



A collection of robotic components is laid out on a blue surface next to a wooden ruler. The components include a Pioneer 3-DX mobile base, a 3D sensor (likely a Kinect), a laser range finder (LRF), a camera, a battery pack, a power supply, and various cables. The items are arranged in a grid-like fashion for documentation.

Fig. 1



Fig. 2



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Fig. 3



Fig. 4





Fig. 5



Fig. 6





Fig. 7



Fig. 8





Fig. 9



Fig. 10





Fig. 11



Fig. 12





Fig. 13

