



TEST REPORT

APPLICANT : Guilin Zhishen Information Technology Co.,Ltd.
PRODUCT NAME : TransMount Image Transmission Receiver
MODEL NAME : COV-02
BRAND NAME : ZHIYUN
FCC ID : 2AIHFZYCOV02
STANDARD(S) : 47CFR 2.1093
IEEE 1528-2013
RECEIPT DATE : 2019-10-23
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REPORT No. : XM19120046W01

Change history			
Version	Date	Reason for change	Test engineer
1.0	2020-01-09	Original	Peng Fuwei



1. SAR Results Summary

The maximum results of Specific Absorption Rate (SAR) found during test as bellows:

Frequency Band	Highest SAR Summary (1-g SAR,W/kg)
	Body (Separation 5mm)
Max. 5GHz WLAN ANT A	0.650
Max. 5GHz WLAN ANT B	1.169
Max. 5GHz WLAN ANT A+ANT B	1.557
Max Scaled SAR _{1g} (W/Kg):	1.169

Note:

This device is in compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (1.6W/kg as averaged over any 1 gram of tissue; specified in FCC 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1-1992, and had been tested in accordance with the measurement methods and procedures specified in IEEE 1528-2013 and FCC KDB publications.



2. Technical Information

Note: Provide by applicant.

2.1. Applicant and Manufacturer Information

Applicant:	Guilin Zhishen Information Technology Co.,Ltd.
Applicant Address:	Creative Industrial Park, Guimo Road, Qixing District, Guilin 541004, Guangxi, China
Manufacturer:	Guilin Zhishen Information Technology Co.,Ltd.
Manufacturer Address:	Creative Industrial Park, Guimo Road, Qixing District, Guilin 541004, Guangxi, China

2.2. Equipment Under Test (EUT) Description

EUT Type:	TransMount Image Transmission Receiver
Hardware Version:	2.0
Software Version:	1.02
Frequency Bands:	WLAN 5.2GHz: 5180 MHz ~ 5240 MHz WLAN 5.8GHz: 5745 MHz ~ 5825 MHz
Modulation Mode:	802.11 n-HT20: OFDM
Antenna Type:	External Antenna
Antenna Gain:	Ant A:2.15dBi Ant B:2.2dBi
Battery:	3.8V/1400mAh

Difference declaration:

The component differences between COV-01 and COV-02 are as follows:

1. COV-02 cancel the camera control interface and reduces components on the corresponding PCB.
2. HDMI interface is different: COV-01's HDMI interface is input; COV-02's HDMI interface is output; COV-02 has reduced one HDMI receiving chip.

No other changes, all RF parameters remain the same as before. We have evaluated this change in EMC, SAR and RF reports.

Test data reference report: XM19100033W01(FCC ID: 2AIHFZYCOV01).

2.3. Photographs of the EUT

Normal Temperature (NT):	20 ... 25 °C
Relative Humidity:	30 ... 75 %
Air Pressure:	980 ... 1020 hPa

Test frequency:	WLAN 5GHz;
Operation mode:	Fixed frequency transmission
Power Level:	PL=17.5

During SAR test, EUT is in Traffic Mode (Channel Allocated) at Normal Voltage Condition. A communication link is set up with a System Simulator (SS) by air link, and a call is established.

The EUT shall use its internal transmitter. The antenna(s), battery and accessories shall be those specified by the Factory. The EUT battery must be fully charged and checked periodically during the test to ascertain uniform power output. If a wireless link is used, the antenna connected to the output of the base station simulator shall be placed at least 50 cm away from the handset.

The signal transmitted by the simulator to the antenna feeding point shall be lower than the output power level of the handset by at least 35 dB.

For SAR testing, EUT is in WI-FI mode, its crest factor is 1.021.

3. Specific Absorption Rate (SAR)

3.1. Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are Middle than the limits for general population/uncontrolled.

3.2. SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by(dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density. (ρ). The equation description is as below:

$$SAR = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dv} \right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by,

$$SAR = C \left(\frac{\delta T}{\delta t} \right)$$

Where C is the specific head capacity, δT is the temperature rise and δt the exposure duration, or related to the electrical field in the tissue by

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where σ is the conductivity of the tissue, ρ is the mass density of the tissue and |E| is the rmselectrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

4. RF Exposure Limits

Limits for General Population/Uncontrolled Exposure (W/kg)

Type Exposure	Uncontrolled Environment Limit
Spatial Peak SAR (1g cube tissue for head and trunk)	1.60W/kg
Spatial Peak SAR (10g cube tissue for limbs)	4.00W/kg
Spatial Peak SAR (1g cube tissue for whole body)	0.08W/kg

Note:

1. This limit is according to ANSI/IEEE C95.1.
2. Occupational/Uncontrolled Environments are defined as locations where there is exposure that may be incurred by people who are aware of the potential for exposure,(i.e. as a result of employment or occupation)

5. Applied Reference Documents

Leading reference documents for testing:

No.	Identity	Document Title
1	47 CFR§2.1093	Radio Frequency Radiation Exposure Evaluation: Portable Devices
2	IEEE 1528-2013	IEEE Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques
3	KDB 447498 D01v06	General RF Exposure Guidance
4	KDB 248227 D01v02r02	SAR Measurement Procedures for 802.11 Transmitters
5	KDB 865664 D01v01r04	SAR Measurement 100 MHz to 6 GHz
6	KDB 865664 D02v01r02	RF Exposure Reporting

6. SAR Measurement System

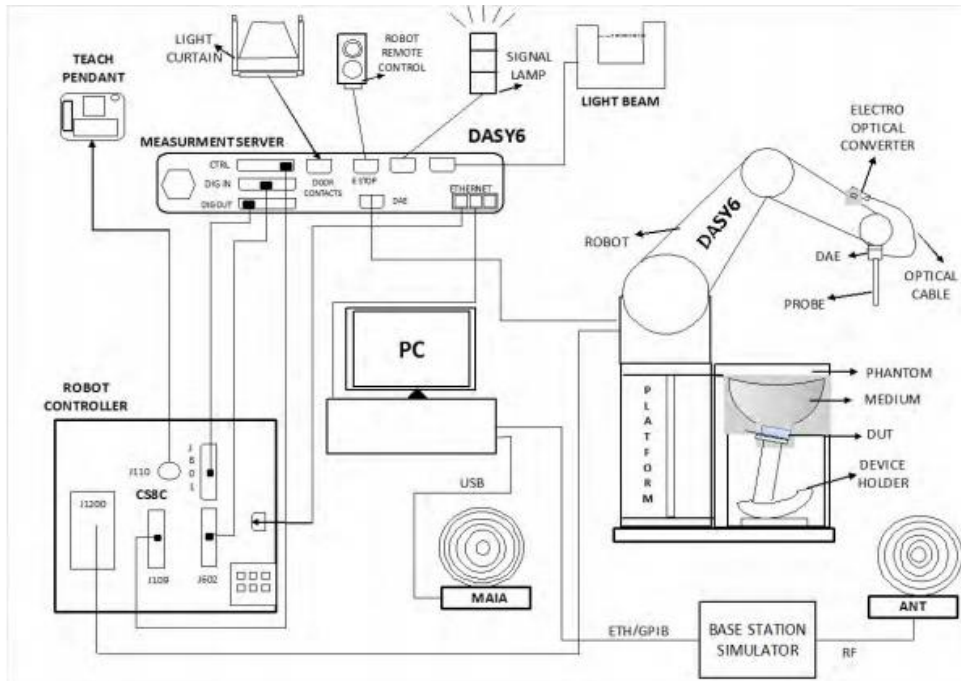


Fig 6.0 SPEAG DASY System Configurations

The DASY system for performance compliance tests is illustrated above graphically. This system consists of the following items:

- A standard high precision 6-axis robot (Staubli TX/RX family, with its software especially configured for SPEAG) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A platform on which robot arm is mounted and phantom shells to be inserted in dedicated slots.
- An isotropic field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running Win8.1/Win10 professional operating system and the cDASY6 V6.4 and

DASY5 V5.2 software. Please see 1.6 DASY6 Software Installation for detailed computer requirements.

- Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.

6.1.E-Field Probe

The SAR measurement is conducted with the dosimetric probe (manufactured by SPEAG).The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. This probe has a built in optical surface detection system to prevent from collision with phantom.

E-Field ProbeSpecification

Model	Ex3DV4	
Construction	Symmetrical design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)	
Frequency	10 MHz to 6 GHz; Linearity: ± 0.2 dB	
Directivity	± 0.3 dB in HSL (rotation around probe axis) ± 0.5 dB in tissue material (rotation normal to probe axis)	
Dynamic Range	10 μ W/g to 100 mW/g; Linearity: ± 0.2 dB	
Dimensions	Overall length: 330 mm (Tip: 20 mm) Tip diameter: 2.5 mm (Body: 12 mm) Typical distance from probe tip to dipole centers: 1 mm	
Application	High precision dosimetric measurements in any exposure scenario(e.g.,very strong gradient fields).Only probe which enables compliance testing forfrequencies up to 6 GHz with precision of better 30%	

Fig 6.1 Photo of EX3DV4

E-Field Probe Calibration

Each probe needs to be calibrated according to a dosimetric assessment procedure with accuracy better than $\pm 10\%$. The spherical isotropy shall be evaluated and within ± 0.25 dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested. The calibration data can be referred to appendix C of this report.

6.2. Data Acquisition Electronics (DAE)

The data acquisition electronics (DAE4 or DAE3) consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16-bit AD-converter, and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock. The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts used for mechanical surface detection and probe collision detection. The input impedance of both the DAE4 as well as of the DAE3 box is 200 MOhm; the inputs are symmetric and floating. Common mode rejection is above 80 dB.



Fig 6.2 Photo of DAE

6.3. Robot

The DASY6 system uses the high-precision industrial robots TX60L from Stäubli SA (France). The TX robot family – the successor of the well-known RX robot family – continues to offer the features important for DASY6 applications:

- High precision (repeatability 0.02 mm)
- High reliability (industrial design)
- Low maintenance costs (virtually maintenance-free as all gears are direct drive, no belt drives)
- Jerk-free straight movements (brushless synchronous motors, no stepper motors)
- Low extremely low frequency (ELF) interference (motor control fields are shielded by the closed metallic construction)

The robots are controlled by the Stäubli CS8c robot controllers. All information regarding the use and maintenance of the robot arm and the robot controller is provided on CDs delivered with the robot. Paper manuals are available directly from Stäubli upon request



Fig 6.3 Robot

6.4. Measurement Server

The DASY6 measurement server is based on a PC/104 CPU board with a 400 MHz intel ULVCeleron, 128 MB chip-disk and 128 MB RAM. The necessary circuits for communication with the DAE4(or DAE3) electronics box, as well as the 16-bit AD converter system for optical detection and digital I/O interface are contained on the DASY6 I/O board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all real-time data evaluations of field measurements and surface detection, controls robot movements, and handles safety operations.



Fig 6.4 Measurement Server

6.5. Phantom

The SAM-Twin phantom (shown in front of DASY6) is a fiberglass shell phantom with shell thickness 2 mm, except in the ear region where the thickness is increased to 6 mm. The phantom has three measurement areas:

- 1) Left Head
- 2) Right Head
- 3) Flat Section

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. Reference points on the phantoms (P1, P2, P3) are used to teach the absolute phantom position relative to the robot.

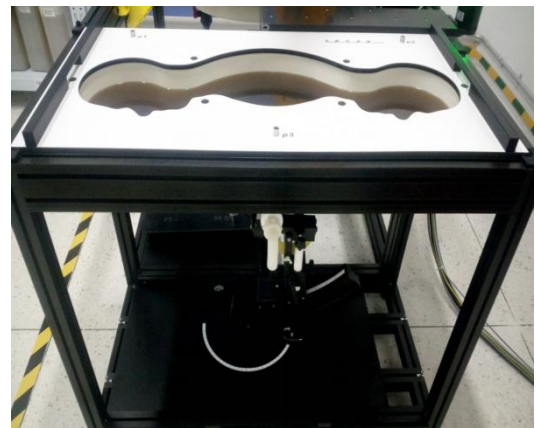


Fig 6.5 Photo of SAM Phantom

7. Device Holder

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5 mm distance, a positioning uncertainty of ± 0.5 mm would produce uncertainty in the SAR of $\pm 20\%$. Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions at which the devices must be measured are defined by the standards.

The DASY device holder is designed to cope with the different positions described in the standard. It has two scales for device rotation (with respect to the body axis) and device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point (ERP). Thus, the device needs no repositioning when the angles are changed. The DASY device holder is constructed of low-loss polyoxymethylene (POM) material, which has the following dielectric parameters: relative permittivity $\epsilon = 3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered



Fig 7.1 Device Holder

7.1. Data Storage and Evaluation

Data Storage

The DASY software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files. The post-processing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.



The measured data can be visualized or exported in different units or formats, depending on the selected probe type (e.g., [V/m], [A/m], [mW/g]). Some of these units are not available in certain situations or give meaningless results, e.g., a SAR-output in a non-lose media, will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

Data Evaluation

The DASY post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software.

Probe parameters:	- Sensitivity	Norm _i , a _{i0} , a _{i1} , a _{i2}
	- Conversion factor	ConvF _i
	- Diode compression point	dcpi
Device parameters:	- Frequency	f
	- Crest factor	cf
Media parameters:	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power.

The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \times \frac{cf}{dcp_i}$$

With
V_i = compensated signal of channel i, (i = x, y, z)
U_i = input signal of channel i, (i = x, y, z)
cf = crest factor of exciting field (DASY parameter)
dcp_i = diode compression point (DASY parameter)

From the compensated input signals, the primary field data for each channel can be evaluated:

$$\text{E-field Probes: } E_i = \sqrt{\frac{V_i}{\text{Norm}_i \times \text{ConvF}}}$$

$$\text{H-field Probes: } H_i = \sqrt{V_i} \times \frac{a_{i0} + a_{i1} + a_{i2}f^2}{f}$$

With V_i = compensated signal of channel i , ($i = x, y, z$)
 Norm_i = sensor sensitivity of channel i , ($i = x, y, z$), $\mu\text{V}/(\text{V/m})^2$ for E-field
 Probes ConvF = sensitivity enhancement in solution
 a_{ij} = sensor sensitivity factors for H-field probes
 f = carrier frequency [GHz]
 E_i = electric field strength of channel i in V/m
 H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{\text{tot}} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$\text{SAR} = E_{\text{tot}}^2 \times \frac{\sigma}{\rho \times 1000}$$

with SAR = local specific absorption rate in mW/g
 E_{tot} = total field strength in V/m
 σ = conductivity in [mho/m] or [Siemens/m]
 ρ = equivalent tissue density in g/cm^3

Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.



7.2. Equipment information

No.	Instrument	Type	Cal. Date	Cal. Due
1	PC	HP (IntellCoreli7-7600CPU &3.4GHz, SN:CZC099QQF)	N/A	N/A
2	Network Analyzer	Agilent(E5071C ,SN:MY46529009)	2019.01.07	1year
3	Network Emulator	R&S(CMW500,SN: 100915)	2019.01.07	1year
4	Signal Generator	KEYSIGHT(E8257D, SN:MY56440492)	2019.01.04	1year
5	Power Meter	Anritsu (NRVD,SN:101066)	2019.11.23	1year
6	Power Meter	Agilent (E4416A,SN:MY45102093)	2019.11.23	1year
7	Power Sensor	Agilent (N8482A,SN:MY41091706)	2019.11.23	1year
8	Amplifier	mini-circuits (ZVE-8G+,SN:754401735)	N/A	N/A
9	Probe	SPEAG (EX3DV4, SN:3685)	2019.3.25	1year
10	Data Acquisition Electronics	SPEAG(DAE4, SN:871)	2019.6.27	1year
11	Phantom	SPEAG (QD 000 P41 AA,SN:1922)	N/A	N/A
12	Dielectric Assessment KIT	SPEAG (DAK-3.5,SN:1279)	2019.11.03	1year
13	Liquid	HBBL600-6000V2	24H	
14	Thermo meter	NT-312(SN:121529)	2019.06.26	1year
15	Dipole 5GHz	D5GHzV2(SN:1176)	2018.11.06	3year

8. Tissue Simulating Liquids

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing, the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm, which is shown in Fig. 5.1. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15 cm, which is shown in Fig. 5.2. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 5% are listed in below table.

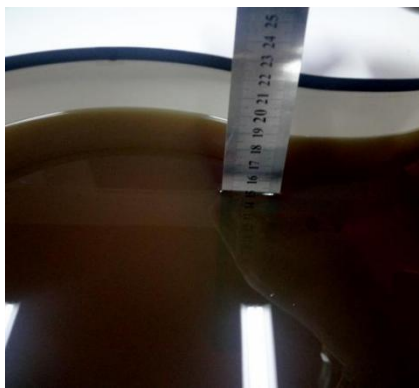


Fig 8.1 Photo of Liquid Height for Head SAR

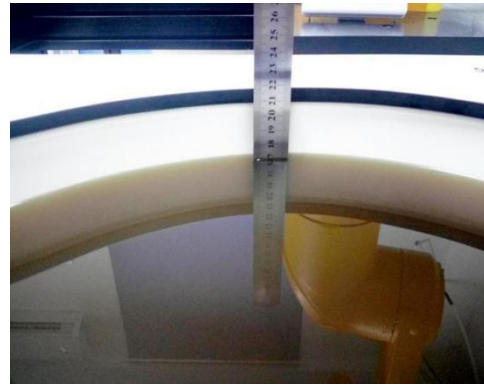


Fig 8.2 Photo of Liquid Height for Body SAR

The following table gives the recipes for tissue simulating liquids

Simulating Liquid for 5GHz, Manufactured by SPEAG

Ingredients	(% by weight)
Water	64~78%
Mineral oil	11~18%
Emulsifiers	9~15%
Additives and Salt	2~3%

Note: Please refer to the validation results for dielectric parameters of each frequency band.

The dielectric properties of the tissue simulating liquids were verified prior to the SAR evaluation using an Agilent 85033E Dielectric Probe Kit and an Agilent Network Analyzer.

Table 1: Dielectric Performance of Tissue Simulating Liquid

Frequency (MHz)	Tissue Type	Liquid Temp. (°C)	Conductivity (σ)	Conductivity Target (σ)	Delta (σ) (%)	Permittivity (ϵ_r)	Permittivity Target (ϵ_r)	Delta (ϵ_r) (%)	Limit (%)	Date
5250	HSL	22.6	4.710	4.71	0.00	34.601	35.95	-3.75	±5	2019.10.28
5750	HSL	22.9	5.443	5.22	4.27	33.737	35.35	-4.56	±5	2019.10.29
5250	HSL	22.6	4.830	4.71	2.55	35.246	35.95	-1.96	±5	2019.12.31
5750	HSL	22.9	5.248	5.22	0.54	35.642	35.35	0.83	±5	2019.12.31

9. SAR System Verification

Each DASY system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system performance check and system validation. System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder.

9.1. Purpose of System Performance check

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

9.2. System Setup

The output power on dipole port must be calibrated to 24 dBm (250 mW) before dipole is connected. In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave which comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The system check verifies that the system operates within its specifications. It is performed daily or before every SAR measurement. The system check uses normal SAR measurements in the flat section of the phantom with a matched dipole at a specified distance. The system verification setup is shown as below.



Fig 9.1 Photo of Dipole Setup

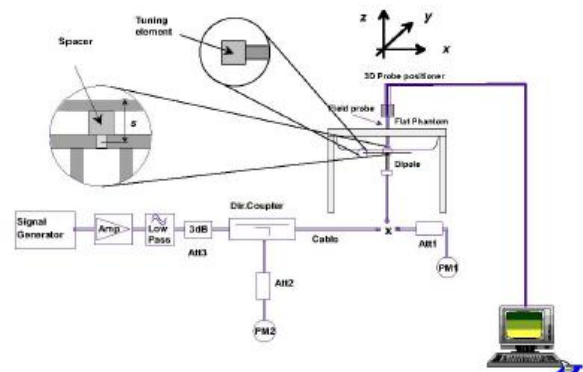


Fig 9.2 System Setup for System Evaluation

9.3. Validation Results

After system check testing, the SAR result will be normalized to 1W forward input power and compared with the reference SAR value derived from validation dipole certificate report. The deviation of system check should be within 10 %.

<Validation Setup>

Frequency (MHz) ²	Tissue Type	Input Power (mW)	Dipole S/N	Probe S/N	DAE S/N
5250	HSL	100	D5GHzV2-1176-5250	3685	871
5750	HSL	100	D5GHzV2-1176-5750	3685	871

<1g SAR>

Date	Frequency (MHz)	Tissue Type	Input Power (mW)	Measured 1g SAR (W/kg)	Targeted 1g SAR (W/kg)	Normalized 1g SAR (W/kg)	Deviation (%)
10.28	5250	HSL	100	8.05	78.90	80.5	2.03
10.29	5750	HSL	100	8.03	80.00	80.3	0.37
12.31	5250	HSL	100	7.97	78.90	79.7	1.01
12.31	5750	HSL	100	8.29	80.00	82.9	3.63

<10g SAR>

Date	Frequency (MHz) ²	Tissue Type	Input Power (mW)	Measured 10g SAR (W/kg)	Targeted 10g SAR (W/kg) ³	Normalized 10g SAR (W/kg)	Deviation (%)
10.28	5250	HSL	100	2.31	22.50	23.1	2.67
10.29	5750	HSL	100	2.29	22.60	22.9	1.33
12.31	5250	HSL	100	2.3	22.50	23	2.22
12.31	5750	HSL	100	2.37	22.60	23.7	4.87

Note: System checks the specific test data please see Annex C

10. EUT Testing Position

This EUT was tested in five different positions. The EUT with phantom 5 mm gap, as illustrated below, please refer to Appendix B for the test setup photos.

10.1. Body Configurations

For devices that employ one or more external antennas with variable positions (e.g. antenna extended, retracted, rotated), these shall be positioned in accordance with the user instructions provided by the manufacturer. For a device with only one antenna, if no intended antenna position is specified, tests shall be performed if applicable in both the horizontal and vertical positions relative to the phantom, and with the antenna oriented away from the body of the DUT and/or with the antenna extended and retracted such as to obtain the highest exposure condition. For antennas that may be rotated through one or two planes, an evaluation should be made and documented in the measurement report to the highest exposure scenario and only that position(s) need(s) to be tested.

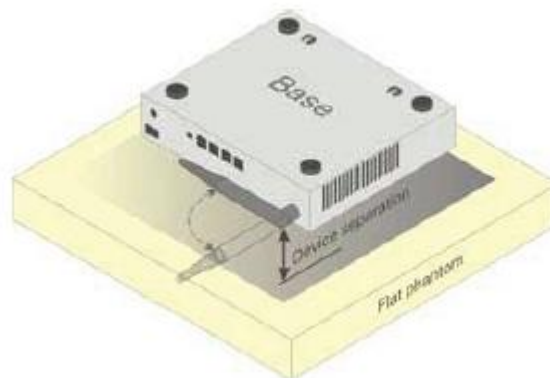


Fig 10.1 Device with swivel antenna

11. Measurement Procedures

The measurement procedures are as follows:

<Conducted power measurement>

- (a) For WWAN power measurement, use base station simulator to configure EUT WWAN transmission in conducted connection with RF cable, at maximum power in each supported wireless interface and frequency band.
- (b) Read the WWAN RF power level from the base station simulator.
- (c) For WLAN/BT power measurement, use engineering software to configure EUT WLAN/BT continuously transmission, at maximum RF power in each supported wireless interface and frequency band
- (d) Connect EUT RF port through RF cable to the power meter, and measure WLAN/BT output power

<SAR measurement>

- (a) Use base station simulator to configure EUT WWAN transmission in radiated connection, and engineering software to configure EUT WLAN/BT continuously transmission, at maximum RF power, in the highest power channel
- (b) Place the EUT in the positions as Appendix D demonstrates.
- (c) Set scan area, grid size and other setting on the DASY software.
- (d) Measure SAR results for the highest power channel on each testing position.
- (e) Find out the largest SAR result on these testing positions of each band
- (f) Measure SAR results for other channels in worst SAR testing position if the reported SAR of highest power channel is larger than 0.8 W/kg

According to the test standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- (a) Power reference measurement
- (b) Area scan
- (c) Zoom scan
- (d) Power drift measurement

11.1. Spatial Peak SAR Evaluation

The procedure for spatial peak SAR evaluation has been implemented according to the test standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY software includes all numerical procedures necessary to evaluate the spatial peak SAR value. The base for the evaluation is a "cube" measurement. The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the



measured volume is aligned to the interpolated peak SAR value of a previously performed area scAnt.

The entire evaluation of the spatial peak values is performed within the post-processing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- (a) Extraction of the measured data (grid and values) from the Zoom Scan
- (b) Calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- (c) Generation of a high-resolution mesh within the measured volume
- (d) Interpolation of all measured values from the measurement grid to the high-resolution grid
- (e) Extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- (f) Calculation of the averaged SAR within masses of 1g and 10g

11.2. Power Reference Measurement

The Power Reference Measurement and Power Drift Measurements are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface determines the closest measurement point to phantom surface. This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties.

11.3. Area Scan Procedures

Area scans are defined prior to the measurement process being executed with a user defined variable spacing between each measurement point (integral) allowing low uncertainty measurements to be conducted. Scans defined for FCC applications utilize a 10mm² step integral, with 1mm interpolation used to locate the peak SAR area used for zoom scan assessments.

When an Area Scan has measured all reachable points, it computes the field maxima founding the scanned area, within a range of the global maximum. The range (in dB) is specified in the standards for compliance testing. For example, a 2 dB range is required in IEEE1528-2003, EN 50361 and IEC 62209 standards, whereby 3 dB is a requirement when compliance is assessed in accordance with the ARIB standard (Japan).



11.4. Zoom Scan Procedures

Zoom Scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. A density of 1000 kg/m³ is used to represent the head and body tissue density and not the phantom liquid density, in order to be consistent with the definition of the liquid dielectric properties, i.e. the side length of the 1g cube is 10mm, with the side length of the 10 g cube 21,5mm. The zoom scan integer steps can be user defined so as to reduce uncertainty, but normal practice for typical test applications utilize a physical step of 5x5x7 (8mmx8mmx5mm) providing a volume of 32mm in the X & Y axis, and 30mm in the Z axis.

11.5. SAR Averaged Methods

In DASy, the interpolation and extrapolation are both based on the modified Quadratic Sheppard's method. The interpolation scheme combines a least-square fitted function method and a weighted average method which are the two basic types of computational interpolation and approximation.

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. The uncertainty increases with the extrapolation distance. To keep the uncertainty within 1% for the 1 g and 10 g cubes, the extrapolation distance should not be larger than 5 mm.

11.6. Power Drift Monitoring

All SAR testing is under the DUT install full charged battery and transmit maximum output power. In DASy measurement software, the power reference measurement and power drift measurement procedures are used for monitoring the power drift of DUT during SAR test. Both these procedures measure the field at a specified reference position before and after the SAR testing. The software will calculate the field difference in dB. If the power drift more than 5%, the SAR will be retested.

12. SAR Test Procedure

12.1. General scan Requirements

Probe boundary effect error compensation is required for measurements with the probe tip closer than half a probe tip diameter to the phantom surface. Both the probe tip diameter and sensor offset distance must satisfy measurement protocols; to ensure probe boundary effect errors are minimized and the higher fields closest to the phantom surface can be correctly measured and extrapolated to the phantom surface for computing 1-g SAR. Tolerances of the post-processing algorithms must be verified by the test laboratory for the scan resolutions used in the SAR measurements, according to the reference distribution functions specified in IEEE Std 1528-2013.

			≤ 3 GHz	> 3 GHz
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface			5 mm $\pm$ 1 mm	$\frac{1}{4} \cdot \delta \cdot \ln(2)$ mm $\pm$ 0.5 mm
Maximum probe angle from probe axis to phantom surface normal at the measurement location			30° $\pm$ 1°	20° $\pm$ 1°
Maximum area scan spatial resolution: Δx_{Area} , Δy_{Area}			≤ 2 GHz: ≤ 15 mm 2 – 3 GHz: ≤ 12 mm	3 – 4 GHz: ≤ 12 mm 4 – 6 GHz: ≤ 10 mm
			When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be $\leq$ the corresponding x or y dimension of the test device with at least one measurement point on the test device.	
Maximum zoom scan spatial resolution: Δx_{Zoom} , Δy_{Zoom}			≤ 2 GHz: ≤ 8 mm 2 – 3 GHz: ≤ 5 mm*	3 – 4 GHz: ≤ 5 mm* 4 – 6 GHz: ≤ 4 mm*
Maximum zoom scan spatial resolution, normal to phantom surface	uniform grid: $\Delta z_{Zoom}(n)$		≤ 5 mm	3 – 4 GHz: ≤ 4 mm 4 – 5 GHz: ≤ 3 mm 5 – 6 GHz: ≤ 2 mm
	graded grid	$\Delta z_{Zoom}(1)$: between 1 st two points closest to phantom surface	≤ 4 mm	3 – 4 GHz: ≤ 3 mm 4 – 5 GHz: ≤ 2.5 mm 5 – 6 GHz: ≤ 2 mm
		$\Delta z_{Zoom}(n>1)$: between subsequent points	$\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$ mm	
Minimum zoom scan volume	x, y, z		≥ 30 mm	3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm
Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see IEEE Std 1528-2013 for details.				
* When zoom scan is required and the <u>reported</u> SAR from the <u>area scan based 1-g SAR estimation</u> procedures of KDB Publication 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.				

12.2. Test procedure

The Following steps are used for each test position

1. Establish a call with the maximum output power with a base station simulator. The connection between the mobile and the base station simulator is established via air interface.
2. Measurement of the local E-field value at a fixed location. This value serves as a reference value for calculating a possible power drift.
3. Measurement of the SAR distribution with a grid of 8 to 16mm * 8 to 16 mm and a constant distance to the inner surface of the phantom. Since the sensors cannot directly measure at the inner phantom surface, the values between the sensors and the inner phantom surface are extrapolated. With these values the area of the maximum SAR is calculated by an interpolation scheme.
4. Around this point, a cube of 30 * 30 * 30 mm or 32 * 32 * 32 mm is assessed by measuring 5 or 8 * 5 or 8*4 or 5 mm. With these data, the peak spatial-average SAR value can be calculated.

12.3. Description of interpolation/extrapolation scheme

The local SAR inside the phantom is measured using small dipole sensing elements inside a probe body. The probe tip must not be in contact with the phantom surface in order to minimize measurements errors, but the highest local SAR will occur at the surface of the phantom.

An extrapolation is using to determinate this highest local SAR values. The extrapolation is based on a fourth-order least-square polynomial fit of measured data. The local SAR value is then extrapolated from the liquid surface with a 1mm step.

The measurements have to be performed over a limited time (due to the duration of the battery) so the step of measurement is high. It could vary between 5 and 8 mm. To obtain an accurate assessment of the maximum SAR averaged over 10 grams and 1 gram requires a very fine resolution in the three dimensional scanned data array.

13. SAR Test Configuration

<WLAN 5GHz>

A)U-NII-1 and U-NII-2A Bands

For devices that operate in only one of the U-NII-1 and U-NII-2A bands, the normally required SAR procedures for OFDM configurations are applied. For devices that operate in both U-NII bands using the same transmitter and antenna(s), SAR test reduction is determined according to the following:

- 1) When the same maximum output power is specified for both bands, begin SAR measurement in U- NII-2A band by applying the OFDM SAR requirements. If the highest reported SAR for a test configuration is ≤ 1.2 W/kg, SAR is not required for U-NII-1 band for that configuration (802.11 mode and exposure condition); otherwise, both bands are tested independently for SAR.
- 2) When different maximum output power is specified for the bands, begin SAR measurement in the band with higher specified maximum output power. The highest reported SAR for the tested configuration is adjusted by the ratio of lower to higher specified maximum output power for the two bands. When the adjusted SAR is ≤ 1.2 W/kg, SAR is not required for the band with lower maximum output power in that test configuration; otherwise, both bands are tested independently for SAR.
- 3)The two U-NII bands may be aggregated to support a 160 MHz channel on channel number 50. Without additional testing, the maximum output power for this is limited to the lower of the maximum output power certified for the two bands. When SAR measurement is required for at least one of the bands and the highest reported SAR adjusted by the ratio of specified maximum output power of aggregated to standalone band is > 1.2 W/kg, SAR is required for the 160 MHz channel. This procedure does not apply to an aggregated band with maximum output higher than the standalone band(s); the aggregated band must be tested independently for SAR. SAR is not required when the 160 MHz channel is operating at a reduced maximum power and also qualifies for SAR test exclusion.

B)U-NII-2C and U-NII-3 Bands

The frequency range covered by these bands is 380 MHz (5.47 – 5.85 GHz), which requires a minimum of at least two SAR probe calibration frequency points to support SAR measurements. when Terminal Doppler Weather Radar (TDWR) restriction applies, all channels that operate at 5.60 – 5.65 GHz must be included to apply the SAR test reduction and measurement procedures. When the same transmitter and antenna(s) are used for U-NII-2C band and U-NII-3 band or 5.8 GHz band of §15.247, the bands may be aggregated to enable additional channels with 20, 40 or 80 MHz bandwidth to span across the band gap, as illustrated in Appendix B. The maximum output power for the additional band gap channels is limited to the lower of those certified for the bands. Unless band gap channels are permanently disabled, they must be considered for SAR testing. The frequency range covered by these bands is 380 MHz (5.47 – 5.85 GHz), which requires a minimum of at least two SAR probe calibration frequency points to support SAR measurements. To



maintain SAR measurement accuracy and to facilitate test reduction, the channels in U-NII-2C band above 5.65 GHz may be grouped with the 5.8 GHz channels in U-NII-3 or §15.247 band to enable two SAR probe calibration frequency points to cover the bands, including the band gap channels. When band gap channels are supported and the bands are not aggregated for SAR testing, band gap channels must be considered independently in each band according to the normally required OFDM SAR measurement and probe calibration frequency points requirements.

C) OFDM Transmission Mode SAR Test Configuration and Channel Selection Requirements

The initial test configuration for 5 GHz OFDM transmission modes is determined by the 802.11 configuration with the highest maximum output power specified for production units, including tune-up tolerance, in each standalone and aggregated frequency band. SAR for the initial test configuration is measured using the highest maximum output power channel determined by the default power measurement procedures. When multiple configurations in a frequency band have the same specified maximum output power, the initial test configuration is determined according to the following steps applied sequentially.

- 1) The largest channel bandwidth configuration is selected among the multiple configurations with the same specified maximum output power.
- 2) If multiple configurations have the same specified maximum output power and largest channel bandwidth, the lowest order modulation among the largest channel bandwidth configurations is selected.
- 3) If multiple configurations have the same specified maximum output power, largest channel bandwidth and lowest order modulation, the lowest data rate configuration among these configurations is selected.
- 4) When multiple transmission modes (802.11a/g/n/ac) have the same specified maximum output power, largest channel bandwidth, lowest order modulation and lowest data rate, the lowest order 802.11 mode is selected; i.e., 802.11a is chosen over 802.11n then 802.11ac or 802.11g is chosen over 802.11n. After an initial test configuration is determined, if multiple test channels have the same measured maximum output power, the channel chosen for SAR measurement is determined according to the following. These channel selection procedures apply to both the initial test configuration and subsequent test configuration(s), with respect to the default power measurement procedures or additional power measurements required for further SAR test reduction. The same procedures also apply to subsequent highest output power channel(s) selection.

- 1) The channel closest to mid-band frequency is selected for SAR measurement.
- 2) For channels with equal separation from mid-band frequency; for example, high and low channels or two mid-band channels, the higher frequency (number) channel is selected for SAR measurement.

D) SAR Test Requirements for OFDM configurations

When SAR measurement is required for 802.11 a/n/ac OFDM configurations, each standalone and frequency aggregated band is considered separately for SAR test reduction. When the same transmitter and antenna(s) are used for U-NII-1 and U-NII-2A bands, additional SAR test



reduction Vapplies. When band gap channels between U-NII-2C band and 5.8 GHz U-NII-3 or §15.247 band are supported, the highest maximum output power transmission mode configuration and maximum output power channel across the bands must be used to determine SAR test reduction, according to the initial test configuration and subsequent test configuration requirements. In applying the initial test configuration and subsequent test configuration procedures, the 802.11 transmission configuration with the highest specified maximum output power and the channel within a test configuration with the highest measured maximum output power should be clearly distinguished to apply the procedures.



14. Conducted RF Output Power

5GHz WLAN:

5.2GHz WLAN ANT A	Mode	Channel	Frequency (MHz)	Average power (dBm)	Tune-Up Limit	Power Setting	Duty Cycle %
	802.11n-HT20 MCS0	CH 36	5180	16.27	16.50	17.5	97.93
		CH 40	5200	16.28	16.50	17.5	
		CH 48	5240	16.18	16.50	17.5	

5.8GHz WLAN ANT A	Mode	Channel	Frequency (MHz)	Average power (dBm)	Tune-Up Limit	Power Setting	Duty Cycle %
	802.11n-HT20 MCS0	CH 149	5745	16.29	16.50	17.5	97.93
		CH 157	5785	17.20	17.50	17.5	
		CH 165	5825	17.27	17.50	17.5	

Note: The WLAN 5G Antenna A gain is 2.15dBi

5.2GHz WLAN ANT B	Mode	Channel	Frequency (MHz)	Average power (dBm)	Tune-Up Limit	Power Setting	Duty Cycle %
	802.11n-HT20 MCS0	CH 36	5180	17.21	18.00	17.5	97.93
		CH 40	5200	17.98	18.50	17.5	
		CH 48	5240	17.95	18.50	17.5	

5.8GHz WLAN ANT B	Mode	Channel	Frequency (MHz)	Average power (dBm)	Tune-Up Limit	Power Setting	Duty Cycle %
	802.11n-HT20 MCS0	CH 149	5745	17.33	17.50	17.5	97.93
		CH 157	5785	16.54	17.00	17.5	
		CH 165	5825	17.65	18.00	17.5	

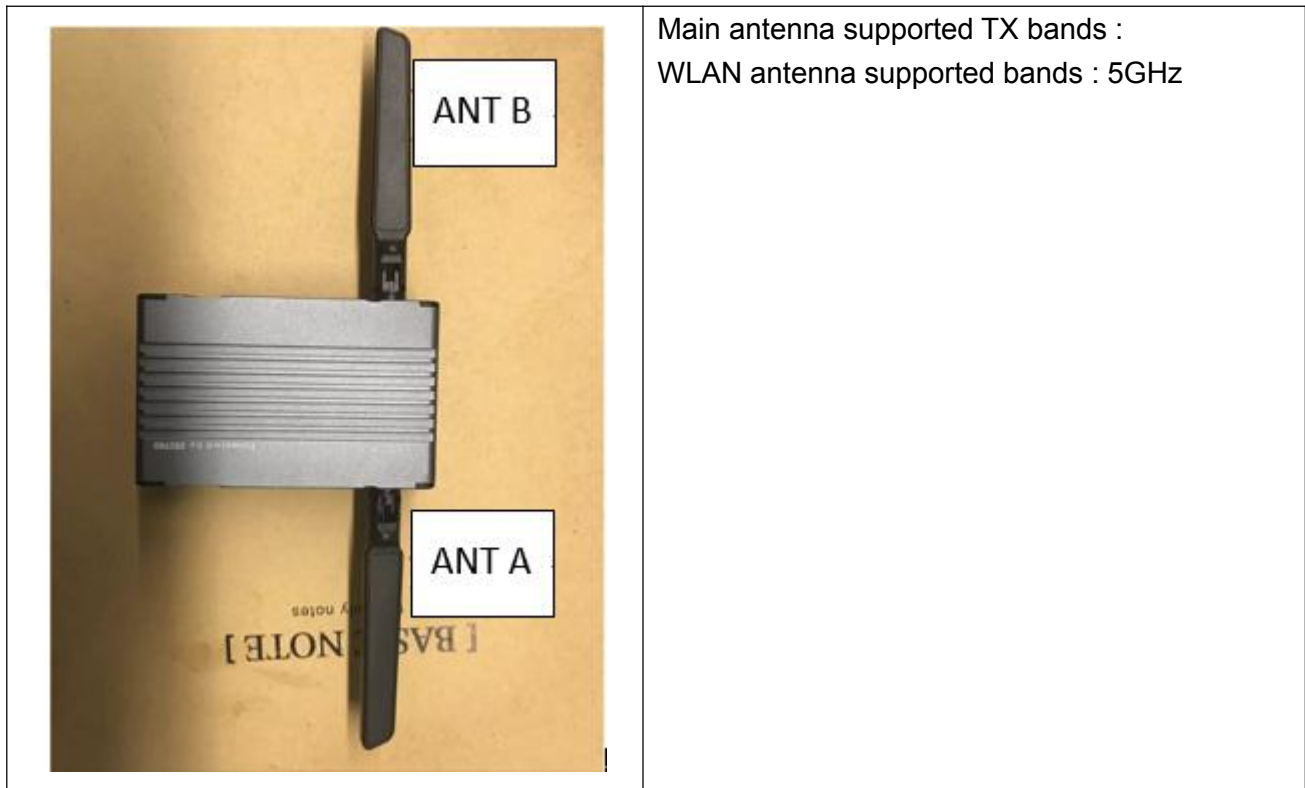
Note: The WLAN 5G Antenna B gain is 2.2dBi

**ANT A+ANT B**

5.2GHz WLAN ANT A+B	Mode	Channel	Frequency (MHz)	Average power (dBm)	Tune-Up Limit	Power Setting	Duty Cycle %
	802.11n-HT20 MCS0	CH 36	5180	19.87	20.50	17.5	97.93
		CH 40	5200	20.31	20.50	17.5	
		CH 48	5240	20.26	20.50	17.5	

5.8GHz WLAN ANT A+B	Mode	Channel	Frequency (MHz)	Average power (dBm)	Tune-Up Limit	Power Setting	Duty Cycle %
	802.11n-HT20 MCS0	CH 149	5745	19.94	20.50	17.5	97.93
		CH 157	5785	19.98	20.50	17.5	
		CH 165	5825	20.57	21.00	17.5	

15. EUT Antenna Location



Evaluation:

Assessment	SAR Test distance: 5mm				
Test position	Ant in close 0 degrees	Ant in close 90 degrees	Ant in close 180 degrees	Ant in open 45 degrees	Ant in open 90 degrees
WLAN Antenna A	Yes	Yes	Yes	Yes	Yes
WLAN Antenna B	Yes	Yes	Yes	Yes	Yes

16. Block diagram of the tests to be performed

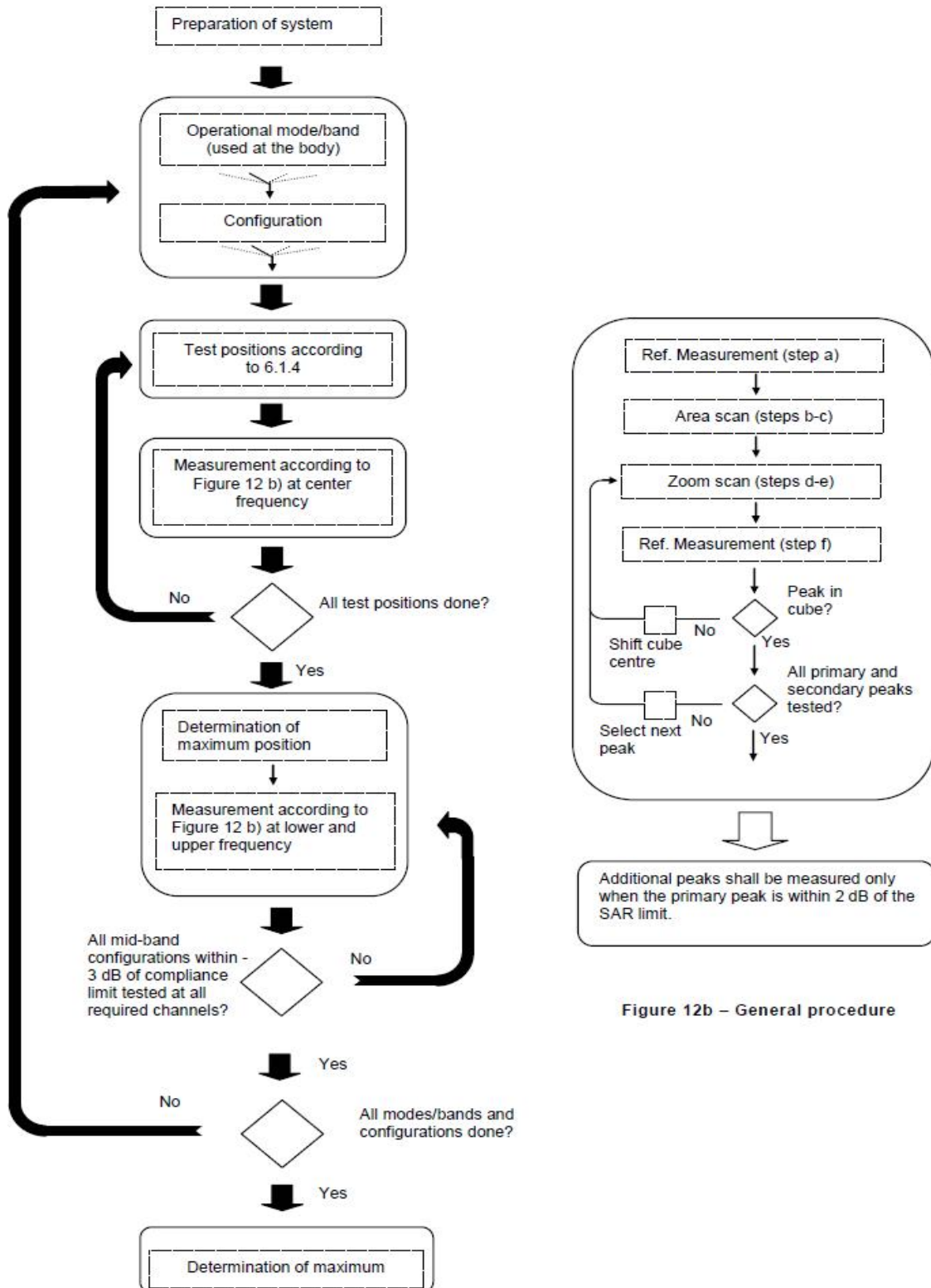


Figure 12b – General procedure

17. Test Results List

17.1. Test Guidance

1. Per KDB 447498 D01v06, the reported SAR is the measured SAR value adjusted for maximum tune-up tolerance.
 - a. Tune-up scaling Factor = tune-up limit power (mW) / EUT RF power (mW), where tune-up limit is the maximum rated power among all production units.
 - b. For SAR testing of WLAN signal with non-100% duty cycle, the measured SAR is scaled-up by the duty cycle scaling factor which is equal to "1/(duty cycle)"
 - c. For WWAN: Reported SAR(W/kg)= Measured SAR(W/kg)*Tune-up Scaling Factor
 - d. For WLAN/Bluetooth: Reported SAR(W/kg)= Measured SAR(W/kg)* Duty Cycle scaling factor * Tune-up scaling factor
2. Per KDB 447498 D01v06, for each exposure position, testing of other required channels within the operating mode of a frequency band is not required when the *reported* 1-g or 10-g SAR for the mid-band or highest output power channel is:
 - ≤ 0.8 W/kg or 2.0 W/kg, for 1-g or 10-g respectively, when the transmission band is ≤ 100 MHz
 - ≤ 0.6 W/kg or 1.5 W/kg, for 1-g or 10-g respectively, when the transmission band is between 100 MHz and 200 MHz
 - ≤ 0.4 W/kg or 1.0 W/kg, for 1-g or 10-g respectively, when the transmission band is ≥ 200 MHz
3. Per KDB 865664 D01v01r04, for each frequency band, repeated SAR measurement is required only when the measured SAR is ≥ 0.8 W/kg.
4. Per KDB648474 D04v01r03, for smart phones with a display diagonal dimension > 15.0 cm or an overall diagonal dimension > 16.0 cm, when hotspot mode applies, 10-g extremity SAR is required only for the surfaces and edges with hotspot mode 1-g reported SAR > 1.2 W/kg, however, when power reduction applies to hotspot mode the measured SAR must be scaled to the maximum output power, including tolerance, allowed for tablet modes to compare with the 1.2 W/kg SAR test reduction threshold.
5. Per KDB248227 D01v02r02,a Wi-Fi device must be configured to transmit continuously at the required data rate, channel bandwidth and signal modulation, using the highest transmission duty factor supported by the test mode tools for SAR measurement. The test frequencies established using test mode must correspond to the actual channel frequencies required for operations in the U.S. When 802.11 frame gaps are accounted for in the transmission, a maximum transmission duty factor of 92 - 96% is typically achievable in most test mode



configurations. A minimum transmission duty factor of 85% is required to avoid certain hardware and device implementation issues related to wide range SAR scaling. In addition, a periodic transmission duty factor is required for current generation SAR systems to measure SAR correctly. Unless it is permitted by specific KDB procedures or continuous transmission is specifically restricted by the device, the reported SAR must be scaled to 100% transmission duty factor to determine compliance at the maximum tune-up tolerance limit. When a device is not capable of sustaining continuous transmission or the output can become nonlinear, and it is limited by hardware design and unable to transmit at higher than 85% duty factor, a periodic duty factor within 15% of the maximum duty factor the device is capable of transmitting should be used. The reported SAR must be scaled to the maximum transmission duty factor to determine compliance. Descriptions of the procedures applied to establish the specific duty factor used for SAR testing are required in SAR reports to support the test results.

17.2. Body SAR Data

<5G WLAN >

ANT A

Plot No.	Mode	Test Position	Ch.	Average Power (dBm)	Tune-Up Limit (dBm)	Tune-up Scaling Factor	Duty Cycle Scaling Factor	Measured 1g SAR (W/kg)	Reported 1g SAR (W/kg)
Band 1									
	802.11n	close_0 degrees	40	16.28	16.5	1.052	1.021	0.336	0.361
	802.11n	close_90 degrees	40	16.28	16.5	1.052	1.021	0.153	0.164
1#	802.11n	close_180 degrees	40	16.28	16.5	1.052	1.021	0.402	0.432
	802.11n	open_45 degrees	40	16.28	16.5	1.052	1.021	0.202	0.217
	802.11n	open_90 degrees	40	16.28	16.5	1.052	1.021	0.273	0.293
Band 4									
	802.11n	close_0 degrees	165	17.27	17.5	1.054	1.021	0.361	0.389
	802.11n	close_90 degrees	165	17.27	17.5	1.054	1.021	0.202	0.217
2#	802.11n	close_180 degrees	165	17.27	17.5	1.054	1.021	0.604	0.650
	802.11n	open_45 degrees	165	17.27	17.5	1.054	1.021	0.360	0.388
	802.11n	open_90 degrees	165	17.27	17.5	1.054	1.021	0.355	0.382

**ANT B**

Plot No.	Mode	Test Position	Ch.	Average Power (dBm)	Tune-Up Limit (dBm)	Tune-up Scaling Factor	Duty Cycle Scaling Factor	Measured 1g SAR (W/kg)	Reported 1g SAR (W/kg)
Band 1									
	802.11n	close_0 degrees	40	17.98	18.5	1.127	1.021	0.447	0.514
	802.11n	close_90 degrees	40	17.98	18.5	1.127	1.021	0.194	0.223
	802.11n	close_180 degrees	40	17.98	18.5	1.127	1.021	0.451	0.519
3#	802.11n	open_45 degrees	40	17.98	18.5	1.127	1.021	0.649	0.747
	802.11n	open_90 degrees	40	17.98	18.5	1.127	1.021	0.641	0.738
Band 4									
	802.11n	close_0 degrees	165	17.65	18	1.084	1.021	0.732	0.810
	802.11n	close_90 degrees	165	17.65	18	1.084	1.021	0.252	0.279
	802.11n	close_180 degrees	165	17.65	18	1.084	1.021	0.809	0.895
	802.11n	open_45 degrees	165	17.65	18	1.084	1.021	1.050	1.162
	802.11n	open_90 degrees	165	17.65	18	1.084	1.021	0.734	0.812
	802.11n	open_45 degrees	149	17.33	17.5	1.040	1.021	1.000	1.062
4#	802.11n	open_45 degrees	157	16.54	17	1.112	1.021	1.030	1.169
	802.11n	close_180 degrees	149	17.33	17.5	1.040	1.021	0.773	0.821
	802.11n	close_180 degrees	157	16.54	17	1.112	1.021	0.764	0.867
	802.11n	close_0 degrees	149	17.33	17.5	1.040	1.021	0.750	0.796
	802.11n	close_0 degrees	157	16.54	17	1.112	1.021	0.742	0.842
	802.11n	open_90 degrees	149	17.33	17.5	1.040	1.021	0.753	0.800
	802.11n	open_90 degrees	157	16.54	17	1.112	1.021	0.744	0.844

Note: The WLAN Reported 1g SAR (W/kg) has been calculated together with the duty cycle (97.93%) scaling factor.

**test at worst condition:**

Plot No.	Mode	Test Position	Ch.	Average Power (dBm)	Tune-Up Limit (dBm)	Tune-up Scaling Factor	Duty Cycle Scaling Factor	Measured 1g SAR (W/kg)	Reported 1g SAR (W/kg)
	802.11n	open_45 degrees	40	17.98	18.5	1.127	1.021	0.360	0.414
	802.11n	open_45 degrees	157	16.54	17	1.112	1.021	0.810	0.919

Note: According to KDB 484596D01, the report FCC ID: 2AIHFZYCOV02 some test data reference test data from original SAR report FCC ID: 2AIHFZYCOV01. The component differences between COV-01 and COV-02 are as follows:

1. COV-02 cancel the camera control interface and reduces components on the corresponding PCB.
2. HDMI interface is different: COV-01's HDMI interface is input; COV-02's HDMI interface is output; COV-02 has reduced one HDMI receiving chip. No other changes, all RF parameters remain the same as before. We have evaluated this change, test worst case mode and compared the data.

17.3. Repeated SAR Measurement

In accordance with published RF Exposure KDB procedure 865664 D01 SAR measurement 100 MHz to 6 GHz. These additional measurements are repeated after the completion of all measurements requiring the same head or body tissue-equivalent medium in a frequency band. The test device should be returned to ambient conditions (normal room temperature) with the battery fully charged before it is re-mounted on the device holder for the repeated measurement(s) to minimize any unexpected variations in the repeated results.

- 1) Repeated measurement is not required when the original highest measured SAR is < 0.80 W/kg; steps 2) through 4) do not apply.
- 2) When the original highest measured SAR is ≥ 0.80 W/kg, repeat that measurement once.
- 3) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 1.45 W/kg ($\sim 10\%$ from the 1-g SAR limit).
- 4) Perform a third repeated measurement only if the original, first or second repeated measurement is ≥ 1.5 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20 .

ANT B Repeat test result

Mode	Test Position	Ch.	Power Setting	Tune-up Scaling Factor	Duty Cycle Scaling Factor	Measured 1g SAR (W/kg)	Reported 1g SAR (W/kg)
Band 4							
802.11n	close_180 degrees	165	17.5	1.084	1.021	0.753	0.833
802.11n	open_45 degrees	165	17.5	1.084	1.0210	1.000	1.107

18. Simultaneous Transmission Evaluation

Simultaneous Evaluation:

No.	Simultaneous transmission Condition	Body
1	5GHz WLAN ANT A + ANT B	Yes

Note:

- Per KDB 447498D01v06, Simultaneous Transmission SAR Evaluation procedures is as followed:

Step 1: If sum of 1 g SAR < 1.6 W/kg, Simultaneous SAR measurement is not required.

Step 2: If sum of 1 g SAR > 1.6 W/kg, ratio of SAR to peak separation distance for pair of transmitters calculated.

Step 3: If the ratio of SAR to peak separation distance is ≤ 0.04 , Simultaneous SAR measurement is not required.

Step 4: If the ratio of SAR to peak separation distance is > 0.04 , Simultaneous SAR measurement is required and simultaneous transmission SAR value is calculated.

(The ratio is determined by: $(SAR1 + SAR2) \wedge 1.5/R_i \leq 0.04$,

R_i is the separation distance between the peak SAR locations for the antenna pair in mm.

- This device can only support simultaneous transmission within the same frequency band.

Band	5GHz WLAN ANT A	5GHz WLAN ANT B	WLAN ANT A+ ANT B
	Max. 1g SAR (W/kg)	Max. 1g SAR (W/kg)	Summed Max. 1g SAR (W/kg)
Band 1			
802.11n	0.432	0.747	1.179
Band 4			
802.11n	0.650	1.169	1.819

SAR (W/kg)	Gap	SAR peak location (cm)			3D distance (mm)	Summed SAR (W/kg)	SPLSR Results
	(mm)	X	Y	Z			
0.65	5	-0.039	-0.047	-0.207	60.80	1.82	0.04
1.169	5	-0.003	0.002	-0.207			

The ratio is determined by: $(SAR1 + SAR2) \wedge 1.5/R_i \leq 0.04$, So simultaneous transmission for ANT A& ANT B is unnecessary.

19. Uncertainty Assessment

The component of uncertainty may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainty by the statistical analysis of a series of observations is termed a Type A evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience, and knowledge of the behavior and properties of relevant materials and instruments, manufacture's specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in table below.

Uncertainty	Normal	Rectangular	Triangular	U-Shape
Multi-plying Factor ^(a)	1/ κ ^(b)	1/ $\sqrt{3}$	1/ $\sqrt{6}$	1/ $\sqrt{2}$

Table 19.1. Standard Uncertainty for Assumed Distribution

(a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity

(b) κ is the coverage factor

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual "root-sum-squares" (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %. The DASY uncertainty Budget is shown in the following



tables.

Error Description	Uncertainty Value (±%)	Probability	Divisor	(Ci) 1g	(Ci) 10g	Standard Uncertainty (1g) (±%)	Standard Uncertainty (10g) (±%)
Measurement System							
Probe Calibration	6.0	N	1	1	1	6.0	6.0
Axial Isotropy	4.7	R	1.732	0.7	0.7	1.9	1.9
Hemispherical Isotropy	9.6	R	1.732	0.7	0.7	3.9	3.9
Boundary Effects	1.0	R	1.732	1	1	0.6	0.6
Linearity	4.7	R	1.732	1	1	2.7	2.7
System Detection Limits	1.0	R	1.732	1	1	0.6	0.6
Modulation Response	3.2	R	1.732	1	1	1.8	1.8
Readout Electronics	0.3	N	1	1	1	0.3	0.3
Response Time	0.0	R	1.732	1	1	0.0	0.0
Integration Time	2.6	R	1.732	1	1	1.5	1.5
RF Ambient Noise	3.0	R	1.732	1	1	1.7	1.7
RF Ambient Reflections	3.0	R	1.732	1	1	1.7	1.7
Probe Positioner	0.4	R	1.732	1	1	0.2	0.2
Probe Positioning	2.9	R	1.732	1	1	1.7	1.7
Max. SAR Eval.	2.0	R	1.732	1	1	1.2	1.2
Test Sample Related							
Device Positioning	3.0	N	1	1	1	3.0	3.0
Device Holder	3.6	N	1	1	1	0.089	0.089
Power Drift	5.0	R	1.732	1	1	2.9	2.9
Power Scaling	0.0	R	1.732	1	1	0.0	0.0
Phantom and Setup							
Phantom Uncertainty	6.1	R	1.732	1	1	3.5	3.5
SAR correction	0.0	R	1.732	1	0.84	0.0	0.0
Liquid Conductivity Repeatability	0.2	N	1	0.78	0.71	0.1	0.1
Liquid Conductivity (target)	5.0	R	1.732	0.78	0.71	2.3	2.0
Liquid Conductivity (mea.)	2.5	R	1.732	0.78	0.71	1.1	1.0
Temp. unc. - Conductivity	3.4	R	1.732	0.78	0.71	1.5	1.4
Liquid Permittivity Repeatability	0.15	N	1	0.23	0.26	0.0	0.0
Liquid Permittivity (target)	5.0	R	1.732	0.23	0.26	0.7	0.8
Liquid Permittivity (mea.)	2.5	R	1.732	0.23	0.26	0.3	0.4
Temp. unc. - Permittivity	0.83	R	1.732	0.23	0.26	0.1	0.1
Combined Std. Uncertainty						11.4%	11.4%
Coverage Factor for 95 %						K=2	K=2
Expanded STD Uncertainty						22.9%	22.7%



Error Description	Uncertainty Value (±%)	Probability	Divisor	(Ci) 1g	(Ci) 10g	Standard Uncertainty (1g) (±%)	Standard Uncertainty (10g) (±%)
Measurement System							
Probe Calibration	6.55	N	1	1	1	6.0	6.0
Axial Isotropy	4.7	R	1.732	0.7	0.7	1.9	1.9
Hemispherical Isotropy	9.6	R	1.732	0.7	0.7	3.9	3.9
Boundary Effects	2.0	R	1.732	1	1	1.2	1.2
Linearity	4.7	R	1.732	1	1	2.7	2.7
System Detection Limits	1.0	R	1.732	1	1	0.6	0.6
Modulation Response	3.2	R	1.732	1	1	1.8	1.8
Readout Electronics	0.3	N	1	1	1	0.3	0.3
Response Time	0.0	R	1.732	1	1	0.0	0.0
Integration Time	2.6	R	1.732	1	1	1.5	1.5
RF Ambient Noise	3.0	R	1.732	1	1	1.7	1.7
RF Ambient Reflections	3.0	R	1.732	1	1	1.7	1.7
Probe Positioner	0.4	R	1.732	1	1	0.2	0.2
Probe Positioning	6.7	R	1.732	1	1	3.9	3.9
Max. SAR Eval.	4.0	R	1.732	1	1	2.3	2.3
Test Sample Related							
Device Positioning	3.0	N	1	1	1	3.0	3.0
Device Holder	3.6	N	1	1	1	0.089	0.089
Power Drift	5.0	R	1.732	1	1	2.9	2.9
Power Scaling	0.0	R	1.732	1	1	0.0	0.0
Phantom and Setup							
Phantom Uncertainty	6.1	R	1.732	1	1	3.8	3.8
SAR correction	0.0	R	1.732	1	0.84	0.0	0.0
Liquid Conductivity Repeatability	0.2	N	1	0.78	0.71	0.1	0.1
Liquid Conductivity (target)	5.0	R	1.732	0.78	0.71	2.3	2.0
Liquid Conductivity (mea.)	2.5	R	1.732	0.78	0.71	1.1	1.0
Temp. unc. - Conductivity	3.4	R	1.732	0.78	0.71	1.5	1.4
Liquid Permittivity Repeatability	0.15	N	1	0.23	0.26	0.0	0.0
Liquid Permittivity (target)	5.0	R	1.732	0.23	0.26	0.7	0.8
Liquid Permittivity (mea.)	2.5	R	1.732	0.23	0.26	0.3	0.4
Temp. unc. - Permittivity	0.83	R	1.732	0.23	0.26	0.1	0.1
Combined Std. Uncertainty						12.5%	12.5%
Coverage Factor for 95 %						K=2	K=2
Expanded STD Uncertainty						25.1 %	25.1%



Annex A General Information

1. Identification of the Responsible Testing Laboratory

Company Name:	Kehu-Morlab Test Laboratory
Department:	Morlab Laboratory
Address:	Unit 101, No.1732 Gangzhong Road, Xiamen Area, Pilot Free Trade Zone (Fujian), P. R. China
Responsible Test Lab Manager:	Di Dehai
Telephone:	+865925612050
Facsimile:	+865925612095

2. Identification of the Responsible Testing Location

Name:	Kehu-Morlab Test Laboratory
Address:	Unit 101, No.1732 Gangzhong Road, Xiamen Area, Pilot Free Trade Zone (Fujian), P. R. China

***** END OF MAIN REPORT *****