Perception Neuron 3 User Manual

Hardware Setup

1. Overview

Manufacturer: Beijing Noitom Technology Ltd.

Address: 502, Tower A,28 Xinjiekouwai Blvd, Beijing, China

1.1 Main Hardware list

PN3 gloves version:

| Item | Unit | QTY |
|-----------------|------|-----|
| PN3 Sensor | PC | 30 |
| PN3 Transceiver | PC | 1 |
| Body Straps | Set | 1 |
| PN3 Gloves | pari | 1 |
| Charging Case | PC | 5 |
| Suitcase | PC | 1 |
| Wibu dongle | PC | 1 |

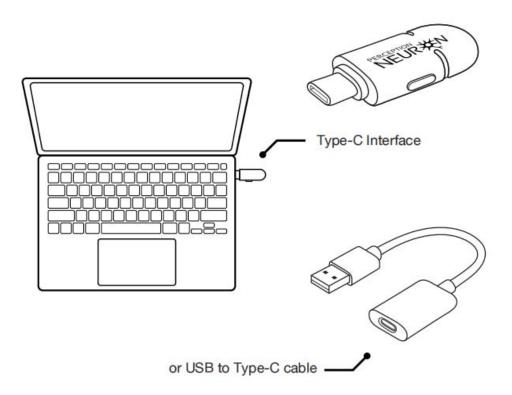
without pn3 gloves version:

| Item | Unit | QTY |
|-----------------|------|-----|
| PN3 Sensor | PC | 18 |
| PN3 Transceiver | PC | 1 |
| Body Straps | Set | 1 |
| Charging Case | PC | 3 |
| Suitcase | PC | 1 |

1.2 Computer Requirements

| Recommended |
|---------------------------|
| OS: Windows 10 |
| Direct X9 |
| OpenGL 4.4 |
| CPU: 3.0 GHz i5 processor |
| RAM: 4GB of memory |

1.3 Topological Diagram



2. Hardware information

2.1 PN3 Sensor

Wireless MEMS inertial sensor. Gyroscope, accelerometer and magnetometer integrated.



Turn on the PN3 Sensors

>>Automatically

After pull off the charging cable, the sensor will automatically turn on. If they are not be connected with Axis Studio, they will automatically turn off after 5min.

>>Manually

Even if we can automatically turn on the PN3 Sensors, we still can manually control it. Press the sensor button on the top for about 2s to turn on the sensor; Press the button for about 5s to turn off the sensor. The indicator light of the sensor will display the status. (Refer to the PN3 Sensor Indicator Instruction below)

Light Instruction

| Light status | Description |
|--------------|---|
| Slow Blink | Sensor in standby mode to save the power |
| Fast Blink | Sensor in working mode, calculating the transferring the data |
| Solid light | There is magnetic interference environment around the sensor |
| Red light | Sensor low battery/charging |
| Green light | Sensor in channel 1 |
| Blue light | Sensor in channel 2 |
| Purple light | Sensor in channel 3 |

Detailed parameters

| Item | parameters | Item | parameters |
|---------------------------|--------------------------------|-----------------------------|-----------------|
| size | 27.9 x 16.2 x 11.6 mm | Battery capacity | 42mAh |
| weight | 4.1g | Working hours | 6h |
| Range of gyroscope | ±2000dps | Data calculation frame rate | 600Hz |
| Accelerometer range | ±8g | Data output frame rate | 60Hz |
| Minimum resolution | 0.02degrees | time delay | < 20ms |
| Static attitude accuracy | Roll / Pitch 0.5°, Yaw 1.5° | Waterproof grade | IP66 |
| Dynamic attitude accuracy | Roll /Pitch 1.0°, Yaw 2.0° | working temperature | -10°C - 60°C |
| working voltage | 3.7V | Charging time | 1hr |

Charging

Insert the PN3 sensor into the charging box for charging.



2.2 PN3 Transceiver



The data transceiver is mainly used for instruction sending and data receiving. Command sending: the data transceiver receives the command from axis studio and sends it to each sensor through 2.4GHz wireless network.

Data receiving: the data transceiver receives the data from the sensor in real time through the 2.4GHz wireless network, synchronizes the time of the data, and transmits the data to the axis Studio software.

Light Instruction

| Light status | Description |
|-----------------|--------------------------|
| Red solid light | Wait for DHCP assignment |
| Green light | Transceiver in channel 1 |
| Blue light | Transceiver in channel 2 |
| Purple light | Transceiver in channel 3 |
| Yellow light | Stop broadcasting |

Detailed parameters

| Item | Parameters | Item | Parameters |
|--------|----------------------|-----------------------|------------|
| size | 38.5 x 17.2 x 6.7 mm | Interface type | USB Type-C |
| weight | 2.8g | transmission distance | 8m |

2.3 PN3 gloves

Use PN3 gloves for finger tracking.



Install Sensors

Insert the pn3 sensors into the gloves.



2.4 Charging Case

Case for charging and storing sensors. It's also an essential part for calibration.



Detailed parameters

| Item | Parameters |
|-------------------|------------|
| length | 146.23mm |
| width | 37.29mm |
| height | 24.30mm |
| Number of sockets | 6个 |
| Interface type | Туре С |

2.5 Suitcase

We provide two kinds of suitcase

| Item | Size |
|--------------------------|------------------------|
| Handy suitcase | 310×260×110mm |
| High strength safety box | 415× <i>335</i> ×180mm |

Handy suitcase:



High strength safety box:



2.6 Body Straps



Use the appropriate length of strap that fits the performer for each segment. Attach the straps according to the diagram below.

Detailed parameters

| Item | Size |
|---------------------------|------------------------|
| Shoulder and back bandage | 3.8cm×35cm, 3.8cm×47cm |
| Waist strap | 10cm×115cm |
| Thigh strap | 5cm×70cm |
| Head strap | 5cm×70cm |
| Upper arm bandage | 5cm×55cm |
| Leg bandage | 5cm×55cm |
| Small arm strap | 5cm×40cm |
| Foot bandage | 5cm×40cm |
| Hand bandage | 5cm×27.5cm |

2.7 Wibu dongle



Used for software activation and payment function unlocking.

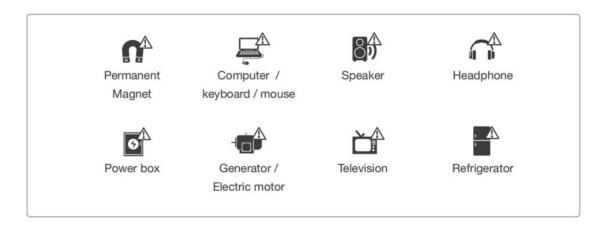
3. Preparing the Capture Area

Axis Studio contains magnetometers, magnetometer sensors can be affected by strong magnetic environment. Users must operate the sensors in an environment with the least amount of magnetic interference.

If you choose to use Perception Neuron Studio Inertial System in a location with strong magnetic interference, utilize our "Anti-mag mode" found in our software.

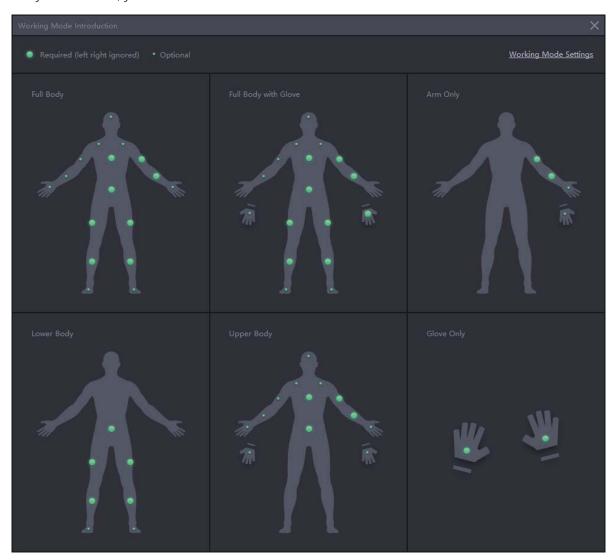


Keep 10-100 cm (depending on the strength of the source) away from magnetic sources.



4. Working mode introduction

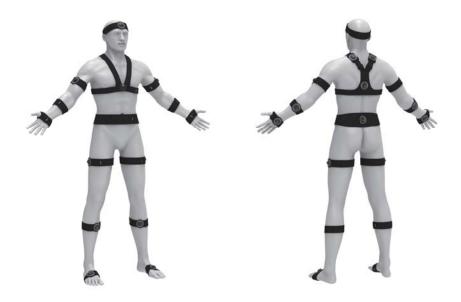
There are six different wearing modes. You can wear the corresponding straps and sensors according to different needs. For example, if you only need to capture hand movements or upper body movements, you do not need to wear a full set of devices.



4.1 Wear straps

Choose the appropriate length of bandage to fit all parts of the human body, and wear the bandage according to the position in the figure below. Because the PN3 sensor measures the movement of bones, it is necessary to eliminate the interference of muscle stretching and shaking as much as possible. The wearable position needs to choose the position with the least amount of muscle, which can capture the data better.

The posture calibration in the future will recalculate the wearing position. Even if there is a little error between the wearing position and the picture, it can be used normally.



4.2 Insert sensors

Insert the PN3 sensor into the base of the strap to ensure that it will not fall off due to movement.



Software Setup

1. Overview

1.1 Version list

| Software | Version |
|---------------------|----------------------|
| Windows(Microsoft) | Microsoft Windows 10 |
| Axis Studio(Noitom) | Axis_Studio_x64_2_4 |

1.2 Installation

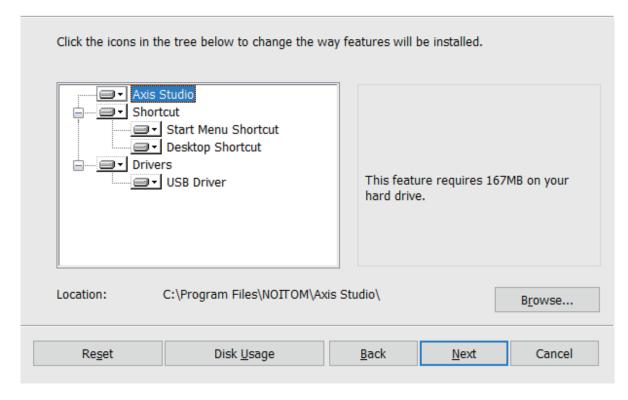
Run the installer to initiate the installation process. Follow the installation prompts and install Axis Studio. We recommend installing the software in the default directory.



Custom Setup

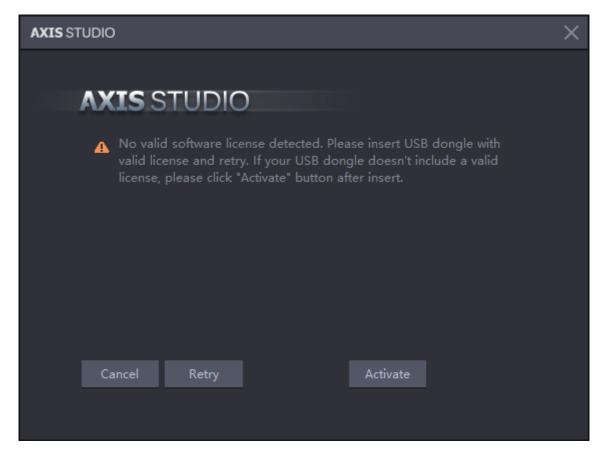
Select the way you want features to be installed.



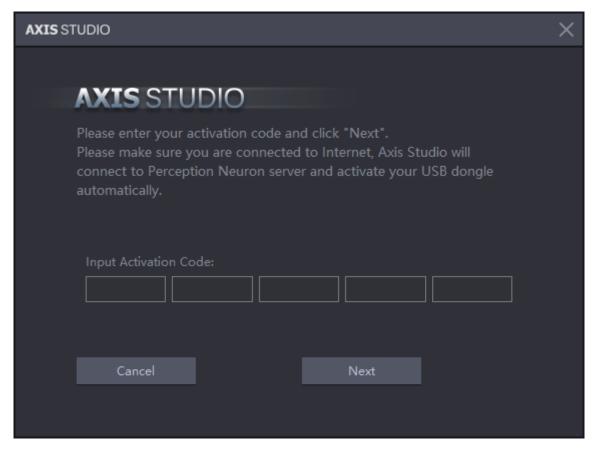


1.3 Activate

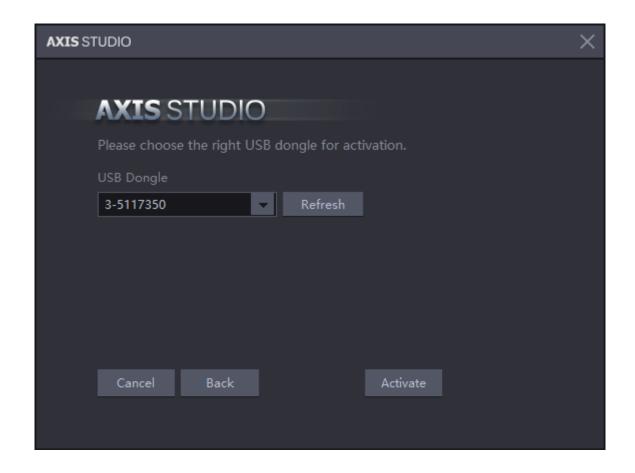
Plug in the Wibu dongle.



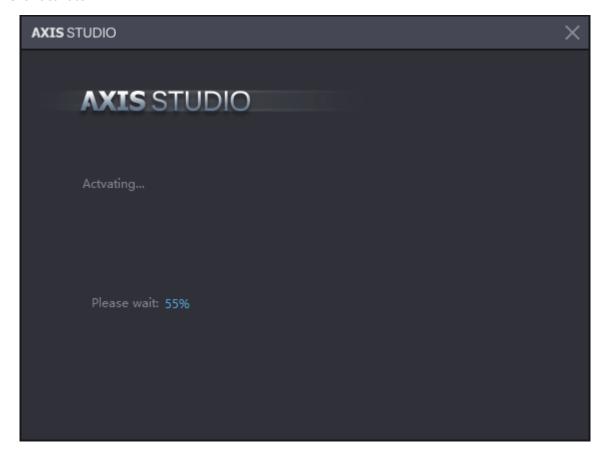
Click activate, input activation code and click next.



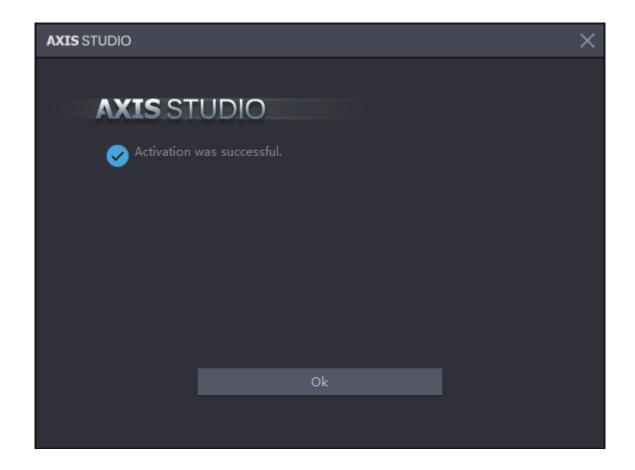
If there are more than 2 wibu dongles in your computer, please choose the right USB dongle for activation.



Click activate



Click ok to run the Axis Studio software.



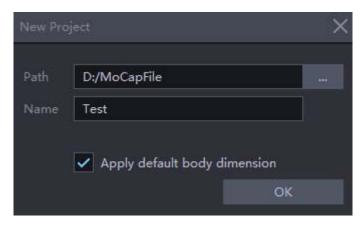
2. First launch

You can create or open project. Use Projects to manage all the files associated with motion capture sessions.

2.1 Project management

Create project

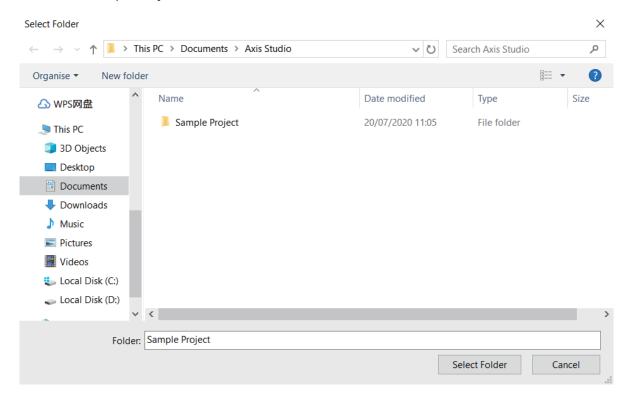
- Click New Project.
- Enter the project name and choose the location of the project.
- Selecting Add default body size will include body size preset into your project.



Open Project

Opening a project opens an already created project, and we provide a sample project data for reference.

- Click Open Project.
- Select Sample Project folder.



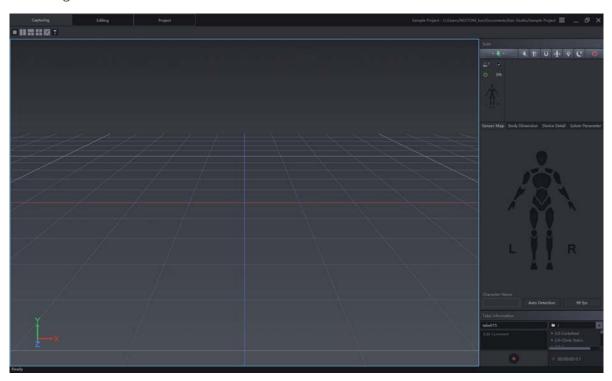
2.2 Connect PN3 hardware

• When connecting the transceiver for the first time, the following interface will pop up, please click Yes. This step allows Axis Studio software to automatically identify the transceiver without manual setup. (USB mode)



• If you use Ethernet mode, this interface will not pop up, you don't need to set any IP address, just wait for a moment, the transceiver will automatically be connected.

• If the hardware part has been deployed, the interface should be as shown in the figure. Click the green connection button to enter the wizard mode.



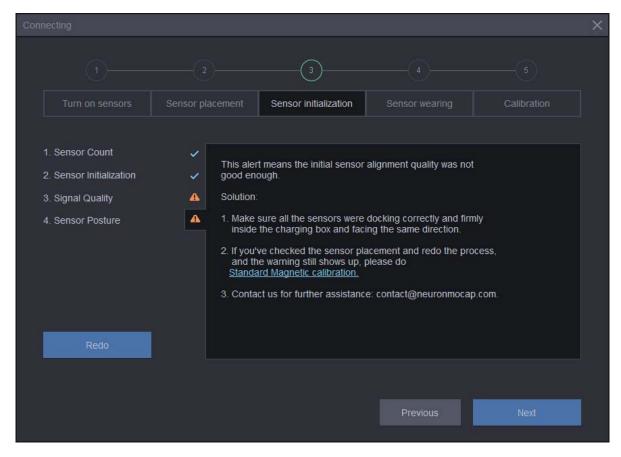
• Plug and unplug the charging box and the PNS sensor will automatically turn on. Press the side switch of PNS gloves for about 2S to open the gloves. Click next after opening.



• Place a non-iron table or high stool in the center of the moving capture area, stack the antimagnetic suitcase on the table, and put the sensor charging case and gloves on the suitcase. Click Next when you're done.

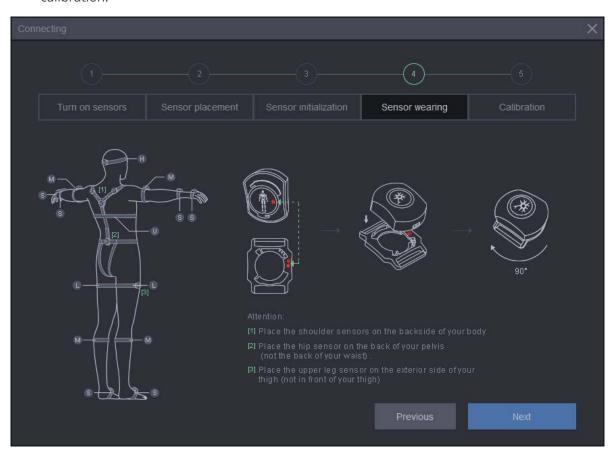


This step will carry out four checks. If the orange exclamation mark as shown in the figure
appears, clicking the exclamation mark will show the cause of the error. Please check the
device according to the solution on the picture, and click the next step until all the four items
are correct.

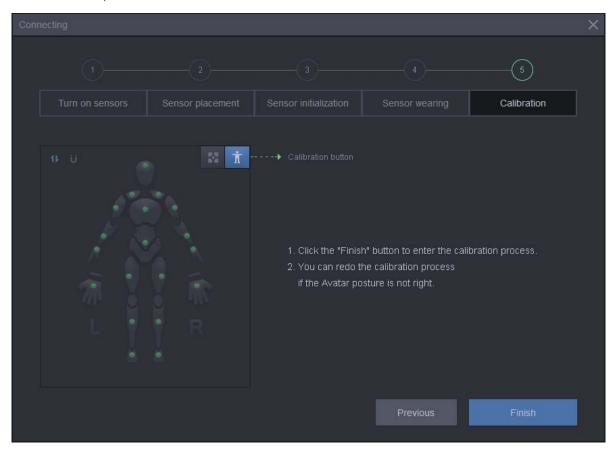


• Please refer to the wearing part in the hardware setting for wearing. Each sensor has a unique part of the human body, and the wrong position can lead to a posture error. If you

have properly worn the body straps and installed the PNS sensor, click next to enter calibration.



• Enter this part, click finish button will enter calibration interface.



2.3 Posture Calibration

Posture calibration can be divided into A、S、T、B、P pose, different working mode match different calibration pose.

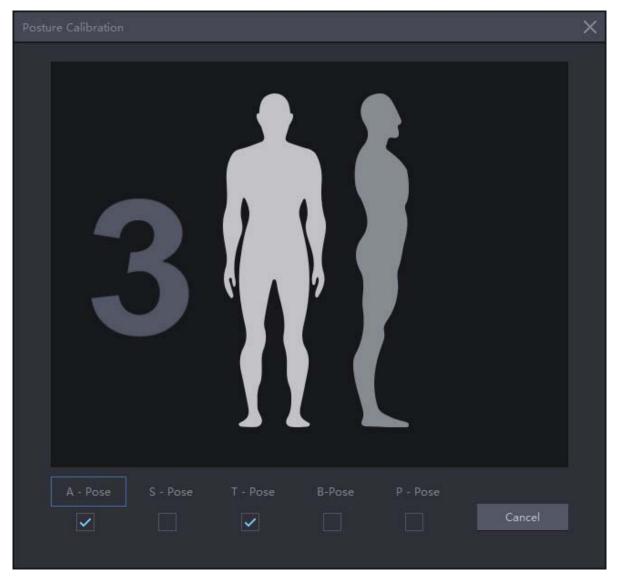
| Working mode | Calibration pose |
|----------------------|------------------|
| Full body | AT |
| Full body with glove | ATBP |
| Arm only | AT |
| Lower body | AS |
| Upper body | AT |
| Glove only | ATBP |

When the working mode is automatic identification, the system will automatically identify different working modes and automatically check the corresponding calibration attitude, which cannot be manually checked.

Details

• A Pose:

Stand straight, arms facing down with palms facing your body. Position feet distance approximately the same distance of your hip width and maintain feet parallel to each other.



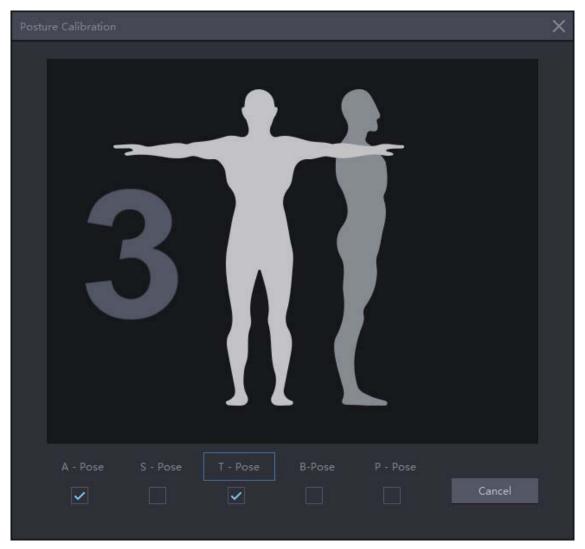
• S Pose:

Crouch down with feet flat on the ground while maintaining feet and legs parallel to each other. Extend arms forward with palms facing down.



• T Pose:

Stand straight spread out arms perpendicular to your body's upward position, with palms facing down. If you are using gloves, extend fingers and position thumb in a resting position.



• B Pose:

Place your hands together in front of your chest. Palm to stick. The thumb and the other four fingers are at an Angle of about 45 degrees.



• P Pose:

Gently knead the thumb between the forefinger and the straight thumb. Try to keep your thumb on a straight line from the base of your finger to the tip of your finger. The middle finger, ring finger and little finger can also be bent naturally.

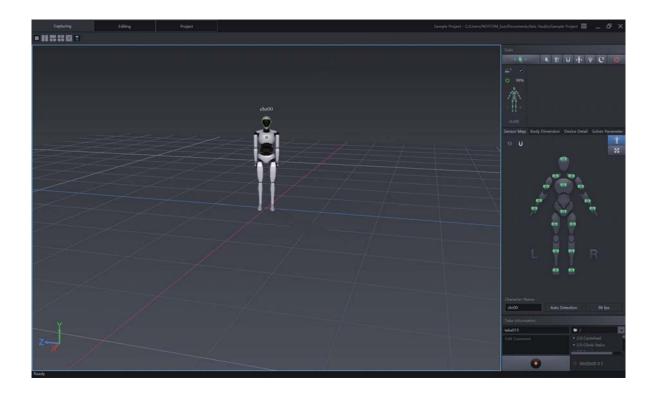


Start calibration

If you have learned to calibrate the action, click start, and you will hear the sound of the three-second countdown. At this time, it is time to prepare. At this time, the actor should adjust his posture to keep the same posture as the one on the picture.

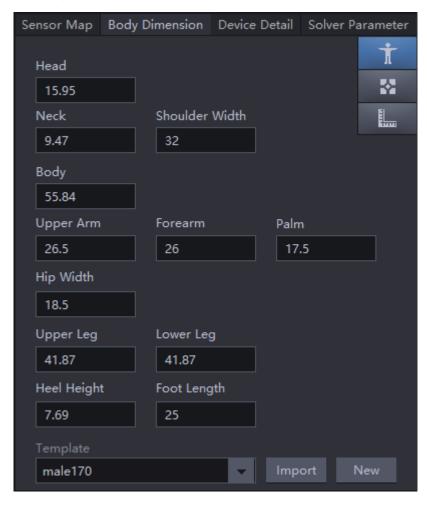
Calibration completed

If you have completed the calibration properly, the interface should be as shown in the figure.

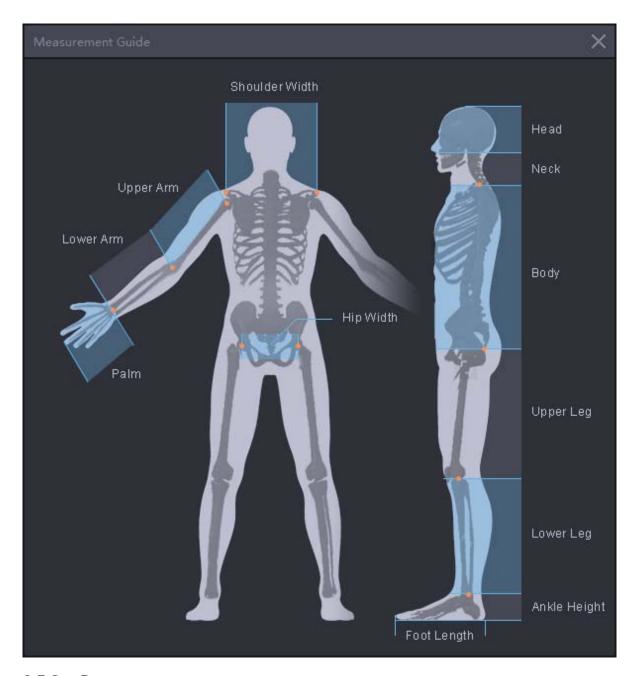


2.4 Measure Body Segment Length

Axis Studio allows users to input their own body size dimensions if the provided default body size presets do not apply. Prior to capturing, choose the body size preset that fits the actor's body dimension closest before carrying out the posture calibration. Inertial motion capture accuracy is affected by the body segment length of the Avatar.



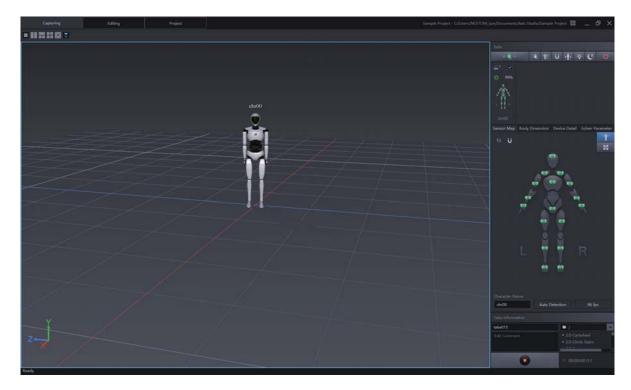
Please refer to measurement guide for bone measurement.



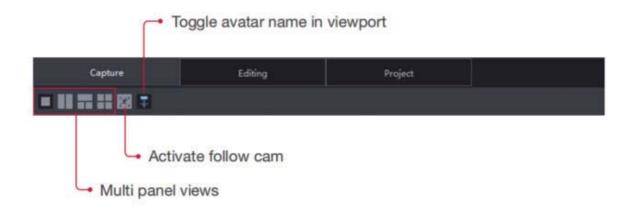
2.5 Set Parameter

Refer to 3.7- Solver Parameter.

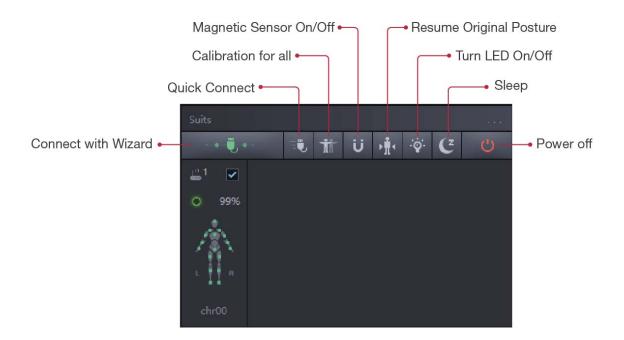
3. Capturing Interface



3.1 3D view functions



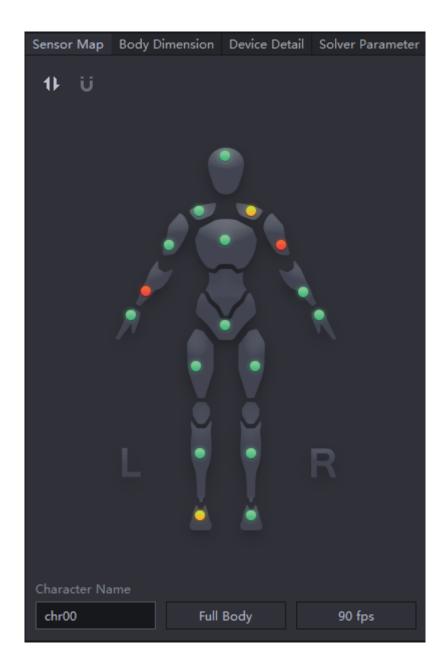
3.2 Suits



3.3 Sensor Map

Sensor signal strength (round dot)

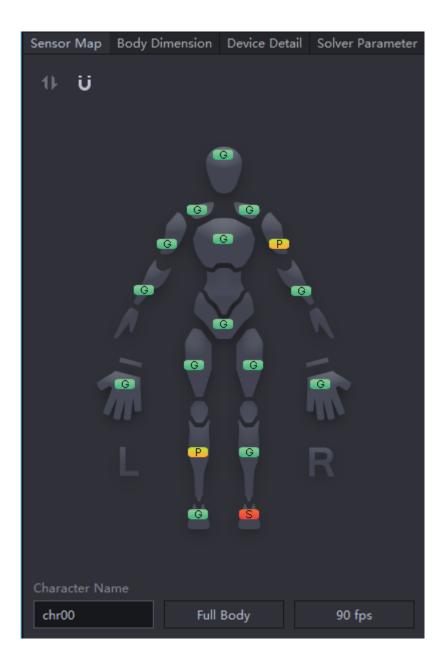
- Green is good
- Yellow is medium
- Red is bad
- Grey is no sensor linked



- You can customize the role name in the role name option box in the lower left corner.
- In the lower right corner are the motion capture mode and the number of capture frames.

Magnetic environment (Square dot)

- Green is good (G)
- Yellow is poor (P)
- Red is severe (S)
- Grey is no sensor linked or in Anti-mag Mode



3.4 Body Dimension



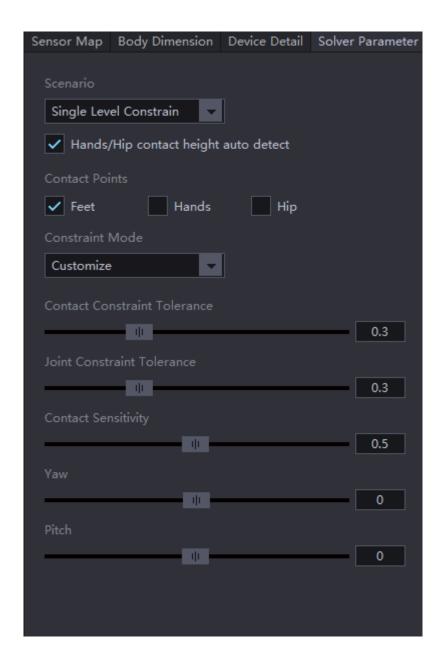
3.5 Device Detail

Displays detailed information of the individual sensors, including sensor ID, sensor signal, magnetic levels, and battery life.



3.6 Solver parameter

Adjust algorithm behaviour to control motion capture performance.



Scenario

- Single Level Constrain: If you are doing motion capture on a flat floor, use Single Level Constrain.
- Free Climbing: If you are capturing go upstairs, downstairs or any motion without a certain floor, use Free Climbing.
- Hip Locked: Hip Locked means lock your Avatar in the certain position, you can use it as running on a treadmill or hanging wire.

Hands/Hip contact height auto detect

Check this box to do different height of hand and hip contact in single level mode.

Contact Points

- Choose which body segment will make contact with the floor or a solid surface during the performance.
- For most scenarios we choose foot contact, selected by default. If you want to record a movement with hand.
- Contact such as cartwheel, select both the foot and the hand contact.

Constraint Mode

- Normal Mode: For normal situation.
- Steady Contact: Select steady contact will let contact point more steady.
- Customize: When the above default parameter mode is not applicable, adjust the parameter to adapt the current mocap state.

Contact Constraint Tolerance

- Axis Studio will use a pattern recognition algorithm to determine the contact between the feet and ground.
- The Step Stiffness value affects the speed of this status change.
- Smaller values will plant the feet firmly on the ground and larger values will allow the feet to slide easily while contacting the ground.

Joint Constraint Tolerance

- There are gaps between different body segments, and Joint constraint tolerance is to modify the tolerance of the gaps.
- The smaller the value is, the gaps will be smaller.

Contact Sensitivity

- The step constraint value determines the threshold a foot contact is activated.
- A higher value increases sensitivity of the foot contact algorithm. A low value reduces the sensitivity of a foot contact.

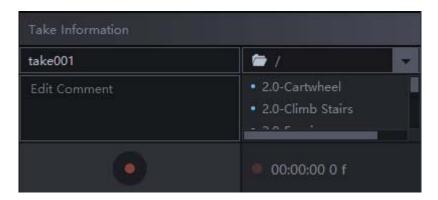
Yaw

- Adjust the yaw direction of the Character.
- You can use it to control the Avatar direction directly in third party software.

Pitch

- Adjust the pitch direction of the Character.
- If you find the Avatar is too leaned forward than it should be, you can make the Pitch value a little lower.
- Or if you find the Avatar is too leaned back, make the Pitch value higher.

3.7 Record Function



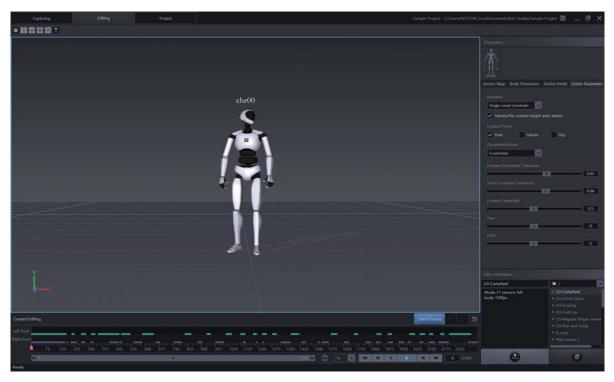
Click red icon start/stop record.

4. Editing Interface

In edit view, review and perform post processing of your captured data. Axis Studio provides an abundance of optimized algorithms to achieve an ideal contact result. Adjustments of the effect can be done by single frames or interval frames values.

4.1 Data Process

By click "Data Process" button after the first time of opening a new recording data, Axis Studio incorporates an automatic post-processing algorithm that will optimize the original motion capture file, such as make-up lost frames during wireless data transfer or correct sensor error data produced by unwanted muscle movement during real-time motion capture. Several files will take longer than others to open due to the amount of post-processing that may be required.



4.2 Contact Editing Window



The line color indicates a floor contact captured on particular body segment.

- L Hand: Left hand contact editing area.
- R Hand: Right hand contact editing area
- L Foot: Left foot contact editing area.
- R Foot: Right foot contact editing area.
- Right click and drag to modify the frames that you want to edit contact/uncontact points.
- Change the length of the frames that will be displayed in the bar in order to edit frame by frame. See example below, a capture with 2363 frames, where the visible frames are not long enough to show and edit each frame. If you change the length to make the bar to show a certain length of frame (e.g frame 864-1023) only then you will be able to select and edit each frame as needed.



- After you edit the body segments contact points successfully, you can click "Data Process" button to get an optimized data result.
- You can choose button to undo your editing process, and button to redo your editing process. After you undo or redo the contact editing, you always need to click "Data Process" button to make your editing become effective.



• When you click the data process, you may found other segment might be changed, the reason is the algorithm will work with the whole data, if you change one part, the other data might be impacted, so you need to use the mark edit functuion to protect the data which you don't want to change. Hold down the right mouse button and drag a piece of data, you will see mark edit function. this function will protect the current editing state.

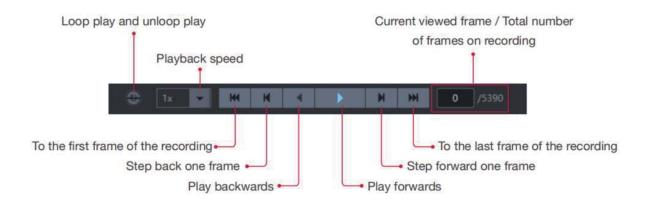


You can also click revert to origin button to back to restore to the state before editing.





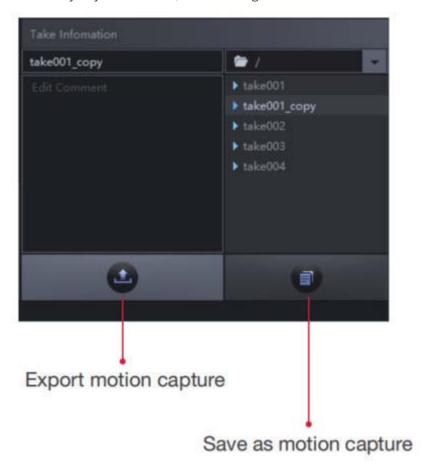
4.3 Frame Editing Toolbar



4.4 Save and export editing work

- The modifications will be automatically saved when you close your motion capture file.
- To save your edits while keeping the original file at the same time, or to save multiple versions of editing work for a single motion capture file, use the "save as" button.
- Click the save as button, then you will be able to input a new name for the file that you want to save, choose "save" then the file you are currently editing will be the new file with the

name that you just renamed, now the original file will remain the same as it was opened.



4.5 Body Dimension

You can still adjust the body dimension of the model in the editing process. If you want to create a custom body size based on the original template, first select the body size template you want to use. The original body size name will automatically add behind, then you can entering the appropriate body size, click save to project to save. The original bone size will not be covered. If you do not save to project, this modification is temporary.



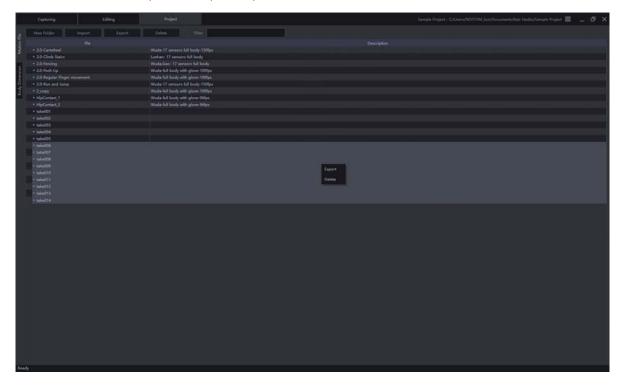
5. Project Interface

Manage motion capture files in this project.

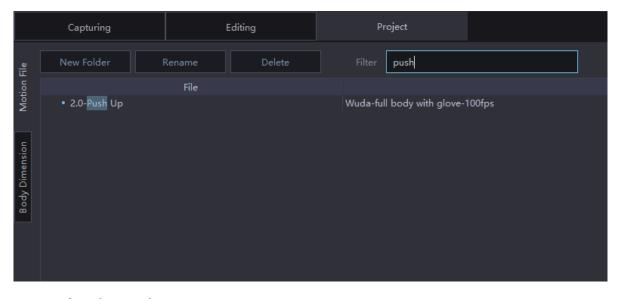
5.1 Motion File



- You can Rename and Delete your files directly.
- You can batch export or import captured data.

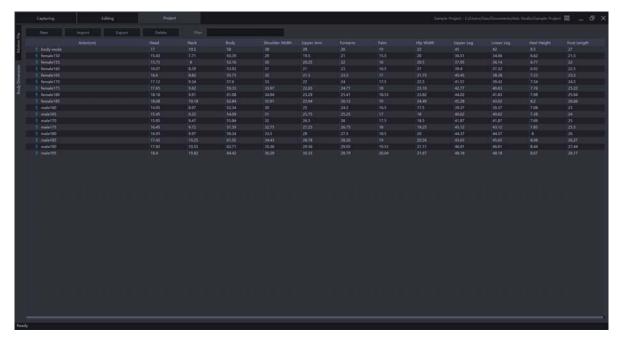


- Create new folders to organize large amount of capture files in this project to optimize file management.
- If you have a lot of capture files in one project, you will be able to tap key words in the filter to find your file. For example, I tapped "push" in the filter to find the three files with the word walk in the title.



5.2 Body Dimension

Manage body dimension profiles that will be used in the working project. You can modify the skeleton length directly in this page. The body dimension file is a simple xml file which includes the body dimension name and length for each body segment.



- You can Add and Delete a Body Dimension file.
- You can Import and Export a Body Dimension file. Body Dimension file is an *. xml file. You can copy and paste the *. xml body dimension file to anywhere.

6. Menu

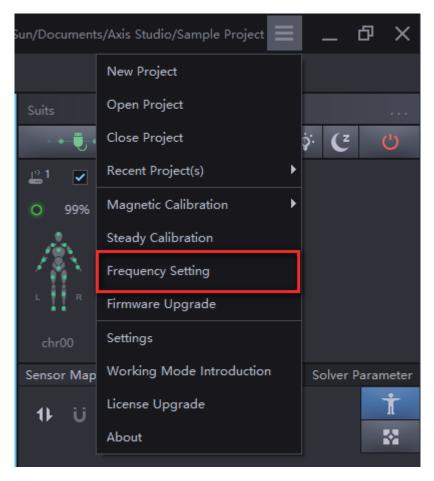
6.1 Overview

- New Project: Create a new project.
- Open Project: Open an existing project.
- Close Project: Close the project which is opened now.
- Recent Project: A shortcut to find the lasted projects that you opened before.
- Magnetic Calibration: Calibrate your sensors to resist magnetic interference.
- Steady calibration: Calibrate the gyroscope of the sensor.
- Frequency Setting: PN3 support 3 different data transfer frequencies. If you are using more
 than one set PN3 at the same time, you need to make sure the these sets of PN3 are using
 different frequencies.
- Firmware Upgrade: Upgrade your transceiver, sensor and glove separately.
- Settings: Basic software settings.
- Working mode introduction: Introduce 6 working mode.
- License update: When you purchase the payment function, click here to input the activation code provided by Noitom company to activate your payment function.
- About: Including Axis Studio version, Calculation Engine Version and Usage License.

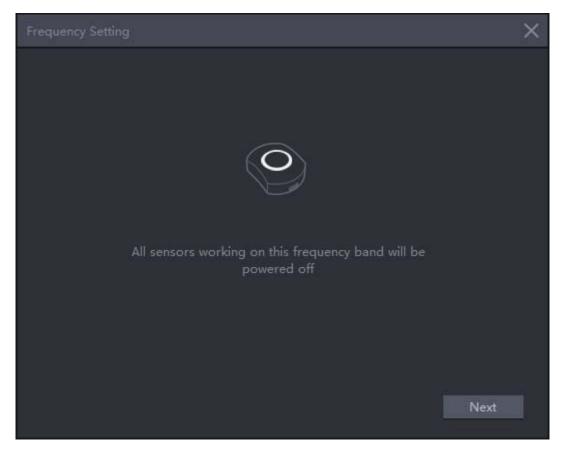
6.2 Frequency Setting

When there are multiple pn3 devices in one site, or the current signal quality shows bad, you can use frequency setting function.

• Click frequency switch function in the menu.



• Check the quantity of connected sensors in the left corner of the popup window.



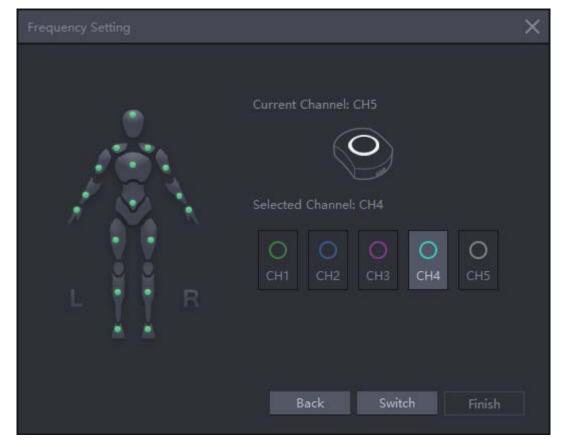
• Turn on all the sensors, then click connect button.



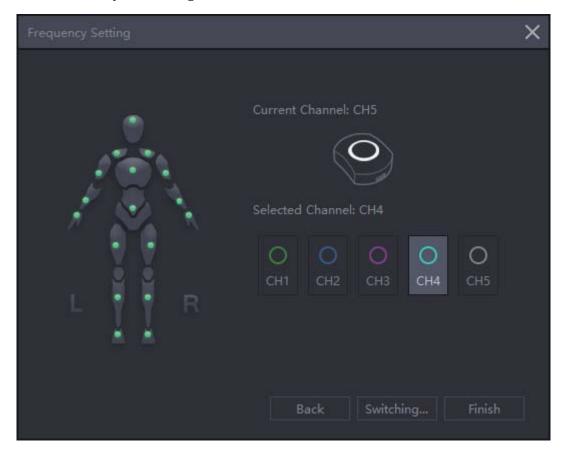
• You will see the sensors are shown in the left side.



• Select the channel.

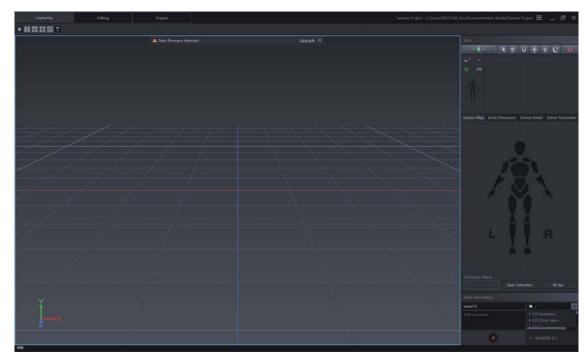


• Next Switch, all sensor LED color should be changed accordingly, then check the connection sensor number in the left corner of the popup window, make sure it matches the actual sensor number you are using, then click Finish.

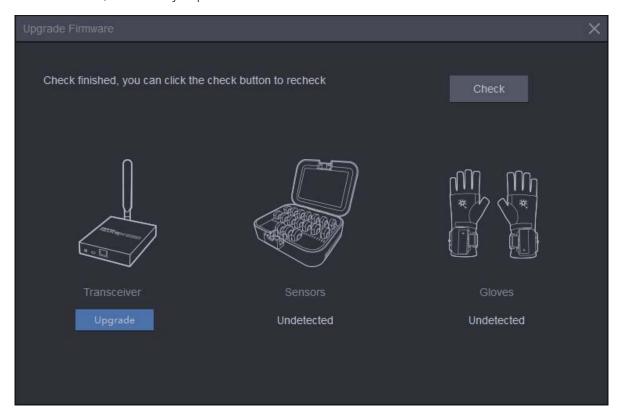


6.3 Firmware Upgrade

• If the firmware is not the latest version, there will be prompted at the top of the software interface.



• Click Upgrade, it will jump to the following interface, and if you click firmware upgrade in the menu bar, it will also jump to the interface.

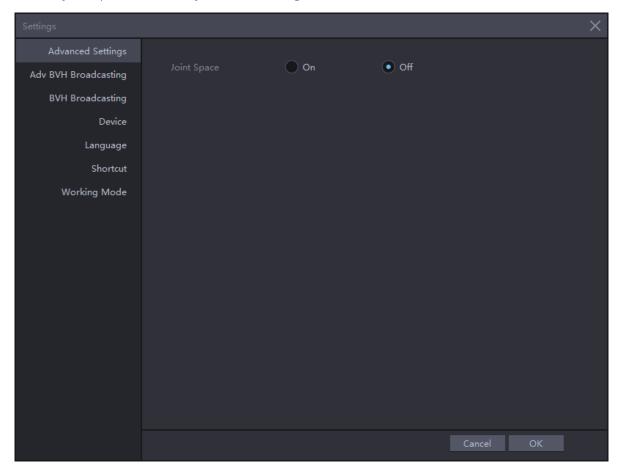


• Click upgrade, then you will upgrade the device.

6.4 Settings

Adcanced setting

Control joint space on/off, only works in editing mode.

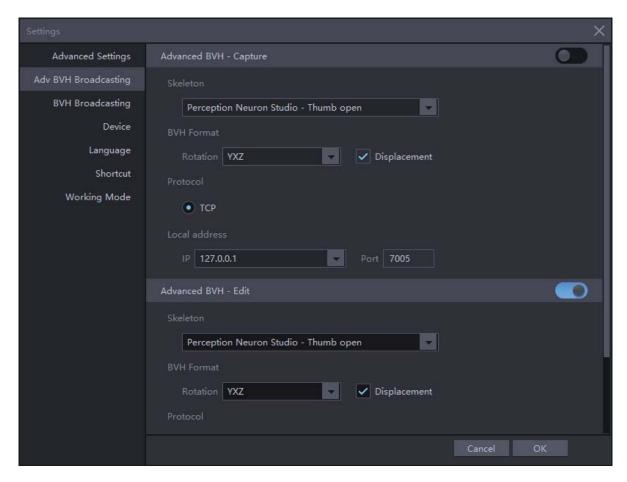


Adv BVH Broadcasting

BVH used in Autodesk software is a special BVH format. If you use Autodesk series software, use advanced BVH data broadcast in axis studio.

| Function | Description | Used for |
|----------------------|------------------------|----------------------|
| Advanced BVH-Capture | Broadcast capture data | Motion builder, Maya |
| Advanced BVH-Edit | Broadcast Edit data | Motion builder, Maya |

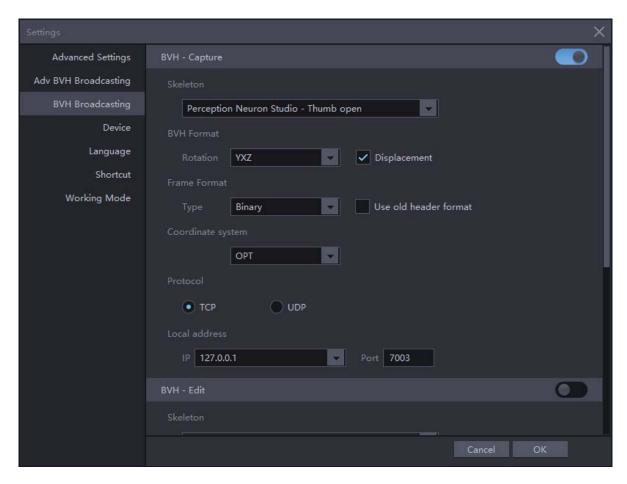
• Slide the upper right slider to enable the function.



BVH Broadcasting

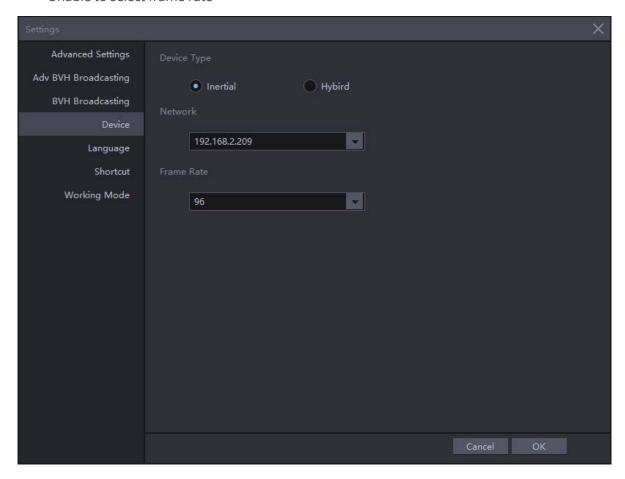
| Function | Description | Used for |
|-------------|------------------------|-----------|
| BVH-Capture | Broadcast capture data | Unity, UE |
| BVH-Edit | Broadcast Edit data | Unity, UE |

• Slide the upper right slider to enable the function.

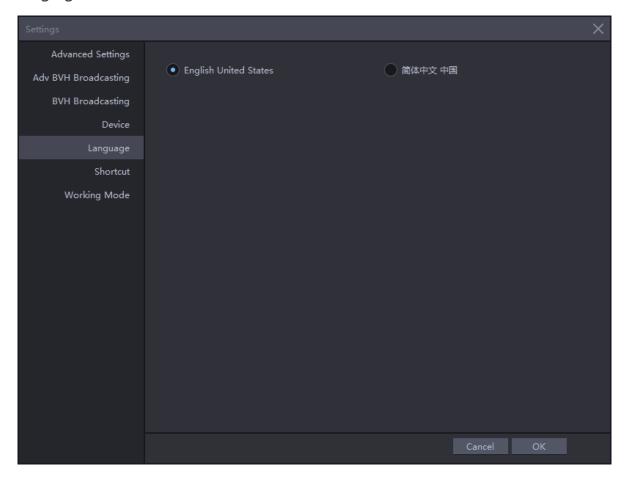


Device

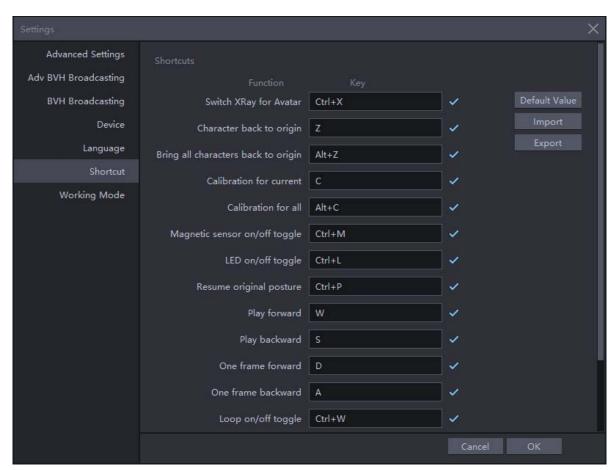
- Switchable device type
- Select network
- Unable to select frame rate



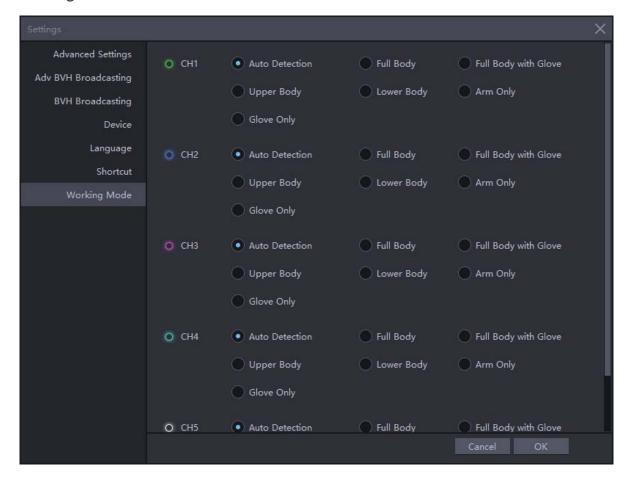
Language



Shortcut



Working Mode



FCC Caution:

Any Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

FCC RF Radiation Exposure Statement:

- 1. This Transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.
- 2. This equipment complies with RF radiation exposure limits set forth for an uncontrolled environment.
 - The device has been evaluated to meet general RF exposure requirement. The device can be used in portable exposure condition without restriction.

Product Name: Perception Neuron 3
Model: NTM-MCP-05-TC-01
Supply by USB: 5V === 25mA
FCC ID: 2ABTR-NTM-MCP05TC01
MSIP ID: R-C-ntm-MCP05TC01
Manufactured by: Beijing Noitom

Technology Ltd.

Address: 502, Tower A,

28 Xinjiekouwai Blvd, Beijing, China

MADE IN CHINA



Product Name: Perception Neuron 3
Model: NTM-MCP-05-BS-01
Supply by USB: 5V === 20mA
FCC ID: 2ABTR-NTM-MCP05BS01
MSIP ID: R-C-ntm-MCP05BS01
Manufactured by: Beijing Noitom
Technology Ltd.
Address: 502, Tower A,
28 Xinjiekouwai Blvd, Beijing, China
MADE IN CHINA

