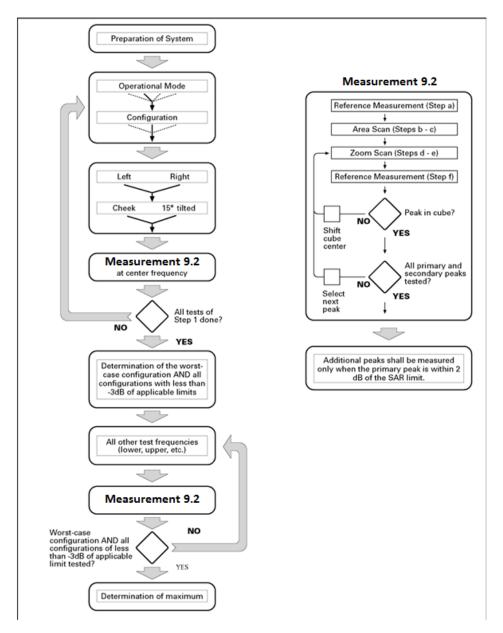
- a) all device positions (cheek and tilt, for both left and right sides of the SAM phantom, as described in annex D),
- b) all configurations for each device position in a), e.g., antenna extended and retracted, and
- c) all operational modes, e.g., analogue and digital, for each device position in a) and configuration in b) in each frequency band.

If more than three frequencies need to be tested according to 11.1 (i.e., $N_c > 3$), then all frequencies, configurations and modes shall be tested for all of the above test conditions.

Step 2: For the condition providing highest peak spatial-average SAR determined in Step 1, perform all tests described in 9.2 at all other test frequencies, i.e., lowest and highest frequencies. In addition, for all other conditions (device position, configuration and operational mode) where the peak spatial-average SAR value determined in Step 1 is within 3 dB of the applicable SAR limit, it is recommended that all other test frequencies shall be tested as well.

Step 3: Examine all data to determine the highest value of the peak spatial-average SAR found in Steps 1 to 2.





Picture 9.1Block diagram of the tests to be performed

9.2 General Measurement Procedure

The area and zoom scan resolutions specified in the table below must be applied to the SAR measurements and fully documented in SAR reports to qualify for TCB approval. Probe boundary effect error compensation is required for measurements with the probe tip closer than half a probe tip diameter to the phantom surface. Both the probe tip diameter and sensor offset distance must satisfy measurement protocols; to ensure probe boundary effect errors are minimized and the higher fields closest to the phantom surface can be correctly measured and extrapolated to the phantom surface for computing 1-g SAR. Tolerances of the post-processing algorithms must be verified by the test laboratory for the scan resolutions used in the SAR measurements, according to the reference distribution functions specified in IEEE Std 1528-2013. The results should be documented as part of the system validation records and may be requested to support test results



when all the measurement parameters in the following table are not satisfied.

			≤ 3 GHz	> 3 GHz		
Maximum distance from (geometric center of pro			5 ± 1 mm	½-5-ln(2) ± 0.5 mm		
Maximum probe angle f normal at the measurem	•	-	30°±1°	20° ± 1°		
			≤ 2 GHz: ≤ 15 mm 2 – 3 GHz: ≤ 12 mm	3 – 4 GHz: ≤ 12 mm 4 – 6 GHz: ≤ 10 mm		
Maximum area scan spa	tial resoluti	on: Δx _{Area} , Δy _{Area}	When the x or y dimension of t measurement plane orientation, measurement resolution must b dimension of the test device wi point on the test device.	is smaller than the above, the e < the corresponding x or y		
Maximum zoom scan sp	atial resolu	tion: Δx_{Zoom} , Δy_{Zoom}	≤ 2 GHz: ≤ 8 mm 2 – 3 GHz: ≤ 5 mm*	3 – 4 GHz: ≤ 5 mm* 4 – 6 GHz: ≤ 4 mm*		
	uniform (grid: Δz _{Zoom} (n)	≤ 5 mm	3 – 4 GHz: ≤ 4 mm 4 – 5 GHz: ≤ 3 mm 5 – 6 GHz: ≤ 2 mm		
Maximum zoom scan spatial resolution, normal to phantom surface	graded	Δz _{Zoom} (1): between 1 st two points closest to phantom surface	≤ 4 mm	3 – 4 GHz: ≤ 3 mm 4 – 5 GHz: ≤ 2.5 mm 5 – 6 GHz: ≤ 2 mm		
	grid	Δz _{Zoom} (n>1): between subsequent points	≤ 1.5·Δz	Z _{com} (n-1)		
Minimum zoom scan volume	x, y, z	1	≥ 30 mm	3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: > 22 mm		

Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.

9.3 Bluetooth & Wi-Fi Measurement Procedures for SAR

Normal network operating configurations are not suitable for measuring the SAR of 802.11 transmitters in general. Unpredictable fluctuations in network traffic and antenna diversity conditions can introduce undesirable variations in SAR results. The SAR for these devices should be measured using chipset based test mode software to ensure that the results are consistent and reliable.

Chipset based test mode software is hardware dependent and generally varies among manufacturers. The device operating parameters established in a test mode for SAR measurements must be identical to those programmed in production units, including output power levels, amplifier gain settings and other RF performance tuning parameters. The test frequencies should correspond to actual channel frequencies defined for domestic use. SAR for devices with switched diversity should be measured with only one antenna transmitting at a time during each SAR measurement, according to a fixed modulation and data rate. The same data pattern should be used for all measurements.

^{*} When zoom scan is required and the <u>reported</u> SAR from the area scan based 1-g SAR estimation procedures of KDB 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.



9.4 Power Drift

To control the output power stability during the SAR test, DASY5 system calculates the power drift by measuring the E-field at the same location at the beginning and at the end of the measurement for each test position. These drift values can be found in Section 14 labeled as: (Power Drift [dB]). This ensures that the power drift during one measurement is within 5%.



10 Area Scan Based 1-g SAR

10.1 Requirement of KDB

According to the KDB447498 D01, when the implementation is based the specific polynomial fit algorithm as presented at the 29th Bio electromagnetics Society meeting (2007) and the estimated 1-gSAR is ≤ 1.2 W/kg, a zoom scan measurement is not required provided it is also not needed for any other purpose; for example, if the peak SAR location required for simultaneous transmission SAR test exclusion can be determined accurately by the SAR system or manually to discriminate between distinctive peaks and scattered noisy SAR distributions from area scans.

There must not be any warning or alert messages due to various measurement concerns identified by the SAR system; for example, noise in measurements, peaks too close to scan boundary, peaks are too sharp, spatial resolution and uncertainty issues etc. The SAR system verification must also demonstrate that the area scan estimated 1-g SAR is within 3% of the zoom scan 1-g SAR (See Annex B). When all the SAR results for each exposure condition in a frequency band and wireless mode are based on estimated 1-g SAR, the 1-g SAR for the highest SAR configuration must be determined by a zoom scan.

10.2 Fast SAR Algorithms

The approach is based on the area scan measurement applying a frequency dependent attenuation parameter. This attenuation parameter was empirically determined by analyzing a large number of phones. The MOTOROLA FAST SAR was developed and validated by the MOTOROLA Research Group in Ft. Lauderdale.

In the initial study, an approximation algorithm based on Linear fit was developed. The accuracy of the algorithm has been demonstrated across a broad frequency range (136-2450 MHz) and for both 1- and 10-g averaged SAR using a sample of 264 SAR measurements from 55 wireless handsets. For the sample size studied, the root-mean-squared errors of the algorithm are 1.2% and 5.8% for 1- and 10-g averaged SAR, respectively. The paper describing the algorithm in detail is expected to be published in August 2004 within the Special Issue of Transactions on MTT.

In the second step, the same research group optimized the fitting algorithm to an Polynomial fit whereby the frequency validity was extended to cover the range 30-6000MHz. Details of this study can be found in the BEMS 2007 Proceedings.

Both algorithms are implemented in DASY software.



11 Conducted Output Power

11.1 Manufacturing tolerance

Table 11.1: WiFi

Mode	Channel/Data rate	Target (dBm)	Tolerance ±(dB)
802.11 b (2.4GHz)	1-11Mbps	16	1
802.11 g (2.4GHz)	6-54Mbps	15	1
802.11 n (2.4GHz HT20)	MCS0-7	14	1

Table 11.2: BT

Mode	Target (dBm)	Tolerance ±(dB)
GFSK	-8	2
π/4 DQPSK	-10	2
8DPSK	-10	2
BLE	4	2

11.2 Wi-Fi Measurement result

The average conducted power for Wi-Fi is as following:

802.11b (dBm)

Channel\data rate	1Mbps	2Mbps	5.5Mbps	11Mbps
1(2412MHz) 15.9		15.5	15.6	15.4
6(2437MHz)	15.8	15.4	15.6	15.4
11(2462MHz)	15.5	15.5	15.3	15.0

802.11g (dBm)

	Channel\data rate	6Mbps	9Mbps	12Mbps	18Mbps	24Mbps	36Mbps	48Mbps	54Mbps
	1(2412MHz)	15.0	14.9	15.0	14.8	15.0	14.9	15.0	15.0
	6(2437MHz)	15.0	14.8	14.9	14.8	15.0	14.8	15.0	15.0
	11(2462MHz)	14.7	14.5	14.5	14.6	14.7	14.5	14.5	14.7

802.11n (dBm) - HT20 (2.4G)

Channel\data rate	MCS0	MCS1	MCS2	MCS3	MCS4	MCS5	MCS6	MCS7
1(2412MHz)	14.0	14.0	13.8	13.9	13.7	14.0	13.8	13.9
6(2437MHz)	13.8	13.9	13.5	13.5	13.5	13.5	13.5	13.7
11(2462MHz)	13.6	13.5	13.3	13.5	13.6	13.2	13.3	13.6

Note: The conducted power is provided by Manufacturer.



The output power of BT antenna is as following:

Mode	Conducted Power (dBm)						
Mode	Channel 0 (2402MHz)	Channel 39 (2441MHz)	Channel 78 (2480MHz)				
GFSK	-6.15	-6.77	-9.12				
π/4 DQPSK	-9.20	-10.38	-11.18				
8DPSK	-8.85	-10.54	-11.24				
BLE	5.66	5.27	3.76				

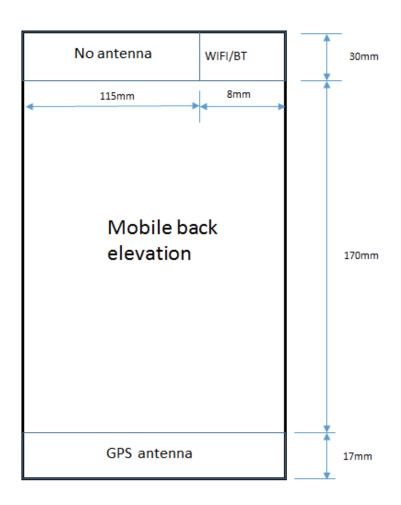
Note: The conducted power is provided by Manufacturer.

12 Simultaneous TX SAR Considerations

12.1 Introduction

The following procedures adopted from "FCC SAR Considerations for Cell Phones with Multiple Transmitters" are applicable to handsets with built-in unlicensed transmitters such as 802.11 a/b/g and Bluetooth devices which may simultaneously transmit with the licensed transmitter. For this device, the BT and Wi-Fi can transmit simultaneous with other transmitters.

12.2 Transmit Antenna Separation Distances



Picture 12.1 Antenna Locations



12.3 Standalone SAR Test Exclusion Considerations

Standalone 1-g head or body SAR evaluation by measurement or numerical simulation is not required when the corresponding SAR Exclusion Threshold condition, listed below, is satisfied. The 1-g SAR test exclusion threshold for 100 MHz to 6 GHz at test separation distances ≤ 50 mm are determined by:

[(max. power of channel, including tune-up tolerance, mW) / (min. test separation distance, mm)] \cdot [$\sqrt{f(GHz)}$] \leq 3.0 for 1-g SAR, where

- f(GHz) is the RF channel transmit frequency in GHz
- Power and distance are rounded to the nearest mW and mm before calculation
- The result is rounded to one decimal place for comparison

Table 12.1: Standalone SAR test exclusion considerations

Band/Mode	f(GHz)	Position	SAR test exclusion	RF o	utput wer	SAR test
			threshold (mW)	dBm	mW	exclusion
2.4GHz WLAN 802.11 b	2.45	Body	19.17	17	50.12	No
Bluetooth	2.40	Body	19.17	6	3.98	Yes



13 SAR Test Result

It is determined by user manual for the distance between the EUT and the phantom bottom. The distance is 10mm and just applied to the condition of body worn accessory. It is performed for all SAR measurements with area scan based 1-g SAR estimation (Fast SAR). A zoom scan measurement is added when the estimated 1-g SAR is the highest measured SAR in each exposure configuration, wireless mode and frequency band combination or >1.2W/kg. The calculated SAR is obtained by the following formula:

Reported SAR = Measured SAR $\times 10^{(P_{Target} - P_{Measured})/10}$

Where P_{Target} is the power of manufacturing upper limit; $P_{Measured}$ is the measured power in chapter 11.



13.1 WLAN Evaluation

Body Evaluation

Table 13.1: SAR Values (WLAN - Body) – 802.11b 1Mbps (Fast SAR)

		Д	mbient	Temperature	e: 21.7°C	Liquid Tem	perature: 2	1.2°C	2°C		
Frequency		Test	Figure	Conducted	Max. tune-up	Measured	Reported	Measured	Reported	Power	
MHz	Ch.	Position	No.	Power (dBm)	Power (dBm)	SAR(10g) (W/kg)	SAR(10g) (W/kg)	SAR(1g) (W/kg)	SAR(1g)(W/kg)	Drift (dB)	
2412	1	Front	/	15.9	17	0.092	0.12	0.185	0.24	0.07	
2412	1	Rear	/	15.9	17	0.132	0.17	0.270	0.35	0.04	
2412	1	Left	/	15.9	17	0.005	0.01	0.010	0.01	-0.08	
2412	1	Right	/	15.9	17	0.048	0.06	0.096	0.12	-0.10	
2412	1	Тор	/	15.9	17	0.062	0.08	0.121	0.16	0.03	
2412	1	Bottom	/	15.9	17	0.004	0.01	0.008	0.01	0.05	

Note1: The distance between the EUT and the phantom bottom is 10mm.

As shown above table, the <u>initial test position</u> for body is "Rear". So the body SAR of WLAN is presented as below:

Table 13.2: SAR Values (WLAN - Body) - 802.11b 1Mbps (Full SAR)

		А	mbient T	emperature	Liquid Tem	perature: 2	21.2°C			
Frequency Test Figure Conducted Max. tur		May tung up	Measured	Reported	Measured	Reported	Power			
	ı		Figure	Power	Max. tune-up	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)(Drift
MHz	Ch.	Position	No.	(dBm)	Power (dBm)	(W/kg)	(W/kg)	(W/kg)	W/kg)	(dB)
2412	1	Rear	Fig.1	15.9	17	0.135	0.17	0.272	0.35	0.04

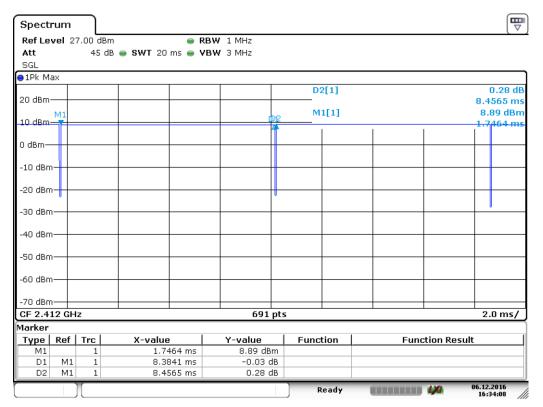
According to the KDB248227 D01, The reported SAR must be scaled to 100% transmission duty factor to determine compliance at the maximum tune-up tolerance limit. A maximum transmission duty factor of 99.14% is achievable for WLAN in this project and the scaled reported SAR is presented as below.

Table 13.3: SAR Values (WLAN - Body) – 802.11b 1Mbps (Scaled Reported SAR)

	Ambient Temperature: 21.7°C Liquid Temperature: 21.2°C											
Frequency Test Actual duty maximum duty Reported SAR Scaled reported SAR												
MHz	MHz Ch. Posit		factor	factor	(1g)(W/kg)	(1g)(W/kg)						
2412	1	Rear	99.14	100%	0.35	0.35						

SAR is not required for OFDM because the 802.11b adjusted SAR \leq 1.2 W/kg.





Date: 6.DEC.2016 16:34:08

Picture 13.1: The plot of duty factor



14 Measurement Uncertainty

14.1 Measurement Uncertainty for Normal SAR Tests (300MHz~3GHz)

	4.1 Wieasurement		anney for the	71111ai 07 ti t	. 0010	10001		, 				
No.	Error Description	Туре	Uncertainty value	Probably Distribution	Div.	(Ci) 1g	(Ci) 10g	Std. Unc. (1g)	Std. Unc. (10g)	Degree of freedom		
			Measu	rement syste	em							
1	Probe calibration	В	6	N	1	1	1	6	6	8		
2	Isotropy	В	4.7	R	$\sqrt{3}$	1	1	1.6	1.6	∞		
3	Boundary effect	В	1.0	R	$\sqrt{3}$	1	1	6.4	6.4	∞		
4	Linearity	В	4.7	R	$\sqrt{3}$	1	1	0.5	0.5	∞		
5	Detection limit	В	1.0	N	1	1	1	1	1	∞		
6	Readout electronics	В	0.3	R	$\sqrt{3}$	1	1	0.6	0.6	∞		
7	Response time	В	0.8	R	$\sqrt{3}$	1	1	0.0	0.0	∞		
8	Integration time	В	2.6	R	$\sqrt{3}$	1	1	1.0	1.0	∞		
9	RF ambient conditions-noise	В	0	R	$\sqrt{3}$	1	1	1.7	1.7	∞		
10	RF ambient conditions-reflection	В	0	R	$\sqrt{3}$	1	1	1.7	1.7	∞		
11	Probe positioned mech. restrictions	В	0.4	R	$\sqrt{3}$	1	1	0.2	0.2	∞		
12	Probe positioning with respect to phantom shell	В	2.9	R	$\sqrt{3}$	1	1	1.7	1.7	∞		
13	Post-processing	В	1.0	R	$\sqrt{3}$	1	1	1.2	1.2	∞		
14	Probe modulation response	В	2.3	R	$\sqrt{3}$	1	1	1.21	1.21	8		
Test sample related												
15	Test sample positioning	Α	3.3	N	1	1	1	3.3	3.3	5		
16	Device holder uncertainty	Α	3.4	N	1	1	1	3.4	3.4	5		
17	Power scaling	В	2.4	R	$\sqrt{3}$	1	1	2.4	2.4	∞		
18	Drift of output power	В	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	8		
			Phant	om and set-ι	ıp							
19	Phantom uncertainty	В	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	∞		
20	Liquid conductivity (target)	В	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	∞		
21	Liquid conductivity (meas.)	Α	2.06	N	1	0.64	0.43	1	0.28	9		
22	Liquid permittivity (target)	В	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4	∞		
23	Liquid permittivity (meas.)	Α	1.6	N	1	0.6	0.49	0.31	0.25	9		
24	Algorithm for correcting SAR for	В	1.9	N	1	1	1	1.9	1.9	∞		



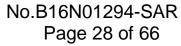
deviations in permittivity and conductivity						
Combined standard uncertainty	$u_{c}' = \sqrt{\sum_{i=1}^{21} c_{i}^{2} u_{i}^{2}}$			11.9	11.8	323
Expanded uncertainty (Confidence interval of 95 %)	$u_e = 2u_c$			23.8	23.7	



14.2 Measurement Uncertainty for Fast SAR Tests (300MHz~3GHz)

N Error Description	17	.2 Measurement Und		Inity for ra	St OAIT 163	13 (30	JOIVII I	Z~3G		T _	I		
No. Error Description Y Y Value Distribution 10 10 10 10 10 10 10 1			Т	Uncertaint	Probably		,	,	Std.	Std.	Degree		
Probe calibration Probe calibration Probe calibration B G N 1 1 1 1 1 1 1 1 1		Error Description	_		1	Div.	` '	` ,	Unc		1		
Note	0.			-			1g	10g		(10g	freedom		
1			е						(1g))			
2													
3 Boundary effect B 1.0 R √3 1 1 6.4 6.4 ∞											∞		
4 Linearity B 4.7 R √3 1 1 0.5 0.5 5 Detection limit B 1.0 R 1								1	1.6		∞		
5 Detection limit B 1.0 R 1 1 1 1 1 1 1 1 0 ∞ 6 Readout electronics B 0.3 R √3 1 1 0.6 0.6 ∞ 7 Response time B 0.8 R √3 1 1 0.0 0.0 ∞ 8 Integration time B 0.8 R √3 1 1 1.0 1.0 ∞ 9 RF ambient conditions-noise B 0 R √3 1 1 1.7 1.7 ∞ 10 RF ambient conditions-reliection B 0 R √3 1 1 1.7 1.7 ∞ 10 RF ambient conditions-reliection B 0.4 R √3 1 1 1.7 1.7 ∞ 11 Probe positioning with respect to phantom shell B 2.9 R √3	3	Boundary effect	В		R		1	1	6.4	6.4	∞		
6 Readout electronics B 0.3 R √3 1 1 0.6 0.6 ∞ 7 Response time B 0.8 R √3 1 1 0.0 0.0 ∞ 8 Integration time B 0.8 R √3 1 1 1.0 1.0 ∞ 9 RF ambient conditions-noise B 0 R √3 1 1 1.7 1.7 ∞ 10 RF ambient conditions-reflection B 0 R √3 1 1 1.7 1.7 ∞ 10 RF ambient conditions-reflection B 0 R √3 1 1 1.7 1.7 ∞ 11 Probe positioning with respect to phantom shell B 0.4 R √3 1 1 1.7 1.7 ∞ 13 Post-processing B 1.0 R √3 1 1 1.2 1.2	4	•					1		0.5	0.5	∞		
7 Response time B 0.8 R √3 1 1 0.0 0.0 ∞ 8 Integration time B 2.6 R √3 1 1 1.0 1.0 ∞ 9 RF ambient conditions-noise B 0 R √3 1 1 1.7 1.7 ∞ 10 RF ambient conditions-reflection B 0 R √3 1 1 1.7 1.7 ∞ 10 Probe positioned mech. Restrictions B 0.4 R √3 1 1 1.7 1.7 ∞ 11 Probe positioning with respect to phantom shell B 0.4 R √3 1 1 1.7 1.7 ∞ 12 respect to phantom shell B 2.9 R √3 1 1 1.7 1.7 ∞ 12 respect to phantom shell B 1.0 R √3 1 1 1.7	5	Detection limit	В	1.0	R	1	1	1	1	1	∞		
8 Integration time B 2.6 R √3 1 1 1.0 1.0 ∞ 9 RF ambient conditions-noise B 0 R √3 1 1 1.7 1.7 ∞ 10 RF ambient conditions-reflection B 0 R √3 1 1 1.7 1.7 ∞ 11 Probe positioned mech. Restrictions B 0.4 R √3 1 1 0.2 0.2 ∞ 12 Probe positioning with respect to phantom shell B 0.4 R √3 1 1 1.7 1.7 ∞ 13 Post-processing B 1.0 R √3 1 1 1.2 1.2 ∞ 14 Probe modulation response B 2.3 R √3 1 4.0 4.0 1 ∞ Test SAR 2-Approximation B 7.0 R √3 1 4.0 4.0 1 <td>6</td> <td>Readout electronics</td> <td>В</td> <td>0.3</td> <td>R</td> <td>$\sqrt{3}$</td> <td>1</td> <td>1</td> <td>0.6</td> <td>0.6</td> <td>∞</td>	6	Readout electronics	В	0.3	R	$\sqrt{3}$	1	1	0.6	0.6	∞		
9 RF ambient conditions-noise conditions-noise B 0 R √3 1 1 1.7 1.7 ∞ 10 RF ambient conditions-reflection conditions-reflection B 0 R √3 1 1 1.7 1.7 ∞ 11 Probe positioned mech. Restrictions B 0.4 R √3 1 1 0.2 0.2 ∞ Probe positioning with respect to phantom shell B 2.9 R √3 1 1 1.7 1.7 ∞ 13 Post-processing B 1.0 R √3 1 1 1.7 1.7 ∞ 14 Probe modulation response B 2.3 R √3 1 1 1.2 1.2 ∞ 15 Z-asynce B 7.0 R √3 1 1 1.2 1.2 ∞ Test sample related 16 Test sample positioning A 3.3 N 1 1 1 3.3 3.3 71 17 <t< td=""><td>7</td><td>Response time</td><td>В</td><td>0.8</td><td>R</td><td>$\sqrt{3}$</td><td>1</td><td>1</td><td>0.0</td><td>0.0</td><td>∞</td></t<>	7	Response time	В	0.8	R	$\sqrt{3}$	1	1	0.0	0.0	∞		
9 conditions-noise	8	-	В	2.6	R	$\sqrt{3}$	1	1	1.0	1.0	∞		
10	9	conditions-noise	В	0	R	$\sqrt{3}$	1	1	1.7	1.7	∞		
11 mech. Restrictions B 0.4 R √3 1 1 0.2 0.2 ∞	10	conditions-reflection	В	0	R	$\sqrt{3}$	1	1	1.7	1.7	∞		
12 respect to phantom shell B 2.9 R √3 1 1 1.7 1.7 ∞ 13 Post-processing B 1.0 R √3 1 1 1.2 1.2 ∞ 14 Probe modulation response B 2.3 R √3 1 1 1.2 1.21 ∞ 15 Fast SAR z-Approximation B 7.0 R √3 1 4.0 4.0 1 ∞ Test sample related 16 Test sample positioning A 3.3 N 1 1 1 3.3 3.3 71 17 Device holder uncertainty A 3.4 N 1 1 1 3.4 3.4 5 18 Power scaling B 2.2 R √3 1 1 2.2 2.2 ∞ 19 Drift of output power B 5.0 R √3 1 1 2.3 2.3 ∞ Phantom and set-up 21	11	mech. Restrictions	В	0.4	R	$\sqrt{3}$	1	1	0.2	0.2	∞		
14 Probe modulation response B 2.3 R √3 1 1 1.2 1.21 ∞ 15 Fast SAR z-Approximation B 7.0 R √3 1 4.0 4.0 1 ∞ Test Sample related 16 Test sample positioning A 3.3 N 1 1 1 3.3 3.3 71 17 Device holder uncertainty A 3.4 N 1 1 1 3.4 3.4 5 18 Power scaling B 2.2 R √3 1 1 2.2 2.2 ∞ 19 Drift of output power B 5.0 R √3 1 1 2.9 2.9 ∞ Phantom and set-up 20 Phantom uncertainty B 4.0 R √3 1 1 2.3 2.3 ∞ 21 Liquid conductivity (target) B 5.0 R √3 0.6 0.4 1.3 1.2 ∞ <	12	respect to phantom	В	2.9	R	$\sqrt{3}$	1	1	1.7	1.7	8		
14 response B 2.3 R $\sqrt{3}$ 1 1 1 1.21 ∞ 15 Fast SAR z-Approximation B 7.0 R $\sqrt{3}$ 1 4.0 4.0 1 ∞ Test sample positioning A 3.3 N 1 1 1 3.3 3.3 71 17 Device holder uncertainty A 3.4 N 1 1 1 3.4 3.4 5 18 Power scaling B 2.2 R $\sqrt{3}$ 1 1 2.2 2.2 ∞ 19 Drift of output power B 5.0 R $\sqrt{3}$ 1 1 2.9 2.9 ∞ Phantom and set-up 20 Phantom uncertainty B 4.0 R $\sqrt{3}$ 1 1 2.3 2.3 ∞ 21 Liquid conductivity (target) B 5.0 R $\sqrt{3}$ 0.6 0.4 1.3 1.2 ∞ 22 Liquid conductivity (meas.)	13	_	В	1.0	R	$\sqrt{3}$	1	1		1.2	∞		
Test sample related R $\sqrt{3}$ 1 4.0 4.0 1 ∞ Test sample positioning A 3.3 N 1 1 1 3.3 3.3 71 17 Device holder uncertainty A 3.4 N 1 1 1 3.4 3.4 5 18 Power scaling B 2.2 R $\sqrt{3}$ 1 1 2.2 2.2 ∞ 19 Drift of output power B 5.0 R $\sqrt{3}$ 1 1 2.9 2.9 ∞ Phantom and set-up 20 Phantom uncertainty B 4.0 R $\sqrt{3}$ 1 1 2.3 2.3 ∞ 21 Liquid conductivity (target) B 5.0 R $\sqrt{3}$ 0.6 0.4 1.3 1.2 ∞ 22 Liquid conductivity (meas.) A 2.06 N 1 0.6 0.4 1.7 1.	14		В	2.3	R	$\sqrt{3}$	1	1		1.21	∞		
16 Test sample positioning A 3.3 N 1 1 1 3.3 3.3 71 17 Device holder uncertainty A 3.4 N 1 1 1 3.4 3.4 5 18 Power scaling B 2.2 R √3 1 1 2.2 2.2 ∞ 19 Drift of output power B 5.0 R √3 1 1 2.9 2.9 ∞ Phantom and set-up 20 Phantom uncertainty B 4.0 R √3 1 1 2.3 2.3 ∞ 21 Liquid conductivity (target) B 5.0 R √3 0.6 0.4 1.3 1.2 ∞ 22 Liquid conductivity (meas.) A 2.06 N 1 0.6 0.4 1.3 2 0.89 43 23 Liquid permittivity (target) B 5.0 R √3 0.6 0.4 9 1.7 1.4 ∞	15		В	7.0	R	$\sqrt{3}$	1	4.0	4.0	1	∞		
16 Test sample positioning A 3.3 N 1 1 1 3.3 3.3 71 17 Device holder uncertainty A 3.4 N 1 1 1 3.4 3.4 5 18 Power scaling B 2.2 R √3 1 1 2.2 2.2 ∞ 19 Drift of output power B 5.0 R √3 1 1 2.9 2.9 ∞ Phantom and set-up 20 Phantom uncertainty B 4.0 R √3 1 1 2.3 2.3 ∞ 21 Liquid conductivity (target) B 5.0 R √3 0.6 0.4 1.3 1.2 ∞ 22 Liquid conductivity (meas.) A 2.06 N 1 0.6 0.4 1.3 2 0.89 43 23 Liquid permittivity (target) B 5.0 R √3 0.6 0.4 9 1.7 1.4 ∞	Tes	t sample related		<u> </u>	1	1	1	1	ı	ı	<u> </u>		
17 uncertainty A 3.4 N 1 1 1 3.4 3.4 5 18 Power scaling B 2.2 R $\sqrt{3}$ 1 1 2.2 2.2 ∞ 19 Drift of output power B 5.0 R $\sqrt{3}$ 1 1 2.9 2.9 ∞ Phantom and set-up 20 Phantom uncertainty B 4.0 R $\sqrt{3}$ 1 1 2.3 2.3 ∞ 21 Liquid conductivity (target) B 5.0 R $\sqrt{3}$ 0.6 0.4 1.8 1.2 ∞ 22 Liquid conductivity (meas.) A 2.06 N 1 0.6 4 3 2 0.89 43 23 Liquid permittivity (target) B 5.0 R $\sqrt{3}$ 0.6 0.4 9 1.7 1.4 ∞		Test sample positioning	Α	3.3	N	1	1	1	3.3	3.3	71		
19 Drift of output power B 5.0 R $\sqrt{3}$ 1 1 2.9 2.9 ∞ Phantom and set-up 20 Phantom uncertainty B 4.0 R $\sqrt{3}$ 1 1 2.3 2.3 ∞ 21 Liquid conductivity (target) B 5.0 R $\sqrt{3}$ 0.6 0.4 1.8 1.2 ∞ 22 Liquid conductivity (meas.) A 2.06 N 1 0.6 0.4 1.3 2 0.89 43 23 Liquid permittivity B 5.0 R $\sqrt{3}$ 0.6 0.4 0.4 0.8 0.8 0.8 43	17		Α	3.4	N	1	1	1	3.4	3.4	5		
Phantom and set-up 20 Phantom uncertainty B 4.0 R $\sqrt{3}$ 1 1 2.3 2.3 ∞ 21 Liquid conductivity (target) B 5.0 R $\sqrt{3}$ 0.6 0.4 1.8 1.2 ∞ 22 Liquid conductivity (meas.) A 2.06 N 1 0.6 0.4 1.3 0.89 43 23 Liquid permittivity (target) B 5.0 R $\sqrt{3}$ 0.6 0.4 9 1.7 1.4 ∞	18	Power scaling	В	2.2	R	$\sqrt{3}$	1	1	2.2	2.2	∞		
20 Phantom uncertainty B 4.0 R $\sqrt{3}$ 1 1 2.3 2.3 ∞ 21 Liquid conductivity (target) B 5.0 R $\sqrt{3}$ 0.6 0.4 1.8 1.2 ∞ 22 Liquid conductivity (meas.) A 2.06 N 1 0.6 0.4 1.3 2 0.89 43 23 Liquid permittivity (target) B 5.0 R $\sqrt{3}$ 0.6 0.4 9 1.7 1.4 ∞	19	Drift of output power	В	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	∞		
20 Phantom uncertainty B 4.0 R $\sqrt{3}$ 1 1 2.3 2.3 ∞ 21 Liquid conductivity (target) B 5.0 R $\sqrt{3}$ 0.6 0.4 1.8 1.2 ∞ 22 Liquid conductivity (meas.) A 2.06 N 1 0.6 0.4 1.3 2 0.89 43 23 Liquid permittivity (target) B 5.0 R $\sqrt{3}$ 0.6 0.4 9 1.7 1.4 ∞	Pha	ntom and set-up		I	1	1	ı	ı	I	I.	ı		
21 (target) B 5.0 R $\sqrt{3}$ 4 3 1.8 1.2 ∞ 22 Liquid conductivity (meas.) A 2.06 N 1 0.6 0.4 1.3 2 0.89 43 23 Liquid permittivity (target) B 5.0 R $\sqrt{3}$ 0.6 0.4 9 1.7 1.4 ∞		<u> </u>	В	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	∞		
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	21		В	5.0	R	$\sqrt{3}$			1.8	1.2	∞		
23 $\frac{1}{\text{(target)}}$ B 5.0 R $\sqrt{3}$ 0.6 9 1.7 1.4 ∞	22		Α	2.06	N	1				0.89	43		
24 Liquid permittivity A 1.6 N 1 0.6 0.4 1.0 0.8 521	23		В	5.0	R	$\sqrt{3}$	0.6		1.7	1.4	∞		
<u> </u>	24	Liquid permittivity	Α	1.6	N	1	0.6	0.4	1.0	0.8	521		

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	(meas.)						9			
25	Algorithm for correcting SAR for deviations in permittivity and conductivity	В	1.9	N	1	1	0.8	1.9	1.6	∞
Combined standard uncertainty		u_c	$= \sqrt{\sum_{i=1}^{22} c_i^2 u_i^2}$					12. 6	12.5	257
(Co	Expanded uncertainty (Confidence interval of 95 %)		$u_e = 2u_c$					25. 1	25.0	



15 MAIN TEST INSTRUMENTS

Table 15.1: List of Main Instruments

No.	Name	Туре	Serial Number	Calibration Date	Valid Period	
01	Network analyzer	Agilent E5071C	MY46103759	2015-11-20	One year	
02	Dielectric probe	85070E	MY44300317	/		
03	Power meter	NRP	102603	2016-01-10		
04	Power sensor	NRP-Z51	102211	2016-01-10	One year	
05	Signal Generator	E8257D	MY47461211	2016-06-15	One year	
06	Amplifier	VTL5400	0404	/		
07	Dipole Validation Kit	SPEAG D2450V2	873	2015-10-30	Three year	
08	E-field Probe	SPEAG EX3DV4	3633	2016-06-21	One year	
09	DAE	SPEAG DAE4	786	2015-11-16	One year	

END OF REPORT BODY



ANNEX A Graph Results

Wi-Fi 802.11b Body Rear Channel 1

Date/Time: 2016-11-9 Electronics: DAE4 Sn786 Medium: Body 2450 MHz

Medium parameters used: f = 2412 MHz; σ = 1.902 S/m; ϵ_r = 51.476; ρ = 1000 kg/m³

Ambient Temperature: 21.7°C Liquid Temperature: 21.2°C

Communication System: UID 0, WiFi (0) Frequency: 2412 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3633 ConvF (7.00, 7.00, 7.00);

Rear side Low /Area Scan (61x111x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Maximum value of SAR (interpolated) = 0.277 W/kg

Rear side Low /Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 3.21 V/m; Power Drift = 0.04 dB

Peak SAR (extrapolated) = 0.539 W/kg

SAR(1 g) = 0.272 W/kg; SAR(10 g) = 0.135 W/kg

Maximum value of SAR (measured) = 0.299 W/kg

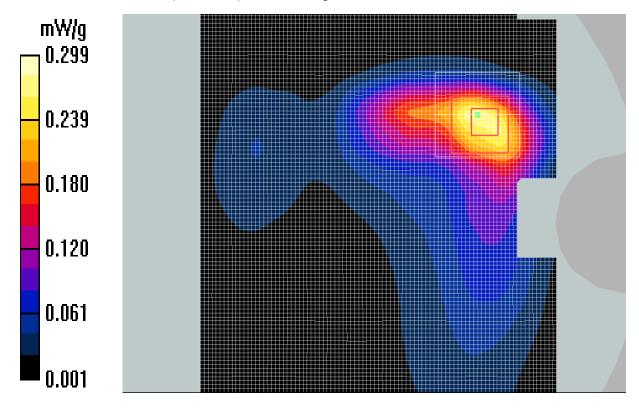


Fig.15 Wi-Fi 2450 MHz CH1



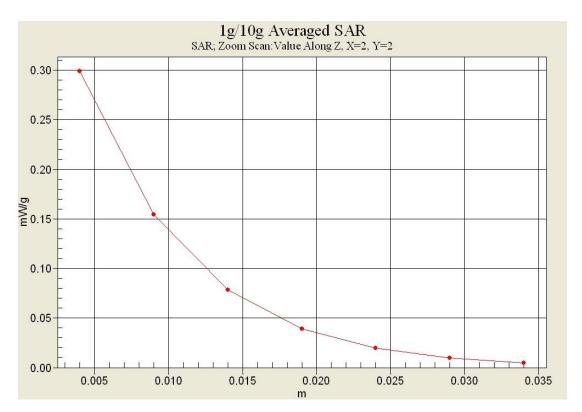


Fig.1-1 Z-Scan at power reference point (Wi-Fi 2450 MHz CH1)



ANNEX B SystemVerification Results

2450MHz

Date: 2016-11-9

Electronics: DAE4 Sn786 Medium: Body 2450 MHz

Medium parameters used: f = 2450 MHz; σ = 1.972 S/m; $ε_r$ = 53.152; ρ = 1000 kg/m³

Ambient Temperature: 22.0°C Liquid Temperature: 21.6°C Communication System: CW Frequency: 2450 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3633 ConvF (7.00, 7.00, 7.00)

System Validation/Area Scan (81x101x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Reference Value = 86.776 V/m; Power Drift = 0.04 dB

SAR(1 g) = 12.4 W/kg; SAR(10 g) = 5.79 W/kg

Maximum value of SAR (interpolated) = 14.1 W/kg

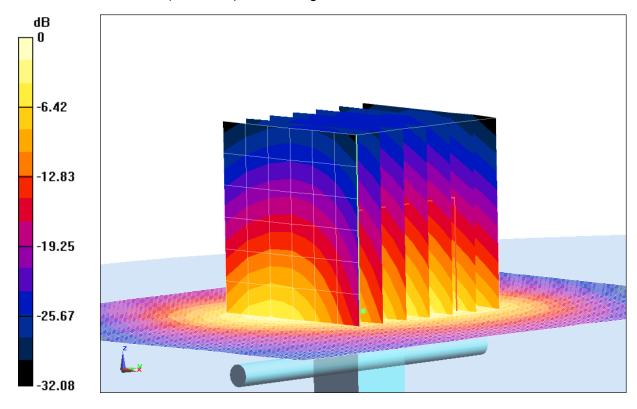
System Validation/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 86.776 V/m; Power Drift = 0.04 dB

Peak SAR (extrapolated) = 24.88 W/kg

SAR(1 g) = 12.6 W/kg; SAR(10 g) = 5.88 W/kg

Maximum value of SAR (measured) = 14.4 W/kg



0 dB = 14.4 W/kg = 11.58 dB W/kg

Fig.B.10validation 2450MHz 250mW



The SAR system verification must be required that the area scan estimated 1-g SAR is within 3% of the zoom scan 1-g SAR.

Table B.1 Comparison between area scan and zoom scan for system verification

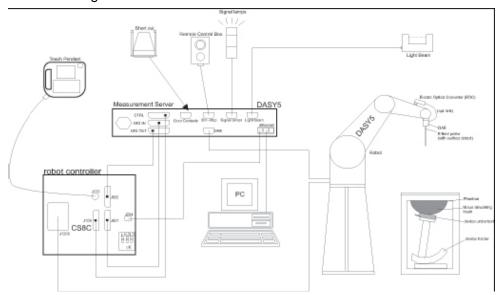
Date	Band	Position	Area scan (1g)	Zoom scan (1g)	Drift (%)
2016-11-09	2450	Body	12.4	12.6	1.61



ANNEX C SAR Measurement Setup

C.1 Measurement Set-up

DASY5 system for performing compliance tests is illustrated above graphically. This system consists of the following items:



Picture C.1 SAR Lab Test Measurement Set-up

- A standard high precision 6-axis robot (Stäubli TX=RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc.
 The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals
 for the digital communication to the DAE. To use optical surface detection, a special version of
 the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running Win XP and the DASY5 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as
- warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.



C.2 DASY5 E-field Probe System

The SAR measurements were conducted with the dosimetric probe designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY5 software reads the reflection durning a software approach and looks for the maximum using 2ndord curve fitting. The approach is stopped at reaching the maximum.

Probe Specifications:

Model: ES3DV3, EX3DV4

Frequency 10MHz — 6.0GHz(EX3DV4) Range: 10MHz — 4GHz(ES3DV3)

Calibration: In head and body simulating tissue at

Frequencies from 835 up to 5800MHz

Linearity: $\pm 0.2 \text{ dB}(30 \text{ MHz to 6 GHz}) \text{ for EX3DV4}$

± 0.2 dB(30 MHz to 4 GHz) for ES3DV3

Dynamic Range: 10 mW/kg — 100W/kg

Probe Length: 330 mm

Probe Tip

Length: 20 mm Body Diameter: 12 mm

Tip Diameter: 2.5 mm (3.9 mm for ES3DV3)
Tip-Center: 1 mm (2.0mm for ES3DV3)
Application: SAR Dosimetry Testing

Compliance tests of mobile phones

Dosimetry in strong gradient fields



Picture C.2 Near-field Probe



Picture C.3 E-field Probe

C.3 E-field Probe Calibration

Each E-Probe/Probe Amplifier combination has unique calibration parameters. A TEM cell calibration procedure is conducted to determine the proper amplifier settings to enter in the probe parameters. The amplifier settings are determined for a given frequency by subjecting the probe to a known E-field density (1 mW/cm²) using an RF Signal generator, TEM cell, and RF Power Meter.

The free space E-field from amplified probe outputs is determined in a test chamber. This calibration can be performed in a TEM cell if the frequency is below 1 GHz and inn a waveguide or other methodologies above 1 GHz for free space. For the free space calibration, the probe is placed ©Copyright. All rights reserved by CTTL.