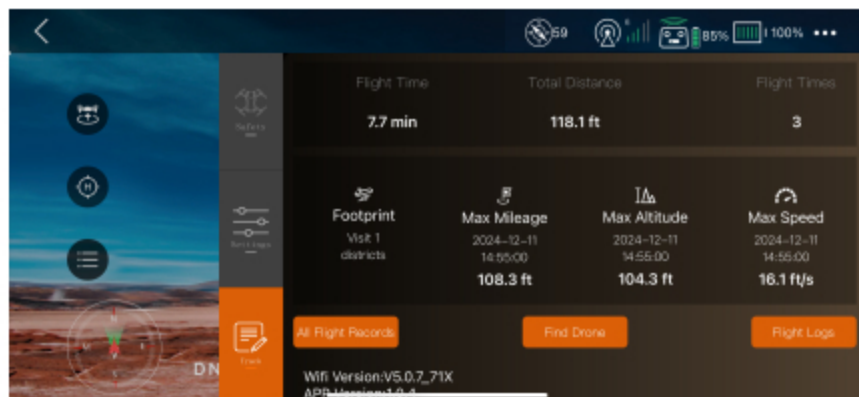


Track



- **All Flight Records:** The date, location, distance, duration and maximum altitude of each flight.
- **Find Drone:** It shows the last position of the aircraft when it lost the image transmission signal. Open the map to find the position where the aircraft is disconnected from the App.
- **Drone information display:** App version, Wi-Fi version, ID number.



- Before using the Bwine GPS App, please correctly enable the required permissions for the App:
- Allow Bwine F7MINI 4K to get your location. Otherwise, the following functions cannot be realized.
- Allow Bwine F7MINI 4K to connect to the mobile phone on the local network, otherwise you will not be able to see the aircraft image transmission screen.
- Allow Bwine F7MINI 4K to access to albums, recordings and other permissions.
- When using the Bwine GPS App on your phone, please keep your phone running smoothly and close other background software that you do not use.
- The map used in the map interface needs to be downloaded from the Internet before use.

6 Flight

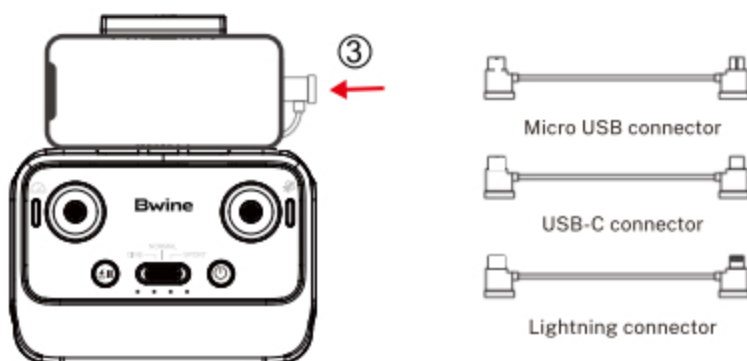
- After the installation preparation is complete, please conduct flight training or training first. It is recommended to conduct training in the beginner mode. Please choose a suitable flight environment when flying. The flying altitude is limited to 393ft, and the local laws and regulations must be strictly observed during flight. Please be sure to read the F7MINI 4K Disclaimer and Safety Summary, and understand the safety precautions before flying.

6.1 Flight Environment Requirements

1. Do not fly in severe weather such as strong wind, snow, rain, and fog.
2. Choose an open place with no obstructions around as the flying field. The compass and GPS signals on the Aircraft will be interfered by buildings, mountains, and trees. It is recommended to fly in an open space with a diameter of 33ft without interference. It is recommended that the flight altitude be greater than 49ft to avoid ground obstacles and other signal interference from the ground.
3. When flying, keep in sight and control, and stay away from obstacles, crowds, etc. When flying on the water surface, please be more than 9ft above the water surface.
4. The remote control may be interfered by high-voltage lines, communication base stations or transmission towers. Please fly away from these areas.
5. Please fly below 9842ft above sea level to ensure that the Air pressure setting function of the Aircraft can work normally.
6. When GPS is active, the Aircraft can achieve stable hovering, intelligent return to home, and intelligent flight functions. When the GPS function fails, these functions cannot be implemented. The Aircraft will be unable to hover, drifting away in the direction of the wind.

6.2 Connection&Settings

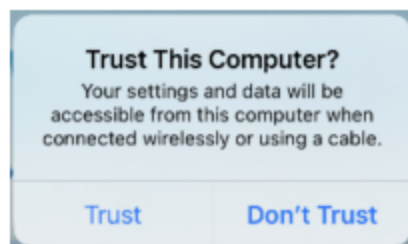
1. Choose the appropriate data cable to connect your phone to the remote controller.



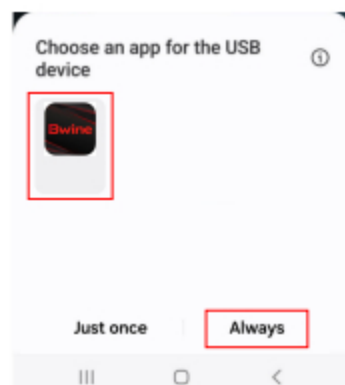
2. Tap the App, the first time to use the interface will pop up the permission setting.

Please allow the following permissions

1. Mobile phone location rights
2. Network rights
3. Recording rights
4. Album access rights

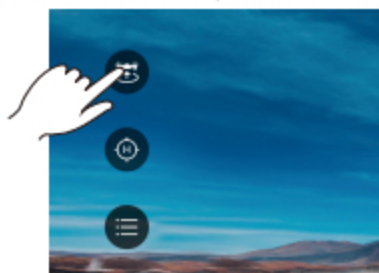


iPhone Settings

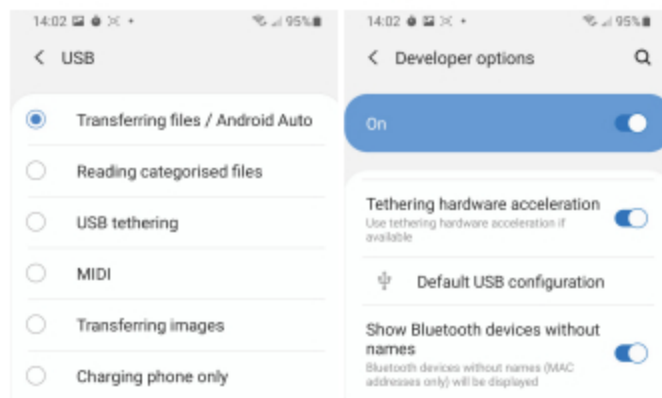


Android phone USB Settings

3. When you enter the operation interface and see the image transmission screen of the drone, the connection is successful.



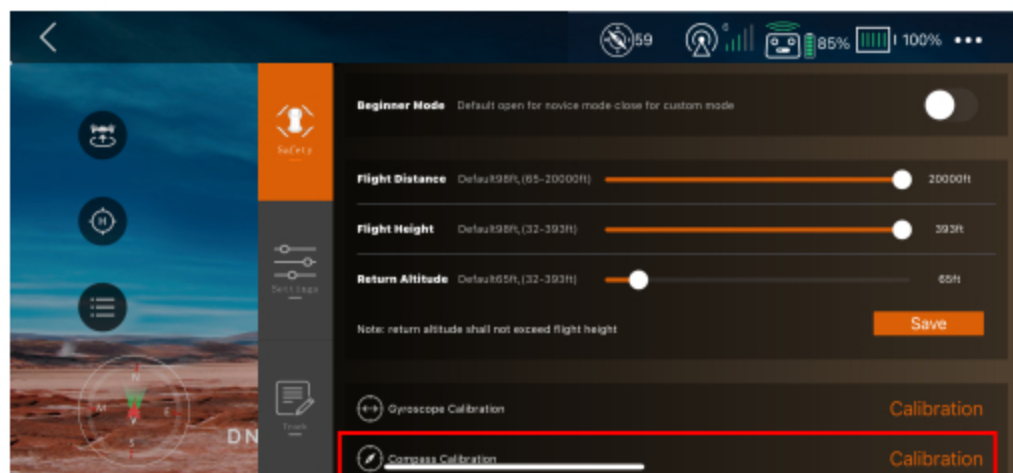
1. When connecting the data cable, ensure that the plug of the data cable is in place.
2. For some mobile phones, due to the reasons of the phone case, the plug of the data cable is not installed in place, resulting in data transmission failure, poor contact, and no way to see the transmitted image.
3. Please set the permissions required by the App correctly to avoid the inability to preview the image.
4. USB Settings on some Android phones are hidden in the "Developer options", you need to change the "Default USB configuration" to "Transferring files" after opening the developer mode.
(The way to open "Developer options" varies depending on the phone model. You can search Google for details).



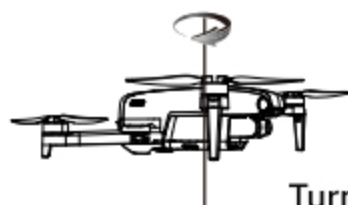
6.3 Calibration before Flight

Calibrate the compass

- When the drone flies in a complex environment or when the magnetic field interference exceeds the set value, it is necessary to calibrate the compass.



1. Push the left and right joysticks to the "11 o'clock" and "1 o'clock" hold for 2 seconds (as shown in picture 1) or tap "Compass calibration" on the App calibration interface (as shown in picture 2) to turn off the green light of the drone and enter the calibration step.




Turn 3 times

- At this time, you need to follow the prompts to pick up the Aircraft at a distance of 3.28ft from the ground and rotate the Aircraft horizontally for 3 laps until the App interface prompts to enter the vertical calibration.
- Pick up the Aircraft at a distance of 3.28ft from the ground, and rotate the Aircraft 3 laps vertically with the camera facing upwards until the prompt of vertical calibration on the App interface disappears. After the compass calibration is completed, place the Aircraft on a level ground. At this time, the three lights of the drone flash in turn.



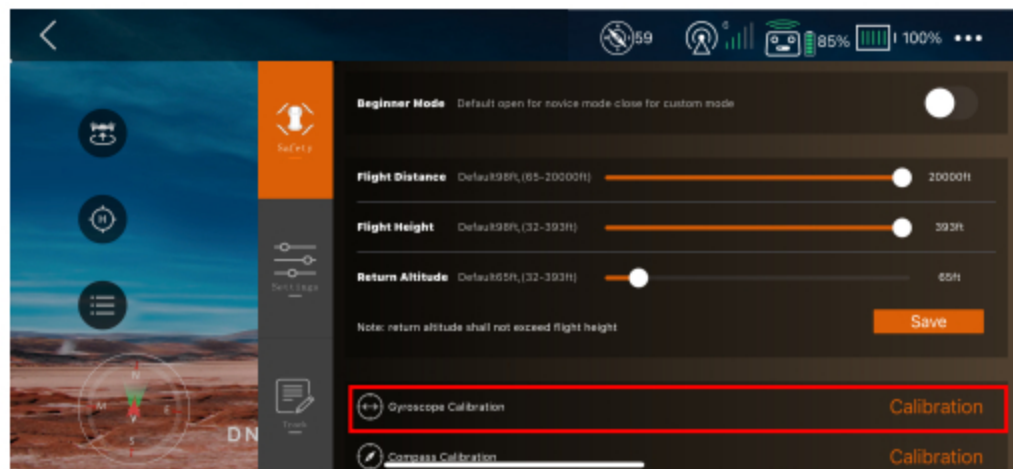
Turn 3 times



- Before the flight, pay attention to the compass interference value on the App. () When the interference value is close to 120, we can manually calibrate the compass, or change the environment to fly. When the interference value exceeds 180, the drone will automatically enter the compass calibration.
- When the Aircraft is flying in a circle or out of control in a complex environment, the aircraft compass calibration is not standard or interfered. Please land the Aircraft manually in time to manually calibrate the Aircraft (refer to the first step of calibrating the compass).
- When calibrating the Aircraft, please open the arm and keep the aircraft 1 meter above the ground to avoid the influence of the magnetic field of the motor.

Calibrate the Gyroscope

1. Make sure that the Aircraft is placed on a level ground.
2. It can be calibrated by gyroscope calibration function of App.



- Or push the right joystick of the remote control to the "5 o'clock" position for calibration.
3. The rear light flashes quickly, and the drone enters horizontal automatic calibration.
 4. The light changes back to the original light state, indicating that the calibration is complete.
 5. "Fly" is displayed in the App, and you can now prepare to take off.

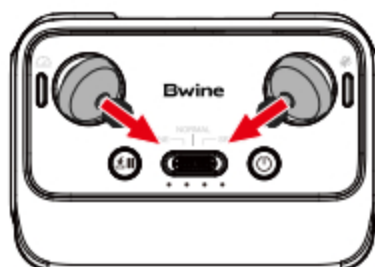


- When the Aircraft's flight state is tilted and unstable, please land the Aircraft on a level ground for gyroscope/horizontal calibration.
- When the tilt Angle of the fuselage is greater than 10° , the horizontal correction cannot be performed.

6.4 Starting/Stopping the Motors

Starting the Motors

- Push the joysticks into 5 & 7 o'clock positions to start the motor. After the motor starts, please release the joystick immediately.



- **Stopping the Motors**
After the motor starts rotating, there are two ways to stop:
- Method 1: After the Aircraft takes off, push the throttle stick to the lowest position and operate the Aircraft to land until the motor stops, then release the joystick.
- Method 2: When the flight is not taking off, Push the joysticks into 5 & 7 o'clock position to stop the motor. After the motor is turned off, please release the joystick immediately.

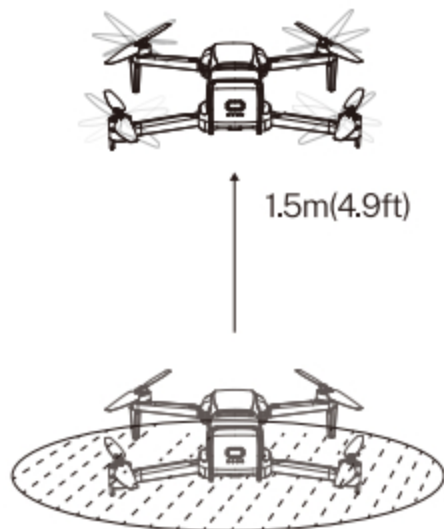


- When manually landing the aircraft, continue to pull down the remote control throttle lever, landing 1.6 ft (0.5 meters) will stop, confirm the landing continue to pull down the throttle lever, the drone will land and stop the motor.
- Please choose the flat surface to landing.

6.5 Auto Takeoff/Landing

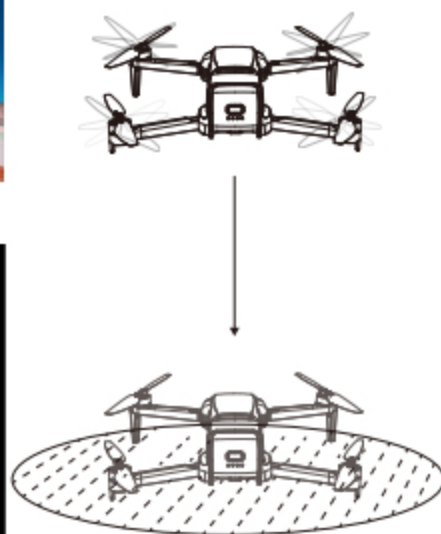
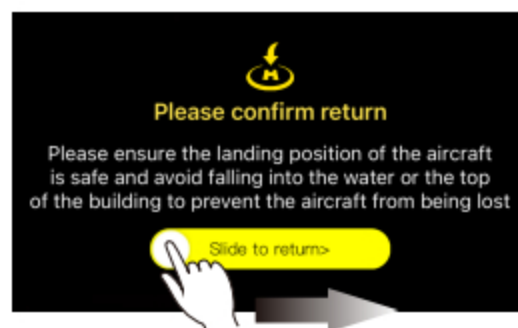
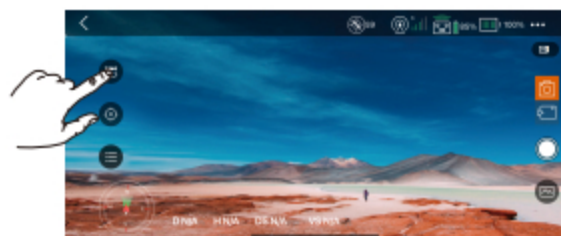
Auto Takeoff

- After the Aircraft is calibrated, users can use the take-off function on the App:
1. Start the motor after confirming the safe take-off conditions.
 2. Tap "🚁" on the App to take off.
 3. Slide to unlock motor.
 4. Press the One-key Takeoff button on remote controller or enter the App and tap to take off.
 5. The Aircraft will take off automatically and hover at a distance of 1.5m(4.9ft) from the ground.



Auto Landing

- After the aircraft takes off, the user can choose to use the automatic landing function on the App:
- Confirm the safe landing conditions, tap the "🚁" on the App.
 - Slide to confirm automatic landing.
 - The aircraft descends to the ground and turns off its motors.



6.6 Basic Flight Steps

Basic Flight Steps

1. Place the Aircraft on a flat and open ground with the nose facing forward and the tail facing the pilot.
2. Press and hold to turn on the aircraft power.
3. Long press to turn on the remote control power, the drone and the remote control will automatically match the frequency, the time is about 30 seconds.
4. After a successful match, connect the phone to the remote control through the data cable (pay attention to the USB permission setting).
5. Open the Bwine GPS App, and enter the operation interface.
6. GPS signal search is completed, and the drone light is green and on.
7. Unlock and start the motor.
8. Slowly push the throttle stick upward to let the Aircraft take off smoothly.
9. Pull down the throttle stick to lower the Aircraft.
10. After landing, pull the throttle stick to the lowest position and hold it until the motor stops.
11. Turn off the power of Aircraft and Remote control.

Aerial Photography Tips & Tricks

1. Perform pre-flight inspection.
2. It is recommended to take photos or videos in low-speed or medium-speed gear.
3. Choose sunny and less windy weather for shooting.
4. Push the stick as little as possible during the flight to make the Aircraft fly smoothly.

7 Appendix

7.1 Specification Parameter

Drone	Model	F7MINI 4K
	Weight (Including Battery)	<249g
	Motor Model	1503
	Operating Temperature Range	32° to 104°F (0° to 40°C)
	Satellite Systems	GPS / GLONASS
	Dimensions (L x W x H)	Unfolded: 32x19.2x5.8 cm Folded: 14.1x8.7x5.8 cm
Camera	Controllable Range of Camera (Up and down)	About -90° to +0°
	Focus Range	Fixed-focus
	Resolution of Photo	Phone 3840×2160P
		SD Card 8000×6000P
	Resolution of Video	Phone 1280×720P / 30FPS
		SD Card 3840×2160P / 30FPS 1920×1080P / 60FPS
	Photo Format	JPG
	Video Format	MP4
5G Transmission	Supported SD Cards	Micro SD card(Class 10/U1 or later) 256G
	Supported File Systems	FAT32
Remote controller	Operating Frequency	5.15-5.35 GHZ; 5.725-5.825 GHZ
	Video Transmission Frame Rate	30 FPS
	Battery	1500 mAh Li-polymer
	Charging Time	About 80 minutes
	Operating Voltage	7.4V
Remote controller	Mobile Device Holder	4.7 to 6.7 inches Smart Phones
	Operating Temperature	32° to 104°F (0° to 40°C)

Drone Battery	Capacity	2200mAh
	Voltage	7.6V
	Battery Type	Li-polymer
	Power	16.72Wh
	Net Weight	93 g/3.28 oz
	Max Charging Time	About 3 Hours(Depending on Charging Power)
	Charging Temperature Range	41° to 104°F (5° to 40°C)
Charging Cable	Interface Type	Type - C
	Input	100 - 240V, 50/60Hz, 0.5A
	Output	5V/1.5A or 5V/2A or 5V/3A
	Rated Power	≤ 15W
App	App Name	Bwine GPS
	Mobile Phone System	Android 6.0 And Above System IOS 10.0.2 And Above System
	Connection Mode	Data Line Connection

7.2 Accessories



Intelligent Flight Battery



Spare Propeller



Remote Controller

- Always use original accessories. The use of non-original accessories may pose a risk to the safe use of the aircraft.

7.3 Common Problems and Solutions

Question	Reason	Solutions
The drone cannot be unlocked	No GPS signal (green light flashing)	Fly in an open area with a strong GPS signal
	Compass interference (green light off)	Complete the compass calibration. For details, refer to page 55 of the manual
	Gyroscope calibration in progress (green light flashes rapidly for 1–2 seconds)	Place the drone on a level surface and wait for the gyroscope calibration to complete
	Drone has low battery (drone shows red light)	Please charge the battery in time
	The left and right joysticks are not in place	Push the left stick to the 5 o'clock direction and the right stick to the 7 o'clock direction simultaneously, or use the one-key takeoff function in the App
Flight is unstable	Flying too low, affected by airflow	Please fly the aircraft above 9.84ft(3 meters)
	The gyroscope is not calibrated	Place the aircraft on a horizontal surface and conduct gyroscope/horizontal calibration. For details, refer to page 58 of the manual
	The propellers become deformed and incomplete	Replace the propellers with new ones
	GPS signal is unstable. Flying near buildings or in obstructed places	Fly the aircraft in an open, obstacle-free area within a 32.81ft (10 meter) radius
Fly not far, fly out a distance to bounce back	In beginner mode, you will only be able to fly 30 metres in height and 30 metres in distance	Enter the setting interface of App, turn off the beginner mode, set the flight distance and height, and save the Settings
	When the drone enters the first low battery level, it can only fly up to 30 meters high and 30 meters far	Change to another battery for flight
After the drone is unlocked, it flips to the side during takeoff	4 propellers are installed backwards or a wrong propeller is installed	When installing the propeller, install it according to the corresponding mark
The drone suddenly crashed	1.The battery is not installed properly 2.The propeller is not securely installed and falls off	Check whether the battery or propellers is abnormal, and re-test after firm installation

Question	Reason	Solutions
Out of control, spinning around on its own, abnormal sound	Compass interference	Please manually land the aircraft in time and calibrate the compass, Please make sure to fly away from the buildings, trees, power lines, and signal towers
	The propellers become deformed and incomplete	Replace the propellers with new ones
Blurry or unclear image	The camera cover is not removed	Remove the camera cover before flying
	The camera lens is dirty	Use a clean cloth to clean the lens
	The lens film has not been removed	Please remove the lens film
	The video saved on the phone is only in 720P quality	Please insert an SD card into the drone, as videos saved on the SD card are in 4K quality
Video freezes, image transmission distance is short	Long-distance flight, with the transmission signal affected by obstacles	1. Choose a wide-open flying environment and ensure the drone's flight altitude is higher than the surrounding obstacles 2. Point the remote controller towards the drone's flight position
	Phone performance freezes	Close unused Apps running in the background to maintain the best performance of the phone
No image is displayed on the App	The phone is not connected to the remote controller	The phone and remote controller need to be connected via a cable. Please select the correct cable and ensure the connection is secure
	Wrong App downloaded	Download the correct App (Bwine GPS)
	The drone cannot be paired with the remote controller	It takes about 30 seconds for the drone and the remote control to match, and the image captured by drone will be displayed once the match is successful
App crashes or functions abnormally	Wrong App downloaded	Download the correct App (Bwine GPS)
	Some phone versions are old and incompatible with App	Please provide version and model of the phone, we will try to help you to solve it
GPS signal is weak	When the drone is indoors	GPS signals cannot be found indoors. Please search for GPS signals in an open area
	Under the tree, next to the building, in an obstructed place	Please stay away from obstacles for more than 32.81 feet(10 meters), and search for GPS signals in an open area

Question	Reason	Solutions
Unable to return home, drifting and flying away	The drone has lost GPS signal	Fly away from buildings or covered areas
	The drone's compass is being interfered with	Stay away from metal devices, electronic equipment, or signal towers
The remote control and the drone take a long time to match	It takes about 30 seconds to match the remote to the drone	Please wait patiently
Unable to charge battery/Not fully charged	Using inferior charger or charging on the computer with unstable voltage output	Ensure you use a charger with stable output power. Do not use a charger with an output lower than 5V
	Using inferior charging cables	Please use the original factory charging cable to charge
Short battery life	Flying in windy weather	Flying in windy weather will accelerate power loss
	The drone was not be charged when you received it	The batteries are fully charged with the correct USB charger before flying
	Flying in cold weather	In low temperatures, the chemical reaction of the lithium battery is slowed down and the energy cannot be fully released
The product has slight marks	We tested all drone before shipping	In order to give you the best experience, we tested functions of all drone before shipping. Therefore, it is inevitable that there will be slight traces. However, it can be guaranteed that all drone are 100% brand new



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