

# TEST REPORT

**Product Name** : PORTABLE LED BULB  
**Model Number** : Sphere C  
**FCC ID** : 2A44S-SPHEREC

**Prepared for** : Shenzhen Olight E-Commerce Technology Co., Ltd.  
**Address** : 5th Floor, Building A2, Fuhai Information Harbor, Fuhai  
Subdistrict, Baoan District, Shenzhen, Guangdong, 518000,  
China

**Prepared by** : EMTEK (SHENZHEN) CO., LTD.  
**Address** : Bldg 69, Majialong Industry Zone, Nanshan District,  
Shenzhen, Guangdong, China

Tel: (0755) 26954280  
Fax: (0755) 26954282

**Report Number** : ENS2503040214W01601R  
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## TABLE OF CONTENTS

|   |           |
|---|-----------|
| <b>1. TEST RESULT CERTIFICATION .....</b>                           | <b>4</b>  |
| <b>2. Description of Equipment Under Test .....</b>                 | <b>6</b>  |
| <b>3. SAR Measurement System .....</b>                              | <b>7</b>  |
| 3.1 Definition of Specific Absorption Rate (SAR) .....              | 7         |
| 3.2 SPEAG DASY System .....   | 7         |
| 3.2.1 Robot .....   | 8         |
| 3.2.2 Probes .....  | 9         |
| 3.2.3 Data Acquisition Electronics (DAE) .....                      | 9         |
| 3.2.4 Phantoms .....  | 10        |
| 3.2.5 Device Holder .....   | 11        |
| 3.2.6 System Validation Dipoles .....                               | 11        |
| 3.2.7 Tissue Simulating Liquids .....                               | 12        |
| 3.3 SAR System Verification .....                                   | 14        |
| 3.4 SAR Measurement Procedure .....                                 | 15        |
| 3.4.1 Area & Zoom Scan Procedure .....                              | 15        |
| 3.4.2 VolumeScan Procedure .....                                    | 15        |
| 3.4.3 Power Drift Monitoring .....                                  | 16        |
| 3.4.4 Spatial Peak SAR Evaluation .....                             | 16        |
| 3.4.5 SAR Averaged Methods .....                                    | 16        |
| <b>4. SAR Measurement Evaluation .....</b>                          | <b>17</b> |
| 4.1 Applicable Standards .....                                      | 17        |
| 4.2 EUT Testing Position .....                                      | 17        |
| 4.2.1 Hand-held usage of the device, not at the head or torso ..... | 17        |
| 4.2.1 SAR Test Exclusion Evaluations .....                          | 19        |
| 4.3 Tissue Verification .....                                       | 20        |
| 4.4 System Validation .....   | 20        |
| 4.5 System Verification .....                                       | 21        |
| 4.6 Maximum Output Power .....                                      | 22        |
| 4.6.1 Maximum Conducted Power .....                                 | 22        |
| 4.6.2 Measured Conducted Power Result .....                         | 23        |
| 4.7 SAR Testing Results .....                                       | 24        |
| 4.7.1 SAR Test Reduction Considerations .....                       | 24        |
| 4.7.2 SAR Results for Head Exposure Condition .....                 | 24        |
| <b>5. Calibration of Test Equipment .....</b>                       | <b>25</b> |
| <b>6. Measurement Uncertainty .....</b>                             | <b>26</b> |
| <b>7. Information on the Testing Laboratories .....</b>             | <b>28</b> |
| <br>  |           |
| <b>Appendix A. SAR Plots of System Verification</b>                 |           |
| <b>Appendix B. SAR Plots of SAR Measurement</b>                     |           |
| <b>Appendix C. Calibration Certificate for Probe and Dipole</b>     |           |
| <b>Appendix D. Photographs of EUT and Setup</b>                     |           |

## Modified Information

| Version | Report No.           | Revision Date | Summary         |
|---------|----------------------|---------------|-----------------|
| Ver.1.0 | ENS2503040214W01601R | /             | Original Report |
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## 1. TEST RESULT CERTIFICATION

Applicant : Shenzhen Olight E-Commerce Technology Co., Ltd.

Address : 5th Floor, Building A2, Fuhai Information Harbor, Fuhai Subdistrict, Baoan District, Shenzhen, Guangdong, 518000, China

Manufacturer : Dongguan Olight E-Commerce Technology Co., Ltd

Address : 4th Floor Building 4 Kegou Industrial Park No.6 Zhongnan Road, Changan Town, Dongguan City, Guangdong, China.

EUT : PORTABLE LED BULB

Model Name : Sphere C


Trademark : OLIGHT


### Measurement Procedure Used:


| APPLICABLE STANDARDS  |             |
|---|-------------|
| STANDARD  | TEST RESULT |
| FCC 47 CFR Part 2§2.1093, KDB 865664 D01 v01r04, IEEE Std C95.1-2005 , KDB 447498 D01 v06, KDB 865664 D02 v01r02  | PASS        |
| <p>This report is for your exclusive use. Any copying or replication of this report to or for any other person or entity, or use of our name or trademark, is permitted only with our prior written permission. This report sets forth our findings solely with respect to the test samples identified herein. The results set forth in this report are not indicative or representative of the quality or characteristics of the lot from which a test sample was taken or any similar or identical product unless specifically and expressly noted. Our report includes all of the tests requested by you and the results thereof based upon the information that you provided to us. You have 60 days from date of issuance of this report to notify us of any material error or omission caused by our negligence, provided, however, that such notice shall be in writing and shall specifically address the issue you wish to raise. A failure to raise such issue within the prescribed time shall constitute your unqualified acceptance of the completeness of this report, the tests conducted and the correctness of the report contents. Unless specific mention, the uncertainty of measurement has been explicitly taken into account to declare the compliance or non-compliance to the specification.</p> |             |

CERTIFICATION: The above equipment have been tested by EMTEK (SHENZHEN) CO., LTD. Bldg 69, Majialong Industry Zone, Nanshan District, Shenzhen, Guangdong, China, and found compliance with the requirement of the above standards. The test record, data evaluation & Equipment Under Test (EUT) configurations represented herein are true and accurate accounts of the measurements of the sample's SAR characteristics under the conditions specified in this report. This report shall not be reproduced, except in full, without the written approval of EMTEK (SHENZHEN) CO., LTD.

Date of Test : June 12, 2025 to June 12, 2025

Prepared by :   
Jim Cai/Editor

Reviewer :   
Joe Xia/Supervisor

Approved & Authorized Signer :   
Lisa Wang/Manager

| Equipment Class | Mode      | Highest Reported Head SAR <sub>1g</sub> (W/kg) |
|-----------------|-----------|--|
| DTS             | Bluetooth | 0.033  |

**Note:**

1. The SAR limit (**Head & Body: SAR<sub>1g</sub> 1.6 W/kg, Extremity: SAR<sub>10g</sub> 4.0 W/kg**) for general population/uncontrolled exposure is specified in FCC 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1-1992.



## 2. Description of Equipment Under Test

|  |                                       |
|--|---------------------------------------|
| <b>EUT Type</b>  | PORTABLE LED BULB                     |
| <b>Trade Mark</b>                                      | OLIGHT                                |
| <b>Model Name</b>                                      | Sphere C                              |
| <b>Test Sample S/N</b>                                 | 1#                                    |
| <b>Bluetooth Version</b>                               | Bluetooth V5.0                        |
| <b>Tx Frequency Bands<br/>(Unit: MHz)</b>              | Bluetooth : 2402 ~ 2480               |
| <b>Uplink Modulations</b>                              | BLE:GFSK                              |
| <b>Maximum Tune-up Conducted Power<br/>(Unit: dBm)</b> | BLE:9.50                              |
| <b>Power supply</b>                                    | DC 5V from USB<br>DC3.7V from BATTERY |
| <b>Antenna Type</b>                                    | Helical antenna                       |



### 3. SAR Measurement System

#### 3.1 Definition of Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho dv} \right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

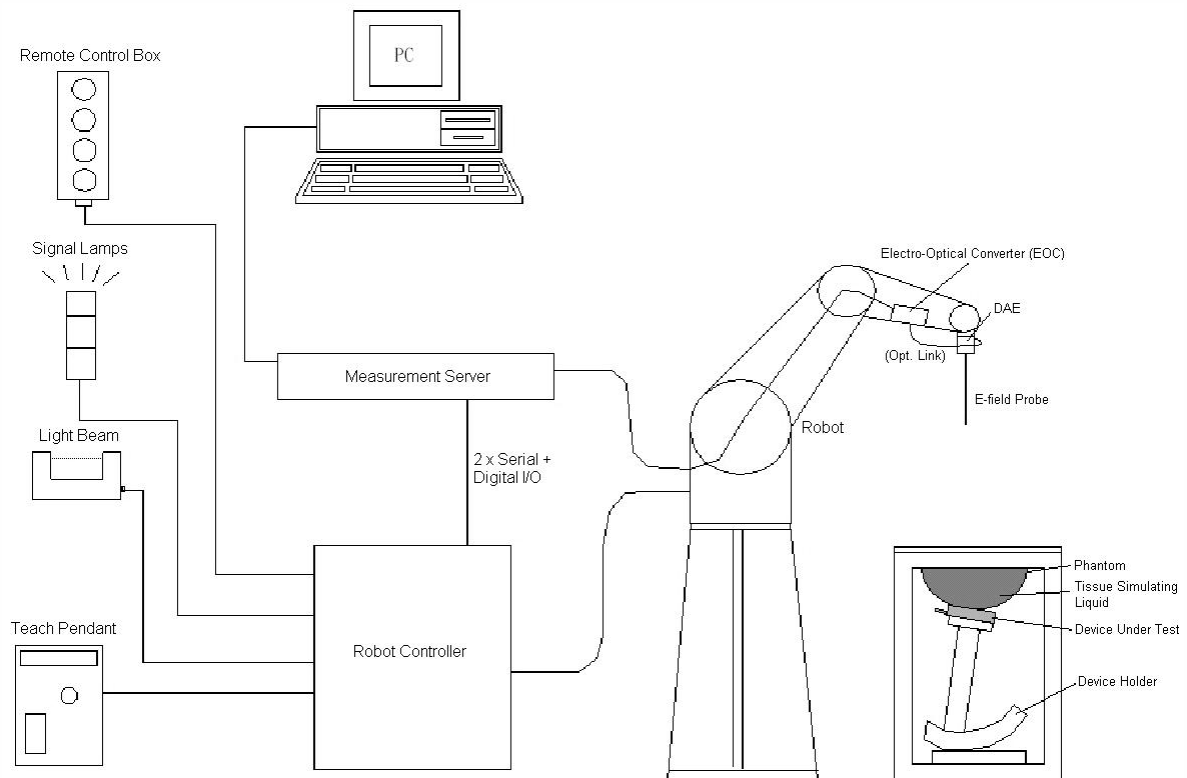
SAR measurement can be related to the electrical field in the tissue by

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where: σ is the conductivity of the tissue, ρ is the mass density of the tissue and E is the RMS electrical field strength.

#### 3.2 SPEAG DASY System

DASY system consists of high precision robot, probe alignment sensor, phantom, robot controller, controlled measurement server and near-field probe. The robot includes six axes that can move to the precision position of the DASY5 software defined. The DASY software can define the area that is detected by the probe. The robot is connected to controlled box. Controlled measurement server is connected to the controlled robot box. The DAE includes amplifier, signal multiplexing, AD converter, offset measurement and surface detection. It is connected to the Electro-optical coupler (ECO). The ECO performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC.

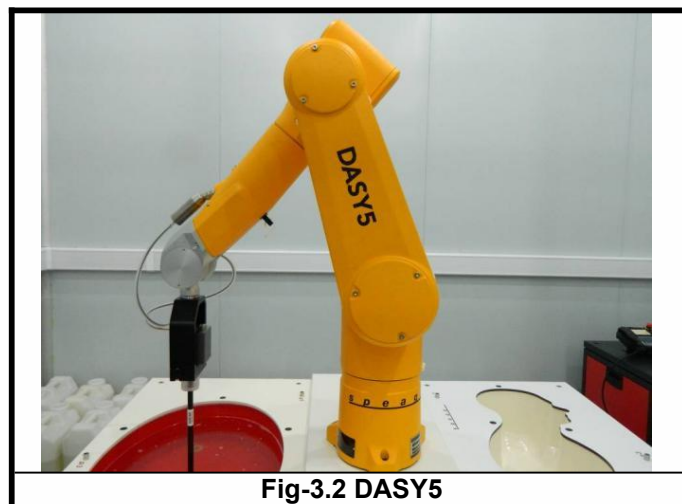


**Fig-3.1 DASY System Setup**

### 3.2.1 Robot

The DASYsystem uses the high precision robots from Stäubli SA (France). For the 6-axis controller system, the robot controller version (DASY5: CS8c) from Stäubli is used. The Stäubli robot series have many features that are important for our application:


- High precision (repeatability  $\pm 0.035$  mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)




**Fig-3.2 DASY5**

### 3.2.2 Probes


The SAR measurement is conducted with the dosimetric probe. The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency.


|                      |  |   |
|----------------------|--|---|
| <b>Model</b>         | EX3DV4   |  |
| <b>Construction</b>  | Symmetrical design with triangular core. Built-in shielding against static charges. PEEK enclosure material (resistant to organic solvents, e.g., DGBE). |   |
| <b>Frequency</b>     | 10 MHz to 6 GHz<br>Linearity: $\pm 0.2$ dB   |   |
| <b>Directivity</b>   | $\pm 0.3$ dB in HSL (rotation around probe axis)<br>$\pm 0.5$ dB in tissue material (rotation normal to probe axis)                                      |   |
| <b>Dynamic Range</b> | 10 $\mu$ W/g to 100 mW/g<br>Linearity: $\pm 0.2$ dB (noise: typically $< 1$ $\mu$ W/g)   |   |
| <b>Dimensions</b>    | Overall length: 337 mm (Tip: 20 mm)<br>Tip diameter: 2.5 mm (Body: 12 mm)<br>Typical distance from probe tip to dipole centers: 1 mm                     |   |

### 3.2.3 Data Acquisition Electronics (DAE)


|                             |   |   |
|-----------------------------|---|---|
| <b>Model</b>                | DAE4  |  |
| <b>Construction</b>         | Signal amplifier, multiplexer, A/D converter and control logic. Serial optical link for communication with DASY embedded system (fully remote controlled). Two step probe touch detector for mechanical surface detection and emergency robot stop. |   |
| <b>Measurement Range</b>    | -100 to +300 mV (16 bit resolution and two range settings: 4mV, 400mV)  |   |
| <b>Input Offset Voltage</b> | $< 5\mu$ V (with auto zero)   |   |
| <b>Input Bias Current</b>   | $< 50$ fA   |   |
| <b>Dimensions</b>           | 60 x 60 x 68 mm   |   |

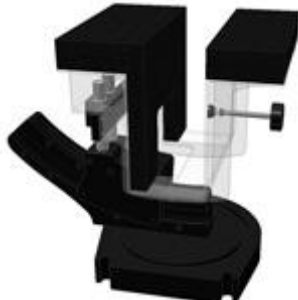
### 3.2.4 Phantoms

|                        |   |   |
|------------------------|---|---|
| <b>Model</b>           | Twin SAM  |  |
| <b>Construction</b>    | The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528 and IEC 62209-1. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by teaching three points with the robot. |   |
| <b>Material</b>        | Vinylester, glass fiber reinforced (VE-GF)  |   |
| <b>Shell Thickness</b> | $2 \pm 0.2$ mm ( $6 \pm 0.2$ mm at ear point)   |   |
| <b>Dimensions</b>      | Length: 1000 mm<br>Width: 500 mm<br>Height: adjustable feet   |   |
| <b>Filling Volume</b>  | approx. 25 liters   |   |


|                        |   |  |
|------------------------|---|--|
| <b>Model</b>           | ELI   |  |
| <b>Construction</b>    | Phantom for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30 MHz to 6 GHz. ELI is fully compatible with the IEC 62209-2 standard and all known tissue simulating liquids. ELI has been optimized regarding its performance and can be integrated into our standard phantom tables. A cover prevents evaporation of the liquid. Reference markings on the phantom allow installation of the complete setup, including all predefined phantom positions and measurement grids, by teaching three points. The phantom is compatible with all SPEAG dosimetric probes and dipoles. |  |
| <b>Material</b>        | Vinylester, glass fiber reinforced (VE-GF)  |  |
| <b>Shell Thickness</b> | $2.0 \pm 0.2$ mm (bottom plate)   |  |
| <b>Dimensions</b>      | Major axis: 600 mm<br>Minor axis: 400 mm  |  |
| <b>Filling Volume</b>  | approx. 30 liters   |  |

### 3.2.5 Device Holder

|                     |   |   |
|---------------------|---|---|
| <b>Model</b>        | Mounting Device   |  |
| <b>Construction</b> | In combination with the Twin SAM Phantom or ELI4, the Mounting Device enables the rotation of the mounted transmitter device in spherical coordinates. Rotation point is the ear opening point. Transmitter devices can be easily and accurately positioned according to IEC, IEEE, FCC or other specifications. The device holder can be locked for positioning at different phantom sections (left head, right head, flat). |   |
| <b>Material</b>     | POM   |   |

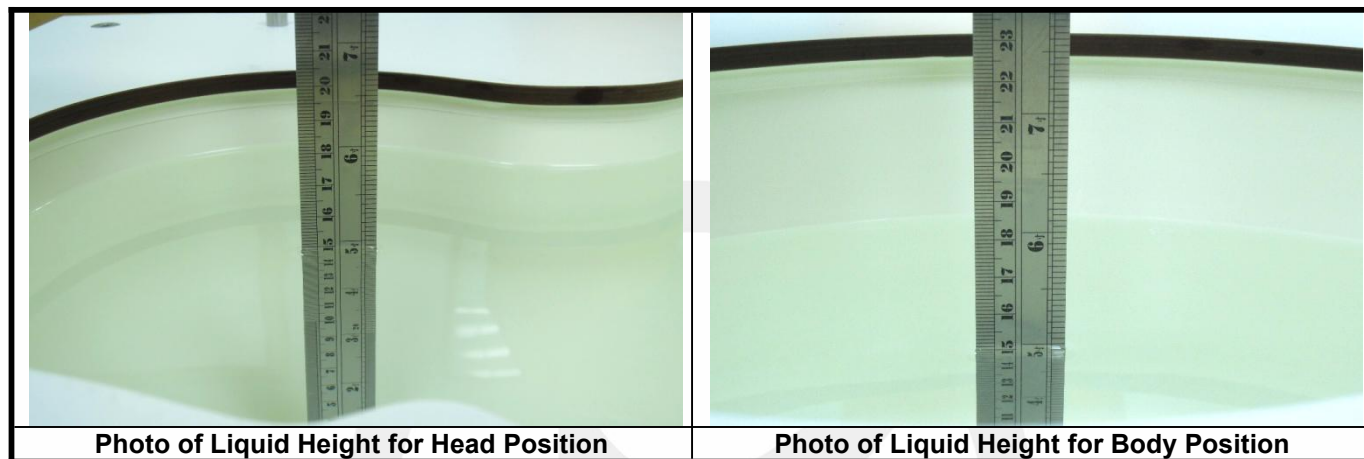
|                     |   |   |
|---------------------|---|---|
| <b>Model</b>        | Laptop Extensions Kit   |  |
| <b>Construction</b> | Simple but effective and easy-to-use extension for Mounting Device that facilitates the testing of larger devices according to IEC 62209-2 (e.g., laptops, cameras, etc.). It is lightweight and fits easily on the upper part of the Mounting Device in place of the phone positioner. |   |
| <b>Material</b>     | POM, Acrylic glass, Foam  |   |

### 3.2.6 System Validation Dipoles

|                         |   |   |
|-------------------------|---|---|
| <b>Model</b>            | D-Serial  |  |
| <b>Construction</b>     | Symmetrical dipole with 1/4 balun. Enables measurement of feedpoint impedance with NWA. Matched for use near flat phantoms filled with tissue simulating solutions. |   |
| <b>Frequency</b>        | 750 MHz to 5800 MHz   |   |
| <b>Return Loss</b>      | > 20 dB   |   |
| <b>Power Capability</b> | > 100 W ( $f < 1\text{GHz}$ ), > 40 W ( $f > 1\text{GHz}$ )   |   |

### 3.2.7 Tissue Simulating Liquids

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15 cm. For head SAR testing, the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15 cm. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15 cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 5% are listed in Table-3.1.



The dielectric properties of the head tissue simulating liquids are defined in IEEE1528, and KDB 865664 D01 Appendix A. For the body tissue simulating liquids, the dielectric properties are defined in KDB 865664 D01 Appendix A. The dielectric properties of the tissue simulating liquids were verified prior to the SAR evaluation using a dielectric assessment kit and a network analyzer.

**Table-3.1 Targets of Tissue Simulating Liquid**

| Frequency (MHz) | Target Permittivity | Range of $\pm 5\%$ | Target Conductivity | Range of $\pm 5\%$ |
|-----------------|---------------------|--------------------|---------------------|--------------------|
| <b>For Head</b> |                     |                    |                     |                    |
| 750             | 41.9                | 39.8 ~ 44.0        | 0.89                | 0.85 ~ 0.93        |
| 835             | 41.5                | 39.4 ~ 43.6        | 0.90                | 0.86 ~ 0.95        |
| 900             | 41.5                | 39.4 ~ 43.6        | 0.97                | 0.92 ~ 1.02        |
| 1450            | 40.5                | 38.5 ~ 42.5        | 1.20                | 1.14 ~ 1.26        |
| 1640            | 40.3                | 38.3 ~ 42.3        | 1.29                | 1.23 ~ 1.35        |
| 1750            | 40.1                | 38.1 ~ 42.1        | 1.37                | 1.30 ~ 1.44        |
| 1800            | 40.0                | 38.0 ~ 42.0        | 1.40                | 1.33 ~ 1.47        |
| 1900            | 40.0                | 38.0 ~ 42.0        | 1.40                | 1.33 ~ 1.47        |
| 2000            | 40.0                | 38.0 ~ 42.0        | 1.40                | 1.33 ~ 1.47        |
| 2300            | 39.5                | 37.5 ~ 41.5        | 1.67                | 1.59 ~ 1.75        |
| 2450            | 39.2                | 37.2 ~ 41.2        | 1.80                | 1.71 ~ 1.89        |
| 2600            | 39.0                | 37.1 ~ 41.0        | 1.96                | 1.86 ~ 2.06        |
| 3500            | 37.9                | 36.0 ~ 39.8        | 2.91                | 2.76 ~ 3.06        |
| 5200            | 36.0                | 34.2 ~ 37.8        | 4.66                | 4.43 ~ 4.89        |
| 5300            | 35.9                | 34.1 ~ 37.7        | 4.76                | 4.52 ~ 5.00        |
| 5500            | 35.6                | 33.8 ~ 37.4        | 4.96                | 4.71 ~ 5.21        |
| 5600            | 35.5                | 33.7 ~ 37.3        | 5.07                | 4.82 ~ 5.32        |
| 5800            | 35.3                | 33.5 ~ 37.1        | 5.27                | 5.01 ~ 5.53        |

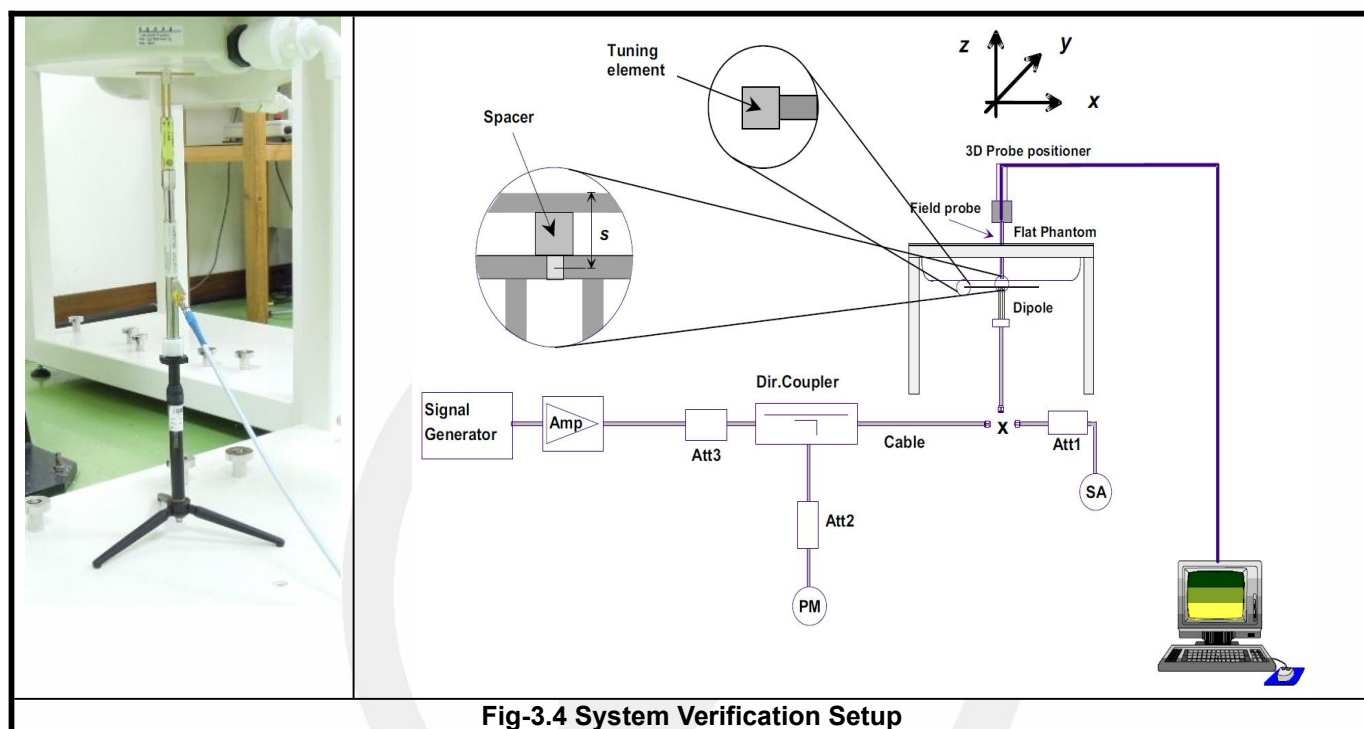
The following table gives the recipes for tissue simulating liquids.

**Table-3.2 Recipes of Tissue Simulating Liquid**

| Tissue Type | Bactericide | DGBE | HEC | NaCl | Sucrose | Triton X-100 | Water | Diethylene Glycol Mono-hexylether |
|-------------|-------------|------|-----|------|---------|--------------|-------|-----------------------------------|
| H750        | 0.2         | -    | 0.2 | 1.5  | 56.0    | -            | 42.1  | -                                 |
| H835        | 0.2         | -    | 0.2 | 1.5  | 57.0    | -            | 41.1  | -                                 |
| H900        | 0.2         | -    | 0.2 | 1.4  | 58.0    | -            | 40.2  | -                                 |
| H1450       | -           | 43.3 | -   | 0.6  | -       | -            | 56.1  | -                                 |
| H1640       | -           | 45.8 | -   | 0.5  | -       | -            | 53.7  | -                                 |
| H1750       | -           | 47.0 | -   | 0.4  | -       | -            | 52.6  | -                                 |
| H1800       | -           | 44.5 | -   | 0.3  | -       | -            | 55.2  | -                                 |
| H1900       | -           | 44.5 | -   | 0.2  | -       | -            | 55.3  | -                                 |
| H2000       | -           | 44.5 | -   | 0.1  | -       | -            | 55.4  | -                                 |
| H2300       | -           | 44.9 | -   | 0.1  | -       | -            | 55.0  | -                                 |
| H2450       | -           | 45.0 | -   | 0.1  | -       | -            | 54.9  | -                                 |
| H2600       | -           | 45.1 | -   | 0.1  | -       | -            | 54.8  | -                                 |
| H3500       | -           | 8.0  | -   | 0.2  | -       | 20.0         | 71.8  | -                                 |
| H5G         | -           | -    | -   | -    | -       | 17.2         | 65.5  | 17.3                              |

### 3.3 SAR System Verification

The system check verifies that the system operates within its specifications. It is performed daily or before every SAR measurement. The system check uses normal SAR measurements in the flat section of the phantom with a matched dipole at a specified distance. The system verification setup is shown as below.



The validation dipole is placed beneath the flat phantom with the specific spacer in place. The distance spacer is touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The spectrum analyzer measures the forward power at the location of the system check dipole connector. The signal generator is adjusted for the desired forward power (250 mW is used for 700 MHz to 3 GHz, 100 mW is used for 3.5 GHz to 6 GHz) at the dipole connector and the power meter is read at that level. After connecting the cable to the dipole, the signal generator is readjusted for the same reading at power meter.

After system check testing, the SAR result will be normalized to 1W forward input power and compared with the reference SAR value derived from validation dipole certificate report. The deviation of system check should be within 10 %.

### 3.4 SAR Measurement Procedure

According to the SAR test standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- Power reference measurement
- Area scan
- Zoom scan
- Power drift measurement

The SAR measurement procedures for each of test conditions are as follows:

- Make EUT to transmit maximum output power
- Measure conducted output power through RF cable
- Place the EUT in the specific position of phantom
- Perform SAR testing steps on the DASY system
- Record the SAR value

#### 3.4.1 Area & Zoom Scan Procedure

First Area Scan is used to locate the approximate location(s) of the local peak SAR value(s). The measurement grid within an Area Scan is defined by the grid extent, grid step size and grid offset. Next, in order to determine the EM field distribution in a three-dimensional spatial extension, Zoom Scan is required. The Zoom Scan is performed around the highest E-field value to determine the averaged SAR-distribution over 10 g. According to KDB 865664D01, the resolution for Area and Zoom scan is specified in the table below.

| Items                                 | ≤ 2 GHz | 2-3 GHz | 3-4 GHz | 4-5 GHz | 5-6 GHz |
|---------------------------------------|---------|---------|---------|---------|---------|
| Area Scan<br>( $\Delta x, \Delta y$ ) | ≤ 15 mm | ≤ 12 mm | ≤ 12 mm | ≤ 10 mm | ≤ 10 mm |
| Zoom Scan<br>( $\Delta x, \Delta y$ ) | ≤ 8 mm  | ≤ 5 mm  | ≤ 5 mm  | ≤ 4 mm  | ≤ 4 mm  |
| Zoom Scan<br>( $\Delta z$ )           | ≤ 5 mm  | ≤ 5 mm  | ≤ 4 mm  | ≤ 3 mm  | ≤ 2 mm  |
| Zoom Scan<br>Volume                   | ≥ 30 mm | ≥ 30 mm | ≥ 28 mm | ≥ 25 mm | ≥ 22 mm |

#### Note:

When zoom scan is required and report SAR is ≤ 1.4 W/kg, the zoom scan resolution of  $\Delta x / \Delta y$  (2-3GHz: ≤ 8 mm, 3-4GHz: ≤ 7 mm, 4-6GHz: ≤ 5 mm) may be applied.

#### 3.4.2 VolumeScan Procedure

The volume scan is used for assess overlapping SAR distributions for antennas transmitting in different frequency bands. It is equivalent to an oversized zoom scan used in standalone measurements. The measurement volume will be used to enclose all the simultaneous transmitting antennas. For antennas transmitting simultaneously in different frequency bands, the volume scan is measured separately in each frequency band. In order to sum correctly to compute the 1g aggregate SAR, the EUT remain in the same test position for all measurements and all volume scan use the same spatial resolution and grid spacing. When all volume scan were completed, the software, SEMCAD postprocessor can combine and subsequently superpose these measurement data to calculating the multiband SAR.

### 3.4.3 Power Drift Monitoring

All SAR testing is under the EUT install full charged battery and transmit maximum output power. In DASY measurement software, the power reference measurement and power drift measurement procedures are used for monitoring the power drift of EUT during SAR test. Both these procedures measure the field at a specified reference position before and after the SAR testing. The software will calculate the field difference in dB. If the power drift more than 5%, the SAR will be retested.

### 3.4.4 Spatial Peak SAR Evaluation

The procedure for spatial peak SAR evaluation has been implemented according to the test standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

The entire evaluation of the spatial peak values is performed within the post-processing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- (a) Extraction of the measured data (grid and values) from the Zoom Scan
- (b) Calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- (c) Generation of a high-resolution mesh within the measured volume
- (d) Interpolation of all measured values from the measurement grid to the high-resolution grid
- (e) Extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- (f) Calculation of the averaged SAR within masses of 1g and 10g

### 3.4.5 SAR Averaged Methods

In DASY, the interpolation and extrapolation are both based on the modified Quadratic Shepard's method. The interpolation scheme combines a least-square fitted function method and a weighted average method which are the two basic types of computational interpolation and approximation.

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. The uncertainty increases with the extrapolation distance. To keep the uncertainty within 1% for the 1 g and 10 g cubes, the extrapolation distance should not be larger than 5 mm.

## 4. SAR Measurement Evaluation

### 4.1 Applicable Standards

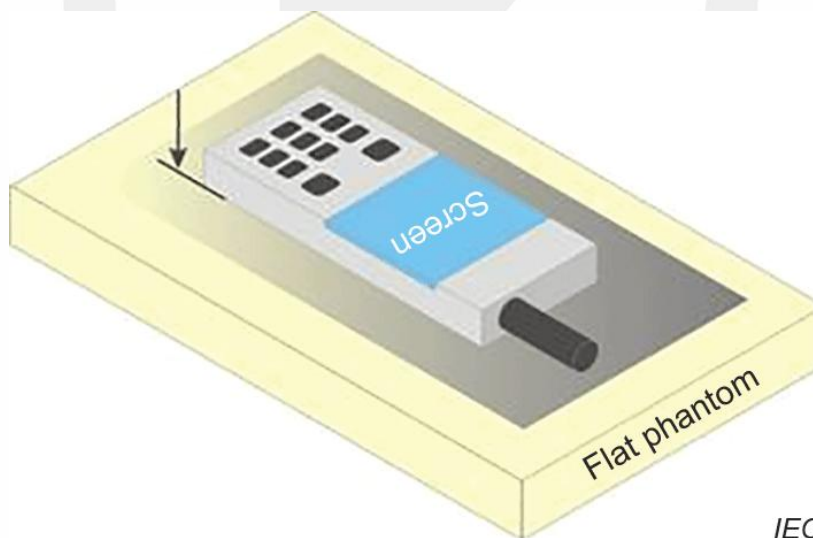
FCC 47 CFR Part 2§2.1093  
KDB 865664 D01 v01r04  
IEEE Std C95.1-2005  
KDB 447498 D01 v06  
KDB 865664 D02 v01r02

### 4.2 EUT Testing Position

#### 4.2.1 Hand-held usage of the device, not at the head or torso

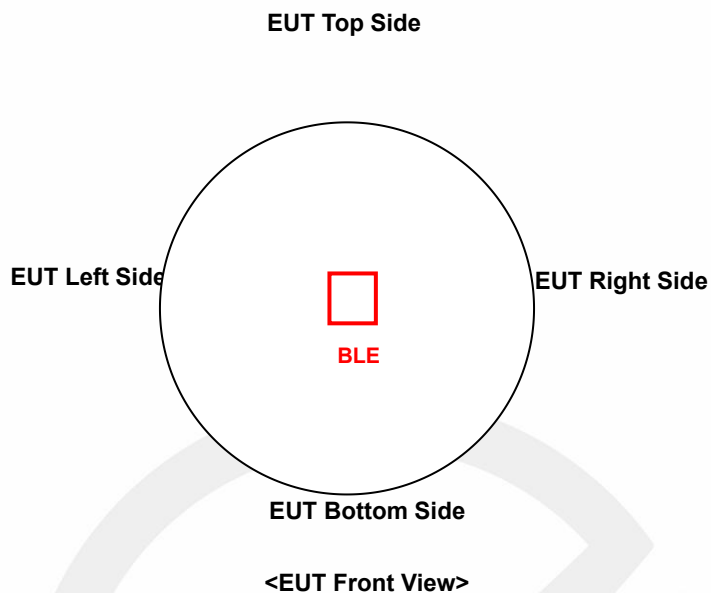
When SAR measurement is necessary for hand-held devices that do not transmit while at the head or torso, a flat phantom may be used. To assess this type of device, the device shall be placed directly against the flat phantom as shown in Figure 11, for the sides of the device that are in contact with the hand for the intended use.

NOTE Concerning a measurement phantom representing the hand, there are practical difficulties in specifying a unique hand holding position that is applicable to all devices. Additional studies are needed for devising a representative method for evaluating SAR in the hand of hand-held devices (whether or not they are hand-operated devices). Future versions of this document are intended to contain a test method based on scientific data and rationale.



**Fig-4.1 Test position for hand-held devices, not used at the head or torso**

# <Antenna Location>



The separation distance for antenna to edge:

| Antenna | To Left Side (mm) | To Right Side (mm) | To Top Side (mm) | To Rear Face (mm) | To Bottom Side (mm) | To Front Face (mm) |
|---------|-------------------|--------------------|------------------|-------------------|---------------------|--------------------|
| BT      | 30                | 30                 | 5                | 30                | 55                  | 30                 |

#### 4.2.1 SAR Test Exclusion Evaluations

SAR evaluation is required if the separation distance between the user and/or bystander and the antenna and/or radiating element of the device is less than or equal to 20 cm, except when the device operates at or below the applicable output power level (adjusted for tune-up tolerance) for the specified separation distance defined in Table 1.

| Frequency (MHz) | ≤ 5 mm (mW) | 10 mm (mW) | 15 mm (mW) | 20 mm (mW) | 25 mm (mW) | 30 mm (mW) | 35 mm (mW) | 40 mm (mW) | 45 mm (mW) | > 50 mm (mW) |
|-----------------|-------------|------------|------------|------------|------------|------------|------------|------------|------------|--------------|
| ≤ 300           | 45          | 116        | 139        | 163        | 189        | 216        | 246        | 280        | 319        | 362          |
| 450             | 32          | 71         | 87         | 104        | 124        | 147        | 175        | 208        | 248        | 296          |
| 835             | 21          | 32         | 41         | 54         | 72         | 96         | 129        | 172        | 228        | 298          |
| 1900            | 6           | 10         | 18         | 33         | 57         | 92         | 138        | 194        | 257        | 323          |
| 2450            | 3           | 7          | 16         | 32         | 56         | 89         | 128        | 170        | 209        | 245          |
| 3500            | 2           | 6          | 15         | 29         | 50         | 72         | 94         | 114        | 134        | 158          |
| 5800            | 1           | 5          | 13         | 23         | 32         | 41         | 54         | 74         | 102        | 128          |

#### Note:

- The exemption limits in Table 1 are based on measurements and simulations of half-wave dipole antennas at separation distances of 5 mm to 25 mm from a flat phantom, providing a SAR value of approximately 0.4 W/kg for 1g of tissue. For low frequencies (300 MHz to 835 MHz), the exemption limits are derived from a linear fit. For high frequencies (1900 MHz and above), the exemption limits are derived from a third order polynomial fit.
- Transmitters operating between 0.003-10 MHz, meeting the exemption from routine SAR evaluation, shall demonstrate compliance to the instantaneous limits as below.

#### <For BLE >

| Mode | Max. Tune-up Power (dBm) | Max. Tune-up Power (mW) | Rear Face            |         |                      | Left Side            |         |                      | Right Side           |         |                      | Top Side             |         |                      | Bottom Side          |         |                      |
|------|--------------------------|-------------------------|----------------------|---------|----------------------|----------------------|---------|----------------------|----------------------|---------|----------------------|----------------------|---------|----------------------|----------------------|---------|----------------------|
|      |                          |                         | Ant. to Surface (mm) | Pth(mW) | Require SAR Testing? | Ant. to Surface (mm) | Pth(mW) | Require SAR Testing? | Ant. to Surface (mm) | Pth(mW) | Require SAR Testing? | Ant. to Surface (mm) | Pth(mW) | Require SAR Testing? | Ant. to Surface (mm) | Pth(mW) | Require SAR Testing? |
| BLE  | 9.50                     | 8.91                    | 30                   | 89      | NO                   | 30                   | 89      | NO                   | 30                   | 89      | NO                   | 5                    | 3       | Yes                  | 30                   | 89      | NO                   |
| Mode | Max. Tune-up Power (dBm) | Max. Tune-up Power (mW) | Front Face           |         |                      |                      |         |                      |                      |         |                      |                      |         |                      |                      |         |                      |
|      |                          |                         | Ant. to Surface (mm) | Pth(mW) | Require SAR Testing? |                      |         |                      |                      |         |                      |                      |         |                      |                      |         |                      |
| BLE  | 9.50                     | 8.91                    | 30                   | 89      | NO                   |                      |         |                      |                      |         |                      |                      |         |                      |                      |         |                      |

#### Note:

- When separation distance ≤ 50 mm and the calculated result shown in above table is ≤ 3.0 for SAR-1g exposure condition, or ≤ 7.5 for SAR-10g exposure condition, the SAR testing exclusion is applied.
- When separation distance > 50 mm and the device output power is less than the calculated result (power threshold, mW) shown in above table, the SAR testing exclusion is applied.

### 4.3 Tissue Verification

The measuring results for tissue simulating liquid are shown as below.

| Test Date    | Tissue Type | Frequency (MHz) | Liquid Temp. (°C) | Measured Conductivity ( $\sigma$ ) | Measured Permittivity ( $\epsilon_r$ ) | Target Conductivity ( $\sigma$ ) | Target Permittivity ( $\epsilon_r$ ) | Conductivity Deviation (%) | Permittivity Deviation (%) |
|--------------|-------------|-----------------|-------------------|------------------------------------|--|----------------------------------|--------------------------------------|----------------------------|----------------------------|
| June 12,2025 | Head        | 2450            | 21.8              | 1.78                               | 40.11                                  | 1.80                             | 39.20                                | -1.11                      | 2.32                       |

**Note:**

The dielectric properties of the tissue simulating liquid must be measured within 24 hours before the SAR testing and within  $\pm 5\%$  of the target values. Liquid temperature during the SAR testing must be within  $\pm 2^\circ\text{C}$ .

### 4.4 System Validation

The SAR measurement system was validated according to procedures in KDB 865664 D01. The validation status in tabulated summary is as below.

| Calibration Date | Probe S/N | Calibration Point |      | Measured Conductivity ( $\sigma$ ) | Measured Permittivity ( $\epsilon_r$ ) | Validation for CW |                 |                | Validation for Modulation |             |      |
|------------------|-----------|-------------------|------|------------------------------------|--|-------------------|-----------------|----------------|---------------------------|-------------|------|
|                  |           |                   |      |                                    |  | Sensitivity Range | Probe Linearity | Probe Isotropy | Modulation Type           | Duty Factor | PAR  |
| June 12,2025     | 3970      | Head              | 2450 | 1.78                               | 40.11                                  | Pass              | Pass            | Pass           | CW                        | N/A         | Pass |

## 4.5 System Verification

The measuring result for system verification is tabulated as below.

| Test Date     | Mode | Frequency (MHz) | 1W Target SAR-1g (W/kg) | Measured SAR-1g (W/kg) | Normalized to 1W SAR-1g (W/kg) | Deviation (%) | Dipole S/N | Probe S/N | DAE S/N |
|---------------|------|-----------------|-------------------------|------------------------|--------------------------------|---------------|------------|-----------|---------|
| June 12, 2025 | Head | 2450            | 51.60                   | 13.08                  | 52.32                          | 1.40          | 927        | 3970      | 1418    |

### Note:

Comparing to the reference SAR value provided by SPEAG, the validation data should be within its specification of 10 %. The result indicates the system check can meet the variation criterion and the plots can be referred to Appendix A of this report.



## 4.6 Maximum Output Power

### 4.6.1 Maximum Conducted Power

The maximum conducted average power (Unit: dBm) including tune-up tolerance is shown as below.

| Mode | 2.4G Bluetooth |
|------|----------------|
| LE   | 9.50           |



#### 4.6.2 Measured Conducted Power Result

The measuring conducted power (Unit: dBm) is shown as below.

##### <Bluetooth>

| Mode                      | Bluetooth LE |           |           |
|---------------------------|--------------|-----------|-----------|
| Channel / Frequency (MHz) | 0 (2402)     | 19 (2440) | 39 (2480) |
| conducted power(1M)       | 9.09         | 7.16      | 6.48      |
| conducted power(2M)       | 9.03         | 7.11      | 6.40      |



## 4.7 SAR Testing Results

### 4.7.1 SAR Test Reduction Considerations

#### <KDB 447498 D01, General RF Exposure Guidance>

Testing of other required channels within the operating mode of a frequency band is not required when the reported SAR for the mid-band or highest output power channel is:

- (1)  $\leq 0.8$  W/kg or 2.0 W/kg, for 1-g or 10-g respectively, when the transmission band is  $\leq 100$  MHz
- (2)  $\leq 0.6$  W/kg or 1.5 W/kg, for 1-g or 10-g respectively, when the transmission band is between 100 MHz and 200 MHz
- (3)  $\leq 0.4$  W/kg or 1.0 W/kg, for 1-g or 10-g respectively, when the transmission band is  $\geq 200$  MHz

### 4.7.2 SAR Results for Head Exposure Condition

| Plot No. | Band      | Mode | Test Position | Antenna | Ch. | Max. Tune-up Power (dBm) | Measured Conducted Power (dBm) | Power Drift (dB) | Measured SAR-1g (W/kg) | Scaling Factor | Scaled SAR-1g (W/kg) |
|----------|-----------|------|---------------|---------|-----|--------------------------|--------------------------------|------------------|------------------------|----------------|----------------------|
| 1        | Bluetooth | 1M   | Top Side      | -       | 0   | 9.50                     | 9.09                           | -0.10            | 0.030                  | 1.099          | 0.033                |
|          | Bluetooth | 2M   | Top Side      | -       | 0   | 9.50                     | 9.03                           | -0.02            | 0.024                  | 1.114          | 0.027                |

Note:

- 1.SAR tests use the same power level as RF tests.
- 2.The scaled sar calculation takes into account the values including the Bluetooth duty cycle during the test,Has been configured in software testing,It is reflected in Appendix B,Therefore, the final sar value includes the Bluetooth duty cycle coefficient calculation

**Test Engineer:** Jim Cai

## 5. Calibration of Test Equipment

| Equipment                    | Manufacturer | Model      | SN           | Cal. Date     | Cal. Interval |
|------------------------------|--------------|------------|--------------|---------------|---------------|
| System Validation Dipole     | SPEAG        | D2450V2    | 927          | May. 09, 2025 | 3 Year        |
| Dosimetric E-Field Probe     | SPEAG        | EX3DV4     | 3970         | Jun. 05, 2025 | 1 Year        |
| Data Acquisition Electronics | SPEAG        | DAE4       | 1418         | Jun. 05, 2025 | 1 Year        |
| ENA Series Network Analyzer  | Agilent      | E5071B     | MY42404246   | May. 10, 2025 | 1 Year        |
| Signal Analyzer              | Agilent      | N9010A     | MY53470879   | May. 10, 2025 | 1 Year        |
| Signal Generator             | Agilent      | SMM100A    | 17-1050100-C | Sep. 16, 2024 | 1 Year        |
| Power Sensor                 | Agilent      | E9304A H18 | MY52050011   | May. 10, 2025 | 1 Year        |
| Power Meter                  | BOONTON      | 4232A      | 10539        | May. 10, 2025 | 1 Year        |
| Power Sensor                 | BOONTON      | 51011EMC   | 36164        | May. 10, 2025 | 1 Year        |
| Electronic Thermometer       | Hegao        | HTC-1      | \            | May. 12, 2025 | 1 Year        |
| Directional Coupler          | MILMEGA      | DC6180AM1  | 0340463      | May. 10, 2025 | 1 Year        |

## 6. Measurement Uncertainty

| Source of Uncertainty                | Tolerance<br>(±%) | Probability<br>Distribution | Divisor | Ci 1g | Ci<br>10g | Standard<br>Uncertainty<br>1g (±%) | Standard<br>Uncertainty<br>10g (±%) | Vi<br>Veff |
|--------------------------------------|-------------------|-----------------------------|---------|-------|-----------|------------------------------------|-------------------------------------|------------|
| <b>Measurement System</b>            |                   |                             |         |       |           |                                    |                                     |            |
| Probe Calibration                    | 6.05              | Normal                      | 1       | 1     | 1         | 6.10                               | 6.10                                | ∞          |
| Axial Isotropy                       | 4.7               | Rectangular                 | √3      | 0.7   | 0.7       | 1.8                                | 1.8                                 | ∞          |
| Hemispherical Isotropy               | 9.6               | Rectangular                 | √3      | 0.7   | 0.7       | 3.9                                | 3.9                                 | ∞          |
| Linearity                            | 4.7               | Rectangular                 | √3      | 1     | 1         | 2.7                                | 2.7                                 | ∞          |
| Probe Modulation Response            | 2.4               | Rectangular                 | √3      | 1     | 1         | 1.4                                | 1.4                                 | ∞          |
| Detection Limits                     | 0.25              | Rectangular                 | √3      | 1     | 1         | 0.1                                | 0.1                                 | ∞          |
| Boundary Effect                      | 2                 | Rectangular                 | √3      | 1     | 1         | 1                                  | 1                                   | ∞          |
| Readout Electronics                  | 0.3               | Normal                      | 1       | 1     | 1         | 0.3                                | 0.3                                 | ∞          |
| Response Time                        | 0                 | Rectangular                 | √3      | 1     | 1         | 0                                  | 0                                   | ∞          |
| Integration Time                     | 1.7               | Rectangular                 | √3      | 1     | 1         | 1                                  | 1                                   | ∞          |
| RF Ambient Conditions –              | 3                 | Rectangular                 | √3      | 1     | 1         | 1.7                                | 1.7                                 | ∞          |
| RF Ambient Conditions –              | 3                 | Rectangular                 | √3      | 1     | 1         | 1.7                                | 1.7                                 | ∞          |
| Probe Positioner Mech.               | 0.4               | Rectangular                 | √3      | 1     | 1         | 0.2                                | 0.2                                 | ∞          |
| Probe Positioning with               | 2.8               | Rectangular                 | √3      | 1     | 1         | 1.7                                | 1.7                                 | ∞          |
| Post-processing                      | 2                 | Rectangular                 | √3      | 1     | 1         | 1.2                                | 1.2                                 | ∞          |
| <b>Test Sample Related</b>           |                   |                             |         |       |           |                                    |                                     |            |
| Device Holder Uncertainty            | 4.1 / 1.7         | Normal                      | 1       | 1     | 1         | 4.1                                | 1.7                                 | 32         |
| Test Sample Positioning              | 1.5 / 0.7         | Normal                      | 1       | 1     | 1         | 1.5                                | 0.7                                 | 32         |
| Power Scaling                        | 0                 | Rectangular                 | √3      | 1     | 1         | 0                                  | 0                                   | ∞          |
| Power Drift of Measured              | 5                 | Rectangular                 | √3      | 1     | 1         | 2.9                                | 2.9                                 | ∞          |
| <b>Phantom and Setup</b>             |                   |                             |         |       |           |                                    |                                     |            |
| Phantom Uncertainty (Shape)          | 7.1               | Rectangular                 | √3      | 1     | 1         | 4.0                                | 4.0                                 | ∞          |
| Algorithm for Correcting             | 1.2 / 0.97        | Normal                      | 1       | 1     | 0.84      | 1.2                                | 0.7                                 | ∞          |
| Liquid Conductivity (Meas.)          | 1                 | Normal                      | 1       | 0.78  | 0.71      | 0.8                                | 0.7                                 | 25         |
| Liquid Permittivity (Meas.)          | 0.5               | Normal                      | 1       | 0.23  | 0.26      | 0.1                                | 0.1                                 | 25         |
| Liquid Conductivity–                 | 2.2               | Rectangular                 | √3      | 0.78  | 0.71      | 1                                  | 0.9                                 | ∞          |
| Liquid Permittivity–                 | 1.9               | Rectangular                 | √3      | 0.23  | 0.26      | 0.3                                | 0.3                                 | ∞          |
| <b>Combined Standard Uncertainty</b> |                   |                             |         |       |           | ±12.05%                            | ±11.30%                             |            |
| <b>Expanded Uncertainty (K=2)</b>    |                   |                             |         |       |           | ±24.09%                            | ±22.60%                             |            |

Uncertainty budget for frequency range 600 MHz to 3 GHz

| Source of Uncertainty                | Tolerance<br>(±%) | Probability<br>Distribution | Divisor | Ci 1g | Ci 10g | Standard<br>Uncertainty<br>1g (±%) | Standard<br>Uncertainty<br>10g (±%) | Vi<br>Veff |
|--------------------------------------|-------------------|-----------------------------|---------|-------|--------|------------------------------------|-------------------------------------|------------|
| <b>Measurement System</b>            |                   |                             |         |       |        |                                    |                                     |            |
| Probe Calibration                    | 6.45              | Normal                      | 1       | 1     | 1      | 6.55                               | 6.55                                | ∞          |
| Axial Isotropy                       | 4.7               | Rectangular                 | √3      | 0.7   | 0.7    | 1.9                                | 1.9                                 | ∞          |
| Hemispherical Isotropy               | 9.6               | Rectangular                 | √3      | 0.7   | 0.7    | 3.9                                | 3.9                                 | ∞          |
| Linearity                            | 4.7               | Rectangular                 | √3      | 1     | 1      | 2.7                                | 2.7                                 | ∞          |
| Probe Modulation Response            | 2.4               | Rectangular                 | √3      | 1     | 1      | 1.4                                | 1.4                                 | ∞          |
| Detection Limits                     | 0.25              | Rectangular                 | √3      | 1     | 1      | 0.1                                | 0.1                                 | ∞          |
| Boundary Effect                      | 2                 | Rectangular                 | √3      | 1     | 1      | 1                                  | 1                                   | ∞          |
| Readout Electronics                  | 0.3               | Normal                      | 1       | 1     | 1      | 0.3                                | 0.3                                 | ∞          |
| Response Time                        | 0                 | Rectangular                 | √3      | 1     | 1      | 0                                  | 0                                   | ∞          |
| Integration Time                     | 1.7               | Rectangular                 | √3      | 1     | 1      | 1                                  | 1                                   | ∞          |
| RF Ambient Conditions –              | 3                 | Rectangular                 | √3      | 1     | 1      | 1.7                                | 1.7                                 | ∞          |
| RF Ambient Conditions –              | 3                 | Rectangular                 | √3      | 1     | 1      | 1.7                                | 1.7                                 | ∞          |
| Probe Positioner Mech.               | 0.4               | Rectangular                 | √3      | 1     | 1      | 0.2                                | 0.2                                 | ∞          |
| Probe Positioning with               | 2.8               | Rectangular                 | √3      | 1     | 1      | 1.7                                | 1.7                                 | ∞          |
| Post-processing                      | 2                 | Rectangular                 | √3      | 1     | 1      | 1.2                                | 1.2                                 | ∞          |
| <b>Test Sample Related</b>           |                   |                             |         |       |        |                                    |                                     |            |
| Device Holder Uncertainty            | 4.5 / 1.9         | Normal                      | 1       | 1     | 1      | 4.5                                | 1.9                                 | 32         |
| Test Sample Positioning              | 1.8 / 0.8         | Normal                      | 1       | 1     | 1      | 1.8                                | 0.8                                 | 32         |
| Power Scaling                        | 0                 | Rectangular                 | √3      | 1     | 1      | 0                                  | 0                                   | ∞          |
| Power Drift of Measured SAR          | 5                 | Rectangular                 | √3      | 1     | 1      | 2.9                                | 2.9                                 | ∞          |
| <b>Phantom and Setup</b>             |                   |                             |         |       |        |                                    |                                     |            |
| Phantom Uncertainty (Shape)          | 7.8               | Rectangular                 | √3      | 1     | 1      | 4.4                                | 4.4                                 | ∞          |
| Algorithm for Correcting SAR         | 1.2 / 0.97        | Normal                      | 1       | 1     | 0.84   | 1.2                                | 0.8                                 | ∞          |
| Liquid Conductivity (Meas.)          | 1                 | Normal                      | 1       | 0.78  | 0.71   | 0.8                                | 0.7                                 | 25         |
| Liquid Permittivity (Meas.)          | 0.5               | Normal                      | 1       | 0.23  | 0.26   | 0.1                                | 0.1                                 | 25         |
| Liquid Conductivity–                 | 2.2               | Rectangular                 | √3      | 0.78  | 0.71   | 1                                  | 0.9                                 | ∞          |
| Liquid Permittivity–                 | 1.9               | Rectangular                 | √3      | 0.23  | 0.26   | 0.3                                | 0.3                                 | ∞          |
| <b>Combined Standard Uncertainty</b> |                   |                             |         |       |        | ±12.61%                            | ±11.75%                             |            |
| <b>Expanded Uncertainty (K=2)</b>    |                   |                             |         |       |        | ±25.22%                            | ±23.50%                             |            |

### Uncertainty budget for frequency range 3 GHz to 6 GHz

## 7. Information on the Testing Laboratories

We, EMTEK (SHENZHEN) CO., LTD., were founded in 2000 to provide our best service in EMC, Radio, Telecom and Safety consultation. Our laboratories are accredited and approved according to ISO/IEC 17025.

Site Description  
EMC Lab.

: **Accredited by CNAS**  
The Certificate Registration Number is L2291.  
The Laboratory has been assessed and proved to be in compliance with  
CNAS-CL01 (identical to ISO/IEC 17025:2017)

**Accredited by FCC**

Designation Number: CN1204  
Test Firm Registration Number: 882943

**Accredited by A2LA**

The Certificate Number is 4321.01.

**Accredited by Industry Canada**

The Conformity Assessment Body Identifier is CN0008

Name of Firm  
Site Location

: EMTEK (SHENZHEN) CO., LTD.  
: Building 69, Majialong Industry Zone, Nanshan District, Shenzhen,  
Guangdong, China

If you have any comments, please feel free to contact us at the following:

Add: Bldg 69, Majialong Industry Zone, Nanshan District, Shenzhen, Guangdong, China

TEL: 86-755-26954280

FAX: 86-755-26954282

**Email:** csg@emtek.com.cn

**Web Site:** www.emtek.com.cn

The road map of all our labs can be found in our web site also.

--- End of Report ---

## Appendix A. SAR Plots of System Verification

The plots for system verification with largest deviation for each SAR system combination are shown as Appendix A.



## Appendix B. SAR Plots of SAR Measurement

The SAR plots for highest measured SAR in each exposure configuration, wireless mode and frequency band combination are shown as Appendix B.



## Appendix C. Calibration Certificate for Probe and Dipole

The calibration certificates are shown as Appendix C.



## Appendix D. Photographs of EUT and Setup

