

SAR Test Report

Report No.: AGC15705250411FH01

FCC ID : 2AJ551865RY2

APPLICATION PURPOSE : Original Equipment

PRODUCT DESIGNATION : RC quadcopter

BRAND NAME : N/A

MODEL NAME : HS600, HS360E, HS360D, HS600-RID, HS600D, HS600D-RID, HS920, HS600Pro, HS600Plus, HS600G, HS600S, HS600L, HS360G, HS360L, HS360F, HS360C, HS360mini, HS360Pro, HS360Plus, RC244A

APPLICANT : Xiamen Huoshiquan Import & Export CO.,LTD.

DATE OF ISSUE : Jul. 23, 2025

STANDARD(S) : IEEE Std. 1528:2013
FCC 47 CFR Part 2§2.1093
IEEE Std C95.1™-2019

REPORT VERSION : V1.0

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Report Revise Record

Report Version	Revise Time	Issued Date	Valid Version	Notes
V1.0	/	Jul. 23, 2025	Valid	Initial Release

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Test Report	
Applicant Name	Xiamen Huoshiquan Import & Export CO.,LTD.
Applicant Address	Unit 1, Room 501, Hongxiang Building, No.258 Hubin Nan Road, Siming District, Xiamen, Fujian, China
Manufacturer Name	Xiamen Huoshiquan Import & Export CO.,LTD.
Manufacturer Address	Unit 1, Room 501, Hongxiang Building, No.258 Hubin Nan Road, Siming District, Xiamen, Fujian, China
Factory Name	Xiamen Huoshiquan Import & Export CO.,LTD.
Factory Address	Unit 1, Room 501, Hongxiang Building, No.258 Hubin Nan Road, Siming District, Xiamen, Fujian, China
Product Designation	RC quadcopter
Brand Name	N/A
Model Name	HS600
Seriws Model	HS360E, HS360D, HS600-RID, HS600D, HS600D-RID, HS920, HS600Pro, HS600Plus, HS600G, HS600S, HS600L, HS360G, HS360L, HS360F, HS360C, HS360mini, HS360Pro, HS360Plus, RC244A
Different Description	There are differences in appearance color, but the internal circuits are exactly the same.
EUT Voltage	DC 14.8V(7.4V*2) 550 mAh by battery
Applicable Standard	IEEE Std. 1528:2013 FCC 47 CFR Part 2§2.1093 IEEE Std C95.1™-2019
Date of receipt of test item	Apr. 25, 2025
Test Date	Jul. 01, 2025 to Jul. 02, 2025
Report Template	AGCRT-US-5G/SAR (2021-04-20)

Note: The results of testing in this report apply to the product/system which was tested only.

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Jul. 23, 2025

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Jul. 23, 2025

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Jul. 23, 2025

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TABLE OF CONTENTS

1. SUMMARY OF MAXIMUM SAR VALUE	5
2. GENERAL INFORMATION.....	6
2.1. EUT DESCRIPTION.....	6
3. SAR MEASUREMENT SYSTEM.....	7
3.1. THE SATIMO SYSTEM USED FOR PERFORMING COMPLIANCE TESTS CONSISTS OF FOLLOWING ITEMS	7
3.2. COMOSAR E-FIELD PROBE	8
3.3. ROBOT.....	8
3.4. VIDEO POSITIONING SYSTEM	9
3.5. DEVICE HOLDER	9
3.6. SAM TWIN PHANTOM.....	10
4. SAR MEASUREMENT PROCEDURE.....	11
4.1. SPECIFIC ABSORPTION RATE (SAR).....	11
4.2. SAR MEASUREMENT PROCEDURE	12
4.3. RF EXPOSURE CONDITIONS	14
5. TISSUE SIMULATING LIQUID.....	15
5.1. THE COMPOSITION OF THE TISSUE SIMULATING LIQUID.....	15
5.2. TISSUE DIELECTRIC PARAMETERS FOR HEAD AND BODY PHANTOMS	15
5.3. TISSUE CALIBRATION RESULT	16
6. SAR SYSTEM CHECK PROCEDURE	17
6.1. SAR SYSTEM CHECK PROCEDURES	17
6.2. SAR SYSTEM CHECK.....	18
7. EUT TEST POSITION.....	20
7.1. BODY WORN POSITION	20
8. SAR EXPOSURE LIMITS	21
9. TEST FACILITY	22
10. TEST EQUIPMENT LIST	23
11. MEASUREMENT UNCERTAINTY	24
12. CONDUCTED POWER MEASUREMENT.....	27
13. TEST RESULTS.....	28
13.1. SAR TEST RESULTS SUMMARY.....	28
APPENDIX A. SAR SYSTEM CHECK DATA	30
APPENDIX B. SAR MEASUREMENT DATA.....	34
APPENDIX C. TEST SETUP PHOTOGRAPHS.....	38
APPENDIX D. CALIBRATION DATA	41

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1. SUMMARY OF MAXIMUM SAR VALUE

The maximum results of Specific Absorption Rate (SAR) found during testing for EUT are as follows:

Frequency Band	Highest Reported 10-g extremity SAR	SAR Test Limit (W/kg)
	Hand (with 0mm separation)	
5.2 GHz WIFI	0.829	4.0
5.8 GHz WIFI	0.923	
SAR Test Result	PASS	

This device is compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (4.0W/kg) specified in IEEE Std. 1528:2013; FCC 47CFR § 2.1093; IEEE Std C95.1™-2019 and the following specific FCC Test Procedures:

- KDB 447498 D01 General RF Exposure Guidance v06
- KDB 865664 D01 SAR Measurement 100MHz to 6GHz v01r04
- KDB 248227 D01 802 11 Wi-Fi SAR v02r02

Note: This standard FCC 47 CFR Part 2§2.1093 is not within the A2LA control range.

2. GENERAL INFORMATION

2.1. EUT Description

General Information	
Product Designation	RC quadcopter
Test Model	HS600
Hardware Version	V1.0
Software Version	V1.0
Device Category	Portable
RF Exposure Environment	Uncontrolled
Antenna Type	Monopole antenna
5GHz WIFI	
WIFI Specification	<input checked="" type="checkbox"/> 802.11a
Operation Frequency	U-NII-1: 5180MHz~5240MHz; U-NII-3: 5745MHz~5825MHz
Type of modulation	802.11a:(64-QAM, 16-QAM, QPSK, BPSK) OFDM
Avg. Burst Power	U-NII-1: 11.24dBm; U-NII-3: 11.91dBm
Antenna Gain	4.82 dBi

Note: 1.The sample used for testing is end product.

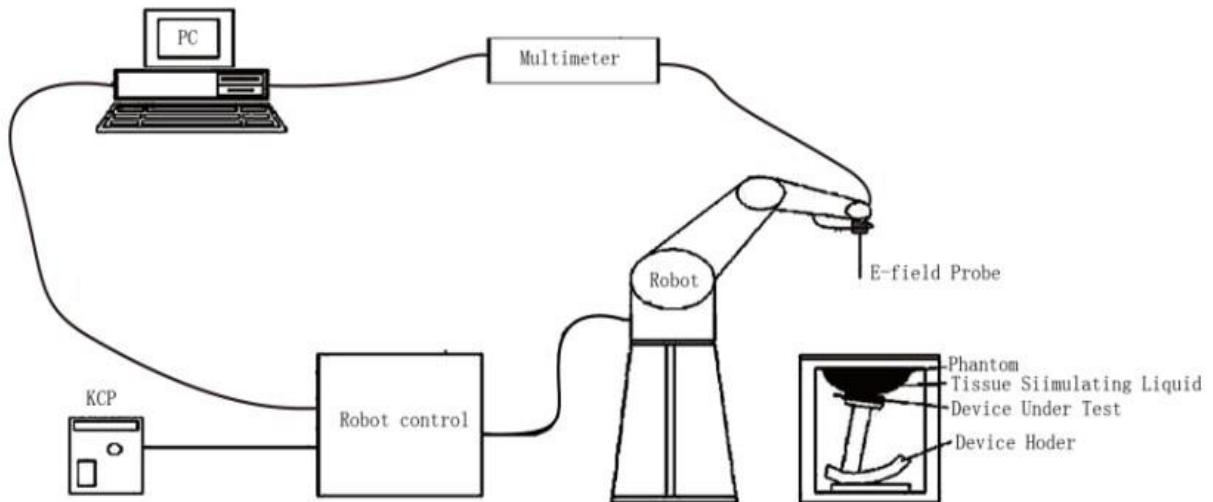
2. The test sample has no any deviation to the test method of standard mentioned in page 1.

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3. SAR MEASUREMENT SYSTEM

3.1. The SATIMO system used for performing compliance tests consists of following items



The COMOSAR system for performing compliance tests consists of the following items:


- The PC. It controls most of the bench devices and stores measurement data. A computer running WinXP and the Opensar software.
- The E-Field probe. The probe is a 3-axis system made of 3 distinct dipoles. Each dipole returns a voltage in function of the ambient electric field.
- The Keithley multimeter measures each probe dipole voltages.
- The SAM phantom simulates a human head. The measurement of the electric field is made inside the phantom.
- The liquids simulate the dielectric properties of the human head tissues.
- The network emulator controls the mobile phone under test.
- The validation dipoles are used to measure a reference SAR. They are used to periodically check the bench to make sure that there is no drift of the system characteristics over time.
- The phantom, the device holder and other accessories according to the targeted measurement.

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3.2. COMOSAR E-Field Probe

The SAR measurement is conducted with the dosimetric probe manufactured by SATIMO. The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. SATIMO conducts the probe calibration in compliance with international and national standards (e.g. IEEE1528 etc.) Under ISO17025. The calibration data are in Appendix D.

Isotropic E-Field Probe Specification

Model	SSE2	
Manufacture	MVG	
Identification No.	2023-EPGO-414	
Frequency	0.15GHz-7.5GHz Linearity:±0.10dB(0.15GHz-7.5GHz)	
Dynamic Range	0.01W/kg-100W/kg Linearity:±0.10dB	
Dimensions	Overall length:330mm Length of individual dipoles:2mm Maximum external diameter:8mm Probe Tip external diameter:2.5mm Distance between dipoles/ probe extremity:1mm	
Application	High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 6 GHz with precisin of better 30%.	

3.3. Robot

The COMOSAR system uses the KUKA robot from SATIMO SA (France). For the 6-axis controller COMOSAR system, the KUKA robot controller version from SATIMO is used.

The XL robot series have many features that are important for our application:

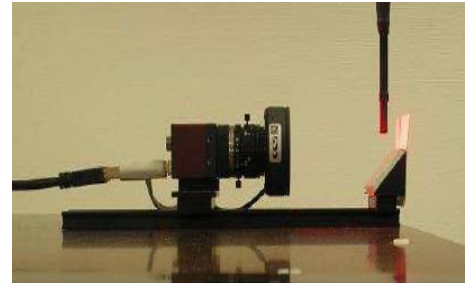
- ☐ High precision (repeatability 0.02 mm)
- ☐ High reliability (industrial design)
- ☐ Jerk-free straight movements
- ☐ Low ELF interference (the closed metallic construction shields against motor control fields)
- ☐ 6-axis controller



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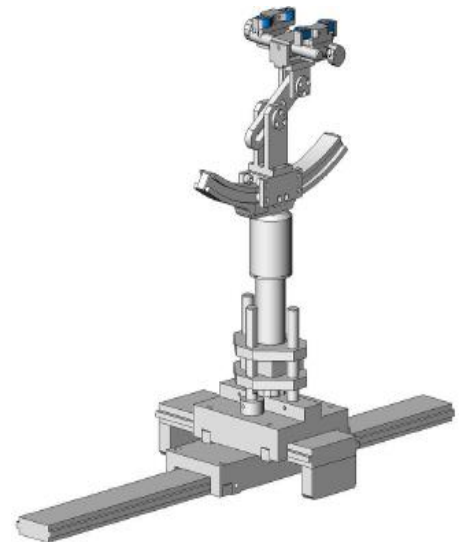
3.4. Video Positioning System

The video positioning system is used in OpenSAR to check the probe. Which is composed of a camera, LED, mirror and mechanical parts. The camera is piloted by the main computer with firewire link. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip. The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.



3.5. Device Holder

The COMOSAR device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR). Thus the device needs no repositioning when changing the angles. The COMOSAR device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity $\epsilon_r = 3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



3.6. SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

- ☐ Left head
- ☐ Right head
- ☐ Flat phantom



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

ELLI39 Phantom

The Flat phantom is a fiberglass shell phantom with 2mm+/- 0.2 mm shell thickness. It has only one measurement area for Flat phantom



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4. SAR MEASUREMENT PROCEDURE

4.1. Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and occupational/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element(dv) of given mass density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dV} \right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR can be obtained using either of the following equations:

$$SAR = \frac{\sigma E^2}{\rho}$$

$$SAR = c_h \left. \frac{dT}{dt} \right|_{t=0}$$

Where

SAR	is the specific absorption rate in watts per kilogram;
E	is the r.m.s. value of the electric field strength in the tissue in volts per meter;
σ	is the conductivity of the tissue in siemens per metre;
ρ	is the density of the tissue in kilograms per cubic metre;
c _h	is the heat capacity of the tissue in joules per kilogram and Kelvin;

$\left. \frac{dT}{dt} \right|_{t=0}$ is the initial time derivative of temperature in the tissue in kelvins per second

4.2. SAR Measurement Procedure

Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurement are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface is 2.7mm This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties,

Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in SATIMO software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in db) is specified in the standards for compliance testing. For example, a 2db range is required in IEEE Standard 1528 standards, whereby 3db is a requirement when compliance is assessed in accordance with the ARIB standard (Japan) If one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximum are detected, the number of Zoom Scan has to be increased accordingly.

Area Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100MHz to 6GHz

	$\leq 3 \text{ GHz}$	$> 3 \text{ GHz}$
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	$5 \pm 1 \text{ mm}$	$\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5 \text{ mm}$
Maximum probe angle from probe axis to phantom surface normal at the measurement location	$30^\circ \pm 1^\circ$	$20^\circ \pm 1^\circ$
Maximum area scan spatial resolution: $\Delta x_{\text{Area}}, \Delta y_{\text{Area}}$	$\leq 2 \text{ GHz}: \leq 15 \text{ mm}$ $2 - 3 \text{ GHz}: \leq 12 \text{ mm}$	$3 - 4 \text{ GHz}: \leq 12 \text{ mm}$ $4 - 6 \text{ GHz}: \leq 10 \text{ mm}$
	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be \leq the corresponding x or y dimension of the test device with at least one measurement point on the test device.	

Step 3: Zoom Scan

Zoom Scan are used to assess the peak spatial SAR value within a cubic average volume containing 1g and 10g of simulated tissue. The Zoom Scan measures points(refer to table below) within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1g and 10g and displays these values next to the job's label.

Zoom Scan Parameters extracted from KDB865664 d01 SAR Measurement 100MHz to 6GHz

Maximum zoom scan spatial resolution: Δx_{Zoom} , Δy_{Zoom}			$\leq 2 \text{ GHz}: \leq 8 \text{ mm}$ $2 - 3 \text{ GHz}: \leq 5 \text{ mm}^*$	$3 - 4 \text{ GHz}: \leq 5 \text{ mm}^*$ $4 - 6 \text{ GHz}: \leq 4 \text{ mm}^*$
Maximum zoom scan spatial resolution, normal to phantom surface	uniform grid: $\Delta z_{Zoom}(n)$		$\leq 5 \text{ mm}$	$3 - 4 \text{ GHz}: \leq 4 \text{ mm}$ $4 - 5 \text{ GHz}: \leq 3 \text{ mm}$ $5 - 6 \text{ GHz}: \leq 2 \text{ mm}$
	graded grid	$\Delta z_{Zoom}(1)$: between 1 st two points closest to phantom surface	$\leq 4 \text{ mm}$	$3 - 4 \text{ GHz}: \leq 3 \text{ mm}$ $4 - 5 \text{ GHz}: \leq 2.5 \text{ mm}$ $5 - 6 \text{ GHz}: \leq 2 \text{ mm}$
		$\Delta z_{Zoom}(n>1)$: between subsequent points	$\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$	
Minimum zoom scan volume	x, y, z		$\geq 30 \text{ mm}$	$3 - 4 \text{ GHz}: \geq 28 \text{ mm}$ $4 - 5 \text{ GHz}: \geq 25 \text{ mm}$ $5 - 6 \text{ GHz}: \geq 22 \text{ mm}$
Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.				
* When zoom scan is required and the <u>reported</u> SAR from the <i>area scan based 1-g SAR estimation</i> procedures of KDB 447498 is $\leq 1.4 \text{ W/kg}$, $\leq 8 \text{ mm}$, $\leq 7 \text{ mm}$ and $\leq 5 \text{ mm}$ zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.				

Step 4: Power Drift Measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the same settings. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

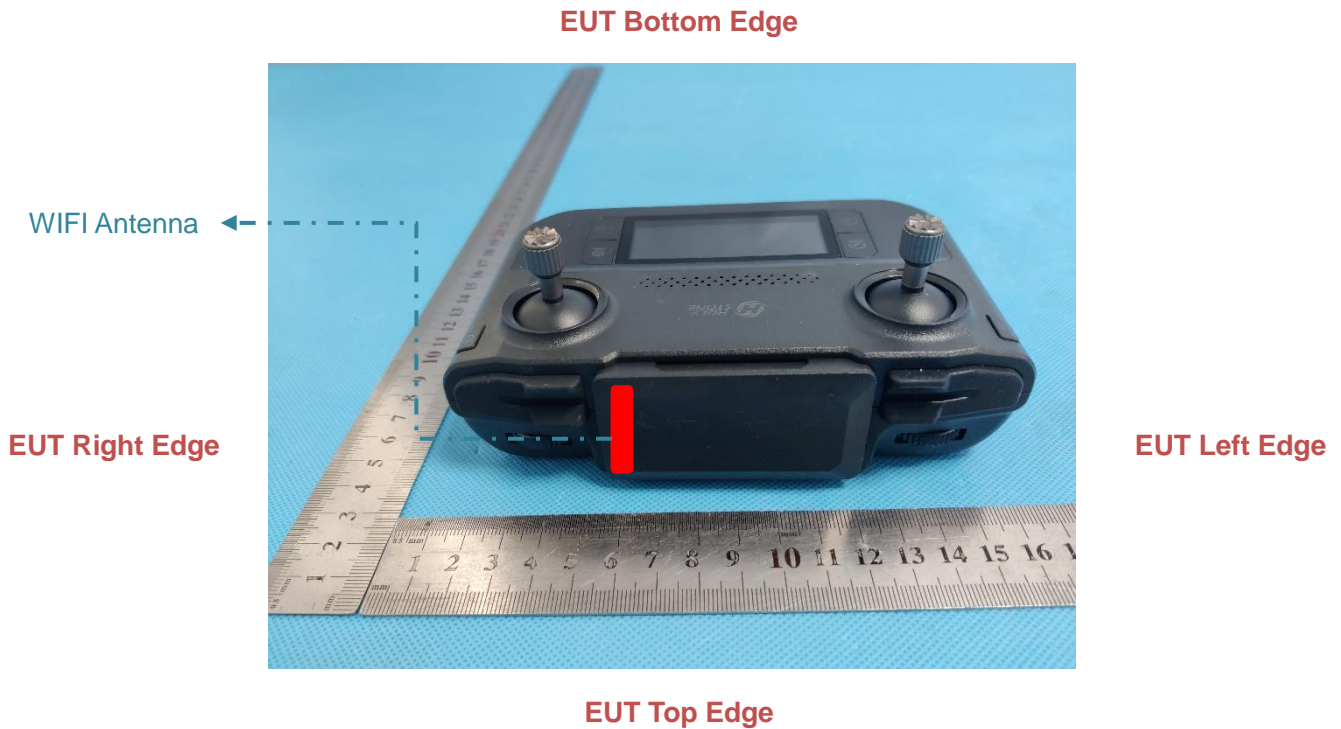
4.3. RF Exposure Conditions

Test Configuration and setting:

The device is a RC quadcopter which support 5.2GHz and 5.8GHz technology.

For SAR testing, the device was controlled by software to test at reference fixed frequency points.

EUT Antenna Location: (the top view)



Test Configurations	Antenna to edges/surface	SAR required
Back	2mm	Yes
Front	2mm	Yes
Edge 1 (Top)	2mm	Yes
Edge 2 (Right)	42mm	No
Edge 3 (Bottom)	105mm	No
Edge 4 (Left)	100mm	No

Note: SAR is measured for all sides and surfaces with a transmitting antenna located within 25 mm from that surface or edge.

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5. TISSUE SIMULATING LIQUID

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 5% are listed in 5.2

5.1. The composition of the tissue simulating liquid

Ingredient (% Weight) Frequency (MHz)	Water	NaCl	Polysorbate 20	DGBE	1,2- Propanediol	Triton X-100	Diethylen glycol monohex ylether
5000 Head	65.52	0.0	0.0	0.0	0.0	17.24	17.24

5.2. Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEEE 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in IEEE 1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations described in Reference [12] and extrapolated according to the head parameters specified in IEEE 1528.

Target Frequency (MHz)	head		body	
	ϵ_r	σ (S/m)	ϵ_r	σ (S/m)
300	45.3	0.87	45.3	0.87
450	43.5	0.87	43.5	0.87
835	41.5	0.90	41.5	0.90
900	41.5	0.97	41.5	0.97
1450	40.5	1.20	40.5	1.20
1800 – 2000	40.0	1.40	40.0	1.40
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	38.5	2.40
5200	36.0	4.66	49.0	5.30
5300	35.9	4.76	48.9	5.42
5600	35.5	5.07	48.5	5.77
5800	35.3	5.27	48.2	6.00

(ϵ_r = relative permittivity, σ = conductivity and ρ = 1000 kg/m³)

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5.3. Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using SATIMO Dielectric Probe Kit and R&S Network Analyzer ZVL6.

Tissue Stimulant Measurement for 5200MHz							
Head	Fr. (MHz)	Dielectric Parameters ($\pm 5\%$)		Ambient Temp [°C]	Relative Humidity (%)	Tissue Temp [°C]	Test time
		ϵ_r 36.0 (34.105-37.695)	δ [s/m] 4.66 (4.427-4.893)				
	5200	36.21	4.62	21.8	59.6	21.4	Jul. 01, 2025

Tissue Stimulant Measurement for 5800MHz							
Head	Fr. (MHz)	Dielectric Parameters ($\pm 5\%$)		Ambient Temp [°C]	Relative Humidity (%)	Tissue Temp [°C]	Test time
		ϵ_r 35.3 (33.535-37.065)	δ [s/m] 5.27 (5.0065-5.5335)				
	5785	35.06	5.15	22.5	55.2	22.3	Jul. 02, 2025
	5800	34.77	5.18				

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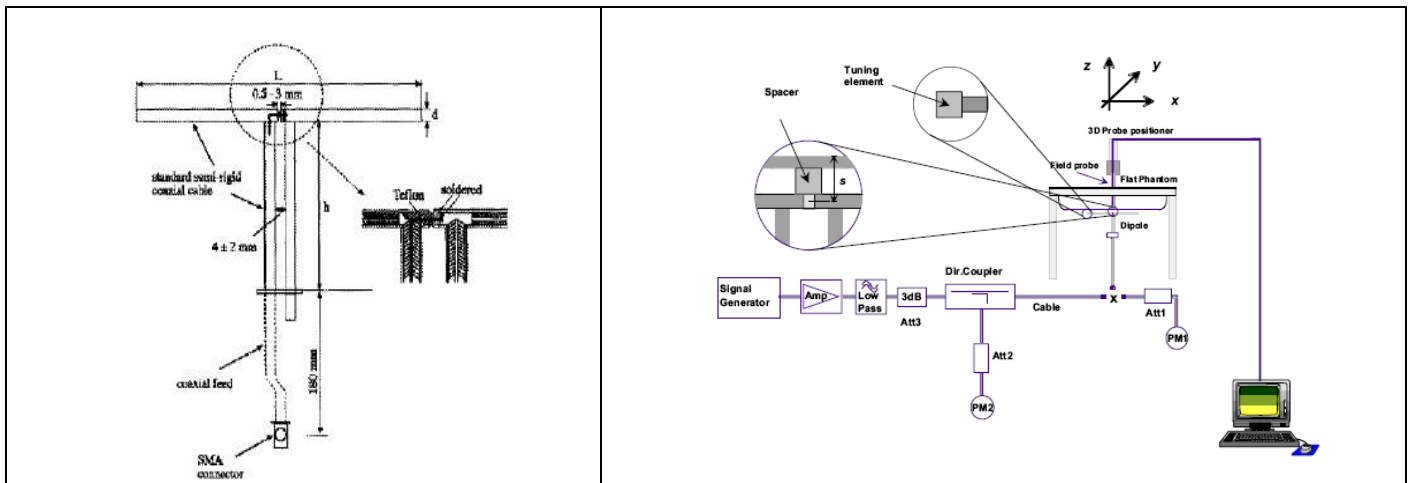
6. SAR SYSTEM CHECK PROCEDURE

6.1. SAR System Check Procedures

SAR system check is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device. The same SAR probe(s) and tissue-equivalent media combinations used with each specific SAR system for system verification must be used for device testing. When multiple probe calibration points are required to cover substantially large transmission bands, independent system verifications are required for each probe calibration point. A system verification must be performed before each series of SAR measurements using the same probe calibration point and tissue-equivalent medium. Additional system verification should be considered according to the conditions of the tissue-equivalent medium and measured tissue dielectric parameters, typically every three to four days when the liquid parameters are remeasured or sooner when marginal liquid parameters are used at the beginning of a series of measurements.

Each SATIMO system is equipped with one or more system check kits. These units, together with the predefined measurement procedures within the SATIMO software, enable the user to conduct the system check and system validation. System kit includes a dipole, and dipole device holder.


The system check verifies that the system operates within its specifications. It's performed daily or before every SAR measurement. The system check uses normal SAR measurement in the flat section of the phantom with a matched dipole at a specified distance. The system check setup is shown as below.



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6.2. SAR System Check

6.2.1. Dipoles

	<p>The dipole is based on the IEEE-1528 standard, and is complied with mechanical and electrical specifications in line with the requirements of IEEE. The table below provides details for the mechanical and electrical specifications for the wave guide.</p>
---	--

Frequency	L (mm)	h (mm)	d (mm)
5000MHz	20.6	40.3	3.6

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6.2.2. System Check Result

System Performance Check at 5200-5800MHz for Head							
Validation Kit: SN 1722 DIP 5G000-671							
Frequency [MHz]	Target Value(W/kg)		Reference Result ($\pm 10\%$)		Normalized to 1W(W/kg)		Test time
	1g	10g	1g	10g	1g	10g	
5200	77.74	22.60	69.97-85.51	20.34-24.86	77.90	22.30	Jul. 01, 2025
5800	75.01	21.84	67.51-82.51	19.66-24.02	78.20	23.40	Jul. 02, 2025

Note:

(1) We use a CW signal of 10dBm for system check, and then all SAR values are normalized to 1W forward power. The result must be within $\pm 10\%$ of target value.

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7. EUT TEST POSITION

This EUT was tested in **Hand back, Hand front and Edge 1 (Top)**.

7.1. Body Worn Position

- (1) To position the EUT parallel to the phantom surface.
- (2) To adjust the EUT parallel to the flat phantom.
- (3) To adjust the distance between the EUT surface and the flat phantom to **0mm**.

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8. SAR EXPOSURE LIMITS

Limits for General Population/Uncontrolled Exposure (W/kg)

Type Exposure	Uncontrolled Environment Limit (W/kg)
Spatial Peak SAR (1 g cube tissue for brain or body)	1.60
Spatial Average SAR (Whole body)	0.08
Spatial Peak SAR (Limbs)	4.0

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9. TEST FACILITY

Test Site	Attestation of Global Compliance (Shenzhen) Co., Ltd
Location	1-2/F, Building 19, Junfeng Industrial Park, Chongqing Road, Heping Community, Fuhai Street, Bao'an District, Shenzhen, Guangdong, China
Designation Number	CN1259
FCC Test Firm Registration Number	975832
A2LA Cert. No.	5054.02
Description	Attestation of Global Compliance(Shenzhen) Co., Ltd is accredited by A2LA

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10. TEST EQUIPMENT LIST

No.	Equipment description	Manufacturer/ Model	Identification No.	Software version	Current calibration date	Next calibration date
AGC-HE-A103	SAR Probe	MVG	2023-EPGO-414	N/A	2025-05-06	2026-05-05
AGC-HE-A071	Phantom	SATIMO	SN_2316_ELLI39	N/A	Validated. No cal required.	Validated. No cal required.
AGC-HE-A073	Multimeter	Keithley 2000	4114939	N/A	2025-05-16	2026-05-15
AGC-HE-S003	SAR Software	MVG-OpenSAR	N/A	V5.3.15.8	N/A	N/A
AGC-HE-A101	Dipole	SID5000	SN 1722 DIP 5G000-671	N/A	2025-05-16	2028-05-15
AGC-HE-E021	Signal Generator	Agilent-E4438C	US41461365	V5.03	2025-05-21	2026-05-20
AGC-EM-E061	EXA Signal Analyzer	Agilent / N9010A	MY53470504	N/A	2025-05-08	2026-05-07
AGC-HE-E004	Network Analyzer	Rhode & Schwarz ZVL6	101443	3.2	2024-07-24	2025-07-23
AGC-ER-A001	Attenuator	SMA-JK	N/A	N/A	2023-09-21	2025-09-20
AGC-EM-E019	Amplifier	AS0104-55_55	1004793	N/A	N/A	N/A
AGC-EM-E040	Directional Couple	Werlatone/ C5571-10	SN99463	N/A	2024-02-01	2026-01-31
AGC-EM-E041	Directional Couple	Werlatone/ C6026-10	SN99482	N/A	2024-02-01	2026-01-31
AGC-BQ-E016	Power Sensor	NRP-Z21	104604	N/A	2025-05-16	2026-05-15
AGC-HE-E023	Power Sensor	NRP-Z23	100323	N/A	2025-01-14	2026.01-13
AGC-HE-S004	Power Viewer	R&S	V2.3.1.0		N/A	N/A
AGC-HE-A001	Calibration standard parts for network sub - port	R&S/ ZV-Z132	100707	V2.3.1.0	2024-11-08	2025-11-07
AGC-HE-A002	Thermometer	DigiMate/TP677	3811930452	N/A	2025-05-24	2027-05-23

Note: Per IEC/IEEE 62209-1528 Dipole SAR Validation, AGC Lab has adopted 3 years calibration intervals. On annual basis, every measurement dipole has been evaluated and is in compliance with the following criteria:

1. There is no physical damage on the dipole;
2. System validation with specific dipole is within 10% of calibrated value;
3. Return-loss is within 20% of calibrated measurement;
4. Impedance is within 5Ω of calibrated measurement.

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11. MEASUREMENT UNCERTAINTY

SATIMO Uncertainty- 2023-EPGO-414 Measurement uncertainty for DUT averaged over 1 gram / 10 gram.									
Uncertainty Component	Sec.	Tol (+-%)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	vi
Measurement System									
Probe calibration	E.2.1	7.000	N	1	1	1	7.000	7.000	∞
Axial Isotropy	E.2.2	0.105	R	1.732	0.707	0.707	0.043	0.043	∞
Hemispherical Isotropy	E.2.2	0.105	R	1.732	0.707	0.707	0.043	0.043	∞
Boundary effect	E.2.3	1.000	R	1.732	1	1	0.577	0.577	∞
Linearity	E.2.4	1.105	R	1.732	1	1	0.638	0.638	∞
System detection limits	E.2.4	1.000	R	1.732	1	1	0.577	0.577	∞
Modulation response	E.2.5	3.000	R	1.732	1	1	1.732	1.732	∞
Readout Electronics	E.2.6	0.021	N	1	1	1	0.021	0.021	∞
Response Time	E.2.7	0.000	R	1.732	1	1	0.000	0.000	∞
Integration Time	E.2.8	1.400	R	1.732	1	1	0.808	0.808	∞
RF ambient conditions-Noise	E.6.1	3.000	R	1.732	1	1	1.732	1.732	∞
RF ambient conditions-reflections	E.6.1	3.000	R	1.732	1	1	1.732	1.732	∞
Probe positioner mechanical tolerance	E.6.2	1.400	R	1.732	1	1	0.808	0.808	∞
Probe positioning with respect to phantom shell	E.6.3	1.400	R	1.732	1	1	0.808	0.808	∞
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.300	R	1.732	1	1	1.328	1.328	∞
Test sample Related									
Test sample positioning	E.4.2	2.6	N	1	1	1	2.60	2.60	∞
Device holder uncertainty	E.4.1	3	N	1	1	1	3.00	3.00	∞
Output power variation—SAR drift measurement	E.2.9	5	R	1.732	1	1	2.89	2.89	∞
SAR scaling	E.6.5	5	R	1.732	1	1	2.89	2.89	∞
Phantom and tissue parameters									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	1.732	1	1	2.309	2.309	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.900	1.596	∞
Liquid conductivity measurement	E.3.3	4	N	1	0.78	0.71	3.120	2.840	M
Liquid permittivity measurement	E.3.3	5	N	1	0.23	0.26	1.150	1.300	M
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	1.732	0.78	0.71	1.126	1.025	∞
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	1.732	0.23	0.26	0.332	0.375	∞
Combined Standard Uncertainty			RSS				10.533	10.348	
Expanded Uncertainty (95% Confidence interval)			K=2				21.065	20.695	

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SATIMO Uncertainty- 2023-EPGO-414									
System Validation uncertainty for DUT averaged over 1 gram / 10 gram.									
Uncertainty Component	Sec.	Tol (+-%)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	vi
Measurement System									
Probe calibration	E.2.1	7.000	N	1	1	1	7.000	7.000	∞
Axial Isotropy	E.2.2	0.105	R	1.732	1.000	1.000	0.061	0.061	∞
Hemispherical Isotropy	E.2.2	0.105	R	1.732	0.000	0.000	0.000	0.000	∞
Boundary effect	E.2.3	1.000	R	1.732	1.000	1.000	0.577	0.577	∞
Linearity	E.2.4	1.105	R	1.732	1.000	1.000	0.638	0.638	∞
System detection limits	E.2.4	1.000	R	1.732	1.000	1.000	0.577	0.577	∞
Modulation response	E.2.5	3.000	R	1.732	0.000	0.000	0.000	0.000	∞
Readout Electronics	E.2.6	0.021	N	1.000	1.000	1.000	0.021	0.021	∞
Response Time	E.2.7	0.000	R	1.732	0.000	0.000	0.000	0.000	∞
Integration Time	E.2.8	1.400	R	1.732	0.000	0.000	0.000	0.000	∞
RF ambient conditions-Noise	E.6.1	3.000	R	1.732	1.000	1.000	1.732	1.732	∞
RF ambient conditions-reflections	E.6.1	3.000	R	1.732	1.000	1.000	1.732	1.732	∞
Probe positioner mechanical tolerance	E.6.2	1.400	R	1.732	1.000	1.000	0.808	0.808	∞
Probe positioning with respect to phantom shell	E.6.3	1.400	R	1.732	1.000	1.000	0.808	0.808	∞
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.300	R	1.732	1.000	1.000	1.328	1.328	∞
System validation source									
Deviation of experimental dipole from numerical dipole	E.6.4	5	N	1	1	1	5	5	∞
Input power and SAR drift measurement	8,6.6.4	5	R	1.732	1	1	2.887	2.887	∞
Dipole axis to liquid distance	8,E.6.6	2	R	1.732	1	1	1.155	1.155	∞
Phantom and set-up									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	1.732	1	1	2.309	2.309	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.9	1.596	∞
Liquid conductivity (temperature uncertainty)	E.3.3	4	N	1	0.78	0.71	3.12	2.84	∞
Liquid conductivity (measured)	E.3.3	5	N	1	0.23	0.26	1.15	1.3	M
Liquid permittivity (temperature uncertainty)	E.3.4	2.5	R	1.732	0.78	0.71	1.126	1.025	∞
Liquid permittivity (measured)	E.3.4	2.5	R	1.732	0.23	0.26	0.332	0.375	M
Combined Standard Uncertainty			RSS				10.466	10.279	
Expanded Uncertainty (95% Confidence interval)			K=2				20.931	20.559	

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SATIMO Uncertainty- 2023-EPGO-414									
System Check uncertainty for DUT averaged over 1 gram / 10 gram.									
Uncertainty Component	Sec.	Tol (+- %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	vi
Measurement System									
Probe calibration drift	E.2.1.3	0.500	N	1	1	1	0.5	0.5	∞
Axial Isotropy	E.2.2	0.105	R	1.732	0	0	0	0	∞
Hemispherical Isotropy	E.2.2	0.105	R	1.732	0	0	0	0	∞
Boundary effect	E.2.3	1.000	R	1.732	0	0	0	0	∞
Linearity	E.2.4	1.105	R	1.732	0	0	0	0	∞
System detection limits	E.2.4	1	R	1.732	0	0	0	0	∞
Modulation response	E.2.5	3	R	1.732	0	0	0	0	∞
Readout Electronics	E.2.6	0.021	N	1	0	0	0	0	∞
Response Time	E.2.7	0	R	1.732	0	0	0	0	∞
Integration Time	E.2.8	1.4	R	1.732	0	0	0	0	∞
RF ambient conditions-Noise	E.6.1	3	R	1.732	0	0	0	0	∞
RF ambient conditions-reflections	E.6.1	3	R	1.732	0	0	0	0	∞
Probe positioner mechanical tolerance	E.6.2	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	∞
Probe positioning with respect to phantom shell	E.6.3	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	∞
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.3	R	$\sqrt{3}$	0	0	0	0.00	∞
System check source (dipole)									
Deviation of experimental dipoles	E.6.4	2	N	1	1	1	2	2	∞
Input power and SAR drift measurement	8,6.6.4	5	R	$\sqrt{3}$	1	1	2.89	2.89	∞
Dipole axis to liquid distance	8,E.6.6	2	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Phantom and tissue parameters									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	$\sqrt{3}$	1	1	2.31	2.31	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1.000	1	0.84	1.90	1.60	∞
Liquid conductivity measurement	E.3.3	4	N	1.000	0.78	0.71	3.12	2.84	∞
Liquid permittivity measurement	E.3.3	5	N	1.000	0.23	0.26	1.15	1.30	M
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.78	0.71	1.13	1.02	∞
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.23	0.26	0.33	0.38	M
Combined Standard Uncertainty			RSS				5.562	5.203	
Expanded Uncertainty (95% Confidence interval)			K=2				11.124	10.406	

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12. CONDUCTED POWER MEASUREMENT

5GHz WIFI

Mode	channel	Frequency	Avg. Burst Power (dBm)							
			Data Rate(bps)							
			6M	9M	12M	18M	24M	36M	48M	54M
802.11a	36	5180	11.24	11.17	11.02	10.84	10.83	10.64	10.59	10.43
	40	5200	10.49	10.33	10.25	10.17	10.04	10.00	9.85	9.84
	48	5240	10.77	10.64	10.53	10.43	10.37	10.30	10.11	9.98
	149	5745	11.91	11.83	11.69	11.62	11.57	11.46	11.33	11.23
	157	5785	11.38	11.21	11.05	10.87	10.78	10.59	10.50	10.35
	165	5825	10.92	10.78	10.61	10.48	10.44	10.30	10.29	10.19

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13. TEST RESULTS

13.1. SAR Test Results Summary

13.1.1. Test position and configuration

1. The EUT is a RC quadcopter.
2. This device, classified as handheld, must comply with the 10g SAR limit of 4 W/kg. Testing at 0 mm separation from the phantom is required for all sides and edges containing antennas within 25 mm. On curved surfaces, the position may require adjustment (e.g., tilting) to position the antennas closest to the phantom.
3. Test procedure:
 - (1) Lab. use the head liquid with a separation of 0mm at flat phantom to test all sides and edges with antennas located within 25 mm from that side/edge
4. For SAR testing, the device was controlled by software to test at reference fixed frequency points.

13.1.2. Operation Mode

5. Per KDB 248227 D01 v02r02 Chapter 5.3.4, SAR measurement requirements for the remaining 802.11 transmission mode configurations that have not been tested in the initial test configuration are determined separately for each standalone and aggregated frequency band, in each exposure condition, according to the maximum output power specified for production units. The initial test position procedure is applied to next to the ear, UMPC mini-tablet and hotspot mode configurations. When the same maximum output power is specified for multiple transmission modes, the procedures in 5.3.2 are applied to determine the test configuration. Additional power measurements may be required to determine if SAR measurements are required for subsequent highest output power channels in a subsequent test configuration. The subsequent test configuration and SAR measurement procedures are described in the following.
 - (1) When SAR test exclusion provisions of KDB Publication 447498 D01 are applicable and SAR measurement is not required for the initial test configuration, SAR is also not required for the next highest maximum output power transmission mode subsequent test configuration(s) in that frequency band or aggregated band and exposure configuration.
 - (2) When the highest reported SAR for the initial test configuration (when applicable, include subsequent highest output channels), according to the initial test position or fixed exposure position requirements, is adjusted by the ratio of the subsequent test configuration to initial test configuration specified maximum output power and the adjusted SAR is ≤ 1.2 W/kg, SAR is not required for that subsequent test configuration.
 - (3) When the specified maximum output power is same for both UNII 1 and UNII 2A, begin SAR measurements in UNII 2A with the channel with the highest measured output power. If the report SAR for UNII 2A is < 1.2 W/kg, SAR is not required for UNII 1; otherwise treat the remaining bands separately and test them independently for SAR.
 - (4) When the specified maximum output power different between UNII 1 and UNII 2A, begin SAR with the band that has the higher specified maximum output. If the highest reported SAR for the band with the highest specified power is ≤ 1.2 W/kg, testing for the band with the lower specified output power is not required; otherwise test is remaining separately for SAR;
6. Maximum Scaling SAR in order to calculate the Maximum SAR values to test under the standard Peak Power, Calculation method is as follows:
Maximum Scaling SAR = tested SAR (Max.) \times [maximum turn-up power (mW)/ maximum measurement output power(mW)]

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13.1.3. SAR Test Results Summary

SAR MEASUREMENT									
Depth of Liquid (cm):>15									
Product: RC quadcopter									
Test Mode: 5.2GHz 802.11a									
Position	Ch.	Fr. (MHz)	Power Drift (<±5%)	10-g extremity SAR (W/kg)	Max. Tune-up Power (dBm)	Meas. Output Power (dBm)	Tune-up Scaling factor	Scaled SAR (W/kg)	Limit (W/kg)
Body back	40	5200	-0.12	0.035	11.50	10.49	1.262	0.044	4.0
Body front	40	5200	0.05	0.034	11.50	10.49	1.262	0.043	4.0
Edge 1 (Top)	40	5200	-0.32	0.657	11.50	10.49	1.262	0.829	4.0

SAR MEASUREMENT									
Depth of Liquid (cm):>15									
Product: RC quadcopter									
Test Mode: 5.8GHz 802.11a									
Position	Ch.	Fr. (MHz)	Power Drift (<±5%)	10-g extremity SAR (W/kg)	Max. Tune-up Power (dBm)	Meas. Output Power (dBm)	Tune-up Scaling factor	Scaled SAR (W/kg)	Limit (W/kg)
Body back	157	5785	0.08	0.077	12.00	11.38	1.153	0.089	4.0
Body front	157	5785	-0.16	0.057	12.00	11.38	1.153	0.066	4.0
Edge 1 (Top)	157	5785	-0.61	0.800	12.00	11.38	1.153	0.923	4.0

Note:

- When the 10-g extremity SAR is ≤ 2.0 W/kg, testing for low and high channel is optional.
- The test separation of all above table is 0mm.
- Plots are only shown for the bold marked worst case SAR results

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APPENDIX A. SAR SYSTEM CHECK DATA

Test Laboratory: AGC Lab

Date: Jul. 01, 2025

System Check Head 5200 MHz

DUT: Dipole 5000MHz Type: SID5000

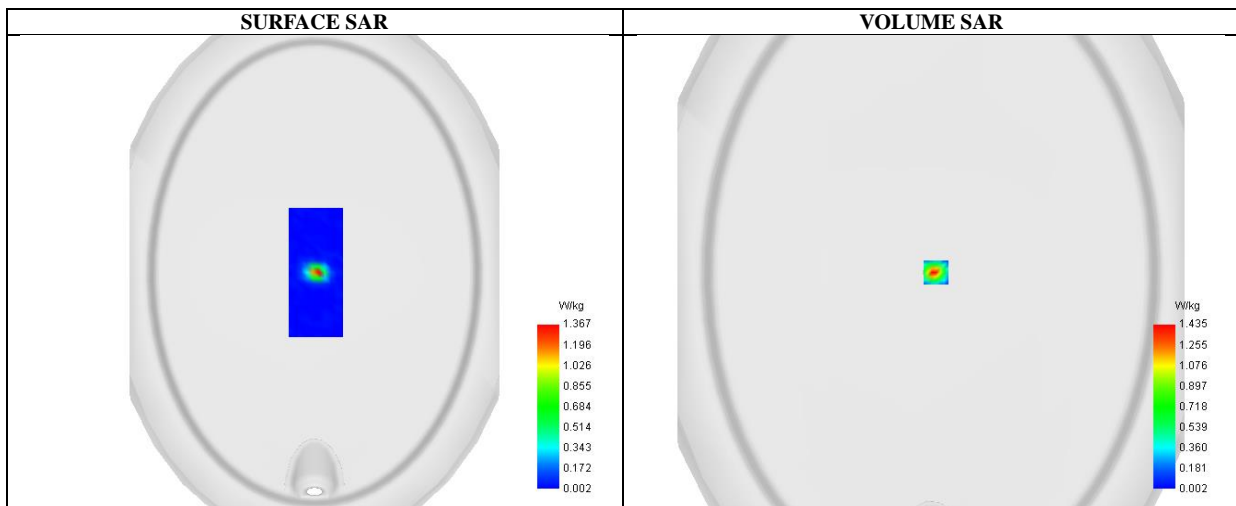
Communication System: CW; Communication System Band: D5000 (5000.0 MHz); Duty Cycle: 1:1; Conv.F=1.54
Frequency: 5200 MHz; Medium parameters used: $f = 5250$ MHz; $\sigma = 4.62$ mho/m; $\epsilon_r = 36.21$; $\rho = 1000$ kg/m³ ;
Phantom section: Flat Section; Input Power=10dBm

SATIMO Configuration:

- Probe: SSE2; Calibrated: 2025-05-06; Serial No.: 2023-EPGO-414
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Phantom: Phantom: ELLI39 Phantom
- Measurement SW: OpenSAR V5.3.15.8

Configuration/System Check 5200 MHz Head/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/System Check 5200 MHz Head/Zoom Scan: Measurement grid: dx=4mm, dy=4mm, dz=2mm



Maximum location: X=5.00, Y=0.00 ; SAR Peak: 2.89 W/kg

SAR 10g (W/Kg)	0.223
SAR 1g (W/Kg)	0.779
Variation (%)	-25.180
Horizontal validation criteria: minimum distance (mm)	8.000000
Vertical validation criteria: SAR ratio M2/M1 (%)	44.360979

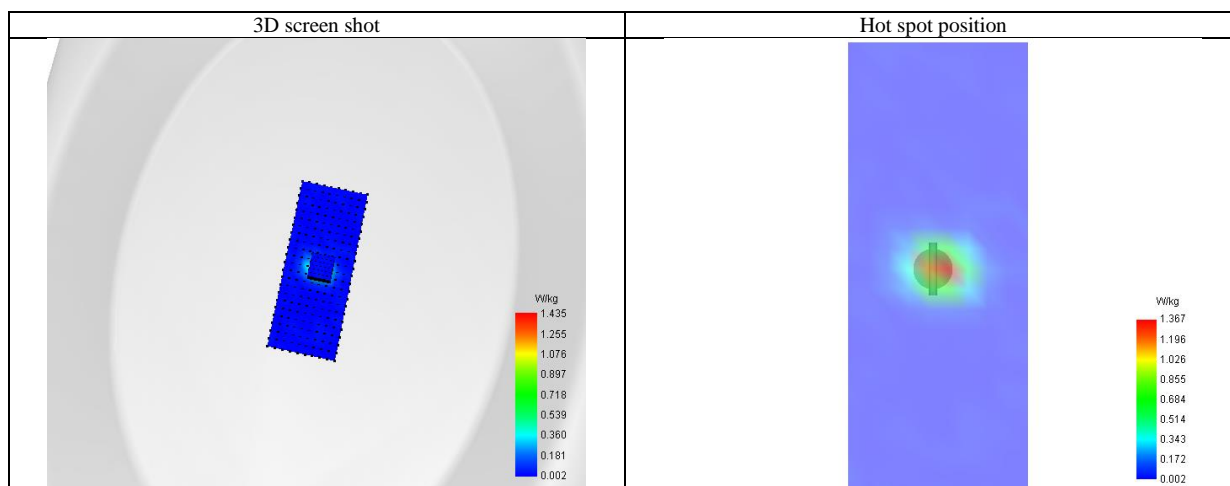
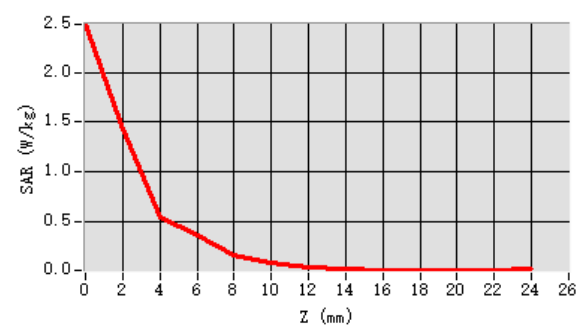
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Z (mm)	0.00	2.00	4.00	6.00	8.00	10.00	12.00	14.00	16.00	18.00	20.00	22.00
SAR (W/Kg)	2.491	1.435	0.536	0.351	0.162	0.079	0.029	0.022	0.004	0.005	0.003	0.002



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Test Laboratory: AGC Lab
System Check Head 5800 MHz
DUT: Dipole 5000MHz Type: SID5000

Date: Jul. 02, 2025

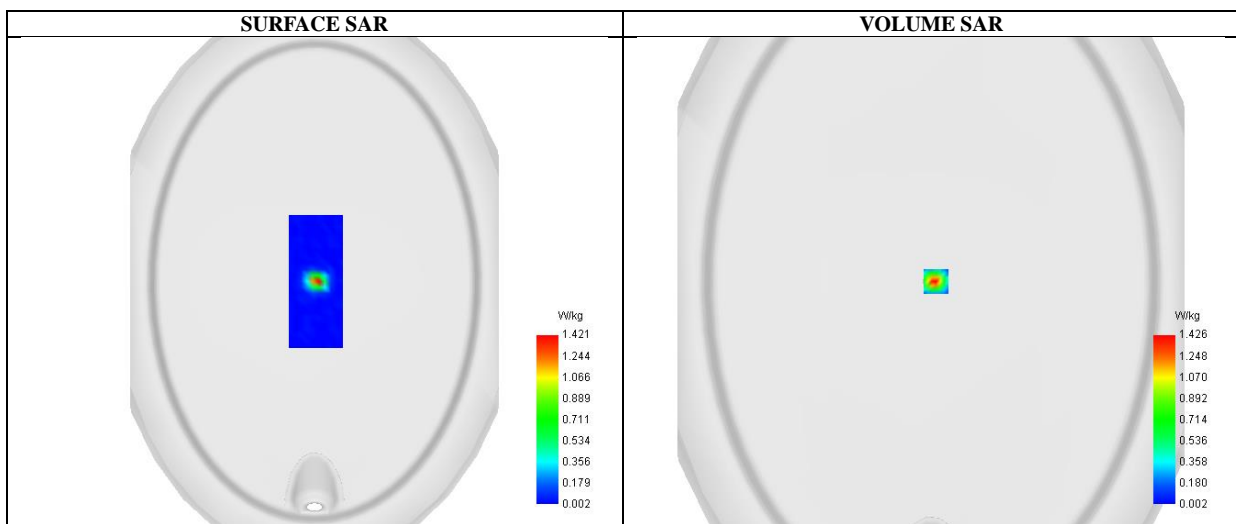
Communication System: CW; Communication System Band: D5000 (5000.0 MHz); Duty Cycle: 1:1; Conv.F=1.41
Frequency: 5800 MHz; Medium parameters used: $f = 5800$ MHz; $\sigma = 5.18$ mho/m; $\epsilon_r = 34.77$; $\rho = 1000$ kg/m³ ;
Phantom section: Flat Section; Input Power=10dBm

SATIMO Configuration:

- Probe: SSE2; Calibrated: 2025-05-06; Serial No.: 2023-EPGO-414
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Phantom: Phantom: ELLI39 Phantom
- Measurement SW: OpenSAR V5.3.15.8

Configuration/System Check 5800 MHz Head/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/System Check 5800 MHz Head/Zoom Scan: Measurement grid: dx=4mm,dy=4mm, dz=2mm



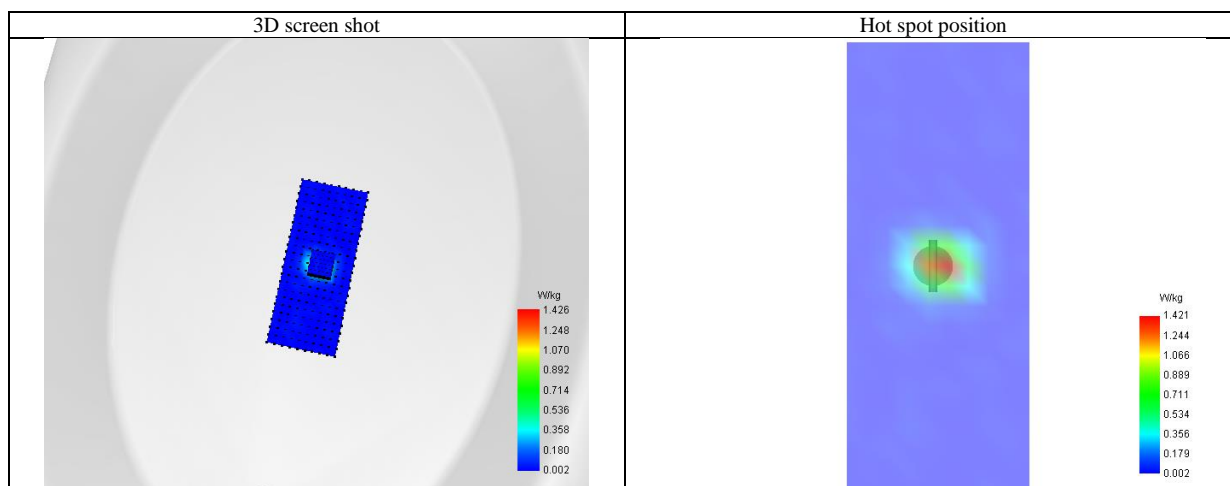
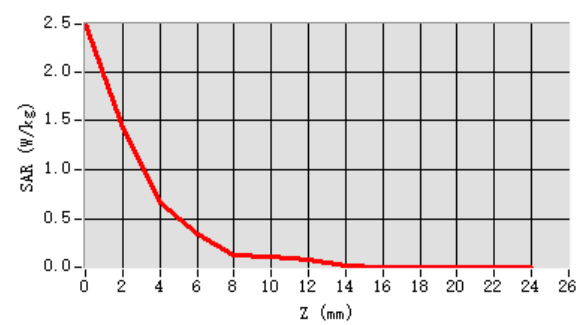
Maximum location: X=5.00, Y=0.00 ; SAR Peak: 2.69 W/kg

SAR 10g (W/Kg)	0.234
SAR 1g (W/Kg)	0.782
Variation (%)	-43.800
Horizontal validation criteria: minimum distance (mm)	8.000000
Vertical validation criteria: SAR ratio M2/M1 (%)	46.264855

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Z (mm)	0.00	2.00	4.00	6.00	8.00	10.00	12.00	14.00	16.00	18.00	20.00	22.00
SAR (W/Kg)	2.485	1.426	0.660	0.344	0.126	0.103	0.084	0.011	0.002	0.005	0.008	0.003



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APPENDIX B. SAR MEASUREMENT DATA

5.2GHz 802.11a

Test Laboratory: AGC Lab

802.11a CH40-Edge 1 (Top)

DUT: RC quadcopter; Type: HS600

Date: Jul. 01, 2025

Communication System: Wi-Fi; Communication System Band: 802.11a; Duty Cycle: 98%; Conv.F=1.54;
Frequency: 5200MHz; Medium parameters used: $f = 5200 \text{ MHz}$; $\sigma = 4.62 \text{ mho/m}$; $\epsilon_r = 36.21$; $\rho = 1000 \text{ kg/m}^3$;
Phantom section: Flat Section

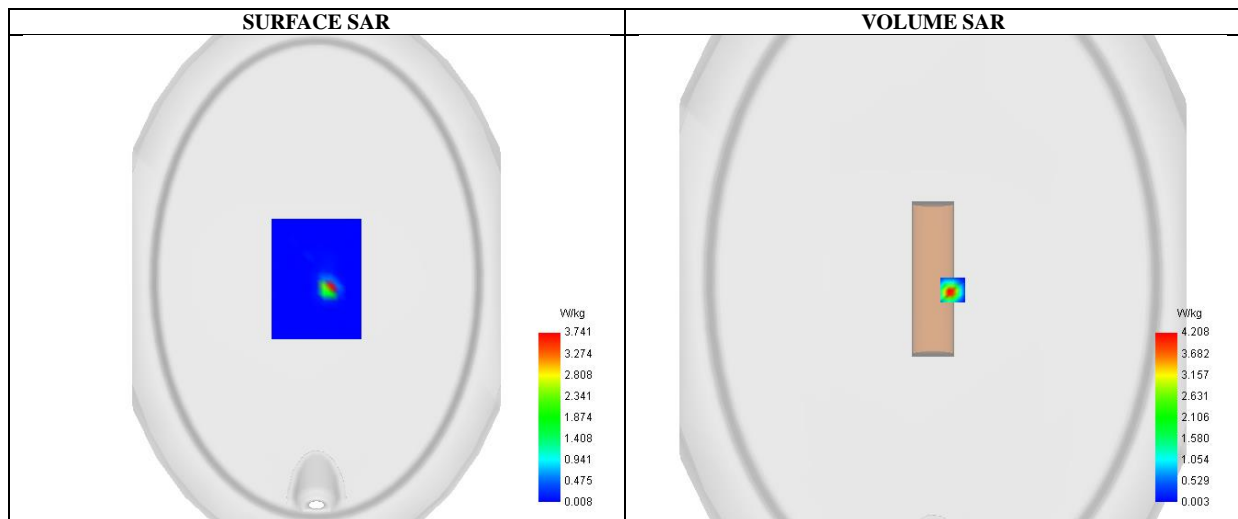
SATIMO Configuration:

- Probe: SSE2; Calibrated: 2025-05-06; Serial No.: 2023-EPGO-414
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Phantom: Phantom: ELLI39 Phantom
- Measurement SW: OpenSAR V5.3.15.8

Configuration/802.11a CH40- Edge 1 (Top) /Area Scan: Measurement grid: $dx=8\text{mm}$, $dy=8\text{mm}$

Configuration/802.11a CH40- Edge 1 (Top) /Zoom Scan: Measurement grid: $dx=4\text{mm}$, $dy=4\text{mm}$, $dz=2\text{mm}$

Area Scan	$dx=8\text{mm}$ $dy=8\text{mm}$, $h= 5.00 \text{ mm}$
ZoomScan	$7 \times 7 \times 12$ $dx=4\text{mm}$ $dy=4\text{mm}$ $dz=2\text{mm}$
Phantom	ELLI
Device Position	Edge 1 (Top)
Band	5200MHz
Channels	CH40
Signal	Crest factor: 1.0



Maximum location: X=19.00, Y=-11.00 ; SAR Peak: 7.89 W/kg

SAR 10g (W/Kg)	0.657
SAR 1g (W/Kg)	2.426
Variation (%)	-44.940
Horizontal validation criteria: minimum distance (mm)	5.656854
Vertical validation criteria: SAR ratio M2/M1 (%)	51.869912

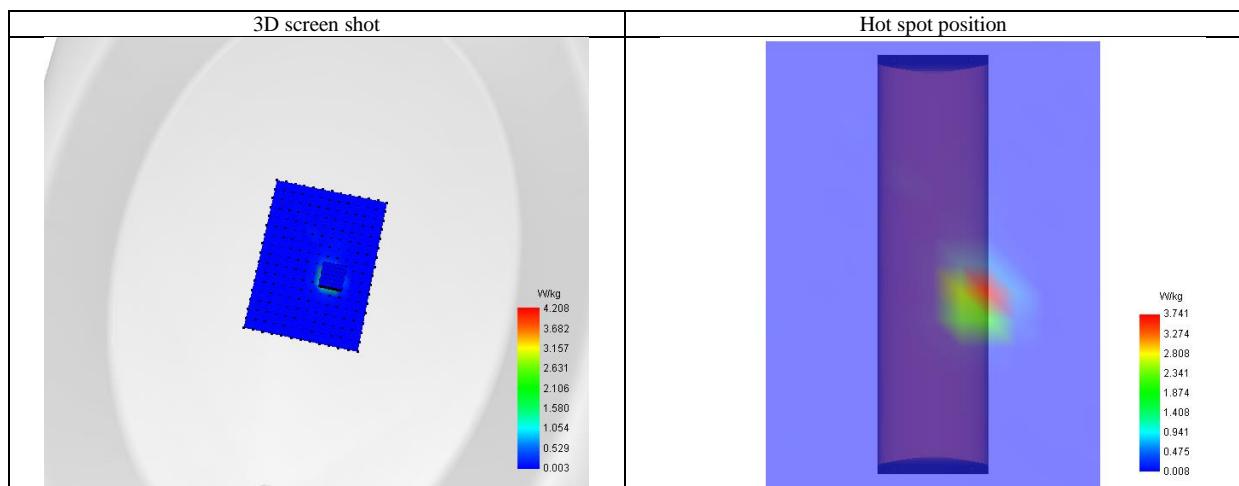
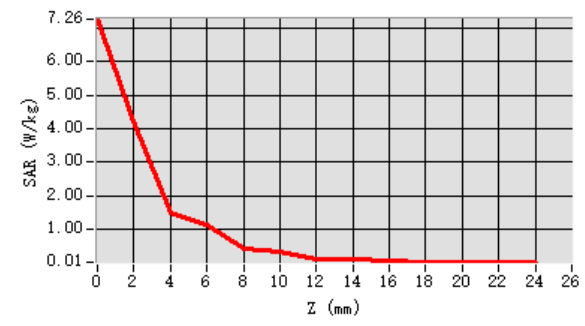
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Z (mm)	0.00	2.00	4.00	6.00	8.00	10.00	12.00	14.00	16.00	18.00	20.00	22.00
SAR (W/Kg)	7.265	4.208	1.477	1.149	0.401	0.316	0.115	0.086	0.036	0.029	0.028	0.015



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5.8GHz 802.11a

Test Laboratory: AGC Lab

Date: Jul. 02, 2025

802.11a Mid-Edge 1 (Top)

DUT: RC quadcopter; Type: HS600

Communication System: Wi-Fi; Communication System Band: 802.11a; Duty Cycle: 98%; Conv.F=1.41;
Frequency: 5785MHz; Medium parameters used: $f = 5800 \text{ MHz}$; $\sigma = 5.15 \text{ mho/m}$; $\epsilon_r = 35.06$; $\rho = 1000 \text{ kg/m}^3$;
Phantom section: Flat Section

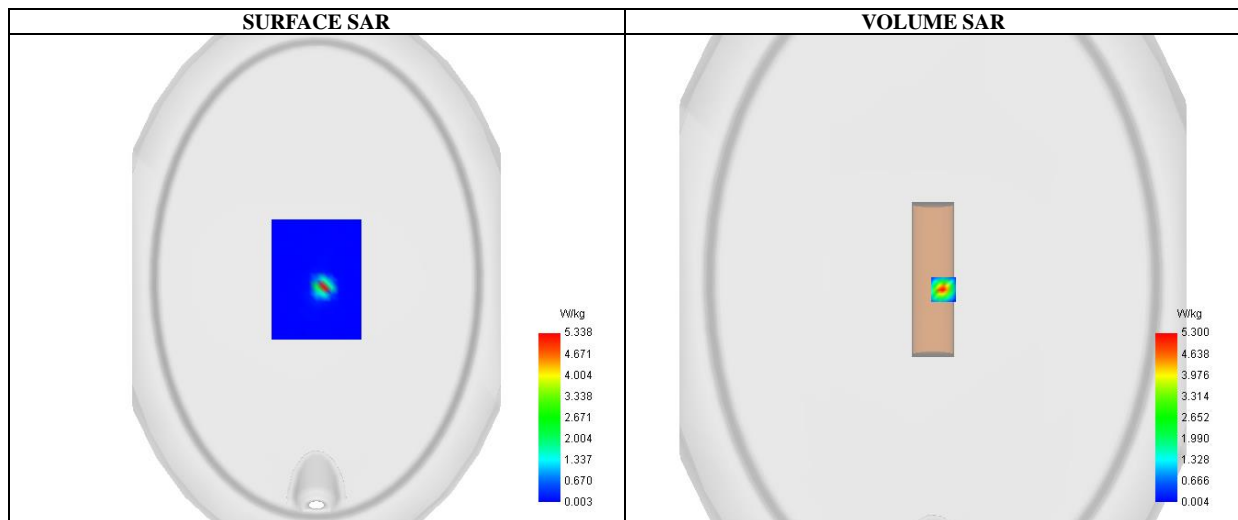
SATIMO Configuration:

- Probe: SSE2; Calibrated: 2025-05-06; Serial No.: 2023-EPGO-414
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Phantom: Phantom: ELLI39 Phantom
- Measurement SW: OpenSAR V5.3.15.8

Configuration/ 802.11a Mid- Edge 1 (Top) /Area Scan: Measurement grid: $dx=8\text{mm}$, $dy=8\text{mm}$

Configuration/ 802.11a Mid- Edge 1 (Top) /Zoom Scan: Measurement grid: $dx=4\text{mm}$, $dy=4\text{mm}$, $dz=2\text{mm}$

Area Scan	$dx=8\text{mm}$ $dy=8\text{mm}$, $h= 5.00 \text{ mm}$
ZoomScan	$7 \times 7 \times 12$ $dx=4\text{mm}$ $dy=4\text{mm}$ $dz=2\text{mm}$
Phantom	ELLI
Device Position	Edge 1 (Top)
Band	5800MHz
Channels	Middle
Signal	Crest factor: 1.0



Maximum location: $X=10.00$, $Y=-10.00$; SAR Peak: 9.67 W/kg

SAR 10g (W/Kg)	0.800
SAR 1g (W/Kg)	2.801
Variation (%)	44.250
Horizontal validation criteria: minimum distance (mm)	8.000000
Vertical validation criteria: SAR ratio M2/M1 (%)	49.412657

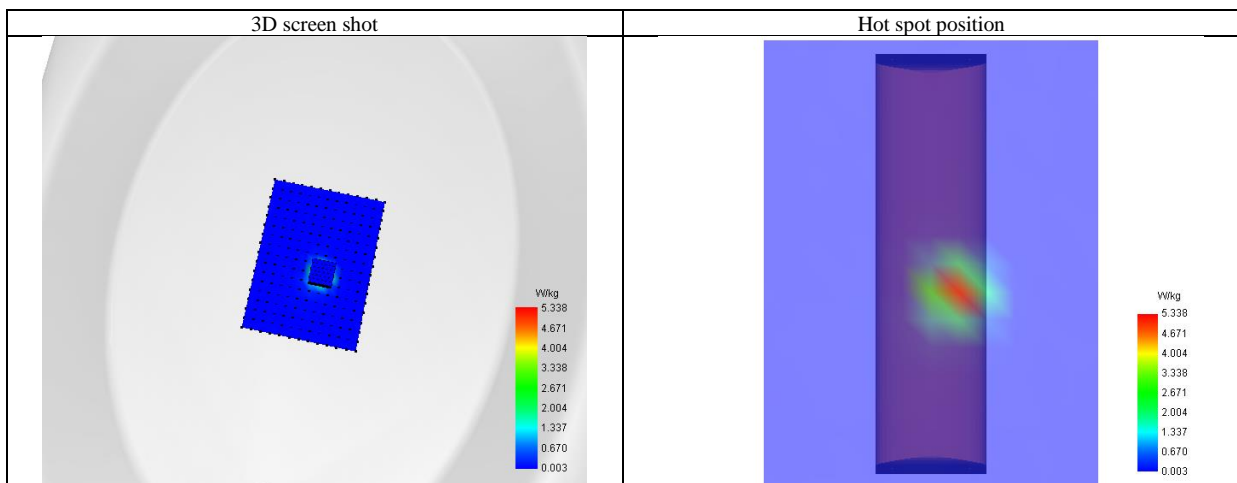
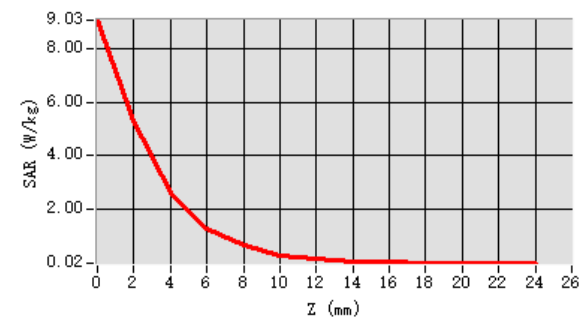
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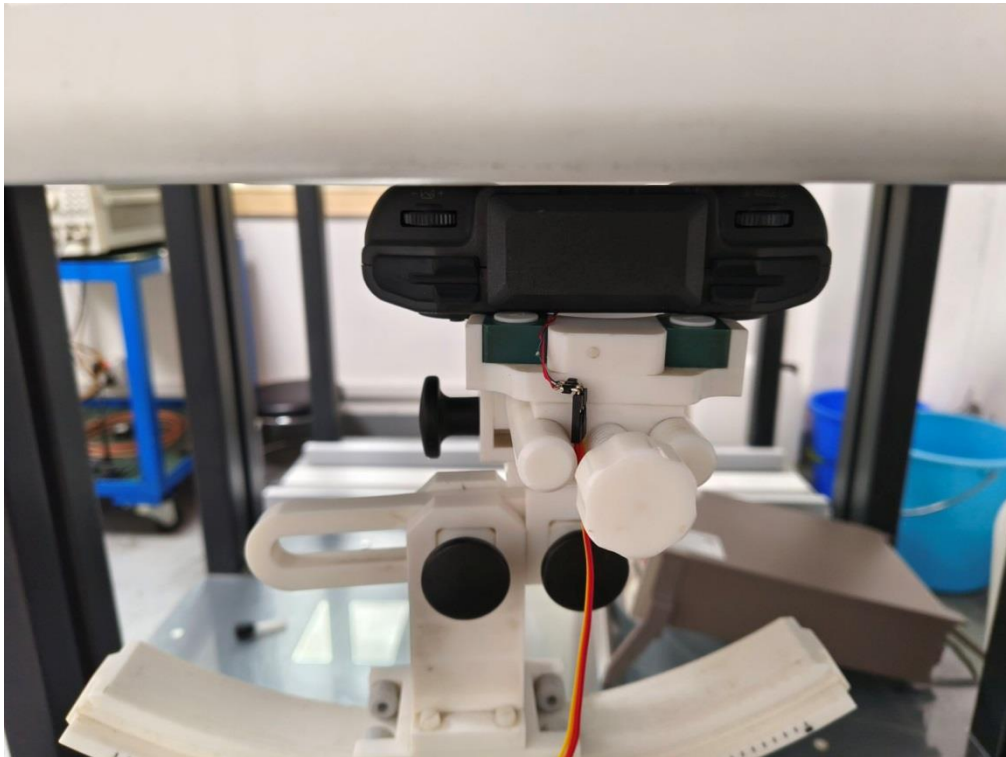
Z (mm)	0.00	2.00	4.00	6.00	8.00	10.00	12.00	14.00	16.00	18.00	20.00	22.00
SAR (W/Kg)	9.033	5.300	2.619	1.318	0.666	0.303	0.167	0.099	0.057	0.037	0.032	0.021



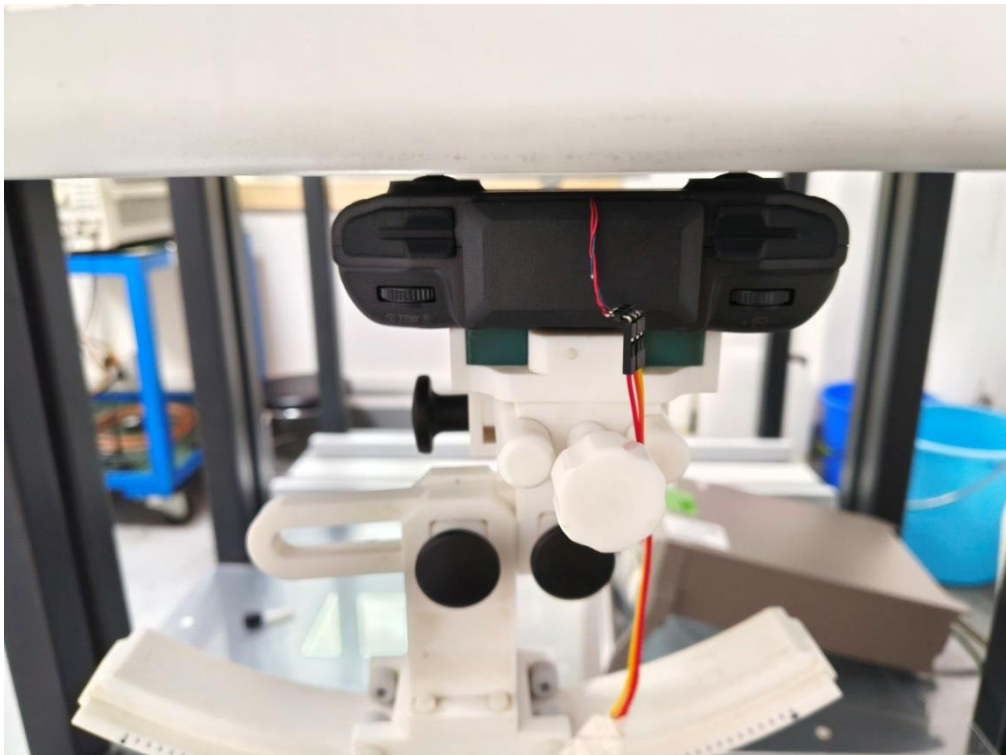
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APPENDIX C. TEST SETUP PHOTOGRAPHS

Hand Back 0mm



Hand Front 0mm



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Edge1(Top) 0mm



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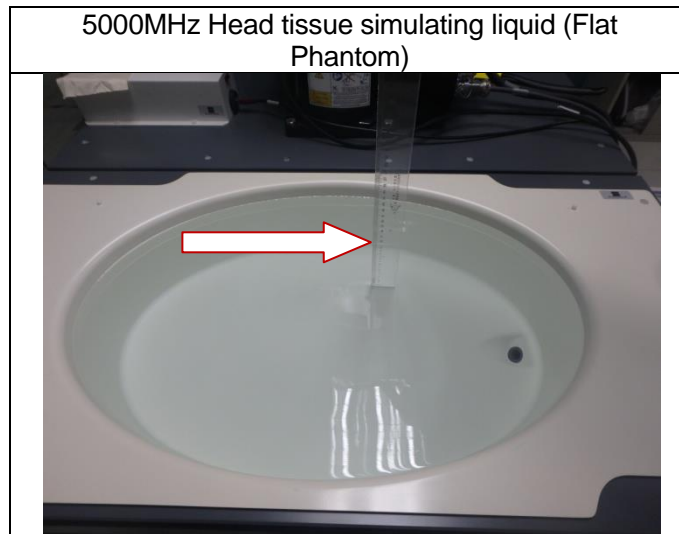
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DEPTH OF THE LIQUID IN THE PHANTOM—ZOOM IN

Note : The position used in the measurement were according to IEEE Std. 1528:2013



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APPENDIX D. CALIBRATION DATA

Refer to Attached files.

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1. All samples and goods are accepted by the Attestation of Global Compliance (Shenzhen) Co., Ltd (the “Company”) solely for testing and reporting in accordance with the following terms and conditions. The company provides its services on the basis that such terms and conditions constitute express agreement between the company and any person, firm or company requesting its services (the “Clients”).
2. Any report issued by Company as a result of this application for testing services (the “Report”) shall be issued in confidence to the Clients and the Report will be strictly treated as such by the Company. It may not be reproduced either in its entirety or in part and it may not be used for advertising or other unauthorized purposes without the written consent of the Company. The Clients to whom the Report is issued may, however, show or send it, or a certified copy thereof prepared by the Company to its customer, supplier or other persons directly concerned. The Company will not, without the consent of the Clients, enter into any discussion or correspondence with any third party concerning the contents of the Report, unless required by the relevant governmental authorities, laws or court orders.
3. The Company shall not be called or be liable to be called to give evidence or testimony on the Report in a court of law without its prior written consent, unless required by the relevant governmental authorities, laws or court orders.
4. In the event of the improper use of the report as determined by the Company, the Company reserves the right to withdraw it, and to adopt any other additional remedies which may be appropriate.
5. Samples submitted for testing are accepted on the understanding that the Report issued cannot form the basis of, or be the instrument for, any legal action against the Company.
6. The Company will not be liable for or accept responsibility for any loss or damage however arising from the use of information contained in any of its Reports or in any communication whatsoever about its said tests or investigations.
7. Clients wishing to use the Report in court proceedings or arbitration shall inform the Company to that effect prior to submitting the sample for testing.
8. The Company is not responsible for recalling the electronic version of the original report when any revision is made to them. The Client assumes the responsibility to providing the revised version to any interested party who uses them.
9. Subject to the variable length of retention time for test data and report stored hereinto as otherwise specifically required by individual accreditation authorities, the Company will only keep the supporting test data and information of the test report for a period of six years. The data and information will be disposed of after the aforementioned retention period has elapsed. Under no circumstances shall we provide any data and information which has been disposed of after retention period. Under no circumstances shall we be liable for damage of any kind, including (but not limited to) compensatory damages, lost profits, lost data, or any form of special, incidental, indirect, consequential or punitive damages of any kind, whether based on breach of contract of warranty, tort (including negligence), product liability or otherwise, even if we are informed in advance of the possibility of such damages.

----END OF REPORT----

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